

## Turing-Computable Functions

- Let  $f : (\Sigma - \{\sqcup\})^* \rightarrow \Sigma^*$ .
  - Optimization problems, root finding problems, etc.
- Let  $M$  be a TM with alphabet  $\Sigma$ .
- $M$  **computes**  $f$  if for any string  $x \in (\Sigma - \{\sqcup\})^*$ ,  
 $M(x) = f(x)$ .
- We call  $f$  a **recursive function**<sup>a</sup> if such an  $M$  exists.

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<sup>a</sup>Kurt Gödel (1931).

Kurt Gödel (1906–1978)



## Church's Thesis or the Church-Turing Thesis

- What is computable is Turing-computable; TMs are algorithms (Kleene 1953).
- Many other computation models have been proposed.
  - Recursive function (Gödel),  $\lambda$  calculus (Church), formal language (Post), assembly language-like RAM (Shepherdson & Sturgis), boolean circuits (Shannon), extensions of the Turing machine (more strings, two-dimensional strings, and so on), etc.
- All have been proved to be equivalent.
- No “intuitively computable” problems have been shown not to be Turing-computable yet.

## Church's Thesis or the Church-Turing Thesis (concluded)

- The thesis may sound merely definitional at first.
- It can also be interpreted as<sup>a</sup>  
a profound claim about the physical laws of our universe, i.e.: any physical system that purports to be a computer is not capable of any computational task that a Turing machine is incapable of.

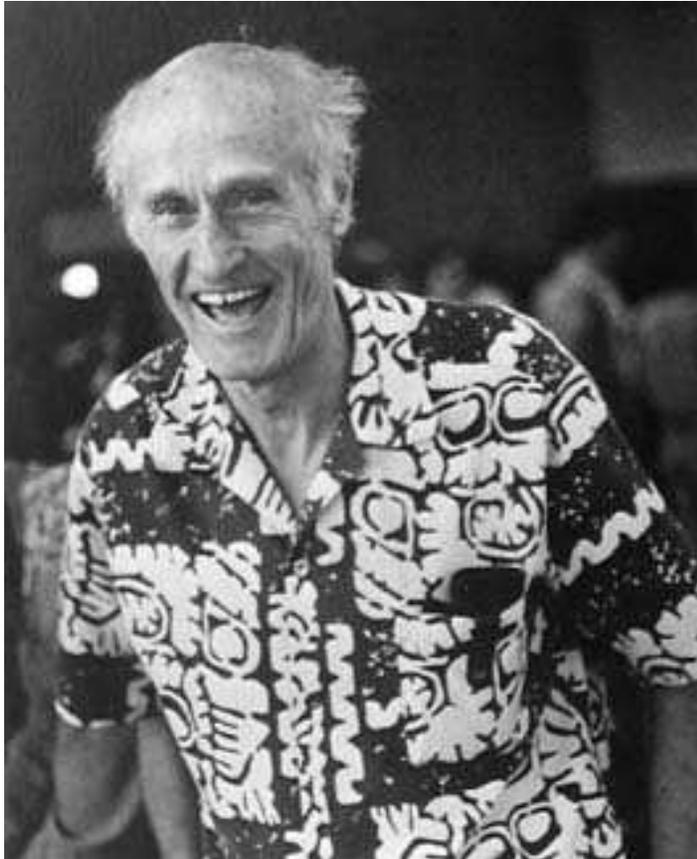
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<sup>a</sup>Smith (1998).

## Alonso Church (1903–1995)



## Stephen Kleene (1909–1994)



## Extended Church's Thesis<sup>a</sup>

- All “reasonably succinct encodings” of problems are *polynomially related*.
  - Representations of a graph as an adjacency matrix and as a linked list are both succinct.
  - The *unary* representation of numbers is not succinct.
  - The *binary* representation of numbers is succinct.
    - \* 1001 vs. 11111111.
- All numbers for TMs will be binary from now on.

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<sup>a</sup>Some call it “polynomial Church's thesis,” which Lószló Lovász attributed to Leonid Levin.

