

## Acceptability and Recursively Enumerable Languages

- Let  $L \subseteq (\Sigma - \{\square\})^*$  be a language.
- Let  $M$  be a TM such that for any string  $x$ :
  - If  $x \in L$ , then  $M(x) = \text{“yes.”}$
  - If  $x \notin L$ , then  $M(x) = \nearrow$ .<sup>a</sup>
- We say  $M$  **accepts**  $L$ .
- It is in general difficult to verify that a TM decides or accepts a language.<sup>b</sup>

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<sup>a</sup>This part is different from recursive languages.

<sup>b</sup>Thanks to a lively discussion on September 23, 2014.

## Acceptability and Recursively Enumerable Languages (concluded)

- If  $L$  is accepted by some TM, then  $L$  is said to be **recursively enumerable** or **semidecidable**.<sup>a</sup>
  - A recursively enumerable language can be *generated* by a TM, thus the name.<sup>b</sup>
  - It means there is a program such that every  $x \in L$  (and only they) will be printed out eventually.
  - Of course, if  $L$  is infinite in size, this program will not terminate.

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<sup>a</sup>Post (1944).

<sup>b</sup>Thanks to a lively class discussion on September 20, 2011.

Emil Post (1897–1954)



## Recursive and Recursively Enumerable Languages

**Proposition 2** *If  $L$  is recursive, then it is recursively enumerable.*

- Let TM  $M$  decide  $L$ .
- Need to design a TM that accepts  $L$ .
- We will modify  $M$  to obtain an  $M'$  that accepts  $L$ .

## The Proof (concluded)

- $M'$  is identical to  $M$  except that when  $M$  is about to halt with a “no” state,  $M'$  goes into an infinite loop.
  - Simply replace any instruction that results in a “no” state with ones that move the cursor to the right forever and never halts.
- $M'$  accepts  $L$ .
  - If  $x \in L$ , then  $M'(x) = M(x) = \text{“yes.”}$
  - If  $x \notin L$ , then  $M(x) = \text{“no”}$  and so  $M'(x) = \nearrow$ .

## Recursively Enumerable Languages: Examples

- The set of C program-input pairs that do not run into an infinite loop is recursively enumerable.
  - Just run its binary code in a simulator environment.
  - Then the simulator will terminate if and only if the C program will terminate.
  - When the C program terminates, the simulator simply exits with a “yes” state.
- The set of C programs that contain an infinite loop is *not* recursively enumerable (see p. 151).

## Turing-Computable Functions

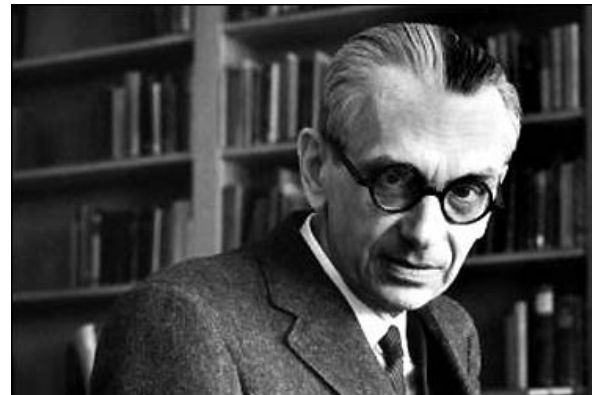
- Let  $f : (\Sigma - \{\sqcup\})^* \rightarrow \Sigma^*$ .
  - Optimization problems, root finding problems, etc.
- Let  $M$  be a TM with alphabet  $\Sigma$ .
- $M$  **computes**  $f$  if for any string  $x \in (\Sigma - \{\sqcup\})^*$ ,  
 $M(x) = f(x)$ .
- We call  $f$  a **recursive function**<sup>a</sup> if such an  $M$  exists.

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<sup>a</sup>Kurt Gödel (1931, 1934).

## Kurt Gödel<sup>a</sup> (1906–1978)

Quine (1978), “this theorem [...] sealed his immortality.”



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<sup>a</sup>This photo was taken by Alfred Eisenstaedt (1898–1995).



