Time Series Analysis

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The historian is a prophet in reverse.

— Friedrich von Schlegel (1772–1829)

Conditional Variance Models for Price Volatility

- Although a stationary model (see text for definition) has constant variance, its *conditional* variance may vary.
- Take for example an AR(1) process $X_t = aX_{t-1} + \epsilon_t$ with |a| < 1.
 - Here, ϵ_t is a stationary, uncorrelated process with zero mean and constant variance σ^2 .
- The conditional variance,

$$Var[X_t | X_{t-1}, X_{t-2}, ...],$$

equals σ^2 , which is smaller than the unconditional variance $\operatorname{Var}[X_t] = \sigma^2/(1-a^2)$.

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Conditional Variance Models for Price Volatility (continued)

- Past information thus has no effects on the variance of prediction.
- To address this drawback, consider models for returns X_t consistent with a changing conditional variance:

$$X_t - \mu = V_t U_t.$$

- $-U_t$ has zero mean and unit variance for all t.
- $-E[X_t] = \mu$ for all t.
- $\operatorname{Var}[X_t | V_t = v_t] = v_t^2.$

Conditional Variance Models for Price Volatility (continued)

- The process $\{V_t^2\}$ models the conditional variance.
- Suppose $\{U_t\}$ and $\{V_t\}$ are independent of each other, which means $\{U_1, U_2, \ldots, U_n\}$ and $\{V_1, V_2, \ldots, V_n\}$ are independent for all n.
- Then $\{X_t\}$ is uncorrelated because

$$Cov[X_t, X_{t+\tau}] = 0 (77)$$

for $\tau > 0$ (see text for proof).

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Conditional Variance Models for Price Volatility (continued)

• If, furthermore, $\{V_t\}$ is stationary, then $\{X_t\}$ has constant variance because

$$E\left[(X_t - \mu)^2\right]$$

$$= E\left[V_t^2 U_t^2\right]$$

$$= E\left[V_t^2\right] E\left[U_t^2\right]$$

$$= E\left[V_t^2\right].$$

• This makes $\{X_t\}$ stationary.

Conditional Variance Models for Price Volatility (concluded)

- In the lognormal model, the conditional variance evolves independently of past returns.
- Suppose we assume that conditional variances are deterministic functions of past returns:

$$V_t = f(X_{t-1}, X_{t-2}, \dots)$$

for some function f.

• Then V_t can be computed given the information set of past returns:

$$I_{t-1} \equiv \{ X_{t-1}, X_{t-2}, \dots \}.$$

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ARCH Models^a

- An influential model in this direction is the autoregressive conditional heteroskedastic (ARCH) model.
- Assume U_t is independent of $V_t, U_{t-1}, V_{t-1}, U_{t-2}, \dots$ for all t.
- Consequently $\{X_t\}$ is uncorrelated by Eq. (77) on p. 712.
- Assume furthermore that $\{U_t\}$ is a Gaussian stationary, uncorrelated process.
- Then $X_t | I_{t-1} \sim N(\mu, V_t^2)$.

 $^{\rm a}{\rm Engle}$ (1982), co-winner of the 2003 Nobel Prize in Economic Sciences.

ARCH Models (continued)

• The ARCH(p) process is defined by

$$X_t - \mu = \left(a_0 + \sum_{i=1}^p a_i (X_{t-i} - \mu)^2\right)^{1/2} U_t,$$

where $a_1, \ldots, a_n \ge 0$ and $a_0 > 0$.

• The variance V_t^2 thus satisfies

$$V_t^2 = a_0 + \sum_{i=1}^p a_i (X_{t-i} - \mu)^2.$$

• The volatility at time t as estimated at time t-1depends on the p most recent observations on squared returns.

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ARCH Models (concluded)

• The ARCH(1) process

$$X_t - \mu = (a_0 + a_1(X_{t-1} - \mu)^2)^{1/2}U_t$$

is the simplest.

• For it,

$$Var[X_t | X_{t-1} = x_{t-1}] = a_0 + a_1(x_{t-1} - \mu)^2.$$

- The process $\{X_t\}$ is stationary with finite variance if and only if $a_1 < 1$, in which case $Var[X_t] = a_0/(1-a_1)$.
- The parameters can be estimated by statistical techniques.