## Turing Machines with Multiple Strings

- A  $k$ -string Turing machine (TM) is a quadruple  $M = (K, \Sigma, \delta, s)$ .
- $K, \Sigma, s$  are as before.
- $\delta : K \times \Sigma^k \rightarrow (K \cup \{h, \text{“yes”}, \text{“no”}\}) \times (\Sigma \times \{\leftarrow, \rightarrow, -\})^k$ .
- All strings start with a  $\triangleright$ .
- The first string contains the input.
- Decidability and acceptability are the same as before.
- When TMs compute functions, the output is on the last ( $k$ th) string.



## PALINDROME Revisited

- A 2-string TM can decide PALINDROME in  $O(n)$  steps.
  - It copies the input to the second string.
  - The cursor of the first string is positioned at the first symbol of the input.
  - The cursor of the second string is positioned at the last symbol of the input.
  - The two cursors are then moved in opposite directions until the ends are reached.
  - The machine accepts if and only if the symbols under the two cursors are identical at all steps.



## Configurations and Yielding

- The concept of configuration and yielding is the same as before except that a configuration is a  $(2k + 1)$ -triple

$$(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k).$$

- $w_i u_i$  is the  $i$ th string.
  - The  $i$ th cursor is reading the last symbol of  $w_i$ .
  - Recall that  $\triangleright$  is each  $w_i$ 's first symbol.
- The  $k$ -string TM's initial configuration is

$$(s, \underbrace{\triangleright, x}_{1}, \underbrace{\triangleright, \epsilon}_{2}, \underbrace{\triangleright, \epsilon}_{3}, \dots, \underbrace{\triangleright, \epsilon}_{k}).$$

## Time Complexity

- The multistring TM is the basis of our notion of the time expended by TM computations.
- If a  $k$ -string TM  $M$  halts after  $t$  steps on input  $x$ , then the **time required by  $M$  on input  $x$**  is  $t$ .
- If  $M(x) = \nearrow$ , then the time required by  $M$  on  $x$  is  $\infty$ .
- Machine  $M$  **operates within time  $f(n)$**  for  $f : \mathbb{N} \rightarrow \mathbb{N}$  if for any input string  $x$ , the time required by  $M$  on  $x$  is at most  $f(|x|)$ .
  - $|x|$  is the length of string  $x$ .
- Function  $f(n)$  is a **time bound** for  $M$ .

## Time Complexity Classes<sup>a</sup>

- Suppose language  $L \subseteq (\Sigma - \{\sqcup\})^*$  is decided by a multistring TM operating in time  $f(n)$ .
- We say  $L \in \text{TIME}(f(n))$ .
- $\text{TIME}(f(n))$  is the set of languages decided by TMs with multiple strings operating within time bound  $f(n)$ .
- $\text{TIME}(f(n))$  is a **complexity class**.
  - PALINDROME is in  $\text{TIME}(f(n))$ , where  $f(n) = O(n)$ .

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<sup>a</sup>Hartmanis and Stearns (1965); Hartmanis, Lewis, and Stearns (1965).

## The Simulation Technique

**Theorem 2** *Given any  $k$ -string  $M$  operating within time  $f(n)$ , there exists a (single-string)  $M'$  operating within time  $O(f(n)^2)$  such that  $M(x) = M'(x)$  for any input  $x$ .*

- The single string of  $M'$  implements the  $k$  strings of  $M$ .
- Represent configuration  $(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k)$  of  $M$  by configuration

$$(q, \triangleright w'_1 u_1 \triangleleft w'_2 u_2 \triangleleft \dots \triangleleft w'_k u_k \triangleleft \triangleleft)$$

of  $M'$ .

- $\triangleleft$  is a special delimiter.
- $w'_i$  is  $w_i$  with the first<sup>a</sup> and last symbols “primed.”

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<sup>a</sup>The first symbol is always  $\triangleright$ .

## The Proof (continued)

- The “priming” of the last symbol of  $w_i$  ensures that  $M'$  knows which symbol is under the cursor for each simulated string.<sup>a</sup>
- Recall the requirement on p. 17 that  $\delta(q, \triangleright) = (p, \triangleright, \rightarrow)$  so that the cursor is not allowed to move to the left of  $\triangleright$ .
- We use the primed version of the first symbol of  $w_i$  (so  $\triangleright$  becomes  $\triangleright'$ ).
- That ensures the single cursor of  $M'$  can move *between* the simulated strings of  $M$ .<sup>b</sup>

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<sup>a</sup>Added because of comments made by Mr. Che-Wei Chang (R95922093) on September 27, 2006.