## Church's Thesis or the Church-Turing Thesis

- What is computable is Turing-computable; TMs are algorithms.<sup>a</sup>
- No “intuitively computable” problems have been shown not to be Turing-computable, yet.<sup>b</sup>

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<sup>a</sup>Church (1936); Kleene (1953).

<sup>b</sup>Quantum computer of Manin (1980) and Feynman (1982) and DNA computer of Adleman (1994).

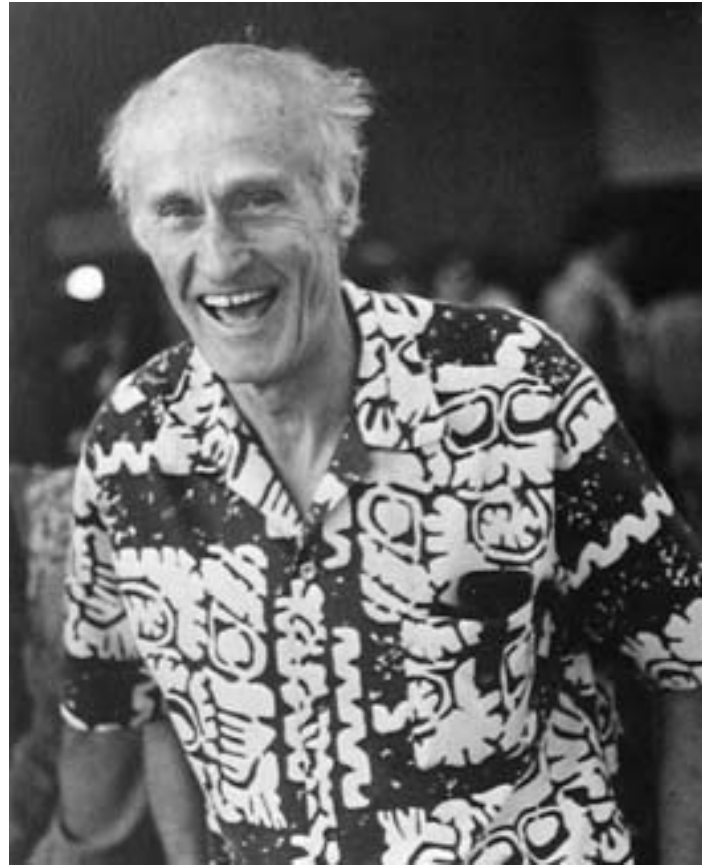
## Church's Thesis or the Church-Turing Thesis (concluded)

- Many other computation models have been proposed.
  - Recursive function (Gödel),  $\lambda$  calculus (Church), formal language (Post), assembly language-like RAM (Shepherdson & Sturgis), boolean circuits (Shannon), extensions of the Turing machine (more strings, two-dimensional strings, and so on), etc.
- All have been proved to be equivalent.

## Alonso Church (1903–1995)



## Stephen Kleene (1909–1994)



## Extended Church's Thesis<sup>a</sup>

- All “reasonably succinct encodings” of problems are *polynomially related* (e.g.,  $n^2$  vs.  $n^6$ ).
  - Representations of a graph as an adjacency matrix and as a linked list are both succinct.
  - The *unary* representation of numbers is not succinct.
  - The *binary* representation of numbers is succinct.
    - \*  $1001_2$  vs.  $111111111_1$ .
- All numbers for TMs will be binary from now on.

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<sup>a</sup>Some call it “polynomial Church's thesis,” which Lószló Lovász attributed to Leonid Levin.

## Extended Church's Thesis (concluded)

- Representations that are not succinct may give misleadingly low complexities.
  - Consider an algorithm with binary inputs that runs in  $2^n$  steps.
  - Suppose the input uses unary representation instead.
  - Then the same algorithm runs in linear time because the input length is now  $2^n$ !
- So a succinct representation is for honest accounting.

## Physical Church-Turing Thesis

- Church's thesis

is a profound claim about the physical laws of our universe, i.e.: any physical system that purports to be a 'computer' is not capable of any computational task that a Turing machine is incapable of.<sup>a</sup>

- Church's and extended Church's theses

are not statements about mathematics, but rather conjectured constraints on physical laws.<sup>b</sup>

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<sup>a</sup>Warren Smith (1998).

<sup>b</sup>Yao (2003).

