Product of Geometric Brownian Motion Processes

• Let

\[
\frac{dY}{Y} = a \, dt + b \, dW_Y, \\
\frac{dZ}{Z} = f \, dt + g \, dW_Z.
\]

• Assume \(dW_Y\) and \(dW_Z\) have correlation \(\rho\).

• Consider the Ito process

\[ U \overset{\Delta}{=} YZ. \]
Product of Geometric Brownian Motion Processes (continued)

- Apply Ito’s lemma (Theorem 20 on p. 611):

\[ dU = Z \, dY + Y \, dZ + dY \, dZ \]
\[ = ZY(a \, dt + b \, dW_Y) + YZ(f \, dt + g \, dW_Z) + YZ(a \, dt + b \, dW_Y)(f \, dt + g \, dW_Z) \]
\[ = U(a + f + bg\rho) \, dt + UbdW_Y + Ug \, dW_Z. \]

- The product of correlated geometric Brownian motion processes thus remains geometric Brownian motion.
Product of Geometric Brownian Motion Processes (continued)

- Note that

\[
Y = \exp \left[ (a - b^2/2) \, dt + b \, dW_Y \right],
\]
\[
Z = \exp \left[ (f - g^2/2) \, dt + g \, dW_Z \right],
\]
\[
U = \exp \left[ (a + f - (b^2 + g^2)/2) \, dt + b \, dW_Y + g \, dW_Z \right].
\]

- There is no \( bg \rho \) term in \( U \)!

- The strong solutions are:

\[
Y(t) = \exp \left[ (a - b^2/2) \, t + b \, W_Y(t) \right],
\]
\[
Z(t) = \exp \left[ (f - g^2/2) \, t + g \, W_Z(t) \right],
\]
\[
U(t) = \exp \left[ (a + f - (b^2 + g^2)/2) \, t + b \, dW_Y + g \, W_Z(t) \right].
\]
Product of Geometric Brownian Motion Processes (concluded)

- $\ln U$ is Brownian motion with a mean equal to the sum of the means of $\ln Y$ and $\ln Z$.
- This holds even if $Y$ and $Z$ are correlated.
- Finally, $\ln Y$ and $\ln Z$ have correlation $\rho$. 
Quotients of Geometric Brownian Motion Processes

• Suppose $Y$ and $Z$ are drawn from p. 618.

• Let

$$U \triangleq Y/Z.$$ 

• We now show that\(^a\)

$$\frac{dU}{U} = (a - f + g^2 - bg\rho) \, dt + b \, dW_Y - g \, dW_Z.$$ 

(83)

• Keep in mind that $dW_Y$ and $dW_Z$ have correlation $\rho$.

\(^a\)Exercise 14.3.6 of the textbook is erroneous.
Quotients of Geometric Brownian Motion Processes (concluded)

- The multidimensional Ito’s lemma (Theorem 20 on p. 611) can be employed to show that

\[
\begin{align*}
dU &= (1/Z) dY - (Y/Z^2) dZ - (1/Z^2) dY dZ + (Y/Z^3) (dZ)^2 \\
&= (1/Z) (aY dt + bY dW_Y) - (Y/Z^2) (fZ dt + gZ dW_Z) \\
&\quad - (1/Z^2) (bgYZ\rho dt) + (Y/Z^3) (g^2 Z^2 dt) \\
&= U(a dt + b dW_Y) - U(f dt + g dW_Z) \\
&\quad - U(bg\rho dt) + U(g^2 dt) \\
&= U(a - f + g^2 - bg\rho) dt + Ub dW_Y - Ug dW_Z.
\end{align*}
\]
Forward Price

• Suppose $S$ follows

$$\frac{dS}{S} = \mu \, dt + \sigma \, dW.$$ 

• Consider functional $F(S, t) \triangleq S e^{y(T-t)}$ for constants $y$ and $T$.

• As $F$ is a function of two variables, we need the various partial derivatives of $F(S, t)$ with respect to $S$ and $t$.

• Note that in partial differentiation with respect to one variable, other variables are held constant.\(^a\)

\(^a\)Contributed by Mr. Sun, Ao (R05922147) on April 26, 2017.
Forward Prices (continued)

• Now,

\[ \frac{\partial F}{\partial S} = e^{y(T-t)}, \]
\[ \frac{\partial^2 F}{\partial S^2} = 0, \]
\[ \frac{\partial F}{\partial t} = -ySe^{y(T-t)}. \]

• Then\(^a\)

\[ dF = e^{y(T-t)} dS - ySe^{y(T-t)} dt \]
\[ = Se^{y(T-t)} (\mu dt + \sigma dW) - ySe^{y(T-t)} dt \]
\[ = F(\mu - y) dt + F\sigma dW. \]

\(^a\)One can also prove it by Eq. (81) on p. 610.
Forward Prices (concluded)

• Thus $F$ follows

$$\frac{dF}{F} = (\mu - y) \, dt + \sigma \, dW.$$ 

• This result has applications in forward and futures contracts.

• In Eq. (57) on p. 487, $\mu = r = y$.