<sup>b</sup>Thanks to a lively discussion on September 22, 2009.

## The Proof (continued)

- The initial configuration of  $M'$  is

$$(s, \triangleright \triangleright' x \triangleleft \overbrace{\triangleright' \triangleleft \cdots \triangleright' \triangleleft}^{k-1 \text{ pairs}} \triangleleft).$$

- We simulate each move of  $M$  thus:
  1.  $M'$  scans the string to pick up the  $k$  symbols under the cursors.
    - The states of  $M'$  must be enlarged to include  $K \times \Sigma^k$  to remember them.
    - The transition functions of  $M'$  must also reflect it.
  2.  $M'$  then changes the string to reflect the overwriting of symbols and cursor movements of  $M$ .

## The Proof (continued)

- It is possible that some strings of  $M$  need to be lengthened (see next page).
  - The linear-time algorithm on p. 32 can be used for each such string.
- The simulation continues until  $M$  halts.
- $M'$  erases all strings of  $M$  except the last one.
- Since  $M$  halts within time  $f(|x|)$ , none of its strings ever becomes longer than  $f(|x|)$ .<sup>a</sup>
- The length of the string of  $M'$  at any time is  $O(kf(|x|))$ .

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<sup>a</sup>We tacitly assume  $f(n) \geq n$ .

string 1	string 2	string 3	string 4
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string 1	string 2	string 3		string 4
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## The Proof (concluded)

- Simulating each step of  $M$  takes, *per string of  $M$* ,  $O(kf(|x|))$  steps.
  - $O(f(|x|))$  steps to collect information.
  - $O(kf(|x|))$  steps to write and, if needed, to lengthen the string.
- $M'$  takes  $O(k^2 f(|x|))$  steps to simulate each step of  $M$  because there are  $k$  strings.
- As there are  $f(|x|)$  steps of  $M$  to simulate,  $M'$  operates within time  $O(k^2 f(|x|)^2)$ .

## Linear Speedup<sup>a</sup>

**Theorem 3** *Let  $L \in \text{TIME}(f(n))$ . Then for any  $\epsilon > 0$ ,  $L \in \text{TIME}(f'(n))$ , where  $f'(n) = \epsilon f(n) + n + 2$ .*

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<sup>a</sup>Hartmanis and Stearns (1965).

## Implications of the Speedup Theorem

- State size can be traded for speed.
  - $m^k \cdot |\Sigma|^{3mk}$ -fold increase to gain a speedup of  $O(m)$ .
- If  $f(n) = cn$  with  $c > 1$ , then  $c$  can be made arbitrarily close to 1.
- If  $f(n)$  is superlinear, say  $f(n) = 14n^2 + 31n$ , then the constant in the leading term (14 in this example) can be made arbitrarily small.
  - *Arbitrary* linear speedup can be achieved.
  - This justifies the asymptotic big-O notation.

## P

- By the linear speedup theorem, any polynomial time bound can be represented by its leading term  $n^k$  for some  $k \geq 1$ .
- If  $L$  is a polynomially decidable language, it is in  $\text{TIME}(n^k)$  for some  $k \in \mathbb{N}$ .
  - Clearly,  $\text{TIME}(n^k) \subseteq \text{TIME}(n^{k+1})$ .
- The union of all polynomially decidable languages is denoted by P:

$$P = \bigcup_{k>0} \text{TIME}(n^k).$$

- P contains problems that can be efficiently solved.

## Space Complexity

- Consider a  $k$ -string TM  $M$  with input  $x$ .
- Assume non- $\sqcup$  is never written over by  $\sqcup$ .<sup>a</sup>
  - The purpose is not to artificially downplay the space requirement.
- If  $M$  halts in configuration  $(H, w_1, u_1, w_2, u_2, \dots, w_k, u_k)$ , then the **space required by  $M$  on input  $x$**  is  $\sum_{i=1}^k |w_i u_i|$ .

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<sup>a</sup>Corrected by Ms. Chuan-Ju Wang (R95922018) on September 27, 2006.

## Space Complexity (continued)

- We do not charge the space used only for input and output.
- Let  $k > 2$  be an integer.
- A  **$k$ -string Turing machine with input and output** is a  $k$ -string TM that satisfies the following conditions.
  - The input string is *read-only*.
  - The last string, the output string, is *write-only*.
  - So the cursor never moves to the left.
  - The cursor of the input string does not wander off into the  $\square$ s.

