

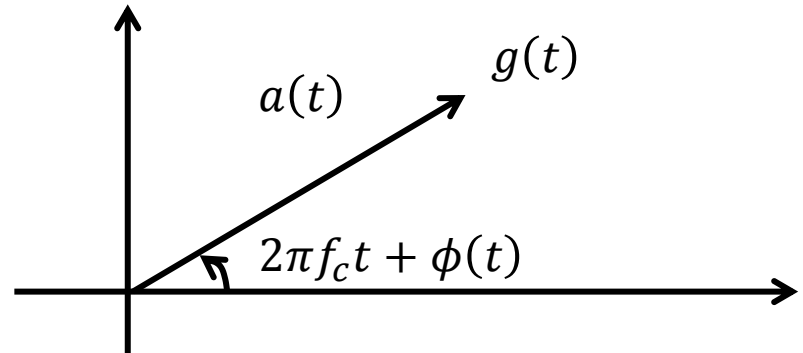
Digital Band-pass Modulation

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Band-pass Signal Representation

- General form:



$$g(t) = a(t) \cos(2\pi f_c t + \phi(t))$$

Envelope

Phase

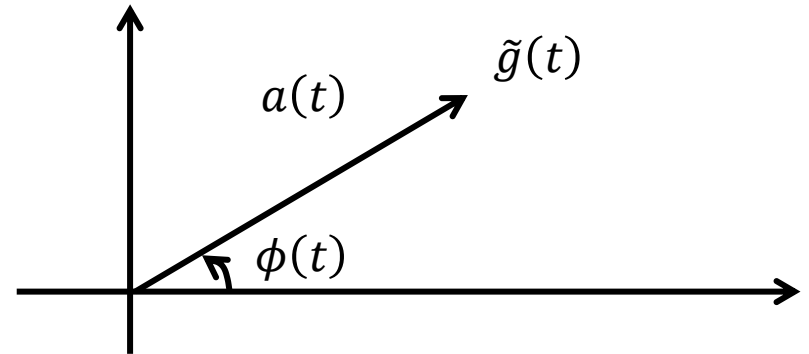
- Envelope is always non-negative, or we can switch the phase by 180 degree
- This is called the canonical representation of a band-pass signal

Band-pass Signal Representation

- $g(t) = a(t)\cos(2\pi f_c t + \phi(t))$ can be re-arranged into
- $g(t) = g_I(t)\cos(2\pi f_c t) - g_Q(t)\sin(2\pi f_c t)$
- $g_I(t) = a(t)\cos(\phi(t))$ and $g_Q(t) = a(t)\sin(\phi(t))$
- $g_I(t)$ and $g_Q(t)$ are called inphase and quadrature components of the signal $g(t)$, respectively
- Then $a(t) = \sqrt{g_I^2(t) + g_Q^2(t)}$ and $\phi(t) = \tan^{-1}\left(\frac{g_Q(t)}{g_I(t)}\right)$

Band-pass Signal Representation

- We can also represent $g(t)$ as



$$g(t) = \text{Re}[\tilde{g}(t)\exp(j2\pi f_c t)]$$

- $\tilde{g}(t) = g_I(t) + jg_Q(t)$
- $\tilde{g}(t)$ is called the complex envelope of the band-pass signal.
- This is to remove the annoying $\exp(j2\pi f_c t)$ in the analysis.

Sinusoidal Functions' Fourier Transform

- **Complex exponential function**

- $F[\exp(j2\pi f_c t)] = \delta(f - f_c)$.

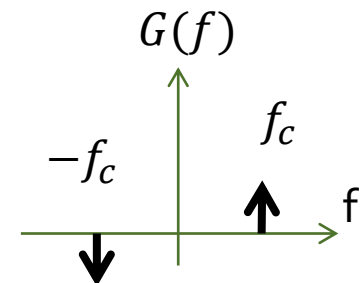
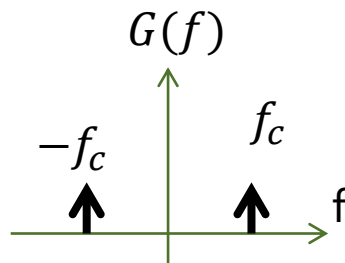
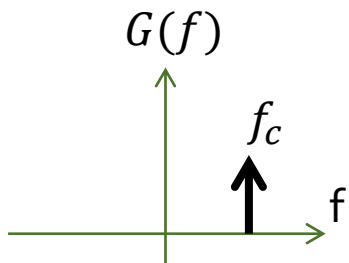
- **Sinusoidal functions:**

- $\cos(2\pi f_c t) = \frac{1}{2}[\exp(j2\pi f_c t) + \exp(-j2\pi f_c t)]$

- $F[\cos(2\pi f_c t)] = \frac{1}{2}[\delta(f - f_c) + \delta(f + f_c)]$

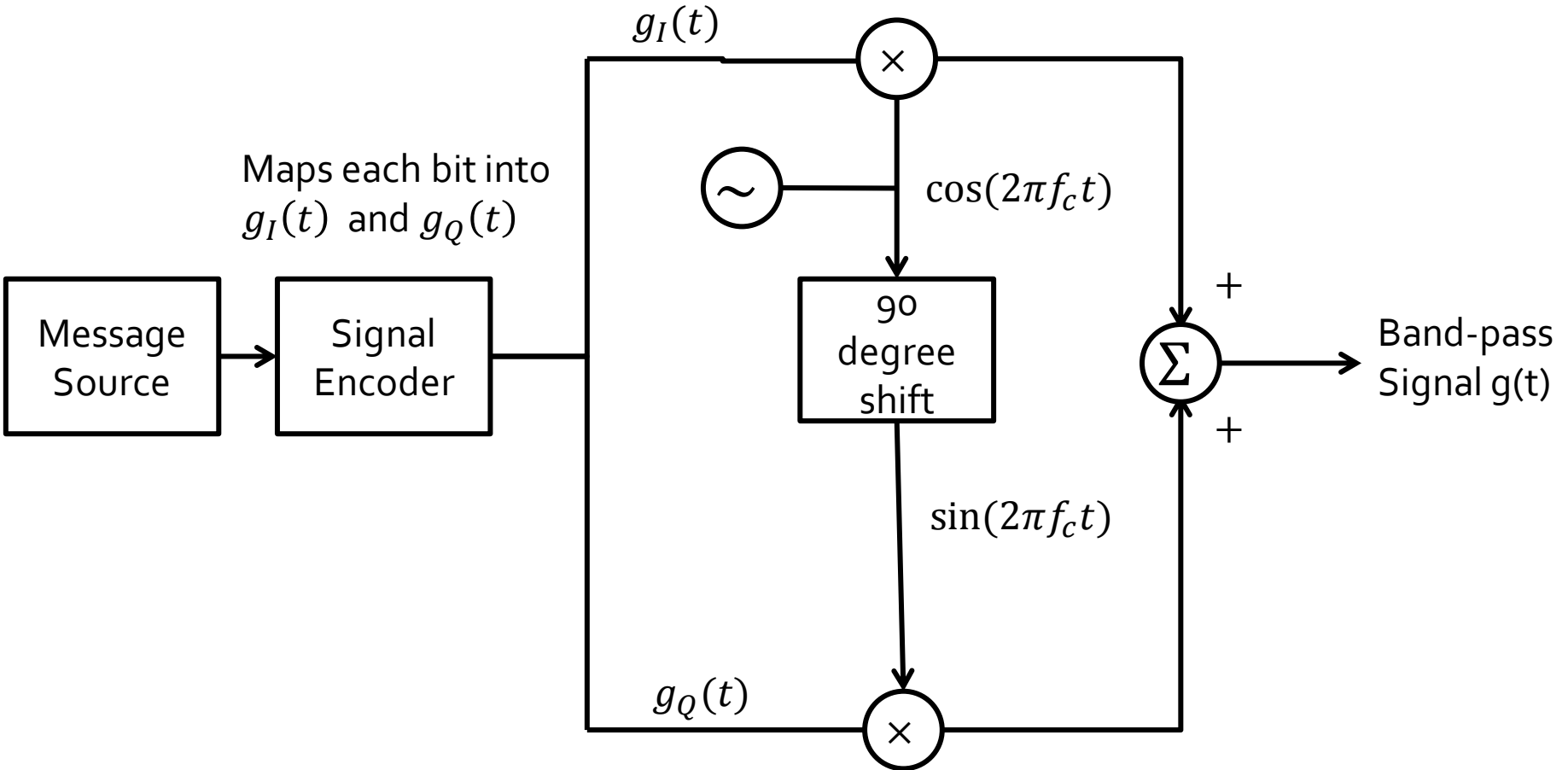
- $\sin(2\pi f_c t) = \frac{1}{2}[\exp(j2\pi f_c t) - \exp(-j2\pi f_c t)]$

