

Theory of Computation Lecture Notes

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Problems and Algorithms

Class Information

- Papadimitriou. *Computational Complexity*. 2nd printing. Addison-Wesley. 1995.

- Check

www.csie.ntu.edu.tw/~lyuu/complexity/2006

for lecture notes.

I have never done anything “useful.”
— Godfrey Harold Hardy (1877–1947),
A Mathematician’s Apology (1940)

What This Course Is All About

Computability: What can be computed?

- What is computation anyway?
- There are *well-defined* problems that cannot be computed.
- In fact, “most” problems cannot be computed.

Tractability and intractability

- Polynomial in terms of the input size n defines tractability.
 - $n, n \log n, n^2, n^{90}$.
 - Time, space, circuit size, number of random bits, etc.
- It results in a fruitful and practical theory of complexity.
- Few practical, tractable problems require a large degree.
- Exponential-time or superpolynomial-time algorithms are usually impractical.
 - $n^{\log n}, 2^{\sqrt{n}}, 2^n, n! \sim \sqrt{2\pi n} (n/e)^n$.

What This Course Is All About (concluded)

Complexity: What is a computable problem’s inherent complexity?

- Some computable problems require at least exponential time and/or space; they are **intractable**.
 - Can’t you let the Moore law take care of it?^a
- Some practical problems require superpolynomial resources unless certain conjectures are disproved.
- Other resource limits besides time and space?
 - Program size, circuit size (growth), number of random bits, etc.

^aContributed by Ms. Amy Liu (J94922016) on May 15, 2006.

Growth of Factorials

n	$n!$	n	$n!$
1	1	9	362,880
2	2	10	3,628,800
3	6	11	39,916,800
4	24	12	479,001,600
5	120	13	6,227,020,800
6	720	14	87,178,291,200
7	5040	15	1,307,674,368,000
8	40320	16	20,922,789,888,000

Turing Machines

Turing Machines^a

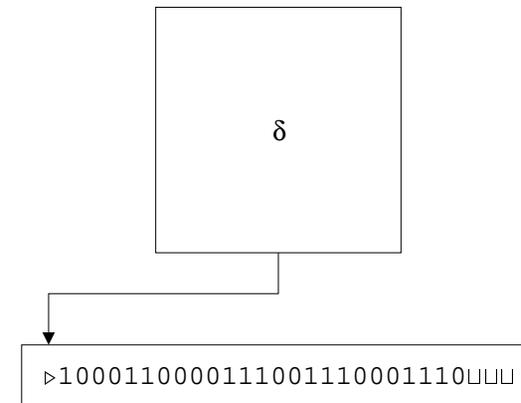
- A Turing machine (TM) is a quadruple $M = (K, \Sigma, \delta, s)$.
- K is a finite set of **states**.
- $s \in K$ is the **initial state**.
- Σ is a finite set of **symbols** (disjoint from K).
 - Σ includes \sqcup (blank) and \triangleright (first symbol).
- $\delta : K \times \Sigma \rightarrow (K \cup \{h, \text{“yes”}, \text{“no”}\}) \times \Sigma \times \{\leftarrow, \rightarrow, -\}$ is a **transition function**.
 - \leftarrow (left), \rightarrow (right), and $-$ (stay) signify cursor movements.

^aTuring (1936).

What Is Computation?

- That can be coded in an **algorithm**.
- An algorithm is a detailed step-by-step method for solving a problem.
 - The Euclidean algorithm for the greatest common divisor is an algorithm.
 - “Let s be the least upper bound of compact set A ” is not an algorithm.
 - “Let s be a smallest element of a finite-sized array” can be solved by an algorithm.

A TM Schema



“Physical” Interpretations

- The tape: computer memory and registers.
- δ : program.
- K : instruction numbers.
- s : “main()” in C.
- Σ : **alphabet** much like the ASCII code.

The Operations of TMs

- Initially the state is s .
- The string on the tape is initialized to a \triangleright , followed by a *finite-length* string $x \in (\Sigma - \{\sqcup\})^*$.
- x is the **input** of the TM.
 - The input must not contain \sqcup s (why?)!
- The cursor is pointing to the first symbol, always a \triangleright .
- The TM takes each step according to δ .
- The cursor may overwrite \sqcup to make the string longer during the computation.