GARCH Models^a

- A very popular extension of the ARCH model is the generalized autoregressive conditional heteroskedastic (GARCH) process.
- The simplest GARCH(1,1) process adds $a_2V_{t-1}^2$ to the ARCH(1) process, resulting in

$$V_t^2 = a_0 + a_1(X_{t-1} - \mu)^2 + a_2 V_{t-1}^2.$$

• The volatility at time t as estimated at time t-1depends on the squared return and the estimated volatility at time t-1.

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GARCH Models (concluded)

- The estimate of volatility averages past squared returns by giving heavier weights to recent squared returns (see text).
- It is usually assumed that $a_1 + a_2 < 1$ and $a_0 > 0$, in which case the unconditional, long-run variance is given by $a_0/(1-a_1-a_2)$.
- A popular special case of GARCH(1, 1) is the exponentially weighted moving average process, which sets a_0 to zero and a_2 to $1 - a_1$.
- This model is used in J.P. Morgan's RiskMetricsTM.

^aBollerslev (1986) and Taylor (1986)

GARCH Option Pricing

- Options can be priced when the underlying asset's return follows a GARCH process.
- Let S_t denote the asset price at date t.
- Let h_t^2 be the conditional variance of the return over the period [t, t+1] given the information at date t.
 - "One day" is merely a convenient term for any elapsed time Δt .

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GARCH Option Pricing (continued)

• Adopt the following risk-neutral process for the price dynamics:^a

$$\ln \frac{S_{t+1}}{S_t} = r - \frac{h_t^2}{2} + h_t \epsilon_{t+1},\tag{78}$$

where

$$h_{t+1}^{2} = \beta_{0} + \beta_{1}h_{t}^{2} + \beta_{2}h_{t}^{2}(\epsilon_{t+1} - c)^{2},$$

$$\epsilon_{t+1} \sim N(0, 1) \text{ given information at date } t,$$

$$r = \text{daily riskless return,}$$

$$c \geq 0.$$

$$(79)$$

GARCH Option Pricing (continued)

- The five unknown parameters of the model are c, h_0 , β_0 , β_1 , and β_2 .
- It is postulated that $\beta_0, \beta_1, \beta_2 \geq 0$ to make the conditional variance positive.
- The above process, called the nonlinear asymmetric GARCH model, generalizes the GARCH(1, 1) model (see text).

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GARCH Option Pricing (concluded)

• With $y_t \equiv \ln S_t$ denoting the logarithmic price, the model becomes

$$y_{t+1} = y_t + r - \frac{h_t^2}{2} + h_t \epsilon_{t+1}. \tag{80}$$

- The pair (y_t, h_t^2) completely describes the current state.
- ullet The conditional mean and variance of y_{t+1} are clearly

$$E[y_{t+1} | y_t, h_t^2] = y_t + r - \frac{h_t^2}{2},$$
 (81)

$$Var[y_{t+1} | y_t, h_t^2] = h_t^2. (82)$$

^aDuan (1995).

The Ritchken-Trevor (RT) Algorithm^a

- The GARCH model is a continuous-state model.
- To approximate it, we turn to trees with discrete states.
- Path dependence in GARCH makes the tree for asset prices explode exponentially.
- We need to mitigate this combinatorial explosion somewhat.
- ^aRitchken and Trevor (1999).

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The Ritchken-Trevor Algorithm (continued)

- \bullet Partition a day into n periods.
- Three states follow each state (y_t, h_t^2) after a period.
- As the trinomial model combines, 2n + 1 states at date t + 1 follow each state at date t (recall p. 550).
- These 2n+1 values must approximate the distribution of (y_{t+1}, h_{t+1}^2) .
- So the conditional moments (81)–(82) at date t+1 on p. 723 must be matched by the trinomial model to guarantee convergence to the continuous-state model.

