# Machine Learning Foundations (機器學習基石)



Lecture 4: Feasibility of Learning

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# Roadmap

### When Can Machines Learn?

### Lecture 3: Types of Learning

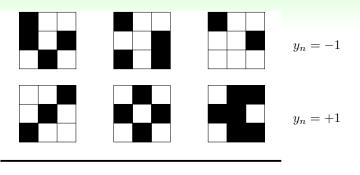
focus: binary classification or regression from a batch of supervised data with concrete features

### Lecture 4: Feasibility of Learning

- Learning is Impossible?
- Probability to the Rescue
- Connection to Learning
- Connection to Real Learning
- 2 Why Can Machines Learn?
- **3** How Can Machines Learn?
- 4 How Can Machines Learn Better?

Learning is Impossible?

## A Learning Puzzle





$$g(\mathbf{x}) = ?$$

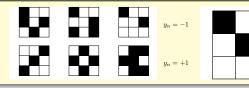
### let's test your 'human learning' with 6 examples :-)

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Learning is Impossible?

## Two Controversial Answers

whatever you say about  $g(\mathbf{x})$ ,



$$g(\mathbf{x}) = ?$$

## truth $f(\mathbf{x}) = +1$ because ...

- symmetry ⇔ +1
- (black or white count = 3) or (black count = 4 and middle-top black) ⇔ +1

## truth $f(\mathbf{x}) = -1$ because ...

- left-top black ⇔ -1
- middle column contains at most 1 black and right-top white ⇔ -1

all valid reasons, your adversarial teacher can always call you 'didn't learn'. :-(

Learning is Impossible?

## What is the Next Number?

1,4,1,5

Learning is Impossible?

## What is the Next Number?

1,4,1,5

1,4,1,5,0,-1,1,6  
by 
$$y_t = y_{t-4} - y_{t-2}$$

1,4,1,5,1,6,1,7  
by 
$$y_t = y_{t-2} + [t \text{ is even}]$$

1,4,1,5,2,9,3,14  
by 
$$y_t = y_{t-4} + y_{t-2}$$

### any number can be the next!

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Feasibility of Learning

Learning is Impossible?

A 'Simple' Binary Classification Problem for Analysis

•  $\mathcal{X} = \{0, 1\}^3$ ,  $\mathcal{Y} = \{\circ, \times\}$ , can enumerate all candidate f as  $\mathcal{H}$ 

### pick $g \in \mathcal{H}$ with all $g(\mathbf{x}_n) = y_n$ (like PLA), does $g \approx f$ ?

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## No Free Lunch

	х	<i>y</i>	$\mid g \mid$	<i>f</i> <sub>1</sub>	f <sub>2</sub>	f <sub>3</sub>	$f_4$	f <sub>5</sub>	f <sub>6</sub>	f <sub>7</sub>	f <sub>8</sub>
	000	0	0	0	0	0	0	0	0	0	0
_	001	×	×	×	×	×	×	×	×	×	×
$\mathcal{D}$	010	×	×	×	×	×	×	×	×	×	×
$\nu$	011	0	0	0	0	0	0	0	0	0	0
	100	×	×	×	×	×	×	×	×	×	×
	101		?	0	0	0	0	X	×	×	X
	110		?	0	0	×	×	0	0	×	×
	111		?	0	×	0	×	0	×	0	×

- $g \approx f$  inside  $\mathcal{D}$ : sure!
- $g \approx f$  outside  $\mathcal{D}$ : No! (but that's really what we want!)

learning from  $\mathcal{D}$  (to infer something outside  $\mathcal{D}$ ) is doomed if any 'unknown' *f* can happen. :-(

### Feasibility of Learning Learning is Impossible? No Free Lunch Theorem for Machine Learning

# (Roughly) Without any assumptions on the learning problem on hand, all learning algorithms perform the same.

(Wolpert, The Lack of A Priori Distinctions Between Learning Algorithms, 1996)



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### no algorithm is best for all learning problems

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This is a popular 'brain-storming' problem, with a claim that 2% of the world's cleverest population can crack its 'hidden pattern'.

$$(5,3,2) \rightarrow 151022, \quad (7,2,5) \rightarrow ?$$

It is like a 'learning problem' with N = 1,  $\mathbf{x}_1 = (5, 3, 2)$ ,  $y_1 = 151022$ . Learn a hypothesis from the one example to predict on  $\mathbf{x} = (7, 2, 5)$ . What is your answer?