## Space Complexity (concluded)

- If  $M$  is a TM with input and output, then the space required by  $M$  on input  $x$  is  $\sum_{i=2}^{k-1} |w_i u_i|$ .
- Machine  $M$  **operates within space bound**  $f(n)$  for  $f : \mathbb{N} \rightarrow \mathbb{N}$  if for any input  $x$ , the space required by  $M$  on  $x$  is at most  $f(|x|)$ .

## Space Complexity Classes

- Let  $L$  be a language.
- Then

$$L \in \text{SPACE}(f(n))$$

if there is a TM with input and output that decides  $L$  and operates within space bound  $f(n)$ .

- $\text{SPACE}(f(n))$  is a set of languages.
  - $\text{PALINDROME} \in \text{SPACE}(\log n)$ : Keep 3 counters.
- As in the linear speedup theorem (Theorem 3), constant coefficients do not matter.

## Nondeterminism<sup>a</sup>

- A **nondeterministic Turing machine (NTM)** is a quadruple  $N = (K, \Sigma, \Delta, s)$ .
- $K, \Sigma, s$  are as before.
- $\Delta \subseteq K \times \Sigma \times (K \cup \{h, \text{“yes”}, \text{“no”}\}) \times \Sigma \times \{\leftarrow, \rightarrow, -\}$  is a relation, not a function.<sup>b</sup>
  - For each state-symbol combination, there may be multiple valid next steps—or none at all.
  - Multiple instructions may be applicable.

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<sup>a</sup>Rabin and Scott (1959).

<sup>b</sup>Corrected by Mr. Chen, Jung-Ying (D95723006) on September 23, 2008.

## Nondeterminism (concluded)

- Think of the program as lines of codes:

$$(q_1, \sigma_1, p_1, \rho_1, D_1) \in \Delta,$$

$$(q_2, \sigma_2, p_2, \rho_2, D_2) \in \Delta,$$

⋮

$$(q_n, \sigma_n, p_n, \rho_n, D_n) \in \Delta.$$

- A configuration yields another configuration in one step if there *exists* a rule in  $\Delta$  that makes this happen.

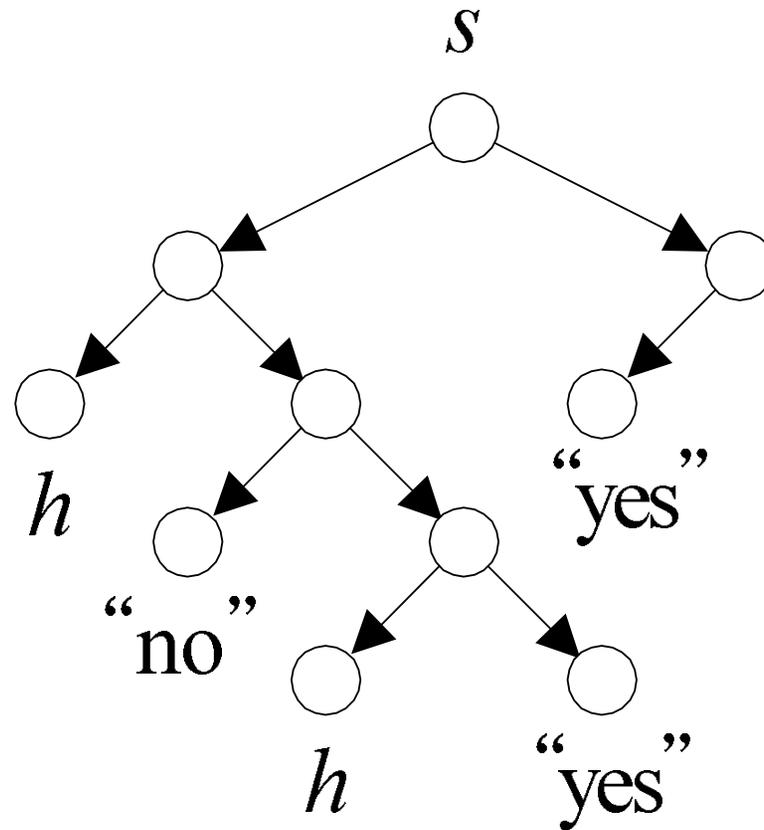
Michael O. Rabin (1931–)