The Ritchken-Trevor Algorithm (continued)

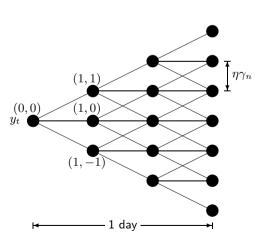
- It remains to pick the jump size and the three branching probabilities.
- The role of σ in the Black-Scholes option pricing model is played by h_t in the GARCH model.
- As a jump size proportional to σ/\sqrt{n} is picked in the BOPM, a comparable magnitude will be chosen here.
- Define $\gamma \equiv h_0$, though other multiples of h_0 are possible, and

$$\gamma_n \equiv \frac{\gamma}{\sqrt{n}}.$$

- The jump size will be some integer multiple η of γ_n .
- We call η the jump parameter (p. 727).

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The seven values on the right approximate the distribution of logarithmic price y_{t+1} .

The Ritchken-Trevor Algorithm (continued)

- The middle branch does not change the underlying asset's price.
- The probabilities for the up, middle, and down branches are

$$p_u = \frac{h_t^2}{2\eta^2 \gamma^2} + \frac{r - (h_t^2/2)}{2\eta \gamma \sqrt{n}}, \tag{83}$$

$$p_m = 1 - \frac{h_t^2}{\eta^2 \gamma^2}, \tag{84}$$

$$p_d = \frac{h_t^2}{2\eta^2 \gamma^2} - \frac{r - (h_t^2/2)}{2\eta \gamma \sqrt{n}}.$$
 (85)

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The Ritchken-Trevor Algorithm (continued)

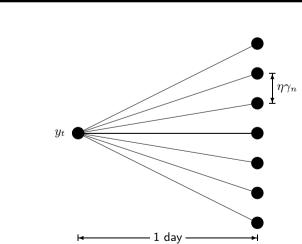
- It can be shown that:
 - The trinomial model takes on 2n+1 values at date t+1 for y_{t+1} .
 - These values have a matching mean for y_{t+1} .
 - These values have an asymptotically matching variance for y_{t+1} .
- ullet The central limit theorem thus guarantees the desired convergence as n increases.

The Ritchken-Trevor Algorithm (continued)

- We can dispense with the intermediate nodes between dates to create a (2n+1)-nomial tree (p. 731).
- The resulting model is multinomial with 2n + 1 branches from any state (y_t, h_t^2) .
- There are two reasons behind this manipulation.
 - Interdate nodes are created merely to approximate the continuous-state model after one day.
 - Keeping the interdate nodes results in a tree that is n times as large.

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This heptanomial tree is the outcome of the trinomial tree on p. 727 after its intermediate nodes are removed.

The Ritchken-Trevor Algorithm (continued)

- A node with logarithmic price $y_t + \ell \eta \gamma_n$ at date t+1 follows the current node at date t with price y_t for some $-n \leq \ell \leq n$.
- To reach that price in n periods, the number of up moves must exceed that of down moves by exactly ℓ .
- The probability that this happens is

$$P(\ell) \equiv \sum_{j_u, j_m, j_d} \frac{n!}{j_u! \, j_m! \, j_d!} \, p_u^{j_u} p_m^{j_m} p_d^{j_d},$$

with $j_u, j_m, j_d \ge 0$, $n = j_u + j_m + j_d$, and $\ell = j_u - j_d$.

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The Ritchken-Trevor Algorithm (continued)

• A particularly simple way to calculate the $P(\ell)$ s starts by noting that

$$(p_u x + p_m + p_d x^{-1})^n = \sum_{\ell=-n}^n P(\ell) x^{\ell}.$$
 (86)

- So we expand $(p_u x + p_m + p_d x^{-1})^n$ and retrieve the probabilities by reading off the coefficients.
- It can be computed in $O(n^2)$ time.

The Ritchken-Trevor Algorithm (continued)

- The updating rule (79) on p. 721 must be modified to account for the adoption of the discrete-state model.
- The logarithmic price $y_t + \ell \eta \gamma_n$ at date t+1 following state (y_t, h_t^2) at date t has a variance equal to

$$h_{t+1}^2 = \beta_0 + \beta_1 h_t^2 + \beta_2 h_t^2 (\epsilon_{t+1}' - c)^2, \tag{87}$$

- Above,

$$\epsilon'_{t+1} = \frac{\ell \eta \gamma_n - (r - h_t^2/2)}{h_t}, \quad \ell = 0, \pm 1, \pm 2, \dots, \pm n,$$

is a discrete random variable with 2n+1 values.