## Physical Church-Turing Thesis (concluded)

- The **physical Church-Turing thesis** states that:  
Anything computable in physics can also be computed on a Turing machine.<sup>a</sup>
- The universe is a Turing machine.<sup>b</sup>

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<sup>a</sup>Cooper (2012).

<sup>b</sup>Edward Fredkin's (1992) digital physics.



## The Strong Church-Turing Thesis<sup>a</sup>

- The **strong Church-Turing thesis** states that:

A Turing machine can compute *any* function computable by any “reasonable” physical device with only polynomial slowdown.<sup>b</sup>

- A CPU and a DSP chip are good examples of physical devices.<sup>c</sup>

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<sup>a</sup>Vergis, Steiglitz, and Dickinson (1986).

<sup>b</sup><http://ocw.mit.edu/courses/mathematics/18-405j-advanced-complexity-theory-fall-2001/lecture-notes/lecture10.pdf>

<sup>c</sup>Thanks to a lively discussion on September 23, 2014.

## The Strong Church-Turing Thesis (concluded)

- Factoring is believed to be a hard problem for Turing machines (but there is no proof yet).
- But a quantum computer can factor numbers in probabilistic polynomial time.<sup>a</sup>
- So if a large-scale quantum computer can be reliably built, the strong Church-Turing thesis may be refuted.<sup>b</sup>

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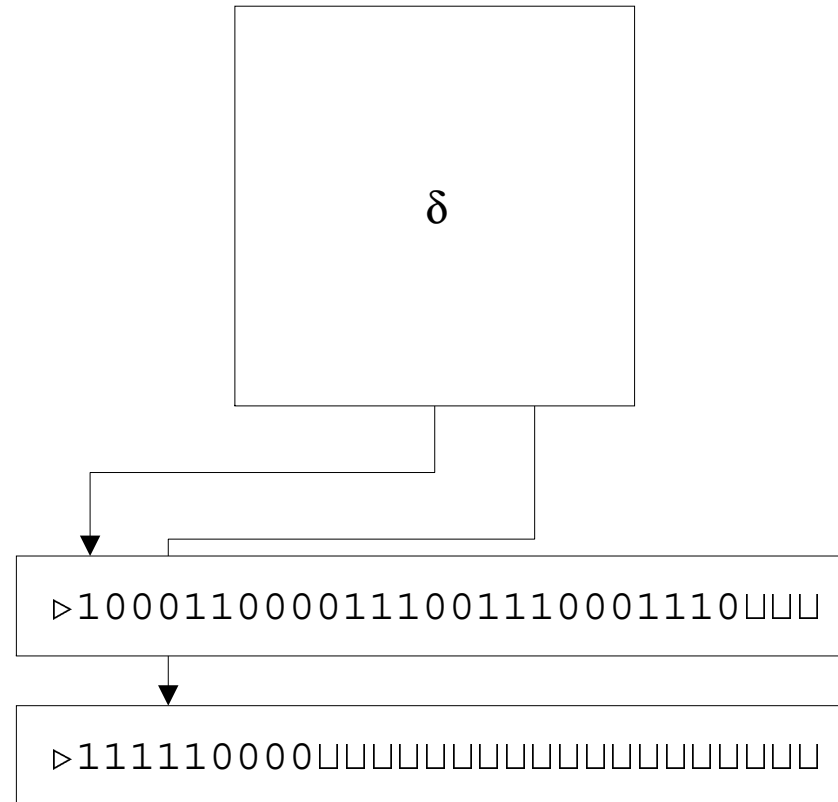
<sup>a</sup>Shor (1994).

<sup>b</sup>Contributed by Mr. Kai-Yuan Hou (B99201038, R03922014) on September 22, 2015.

