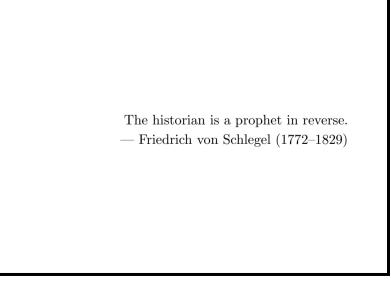


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## Conditional Variance Models for Price Volatility

- Although a stationary model (see text for definition) has constant variance, its *conditional* variance may vary.
- Take for example an AR(1) process  $X_t = aX_{t-1} + \epsilon_t$ with |a| < 1.
  - Here,  $\epsilon_t$  is a stationary, uncorrelated process with zero mean and constant variance  $\sigma^2$ .
- The conditional variance,

$$\operatorname{Var}[X_t | X_{t-1}, X_{t-2}, \dots],$$

equals  $\sigma^2$ , which is smaller than the unconditional variance  $\operatorname{Var}[X_t] = \sigma^2/(1-a^2)$ .

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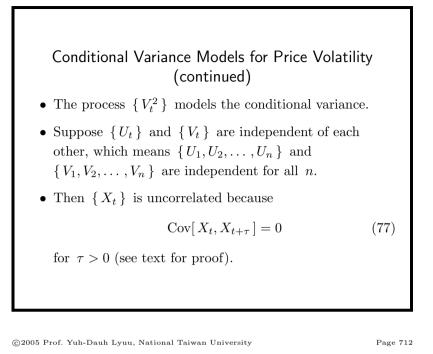
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## Conditional Variance Models for Price Volatility (continued)

- Past information thus has no effects on the variance of prediction.
- To address this drawback, consider models for returns  $X_t$  consistent with a changing conditional variance:

$$X_t - \mu = V_t U_t.$$

- $U_t$  has zero mean and unit variance for all t.
- $E[X_t] = \mu$  for all t.
- $\operatorname{Var}[X_t \,|\, V_t = v_t] = v_t^2.$



Conditional Variance Models for Price Volatility (continued) • If, furthermore,  $\{V_t\}$  is stationary, then  $\{X_t\}$  has constant variance because  $E\left[(X_t - \mu)^2\right]$   $= E\left[V_t^2 U_t^2\right]$   $= E\left[V_t^2\right] E\left[U_t^2\right]$   $= E\left[V_t^2\right].$ • This makes  $\{X_t\}$  stationary.

# Conditional Variance Models for Price Volatility (concluded)

- In the lognormal model, the conditional variance evolves independently of past returns.
- Suppose we assume that conditional variances are deterministic functions of past returns:

$$V_t = f(X_{t-1}, X_{t-2}, \dots)$$

for some function f.

• Then  $V_t$  can be computed given the information set of past returns:

$$I_{t-1} \equiv \{ X_{t-1}, X_{t-2}, \dots \}.$$

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## ARCH Models $^{\rm a}$

- An influential model in this direction is the autoregressive conditional heteroskedastic (ARCH) model.
- Assume  $U_t$  is independent of  $V_t, U_{t-1}, V_{t-1}, U_{t-2}, \ldots$  for all t.
- Consequently  $\{X_t\}$  is uncorrelated by Eq. (77) on p. 712.
- Assume furthermore that  $\{U_t\}$  is a Gaussian stationary, uncorrelated process.
- Then  $X_t | I_{t-1} \sim N(\mu, V_t^2)$ .

 $^{\mathrm{a}}\mathrm{Engle}$  (1982), co-winner of the 2003 Nobel Prize in Economic Sciences.

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#### ARCH Models (continued)

• The ARCH(p) process is defined by

$$X_t - \mu = \left(a_0 + \sum_{i=1}^p a_i (X_{t-i} - \mu)^2\right)^{1/2} U_t$$

where  $a_1, ..., a_p \ge 0$  and  $a_0 > 0$ .

