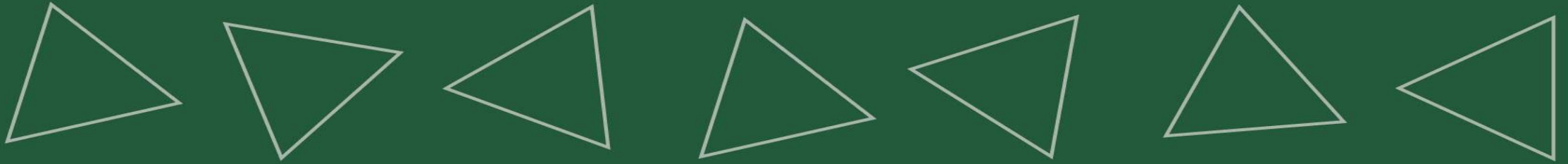


Dynamic Programming



Algorithm Design and Analysis Dynamic Programming (1)

<http://ada.miulab.tw>

Yun-Nung (Vivian) Chen



國立臺灣大學
National Taiwan University



Announcement

- Mini-HW 3 released
 - Due on 10/10 (Thu) 14:20
 - Online submission
- Homework 1 released
 - Due on 10/17 (Thur) 17:20 (2 weeks left)
 - Writing: print out the A4 hard copy and submit to NTU COOL
 - Programming: submit to Online Judge – <http://ada-judge.csie.ntu.edu.tw>

Outline

- Dynamic Programming
- DP #1: Rod Cutting
- DP #2: Stamp Problem
- DP #3: Sequence Alignment Problem
 - Longest Common Subsequence (LCS) / Edit Distance
 - Viterbi Algorithm
 - Space Efficient Algorithm
- DP #4: Matrix-Chain Multiplication
- DP #5: Weighted Interval Scheduling
- DP #6: Knapsack Problem
 - 0/1 Knapsack
 - Unbounded Knapsack
 - Multidimensional Knapsack
 - Fractional Knapsack



動腦一下 – 囚犯問題

- 有100個死囚，隔天執行死刑，典獄長開恩給他們一個存活的機會。
- 當隔天執行死刑時，每人頭上戴一頂帽子(黑或白)排成一隊伍，在死刑執行前，由隊伍中最後的囚犯開始，每個人可以猜測自己頭上的帽子顏色(只允許說黑或白)，猜對則免除死刑，猜錯則執行死刑。
- 若這些囚犯可以前一天晚上先聚集討論方案，是否有好的方法可以使總共存活的囚犯數量期望值最高？



猜測規則

- 囚犯排成一排，每個人可以看到前面所有人的帽子，但看不到自己及後面囚犯的。
- 由最後一個囚犯開始猜測，依序往前。
- 每個囚犯皆可聽到之前所有囚犯的猜測內容。

Example: 奇數者猜測內容為前面一位的帽子顏色 → 存活期望值為75人

有沒有更多人可以存活的好策略？



Algorithm Design Strategy

- Do not focus on “specific algorithms”
- But “some strategies” to “design” algorithms
- First Skill: Divide-and-Conquer (各個擊破/分治法)
- Second Skill: Dynamic Programming (動態規劃)



Dynamic Programming

Textbook Chapter 15 – Dynamic Programming

Textbook Chapter 15.3 – Elements of dynamic programming



What is Dynamic Programming?

- Dynamic programming, like the divide-and-conquer method, solves problems by combining the solutions to subproblems
 - 用空間換取時間
 - 讓走過的留下痕跡
- “Dynamic”: time-varying
- “Programming”: a *tabular* method

Dynamic Programming: planning over time



Algorithm Design Paradigms

- Divide-and-Conquer
 - partition the problem into **independent** or **disjoint** subproblems
 - repeatedly solving the common subsubproblems
 - more work than necessary
- Dynamic Programming
 - partition the problem into **dependent** or **overlapping** subproblems
 - avoid recomputation
 - ✓ Top-down with memoization
 - ✓ Bottom-up method



Dynamic Programming Procedure

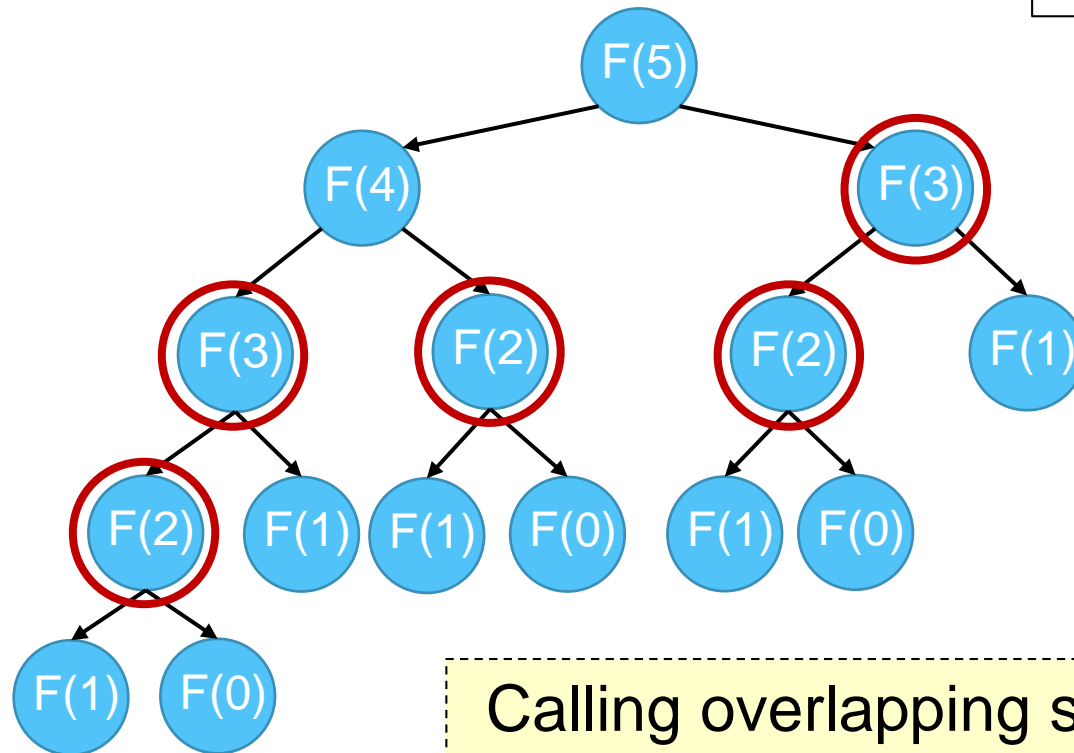
- Apply four steps
 1. Characterize the structure of an optimal solution
 2. **Recursively** define the value of an optimal solution
 3. Compute the value of an optimal solution, typically in a **bottom-up** fashion
 4. Construct an optimal solution from computed information

Rethink Fibonacci Sequence

- Fibonacci sequence (費波那契數列)

- Base case: $F(0) = F(1) = 1$
- Recursive case: $F(n) = F(n-1) + F(n-2)$

```
Fibonacci(n)
  if n < 2 // base case
    return 1
  // recursive case
  return Fibonacci(n-1) + Fibonacci(n-2)
```



✓ F(3) was computed twice

✓ F(2) was computed 3 times

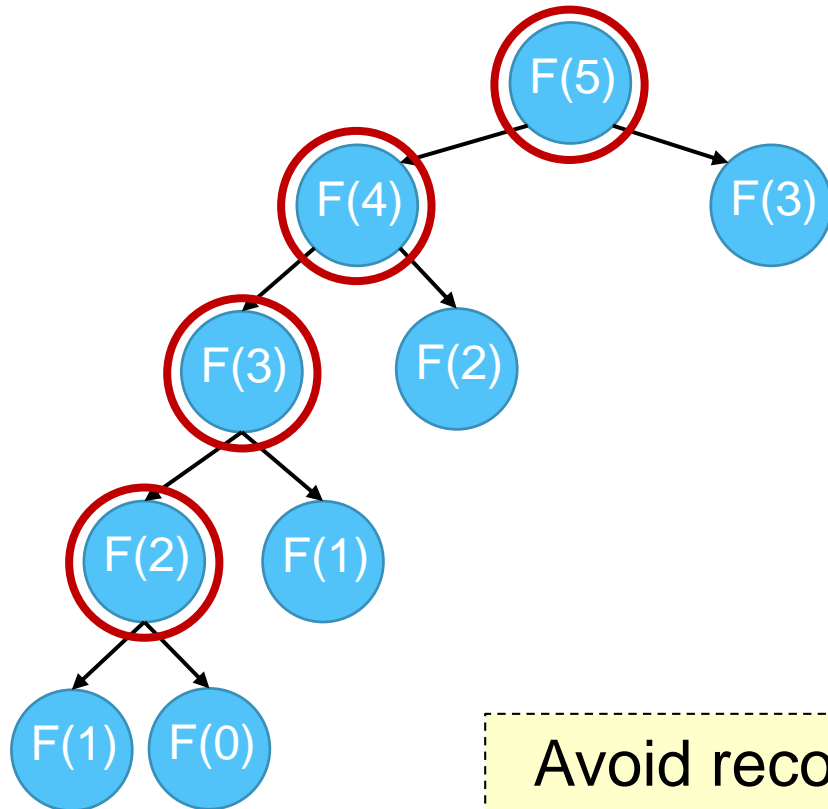
$$T(n) = O(2^n)$$

Calling overlapping subproblems result in poor efficiency

Fibonacci Sequence

Top-Down with Memoization

- Solve the overlapping subproblems recursively with memoization
 - Check the memo before making the calls



n	0	1	2	3	4	5
F(n)	1	1	2	3	5	8



Avoid recomputation of the same subproblems using memo

Fibonacci Sequence

Top-Down with Memoization

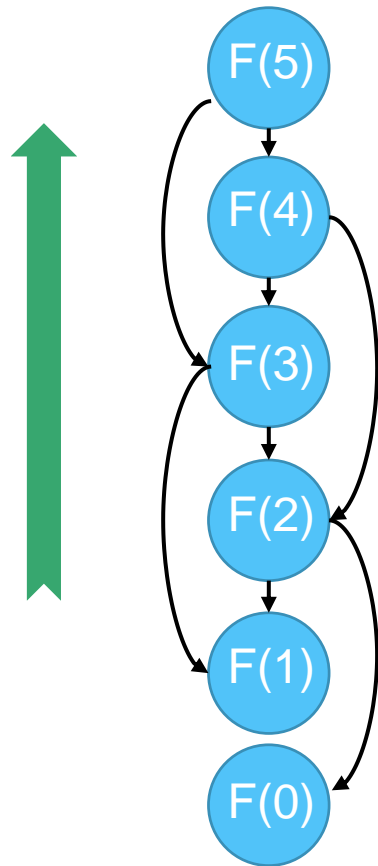
```
Memoized-Fibonacci(n)
    // initialize memo (array a[])
    a[0] = 1
    a[1] = 1
    for i = 2 to n
        a[i] = 0
    return Memoized-Fibonacci-Aux(n, a)

Memoized-Fibonacci-Aux(n, a)
    if a[n] > 0
        return a[n]
    // save the result to avoid recomputation
    a[n] = Memoized-Fibonacci-Aux(n-1, a) + Memoized-Fibonacci-Aux(n-2, a)
    return a[n]
```