## Turing Machines with Multiple Strings

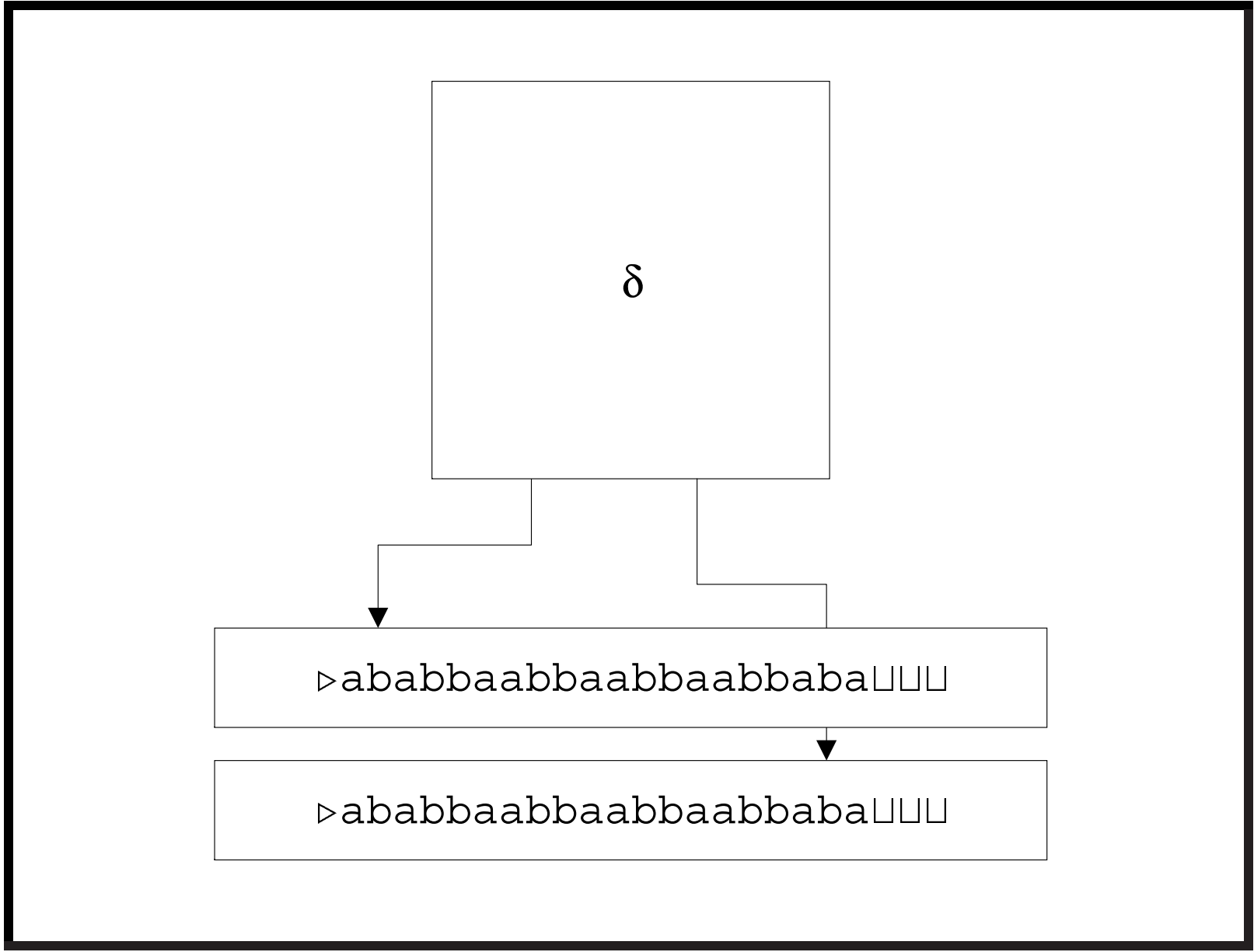
- A  $k$ -string Turing machine (TM) is a quadruple  $M = (K, \Sigma, \delta, s)$ .
- $K, \Sigma, s$  are as before.
- $\delta : K \times \Sigma^k \rightarrow (K \cup \{h, \text{“yes”}, \text{“no”}\}) \times (\Sigma \times \{\leftarrow, \rightarrow, -\})^k$ .
- All strings start with a  $\triangleright$ .
- The first string contains the input.
- Decidability and acceptability are the same as before.
- When TMs compute functions, the output is the last ( $k$ th) string.

# A 2-String TM



## PALINDROME Revisited

- A 2-string TM can decide PALINDROME in  $O(n)$  steps.
  - It copies the input to the second string.
  - The cursor of the first string is positioned at the first symbol of the input.
  - The cursor of the second string is positioned at the last symbol of the input.
  - The symbols under the cursors are then compared.
  - The two cursors are then moved in opposite directions until the ends are reached.
  - The machine accepts if and only if the symbols under the two cursors are identical at all steps.