• So

$$\frac{dF}{F} = \sigma \, dW,$$

a martingale.\(^\text{a}\)

\(^\text{a}\)It is also consistent with p. 563. Furthermore, it explains why Black’s formulas (65)–(66) on p. 515 use the same volatility $\sigma$ as the stock’s.
Ornstein-Uhlenbeck (OU) Process

- The OU process:

\[ dX = -\kappa X \, dt + \sigma \, dW, \]

where \( \kappa, \sigma \geq 0. \)

- For \( t_0 \leq s \leq t \) and \( X(t_0) = x_0 \), it is known that

\[
E[X(t)] = e^{-\kappa(t-t_0)} E[x_0],
\]

\[
\text{Var}[X(t)] = \frac{\sigma^2}{2\kappa} \left( 1 - e^{-2\kappa(t-t_0)} \right) + e^{-2\kappa(t-t_0)} \text{Var}[x_0],
\]

\[
\text{Cov}[X(s), X(t)] = \frac{\sigma^2}{2\kappa} e^{-\kappa(t-s)} \left[ 1 - e^{-2\kappa(s-t_0)} \right]
+ e^{-\kappa(t+s-2t_0)} \text{Var}[x_0].
\]
Ornstein-Uhlenbeck Process (continued)

- $X(t)$ is normally distributed if $x_0$ is a constant or normally distributed.
  - $E[x_0] = x_0$ and $\text{Var}[x_0] = 0$ if $x_0$ is a constant.

- $X$ is said to be a normal process.

- The OU process has the following mean-reverting property if $\kappa > 0$.
  - When $X > 0$, $X$ is pulled toward zero.
  - When $X < 0$, it is pulled toward zero again.
Ornstein-Uhlenbeck Process (continued)

- A generalized version:

\[ dX = \kappa(\mu - X) \, dt + \sigma \, dW, \]

where \( \kappa, \sigma \geq 0 \).

- Given \( X(t_0) = x_0 \), a constant, it is known that

\[
E[X(t)] = \mu + (x_0 - \mu) e^{-\kappa(t-t_0)}, \tag{84}
\]

\[
\text{Var}[X(t)] = \frac{\sigma^2}{2\kappa} \left[ 1 - e^{-2\kappa(t-t_0)} \right],
\]

for \( t_0 \leq t \).
Ornstein-Uhlenbeck Process (concluded)

• The mean and standard deviation are roughly $\mu$ and $\sigma/\sqrt{2\kappa}$, respectively.

• For large $t$, the probability of $X < 0$ is extremely unlikely in any finite time interval when $\mu > 0$ is large relative to $\sigma/\sqrt{2\kappa}$.

• The process is mean-reverting.
  – $X$ tends to move toward $\mu$.
  – Useful for modeling term structure, stock price volatility, and stock price return.$^a$

$^a$See Knutson, Wimmer, Kuhnen, & Winkielman (2008) for the biological basis for mean reversion in financial decision making.
Square-Root Process

- Suppose $X$ is an OU process.

- Consider $V \triangleq X^2$.

- Ito’s lemma says $V$ has the differential,

  
  \[
  dV = 2X \, dX + (dX)^2 \\
  = 2\sqrt{V} (\kappa \sqrt{V} \, dt + \sigma \, dW) + \sigma^2 \, dt \\
  = (-2\kappa V + \sigma^2) \, dt + 2\sigma \sqrt{V} \, dW,
  \]

  a square-root process.
Square-Root Process (continued)

• In general, the square-root process has the SDE,

\[ dX = \kappa(\mu - X)\,dt + \sigma \sqrt{X}\,dW, \]

where \( \kappa, \sigma > 0, \mu \geq 0, \) and \( X(0) \geq 0 \) is a constant.

• Like the OU process, it possesses mean reversion: \( X \) tends to move toward \( \mu \), but the volatility is proportional to \( \sqrt{X} \) instead of a constant.
Square-Root Process (continued)

- When $X$ hits zero and $\mu \geq 0$, the probability is one that it will not move below zero.
  - Zero is a reflecting boundary.

- Hence, the square-root process is a good candidate for modeling interest rates.$^a$

- The OU process, in contrast, allows negative interest rates.$^b$

- The two processes are related, however.$^c$

---

$^a$Cox, Ingersoll, & Ross (1985).
$^b$Some rates did go negative in Europe in 2015.
$^c$Recall p. 631.
Square-Root Process (concluded)

• The random variable $2cX(t)$ follows the noncentral chi-square distribution,\(^a\)

$$\chi \left( \frac{4\kappa \mu}{\sigma^2}, 2cX(0) e^{-\kappa t} \right),$$

where $c \triangleq (2\kappa/\sigma^2)(1 - e^{-\kappa t})^{-1}$ and $\mu > 0$.

• Given $X(0) = x_0$, a constant,

$$E[X(t)] = x_0 e^{-\kappa t} + \mu (1 - e^{-\kappa t}),$$

$$\text{Var}[X(t)] = x_0 \frac{\sigma^2}{\kappa} (e^{-\kappa t} - e^{-2\kappa t}) + \mu \frac{\sigma^2}{2\kappa} (1 - e^{-\kappa t})^2,$$

for $t \geq 0$.

Modeling Stock Prices

- The most popular stochastic model for stock prices has been the geometric Brownian motion,

\[ \frac{dS}{S} = \mu \, dt + \sigma \, dW. \]

- The logarithmic price \( X \triangleq \ln S \) follows

\[ dX = \left( \mu - \frac{\sigma^2}{2} \right) \, dt + \sigma \, dW \]

by Ito’s lemma.\(^a\)

\(^a\)Recall Eq. (82) on p. 614. Consistent with Lemma 9 (p. 297).
Local-Volatility Models

• The deterministic-volatility model for “smile” posits

\[
\frac{dS}{S} = (r_t - q_t) \, dt + \sigma(S, t) \, dW,
\]

where instantaneous volatility \( \sigma(S, t) \) is called the local-volatility function.\(^a\)

  – “A local volatility model is the only complete consistent volatility model[.]”\(^b\)

• A (weak) solution exists if \( S\sigma(S, t) \) is continuous and grows at most linearly in \( S \) and \( t \).\(^c\)

\(^a\)Derman & Kani (1994); Dupire (1994).
\(^b\)Bennett (2014).
\(^c\)Skorokhod (1961); Achdou & Pironneau (2005).
Local-Volatility Models (continued)

- One needs to recover the local volatility surface $\sigma(S, t)$ from the implied volatility surface.