• The variance  $V_t^2$  thus satisfies

$$V_t^2 = a_0 + \sum_{i=1}^p a_i (X_{t-i} - \mu)^2.$$

• The volatility at time t as estimated at time t-1 depends on the p most recent observations on squared returns.

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ARCH Models (concluded)

• The ARCH(1) process

$$X_t - \mu = (a_0 + a_1(X_{t-1} - \mu)^2)^{1/2} U_t$$

is the simplest.

- For it,
  - Var[ $X_t | X_{t-1} = x_{t-1}$ ] =  $a_0 + a_1(x_{t-1} \mu)^2$ .
- The process  $\{X_t\}$  is stationary with finite variance if and only if  $a_1 < 1$ , in which case  $\operatorname{Var}[X_t] = a_0/(1-a_1)$ .
- The parameters can be estimated by statistical techniques.

## $\mathsf{GARCH}\ \mathsf{Models}^{\mathrm{a}}$

- A very popular extension of the ARCH model is the generalized autoregressive conditional heteroskedastic (GARCH) process.
- The simplest GARCH(1, 1) process adds  $a_2V_{t-1}^2$  to the ARCH(1) process, resulting in

$$V_t^2 = a_0 + a_1 (X_{t-1} - \mu)^2 + a_2 V_{t-1}^2.$$

• The volatility at time t as estimated at time t-1 depends on the squared return and the estimated volatility at time t-1.

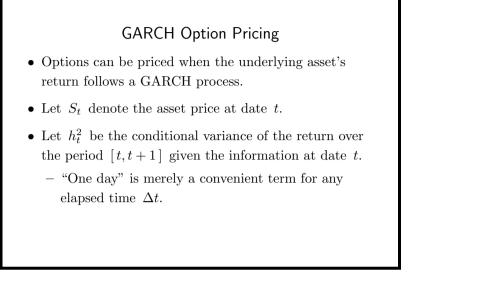
<sup>a</sup>Bollerslev (1986) and Taylor (1986).

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#### GARCH Models (concluded)

- The estimate of volatility averages past squared returns by giving heavier weights to recent squared returns (see text).
- It is usually assumed that  $a_1 + a_2 < 1$  and  $a_0 > 0$ , in which case the unconditional, long-run variance is given by  $a_0/(1 a_1 a_2)$ .
- A popular special case of GARCH(1, 1) is the exponentially weighted moving average process, which sets  $a_0$  to zero and  $a_2$  to  $1 a_1$ .
- This model is used in J.P. Morgan's Risk Metrics  $^{\rm TM}.$



## GARCH Option Pricing (continued)

- The five unknown parameters of the model are  $c, h_0, \beta_0, \beta_1$ , and  $\beta_2$ .
- It is postulated that β<sub>0</sub>, β<sub>1</sub>, β<sub>2</sub> ≥ 0 to make the conditional variance positive.
- The above process, called the nonlinear asymmetric GARCH model, generalizes the GARCH(1, 1) model (see text).

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#### GARCH Option Pricing (concluded)

• With  $y_t \equiv \ln S_t$  denoting the logarithmic price, the model becomes

$$y_{t+1} = y_t + r - \frac{h_t^2}{2} + h_t \epsilon_{t+1}.$$
 (80)

- The pair  $(y_t, h_t^2)$  completely describes the current state.
- The conditional mean and variance of  $y_{t+1}$  are clearly

$$E[y_{t+1} | y_t, h_t^2] = y_t + r - \frac{h_t^2}{2}, \qquad (81)$$

$$\operatorname{Var}[y_{t+1} | y_t, h_t^2] = h_t^2.$$
(82)

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GARCH Option Pricing (continued)

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• Adopt the following risk-neutral process for the price dynamics:<sup>a</sup>

$$\ln \frac{S_{t+1}}{S_t} = r - \frac{h_t^2}{2} + h_t \epsilon_{t+1}, \tag{78}$$

where

$$h_{t+1}^{2} = \beta_{0} + \beta_{1}h_{t}^{2} + \beta_{2}h_{t}^{2}(\epsilon_{t+1} - c)^{2}, \qquad (79)$$
  

$$\epsilon_{t+1} \sim N(0, 1) \text{ given information at date } t,$$
  

$$r = \text{ daily riskless return,}$$
  

$$c \geq 0.$$

<sup>a</sup>Duan (1995).