## PALINDROME Revisited (concluded)

- The running times of a 2-string TM and a single-string TM are quadratically related:  $n^2$  vs.  $n$ .
- This is consistent with the extended Church's thesis.
  - “Reasonable” models are related polynomially in running times.

## Configurations and Yielding

- The concept of configuration and yielding is the same as before except that a configuration is a  $(2k + 1)$ -tuple

$$(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k).$$

- $w_i u_i$  is the  $i$ th string.
  - The  $i$ th cursor is reading the last symbol of  $w_i$ .
  - Recall that  $\triangleright$  is each  $w_i$ 's first symbol.
- The  $k$ -string TM's initial configuration is

$$(s, \underbrace{\triangleright, x}_{1}, \underbrace{\triangleright, \epsilon}_{2}, \underbrace{\triangleright, \epsilon}_{3}, \dots, \underbrace{\triangleright, \epsilon}_{k}).$$



Time seemed to be  
the most obvious measure  
of complexity.  
— Stephen Arthur Cook (1939–)

## Time Complexity

- The multistring TM is the basis of our notion of the time expended by TMs.
- If a  $k$ -string TM  $M$  halts after  $t$  steps on input  $x$ , then the **time required by  $M$  on input  $x$**  is  $t$ .
- If  $M(x) = \nearrow$ , then the time required by  $M$  on  $x$  is  $\infty$ .

## Time Complexity (concluded)

- Machine  $M$  **operates within time**  $f(n)$  for  $f : \mathbb{N} \rightarrow \mathbb{N}$  if for any input string  $x$ , the time required by  $M$  on  $x$  is at most  $f(|x|)$ .
  - $|x|$  is the length of string  $x$ .
- Function  $f(n)$  is a **time bound** for  $M$ .

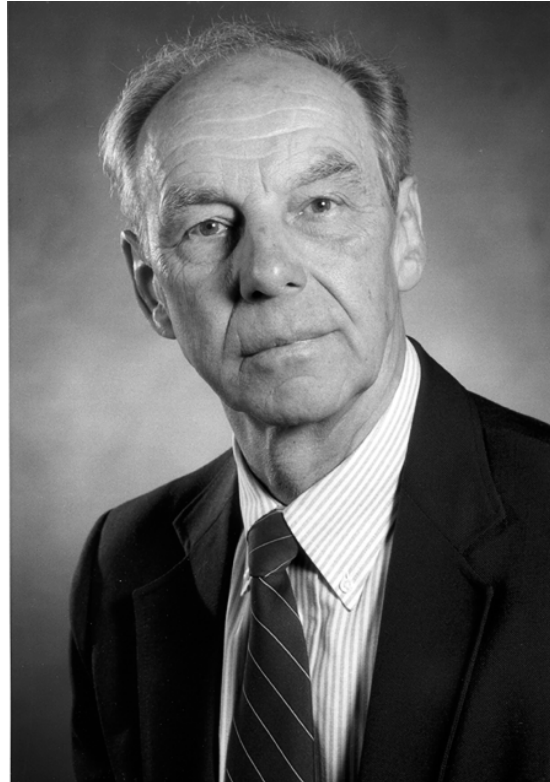
## Time Complexity Classes<sup>a</sup>

- Suppose language  $L \subseteq (\Sigma - \{\sqcup\})^*$  is decided by a multistring TM operating in time  $f(n)$ .
- We say  $L \in \text{TIME}(f(n))$ .
- $\text{TIME}(f(n))$  is the set of languages decided by TMs with multiple strings operating within time bound  $f(n)$ .
- $\text{TIME}(f(n))$  is a **complexity class**.
  - PALINDROME is in  $\text{TIME}(f(n))$ , where  $f(n) = O(n)$ .

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<sup>a</sup>Hartmanis and Stearns (1965); Hartmanis, Lewis, and Stearns (1965).

## Juris Hartmanis<sup>a</sup> (1928–)



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<sup>a</sup>Turing Award (1993).

## Richard Edwin Stearns<sup>a</sup> (1936–)



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<sup>a</sup>Turing Award (1993).