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The Ritchken-Trevor Algorithm (continued)

- Different conditional variances h_t^2 may require different η so that the probabilities calculated by Eqs. (83)–(85) on p. 728 lie between 0 and 1.
- This implies varying jump sizes.
- The necessary requirement $p_m \ge 0$ implies $\eta \ge h_t/\gamma$.
- Hence we try

$$\eta = \lceil h_t/\gamma \rceil, \lceil h_t/\gamma \rceil + 1, \lceil h_t/\gamma \rceil + 2, \dots$$

until valid probabilities are obtained or until their nonexistence is confirmed.

The Ritchken-Trevor Algorithm (continued)

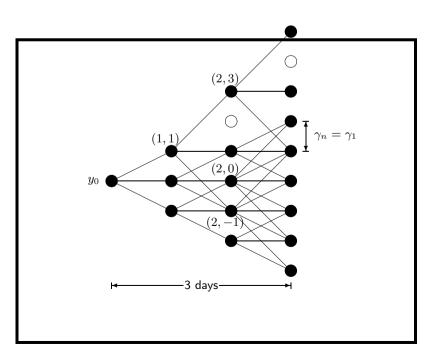
• The sufficient and necessary condition for valid probabilities to exist is

$$\frac{|r-(h_t^2/2)|}{2\eta\gamma\sqrt{n}} \leq \frac{h_t^2}{2\eta^2\gamma^2} \leq \min\left(1 - \frac{|r-(h_t^2/2)|}{2\eta\gamma\sqrt{n}}, \frac{1}{2}\right).$$

- Obviously, the magnitude of η tends to grow with h_t .
- The plot on p. 737 uses n = 1 to illustrate our points for a 3-day model.
- For example, node (1,1) of date 1 and node (2,3) of date 2 pick $\eta = 2$.

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The Ritchken-Trevor Algorithm (continued)

- The topology of the tree is not a standard combining multinomial tree.
- For example, a few nodes on p. 737 such as nodes (2,0) and (2,-1) have multiple jump sizes.
- The reason is the path dependence of the model.
 - Two paths can reach node (2,0) from the root node, each with a different variance for the node.
 - One of the variances results in $\eta = 1$, whereas the other results in $\eta = 2$.

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The Ritchken-Trevor Algorithm (concluded)

- The possible values of h_t^2 at a node are exponential nature.
- \bullet To address this problem, we record only the maximum and minimum $\,h_t^2\,$ at each node. $^{\rm a}$
- Therefore, each node on the tree contains only two states (y_t, h_{max}^2) and (y_t, h_{min}^2) .
- Each of (y_t, h_{max}^2) and (y_t, h_{min}^2) carries its own η and set of 2n+1 branching probabilities.

^aCakici and Topyan (2000).

Negative Aspects of the Ritchken-Trevor Algorithm^a

- \bullet A small n may yield inaccurate option prices.
- ullet But the tree will grow exponentially if n is large enough.
 - Specifically, $n > (1 \beta_1)/\beta_2$ when r = c = 0.
- \bullet A large n has another serious problem: The tree cannot grow beyond a certain date.
- Thus the choice of n may be limited in practice.
- The RT algorithm can be modified to be free of exponential complexity and shortened maturity.^b

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Numerical Examples

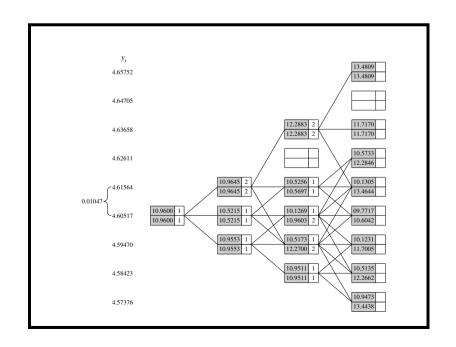
- Assume $S_0 = 100$, $y_0 = \ln S_0 = 4.60517$, r = 0, $h_0^2 = 0.0001096$, $\gamma = h_0 = 0.010469$, n = 1, $\gamma_n = \gamma/\sqrt{n} = 0.010469$, $\beta_0 = 0.000006575$, $\beta_1 = 0.9$, $\beta_2 = 0.04$, and c = 0.
- A daily variance of 0.0001096 corresponds to an annual volatility of $\sqrt{365 \times 0.0001096} \approx 20\%$.
- Let $h^2(i,j)$ denote the variance at node (i,j).
- Initially, $h^2(0,0) = h_0^2 = 0.0001096$.