- $F[\sin(2\pi f_c t)] = \frac{1}{2}[\delta(f - f_c) - \delta(f + f_c)]$



$$g(t) = g_I(t) \cos(2\pi f_c t) + g_Q(t) \sin(2\pi f_c t)$$

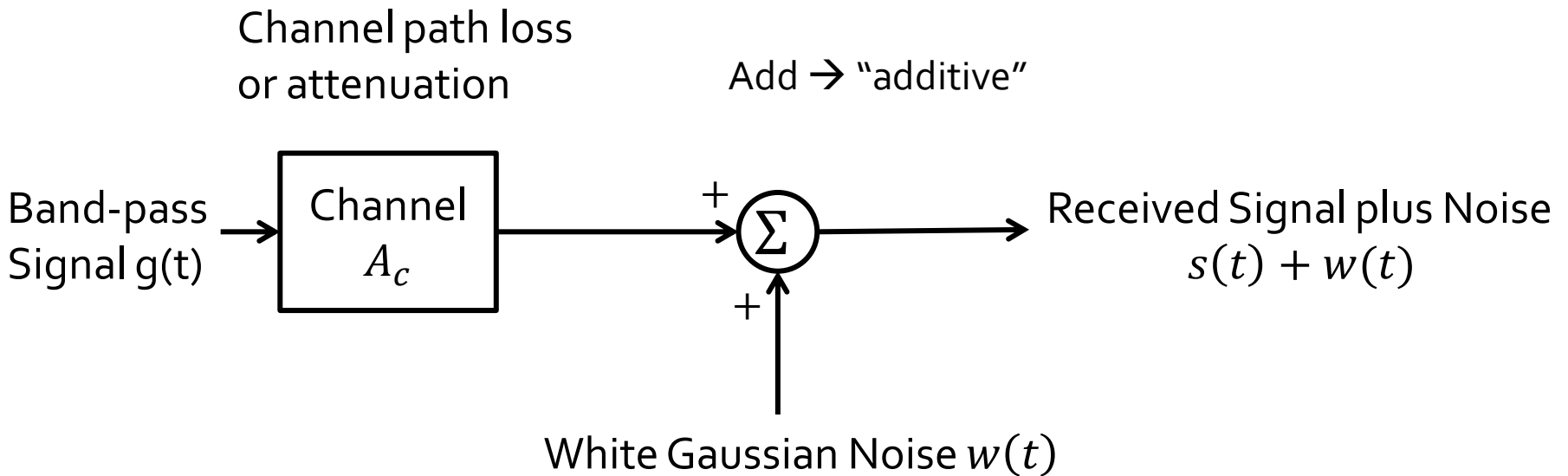
Band-pass Signal Transmitter



Assumption

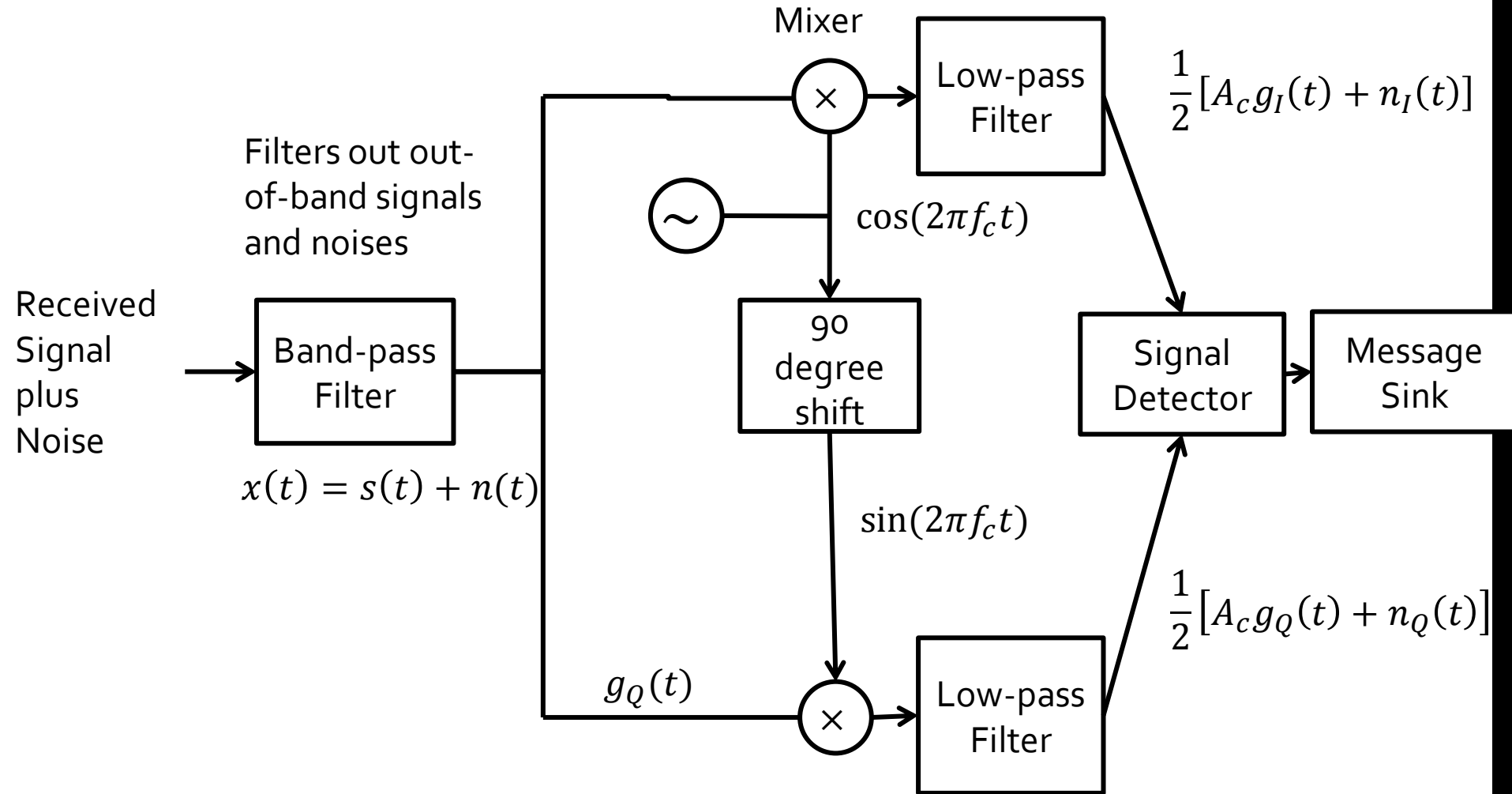
- **The channel is linear: flat-fading channel.**
 - $B_c > B_s$
 - Negligible distortion to $g(t)$
- **The received signal $s(t)$ is perturbed by AWGN**
 - noise $w(t) \sim N\left(0, \frac{N_0}{2}\right)$
 - $\frac{N_0}{2}$ is the PSD of the noise and also its variance (since it's white)