The Ritchken-Trevor (RT) Algorithm $^{\rm a}$ 

- The GARCH model is a continuous-state model.
- To approximate it, we turn to trees with *discrete* states.
- Path dependence in GARCH makes the tree for asset prices explode exponentially.
- We need to mitigate this combinatorial explosion somewhat.

<sup>a</sup>Ritchken and Trevor (1999).

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## The Ritchken-Trevor Algorithm (continued)

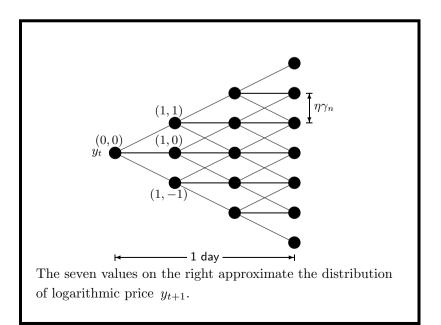
- It remains to pick the jump size and the three branching probabilities.
- The role of  $\sigma$  in the Black-Scholes option pricing model is played by  $h_t$  in the GARCH model.
- As a jump size proportional to σ/√n is picked in the BOPM, a comparable magnitude will be chosen here.
- Define  $\gamma \equiv h_0$ , though other multiples of  $h_0$  are possible, and

$$\gamma_n \equiv \frac{\gamma}{\sqrt{n}}$$

- The jump size will be some integer multiple  $\eta$  of  $\gamma_n$ .
- We call  $\eta$  the jump parameter (p. 727).

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## The Ritchken-Trevor Algorithm (continued)

- Partition a day into n periods.
- Three states follow each state  $(y_t, h_t^2)$  after a period.
- As the trinomial model combines, 2n + 1 states at date t + 1 follow each state at date t (recall p. 550).
- These 2n + 1 values must approximate the distribution of  $(y_{t+1}, h_{t+1}^2)$ .
- So the conditional moments (81)–(82) at date t + 1 on p. 723 must be matched by the trinomial model to guarantee convergence to the continuous-state model.

The Ritchken-Trevor Algorithm (continued)

- The middle branch does not change the underlying asset's price.
- The probabilities for the up, middle, and down branches are

$$p_{u} = \frac{h_{t}^{2}}{2\eta^{2}\gamma^{2}} + \frac{r - (h_{t}^{2}/2)}{2\eta\gamma\sqrt{n}},$$

$$p_{m} = 1 - \frac{h_{t}^{2}}{\eta^{2}\gamma^{2}},$$

$$h_{t}^{2} = r - (h_{t}^{2}/2)$$
(83)
(84)

$$p_d = \frac{h_t}{2\eta^2 \gamma^2} - \frac{r - (h_t/2)}{2\eta\gamma\sqrt{n}}.$$
 (85)

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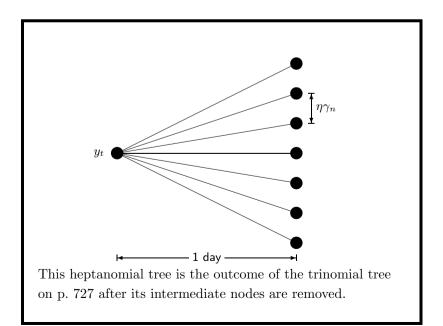
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The Ritchken-Trevor Algorithm (continued)

- We can dispense with the intermediate nodes between dates to create a (2n + 1)-nomial tree (p. 731).
- The resulting model is multinomial with 2n + 1 branches from any state  $(y_t, h_t^2)$ .
- There are two reasons behind this manipulation.
  - Interdate nodes are created merely to approximate the continuous-state model after one day.
  - Keeping the interdate nodes results in a tree that is n times as large.