- Theoretically,$^{a}$

$$\sigma(X, T)^2 = 2 \frac{\partial C}{\partial T} + (r_T - q_T)X \frac{\partial C}{\partial X} + q_TC \frac{X^2 \frac{\partial^2 C}{\partial X^2}}{X^2}.$$  \hspace{1cm} (85)

- $C$ is the call price at time $t = 0$ (today) with strike price $X$ and time to maturity $T$.

- $\sigma(X, T)$ is the local volatility that will prevail at future time $T$ and stock price $S_T = X$.

---

Local-Volatility Models (continued)

- For more general models, this equation gives the expectation as seen from today, under the risk-neutral probability, of the instantaneous variance at time $T$ given that $S_T = X$.\(^a\)

- In practice, the $\sigma(S, t)^2$ derived by Dupire’s formula (85) may have spikes, vary wildly, or even be negative.

- The term $\partial^2 C/\partial X^2$ in the denominator often results in numerical instability.

\(^a\)Derman & Kani (1997); R. W. Lee (2001); Derman & M. B. Miller (2016).
Local-Volatility Models (continued)

- Denote the implied volatility surface by \( \Sigma(X, T) \) and the local volatility surface by \( \sigma(S, t) \).

- The relation between \( \Sigma(X, T) \) and \( \sigma(X, T) \) is

\[
\sigma(X, T)^2 = \frac{\Sigma^2 + 2\Sigma \tau \left[ \frac{\partial \Sigma}{\partial T} + (r_T - q_T) X \frac{\partial \Sigma}{\partial X} \right]}{(1 - \frac{X y}{\Sigma} \frac{\partial \Sigma}{\partial X})^2 + X \Sigma \tau \left[ \frac{\partial \Sigma}{\partial X} - \frac{X \Sigma \tau}{4} \left( \frac{\partial \Sigma}{\partial X} \right)^2 + X \frac{\partial^2 \Sigma}{\partial X^2} \right]},
\]

\[\tau \triangleq T - t,\]

\[y \triangleq \ln(X/S_t) + \int_t^T (q_s - r_s) \, ds.\]

\(^a\text{Andreasen (1996); Andersen & Brotherton-Ratcliffe (1998); Gatheral (2003); Wilmott (2006); Kamp (2009).}\)
Local-Volatility Models (continued)

- Although this version may be more stable than Eq. (85) on p. 637, it is expected to suffer from similar problems.

- Under fairly loose conditions, $\Sigma$ is symmetric if and only if $\sigma$ is, in terms of $y \equiv \ln\left(\frac{S_t}{X}\right)$ instead of $X$.$^{a}$

- Small changes to the implied volatility surface may produce big changes to the local volatility surface.

---

Implied and Local Volatility Surfaces

Contributed by Mr. Lok, U Hou (d99922028) on April 5, 2014.
Local-Volatility Models (continued)

- In reality, option prices only exist for a finite set of maturities and strike prices.
- Hence interpolation and extrapolation may be needed to construct the volatility surface.\(^a\)
- But then some implied volatility surfaces generate option prices that allow arbitrage opportunities.\(^b\)

\(^{a}\)Doing it to the option prices produces worse results (Li, 2000/2001).
\(^{b}\)See Rebonato (2004) for an example.
Local-Volatility Models (concluded)

- There exist conditions for a set of option prices to be arbitrage-free.\(^a\)

- Some adopt parameterized implied volatility surfaces that guarantee freedom from certain arbitrages.\(^b\)

- For some vanilla equity options, the Black-Scholes model seems better than the local-volatility model in predictive power.\(^c\)

- The exact opposite is concluded for hedging in equity index markets!\(^d\)

\(^a\) Kahalé (2004); Davis & Hobson (2007).
\(^b\) Gatheral & Jacquier (2014).
\(^c\) Dumas, Fleming, & Whaley (1998).
\(^d\) Crépey (2004); Derman & M. B. Miller (2016).
Local-Volatility Models: Popularity


- Bennett (2014), “Of all the four volatility regimes, [sticky local volatility] is arguably the most realistic and fairly prices skew.”

- Derman & M. B. Miller (2016), “Right or wrong, local volatility models have become popular and ubiquitous in modeling the smile.”
Implied Trees

• The trees for the local volatility model are called implied trees.\textsuperscript{a}

• Their construction requires option prices at all strike prices and maturities.
  – That is, an implied volatility surface.

• The local volatility model does \textit{not} require that the implied tree combine.

• Exponential-sized implied trees exist.\textsuperscript{b}

\textsuperscript{a}Derman & Kani (1994); Dupire (1994); Rubinstein (1994).
\textsuperscript{b}Charalambousa, Christofidesb, & Martzoukosa (2007); Gong & Xu (2019).
Implied Trees (continued)

- How to construct a valid implied tree with efficiency has been open for a long time.\(^a\)
  - Reasons may include: noise and nonsynchrony in data, arbitrage opportunities in the smoothed and interpolated/extrapolated implied volatility surface, wrong model, wrong algorithms, nonlinearity, instability, etc.

- Inversion is an ill-posed numerical problem.\(^b\)

\(^a\)Rubinstein (1994); Derman & Kani (1994); Derman, Kani, & Chriss (1996); Jackwerth & Rubinstein (1996); Jackwerth (1997); Coleman, Kim, Li, & Verma (2000); Li (2000/2001); Rebonato (2004); Moriggia, Muzio, & Torricelli (2009).