## Dana Stewart Scott (1932–)



## Computation Tree and Computation Path



## Decidability under Nondeterminism

- Let  $L$  be a language and  $N$  be an NTM.
- $N$  **decides**  $L$  if for any  $x \in \Sigma^*$ ,  $x \in L$  if and only if there is a sequence of valid configurations that ends in “yes.”
  - It is not required that the NTM halts in all computation paths.<sup>a</sup>
  - If  $x \notin L$ , no nondeterministic choices should lead to a “yes” state.
- What is key is the algorithm’s overall behavior not whether it gives a correct answer for each particular run.
- Determinism is a special case of nondeterminism.

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<sup>a</sup>So “accepts” may be a more proper term here.

## An Example

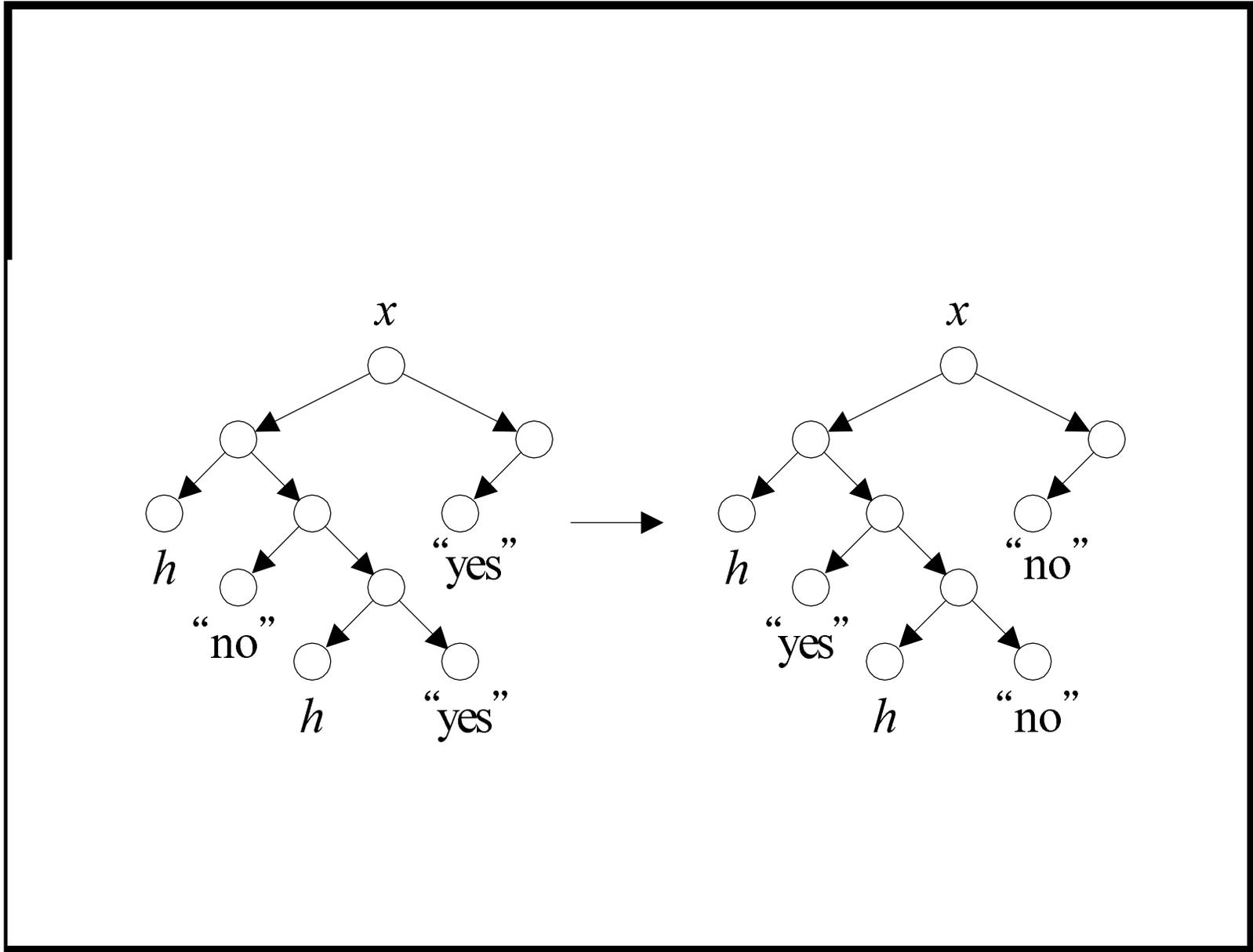
- Let  $L$  be the set of logical conclusions of a set of axioms.
  - Predicates not in  $L$  may be false under the axioms.
  - They may also be independent of the axioms.
    - \* That is, they can be assumed true or false without contradicting the axioms.