151026
 I need more examples to get the correct answer
 143547
 there is no 'correct' answer

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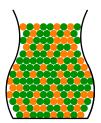
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## Reference Answer: (4)

Following the same nature of the no-free-lunch problems discussed, we cannot hope to be correct under this 'adversarial' setting. BTW, (2) is the designer's answer: the first two digits =  $x_1 \cdot x_2$ ; the next two digits =  $x_1 \cdot x_3$ ; the last two digits =  $(x_1 \cdot x_2 + x_1 \cdot x_3 - x_2)$ .

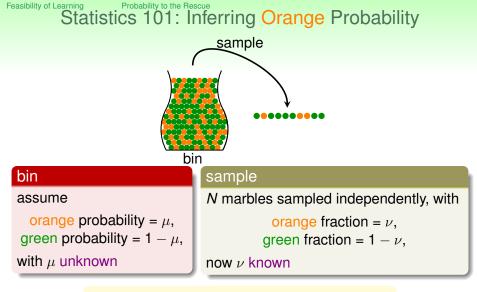
Probability to the Rescue

## Inferring Something Unknown difficult to infer unknown target f outside D in learning; can we infer something unknown in other scenarios?



- consider a bin of many many orange and green marbles
- do we know the orange portion (probability)? No!

can you infer the orange probability?



does in-sample  $\nu$  say anything about out-of-sample  $\mu$ ?

Probability to the Rescue

## Possible versus Probable

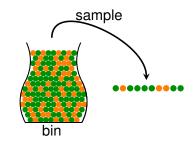
does in-sample  $\nu$  say anything about out-of-sample  $\mu$ ?

### No!

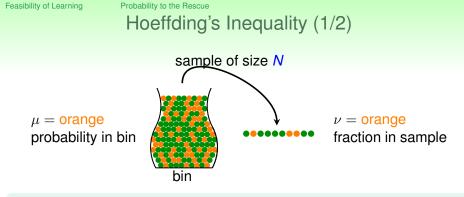
possibly not: sample can be mostly green while bin is mostly orange

### Yes!

probably yes: in-sample  $\nu$  likely close to unknown  $\mu$ 



formally, what does  $\nu$  say about  $\mu$ ?



• in big sample (*N* large),  $\nu$  is probably close to  $\mu$  (within  $\epsilon$ )

$$\mathbb{P}\left[\left|\nu-\mu\right| > \epsilon\right] \leq 2\exp\left(-2\epsilon^2 N\right)$$

called Hoeffding's Inequality, for marbles, coin, polling, ...

the statement ' $\nu = \mu$ ' is probably approximately correct (PAC)

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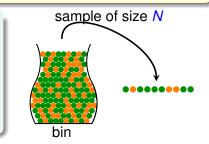
Probability to the Rescue

Hoeffding's Inequality (2/2)

$$\mathbb{P}\left[\left|
u - \mu\right| > \epsilon
ight] \leq 2\exp\left(-2\epsilon^2 N
ight)$$

- valid for all N and  $\epsilon$
- does not depend on  $\mu$ , no need to 'know'  $\mu$
- larger sample size N or looser gap  $\epsilon$

 $\Longrightarrow$  higher probability for ' $u pprox \mu$ '



if large *N*, can probably infer unknown  $\mu$  by known  $\nu$ 

## Let $\mu = 0.4$ . Use Hoeffding's Inequality

$$\mathbb{P}\left[\left|
u-\mu
ight|>\epsilon
ight]\leq 2\exp\left(-2\epsilon^2N
ight)$$

to bound the probability that a sample of 10 marbles will have  $\nu \leq$  0.1. What bound do you get?

1	).67
---	------

- 2 0.40
- 3 0.33
- **4** 0.05

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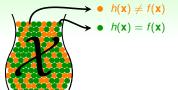
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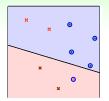
- 1 0.67
- 2 0.40
- **3** 0.33
- **4** 0.05

## Reference Answer: (3)

Set N = 10 and  $\epsilon = 0.3$  and you get the answer. BTW, (4) is the actual probability and Hoeffding gives only an upper bound to that.