AWGN Channel



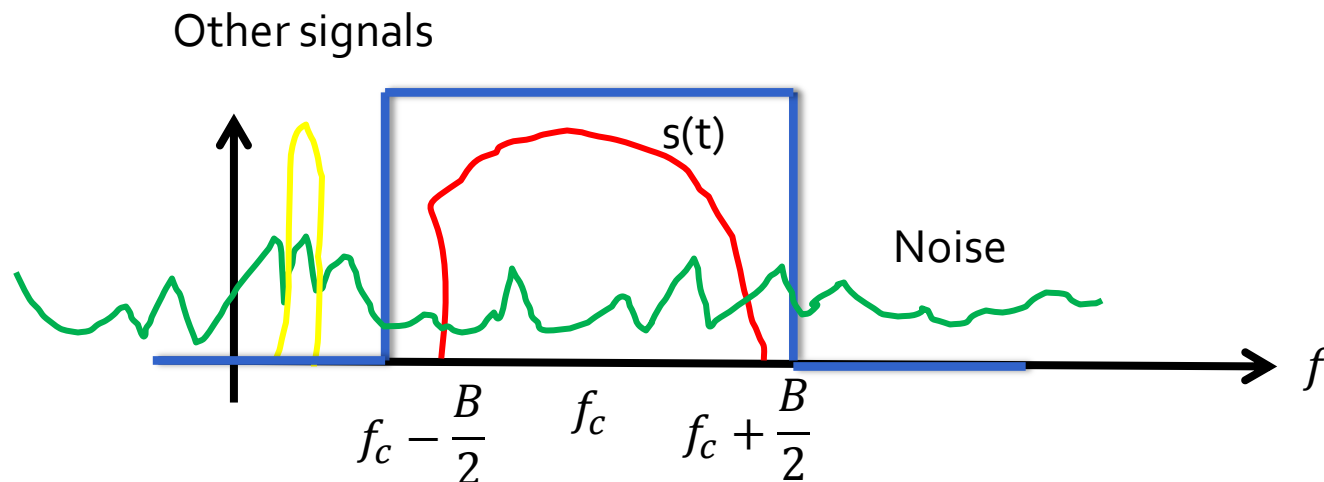
$$x(t) = s(t) + w(t) = A_c g(t) + w(t)$$

Band-pass Signal Receiver

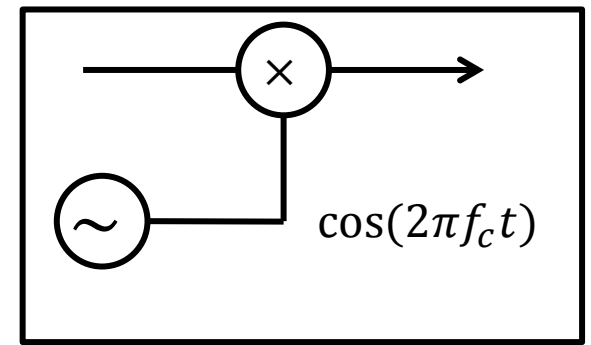


Band-pass Filter

- The band-pass filter at the frontend filters out out-of-band signals and noises
 1. Signal $s(t)$ is within the band \rightarrow not affected
 2. White noise $w(t)$ becomes narrowband noise $n(t)$
 - Much smaller since now we only include noises within the band
 - Still “white over the bandwidth of the signal”
 3. Other signal (out-of-band) is filtered out



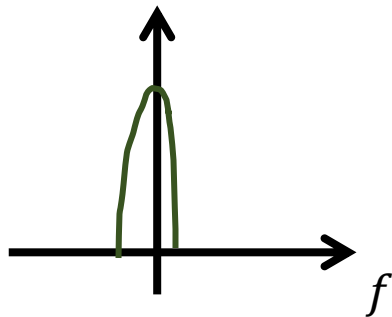
Up-conversion (TX)



In time domain

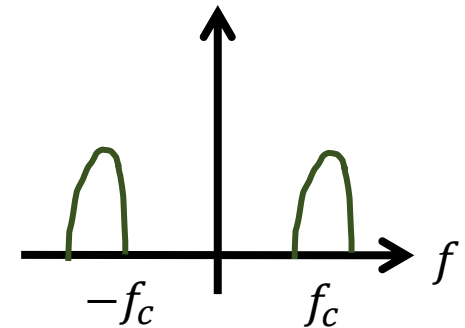
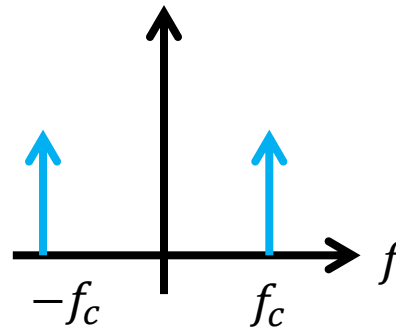
$$A(t) \exp(j\theta(t)) \quad \otimes \quad A_c \cos(2\pi f_c t)$$

In frequency domain

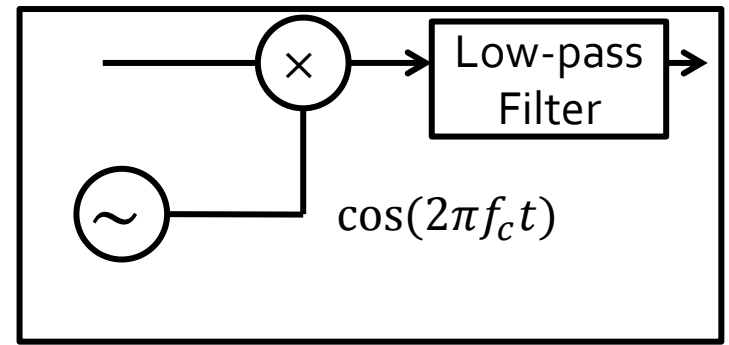


Convolution

\otimes



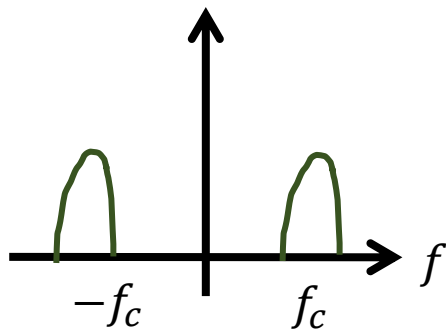
Down-conversion (RX)