Numerical Examples (continued)

- Let $h_{\text{max}}^2(i,j)$ denote the maximum variance at node (i,j).
- Let $h_{\min}^2(i,j)$ denote the minimum variance at node (i,j).
- Initially, $h_{\text{max}}^2(0,0) = h_{\text{min}}^2(0,0) = h_0^2$.
- The resulting three-day tree is depicted on p. 743.

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^aLyuu and Wu (2003).

^bLyuu and Wu (2005).

A top (bottom) number inside a gray box refers to the minimum (maximum, respectively) variance h_{\min}^2 (h_{\max}^2 , respectively) for the node. Variances are multiplied by 100,000 for readability. A top (bottom) number inside a white box refers to η corresponding to h_{\min}^2 (h_{\max}^2 , respectively).

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Numerical Examples (continued)

- Let us see how the numbers are calculated.
- Start with the root node, node (0,0).
- Try $\eta = 1$ in Eqs. (83)–(85) on p. 728 first to obtain

$$p_u = 0.4974,$$

$$p_m = 0,$$

 $p_d = 0.5026.$

• As they are valid probabilities, the three branches from the root node use single jumps.

Numerical Examples (continued)

- Move on to node (1,1).
- It has one predecessor node—node (0,0)—and it takes an up move to reach the current node.
- So apply updating rule (87) on p. 734 with $\ell=1$ and $h_t^2=h^2(0,0)$.
- The result is $h^2(1,1) = 0.000109645$.

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Numerical Examples (continued)

• Because $\lfloor h(1,1)/\gamma \rfloor = 2$, we try $\eta = 2$ in Eqs. (83)–(85) on p. 728 first to obtain

$$p_u = 0.1237,$$

$$p_m = 0.7499,$$

$$p_d = 0.1264.$$

• As they are valid probabilities, the three branches from node (1,1) use double jumps.

- Carry out similar calculations for node (1,0) with $\ell = 0$ in updating rule (87) on p. 734.
- Carry out similar calculations for node (1, -1) with $\ell = -1$ in updating rule (87).
- Single jump $\eta = 1$ works in both nodes.
- The resulting variances are

$$h^2(1,0) = 0.000105215,$$

 $h^2(1,-1) = 0.000109553.$

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Numerical Examples (continued)

- Node (2,0) has 2 predecessor nodes, (1,0) and (1,-1).
- Both have to be considered in deriving the variances.
- Let us start with node (1,0).
- Because it takes a middle move to reach the current node, we apply updating rule (87) on p. 734 with $\ell = 0$ and $h_t^2 = h^2(1,0)$.
- The result is $h_{t+1}^2 = 0.000101269$.

Numerical Examples (continued)

- Now move on to the other predecessor node (1, -1).
- Because it takes an up move to reach the current node, apply updating rule (87) on p. 734 with $\ell = 1$ and $h_t^2 = h^2(1, -1)$.
- The result is $h_{t+1}^2 = 0.000109603$.
- We hence record

$$h_{\min}^2(2,0) = 0.000101269,$$

 $h_{\max}^2(2,0) = 0.000109603.$

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Numerical Examples (continued)

- Consider state $h_{\text{max}}^2(2,0)$ first.
- Because $\lfloor h_{\max}(2,0)/\gamma \rfloor = 2$, we first try $\eta = 2$ in Eqs. (83)–(85) on p. 728 to obtain

$$p_u = 0.1237,$$

 $p_m = 0.7500,$
 $p_d = 0.1263.$

• As they are valid probabilities, the three branches from node (2,0) with the maximum variance use double jumps.