## The Simulation Technique

**Theorem 3** *Given any  $k$ -string  $M$  operating within time  $f(n)$ , there exists a (single-string)  $M'$  operating within time  $O(f(n)^2)$  such that  $M(x) = M'(x)$  for any input  $x$ .*

- The single string of  $M'$  implements the  $k$  strings of  $M$ .

## The Proof

- Represent configuration  $(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k)$  of  $M$  by this string of  $M'$ :

$$(q, \triangleright w'_1 u_1 \triangleleft w'_2 u_2 \triangleleft \dots \triangleleft w'_k u_k \triangleleft \triangleleft).$$

- $\triangleleft$  is a special delimiter.
- $w'_i$  is  $w_i$  with the first<sup>a</sup> and last symbols “primed.”
- It serves the purpose of “,” in a configuration.<sup>b</sup>

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<sup>a</sup>The first symbol is always  $\triangleright$ .

<sup>b</sup>An alternative is to use  $(q, \triangleright w'_1 u_1, ' \triangleleft w'_2, ' u_2 \triangleleft \dots \triangleleft w'_k, ' u_k \triangleleft \triangleleft)$  by priming only  $\triangleright$  in  $w_i$ , where “,'” is a new symbol.



## The Proof (continued)

- The “priming” of the last symbol of  $w_i$  ensures that  $M'$  knows which symbol is under each cursor of  $M$ .<sup>a</sup>
- The first symbol of  $w_i$  is the primed version of  $\triangleright$ :  $\triangleright'$ .
  - Recall TM cursors are not allowed to move to the left of  $\triangleright$  (p. 21).
  - Now the cursor of  $M'$  can move *between* the simulated strings of  $M$ .<sup>b</sup>

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<sup>a</sup>Added because of comments made by Mr. Che-Wei Chang (R95922093) on September 27, 2006.

<sup>b</sup>Thanks to a lively discussion on September 22, 2009.

## The Proof (continued)

- The initial configuration of  $M'$  is

$$(s, \triangleright \triangleright'' x \triangleleft \overbrace{\triangleright'' \triangleleft \cdots \triangleright'' \triangleleft}^{k-1 \text{ pairs}} \triangleleft).$$

- $\triangleright''$  is double-primed because it is the beginning and the ending symbol as the cursor is reading it.<sup>a</sup>

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<sup>a</sup>Added after the class discussion on September 20, 2011.

## The Proof (continued)

- We simulate each move of  $M$  thus:
  1.  $M'$  scans the string to pick up the  $k$  symbols under the cursors.
    - The states of  $M'$  must be enlarged to include  $K \times \Sigma^k$  to remember them.<sup>a</sup>
    - The transition functions of  $M'$  must also reflect it.
  2.  $M'$  then changes the string to reflect the overwriting of symbols and cursor movements of  $M$ .

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<sup>a</sup>Recall the TM program on p. 27.

## The Proof (continued)

- It is possible that some strings of  $M$  need to be lengthened (see next page).
  - The linear-time algorithm on p. 33 can be used for each such string.
- The simulation continues until  $M$  halts.
- $M'$  then erases all strings of  $M$  except the last one.<sup>a</sup>

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<sup>a</sup>Because whatever appears on the string of  $M'$  will be considered the output. So those  $\triangleright$ 's and  $\triangleright$ ''s need to be removed.

## The Proof (continued)<sup>a</sup>

|          |          |          |          |
|----------|----------|----------|----------|
| string 1 | string 2 | string 3 | string 4 |
|----------|----------|----------|----------|

|          |          |          |  |          |
|----------|----------|----------|--|----------|
| string 1 | string 2 | string 3 |  | string 4 |
|----------|----------|----------|--|----------|

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<sup>a</sup>If we interleave the strings, the simulation may be easier. Contributed by Mr. Kai-Yuan Hou (B99201038, R03922014) on September 22, 2015.

## The Proof (continued)

- Since  $M$  halts within time  $f(|x|)$ , none of its strings ever becomes longer than  $f(|x|)$ .<sup>a</sup>
- The length of the string of  $M'$  at any time is  $O(kf(|x|))$ .
- Simulating each step of  $M$  takes, *per string of  $M$* ,  $O(kf(|x|))$  steps.
  - $O(f(|x|))$  steps to collect information from this string.
  - $O(kf(|x|))$  steps to write and, if needed, to lengthen the string.