More about δ

- The program has the **halting state** (h), the **accepting state** (“yes”), and the **rejecting state** (“no”).
- Given current state $q \in K$ and current symbol $\sigma \in \Sigma$,

$$\delta(q, \sigma) = (p, \rho, D).$$

- It specifies the next state p , the symbol ρ to be written over σ , and the direction D the cursor will move *afterwards*.
- We require $\delta(q, \triangleright) = (p, \triangleright, \rightarrow)$ so that the cursor never falls off the left end of the string.

The Halting of a TM

- A TM M may **halt** in three cases.
 - “**yes**”: M **accepts** its input x , and $M(x) = \text{“yes”}$.
 - “**no**”: M **rejects** its input x , and $M(x) = \text{“no”}$.
 - h : $M(x) = y$, where the string consists of a \triangleright , followed by a finite string y , whose last symbol is not \sqcup , followed by a string of \sqcup s.
 - y is the **output** of the computation.
 - y may be empty denoted by ϵ .
- If M never halts on x , then write $M(x) = \nearrow$.

Why TMs?

- Because of the simplicity of the TM, the model has the advantage when it comes to complexity issues.
- One can develop a complexity theory based on C++ or Java, say.
- But the added complexity does not yield additional fundamental insights.
- We will describe TMs in pseudocode.

Remarks (concluded)

- Any computation model must be physically realizable.
 - A model that requires nearly infinite precision to build is not physically realizable.
 - For example, if the TM required a voltage of 100 ± 10^{-100} to work, it would not be considered a successful model for computation.

Remarks

- A problem is computable if there is a TM that halts with the correct answer.
 - If a TM (i.e., program) does not always halt, it does not solve the problem, assuming the problem is computable.^a
 - OS does not halt as it does not solve a well-defined problem (but parts of it do).^b

^aContributed by Ms. Amy Liu (J94922016) on May 15, 2006. Control-C is not a legitimate way to halt a program.

^bContributed by Mr. Shuai-Peng Huang (J94922019) on May 15, 2006.

The Concept of Configuration

- A **configuration** is a complete description of the current state of the computation.
- The specification of a configuration is sufficient for the computation to continue as if it had not been stopped.
 - What does your PC save before it sleeps?
 - Enough for it to resume work later.

Configurations (concluded)

- A configuration is a triple (q, w, u) :
 - $q \in K$.
 - $w \in \Sigma^*$ is the string to the left of the cursor (inclusive).
 - $u \in \Sigma^*$ is the string to the right of the cursor.
- Note that (w, u) describes both the string and the cursor position.

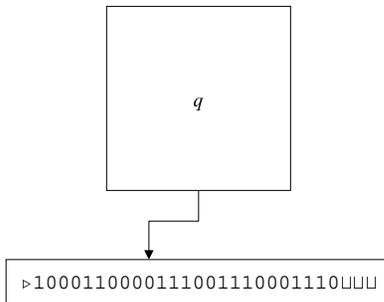
Yielding

- Fix a TM M .
- Configuration (q, w, u) **yields** configuration (q', w', u') in one step,

$$(q, w, u) \xrightarrow{M} (q', w', u'),$$

if a step of M from configuration (q, w, u) results in configuration (q', w', u') .

- $(q, w, u) \xrightarrow{M^k} (q', w', u')$: Configuration (q, w, u) yields configuration (q', w', u') in $k \in \mathbb{N}$ steps.
- $(q, w, u) \xrightarrow{M^*} (q', w', u')$: Configuration (q, w, u) yields configuration (q', w', u') .



- $w = \triangleright 1000110000$.
- $u = 111001110001110$.

Example: How to Insert a Symbol

- We want to compute $f(x) = ax$.
 - The TM moves the last symbol of x to the right by one position.
 - It then moves the next to last symbol to the right, and so on.
 - The TM finally writes a in the first position.
- The total number of steps is $O(n)$, where n is the length of x .

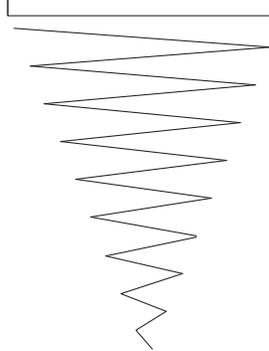
Palindromes

- A string is a **palindrome** if it reads the same forwards and backwards (e.g., 001100).
- A TM program can be written to recognize palindromes:
 - It matches the first character with the last character.
 - It matches the second character with the next to last character, etc. (see next page).
 - “yes” for palindromes and “no” for nonpalindromes.
- This program takes $O(n^2)$ steps.
- Can we do better?