- Now consider state $h_{\min}^2(2,0)$.
- Because $|h_{\min}(2,0)/\gamma| = 1$, we first try $\eta = 1$ in Eqs. (83)–(85) on p. 728 to obtain

$$p_u = 0.4596,$$

$$p_m = 0.0760,$$

$$p_d = 0.4644.$$

• As they are valid probabilities, the three branches from node (2,0) with the minimum variance use single jumps.

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Numerical Examples (continued)

- Node (2, -1) has 3 predecessor nodes.
- Start with node (1,1).
- Because it takes a down move to reach the current node, we apply updating rule (87) on p. 734 with $\ell = -1$ and $h_t^2 = h^2(1,1).$
- The result is $h_{t+1}^2 = 0.0001227$.

Numerical Examples (continued)

- Now move on to predecessor node (1,0).
- Because it also takes a down move to reach the current node, we apply updating rule (87) on p. 734 with $\ell = -1$ and $h_t^2 = h^2(1,0)$.
- The result is $h_{t+1}^2 = 0.000105609$.

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Numerical Examples (continued)

- Finally, consider predecessor node (1, -1).
- Because it takes a middle move to reach the current node, we apply updating rule (87) on p. 734 with $\ell = 0$ and $h_t^2 = h^2(1, -1)$.
- The result is $h_{t+1}^2 = 0.000105173$.
- We hence record

$$h_{\min}^2(2,-1) = 0.000105173,$$

$$h_{\text{max}}^2(2,-1) = 0.0001227.$$

- Consider state $h_{\max}^2(2,-1)$.
- Because $\lfloor h_{\max}(2,-1)/\gamma \rfloor = 2$, we first try $\eta = 2$ in Eqs. (83)–(85) on p. 728 to obtain

$$p_u = 0.1385,$$

$$p_m = 0.7201,$$

$$p_d = 0.1414.$$

• As they are valid probabilities, the three branches from node (2,-1) with the maximum variance use double jumps.

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Numerical Examples (continued)

- Next, consider state $h_{\min}^2(2,-1)$.
- Because $\lfloor h_{\min}(2,-1)/\gamma \rfloor = 1$, we first try $\eta = 1$ in Eqs. (83)–(85) on p. 728 to obtain

$$p_u = 0.4773,$$

$$p_m = 0.0404,$$

$$p_d = 0.4823.$$

• As they are valid probabilities, the three branches from node (2,-1) with the minimum variance use single jumps.

Numerical Examples (concluded)

- Other nodes at dates 2 and 3 can be handled similarly.
- In general, if a node has k predecessor nodes, then 2k variances will be calculated using the updating rule.
 - This is because each predecessor node keeps two variance numbers.
- But only the maximum and minimum variances will be kept.

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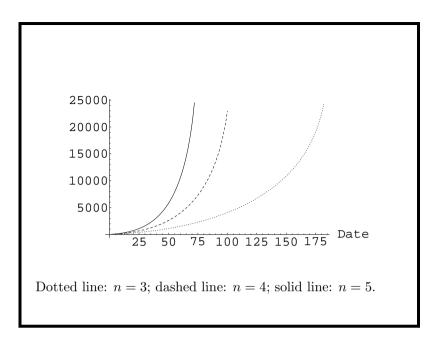
Negative Aspects of the RT Algorithm Revisited^a

- Recall the problems mentioned on p. 740.
- In our case, combinatorial explosion occurs when

$$n > \frac{1 - \beta_1}{\beta_2} = \frac{1 - 0.9}{0.04} = 2.5.$$

- Suppose we are willing to accept the exponential running time and pick n = 100 to seek accuracy.
- But the problem of shortened maturity forces the tree to stop at date 9!

^aLyuu and Wu (2003).



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Backward Induction on the RT Tree

- After the RT tree is constructed, it can be used to price options by backward induction.
- Recall that each node keeps two variances h_{max}^2 and h_{min}^2 .
- We now increase that number to K equally spaced variances between h_{max}^2 and h_{min}^2 at each node.
- Besides the minimum and maximum variances, the other K-2 variances in between are linearly interpolated.^a

Backward Induction on the RT Tree (continued)

- For example, if K=3, then a variance of 10.5436×10^{-6} will be added between the maximum and minimum variances at node (2,0) on p. 743.
- In general, the kth variance at node (i, j) is

$$h_{\min}^2(i,j) + k \frac{h_{\max}^2(i,j) - h_{\min}^2(i,j)}{K-1},$$

$$k = 0, 1, \dots, K - 1.$$

• Each interpolated variance's jump parameter and branching probabilities can be computed as before.