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The Ritchken-Trevor Algorithm (continued)

- It can be shown that:
  - The trinomial model takes on 2n + 1 values at date t + 1 for  $y_{t+1}$ .
  - These values have a matching mean for  $y_{t+1}$ .
  - These values have an asymptotically matching variance for  $\,y_{t+1}\,.$
- The central limit theorem thus guarantees the desired convergence as *n* increases.

## The Ritchken-Trevor Algorithm (continued)

- A node with logarithmic price  $y_t + \ell \eta \gamma_n$  at date t + 1 follows the current node at date t with price  $y_t$  for some  $-n \leq \ell \leq n$ .
- To reach that price in n periods, the number of up moves must exceed that of down moves by exactly  $\ell$ .
- The probability that this happens is

$$P(\ell) \equiv \sum_{j_u, j_m, j_d} \frac{n!}{j_u! j_m! j_d!} p_u^{j_u} p_m^{j_m} p_d^{j_d},$$

with 
$$j_u, j_m, j_d \ge 0, n = j_u + j_m + j_d$$
, and  $\ell = j_u - j_d$ .

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The Ritchken-Trevor Algorithm (continued)

• A particularly simple way to calculate the  $P(\ell)$ s starts by noting that

$$(p_u x + p_m + p_d x^{-1})^n = \sum_{\ell = -n}^n P(\ell) x^{\ell}.$$
 (86)

- So we expand  $(p_u x + p_m + p_d x^{-1})^n$  and retrieve the probabilities by reading off the coefficients.
- It can be computed in  $O(n^2)$  time.

## The Ritchken-Trevor Algorithm (continued)

- The updating rule (79) on p. 721 must be modified to account for the adoption of the discrete-state model.
- The logarithmic price  $y_t + \ell \eta \gamma_n$  at date t + 1 following state  $(y_t, h_t^2)$  at date t has a variance equal to

$$h_{t+1}^2 = \beta_0 + \beta_1 h_t^2 + \beta_2 h_t^2 (\epsilon_{t+1}' - c)^2, \qquad (87)$$

- Above,

$$\epsilon'_{t+1} = \frac{\ell \eta \gamma_n - (r - h_t^2/2)}{h_t}, \quad \ell = 0, \pm 1, \pm 2, \dots, \pm n,$$

is a discrete random variable with 2n + 1 values.

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## The Ritchken-Trevor Algorithm (continued)

- Different conditional variances  $h_t^2$  may require different  $\eta$  so that the probabilities calculated by Eqs. (83)–(85) on p. 728 lie between 0 and 1.
- This implies varying jump sizes.
- The necessary requirement  $p_m \ge 0$  implies  $\eta \ge h_t/\gamma$ .
- Hence we try

$$\eta = \lceil h_t/\gamma \rceil, \lceil h_t/\gamma \rceil + 1, \lceil h_t/\gamma \rceil + 2, \dots$$

until valid probabilities are obtained or until their nonexistence is confirmed.

The Ritchken-Trevor Algorithm (continued)

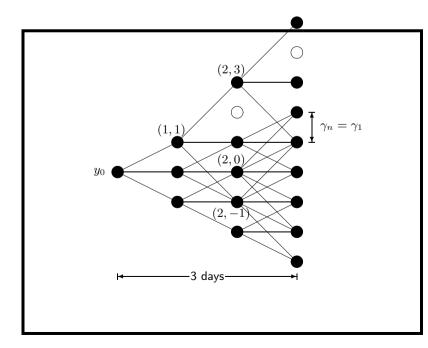
• The sufficient and necessary condition for valid probabilities to exist is

$$\frac{|r-(h_t^2/2)|}{2\eta\gamma\sqrt{n}} \leq \frac{h_t^2}{2\eta^2\gamma^2} \leq \min\left(1 - \frac{|r-(h_t^2/2)|}{2\eta\gamma\sqrt{n}}, \frac{1}{2}\right).$$

- Obviously, the magnitude of  $\eta$  tends to grow with  $h_t$ .
- The plot on p. 737 uses n = 1 to illustrate our points for a 3-day model.
- For example, node (1,1) of date 1 and node (2,3) of date 2 pick η = 2.