\(^b\)Ayache, Henrotte, Nassar, & X. Wang (2004).
Implied Trees (continued)

• It is finally solved for separable local volatilities.\textsuperscript{a}

  – The local-volatility function $\sigma(S, t)$ is separable\textsuperscript{b} if

  $$\sigma(S, t) = \sigma_1(S) \sigma_2(t).$$

• A solution is also available for \textit{any} upper- and lower-bounded $\sigma$.\textsuperscript{c}

\textsuperscript{a}Lok (D99922028) \& Lyuu (2015, 2016, 2017).
\textsuperscript{b}Brace, Gatarek, \& Musiela (1997); Rebonato (2004).
\textsuperscript{c}Lok (D99922028) \& Lyuu (2016, 2017, 2020).
Implied Trees\textsuperscript{a} (concluded)

\textsuperscript{a}Plot supplied by Prof. Lok, U Hou (D99922028) on May 4, 2019.
The Hull-White Model

• Hull and White (1987) postulate the following stochastic-volatility model,

\[
\frac{dS}{S} = r dt + \sqrt{V} \, dW_1, \\
\quad dV = \mu_v V \, dt + bV \, dW_2.
\]

• Above, \( V \) is the instantaneous variance.

• They assume \( \mu_v \) depends on \( V \) and \( t \) (but not \( S \)).
The Barone-Adesi–Rasmussen–Ravanelli Model

- Barone-Adesi, Rasmussen, and Ravanelli (2005) postulate the following model,

\[
\frac{dS}{S} = \mu dt + \sqrt{V} dW_1, \\
\quad dV = \kappa(\theta - V) dt + bV dW_2.
\]

- Above, \(W_1\) and \(W_2\) are correlated.
The Stein-Stein Model

- E. Stein and J. Stein (1991) postulate the following model,

\[
\frac{dS}{S} = r \, dt + V \, dW_1,
\]

\[
dV = \kappa (\mu - V) \, dt + \sigma \, dW.
\]

- Closed-form formulas exist for European calls and puts.\(^a\)

---

\(^a\)Schöbel & Zhu (1999).
The SABR Model

• Hagan, Kumar, Lesniewski, and Woodward (2002) postulate the following model,

\[
\frac{dS}{S} = r \, dt + S^\theta V \, dW_1, \\
dV = bV \, dW_2,
\]

for \(0 \leq \theta \leq 1\).

• A nice feature of this model is that the implied volatility surface has a compact approximate closed form.
The Blacher Model

- Blacher (2001) postulates the following model,

\[
\frac{dS}{S} = r \, dt + \sigma \left[ 1 + \alpha(S - S_0) + \beta(S - S_0)^2 \right] \, dW_1, \\
\frac{d\sigma}{\sigma} = \kappa(\theta - \sigma) \, dt + \epsilon \sigma \, dW_2.
\]

- The volatility \( \sigma \) follows a mean-reverting process to level \( \theta \).
The Hilliard-Schwartz Model

- Hilliard and Schwartz (1996) postulate the following general model,

\[
\frac{dS}{S} = r \, dt + f(S) V^a \, dW_1,
\]

\[
dV = \mu(V) \, dt + bV \, dW_2,
\]

for some well-behaved function \( f(S) \) and constant \( a \).

- It includes all previously mentioned stochastic-volatility models as special cases.\(^a\)

\(^a\)H. Chiu (R98723059) (2012).
Heston’s Stochastic-Volatility Model

- Heston (1993) assumes the stock price follows
  \[
  \frac{dS}{S} = (\mu - q) \, dt + \sqrt{V} \, dW_1, \quad (86)
  \]
  \[
  dV = \kappa(\theta - V) \, dt + \sigma\sqrt{V} \, dW_2. \quad (87)
  \]
  - \( V \) is the instantaneous variance, which follows a square-root process.
  - \( dW_1 \) and \( dW_2 \) have correlation \( \rho \).
  - The riskless rate \( r \) is constant.

- It may be the most popular continuous-time stochastic-volatility model.\(^a\)

\(^a\)Christoffersen, Heston, & Jacobs (2009).
Heston’s Stochastic-Volatility Model (continued)

- Heston assumes the market price of risk is $b_2 \sqrt{V}$.
- So $\mu = r + b_2 V$.
- Define

$$dW_1^* = dW_1 + b_2 \sqrt{V} \, dt,$$
$$dW_2^* = dW_2 + \rho b_2 \sqrt{V} \, dt,$$  
$$\kappa^* = \kappa + \rho b_2 \sigma,$$
$$\theta^* = \frac{\theta \kappa}{\kappa + \rho b_2 \sigma}.$$  

- $dW_1^*$ and $dW_2^*$ have correlation $\rho$. 

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Heston’s Stochastic-Volatility Model (continued)

- Under the risk-neutral probability measure $Q$, both $W_1^*$ and $W_2^*$ are Wiener processes.

- Heston’s model becomes, under probability measure $Q$,

\[
\frac{dS}{S} = (r - q) \, dt + \sqrt{V} \, dW_1^*,
\]

\[
dV = \kappa^*(\theta^* - V) \, dt + \sigma \sqrt{V} \, dW_2^*.
\]
Heston’s Stochastic-Volatility Model (continued)

• Define

\[
\phi(u, \tau) = \exp \left\{ \nu u (\ln S + (r - q) \tau) \right. \\
+ \theta^* \kappa^* \sigma^{-2} \left[ (\kappa^* - \rho \sigma \omega - d) \tau - 2 \ln \left( \frac{1 - ge^{-d\tau}}{1 - g} \right) \right] \\
+ \frac{\nu \sigma^{-2} (\kappa^* - \rho \sigma \omega - d) (1 - e^{-d\tau})}{1 - ge^{-d\tau}} \right\},
\]

\[
d = \sqrt{(\rho \sigma \omega - \kappa^*)^2 - \sigma^2 (-\nu u - u^2)},
\]

\[
g = (\kappa^* - \rho \sigma \omega - d)/(\kappa^* - \rho \sigma \omega + d).
\]
Heston’s Stochastic-Volatility Model (continued)