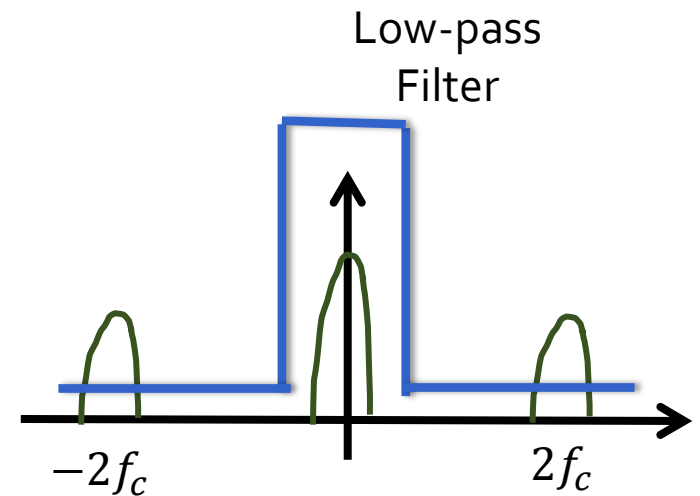
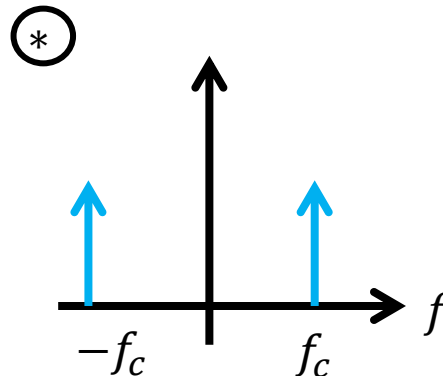
In time domain

$$s(t)A'_c \cos(2\pi f_c t + \phi) \quad (\otimes) \quad A_c \cos(2\pi f_c t)$$

In frequency domain



Convolution



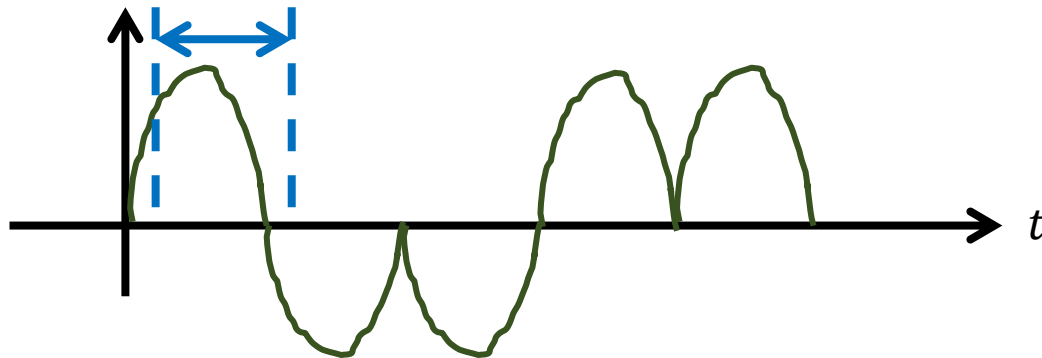
Signal Detector

- **The signal detector:**
 - Observes complex representation of the received signal, $[g_I(t) + n_I(t)] + j[g_Q(t) + n_Q(t)]$,
 - For a duration of T seconds (symbol/bit period)
 - And then make its best estimate of the corresponding transmitted signal $g_I(t) + jg_Q(t)$
 - $g_I(t) + jg_Q(t) \rightarrow$ bit stream

Time synchronization

- To simplify, we assume we have time synchronization between the TX and the RX

Where does each symbol start and end?

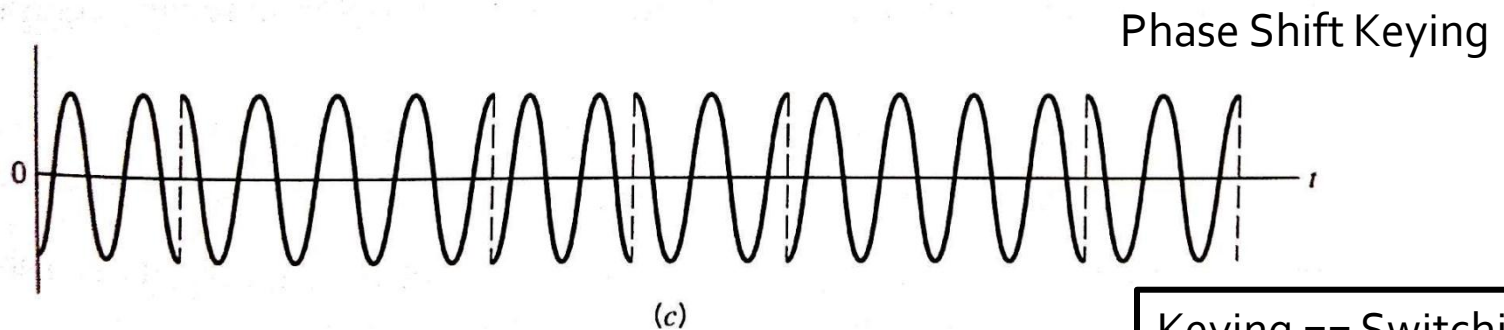
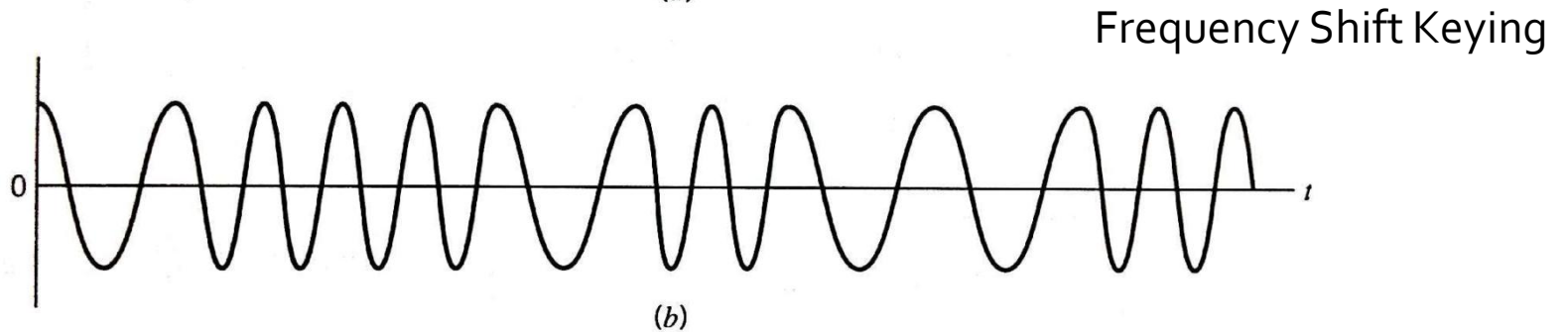
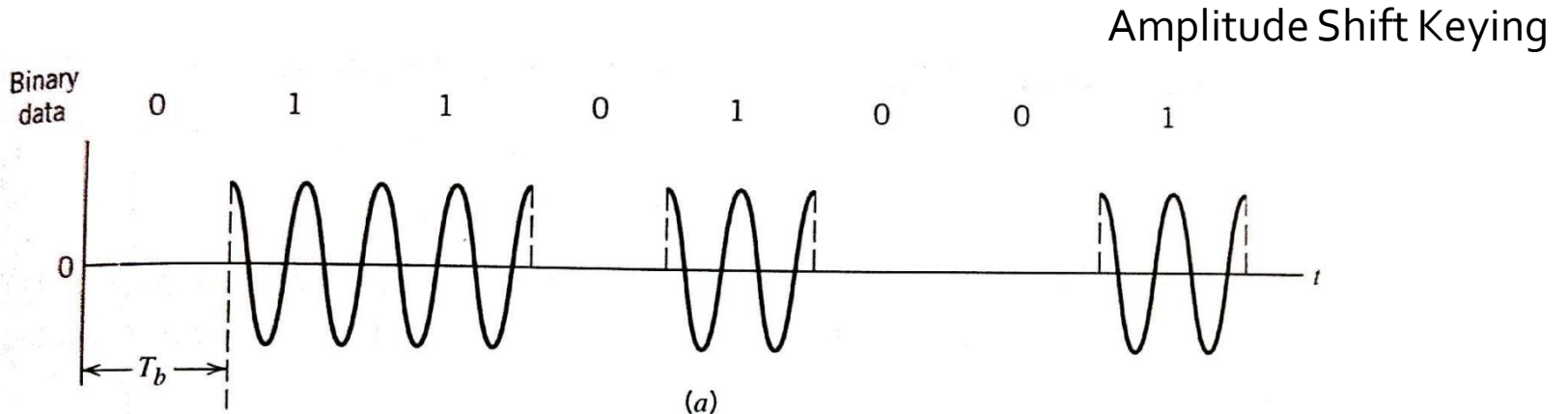