Fibonacci Sequence

Bottom-Up Method

- Building up solutions to larger and larger subproblems



```
Bottom-Up-Fibonacci (n)
  if n < 2
    return 1
  a[0] = 1
  a[1] = 1
  for i = 2 ... n
    a[i] = a[i-1] + a[i-2]
  return a[n]
```

Avoid recomputation of the same subproblems

Optimization Problem

- Principle of Optimality
 - Any subpolicy of an optimum policy must itself be an optimum policy with regard to the initial and terminal states of the subpolicy
- Two key properties of DP for optimization
 - **Overlapping subproblems**
 - **Optimal substructure** – an optimal solution can be constructed from optimal solutions to subproblems
 - ✓ Reduce search space (ignore non-optimal solutions)

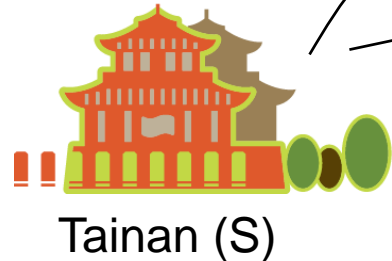
If the optimal substructure (principle of optimality) does not hold, then it is incorrect to use DP

Optimal Substructure Example

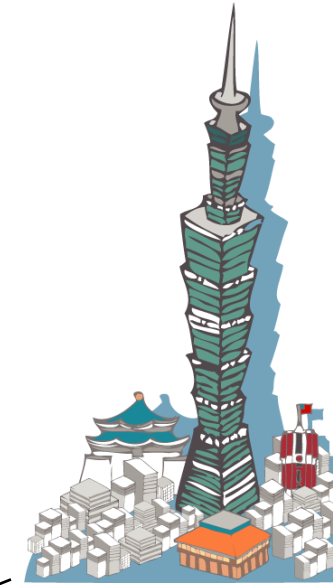
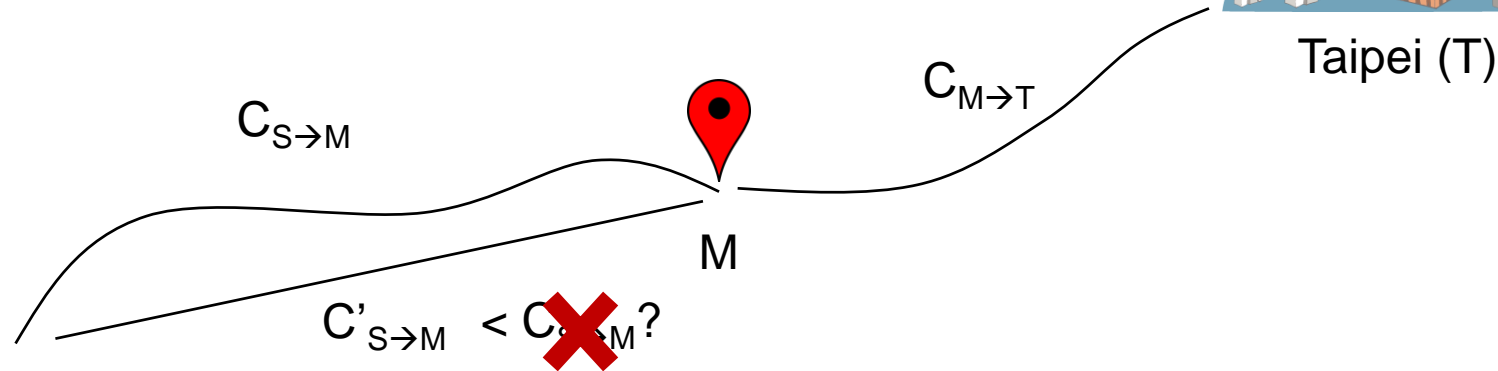
- Shortest Path Problem

- Input: a graph where the edges have positive costs
- Output: a path from S to T with the smallest cost

The path costing $C_{S \rightarrow M} + C_{M \rightarrow T}$ is the shortest path from S to T
→ The path with the cost $C_{S \rightarrow M}$ must be a shortest path from S to M



Tainan (S)



Taipei (T)

Proof by “Cut-and-Paste” argument (proof by contradiction):
Suppose that it exists a path with smaller cost $C'_{S \rightarrow M}$, then we can “cut” $C_{S \rightarrow M}$ and “paste” $C'_{S \rightarrow M}$ to make the original cost smaller



DP#1: Rod Cutting

Textbook Chapter 15.1 – Rod Cutting

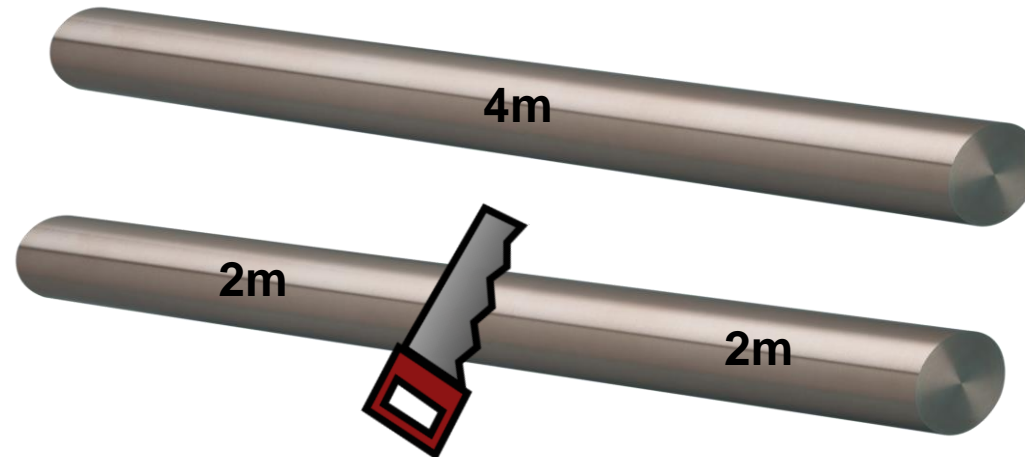


Rod Cutting Problem

- Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

length i (m)	1	2	3	4	5
price p_i	1	5	8	9	10

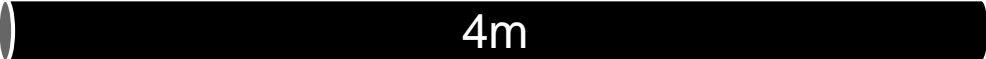







- Output: the maximum revenue r_n obtainable by cutting up the rod and selling the pieces



Brute-Force Algorithm

length i (m)	1	2	3	4	5
price p_i	1	5	8	9	10

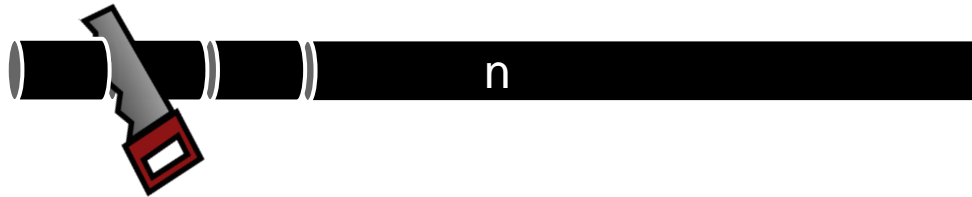
- A rod with the length = 4

	$\rightarrow 9$
	$\rightarrow 8 + 1 = 9$
	$\rightarrow 5 + 5 = 10$
	$\rightarrow 1 + 8 = 9$
	$\rightarrow 5 + 1 + 1 = 7$
	$\rightarrow 1 + 5 + 1 = 7$
	$\rightarrow 1 + 1 + 5 = 7$
	$\rightarrow 1 + 1 + 1 + 1 = 4$

Brute-Force Algorithm

length i (m)	1	2	3	4	5
price p_i	1	5	8	9	10

- A rod with the length = n



- For each integer position, we can choose “cut” or “not cut”
 - There are $n - 1$ positions for consideration
- The total number of cutting results is $2^{n-1} = \Theta(2^{n-1})$



Recursive Thinking

r_n : the maximum revenue obtainable for a rod of length n

- We use a *recursive* function to solve the subproblems
- If we know the answer to the subproblem, can we get the answer to the original problem?



$$r_n = \max(\underbrace{p_n}_{\text{no cut}}, \underbrace{r_1 + r_{n-1}, r_2 + r_{n-2}, \dots, r_{n-1} + r_1}_{\text{cut at the } i\text{-th position (from left to right)}})$$

- Optimal substructure – an optimal solution can be constructed from optimal solutions to subproblems

Recursive Algorithms

- Version 1

$$r_n = \max(\underbrace{p_n}_{\text{no cut}}, \underbrace{r_1 + r_{n-1}, r_2 + r_{n-2}, \dots, r_{n-1} + r_1}_{\text{cut at the } i\text{-th position (from left to right)}})$$

- Version 2

- try to reduce the number of subproblems → focus on the **left-most** cut



$$r_n = \max_{1 \leq i \leq n} (p_i + r_{n-i})$$

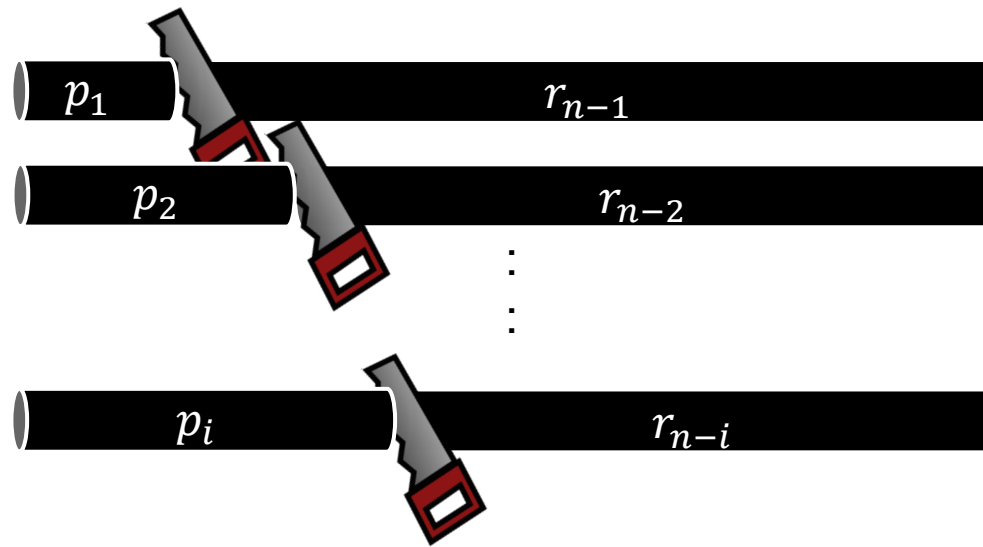
left-most value maximum value obtainable from
the remaining part