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## The Ritchken-Trevor Algorithm (continued)

- The topology of the tree is not a standard combining multinomial tree.
- For example, a few nodes on p. 737 such as nodes (2,0) and (2,-1) have multiple jump sizes.
- The reason is the path dependence of the model.
  - Two paths can reach node (2,0) from the root node, each with a different variance for the node.
  - One of the variances results in  $\eta = 1$ , whereas the other results in  $\eta = 2$ .

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## The Ritchken-Trevor Algorithm (concluded)

- The possible values of  $h_t^2$  at a node are exponential nature.
- To address this problem, we record only the maximum and minimum  $h_t^2$  at each node.<sup>a</sup>
- Therefore, each node on the tree contains only two states  $(y_t, h_{\text{max}}^2)$  and  $(y_t, h_{\min}^2)$ .
- Each of  $(y_t, h_{\max}^2)$  and  $(y_t, h_{\min}^2)$  carries its own  $\eta$  and set of 2n + 1 branching probabilities.

<sup>a</sup>Cakici and Topyan (2000).

Negative Aspects of the Ritchken-Trevor Algorithm  $^{\rm a}$ 

- A small *n* may yield inaccurate option prices.
- But the tree will grow exponentially if n is large enough.
   Specifically, n > (1 − β<sub>1</sub>)/β<sub>2</sub> when r = c = 0.
- A large *n* has another serious problem: The tree cannot grow beyond a certain date.
- Thus the choice of n may be limited in practice.
- The RT algorithm can be modified to be free of exponential complexity and shortened maturity.<sup>b</sup>

<sup>a</sup>Lyuu and Wu (2003). <sup>b</sup>Lyuu and Wu (2005).

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# • Let $h_{\max}^2(i,j)$ denote the maximum variance at node (i,j).

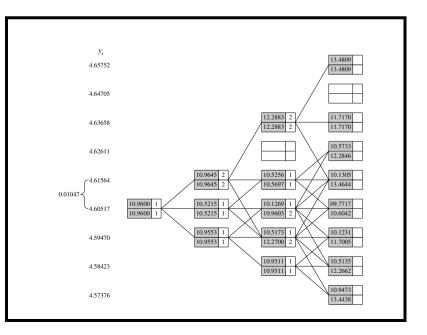
• Let  $h_{\min}^2(i, j)$  denote the minimum variance at node (i, j).

Numerical Examples (continued)

- Initially,  $h_{\max}^2(0,0) = h_{\min}^2(0,0) = h_0^2$ .
- The resulting three-day tree is depicted on p. 743.

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#### Numerical Examples

- Assume  $S_0 = 100$ ,  $y_0 = \ln S_0 = 4.60517$ , r = 0,  $h_0^2 = 0.0001096$ ,  $\gamma = h_0 = 0.010469$ , n = 1,  $\gamma_n = \gamma/\sqrt{n} = 0.010469$ ,  $\beta_0 = 0.000006575$ ,  $\beta_1 = 0.9$ ,  $\beta_2 = 0.04$ , and c = 0.
- A daily variance of 0.0001096 corresponds to an annual volatility of  $\sqrt{365 \times 0.0001096} \approx 20\%$ .
- Let  $h^2(i,j)$  denote the variance at node (i,j).
- Initially,  $h^2(0,0) = h_0^2 = 0.0001096$ .