- Symbol boundary needs to be same for TX and RX
- In practice, a timing recovery circuit is required

Coherent & non-coherent

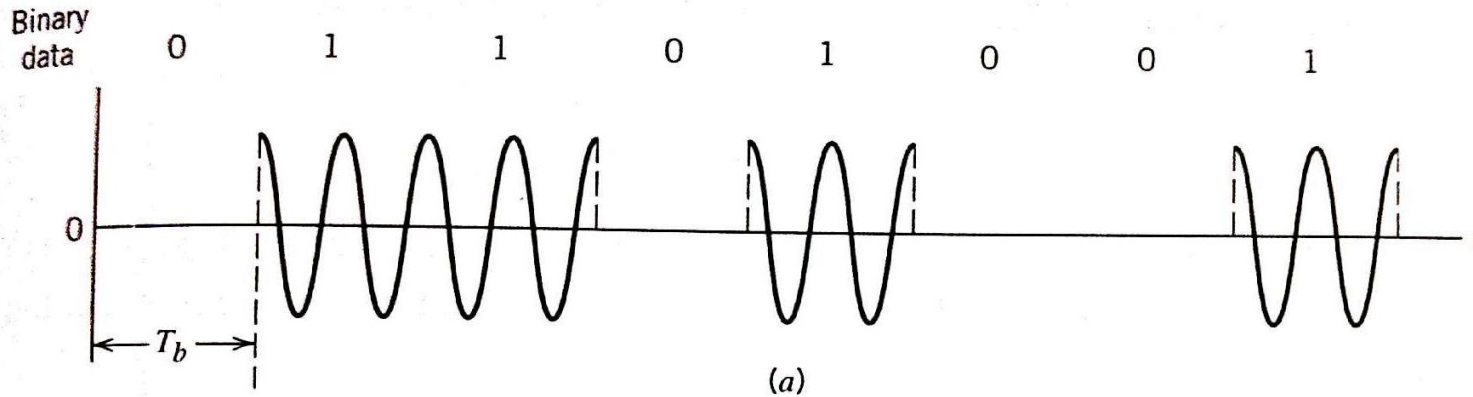
- Sometimes, the receiver is phase-locked to the transmitter
- That means, the \odot in TX and in RX generate $\cos(2\pi f_c t)$ with no phase difference.
 - RX looks at the received signal to lock onto TX's carrier
- **When that happens, we say**
 - The receiver is a coherent receiver, carrying out coherent detection
- **Otherwise, we say**
 - The receiver is a non-coherent receiver, carrying out non-coherent detection

Basic forms of digital modulation



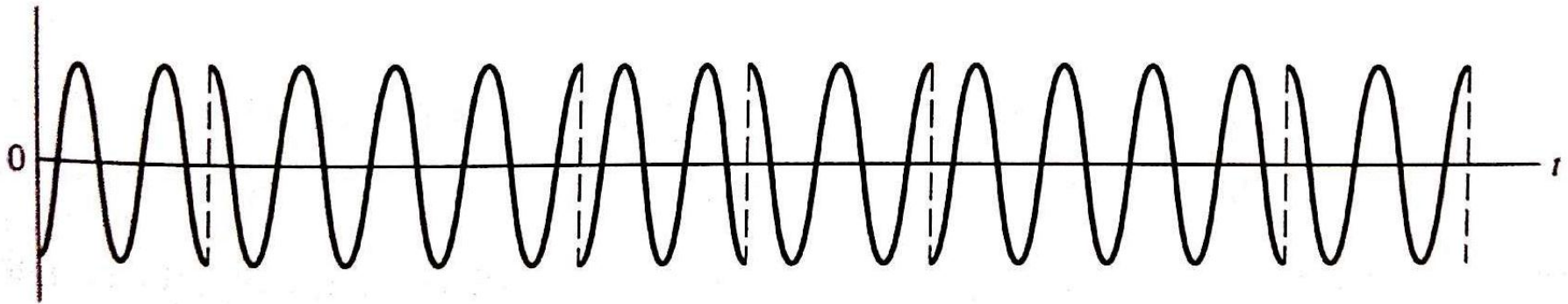
Keying == Switching

(Binary) Amplitude Shift Keying (BASK)



- Fixed Amplitude/fixed frequency for a duration of T_b to represent "1"
 - No transmission to represent "0"
 - Or, more formally,
 - $s_1(t) = A_c \cos(2\pi f_c t)$
 - $s_0(t) = 0$
- } for a duration of T_b

(Binary) Phase Shift Keying (BPSK)