Recursive Procedure

- Focus on the left-most cut
 - assume that we always cut **from left to right** → the **first cut**

$$\boxed{r_n} = \max_{1 \leq i \leq n} (p_i + \boxed{r_{n-i}})$$

optimal solution optimal solution to subproblems



Rod cutting problem has optimal substructure

Naïve Recursion Algorithm

$$r_n = \max_{1 \leq i \leq n} (p_i + r_{n-i})$$

```
Cut-Rod(p, n)
// base case
if n == 0
    return 0
// recursive case
q = -∞
for i = 1 to n
    q = max(q, p[i] + Cut-Rod(p, n - i))
return q
```

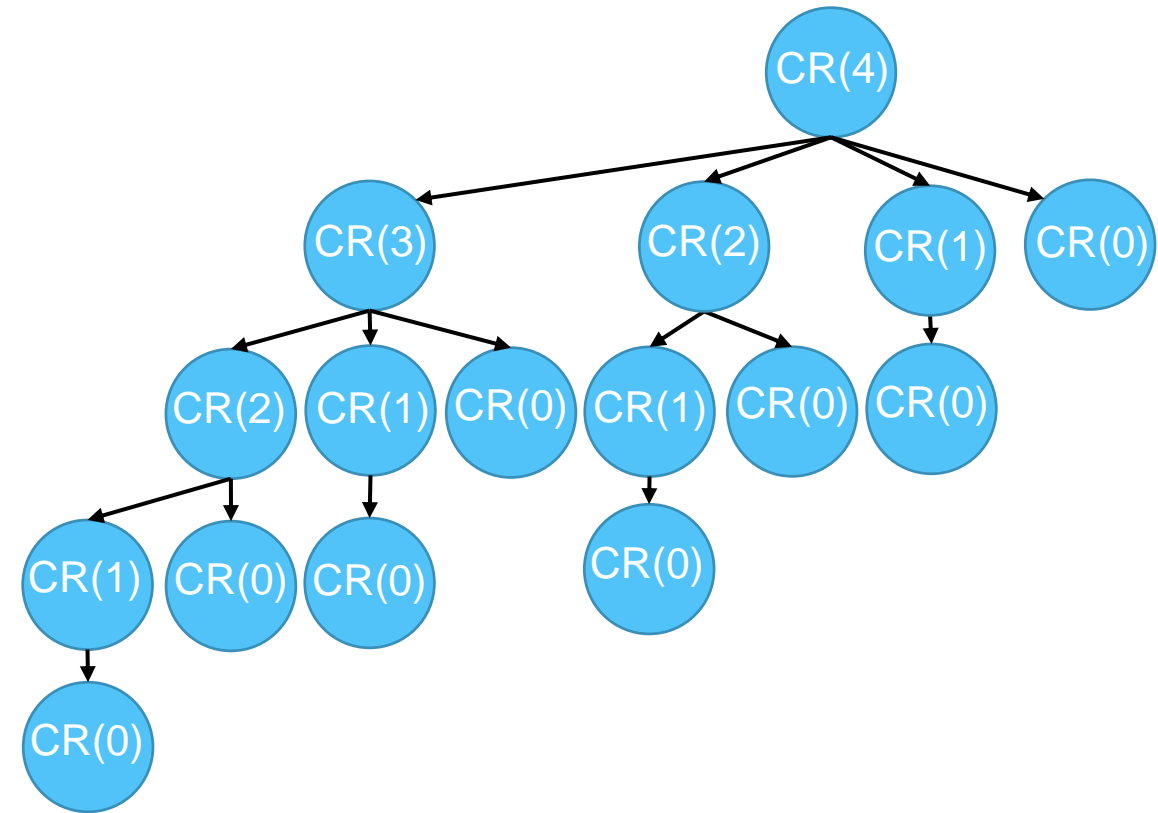
- $T(n)$ = time for running `Cut-Rod(p, n)`

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ \Theta(1) + \sum_{i=0}^{n-1} T(n-i) & \text{if } n \geq 2 \end{cases} \Rightarrow T(n) = \Theta(2^n)$$

Naïve Recursion Algorithm

- Rod cutting problem

```
Cut-Rod(p, n)
    // base case
    if n == 0
        return 0
    // recursive case
    q = -∞
    for i = 1 to n
        q = max(q, p[i] + Cut-Rod(p, n - i))
    return q
```



Calling overlapping subproblems result in poor efficiency

Dynamic Programming

- Idea: use space for better time efficiency
- Rod cutting problem has **overlapping subproblems** and **optimal substructures**
→ can be solved by DP
- When the number of subproblems is polynomial, the time complexity is polynomial using DP
- DP algorithm
 - Top-down: solve overlapping subproblems recursively with memoization
 - Bottom-up: build up solutions to larger and larger subproblems

Dynamic Programming

- Top-Down with Memoization

- Solve recursively and memo the subsolutions (跳著填表)
- Suitable that **not all subproblems should be solved**

$f(0)$	$f(1)$	$f(2)$...	$f(n)$



- Bottom-Up with Tabulation

- Fill the table **from small to large**
- Suitable that **each small problem should be solved**

$f(0)$	$f(1)$	$f(2)$...	$f(n)$



Algorithm for Rod Cutting Problem

Top-Down with Memoization

```
Memoized-Cut-Rod(p, n)
    // initialize memo (an array r[] to keep max revenue)
    r[0] = 0
    for i = 1 to n
        r[i] = -∞ // r[i] = max revenue for rod with length = i
    return Memoized-Cut-Rod-Aux(p, n, r)  $\Theta(n)$ 

Memoized-Cut-Rod-Aux(p, n, r)
    if r[n] >= 0
        return r[n] // return the saved solution  $\Theta(1)$ 
    q = -∞
    for i = 1 to n
        q = max(q, p[i] + Memoized-Cut-Rod-Aux(p, n-i, r))  $\Theta(n^2)$ 
    r[n] = q // update memo
    return q
```

- $T(n)$ = time for running Memoized-Cut-Rod(p, n) $\Rightarrow T(n) = \Theta(n^2)$

Algorithm for Rod Cutting Problem

Bottom-Up with Tabulation

```
Bottom-Up-Cut-Rod(p, n)
  r[0] = 0
  for j = 1 to n // compute r[1], r[2], ... in order
    q = -∞
    for i = 1 to j
      q = max(q, p[i] + r[j - i])
    r[j] = q
  return r[n]
```

$\Theta(n^2)$

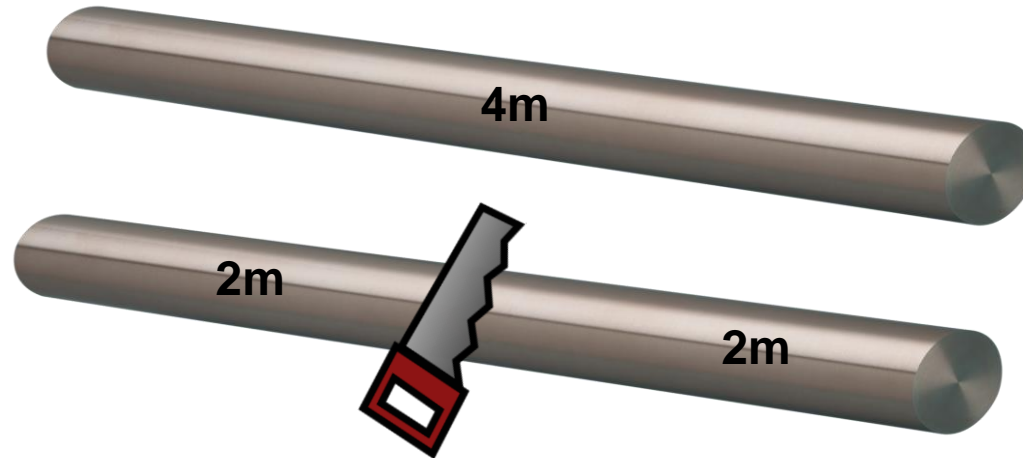
- $T(n)$ = time for running Bottom-Up-Cut-Rod(p, n) $\Rightarrow T(n) = \Theta(n^2)$

Rod Cutting Problem

- Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

length i (m)	1	2	3	4	5
price p_i	1	5	8	9	10

- Output: the maximum revenue r_n obtainable and **the list of cut pieces**



Algorithm for Rod Cutting Problem

Bottom-Up with Tabulation

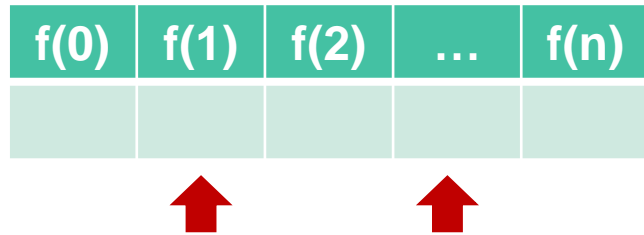
- Add an array to keep the cutting positions **cut**

```
Extended-Bottom-Up-Cut-Rod(p, n)
    r[0] = 0
    for j = 1 to n //compute r[1], r[2], ... in order
        q = -∞
        for i = 1 to j
            if q < p[i] + r[j - i]
                q = p[i] + r[j - i]
                cut[j] = i // the best first cut for len j rod
        r[j] = q
    return r[n], cut
```

```
Print-Cut-Rod-Solution(p, n)
    (r, cut) = Extended-Bottom-up-Cut-Rod(p, n)
    while n > 0
        print cut[n]
        n = n - cut[n] // remove the first piece
```

