Pseudo-reward Algorithms for Contextual Bandits with Linear Payoff Functions

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Contextual bandit problems

Setting: online game between algorithm ${\mathbb A}$ and environment

for $t = 1, \dots, T$:

- 1 A observes context $\mathbf{x}_t \in \mathbb{R}^d$ from the environment
- 2 A selects an action $a_t \in [K] = \{1, 2, \cdots, K\}$
- 3 A receives reward $r_{t,a_t} \in \mathbb{R}$ corresponding to a_t from the environment
- ${}_{4}$ ${}_{3}$ ${}_{4}$ updates its selection strategy with ${}_{{f x}_t},\,a_t$ and r_{t,a_t}

Goal of \mathbb{A}

maximize average cumulative reward, $\frac{1}{T} \sum_{t=1}^{T} r_{t,a_t}$ by implementing

(2) \mathbb{A} .select(\mathbf{x}_t)

(4) A.update(
$$\mathbf{x}_t, a_t, r_{t,a_t}$$
)

ICML 2012 challenge

- news recommendation on Yahoo!'s front page
- 30 million user visits, 652 news articles



- design \mathbb{A} .select(\mathbf{x}_t) and \mathbb{A} .update($\mathbf{x}_t, a_t, r_{t,a_t}$)
- aim for best click through rate (CTR)

ICML 2012 challenge (cont.)

for each user visit $t = 1, \cdots, T$ (30 million):

- 1) observes user features \mathbf{x}_t (gender, age, location, etc...)
- 2 selects an news article $a_t = \mathbb{A}$.select(\mathbf{x}_t) to display to the user
- 3 receives a click ($r_{t,a_t} = 1$) or no-click ($r_{t,a_t} = 0$)
- 4 performs \mathbb{A} .update(\mathbf{x}_t , a_t , r_{t,a_t})

Achievement of Ku-Chun Chou

first place in 1st phase (otherwise cannot graduate :-))

NAME	AFFILIATION	LAST SCORE (CTR * 10 000)	BEST SCORE (CTR * 10 000)	RANK
Ku-Chun	NTU	882.9	905.9	1
tvirot	MIT	903.9	903.9	2
edjoesu	MIT	889.9	903.4	3

Partial feedback

for $t = 1, \cdots, T$:

- 1 $\mathbb A$ observes context $\mathbf x_t \in \mathbb R^d$ from the environment
- **2** A selects an action $a_t \in [K] = \{1, 2, \cdots, K\}$

3 A receives reward $r_{t,a_t} \in \mathbb{R}$ corresponding to a_t from the environment

4 A updates its selection strategy with \mathbf{x}_t , a_t and r_{t,a_t}

- reward r_{t,a_t} of the selected action a_t : revealed at t
- other rewards: unknown (such as $r_{3,a}$ or $r_{4,a}$ below)

$$\mathbf{X}_{t,a} = \begin{pmatrix} - & \mathbf{x}_1 & - \\ - & \mathbf{x}_2 & - \\ - & \mathbf{x}_5 & - \\ & \vdots & \end{pmatrix}, \mathbf{r}_{t,a} = \begin{pmatrix} r_{1,a} \\ r_{2,a} \\ r_{5,a} \\ \vdots \end{pmatrix}$$

Chou et al. (NTU CSIE)

Problem Definition

Linear upper confidence bound (LinUCB)

- part of Ku-Chun's winning solution (Li et al., WWW 2010; Chu et al., JMLR 2011)
- ridge regression on \mathbf{X}_{t,a_t} and \mathbf{r}_{t,a_t} to **update** weights \mathbf{w}_{t+1,a_t} only

LINUCB.update($\mathbf{x}_t, a_t, r_{t,a_t}$)

$$\mathbf{w}_{t+1,a_t} = \left(\lambda \mathbf{I} + \mathbf{X}_{t,a_t}^{ op} \mathbf{X}_{t,a_t}
ight)^{-1} (\mathbf{X}_{t,a_t}^{ op} \mathbf{r}_{t,a_t})$$

 $-(\mathbf{w}_{t,a}^{\top}\mathbf{x})$ estimates reward of selecting action a subject to \mathbf{x}

partial feedback ⇔ need explore the less-certain actions
 —select based on upper confidence bound of ridge regression

LINUCB.select(\mathbf{x}_t)

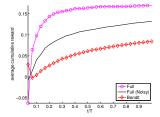
$$a_{t} = \underset{a \in [K]}{\operatorname{argmax}} \left(\underbrace{\mathbf{w}_{t,a}^{\top} \mathbf{x}_{t}}_{\text{estimated reward}} + \alpha \underbrace{\sqrt{\mathbf{x}_{t} \left(\lambda \mathbf{I} + \mathbf{X}_{t-1,a}^{\top} \mathbf{X}_{t-1,a}\right)^{-1} \mathbf{x}_{t}}}_{\text{inconfidence}} \right)$$

Chou et al. (NTU CSIE)

Motivation: conquering partial feedback

- LINUCB way: enforce exploration through UCB —slower in some sense
- another idea: can we CHEAT?