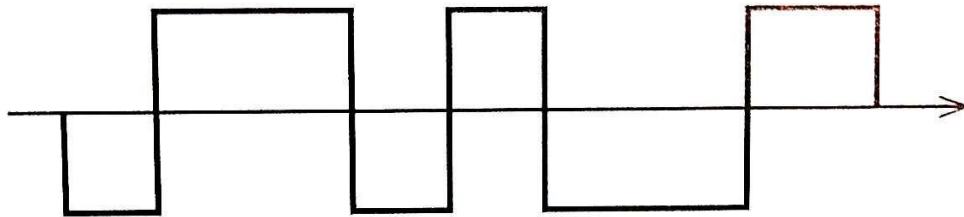
(c)

- Same amplitude, same frequency
- Send the original carrier to represent "1"
- Send an inverted carrier (phase difference 180 degrees) to represent "0"
- Or, more formally,
 - $s_1(t) = A_c \cos(2\pi f_c t)$
 - $s_0(t) = A_c \cos(2\pi f_c t + \pi) = -A_c \cos(2\pi f_c t)$

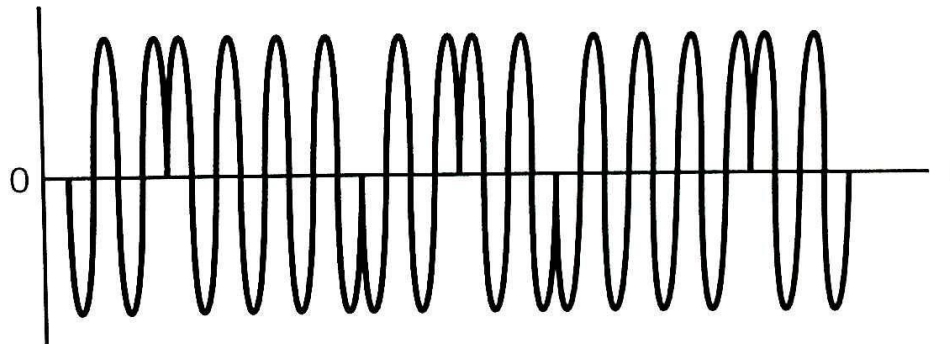
(Binary) Phase Shift Keying (BPSK)

Binary data
0 1 1 0 1 0 0 1

(a)

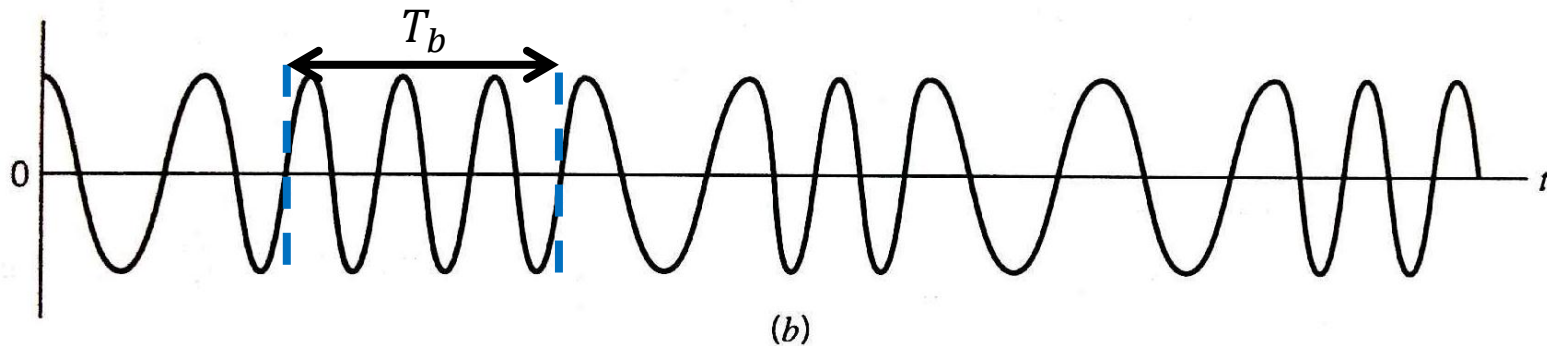


(b)



(c)

(Binary) Frequency Shift Keying (BFSK)



- Same amplitude
- Send a carrier at f_1 to represent "1"
- Send a carrier at f_0 to represent "0"
- Or, more formally,

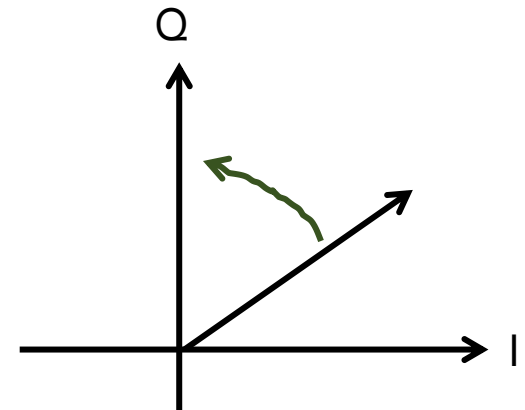
- $s_1(t) = A_c \cos(2\pi f_1 t)$

- $s_0(t) = A_c \cos(2\pi f_0 t)$

} for a duration of T_b

(Binary) Frequency Shift Keying (BFSK)

- Usually we have $f_1 = f_c + \Delta f$, $f_0 = f_c - \Delta f$
 - $s_1(t) = A_c \cos[2\pi(f_c + \Delta f)t]$
 - $s_0(t) = A_c \cos[2\pi(f_c - \Delta f)t]$
- Then,
 - $s_1(t) = \text{Re}\{A_c \exp(j2\pi(f_c + \Delta f)t)\} = g(t) \exp(j2\pi f_c t)$
 - $s_0(t) = \text{Re}\{A_c \exp(j2\pi(f_c - \Delta f)t)\} = g(t) \exp(j2\pi f_c t)$
- So,
 - For "1", $\tilde{g}(t) = g_I(t) + jg_Q(t) = A_c \exp[-j2\pi\Delta f t]$
 - For "0", $\tilde{g}(t) = g_I(t) + jg_Q(t) = A_c \exp[+j2\pi\Delta f t]$