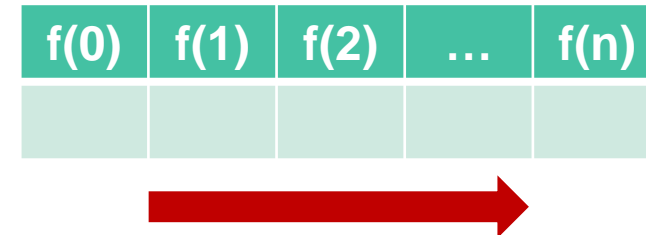
Dynamic Programming

- Top-Down with Memoization

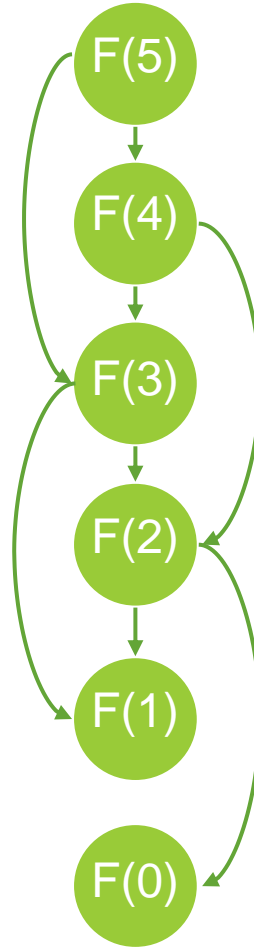


- Better when some subproblems not be solved at all
- Solve only the required parts of subproblems

- Bottom-Up with Tabulation



- Better when all subproblems must be solved at least once
- Typically outperform top-down method by a constant factor
 - No overhead for recursive calls
 - Less overhead for maintaining the table



Informal Running Time Analysis

- Approach 1: approximate via (#subproblems) * (#choices for each subproblem)
 - For rod cutting
 - #subproblems = n
 - #choices for each subproblem = $O(n)$
 - $\rightarrow T(n)$ is about $O(n^2)$
- Approach 2: approximate via subproblem graphs

Subproblem Graphs

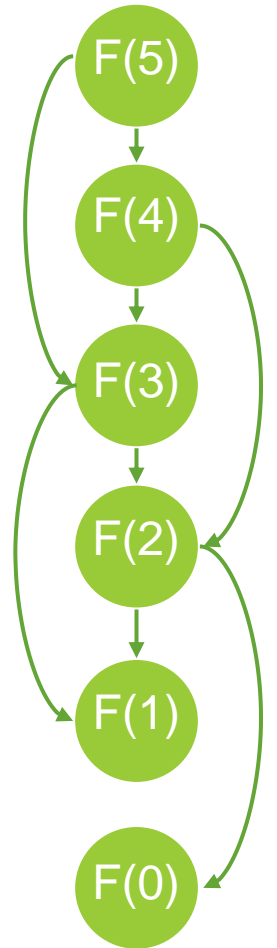
- The size of the subproblem graph allows us to estimate the time complexity of the DP algorithm
- A graph illustrates the set of subproblems involved and how subproblems depend on another $G = (V, E)$ (E: edge, V: vertex)
 - $|V|$: #subproblems
 - A subproblem is run only once
 - $|E|$: sum of #subsubproblems are needed for each subproblem
 - Time complexity: linear to $O(|E| + |V|)$

Top-down: Depth First Search

Bottom-up: Reverse Topological Sort



Graph Algorithm
(taught later)



Dynamic Programming Procedure

1. **Characterize the structure** of an optimal solution
 - ✓ Overlapping subproblems: revisit same subproblems
 - ✓ Optimal substructure: an optimal solution to the problem contains within it optimal solutions to subproblems
2. **Recursively** define the value of an **optimal** solution
 - ✓ Express the solution of the original problem in terms of optimal solutions for subproblems
3. **Compute the value** of an optimal solution
 - ✓ typically in a bottom-up fashion
4. **Construct an optimal solution** from computed information
 - ✓ Step 3 and 4 may be combined

Revisit DP for Rod Cutting Problem

1. Characterize the **structure** of an optimal solution
2. **Recursively** define the value of an **optimal** solution
3. Compute the **value** of an optimal solution
4. Construct an **optimal solution** from computed information

Step 1: Characterize an OPT Solution

Rod Cutting Problem

Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Step 1-Q1: What can be the subproblems?
- Step 1-Q2: Does it exhibit optimal structure? (an optimal solution can be represented by the optimal solutions to subproblems)
 - Yes. \rightarrow continue
 - No. \rightarrow go to Step 1-Q1 or there is no DP solution for this problem

Step 1: Characterize an OPT Solution

Rod Cutting Problem

Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Step 1-Q1: What can be the subproblems?
- Subproblems: $\text{Cut-Rod}(0), \text{Cut-Rod}(1), \dots, \text{Cut-Rod}(n-1)$
 - $\text{Cut-Rod}(i)$: rod cutting problem with length- i rod
 - Goal: $\text{Cut-Rod}(n)$
- Suppose we know the optimal solution to $\text{Cut-Rod}(i)$, there are i cases:
 - Case 1: the first segment in the solution has length 1
從solution中拿掉一段長度為1的鐵條, 剩下的部分是 $\text{Cut-Rod}(i-1)$ 的最佳解
 - Case 2: the first segment in the solution has length 2
從solution中拿掉一段長度為2的鐵條, 剩下的部分是 $\text{Cut-Rod}(i-2)$ 的最佳解
 - :
 - Case i : the first segment in the solution has length i
從solution中拿掉一段長度為 i 的鐵條, 剩下的部分是 $\text{Cut-Rod}(0)$ 的最佳解

Step 1: Characterize an OPT Solution

Rod Cutting Problem

Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Step 1-Q2: Does it exhibit optimal structure? (an optimal solution can be represented by the optimal solutions to subproblems)
- Yes. Prove by contradiction.

Step 2: Recursively Define the Value of an OPT Solution

Rod Cutting Problem

Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Suppose we know the optimal solution to `Cut-Rod(i)`, there are i cases:

- Case 1: the first segment in the solution has length 1

從solution中拿掉一段長度為1的鐵條, 剩下的部分是`Cut-Rod(i-1)`的最佳解

$$r_i = p_1 + r_{i-1}$$

- Case 2: the first segment in the solution has length 2

從solution中拿掉一段長度為2的鐵條, 剩下的部分是`Cut-Rod(i-2)`的最佳解

$$r_i = p_2 + r_{i-2}$$

:

- Case i : the first segment in the solution has length i

從solution中拿掉一段長度為 i 的鐵條, 剩下的部分是`Cut-Rod(0)`的最佳解

$$r_i = p_i + r_0$$

- Recursively define the value
$$r_i = \begin{cases} 0 & \text{if } i = 0 \\ \max_{1 \leq j \leq i} (p_j + r_{i-j}) & \text{if } i \geq 1 \end{cases}$$

Step 3: Compute Value of an OPT Solution

Rod Cutting Problem


Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Bottom-up method: solve smaller subproblems first

$$r_i = \begin{cases} 0 & \text{if } i = 0 \\ \max_{1 \leq j \leq i} (p_j + r_{i-j}) & \text{if } i \geq 1 \end{cases}$$

i	0	1	2	3	4	5	...	n
r[i]								



Bottom-Up-Cut-Rod(p, n)

```
r[0] = 0
for j = 1 to n // compute r[1], r[2], ... in order
    q = -∞
    for i = 1 to j
        q = max(q, p[i] + r[j - i])
    r[j] = q
return r[n]
```

$$T(n) = \Theta(n^2)$$

Step 4: Construct an OPT Solution by Backtracking

length i	1	2	3	4	5
price p_i	1	5	8	9	10

Rod Cutting Problem

Input: a rod of length n and a table of prices p_i for $i = 1, \dots, n$

Output: **the maximum revenue** r_n obtainable

- Bottom-up method: solve smaller subproblems first

$$r_i = \begin{cases} 0 & \text{if } i = 0 \\ \max_{1 \leq j \leq i} (p_j + r_{i-j}) & \text{if } i \geq 1 \end{cases}$$

i	0	1	2	3	4	5	...	n
r[i]	0	1	5	8	10			
cut[i]	0	1	2	3	2			

$$\max(p_1 + r_0)$$

$$\max(p_1 + r_1, p_2 + r_0)$$

$$\max(p_1 + r_2, p_2 + r_1, p_3 + r_0)$$

$$\max(p_1 + r_3, p_2 + r_2, p_3 + r_1, p_4 + r_0)$$

Step 4: Construct an OPT Solution by Backtracking

```
Cut-Rod(p, n)
  r[0] = 0
  for j = 1 to n // compute r[1], r[2], ... in order
    q = -∞
    for i = 1 to j
      if q < p[i] + r[j - i]
        q = p[i] + r[j - i]
        cut[j] = i // the best first cut for len j rod
    r[j] = q
  return r[n], cut
```

$$T(n) = \Theta(n^2)$$

```
Print-Cut-Rod-Solution(p, n)
  (r, cut) = Cut-Rod(p, n)
  while n > 0
    print cut[n]
    n = n - cut[n] // remove the first piece
```

$$T(n) = \Theta(n)$$



DP#2: Stamp Problem

Stamp Problem

- Input: the postage n and the stamps with values v_1, v_2, \dots, v_k



- Output: the minimum number of stamps to cover the postage

A Recursive Algorithm



- The optimal solution S_n can be recursively defined as $1 + \min_i (S_{n-v_i})$

$$1 + \min(S_{n-3}, S_{n-5}, S_{n-7}, S_{n-12})$$

```
Stamp(v, n)
  r_min = ∞
  if n == 0 // base case
    return 0
  for i = 1 to k // recursive case
    r[i] = Stamp(v, n - v[i])
    if r[i] < r_min
      r_min = r[i]
  return r_min + 1
```

$$T(n) = \Theta(k^n)$$



Step 1: Characterize an OPT Solution

Stamp Problem

Input: the postage n and the stamps with values v_1, v_2, \dots, v_k

Output: the minimum number of stamps to cover the postage

- Subproblems
 - $S(i)$: the min #stamps with postage i
 - Goal: $S(n)$
- Optimal substructure: suppose we know the optimal solution to $S(i)$, there are k cases:
 - Case 1: there is a stamp with v_1 in OPT
從solution中拿掉一張郵資為 v_1 的郵票, 剩下的部分是 $S(i-v[1])$ 的最佳解
 - Case 2: there is a stamp with v_2 in OPT
從solution中拿掉一張郵資為 v_2 的郵票, 剩下的部分是 $S(i-v[2])$ 的最佳解
 - :
 - Case k : there is a stamp with v_k in OPT
從solution中拿掉一張郵資為 v_k 的郵票, 剩下的部分是 $S(i-v[k])$ 的最佳解

Step 2: Recursively Define the Value of an OPT Solution

Stamp Problem

Input: the postage n and the stamps with values v_1, v_2, \dots, v_k

Output: the minimum number of stamps to cover the postage

- Suppose we know the optimal solution to $S(i)$, there are k cases:

- Case 1: there is a stamp with v_1 in OPT

從solution中拿掉一張郵資為 v_1 的郵票, 剩下的部分是 $S(i-v[1])$ 的最佳解

$$S_i = 1 + S_{i-v_1}$$

- Case 2: there is a stamp with v_2 in OPT

從solution中拿掉一張郵資為 v_2 的郵票, 剩下的部分是 $S(i-v[2])$ 的最佳解

$$S_i = 1 + S_{i-v_2}$$

:

- Case k : there is a stamp with v_k in OPT

從solution中拿掉一張郵資為 v_k 的郵票, 剩下的部分是 $S(i-v[k])$ 的最佳解

$$S_i = 1 + S_{i-v_k}$$

- Recursively define the value
$$S_i = \begin{cases} 0 & \text{if } i = 0 \\ \min_{1 \leq j \leq k} (1 + S_{i-v_j}) & \text{if } i \geq 1 \end{cases}$$

Step 3: Compute Value of an OPT Solution

Stamp Problem


Input: the postage n and the stamps with values v_1, v_2, \dots, v_k

Output: the minimum number of stamps to cover the postage

- Bottom-up method: solve smaller subproblems first

$$S_i = \begin{cases} 0 & \text{if } i = 0 \\ \min_{1 \leq j \leq k} (1 + S_{i-v_j}) & \text{if } i \geq 1 \end{cases}$$

i	0	1	2	3	4	5	...	n
S[i]								



```
Stamp(v, n)
S[0] = 0
for i = 1 to n // compute r[1], r[2], ... in order
    r_min = ∞
    for j = 1 to k
        if S[i - v[j]] < r_min
            r_min = 1 + S[i - v[j]]
    S[i] = r_min
return S[n]
```

$$T(n) = \Theta(kn)$$

Step 4: Construct an OPT Solution by Backtracking

```
Stamp(v, n)
  S[0] = 0
  for i = 1 to n
    r_min = ∞
    for j = 1 to k
      if S[i - v[j]] < r_min
        r_min = 1 + S[i - v[j]]
        B[i] = j // backtracking for stamp with v[j]
    S[i] = r_min
  return S[n], B
```

$$T(n) = \Theta(kn)$$

```
Print-Stamp-Selection(v, n)
  (S, B) = Stamp(v, n)
  while n > 0
    print B[n]
    n = n - v[B[n]]
```

$$T(n) = \Theta(n)$$



DP#3: Sequence Alignment

Textbook Chapter 15.4 – Longest common subsequence

Textbook Problem 15-5 – Edit distance



Monkey Speech Recognition

- 猴子們各自講話，經過語音辨識系統後，哪一支猴子發出最接近英文字“banana”的語音為優勝者
- How to evaluate the similarity between two sequences?



aeniqadikjaz



svkbrlvpnzanczyqza

banana

Longest Common Subsequence (LCS)

- Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$
 $Y = \langle y_1, y_2, \dots, y_n \rangle$
- Output: longest common subsequence of two sequences
 - The maximum-length sequence of characters that appear left-to-right (but not necessarily a continuous string) in both sequences

$X = \text{banana}$

$Y = \text{aeniqadikjaz}$



$X \rightarrow \text{ba-n--an---a-}$
 $Y \rightarrow \text{-aeniqadikjaz}$

$X = \text{banana}$

$Y = \text{svkbrlvpnzancyqza}$



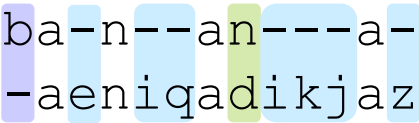



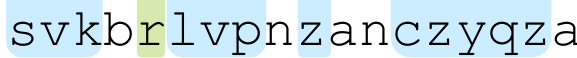
$X \rightarrow \text{---ba---n-an-----a}$
 $Y \rightarrow \text{svkbrlvpnzancyqza}$



The **infinite monkey theorem**: a monkey hitting keys at random for an infinite amount of time will almost surely type a given text

Edit Distance

- Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$
 $Y = \langle y_1, y_2, \dots, y_n \rangle$
- Output: the minimum cost of transformation from X to Y
 - Quantifier of the dissimilarity of two strings

	$X = \text{banana}$		$X = \text{banana}$				
	$Y = \text{aeniqadikjaz}$		$Y = \text{svkbrlvpnzanczyqza}$				
		$X \rightarrow$		$X \rightarrow$			
		$Y \rightarrow$		$Y \rightarrow$			
			1 deletion, 7 insertions, 1 substitution			12 insertions, 1 substitution	

Sequence Alignment Problem

- Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$
 $Y = \langle y_1, y_2, \dots, y_n \rangle$
- Output: the minimal cost $M_{m,n}$ for aligning two sequences
 - Cost = #insertions $\times C_{\text{INS}}$ + #deletions $\times C_{\text{DEL}}$ + #substitutions $\times C_{p,q}$



Step 1: Characterize an OPT Solution

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Subproblems
 - $SA(i, j)$: sequence alignment between prefix strings x_1, \dots, x_i and y_1, \dots, y_j
 - Goal: $SA(m, n)$
- Optimal substructure: suppose OPT is an optimal solution to $SA(i, j)$, there are 3 cases:
 - Case 1: x_i and y_j are aligned in OPT (match or substitution)
 - $OPT/\{x_i, y_j\}$ is an optimal solution of $SA(i-1, j-1)$
 - Case 2: x_i is aligned with a gap in OPT (deletion)
 - OPT is an optimal solution of $SA(i-1, j)$
 - Case 3: y_j is aligned with a gap in OPT (insertion)
 - OPT is an optimal solution of $SA(i, j-1)$

Step 2: Recursively Define the Value of an OPT Solution

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Suppose OPT is an optimal solution to $SA(i, j)$, there are 3 cases:

- Case 1: x_i and y_j are aligned in OPT (match or substitution)

- OPT/ $\{x_i, y_j\}$ is an optimal solution of $SA(i-1, j-1)$

$$M_{i,j} = M_{i-1,j-1} + C_{x_i,y_j}$$

- Case 2: x_i is aligned with a gap in OPT (deletion)

- OPT is an optimal solution of $SA(i-1, j)$

$$M_{i,j} = M_{i-1,j} + C_{\text{DEL}}$$

- Case 3: y_j is aligned with a gap in OPT (insertion)

- OPT is an optimal solution of $SA(i, j-1)$

$$M_{i,j} = M_{i,j-1} + C_{\text{INS}}$$

- Recursively define the value

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

Step 3: Compute Value of an OPT Solution

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Bottom-up method: solve smaller subproblems first

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

X\Y	0	1	2	3	4	5	...	n
0								
1								
:								
m								

$$T(n) = \Theta(mn)$$

Step 3: Compute Value of an OPT Solution

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Bottom-up method: solve smaller subproblems first

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

$$C_{\text{DEL}} = 4, C_{\text{INS}} = 4$$

$$C_{p,q} = 7, \text{ if } p \neq q$$

		a	e	n	i	q	a	d	i	k	j	a	z
X\Y	0	1	2	3	4	5	6	7	8	9	10	11	12
0	0	4	8	12	16	20	24	28	32	36	40	44	48
1	4	7	11	15	19	23	27	31	35	39	43	47	51
2	8	4	8	12	16	20	23	27	31	35	39	43	47
3	12	8	12	8	12	16	20	24	28	32	36	40	44
4	16	12	15	12	15	19	16	20	24	28	32	36	40
5	20	16	19	15	19	22	20	23	27	31	35	39	43
6	24	20	23	19	22	26	22	26	30	34	38	35	39

Step 3: Compute Value of an OPT Solution

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Bottom-up method: solve smaller subproblems first

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

```
Seq-Align(X, Y, CDEL, CINS, Cp,q)  
  for j = 0 to n  
    M[0][j] = j * CINS // |X|=0, cost=|Y|*penalty  
  for i = 1 to m  
    M[i][0] = i * CDEL // |Y|=0, cost=|X|*penalty  
  for i = 1 to m  
    for j = 1 to n  
      M[i][j] = min(M[i-1][j-1]+Cxi,yj, M[i-1][j]+CDEL, M[i][j-1]+CINS)  
  return M[m][n]
```

$$T(n) = \Theta(mn)$$

Step 4: Construct an OPT Solution by Backtracking

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Bottom-up method: solve smaller subproblems first

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

$$C_{\text{DEL}} = 4, C_{\text{INS}} = 4$$

$$C_{p,q} = 7, \text{ if } p \neq q$$

		a	e	n	i	q	a	d	i	k	j	a	z	
X\Y	0	1	2	3	4	5	6	7	8	9	10	11	12	
b a n a n a	0	0	4	8	12	16	20	24	28	32	36	40	44	48
	1	4	7	11	15	19	23	27	31	35	39	43	47	51
	2	8	4	8	12	16	20	23	27	31	35	39	43	47
	3	12	8	12	8	12	16	20	24	28	32	36	40	44
	4	16	12	15	12	15	19	16	20	24	28	32	36	40
	5	20	16	19	15	19	22	20	23	27	31	35	39	43
	6	24	20	23	19	22	26	22	26	30	34	38	35	39

Step 4: Construct an OPT Solution by Backtracking

Sequence Alignment Problem

Input: two sequences $X = \langle x_1, x_2, \dots, x_m \rangle$ $Y = \langle y_1, y_2, \dots, y_n \rangle$

Output: the minimal cost $M_{m,n}$ for aligning two sequences

- Bottom-up method: solve smaller subproblems first

$$M_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(M_{i-1,j-1} + C_{x_i,y_j}, M_{i-1,j} + C_{\text{DEL}}, M_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