Decidability and Recursive Languages

- Let $L \subseteq (\Sigma - \{\sqcup\})^*$ be a **language**, i.e., a set of strings of symbols with a finite length.
 - For example, $\{0, 01, 10, 210, 1010, \dots\}$.
- Let M be a TM such that for any string x :
 - If $x \in L$, then $M(x) = \text{“yes.”}$
 - If $x \notin L$, then $M(x) = \text{“no.”}$
- We say M **decides** L .
- If L is decided by some TM, then L is **recursive**.
 - Palindromes over $\{0, 1\}^*$ are recursive.

100011000000100111



Acceptability and Recursively Enumerable Languages

- Let $L \subseteq (\Sigma - \{\sqcup\})^*$ be a language.
- Let M be a TM such that for any string x :
 - If $x \in L$, then $M(x) = \text{“yes.”}$
 - If $x \notin L$, then $M(x) = \nearrow$.
- We say M **accepts** L .

Acceptability and Recursively Enumerable Languages (concluded)

- If L is accepted by some TM, then L is a **recursively enumerable language**.
 - A recursively enumerable language can be generated by a TM, thus the name.
 - That is, there is an algorithm such that for every $x \in L$, it will be printed out eventually.

Turing-Computable Functions

- Let $f : (\Sigma - \{\sqcup\})^* \rightarrow \Sigma^*$.
 - Optimization problems, root finding problems, etc.
- Let M be a TM with alphabet Σ .
- M **computes** f if for any string $x \in (\Sigma - \{\sqcup\})^*$,
 $M(x) = f(x)$.
- We call f a **recursive function**^a if such an M exists.

^aGödel (1931).

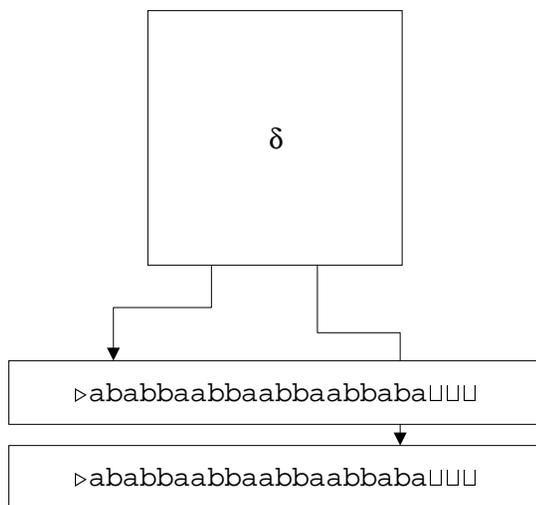
Recursive and Recursively Enumerable Languages

Proposition 1 *If L is recursive, then it is recursively enumerable.*

- We need to design a TM that accepts L .
- Let TM M decide L .
- We next modify M 's program to obtain M' that accepts L .
- M' is identical to M except that when M is about to halt with a “no” state, M' goes into an infinite loop.
- M' accepts L .

Church's Thesis or the Church-Turing Thesis

- What is computable is Turing-computable; TMs are algorithms (Kleene 1953).
- Many other computation models have been proposed.
 - Recursive function (Gödel), λ calculus (Church), formal language (Post), assembly language-like RAM (Shepherdson & Sturgis), boolean circuits (Shannon), extensions of the Turing machine (more strings, two-dimensional strings, and so on), etc.
- All have been proved to be equivalent.
- No “intuitively computable” problems have been shown not to be Turing-computable (yet).



Time Complexity

- The multistring TM is the basis of our notion of the time expended by TM computations.
- If for a k -string TM M and input x , the TM halts after t steps, then the **time required by M on input x** is t .
- If $M(x) = \nearrow$, then the time required by M on x is ∞ .
- Machine M **operates within time** $f(n)$ for $f : \mathbb{N} \rightarrow \mathbb{N}$ if for any input string x , the time required by M on x is at most $f(|x|)$.
 - $|x|$ is the length of string x .
 - Function $f(n)$ is a **time bound** for M .