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<sup>a</sup>We tacitly assume  $f(n) \geq n$ .

## The Proof (concluded)

- $M'$  takes  $O(k^2 f(|x|))$  steps to simulate each step of  $M$  because there are  $k$  strings.
- As there are  $f(|x|)$  steps of  $M$  to simulate,  $M'$  operates within time  $O(k^2 f(|x|)^2)$ .<sup>a</sup>

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<sup>a</sup>Is the time reduced to  $O(kf(|x|)^2)$  if the interleaving data structure is adopted?

## Linear Speedup<sup>a</sup>

**Theorem 4** *Let  $L \in TIME(f(n))$ . Then for any  $\epsilon > 0$ ,  $L \in TIME(f'(n))$ , where  $f'(n) = \epsilon f(n) + n + 2$ .*

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<sup>a</sup>Hartmanis and Stearns (1965).



## Implications of the Speedup Theorem

- State size can be traded for speed.<sup>a</sup>
- If  $f(n) = cn$  with  $c > 1$ , then  $c$  can be made arbitrarily close to 1.
- If  $f(n)$  is superlinear, say  $f(n) = 14n^2 + 31n$ , then the constant in the leading term (14 in this example) can be made arbitrarily small.
  - *Arbitrary* linear speedup can be achieved.<sup>b</sup>
  - This justifies the big-O notation in the analysis of algorithms.

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<sup>a</sup> $m^k \cdot |\Sigma|^{3mk}$ -fold increase to gain a speedup of  $O(m)$ . No free lunch.

<sup>b</sup>Can you apply the theorem multiple times to achieve superlinear speedup? Thanks to a question by a student on September 21, 2010.

## P

- By the linear speedup theorem, any polynomial time bound can be represented by its leading term  $n^k$  for some  $k \geq 1$ .
- If  $L \in \text{TIME}(n^k)$  for some  $k \in \mathbb{N}$ , it is a **polynomially decidable language**.
  - Clearly,  $\text{TIME}(n^k) \subseteq \text{TIME}(n^{k+1})$ .
- The union of all polynomially decidable languages is denoted by P:

$$P = \bigcup_{k>0} \text{TIME}(n^k).$$

- P contains problems that can be efficiently solved.

Philosophers have explained space.  
They have not explained time.  
— Arnold Bennett (1867–1931),  
*How To Live on 24 Hours a Day* (1910)

I keep bumping into that silly quotation  
attributed to me that says  
640K of memory is enough.  
— Bill Gates (1996)

## Space Complexity

- Consider a  $k$ -string TM  $M$  with input  $x$ .
- Assume non- $\sqcup$  is never written over by  $\sqcup$ .<sup>a</sup>
  - The purpose is not to artificially reduce the space needs (see below).
- If  $M$  halts in configuration

$$(H, w_1, u_1, w_2, u_2, \dots, w_k, u_k),$$

then the **space required by  $M$  on input  $x$**  is

$$\sum_{i=1}^k |w_i u_i|.$$

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<sup>a</sup>Corrected by Ms. Chuan-Ju Wang (R95922018, F95922018) on September 27, 2006.

## Space Complexity (continued)

- Suppose we do not charge the space used only for input and output.
- Let  $k > 2$  be an integer.
- A  **$k$ -string Turing machine with input and output** is a  $k$ -string TM that satisfies the following conditions.
  - The input string is *read-only*.
  - The last string, the output string, is *write-only*.
    - \* So the cursor never moves to the left.
  - The cursor of the input string does not wander off into the  $\square$ s.

## Space Complexity (concluded)

- If  $M$  is a TM with input and output, then the space required by  $M$  on input  $x$  is

$$\sum_{i=2}^{k-1} |w_i u_i|.$$

- Machine  $M$  **operates within space bound**  $f(n)$  for  $f : \mathbb{N} \rightarrow \mathbb{N}$  if for any input  $x$ , the space required by  $M$  on  $x$  is at most  $f(|x|)$ .