-what if all rewards revealed?



yes, better than LinUCB, even with noisy rewards!
 —but honor code? :-)

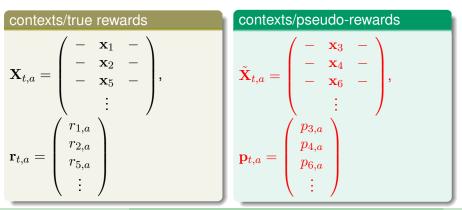
legal (mimic) cheating \iff pseudo-reward

Chou et al. (NTU CSIE)

Using \mathbf{x}_t with pseudo-reward

for unselected actions a

- **1** store \mathbf{x}_t into $\tilde{\mathbf{X}}_{t,a}$
- 2 generate and store corresponding pseudo-reward $p_{t,a}$
- **3** use $(\mathbf{x}_t, p_{t,a})$ to update $\mathbf{w}_{t+1,a}$ as well



Chou et al. (NTU CSIE)

Designing a suitable pseudo-reward

LIN**PRUCB.update**($\mathbf{x}_t, a_t, r_{t,a_t}$)

$$\mathbf{w}_{t+1,a} = \operatorname*{argmin}_{\mathbf{w} \in \mathbb{R}^d} \left(\lambda \|\mathbf{w}\|^2 + \|\mathbf{X}_{t,a}\mathbf{w} - \mathbf{r}_{t,a}\|^2 + \|\tilde{\mathbf{X}}_{t,a}\mathbf{w} - \mathbf{p}_{t,a}\|^2 \right)$$

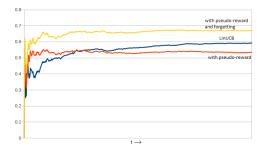
- feasible pseudo-reward: estimate of the actual reward
 - how about $p_{t,a} = \mathbf{w}_{t,a}^T \mathbf{x}_t$?
 - just rechewing w_{t,a}'s own predictions
- proposed pseudo-reward: slight over-estimate of actual reward
 - ≈ close estimate
 - encourage exploration of the unselected action
 - how about $p_{t,a} = \mathbf{w}_{t,a}^T \mathbf{x}_t + \beta \cdot (\text{inconfidence of } \mathbf{w}_{t,a})$? —easily obtained by LinUCB-like calculations

Forgetting needed

• ratio of information from pseudo-rewards and true rewards:

 $\simeq K - 1:1$

- $\mathbf{w}_{t,a}$ biased towards early, inaccurate pseudo-rewards
- proposed scheme: forgetting pseudo-rewards exponentially (see paper)



Chou et al. (NTU CSIE)

Problem Definition

Linear pseudo-reward upper confidence bound (LinPRUCB)

LINPRUCB.select(\mathbf{x}_t)

like LINUCB, but now with

inconfidence term calculated with both $\mathbf{X}_{t,a}$ and (unforgotten) $\tilde{\mathbf{X}}_{t,a}$

pseudo-reward $p_{t,a}$ for **all** unselected actions a

 $p_{t,a} := \mathbf{w}_{t,a}^{\top} \mathbf{x}_t + \beta \cdot \text{inconfidence term}$

LINPRUCB.update($\mathbf{x}_t, a_t, r_{t,a_t}$)

$$\mathbf{w}_{t+1,a} = \underset{\mathbf{w} \in \mathbb{R}^d}{\operatorname{argmin}} \left(\lambda \|\mathbf{w}\|^2 + \|\mathbf{X}_{t,a}\mathbf{w} - \mathbf{r}_{t,a}\|^2 + \operatorname{unforgotten} \|\tilde{\mathbf{X}}_{t,a}\mathbf{w} - \mathbf{p}_{t,a}\|^2 \right)$$

similar theoretical guarantee to LinUCB in the long term

Chou et al. (NTU CSIE)

Long term performance on artificial simulations

Table: Comparisons of average cumulative reward.

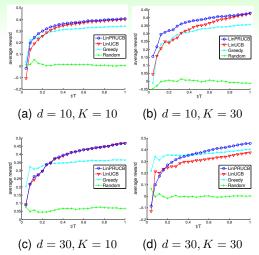
	LINPRUCB	LINUCB
Ν	$\textbf{0.460} \pm \textbf{0.010}$	$\textbf{0.461} \pm \textbf{0.017}$
0	0.558 ± 0.005	0.563 ± 0.007
Ρ	$\textbf{0.270} \pm \textbf{0.008}$	$\textbf{0.268} \pm \textbf{0.008}$
Q	$\begin{array}{c} 0.460 \pm 0.010 \\ 0.558 \pm 0.005 \\ 0.270 \pm 0.008 \\ 0.297 \pm 0.003 \end{array}$	$\textbf{0.297} \pm \textbf{0.005}$

- N: small d, small K
- O: small d, large K
- P: large d, small K
- Q: large d, large K

• LinPRUCB and LinUCB: roughly same long term performance (matching theory)

Simulations

Short term performance on artificial simulations



• LinPRUCB better than LinUCB in the short term (promising in practice)

Chou et al. (NTU CSIE)



Conclusion

- using slightly over-estimated pseudo-reward improves short term performance
- forgetting reduces disadvantages of pseudo-rewards
- LinPRUCB similar to LinUCB in long term; practically better in short term
- other variants for fast action selection: see paper

Thank you! Questions?