The formulas for European calls and puts are\(^{a}\)

\[
C = S \left[ \frac{1}{2} + \frac{1}{\pi} \int_{0}^{\infty} \text{Re} \left( \frac{X^{-i\mu}\phi(u - i, \tau)}{iuSe^{r\tau}} \right) du \right] 
- Xe^{-r\tau} \left[ \frac{1}{2} + \frac{1}{\pi} \int_{0}^{\infty} \text{Re} \left( \frac{X^{-i\mu}\phi(u, \tau)}{iu} \right) du \right],
\]

\[
P = Xe^{-r\tau} \left[ \frac{1}{2} - \frac{1}{\pi} \int_{0}^{\infty} \text{Re} \left( \frac{X^{-i\mu}\phi(u, \tau)}{iu} \right) du \right],
- S \left[ \frac{1}{2} - \frac{1}{\pi} \int_{0}^{\infty} \text{Re} \left( \frac{X^{-i\mu}\phi(u - i, \tau)}{iuSe^{r\tau}} \right) du \right],
\]

where \(i = \sqrt{-1}\) and \(\text{Re}(x)\) denotes the real part of the complex number \(x\).

\(^{a}\)Contributed by Mr. Chen, Chun-Ying (D95723006) on August 17, 2008 and Mr. Liou, Yan-Fu (R92723060) on August 26, 2008. See Lord & Kahl (2009) and Cui, Rollin, & Germano (2017) for alternative formulas.
Heston’s Stochastic-Volatility Model (concluded)

- For American options, trees are needed.

- They are all $O(n^3)$-sized and do not match all moments.\(^a\)

- An $O(n^{2.5})$-sized 9-jump tree that matches all means and variances with valid probabilities is available.\(^b\)

- The size reduces to $O(n^2)$ for knock-out double-barrier options.\(^c\)

---

\(^a\) Nelson & Ramaswamy (1990); Nawalkha & Beliaeva (2007); Leisen (2010); Beliaeva & Nawalkha (2010); M. Chou (R02723073) (2015); M. Chou (R02723073) & Lyuu (2016).

\(^b\) Z. Lu (D00922011) & Lyuu (2018).

\(^c\) Z. Lu (D00922011) & Lyuu (2018).
Stochastic-Volatility Models and Further Extensions\textsuperscript{a}

- How to explain the October 1987 crash?
  - The Dow Jones Industrial Average fell 22.61\% on October 19, 1987 (called the Black Monday).
  - The CBOE S&P 100 Volatility Index (VXO) shot up to 150\%, the highest VXO ever recorded.\textsuperscript{b}

- Stochastic-volatility models require an implausibly high-volatility level prior to and after the crash.
  - Because the processes are continuous.

- Discontinuous jump models in the asset price can alleviate the problem somewhat.\textsuperscript{c}

\textsuperscript{a}Eraker (2004).
\textsuperscript{b}Caprio (2012).
\textsuperscript{c}Merton (1976).
Stochastic-Volatility Models and Further Extensions (continued)

• But if the jump intensity is a constant, it cannot explain the tendency of large movements to cluster over time.

• This assumption also has no impacts on option prices.

• Jump-diffusion models combine both.
  – E.g., add a jump process to Eq. (86) on p. 655.
  – Closed-form formulas exist for GARCH-jump option pricing models.\(^a\)

\(^a\)Liou (R92723060) (2005).
Stochastic-Volatility Models and Further Extensions (concluded)

• But they still do not adequately describe the systematic variations in option prices.\(^a\)

• Jumps \textit{in volatility} are alternatives.\(^b\)
  – E.g., add correlated jump processes to Eqs. (86) \textit{and} Eq. (87) on p. 655.

• Such models allow high level of volatility caused by a jump to volatility.\(^c\)

\(^a\) Bates (2000); Pan (2002).
\(^b\) Duffie, Pan, & Singleton (2000).
Why Are Trees for Stochastic-Volatility Models Difficult?

- The CRR tree is 2-dimensional.\(^a\)
- The constant volatility makes the span from any node fixed.
- But a tree for a stochastic-volatility model must be 3-dimensional.
  - Every node is associated with a combination of stock price and volatility.

\(^a\)Recall p. 294.
Why Are Trees for Stochastic-Volatility Models Difficult (Binomial Case)?
Why Are Trees for Stochastic-Volatility Models Difficult (Trinomial Case)?
Why Are Trees for Stochastic-Volatility Models Difficult? (concluded)

• Locally, the tree looks fine for one time step.

• But the volatility regulates the spans of the nodes on the stock-price plane.

• Unfortunately, those spans differ from node to node because the volatility varies.

• So two time steps from now, the branches will not combine!

• Smart ideas are thus needed.
Complexities of Stochastic-Volatility Models

- A few stochastic-volatility models suffer from subexponential \( (c\sqrt{n}) \) tree size.
- Examples include the Hull-White (1987), Hilliard-Schwartz (1996), and SABR (2002) models.\(^a\)
- Future research may extend this negative result to more stochastic-volatility models.
  - We suspect many GARCH option pricing models entertain similar problems.\(^b\)

\(^a\) H. Chiu (R98723059) (2012).
\(^b\) Y. C. Chen (R95723051) (2008); Y. C. Chen (R95723051), Lyuu, & Wen (D94922003) (2011).
Complexities of Stochastic-Volatility Models (concluded)

- Flexible placement of nodes and removal of low-probability nodes may make the models \(O(n^{2.5})\)-sized!\(^a\)

- Calibration can be computationally hard.
  - Few have tried it on exotic options.\(^b\)

- There are usually several local minima.\(^c\)
  - They will give different prices to options not used in the calibration.
  - But which set capture the smile dynamics?