## An Example (concluded)

- Let  $\phi$  be a predicate whose validity we would like to prove.
- Consider the nondeterministic algorithm:
  - 1:  $b := \text{true};$
  - 2: **while** the input predicate  $\phi \neq b$  **do**
  - 3:     Generate a logical conclusion of  $b$  by applying one of the axioms; {Nondeterministic choice.}
  - 4:     Assign this conclusion to  $b$ ;
  - 5: **end while**
  - 6: “yes”;
- This algorithm decides  $L$ .

## Complementing a TM's Halting States

- Let  $M$  decide  $L$ , and  $M'$  be  $M$  after “yes”  $\leftrightarrow$  “no”.
- If  $M$  is a (deterministic) TM, then  $M'$  decides  $\bar{L}$ .
- But if  $M$  is an NTM, then  $M'$  may not decide  $\bar{L}$ .
  - It is possible that both  $M$  and  $M'$  accept  $x$  (see next page).
  - When this happens,  $M$  and  $M'$  accept languages that are not complements of each other.



## Time Complexity under Nondeterminism

- Nondeterministic machine  $N$  decides  $L$  **in time**  $f(n)$ , where  $f : \mathbb{N} \rightarrow \mathbb{N}$ , if
  - $N$  decides  $L$ , and
  - for any  $x \in \Sigma^*$ ,  $N$  does not have a computation path longer than  $f(|x|)$ .
- We charge only the “depth” of the computation tree.

## Time Complexity Classes under Nondeterminism

- $\text{NTIME}(f(n))$  is the set of languages decided by NTMs within time  $f(n)$ .
- $\text{NTIME}(f(n))$  is a complexity class.

## NP

- Define

$$\text{NP} = \bigcup_{k>0} \text{NTIME}(n^k).$$

- Clearly  $P \subseteq \text{NP}$ .
- Think of NP as efficiently *verifiable* problems.
  - Boolean satisfiability (p. 146).
- The most important open problem in computer science is whether  $P = \text{NP}$ .

## Simulating Nondeterministic TMs

Surprisingly, nondeterminism does not add power to TMs.

**Theorem 4** *Suppose language  $L$  is decided by an NTM  $N$  in time  $f(n)$ . Then it is decided by a 3-string deterministic TM  $M$  in time  $O(c^{f(n)})$ , where  $c > 1$  is some constant depending on  $N$ .*

- On input  $x$ ,  $M$  goes down every computation path of  $N$  using *depth-first* search.
  - $M$  does *not* need to know  $f(n)$ .
  - As  $N$  is time-bounded, the depth-first search will not run indefinitely.

## The Proof (concluded)

- If some path leads to “yes,” then  $M$  enters the “yes” state.
- If none of the paths leads to “yes,” then  $M$  enters the “no” state.