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Backward Induction on the RT Tree (concluded)

- During backward induction, if a variance falls between two of the K variances, linear interpolation of the option prices corresponding to the two bracketing variances will be used as the approximate option price.
- The above ideas are reminiscent of the ones on p. 319, where we dealt with arithmetic average-rate options.

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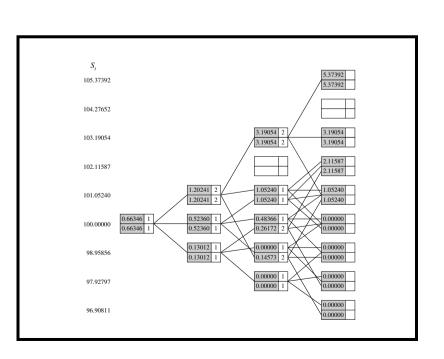
^aIn practice, log-linear interpolation works better; Lyuu and Wu (2005). Log-cubic interpolation works even better; Liu (2005).

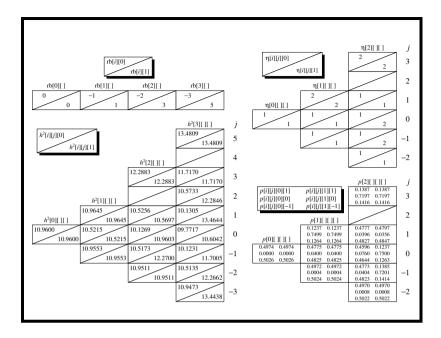
Numerical Examples

- We next use the numerical example on p. 743 to price a European call option with a strike price of 100 and expiring at date 3.
- Recall that the riskless interest rate is zero.
- Assume K = 2; hence there are no interpolated variances.
- The pricing tree is shown on p. 765 with a call price of 0.66346.
 - The branching probabilities needed in backward induction can be found on p. 766.

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Numerical Examples (continued)

- Let us derive some of the numbers on p. 765.
- The option price for a terminal node at date 3 equals $\max(S_3 100, 0)$, independent of the variance level.
- Now move on to nodes at date 2.
- The option price at node (2,3) depends on those at nodes (3,5), (3,3), and (3,1).
- It therefore equals

 $0.1387 \times 5.37392 + 0.7197 \times 3.19054 + 0.1416 \times 1.05240 = 3.19054.$

• Option prices for other nodes at date 2 can be computed similarly.

- For node (1, 1), the option price for both variances is $0.1237 \times 3.19054 + 0.7499 \times 1.05240 + 0.1264 \times 0.14573 = 1.20241.$
- Node (1,0) is most interesting.
- We knew that a down move from it gives a variance of 0.000105609.
- This number falls between the minimum variance 0.000105173 and the maximum variance 0.0001227 at node (2, -1) on p. 743.

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Numerical Examples (continued)

- The option price corresponding to the minimum variance is 0.
- The option price corresponding to the maximum variance is 0.14573.
- The equation

 $x \times 0.000105173 + (1-x) \times 0.0001227 = 0.000105609$ is satisfied by x = 0.9751.

• So the option for the down state is approximated by

$$x \times 0 + (1 - x) \times 0.14573 = 0.00362.$$

Numerical Examples (continued)

- The up move leads to the state with option price 1.05240.
- The middle move leads to the state with option price 0.48366.
- The option price at node (1,0) is finally calculated as $0.4775 \times 1.05240 + 0.0400 \times 0.48366 + 0.4825 \times 0.00362 = 0.52360$.

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Numerical Examples (concluded)

- It is possible for some of the three variances following an interpolated variance to exceed the maximum variance or be exceeded by the minimum variance.
- When this happens, the option price corresponding to the maximum or minimum variance will be used during backward induction.
- An interpolated variance may choose a branch that goes into a node that is not reached in the forward-induction tree-building phase.^a

^aLyuu and Wu (2005).