# Connection to Learning





### bin

### learning

- unknown orange prob.  $\mu$
- marble  $\in$  bin
- orange •
- green •
- size-N sample from bin

of i.i.d. marbles

- fixed hypothesis  $h(\mathbf{x}) \stackrel{?}{=} \text{target } f(\mathbf{x})$
- $\mathbf{X} \in \mathcal{X}$
- *h* is wrong  $\Leftrightarrow h(\mathbf{x}) \neq f(\mathbf{x})$
- *h* is right  $\Leftrightarrow$  *h*(**x**) = *f*(**x**)
- check *h* on  $\mathcal{D} = \{(\mathbf{x}_n, \underbrace{\mathbf{y}_n}_{f(\mathbf{x}_n)})\}$

### with i.i.d. $\mathbf{x}_n$

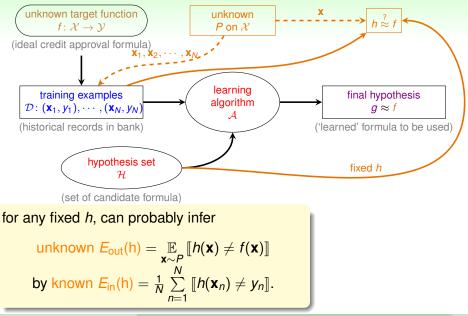
### if large *N* & i.i.d. $\mathbf{x}_n$ , can probably infer unknown $[\![h(\mathbf{x}) \neq f(\mathbf{x})]\!]$ probability

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Connection to Learning

## Added Components



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The Formal Guarantee

for any fixed *h*, in 'big' data (*N* large),

in-sample error  $E_{in}(h)$  is probably close to

out-of-sample error  $E_{out}(h)$  (within  $\epsilon$ )

$$\mathbb{P}\left[\left|E_{\mathsf{in}}(h) - E_{\mathsf{out}}(h)\right| > \epsilon\right] \le 2\exp\left(-2\epsilon^2 N\right)$$

### same as the 'bin' analogy ...

- valid for all N and  $\epsilon$
- does not depend on *E*<sub>out</sub>(*h*), no need to 'know' *E*<sub>out</sub>(*h*)
   *—f* and *P* can stay unknown
- $E_{in}(h) = E_{out}(h)$  is probably approximately correct (PAC)

if  $E_{in}(h) \approx E_{out}(h)$  and  $E_{in}(h)$  small  $\implies E_{out}(h)$  small  $\implies h \approx f$  with respect to *P* 

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Connection to Learning

## Verification of One *h*

for any fixed *h*, when data large enough,

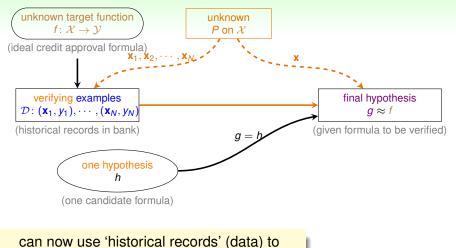
 $E_{\rm in}(h) \approx E_{\rm out}(h)$ 

Can we claim 'good learning' ( $g \approx f$ )?

Yes!	No!
if $E_{in}(h)$ small for the fixed $h$	if $\mathcal{A}$ forced to pick THE <i>h</i> as <i>g</i>
and $A$ pick the <i>h</i> as <i>g</i>	$\implies E_{in}(h)$ almost always not small
$\Longrightarrow$ ' $g = f$ ' PAC	$\implies$ ' $g \neq f$ ' PAC!

real learning:  $\mathcal{A}$  shall make choices  $\in \mathcal{H}$  (like PLA) rather than being forced to pick one *h*. :-( Connection to Learning

## The 'Verification' Flow



verify 'one candidate formula' h

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Your friend tells you her secret rule in investing in a particular stock: 'Whenever the stock goes down in the morning, it will go up in the afternoon; vice versa.' To verify the rule, you chose 100 days uniformly at random from the past 10 years of stock data, and found that 80 of them satisfy the rule. What is the best guarantee that you can get from the verification?