A top (bottom) number inside a gray box refers to the minimum (maximum, respectively) variance  $h_{\min}^2$  ( $h_{\max}^2$ , respectively) for the node. Variances are multiplied by 100,000 for readability. A top (bottom) number inside a white box refers to  $\eta$  corresponding to  $h_{\min}^2$  ( $h_{\max}^2$ , respectively).

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#### Numerical Examples (continued)

- Move on to node (1, 1).
- It has one predecessor node—node (0,0)—and it takes an up move to reach the current node.
- So apply updating rule (87) on p. 734 with  $\ell = 1$  and  $h_t^2 = h^2(0,0)$ .
- The result is  $h^2(1,1) = 0.000109645$ .

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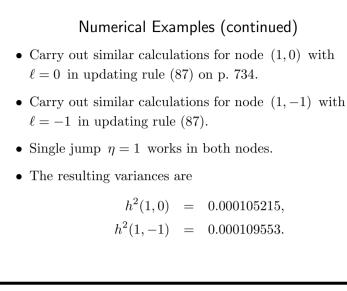
#### Numerical Examples (continued)

- Let us see how the numbers are calculated.
- Start with the root node, node (0,0).
- Try  $\eta = 1$  in Eqs. (83)–(85) on p. 728 first to obtain

$$p_u = 0.4974,$$
  
 $p_m = 0,$   
 $p_d = 0.5026.$ 

• As they are valid probabilities, the three branches from the root node use single jumps.

Numerical Examples (continued)
Because ⌊h(1,1)/γ ⌋ = 2, we try η = 2 in Eqs. (83)–(85) on p. 728 first to obtain
p<sub>u</sub> = 0.1237,
p<sub>m</sub> = 0.7499,
p<sub>d</sub> = 0.1264.
As they are valid probabilities, the three branches from node (1, 1) use double jumps.



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Numerical Examples (continued)

- Node (2,0) has 2 predecessor nodes, (1,0) and (1,-1).
- Both have to be considered in deriving the variances.
- Let us start with node (1,0).
- Because it takes a middle move to reach the current node, we apply updating rule (87) on p. 734 with  $\ell = 0$ and  $h_t^2 = h^2(1,0)$ .
- The result is  $h_{t+1}^2 = 0.000101269$ .

## Numerical Examples (continued)

- Now move on to the other predecessor node (1, -1).
- Because it takes an up move to reach the current node, apply updating rule (87) on p. 734 with  $\ell = 1$  and  $h_t^2 = h^2(1, -1)$ .
- The result is  $h_{t+1}^2 = 0.000109603$ .
- We hence record

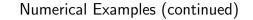
$$h_{\min}^2(2,0) = 0.000101269,$$
  
 $h_{\max}^2(2,0) = 0.000109603.$ 

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#### Numerical Examples (continued)

- Consider state  $h_{\max}^2(2,0)$  first.
- Because  $\lfloor h_{\max}(2,0)/\gamma \rfloor = 2$ , we first try  $\eta = 2$  in Eqs. (83)–(85) on p. 728 to obtain
  - $p_u = 0.1237,$   $p_m = 0.7500,$  $p_d = 0.1263.$
- As they are valid probabilities, the three branches from node (2,0) with the maximum variance use double jumps.



- Now consider state  $h_{\min}^2(2,0)$ .
- Because  $\lfloor h_{\min}(2,0)/\gamma \rfloor = 1$ , we first try  $\eta = 1$  in Eqs. (83)–(85) on p. 728 to obtain

 $p_u = 0.4596,$   $p_m = 0.0760,$  $p_d = 0.4644.$ 

• As they are valid probabilities, the three branches from node (2,0) with the minimum variance use single jumps.

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# Numerical Examples (continued)

- Node (2, -1) has 3 predecessor nodes.
- Start with node (1, 1).
- Because it takes a down move to reach the current node, we apply updating rule (87) on p. 734 with  $\ell = -1$  and  $h_t^2 = h^2(1, 1)$ .
- The result is  $h_{t+1}^2 = 0.0001227$ .