Find-Solution(M)

```
if m = 0 or n = 0
    return {}
v = min(M[m-1][n-1] + Cxm,yn, M[m-1][n] + CDEL, M[m][n-1] + CINS)
if v = M[m-1][n] + CDEL // ↑: deletion
    return Find-Solution(m-1, n)
if v = M[m][n-1] + CINS // ←: insertion
    return Find-Solution(m, n-1)
return {(m, n)} ∪ Find-Solution(m-1, n-1) // ↖: match/substitution
```

$$T(n) = \Theta(m + n)$$

Step 4: Construct an OPT Solution by Backtracking

```
Seq-Align(X, Y, CDEL, CINS, Cp,q)
  for j = 0 to n
    M[0][j] = j * CINS // |X|=0, cost=|Y|*penalty
  for i = 1 to m
    M[i][0] = i * CDEL // |Y|=0, cost=|X|*penalty
  for i = 1 to m
    for j = 1 to n
      M[i][j] = min(M[i-1][j-1]+Cxi,yi, M[i-1][j]+CDEL, M[i][j-1]+CINS)
  return M[m][n]
```

$$T(n) = \Theta(mn)$$

```
Find-Solution(M)
  if m = 0 or n = 0
    return {}
  v = min(M[m-1][n-1] + Cxm,yn, M[m-1][n] + CDEL, M[m][n-1] + CINS)
  if v = M[m-1][n] + CDEL // ↑: deletion
    return Find-Solution(m-1, n)
  if v = M[m][n-1] + CINS // ←: insertion
    return Find-Solution(m, n-1)
  return {(m, n)} ∪ Find-Solution(m-1, n-1) // ↖: match/substitution
```

$$T(n) = \Theta(m + n)$$

Space Complexity

- Space complexity

X\Y	0	1	2	3	4	5	...	n
0								
1								
:								
m								

➔ $\Theta(mn)$

- If only keeping the most recent two rows: `Space-Seq-Align(X, Y)`

X\Y	0	1	2	3	...	j	...	n
i - 1								
i								

➔ $\Theta(n)$

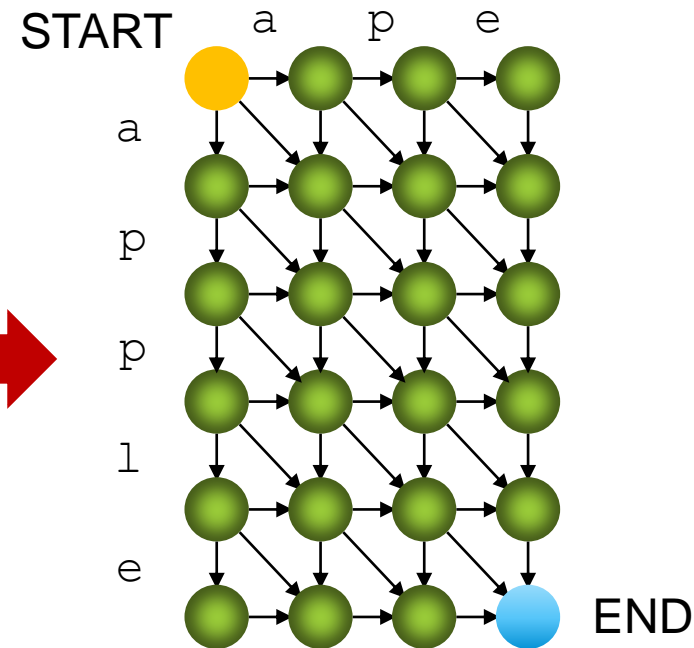
The optimal value can be computed, but the solution cannot be reconstructed

Space-Efficient Solution

Divide-and-Conquer
+
Dynamic
Programming

- Problem: find the min-cost alignment → find the shortest path

			a	p	e
	X\Y	0	1	2	3
	0	0	4	8	12
a	1	4	7	11	15
p	2	8	4	8	12
p	3	12	8	12	8
l	4	16	12	15	12
e	5	20	16	19	15



→ distance = C_{INS}

↓ distance = C_{DEL}

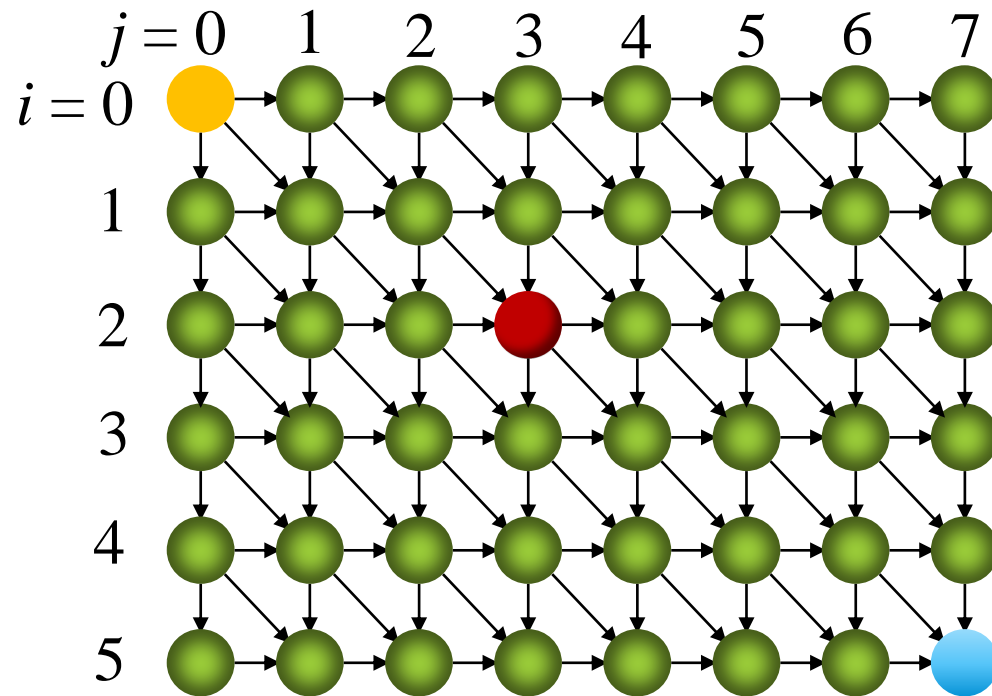
↘ distance = $C_{u,v}$ for edge (u, v)

Shortest Path in Graph

- Each edge has a length/cost
- $F(i, j)$: length of the shortest path from $(0,0)$ to (i, j) (START $\rightarrow (i, j)$)
- $B(i, j)$: length of the shortest path from (i, j) to (m, n) ($(i, j) \rightarrow$ END)
- $F(m, n) = B(0,0)$

$F(2,3)$ = distance of the shortest path  \rightarrow 

$B(2,3)$ = distance of the shortest path  \rightarrow 



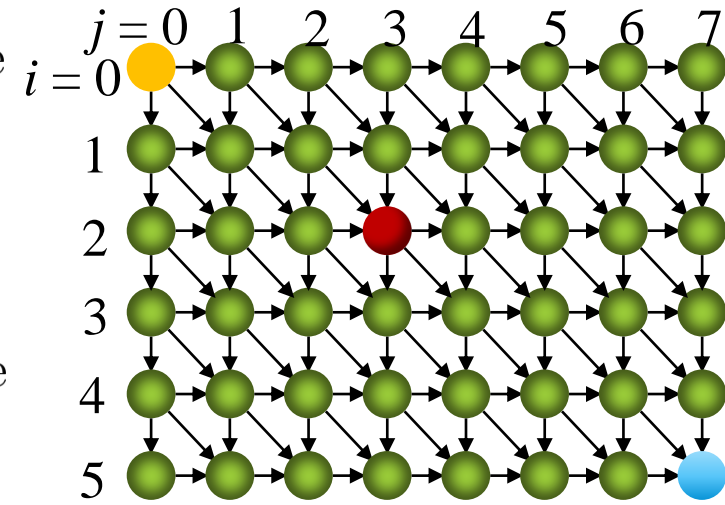
Recursive Equation

- Each edge has a length/cost
- $F(i, j)$: length of the shortest path from $(0,0)$ to (i, j) (START $\rightarrow (i, j)$)
- $B(i, j)$: length of the shortest path from (i, j) to (m, n) ($(i, j) \rightarrow$ END)
- Forward formulation

$$F_{i,j} = \begin{cases} jC_{\text{INS}} & \text{if } i = 0 \\ iC_{\text{DEL}} & \text{if } j = 0 \\ \min(F_{i-1,j-1} + C_{x_i,y_j}, F_{i-1,j} + C_{\text{DEL}}, F_{i,j-1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$

- Backward formulation

$$B_{i,j} = \begin{cases} (n - j)C_{\text{INS}} & \text{if } i = 0 \\ (m - i)C_{\text{DEL}} & \text{if } j = 0 \\ \min(B_{i+1,j+1} + C_{x_i,y_j}, B_{i+1,j} + C_{\text{DEL}}, B_{i,j+1} + C_{\text{INS}}) & \text{otherwise} \end{cases}$$



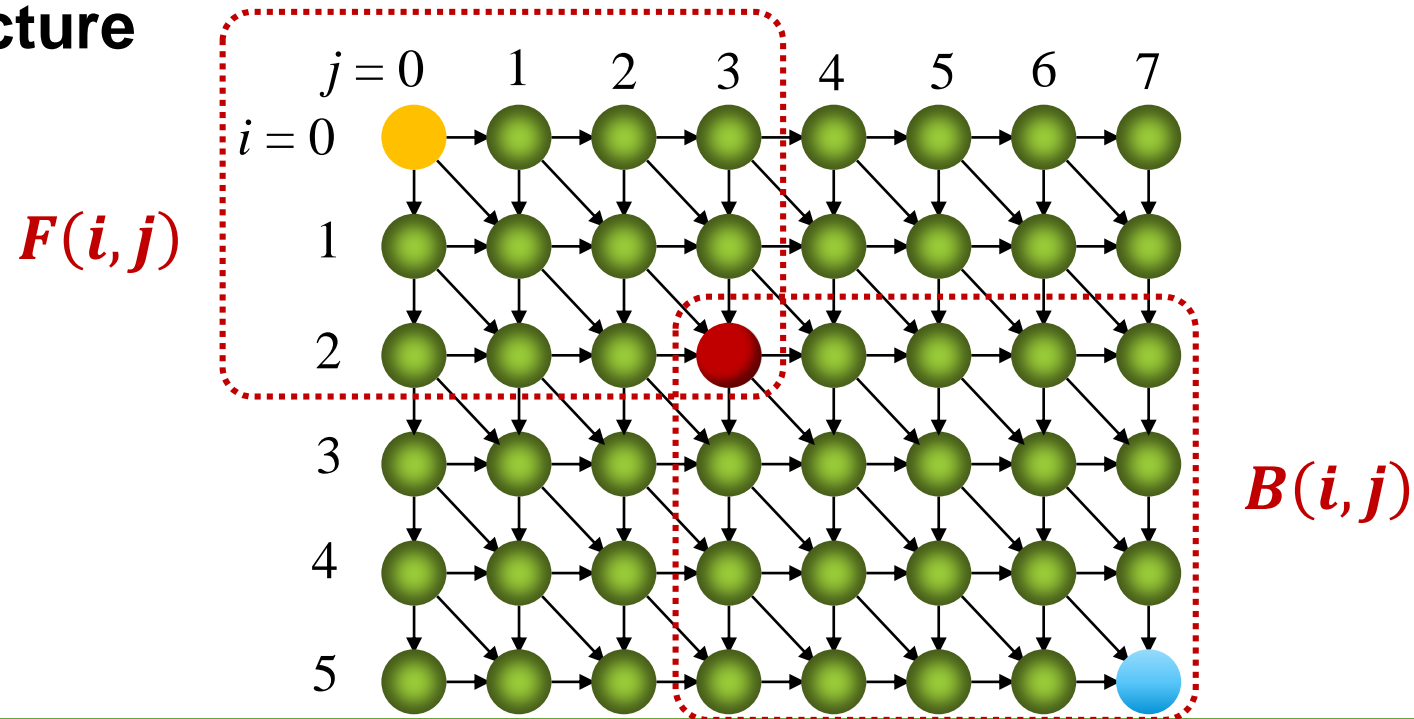
Shortest Path Problem

$F(i, j)$: length of the shortest path from $(0,0)$ to (i, j)