## Space Complexity Classes

- Let  $L$  be a language.
- Then

$$L \in \text{SPACE}(f(n))$$

if there is a TM with input and output that decides  $L$  and operates within space bound  $f(n)$ .

- $\text{SPACE}(f(n))$  is a set of languages.
  - $\text{PALINDROME} \in \text{SPACE}(\log n)$ .<sup>a</sup>
- As in the linear speedup theorem (p. 88), constant coefficients do not matter.

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<sup>a</sup>Keep 3 counters.

## Nondeterminism<sup>a</sup>

- A **nondeterministic Turing machine (NTM)** is a quadruple  $N = (K, \Sigma, \Delta, s)$ .
- $K, \Sigma, s$  are as before.
- $\Delta \subseteq K \times \Sigma \times (K \cup \{h, \text{“yes”}, \text{“no”}\}) \times \Sigma \times \{\leftarrow, \rightarrow, -\}$  is a relation, not a function.<sup>b</sup>
  - For each state-symbol combination  $(q, \sigma)$ , there may be multiple valid next steps.
  - Multiple lines of code may be applicable.

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<sup>a</sup>Rabin and Scott (1959).

<sup>b</sup>Corrected by Mr. Jung-Ying Chen (D95723006) on September 23, 2008.



## Nondeterminism (continued)

- As before, a program contains lines of code:

$$(q_1, \sigma_1, p_1, \rho_1, D_1) \in \Delta,$$

$$(q_2, \sigma_2, p_2, \rho_2, D_2) \in \Delta,$$

⋮

$$(q_n, \sigma_n, p_n, \rho_n, D_n) \in \Delta.$$

- We cannot write

$$\delta(q_i, \sigma_i) = (p_i, \rho_i, D_i)$$

as in the deterministic case (p. 22) anymore.

## Nondeterminism (concluded)

- A configuration yields another configuration in one step if there *exists* a rule in  $\Delta$  that makes this happen.
- But only one will be taken.
- So there is only a single thread of computation.<sup>a</sup>
  - Nondeterminism is no parallelism.

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<sup>a</sup>Thanks to a lively discussion on September 22, 2015.

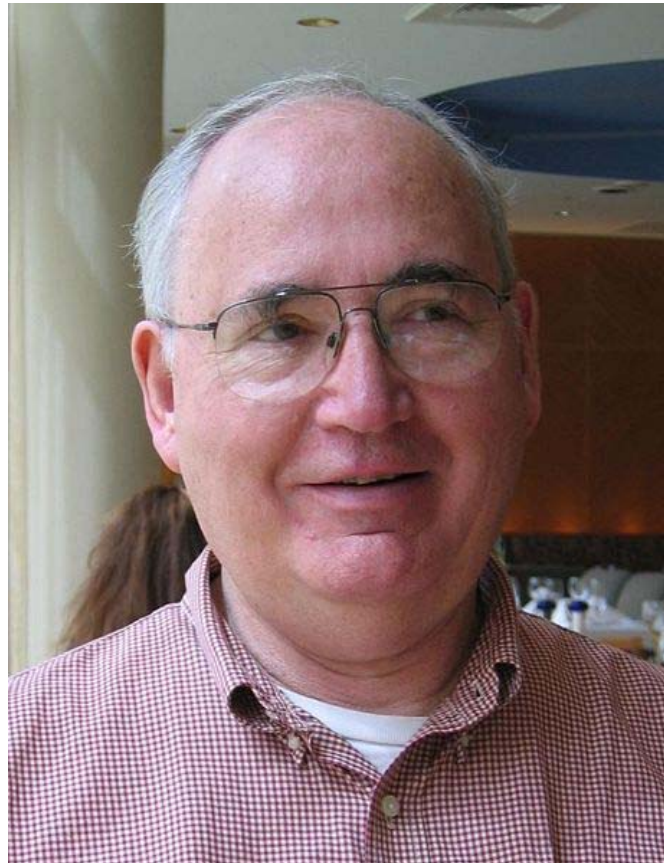
## Michael O. Rabin<sup>a</sup> (1931–)



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<sup>a</sup>Turing Award (1976).

## Dana Stewart Scott<sup>a</sup> (1932–)



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<sup>a</sup>Turing Award (1976).

## Computation Tree and Computation Path