## Numerical Examples (continued)

- Now move on to predecessor node (1,0).
- Because it also takes a down move to reach the current node, we apply updating rule (87) on p. 734 with  $\ell = -1$  and  $h_t^2 = h^2(1,0)$ .
- The result is  $h_{t+1}^2 = 0.000105609$ .

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#### Numerical Examples (continued)

- Finally, consider predecessor node (1, -1).
- Because it takes a middle move to reach the current node, we apply updating rule (87) on p. 734 with  $\ell = 0$ and  $h_t^2 = h^2(1, -1)$ .
- The result is  $h_{t+1}^2 = 0.000105173$ .
- We hence record

 $h_{\min}^2(2,-1) = 0.000105173,$  $h_{\max}^2(2,-1) = 0.0001227.$ 

#### Numerical Examples (continued)

- Consider state  $h_{\max}^2(2,-1)$ .
- Because  $\lfloor h_{\max}(2,-1)/\gamma \rfloor = 2$ , we first try  $\eta = 2$  in Eqs. (83)–(85) on p. 728 to obtain

 $p_u = 0.1385,$   $p_m = 0.7201,$  $p_d = 0.1414.$ 

• As they are valid probabilities, the three branches from node (2, -1) with the maximum variance use double jumps.

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Numerical Examples (continued)

- Next, consider state  $h_{\min}^2(2,-1)$ .
- Because  $\lfloor h_{\min}(2,-1)/\gamma \rfloor = 1$ , we first try  $\eta = 1$  in Eqs. (83)–(85) on p. 728 to obtain
  - $p_u = 0.4773,$   $p_m = 0.0404,$  $p_d = 0.4823.$
- As they are valid probabilities, the three branches from node (2, −1) with the minimum variance use single jumps.

# Numerical Examples (concluded)

- Other nodes at dates 2 and 3 can be handled similarly.
- In general, if a node has k predecessor nodes, then 2k variances will be calculated using the updating rule.
  - This is because each predecessor node keeps two variance numbers.
- But only the maximum and minimum variances will be kept.

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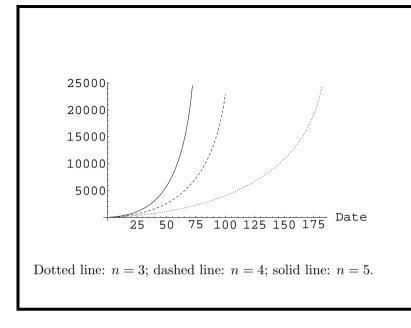
## Negative Aspects of the RT Algorithm Revisited $^{\rm a}$

- Recall the problems mentioned on p. 740.
- In our case, combinatorial explosion occurs when

$$n > \frac{1 - \beta_1}{\beta_2} = \frac{1 - 0.9}{0.04} = 2.5.$$

- Suppose we are willing to accept the exponential running time and pick n = 100 to seek accuracy.
- But the problem of shortened maturity forces the tree to stop at date 9!

<sup>a</sup>Lyuu and Wu (2003).



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Backward Induction on the RT Tree

- After the RT tree is constructed, it can be used to price options by backward induction.
- Recall that each node keeps two variances  $h_{\max}^2$  and  $h_{\min}^2$ .
- We now increase that number to K equally spaced variances between  $h_{\max}^2$  and  $h_{\min}^2$  at each node.
- Besides the minimum and maximum variances, the other K-2 variances in between are linearly interpolated.<sup>a</sup>

 $^{\rm a}{\rm In}$  practice, log-linear interpolation works better; Lyuu and Wu (2005). Log-cubic interpolation works even better; Liu (2005).

#### Backward Induction on the RT Tree (continued)

- For example, if K = 3, then a variance of  $10.5436 \times 10^{-6}$  will be added between the maximum and minimum variances at node (2,0) on p. 743.
- In general, the kth variance at node (i, j) is

$$h_{\min}^2(i,j) + k \, \frac{h_{\max}^2(i,j) - h_{\min}^2(i,j)}{K-1},$$

 $k=0,1,\ldots,K-1.$ 

• Each interpolated variance's jump parameter and branching probabilities can be computed as before.