$B(i, j)$: length of the shortest path from (i, j) to (m, n)

- Observation 1: the length of the shortest path from $(0,0)$ to (m, n) that passes through (i, j) is $F(i, j) + B(i, j)$

→ **optimal substructure**



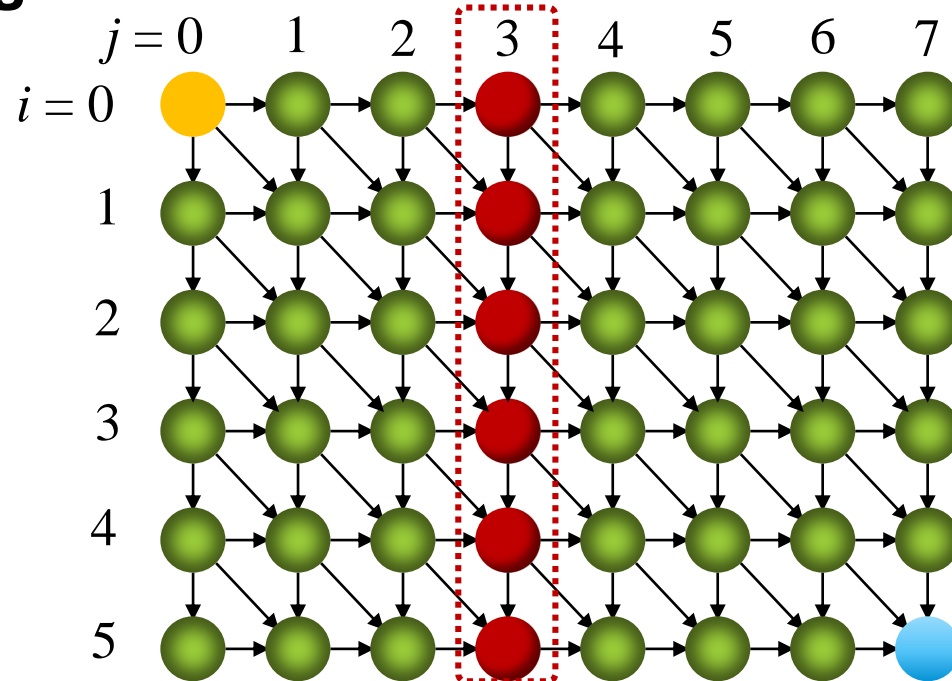
Shortest Path Problem

$F(i, j)$: length of the shortest path from $(0,0)$ to (i, j)

$B(i, j)$: length of the shortest path from (i, j) to (m, n)

- Observation 2: for any v in $\{0, \dots, n\}$, there exists a u s.t. the shortest path between $(0,0)$ and (m, n) goes through (u, v)

→ the shortest path must go across a vertical cut



Shortest Path Problem

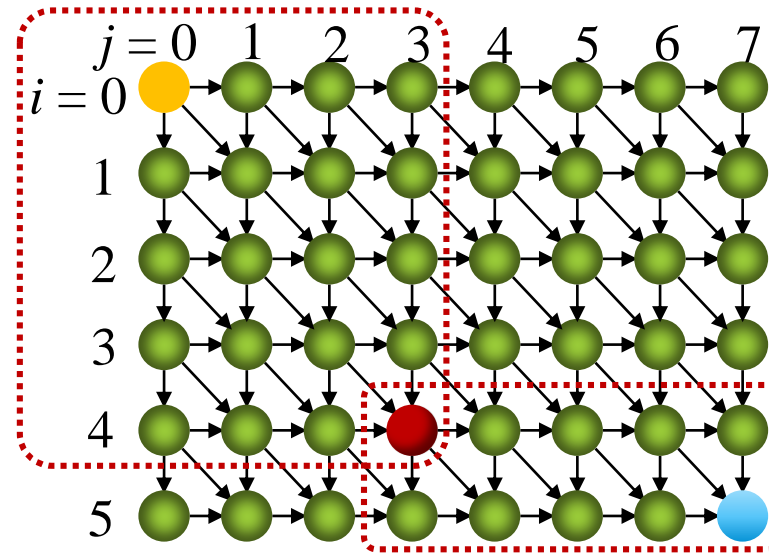
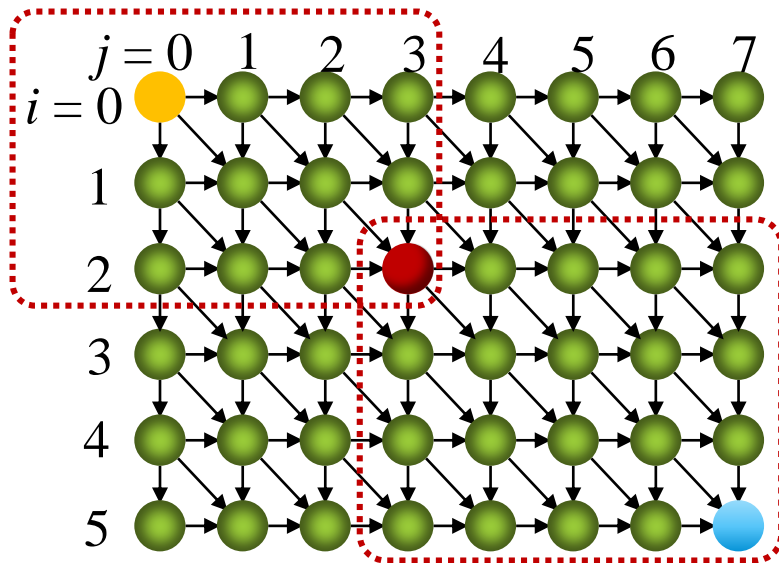
$F(i, j)$: length of the shortest path from $(0, 0)$ to (i, j)

$B(i, j)$: length of the shortest path from (i, j) to (m, n)

- Observation 1+2:

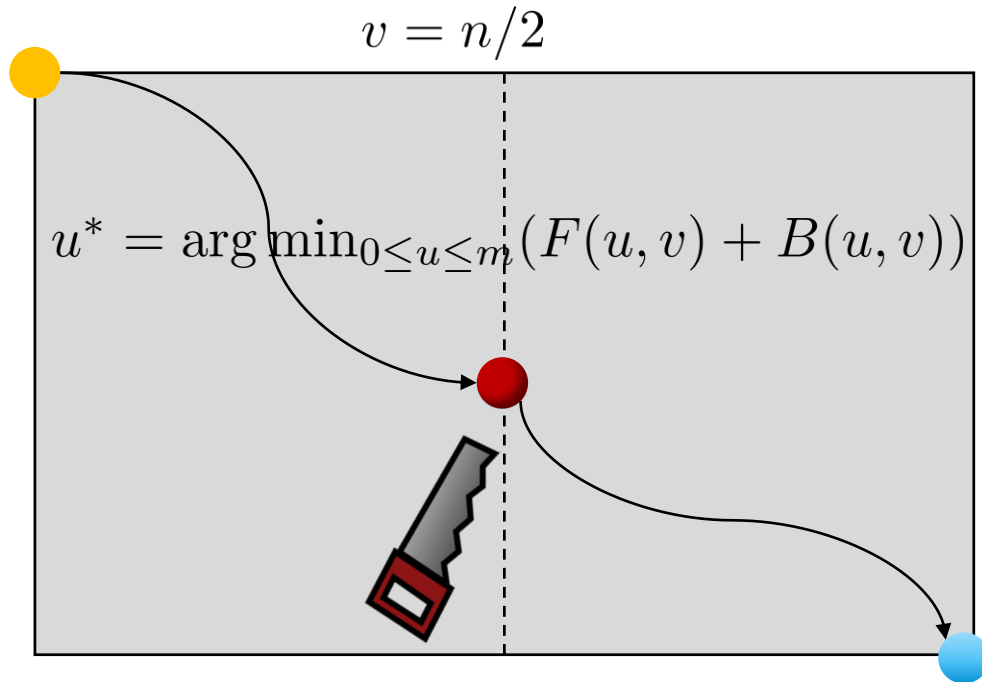
$$F(m, n) = \min (F(0, v) + B(0, v), F(1, v) + B(1, v), \dots, F(m, v) + B(m, v))$$

$$F(m, n) = \min_{0 \leq u \leq m} F(u, v) + B(u, v) \forall v$$



Divide-and-Conquer Algorithm

- Goal: finds optimal solution



How to find the value of u^* ?

