Introduction to Adaptive Boosting

Hsuan-Tien Lin

National Taiwan University

Machine Learning, Fall 2008

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- We want to teach a class of 6 year olds.
- Gather photos from NY Apple Asso. and Google Image.

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Apple Recognition Problem

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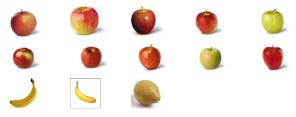
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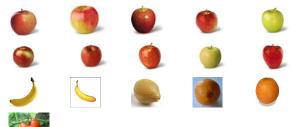
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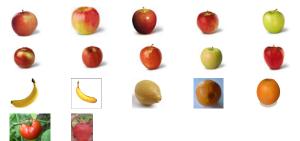
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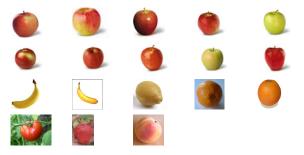
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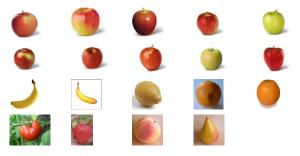
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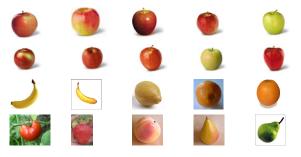
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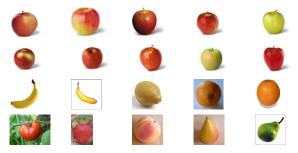
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Our Fruit Class Begins

Teacher: How would you describe an apple? Michael?

Michael: I think apples are circular.

(Class): Apples are circular.

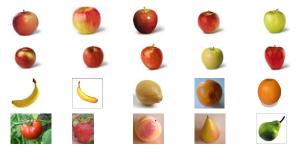


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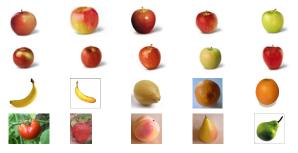
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Our Fruit Class Begins

- Teacher: How would you describe an apple? Michael?
- Michael: I think apples are circular.
- (Class): Apples are circular.



Our Fruit Class Continues

Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?

Tina: It looks like apples are red.

(Class): Apples are somewhat circular and somewhat red.



Our Fruit Class Continues

Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?

Tina: It looks like apples are red.

(Class): Apples are somewhat circular and somewhat red.



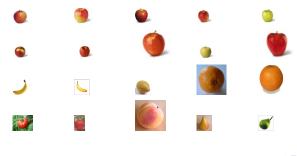
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Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?

Tina: It looks like apples are red.

(Class): Apples are somewhat circular and somewhat red.



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Our Fruit Class Continues

Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?

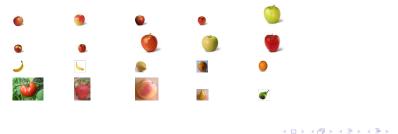
Joey: Apples could also be green.

(Class): Apples are somewhat circular and somewhat red and possibly green.



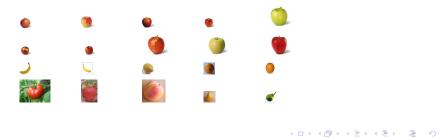
Our Fruit Class Continues

- Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?
 - Joey: Apples could also be green.
 - (Class): Apples are somewhat circular and somewhat red and possibly green.



Our Fruit Class Continues

- Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?
 - Joey: Apples could also be green.
 - (Class): Apples are somewhat circular and somewhat red and possibly green.



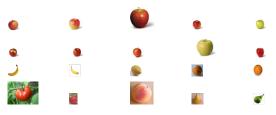
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Our Fruit Class Continues

Teacher: Yes. It seems that apples might be circular, red, green. But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?

Jessica: Apples have stems at the top.

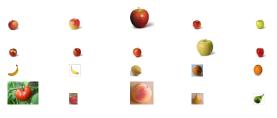
(Class): Apples are somewhat circular, somewhat red, possibly green, and may have stems at the top.



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Our Fruit Class Continues

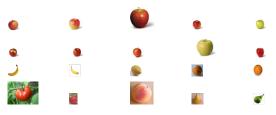
- Teacher: Yes. It seems that apples might be circular, red, green. But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?
- Jessica: Apples have stems at the top.
 - (Class): Apples are somewhat circular, somewhat red, possibly green, and may have stems at the top.



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Our Fruit Class Continues

- Teacher: Yes. It seems that apples might be circular, red, green. But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?
- Jessica: Apples have stems at the top.
 - (Class): Apples are somewhat circular, somewhat red, possibly green, and may have stems at the top.



Put Intuition to Practice

Intuition

- Combine simple rules to approximate complex function.
- Emphasize incorrect data to focus on valuable information.
- AdaBoost Algorithm (Freund and Schapire 1997)
 - Input: training examples $Z = \{(x_n, y_n)\}_{n=1}^N$.

• For
$$t = 1, 2, \cdots, T$$
,

- Learn a simple rule *h_t* from emphasized training examples.
- Get the confidence α_t of such rule
- Emphasize the training examples that do not agree with *h*_t.

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• Output: combined function $H(x) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t h_t(x)\right)$

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Some More Details

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- Input: training examples $Z = \{(x_n, y_n)\}_{n=1}^N$.
- For *t* = 1, 2, · · · , *T*,
 - Learn a simple rule h_t from emphasized training examples.

• How? Choose a $h_t \in \mathcal{H}$ with minimum emphasized error.

- Get the confidence α_t of such rule
 - How? An h_t with lower error should get higher α_t .
- Emphasize the training examples that do not agree with *h*_t.
 - How? Maintain an emphasis value *u_n* per example.
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- Output: combined function H(x) = sign (Σ^T_{t=1} α_th_t(x))
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- Let's see some demos.

• Input:
$$Z = \{(x_n, y_n)\}_{n=1}^N$$
. Set $u_n = \frac{1}{N}$ for all n .
• For $t = 1, 2, \dots, T$,

• Learn a simple rule h_t such that h_t solves

$$\min_{h}\sum_{n=1}^{N}u_{n}\cdot I[y_{n}\neq h(x_{n})].$$

• Compute the error $\epsilon_t = \sum_{n=1}^{N} \frac{u_n}{\sum_{m=1}^{N} u_m} \cdot I[y_n \neq h(x_n)]$ and the confidence

$$\alpha_t = \frac{1}{2} \ln \frac{1 - \epsilon_t}{\epsilon_t}$$

• Emphasize the training examples that do not agree with *h*_t:

$$u_n = u_n \cdot \exp\left(-\alpha_t y_n h_t(x_n)\right).$$

• Output: combined function $H(x) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t h_t(x)\right)$

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