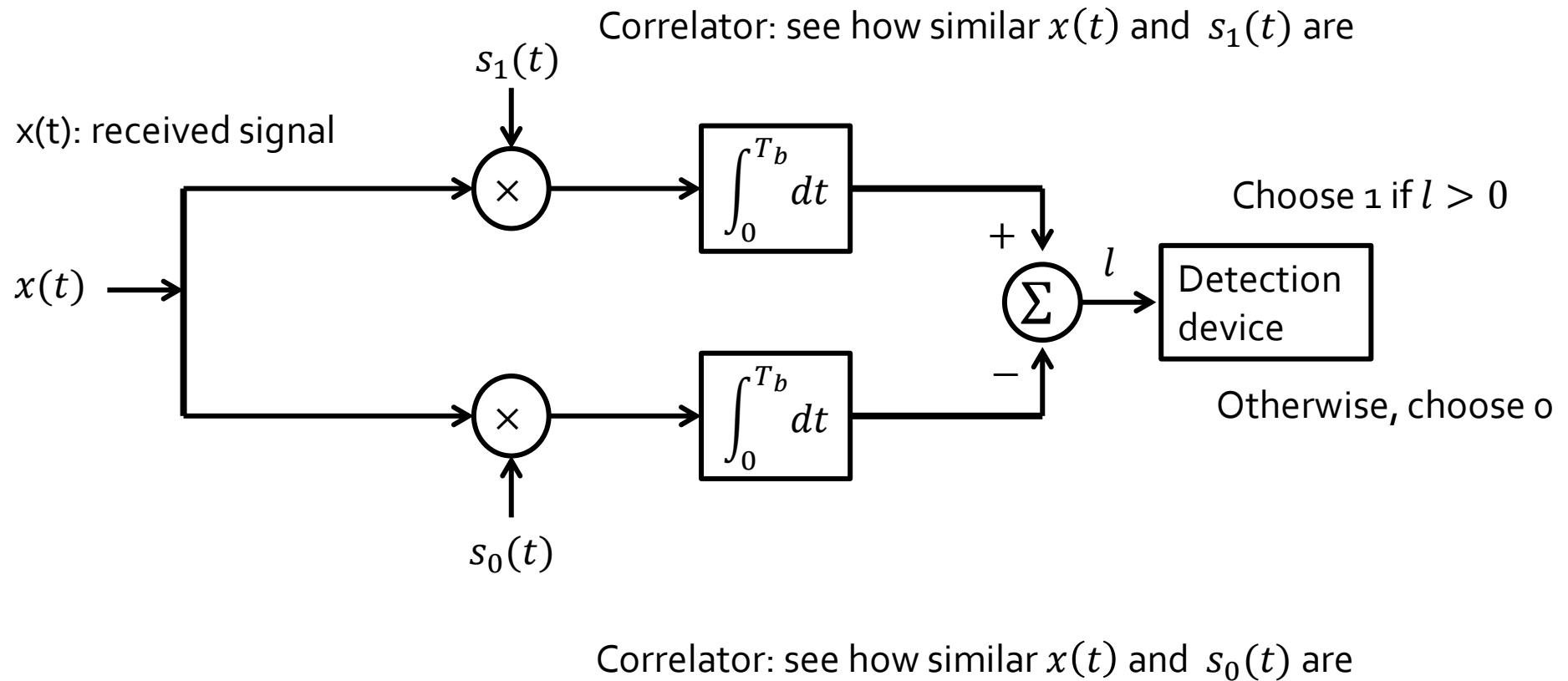


Coherent Detection of FSK and PSK signals

- Since f_c is large compared to $\frac{1}{T_b}$ (symbol rate, or bit rate), we can say that the same signal energy E_b is transmitted in a bit interval T_b :

$$\begin{aligned} E_b &= \int_0^{T_b} s_0^2(t) dt = \int_0^{T_b} s_1^2(t) dt \\ &= \frac{A_c^2 T_b}{2} \end{aligned}$$

Two-path correlation receiver (general case)



Coherent Detection

- $w(t)$: AWGN, $N\left(\mathbf{0}, \frac{N_0}{2}\right)$
- $H_0: x(t) = s_0(t) + w(t)$
- $H_1: x(t) = s_1(t) + w(t)$
- Receiver output:

$$l = \int_0^{T_b} x(t)[s_1(t) - s_0(t)]dt$$

- **Decision level: 0**
 - If l is larger than 0, than $x(t)$ is “more similar” to $s_1(t)$
 - If l is smaller than 0, than $x(t)$ is “more similar” to $s_0(t)$

$$l = \int_0^{T_b} x(t)[s_1(t) - s_0(t)]dt$$

Coherent Detection

- H_1 :

$$l = \int_0^{T_b} s_1(t)[s_1(t) - s_0(t)]dt - \int_0^{T_b} w(t)[s_1(t) - s_0(t)]dt$$

- **Since the noise $w(t)$ is zero-mean**, L : the random variable whose value is l

$$E[L|H_1] = \int_0^{T_b} s_1(t)[s_1(t) - s_0(t)]dt = E_b(1 - \rho)$$

- ρ : the correlation coefficient of the signals $s_0(t)$ and $s_1(t)$

$$\rho = \frac{\int_0^{T_b} s_0(t)s_1(t)dt}{\left[\int_0^{T_b} s_0^2(t)dt \int_0^{T_b} s_1^2(t)dt\right]^{\frac{1}{2}}} = \frac{1}{E_b} \int_0^{T_b} s_0(t)s_1(t)dt$$

$$0 \leq \rho \leq 1$$

Coherent Detection

- Similarly,

$$E[L|H_0] = -E_b(1 - \rho)$$

- **L's variance is the same for H_1 and H_0 . Since $s_1(t)$ and $s_0(t)$ is deterministic given the transmitted bit, we have**

$$\begin{aligned} \text{Var}[L] &= E[\{L - E[L]\}^2] \\ &= E \left[\int_0^{T_b} \int_0^{T_b} w(t)w(u)[s_1(t) - s_0(t)][s_1(u) - s_0(u)] dt du \right] \\ &= \int_0^{T_b} \int_0^{T_b} \mathbf{E}[w(t)w(u)][s_1(t) - s_0(t)][s_1(u) - s_0(u)] dt du \\ &= \int_0^{T_b} \int_0^{T_b} \delta(t - u)[s_1(t) - s_0(t)][s_1(u) - s_0(u)] dt du \end{aligned}$$

$$= \int_0^{T_b} \int_0^{T_b} \delta(t - u) [s_1(t) - s_0(t)] [s_1(u) - s_0(u)] dt du$$

$$= \int_0^{T_b} \frac{N_0}{2} [s_1(t) - s_0(t)]^2 dt = N_0 E_b (1 - \rho)$$

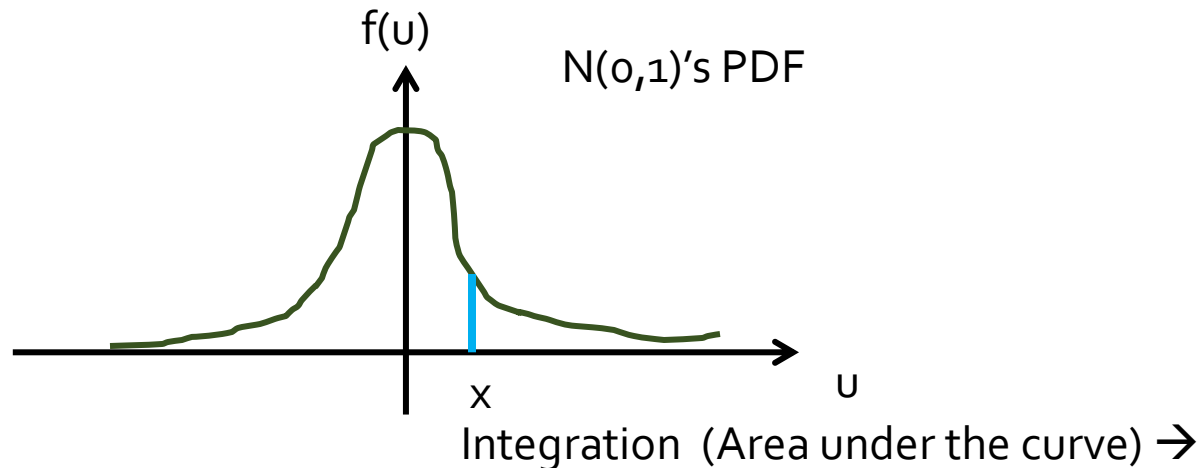
- **Therefore, we know that L conditioned on H_0 is a Gaussian distributed random variable: $N(E_b(1 - \rho), N_0 E_b(1 - \rho))$**