- 1 You'll definitely be rich by exploiting the rule in the next 100 days.
- 2 You'll likely be rich by exploiting the rule in the next 100 days, if the market behaves similarly to the last 10 years.
- Sou'll likely be rich by exploiting the 'best rule' from 20 more friends in the next 100 days.
- You'd definitely have been rich if you had exploited the rule in the past 10 years.

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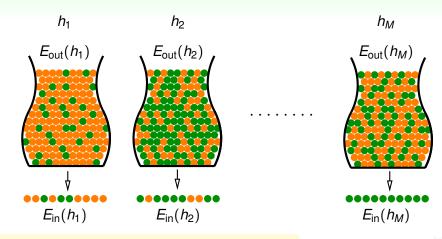
## Reference Answer: (2)

(1): no free lunch; (3): no 'learning' guarantee in verification; (4): verifying with only 100 days, possible that the rule is mostly wrong for whole 10 years.

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Connection to Real Learning

Multiple h



### real learning (say like PLA): BINGO when getting •••••••?

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Q: if everyone in size-150 NTU ML class flips a coin 5 times, and one of the students gets 5 heads for her coin 'g'. Is 'g' really magical?

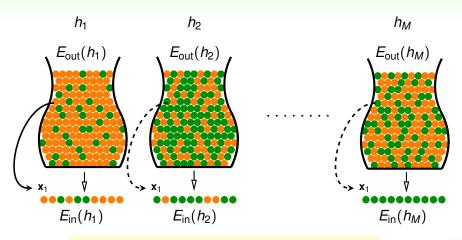
A: No. Even if all coins are fair, the probability that one of the coins results in 5 heads is  $1 - \left(\frac{31}{32}\right)^{150} > 99\%$ .

BAD sample: *E*<sub>in</sub> and *E*<sub>out</sub> far away —can get worse when involving 'choice'

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Connection to Real Learning

# Dependent Sampling from Multiple h



dependent sampling: not easy to analyze with independent BAD probabilities like coin game

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## BAD Sample and BAD Data

### **BAD** Sample

e.g.,  $E_{out} = \frac{1}{2}$ , but getting all heads  $(E_{in} = 0)!$ 

### BAD Data for One h

 $E_{out}(h)$  and  $E_{in}(h)$  far away: e.g.,  $E_{out}$  big (far from f), but  $E_{in}$  small (correct on most examples)

	$\mathcal{D}_1$	$\mathcal{D}_2$	 $\mathcal{D}_{1126}$	 $\mathcal{D}_{5678}$	 Hoeffding
h	BAD			BAD	$\mathbb{P}_{\mathcal{D}} [BAD \ \mathcal{D} \text{ for } h] \leq \dots$

Hoeffding: small
$$\mathbb{P}_{\mathcal{D}} \left[ \mathsf{BAD} \ \mathcal{D} \right] = \sum_{\mathsf{all possible} \mathcal{D}} \mathbb{P}(\mathcal{D}) \cdot \left[ \mathsf{BAD} \ \mathcal{D} \right]$$

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## BAD Data for Many *h*

### BAD data for many h

 $\Longleftrightarrow \mathsf{no} \text{`freedom of choice' by } \mathcal{A}$ 

 $\iff$  there exists some *h* such that  $E_{out}(h)$  and  $E_{in}(h)$  far away

	$\mathcal{D}_1$	$\mathcal{D}_2$	 $\mathcal{D}_{1126}$	 $\mathcal{D}_{5678}$	Hoeffding
$h_1$	BAD			BAD	$\mathbb{P}_{\mathcal{D}} \left[ BAD \ \mathcal{D} \text{ for } h_1 \right] \leq \dots$
$h_2$		BAD			$\mathbb{P}_{\mathcal{D}} \left[ BAD \ \mathcal{D} \text{ for } h_2 \right] \leq \ldots$
h <sub>3</sub>	BAD	BAD		BAD	$\mathbb{P}_{\mathcal{D}} \left[ BAD \ \mathcal{D} \text{ for } h_3 \right] \leq \dots$
h <sub>M</sub>	BAD			BAD	$\mathbb{P}_{\mathcal{D}} \left[ BAD \ \mathcal{D} \text{ for } h_M \right] \leq \dots$
all	BAD	BAD		BAD	?

for *M* hypotheses, bound of  $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD } \mathcal{D}]$ ?

