National Taiwan University 國立臺灣大學 MIULAB •

DogeRM: Equipping Reward Models with Domain Knowledge through Model Merging Tzu-Han Lin, Chen-An Li, Hung-yi Lee, Yun-Nung (Vivian) Chen

National Taiwan University



Motivation

 Collecting preference data for RM training is costly, especially for *domain-specific* preference data requiring domain experts.

Paper Idea

 $\mathcal{P}\mathcal{A}$

• Domain-specific instruction-tuning data are relatively more accessible to domain-specific preference data.

Summary

- Merging RMs with domain LM enhance RM performance on various benchmarks.
- DogeRM can generalize to different benchmarks and model architectures.

Different Model / Multiple Domain

- **Model Merging** combines multiple single-domain LMs \bullet into a multi-domain LM without extra training.
- RQ: Can we merge classifier-based RMs with domain-specific LM to integrate domain knowledge?

Domain Knowledge LM + RM = DogeRM!

SFT RM Instruction+Response x (1- λ) Solve 2x+3=8 Ö Step1: 2x=5 Step2: x=5/2Step3: x=1 Instruction+Response Answer: 1 4.95 Solve 2x+3=8) Scalar ö Step1: 2x=5 **Domain RM** Reward Pretrained Step2: x=5/2Merge Step3: x=1 Answer: 1 Score

DogeRM can be applied to different model architecture!

Madal	Rewar	d Bench	Auto-	J Eval	Best-of-16	
Niodel	Code	Math	Code	Math	GSM8K	
Mistral RM	93.5	55.0	88.1	87.5	44.2	
+ MAmmoTH2-Plus	92.6	85.0	88.1	90.6	46.6	

DogeRM can effectively integrate multiple domains!

Model	Reward Bench		Auto-	J Eval	Best-of-16		
	Code	Math	Code	Math	GSM8K	MBPP	
LLaMA-2 RM	78.9	68.2	76.2	84.2	35.3	17.2	
+ Math & Code	83.0	85.2	81.0	87.5	39.5	17.0	



X @tzuhan_0316





- Starting from the same pre-trained model, we finetune a general classifier-based RM.
- With Domain SFT LMs, we can adopt any model merging techniques to obtain Domain RM!

Experimental Results

DogeRM is effective across different benchmarks!

	Reward Bench					Auto-J Eval			Best-of-16	
Model	Chat	Chat-Hard	Safety	Reasoning		Cada	N / - +1-	Others	COMON	
				Code	Math	Code	Math	Others	G2M9V	MBPP
(a) LLaMA-2 RM	95.8	47.6	44.6	78.9	68.2	76.2	84.4	79.2	35.3	17.2
(b) FT on Auto-J Math	94.7	48.5	44.4	79.1	68.7	76.2†	90.2 [†]	79.2 [†]	35.2	_
(c) FT on Auto-J Code	94.7	48.2	44.3	78.8	66.9	89.3 †	84.4†	79. 4 [†]	-	17.2
(d) Ours (+ MetaMath)	95.8	44.5	43.5	85.7	79.6	79.8	87.5	79.3	40.7	_
(e) Ours (+ MAmmoTH)	96.1	44.7	43.8	84.1	85.2	79.8	87.5	79.7	40.5	-
(f) Ours (+ Code Model)	96.1	45.6	43.9	84.3	71.8	82.1	87.5	79.7	-	17.2

0.05

Scalar

Reward