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## Backward Induction on the RT Tree (concluded)

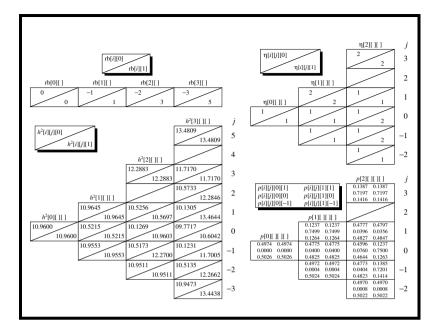
- During backward induction, if a variance falls between two of the K variances, linear interpolation of the option prices corresponding to the two bracketing variances will be used as the approximate option price.
- The above ideas are reminiscent of the ones on p. 319, where we dealt with arithmetic average-rate options.

#### Numerical Examples

- We next use the numerical example on p. 743 to price a European call option with a strike price of 100 and expiring at date 3.
- Recall that the riskless interest rate is zero.
- Assume K = 2; hence there are no interpolated variances.
- The pricing tree is shown on p. 765 with a call price of 0.66346.
  - The branching probabilities needed in backward induction can be found on p. 766.

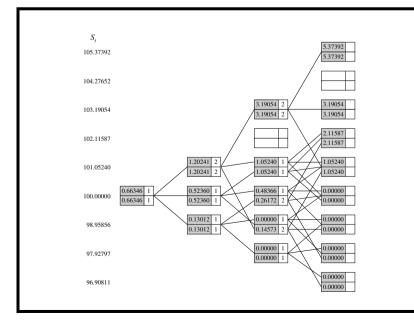


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#### Numerical Examples (continued)

- Let us derive some of the numbers on p. 765.
- The option price for a terminal node at date 3 equals  $\max(S_3 100, 0)$ , independent of the variance level.
- Now move on to nodes at date 2.
- The option price at node (2,3) depends on those at nodes (3,5), (3,3), and (3,1).
- It therefore equals

 $0.1387 \times 5.37392 + 0.7197 \times 3.19054 + 0.1416 \times 1.05240 = 3.19054.$ 

• Option prices for other nodes at date 2 can be computed similarly.

## Numerical Examples (continued)

- For node (1, 1), the option price for both variances is 0.1237 × 3.19054 + 0.7499 × 1.05240 + 0.1264 × 0.14573 = 1.20241.
- Node (1,0) is most interesting.
- We knew that a down move from it gives a variance of 0.000105609.
- This number falls between the minimum variance 0.000105173 and the maximum variance 0.0001227 at node (2, -1) on p. 743.

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Numerical Examples (continued)

- The option price corresponding to the minimum variance is 0.
- The option price corresponding to the maximum variance is 0.14573.
- The equation

 $x \times 0.000105173 + (1 - x) \times 0.0001227 = 0.000105609$ 

is satisfied by x = 0.9751.

• So the option for the down state is approximated by

 $x \times 0 + (1 - x) \times 0.14573 = 0.00362.$ 

#### Numerical Examples (continued)

- The up move leads to the state with option price 1.05240.
- The middle move leads to the state with option price 0.48366.
- The option price at node (1,0) is finally calculated as 0.4775 × 1.05240 + 0.0400 × 0.48366 + 0.4825 × 0.00362 = 0.52360.

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## Numerical Examples (concluded)

- It is possible for some of the three variances following an interpolated variance to exceed the maximum variance or be exceeded by the minimum variance.
- When this happens, the option price corresponding to the maximum or minimum variance will be used during backward induction.
- An interpolated variance may choose a branch that goes into a node that is not reached in the forward-induction tree-building phase.<sup>a</sup>

<sup>a</sup>Lyuu and Wu (2005).