\(^a\)Z. Lu (D00922011) & Lyuu (2018).
\(^b\)Ayache, Henrotte, Nassar, & X. Wang (2004).
\(^c\)Ayache (2004).
Continuous-Time Derivatives Pricing
I have hardly met a mathematician who was capable of reasoning.
— Plato (428 B.C.–347 B.C.)

Fischer [Black] is the only real genius I’ve ever met in finance. Other people, like Robert Merton or Stephen Ross, are just very smart and quick, but they think like me. Fischer came from someplace else entirely.
— John C. Cox, quoted in Mehrling (2005)
Toward the Black-Scholes Differential Equation

- The price of any derivative on a non-dividend-paying stock must satisfy a partial differential equation (PDE).
- The key step is recognizing that the same random process drives both securities.
  - Their prices are perfectly correlated.
- We then figure out the amount of stock such that the gain from it offsets exactly the loss from the derivative.
- The removal of uncertainty forces the portfolio’s return to be the riskless rate.
- PDEs allow many numerical methods to be applicable.
Assumptions

- The stock price follows \( dS = \mu S \, dt + \sigma S \, dW \).
- There are no dividends.
- Trading is continuous, and short selling is allowed.
- There are no transactions costs or taxes.
- All securities are infinitely divisible.
- The term structure of riskless rates is flat at \( r \).
- There is unlimited riskless borrowing and lending.
- \( t \) is the current time, \( T \) is the expiration time, and \( \tau \triangleq T - t \).

\(^{a}\)Derman & Taleb (2005) summarizes criticisms on these assumptions and the replication argument.
Black-Scholes Differential Equation

• Let $C$ be the price of a simple derivative on $S$.
• From Ito’s lemma (p. 607),

$$dC = \left( \mu S \frac{\partial C}{\partial S} + \frac{\partial C}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} \right) dt + \sigma S \frac{\partial C}{\partial S} dW.$$  

– The same $W$ drives both $C$ and $S$.
– Unlike $dS/S$, the diffusion term of $dC/C$ is stochastic!

• Short one derivative and long $\partial C/\partial S$ shares of stock (call it $\Pi$).

• By construction,

$$\Pi = -C + S(\partial C/\partial S).$$
Black-Scholes Differential Equation (continued)

- The change in the value of the portfolio at time $dt$ is

$$d\Pi = -dC + \frac{\partial C}{\partial S} dS.$$

- Substitute the formulas for $dC$ and $dS$ into the partial differential equation to yield

$$d\Pi = \left( -\frac{\partial C}{\partial t} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} \right) dt.$$

- As this equation does not involve $dW$, the portfolio is riskless during $dt$ time: $d\Pi = r\Pi dt$.

---

$a$Bergman (1982) and Bartels (1995) argue this is not quite right. But see Macdonald (1997). Mathematically, it is wrong (Bingham & Kiesel, 2004).
Black-Scholes Differential Equation (continued)

- So

\[
\left( \frac{\partial C}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} \right) dt = r \left( C - S \frac{\partial C}{\partial S} \right) dt.
\]

- Equate the terms to finally obtain\(^a\)

\[
\frac{\partial C}{\partial t} + rS \frac{\partial C}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} = rC.
\]

- This is a backward equation, which describes the dynamics of a derivative’s price \textit{forward} in physical time.

\(^a\)Known as the Feynman-Kac stochastic representation formula.
Black-Scholes Differential Equation (concluded)

• When there is a dividend yield $q$,

$$\frac{\partial C}{\partial t} + (r - q) S \frac{\partial C}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} = rC. \quad (88)$$

• Dupire’s formula (85) for the local-volatility model$^a$ is simply the dual of this equation:$^b$

$$\frac{\partial C}{\partial T} + (r_T - q_T) X \frac{\partial C}{\partial X} - \frac{1}{2} \sigma(X, T)^2 X^2 \frac{\partial^2 C}{\partial X^2} = -q_T C.$$  

• This is a forward equation, which describes the dynamics of a derivative’s price backward in maturity time.

$^a$See p. 637.

$^b$Derman & Kani (1997).
Rephrase

• The Black-Scholes differential equation can be expressed in terms of sensitivity numbers,

\[ \Theta + rS\Delta + \frac{1}{2} \sigma^2 S^2 \Gamma = rC. \quad (89) \]

• Identity (89) leads to an alternative way of computing \( \Theta \) numerically from \( \Delta \) and \( \Gamma \).

• When a portfolio is delta-neutral,

\[ \Theta + \frac{1}{2} \sigma^2 S^2 \Gamma = rC. \]

– A definite relation thus exists between \( \Gamma \) and \( \Theta \).
Black-Scholes Differential Equation: An Alternative

• Perform the change of variable $V \triangleq \ln S$.

• The option value becomes $U(V, t) \triangleq C(e^V, t)$.

• Furthermore,

$$\frac{\partial C}{\partial t} = \frac{\partial U}{\partial t},$$

$$\frac{\partial C}{\partial S} = \frac{1}{S} \frac{\partial U}{\partial V},$$

$$\frac{\partial^2 C}{\partial^2 S} = \frac{1}{S^2} \frac{\partial^2 U}{\partial V^2} - \frac{1}{S^2} \frac{\partial U}{\partial V}. \quad (91)$$
Black-Scholes Differential Equation: An Alternative (concluded)

• Equations (90) and (91) are alternative ways to calculate delta and gamma.a

• They are particularly useful for a tree of logarithmic prices.