- Idea: utilize sequence alignment algo.
 - Call `Space-Seq-Align(X, Y[1:v])` to find $F(0, v), F(1, v), \dots, F(m, v)$
 - Call `Back-Space-Seq-Align(X, Y[v+1:n])` to find $B(0, v), B(1, v), \dots, B(m, v)$
 - Let u be the index minimizing $F(u, v) + B(u, v)$

$$\Theta(m \times \frac{n}{2})$$

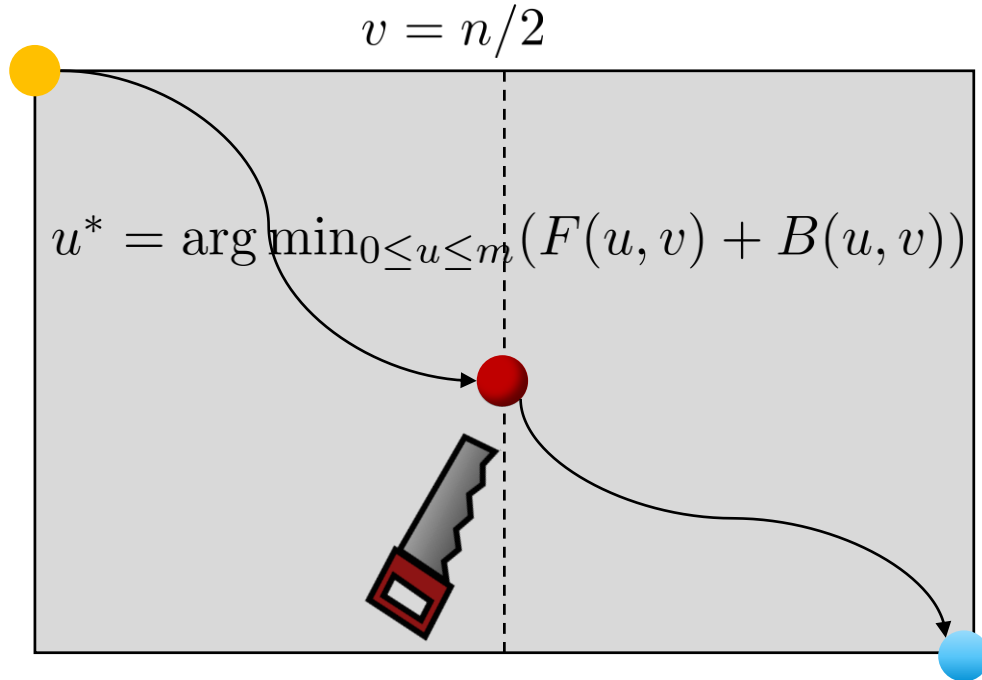
$$\Theta(m \times \frac{n}{2})$$

$$\Theta(m)$$



Divide-and-Conquer Algorithm

- Goal: finds optimal solution – $\text{DC-Align}(X, Y)$ Space Complexity: $O(m + n)$



1. Divide

2. Conquer

3. Combine

- Divide the sequence of size n into 2 subsequences

- Find u to minimize $F(u, v) + B(u, v)$

- Recursive case ($n > 1$) $\Theta(mn)$

- prefix $T(u, \frac{n}{2})$
 $= \text{DC-Align}(X[1:u], Y[1:v])$

- suffix $T(m - u, \frac{n}{2})$
 $= \text{DC-Align}(X[u+1:m], Y[v+1:n])$

- Base case ($n = 1$) $\Theta(m)$

- Return $\text{Seq-Align}(X, Y)$

- Return prefix + suffix $\Theta(1)$

- $T(m, n)$ = time for running $\text{DC-Align}(X, Y)$ with $|X| = m, |Y| = n$

$$T(m, n) = \begin{cases} O(m) & \text{if } n = 1 \\ T(u, n/2) + T(m - u, n/2) + O(mn) & \text{if } n \geq 2 \end{cases} \Rightarrow T(m, n) = O(mn)$$

Time Complexity Analysis

- Theorem

$$T(m, n) = \begin{cases} O(m) & \text{if } n = 1 \\ T(u, n/2) + T(m - u, n/2) + O(mn) & \text{if } n \geq 2 \end{cases} \Rightarrow T(m, n) = O(mn)$$

- Proof

- There exists positive constants a, b s.t. all

$$T(m, n) \leq \begin{cases} a \cdot m & \text{if } n = 1 \\ T(u, n/2) + T(m - u, n/2) + b \cdot mn & \text{if } n \geq 2 \end{cases}$$

- Use induction to prove $T(m, n) \leq kmn$

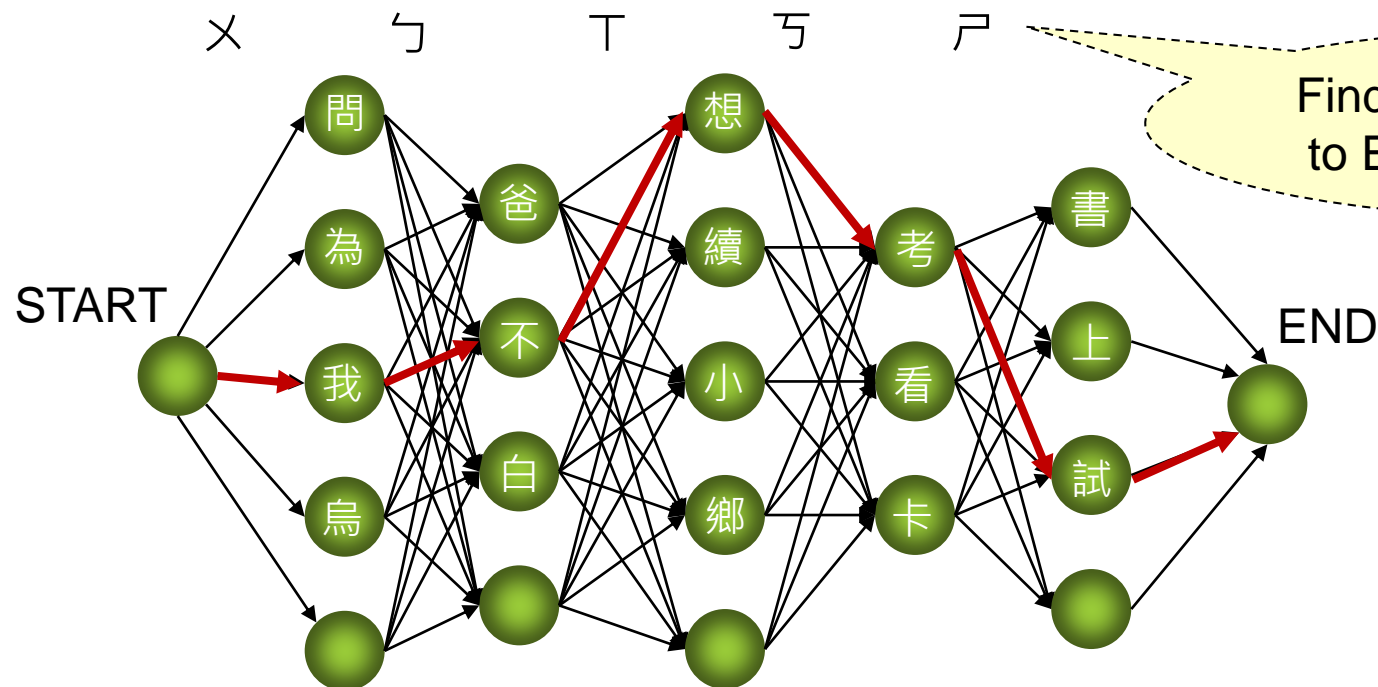
Practice to check the initial condition

$$T(m, n) \leq T(u, \frac{n}{2}) + T(m - u, \frac{n}{2}) + b \cdot mn$$

$$\begin{aligned} \text{Inductive hypothesis } &\leq ku \frac{n}{2} + k(m - u) \frac{n}{2} + b \cdot mn \\ &\leq (\frac{k}{2} + b)mn \\ &\leq kmn \text{ when } k \geq 2b \end{aligned}$$

Extension: 注音文 Recognition

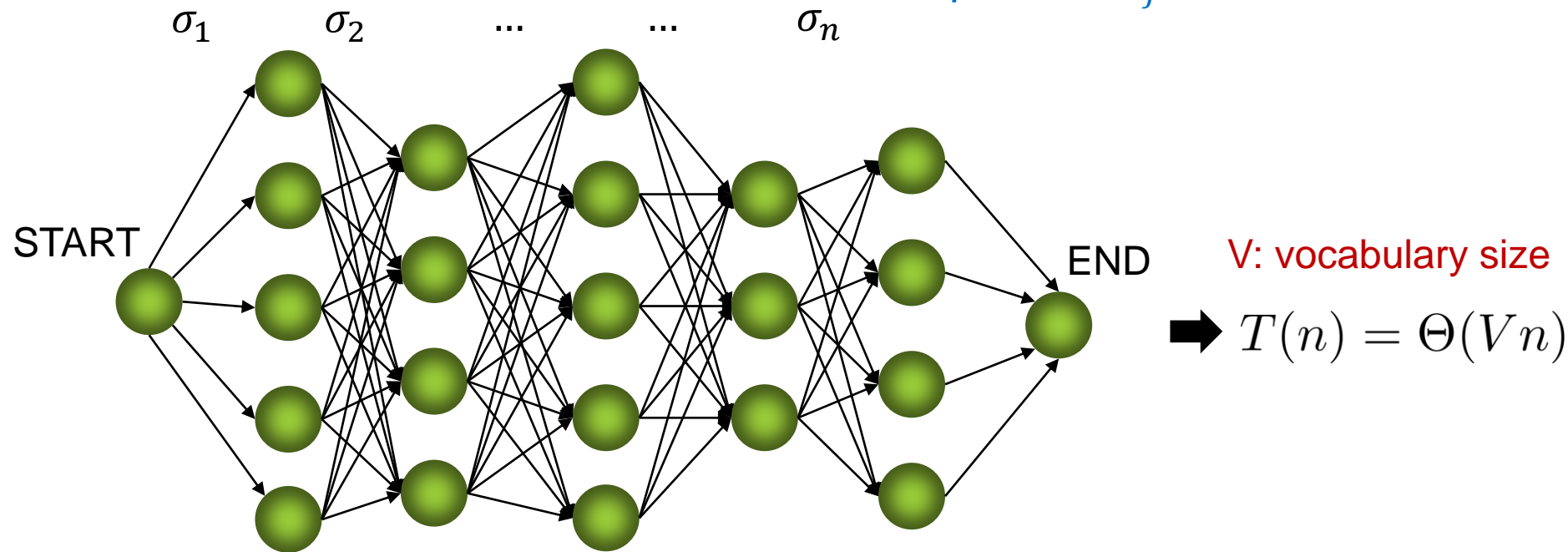
- Given a graph $G = (V, E)$, each edge $(u, v) \in E$ has an associated non-negative probability $p(u, v)$ of traversing the edge (u, v) and producing the corresponding character. Find the most probable path with the label $s = \langle \sigma_1, \sigma_2, \dots, \sigma_n \rangle$.



Find the path from START to END with highest prob

Viterbi Algorithm

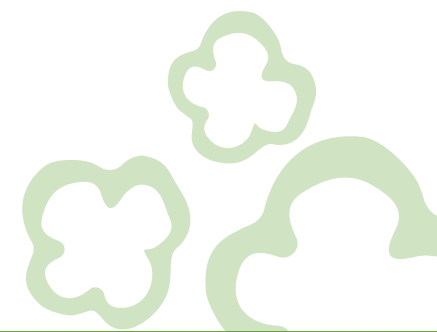
$$P_{i,j} = \begin{cases} \text{produce } \sigma_1 \\ p(\text{START}, v) & \text{if } j = 1 \\ \max_k (P_{k,j-1} \times \text{produce } \sigma_j \\ p(u, v)) & \text{otherwise} \end{cases}$$



Viterbi has been applied to many AI applications, e.g. speech recognition



To Be Continued...





Question?

Important announcement will be sent to
@ntu.edu.tw mailbox & post to the course website

Course Website: <http://ada.miulab.tw>

Email: ada-ta@csie.ntu.edu.tw