Configurations and Yielding

- The concept of configuration and yielding is the same as before except that a configuration is a $(2k + 1)$ -triple

$$(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k).$$

- $w_i u_i$ is the i th string.
- The i th cursor is reading the last symbol of w_i .
- Recall that \triangleright is each w_i 's first symbol.
- The k -string TM's initial configuration is

$$(s, \overbrace{\triangleright, x, \triangleright, \epsilon, \triangleright, \epsilon, \dots, \triangleright, \epsilon}^{2k}).$$

Time Complexity Classes^a

- Suppose language $L \subseteq (\Sigma - \{\sqcup\})^*$ is decided by a multistring TM operating in time $f(n)$.
- We say $L \in \text{TIME}(f(n))$.
- $\text{TIME}(f(n))$ is the set of languages decided by TMs with multiple strings operating within time bound $f(n)$.
- $\text{TIME}(f(n))$ is a **complexity class**.
 - PALINDROME is in $\text{TIME}(f(n))$, where $f(n) = O(n)$.

^aHartmanis and Stearns (1965), Hartmanis, Lewis, and Stearns (1965).

The Simulation Technique

Theorem 2 Given any k -string M operating within time $f(n)$, there exists a (single-string) M' operating within time $O(f(n)^2)$ such that $M(x) = M'(x)$ for any input x .

- The single string of M' implements the k strings of M .
- Represent configuration $(q, w_1, u_1, w_2, u_2, \dots, w_k, u_k)$ of M by configuration

$$(q, \triangleright w'_1 u_1 \triangleleft w'_2 u_2 \triangleleft \dots \triangleleft w'_k u_k \triangleleft \triangleleft)$$

of M' .

- \triangleleft is a special delimiter.
- w'_i is w_i with the first and last symbols “primed.”

The Proof (continued)

- It is possible that some strings of M need to be lengthened.
 - The linear-time algorithm on p. 22 can be used for each such string.
- The simulation continues until M halts.
- M' erases all strings of M except the last one.
- Since M halts within time $f(|x|)$, none of its strings ever becomes longer than $f(|x|)$.^a
- The length of the string of M' at any time is $O(kf(|x|))$.

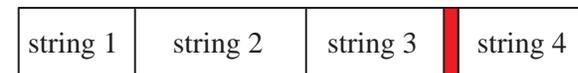
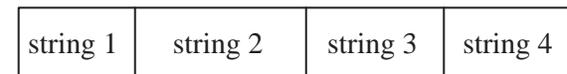
^aWe tacitly assume $f(n) \geq n$.

The Proof (continued)

- The initial configuration of M' is

$$(s, \triangleright \triangleright' x \triangleleft \overbrace{\triangleright' \triangleleft \dots \triangleright' \triangleleft}^{k-1 \text{ pairs}} \triangleleft \triangleleft)$$

- To simulate each move of M :
 - M' scans the string to pick up the k symbols under the cursors.
 - * The states of M' must include $K \times \Sigma^k$ to remember them.
 - * The transition functions of M' must also reflect it.
 - M' then changes the string to reflect the overwriting of symbols and cursor movements of M .



The Proof (concluded)

- Simulating each step of M takes, *per string of M* , $O(kf(|x|))$ steps.
 - $O(f(|x|))$ steps to collect information.
 - $O(kf(|x|))$ steps to write and, if needed, to lengthen the string.
- M' takes $O(k^2f(|x|))$ steps to simulate each step of M .
- As there are $f(|x|)$ steps of M to simulate, M' operates within time $O(k^2f(|x|)^2)$.

Linear Speedup^a

Theorem 3 *Let $L \in \text{TIME}(f(n))$. Then for any $\epsilon > 0$, $L \in \text{TIME}(f'(n))$, where $f'(n) = \epsilon f(n) + n + 2$.*

- If $f(n) = cn$ with $c > 1$, then c can be made arbitrarily close to 1.
- If $f(n)$ is superlinear, say $f(n) = 14n^2 + 31n$, then the constant in the leading term (14 in this example) can be made arbitrarily small.
 - *Arbitrary* linear speedup can be achieved.
 - This justifies the asymptotic big-O notation.

^aHartmanis and Stearns (1965).