• The Black-Scholes differential equation (88) on p. 677 becomes

\[
\frac{1}{2} \sigma^2 \frac{\partial^2 U}{\partial V^2} + \left( r - q - \frac{\sigma^2}{2} \right) \frac{\partial U}{\partial V} - rU + \frac{\partial U}{\partial t} = 0
\]

subject to \( U(V, T) \) being the payoff such as \( \max(X - e^V, 0) \).

---

aSee Eqs. (49) on p. 361 and (50) on p. 363.
[Black] got the equation [in 1969] but then was unable to solve it. Had he been a better physicist he would have recognized it as a form of the familiar heat exchange equation, and applied the known solution. Had he been a better mathematician, he could have solved the equation from first principles. Certainly Merton would have known exactly what to do with the equation had he ever seen it.

— Perry Mehrling (2005)
PDEs for Asian Options

• Add the new variable $A(t) \equiv \int_0^t S(u) \, du$.

• Then the value $V$ of the Asian option satisfies this two-dimensional PDE:\footnote{Kemna & Vorst (1990).}

$$\frac{\partial V}{\partial t} + rS \frac{\partial V}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + S \frac{\partial V}{\partial A} = rV.$$ 

• The terminal conditions are

$$V(T, S, A) = \max \left( \frac{A}{T} - X, 0 \right) \quad \text{for call},$$

$$V(T, S, A) = \max \left( X - \frac{A}{T}, 0 \right) \quad \text{for put}.$$
PDEs for Asian Options (continued)

- The two-dimensional PDE produces algorithms similar to that on pp. 444ff.\(^a\)

- But one-dimensional PDEs are available for Asian options.\(^b\)

- For example, Večer (2001) derives the following PDE for Asian calls:

\[
\frac{\partial u}{\partial t} + r \left( 1 - \frac{t}{T} - z \right) \frac{\partial u}{\partial z} + \frac{\left( 1 - \frac{t}{T} - z \right)^2 \sigma^2}{2} \frac{\partial^2 u}{\partial z^2} = 0
\]

with the terminal condition \(u(T, z) = \max(z, 0)\).

---

\(^a\)Barraquand & Pudet (1996).

\(^b\)Rogers & Shi (1995); Večer (2001); Dubois & Lelièvre (2005).
PDEs for Asian Options (concluded)

• For Asian puts:

\[
\frac{\partial u}{\partial t} + r \left( \frac{t}{T} - 1 - z \right) \frac{\partial u}{\partial z} + \frac{\left( \frac{t}{T} - 1 - z \right)^2 \sigma^2}{2} \frac{\partial^2 u}{\partial z^2} = 0
\]

with the same terminal condition.

• One-dimensional PDEs lead to highly efficient numerical methods.
Hedging
When Professors Scholes and Merton and I invested in warrants, Professor Merton lost the most money. And I lost the least.

— Fischer Black (1938–1995)
Delta Hedge

• The delta (hedge ratio) of a derivative \( f \) is defined as

\[
\Delta \equiv \frac{\partial f}{\partial S}.
\]

• Thus

\[
\Delta f \approx \Delta \times \Delta S
\]

for relatively small changes in the stock price, \( \Delta S \).

• A delta-neutral portfolio is hedged as it is immunized against small changes in the stock price.
Delta Hedge (concluded)

• A trading strategy that dynamically maintains a delta-neutral portfolio is called delta hedge.
  – Trading strategies can also be static (or constant).\(^a\)

• Delta changes with the stock price.

• A delta hedge needs to be rebalanced periodically in order to maintain delta neutrality.

• In the limit where the portfolio is adjusted continuously, “perfect” hedge is achieved and the strategy becomes “self-financing.”

\(^a\)Recall p. 491 for hedging the short forward contract with the underlying asset and loans.
Implementing Delta Hedge

• We want to hedge $N$ *short* derivatives.

• Assume the stock pays no dividends.

• The delta-neutral portfolio maintains $N \times \Delta$ shares of stock plus $B$ borrowed dollars such that

$$-N \times f + N \times \Delta \times S - B = 0.$$ 

• At next rebalancing point when the delta is $\Delta'$, buy $N \times (\Delta' - \Delta)$ shares to maintain $N \times \Delta'$ shares.

• Delta hedge is the discrete-time analog of the continuous-time limit and will rarely be self-financing.
Example

- A hedger is *short* 10,000 European calls.

- $S = 50$, $\sigma = 30\%$, and $r = 6\%$.

- This call’s expiration is four weeks away, its strike price is $50$, and each call has a current value of $f = 1.76791$.

- As an option covers 100 shares of stock, $N = 1,000,000$.

- The trader adjusts the portfolio weekly.

- The calls are replicated well if the cumulative cost of trading *stock* is close to the call premium’s FV.$^a$

---

$a$This takes the replication viewpoint: One starts with zero dollar.
Example (continued)

• As $\Delta = 0.538560$

$$N \times \Delta = 538,560$$

shares are purchased for a total cost of

$$538,560 \times 50 = 26,928,000$$

dollars to make the portfolio delta-neutral.

• The trader finances the purchase by borrowing

$$B = N \times \Delta \times S - N \times f = 25,160,090$$

dollars net.$^{\text{a}}$

$^{\text{a}}$This takes the hedging viewpoint: One starts with the option premium. See Exercise 16.3.2 of the text.
Example (continued)

- At 3 weeks to expiration, the stock price rises to $51.
- The new call value is $f' = 2.10580$.
- So before rebalancing, the portfolio is worth
  \[- N \times f' + 538,560 \times 51 - Be^{0.06/52} = 171,622.\]  
  \[(92)\]
  
- A delta hedge does not replicate the calls perfectly.
  - It is not self-financing because $171,622$ can be withdrawn.
Example (continued)

- The magnitude of the tracking error—the variation in the net portfolio value—can be mitigated if adjustments are made more frequently.