# Bound of BAD Data

 $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\ \mathcal{D}]$ 

- $= \mathbb{P}_{\mathcal{D}} \left[ \textbf{BAD } \mathcal{D} \text{ for } h_1 \text{ or } \textbf{BAD } \mathcal{D} \text{ for } h_2 \text{ or } \dots \text{ or } \textbf{BAD } \mathcal{D} \text{ for } h_M \right]$
- $\leq \mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \ \mathcal{D} \text{ for } h_1] + \mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \ \mathcal{D} \text{ for } h_2] + \ldots + \mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \ \mathcal{D} \text{ for } h_M]$ (union bound)

$$\leq 2\exp\left(-2\epsilon^2N\right) + 2\exp\left(-2\epsilon^2N\right) + \ldots + 2\exp\left(-2\epsilon^2N\right)$$

$$= 2M \exp\left(-2\epsilon^2 N\right)$$

- finite-bin version of Hoeffding, valid for all M, N and  $\epsilon$
- does not depend on any *E*<sub>out</sub>(*h<sub>m</sub>*), no need to 'know' *E*<sub>out</sub>(*h<sub>m</sub>*)
   *—f* and *P* can stay unknown
- $E_{in}(g) = E_{out}(g)$  is PAC, regardless of A

'most reasonable' A (like PLA/pocket): pick the  $h_m$  with lowest  $E_{in}(h_m)$  as g

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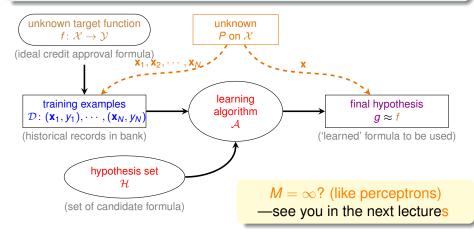
Connection to Real Learning The 'Statistical' Learning Flow

if  $|\mathcal{H}| = M$  finite, *N* large enough,

for whatever g picked by  $\mathcal{A}, \, \mathcal{E}_{\mathsf{out}}(g) pprox \mathcal{E}_{\mathsf{in}}(g)$ 

### if $\mathcal{A}$ finds one g with $E_{in}(g) \approx 0$ ,

PAC guarantee for  $E_{out}(g) \approx 0 \implies$  learning possible :-)



### Consider 4 hypotheses.

$$h_1(\mathbf{x}) = \operatorname{sign}(x_1), \ h_2(\mathbf{x}) = \operatorname{sign}(x_2),$$

$$h_3(\mathbf{x}) = \text{sign}(-x_1), \ h_4(\mathbf{x}) = \text{sign}(-x_2).$$

For any *N* and  $\epsilon$ , which of the following statement is not true?

- **1** the BAD data of  $h_1$  and the BAD data of  $h_2$  are exactly the same
- 2 the BAD data of  $h_1$  and the BAD data of  $h_3$  are exactly the same
- **3**  $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \text{ for some } h_k] \leq 8 \exp\left(-2\epsilon^2 N\right)$
- **4**  $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \text{ for some } h_k] \leq 4 \exp\left(-2\epsilon^2 N\right)$

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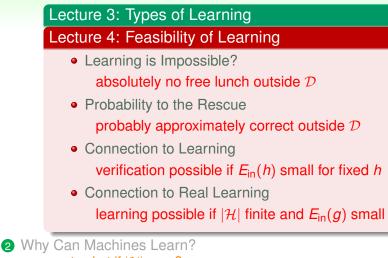
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- $P_{\mathcal{D}}[\mathsf{BAD} \text{ for some } h_k] \leq 4 \exp\left(-2\epsilon^2 N\right)$

### Reference Answer: (1)

The important thing is to note that (2) is true, which implies that (4) is true if you revisit the union bound. Similar ideas will be used to conquer the  $M = \infty$  case.

When Can Machines Learn?



- next: what if  $|\mathcal{H}| = \infty$ ?
- 3 How Can Machines Learn?
- 4 How Can Machines Learn Better?