**Corollary 5**  $\text{NTIME}(f(n)) \subseteq \bigcup_{c>1} \text{TIME}(c^{f(n)})$ .

## NTIME vs. TIME

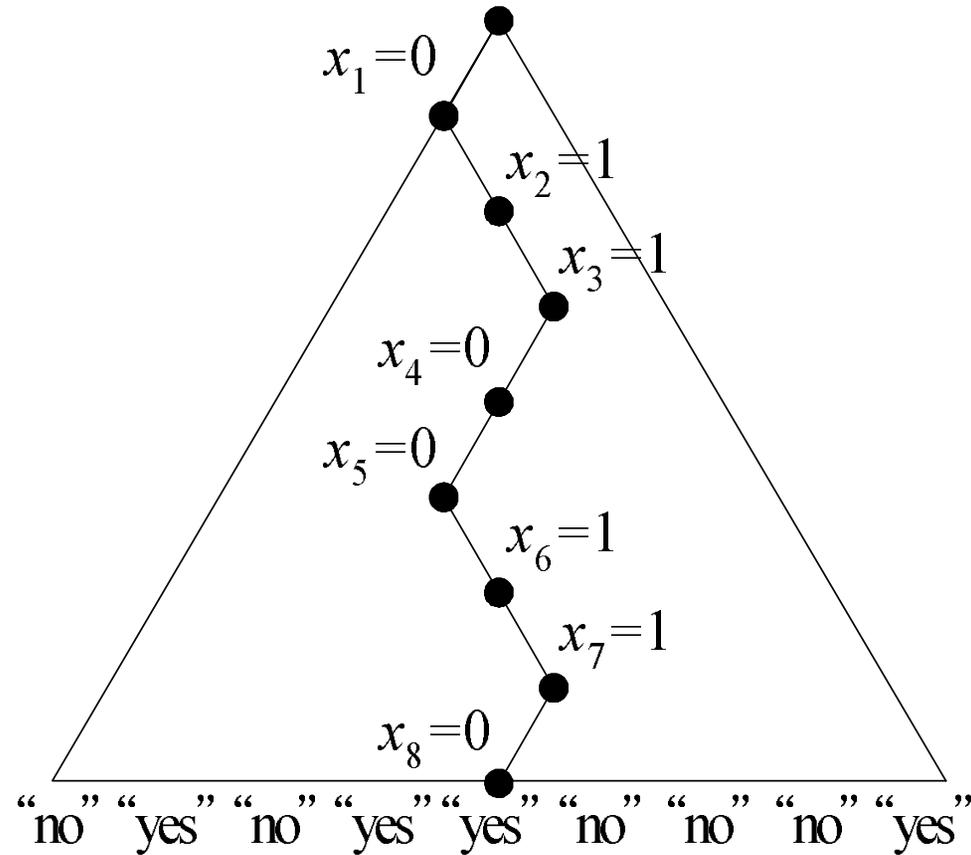
- Does converting an NTM into a TM require exploring all of the computation paths of the NTM as done in Theorem 4 (p. 81)?
- This is the most important question in theory with practical implications.

## A Nondeterministic Algorithm for Satisfiability

$\phi$  is a boolean formula with  $n$  variables.

- 1: **for**  $i = 1, 2, \dots, n$  **do**
- 2:     Guess  $x_i \in \{0, 1\}$ ; {Nondeterministic choice.}
- 3: **end for**
- 4: {Verification:}
- 5: **if**  $\phi(x_1, x_2, \dots, x_n) = 1$  **then**
- 6:     “yes”;
- 7: **else**
- 8:     “no”;
- 9: **end if**

## The Computation Tree for Satisfiability



## Analysis

- The algorithm decides language  $\{\phi : \phi \text{ is satisfiable}\}$ .
  - The computation tree is a complete binary tree of depth  $n$ .
  - Every computation path corresponds to a particular truth assignment out of  $2^n$ .
  - $\phi$  is satisfiable if and only if there is a computation path (truth assignment) that results in “yes.”
- General paradigm: Guess a “proof” and then verify it.

## The Traveling Salesman Problem

- We are given  $n$  cities  $1, 2, \dots, n$  and integer distances  $d_{ij}$  between any two cities  $i$  and  $j$ .
- Assume  $d_{ij} = d_{ji}$  for convenience.
- The **traveling salesman problem** (TSP) asks for the total distance of the shortest tour of the cities.
- The decision version TSP (D) asks if there is a tour with a total distance at most  $B$ , where  $B$  is an input.
- Both problems are extremely important but equally hard (p. 338 and p. 438).

## A Nondeterministic Algorithm for TSP (D)

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1: for  $i = 1, 2, \dots, n$  do
2:   Guess  $x_i \in \{1, 2, \dots, n\}$ ; {The  $i$ th city.}a
3: end for
4:  $x_{n+1} := x_1$ ;
5: {Verification stage:}
6: if  $x_1, x_2, \dots, x_n$  are distinct and  $\sum_{i=1}^n d_{x_i, x_{i+1}} \leq B$  then
7:   “yes”;
8: else
9:   “no”;
10: end if
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<sup>a</sup>Can be made into a series of  $\log_2 n$  binary choices for each  $x_i$  so that the next-state count (2) is a constant, independent of input size. Contributed by Mr. Chih-Duo Hong (R95922079) on September 27, 2006.