- The tracking error over one rebalancing act is positive about 68% of the time, but its expected value is $\sim 0$ under the risk-neutral probability measure.\(^a\)
  
  - Should the profit and loss be calculated under the real-world probability measure instead?\(^b\)

\(^a\)Boyle & Emanuel (1980).
\(^b\)Contributed by Mr. Chiu, Tzu-Hsuan (R08723061) on April 09, 2021.
Example (continued)

- The tracking error at maturity is proportional to vega.\(^a\)
- In practice tracking errors will cease to decrease beyond a certain rebalancing frequency.
- With a higher delta \( \Delta' = 0.640355 \), the trader buys
  \[ N \times (\Delta' - \Delta) = 101,795 \]
  shares for $5,191,545.
- The number of shares is increased to \( N \times \Delta' = 640,355 \).

\(^a\)Kamal & Derman (1999).
Example (continued)

- The cumulative cost is\(^a\)

\[ 26,928,000 \times e^{0.06/52} + 5,191,545 = 32,150,634.\]

- The portfolio is again delta-neutral.

\(^a\)We take the replication viewpoint here. The replicating strategy is by construction self-financing. And it matches the payoff perfectly under the BOPM.
<table>
<thead>
<tr>
<th>$\tau$</th>
<th>$S$</th>
<th>$f$</th>
<th>$\Delta$</th>
<th>$N \times (5)$</th>
<th>$(1) \times (6)$</th>
<th>$FV(8') + (7)$</th>
<th>Cumulative cost</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>50</td>
<td>1.7679</td>
<td>0.53856</td>
<td>—</td>
<td>538,560</td>
<td>26,928,000</td>
<td>26,928,000</td>
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<tr>
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<td>51</td>
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<td>0.64036</td>
<td>0.10180</td>
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<td>5,191,545</td>
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<tr>
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<td>3.3509</td>
<td>0.85578</td>
<td>0.21542</td>
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<td>11,417,525</td>
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<td>0.83983</td>
<td>−0.01595</td>
<td>−15,955</td>
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<td>42,825,960</td>
</tr>
<tr>
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<td>54</td>
<td>4.0000</td>
<td>1.00000</td>
<td>0.16017</td>
<td>160,175</td>
<td>8,649,450</td>
<td>51,524,853</td>
</tr>
</tbody>
</table>

The total number of shares is 1,000,000 at expiration (trading takes place at expiration, too).
Example (continued)

- At expiration, the trader has 1,000,000 shares.
- They are exercised against by the in-the-money calls for $50,000,000.
- The trader is left with an obligation of
  
  \[ 51,524,853 - 50,000,000 = 1,524,853, \]

  which represents the replication cost.
- So if we had started with the PV of $1,524,853, we would have replicated 10,000 such calls in this scenario.
Example (concluded)

- The FV of the call premium equals

$$1,767,910 \times e^{0.06 \times 4/52} = 1,776,088.$$ 

- That means the net gain is

$$1,776,088 - 1,524,853 = 251,235$$

if we are hedging 10,000 European calls.
Tracking Error Revisited

- Define the dollar gamma as $S^2 \Gamma$.
- The change in value of a delta-hedged long option position after a duration of $\Delta t$ is proportional to the dollar gamma.
- It is about

$$(1/2)S^2 \Gamma [(\Delta S/S)^2 - \sigma^2 \Delta t].$$

$$(\Delta S/S)^2$$ is called the daily realized variance.
Tracking Error Revisited (continued)

• In our particular case,

\[ S = 50, \Gamma = 0.0957074, \Delta S = 1, \sigma = 0.3, \Delta t = 1/52. \]

• The estimated tracking error is

\[-(1/2) \times 50^2 \times 0.0957074 \times \left[ (1/50)^2 - (0.09/52) \right] = 159,205.\]

• It is very close to our earlier number of 171,622.\(^a\)

• Delta hedge is also called gamma scalping.\(^b\)

\(^a\)Recall Eq. (92) on p. 692.

\(^b\)Bennett (2014).
Tracking Error Revisited (continued)

• Let the rebalancing times be \( t_1, t_2, \ldots, t_n \).

• Let \( \Delta S_i = S_{i+1} - S_i \).

• The total tracking error at expiration is about

\[
\sum_{i=0}^{n-1} e^{r(T-t_i)} \frac{S_i^2 \Gamma_i}{2} \left[ \left( \frac{\Delta S_i}{S_i} \right)^2 - \sigma^2 \Delta t \right].
\]

• The tracking error is path dependent.

• It is also known that\(^a\)

\[
\sum_{i=0}^{n-1} \left( \frac{\Delta S_i}{S_i} \right)^2 \rightarrow \sigma^2 T.
\]

\(^a\)Protter (2005).
Tracking Error Revisited (concluded)\textsuperscript{a}

- The tracking error\textsuperscript{b} $\epsilon_n$ over $n$ rebalancing acts has about the same probability of being positive as being negative.

- Subject to certain regularity conditions, the root-mean-square tracking error $\sqrt{E[\epsilon_n^2]}$ is $O(1/\sqrt{n})$.\textsuperscript{c}

- The root-mean-square tracking error increases with $\sigma$ at first and then decreases.

\textsuperscript{a}Bertsimas, Kogan, & Lo (2000).
\textsuperscript{b}Such as 251,235 on p. 698.
\textsuperscript{c}Grannan & Swindle (1996).