Q Function

- Q function is defined over the CDF of Gaussian distribution $N(0, 1)$

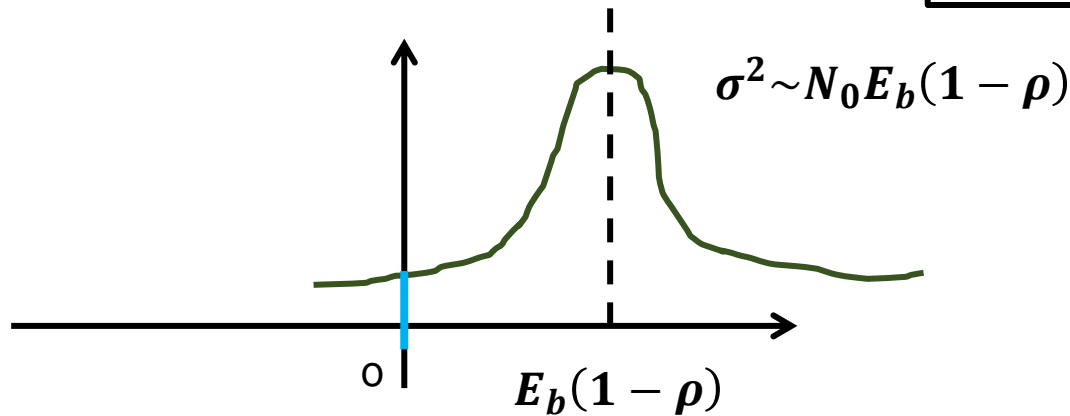
$$Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^{\infty} \exp\left(-\frac{u^2}{2}\right) du = 1 - \Phi(x)$$

CDF of $N(0, 1)$



Bit Error Rate

$$L|H_1 \sim N(E_b(1 - \rho), N_0 E_b(1 - \rho))$$

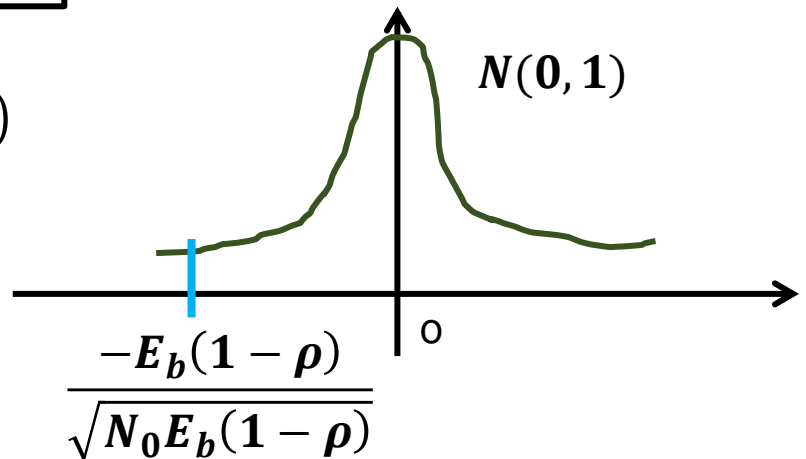
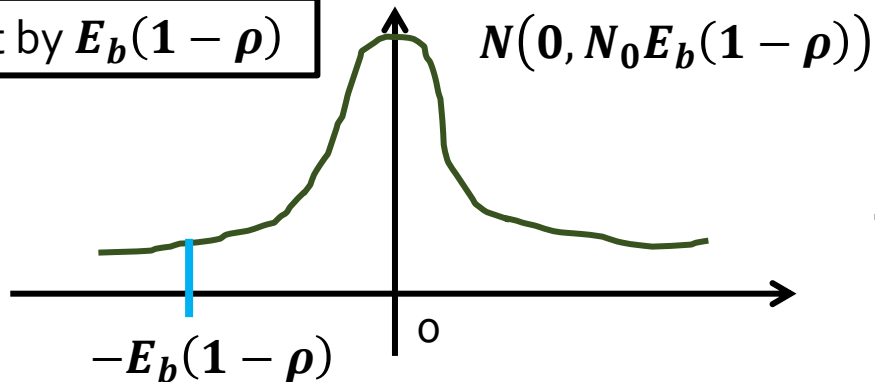


← Integration (Area under the curve)

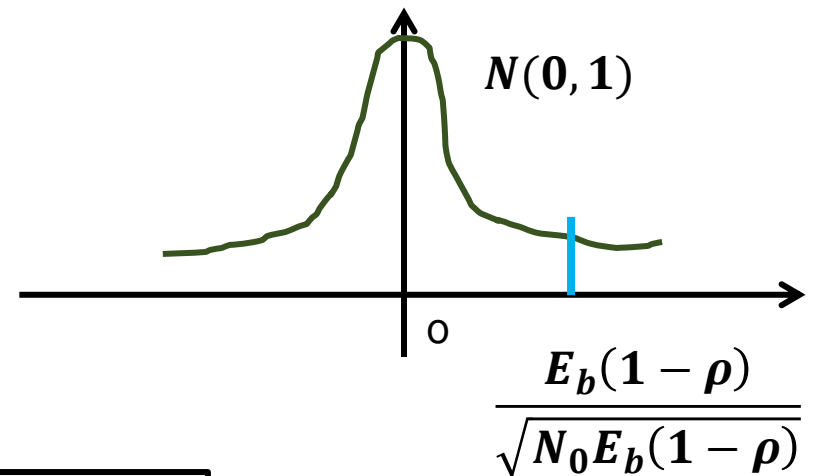
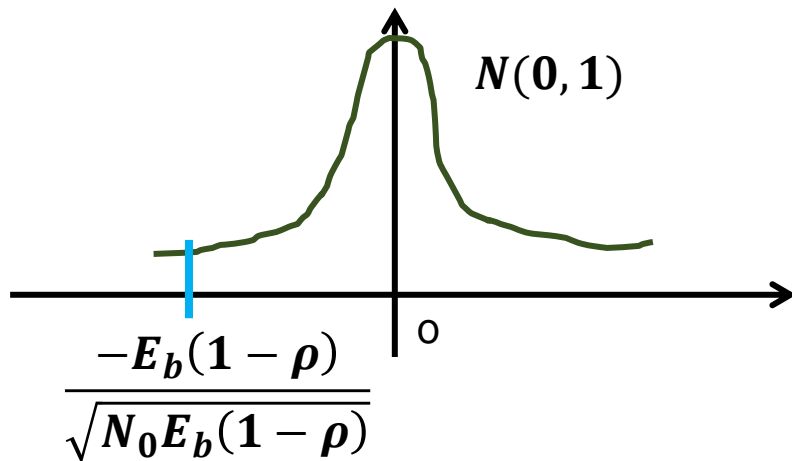
How to express this area with Q function?

Divide u by $\sqrt{N_0 E_b(1 - \rho)}$

Shift left by $E_b(1 - \rho)$



Bit Error Rate



$$P_e = Q\left(\sqrt{\frac{E_b(1-\rho)}{N_0}}\right)$$

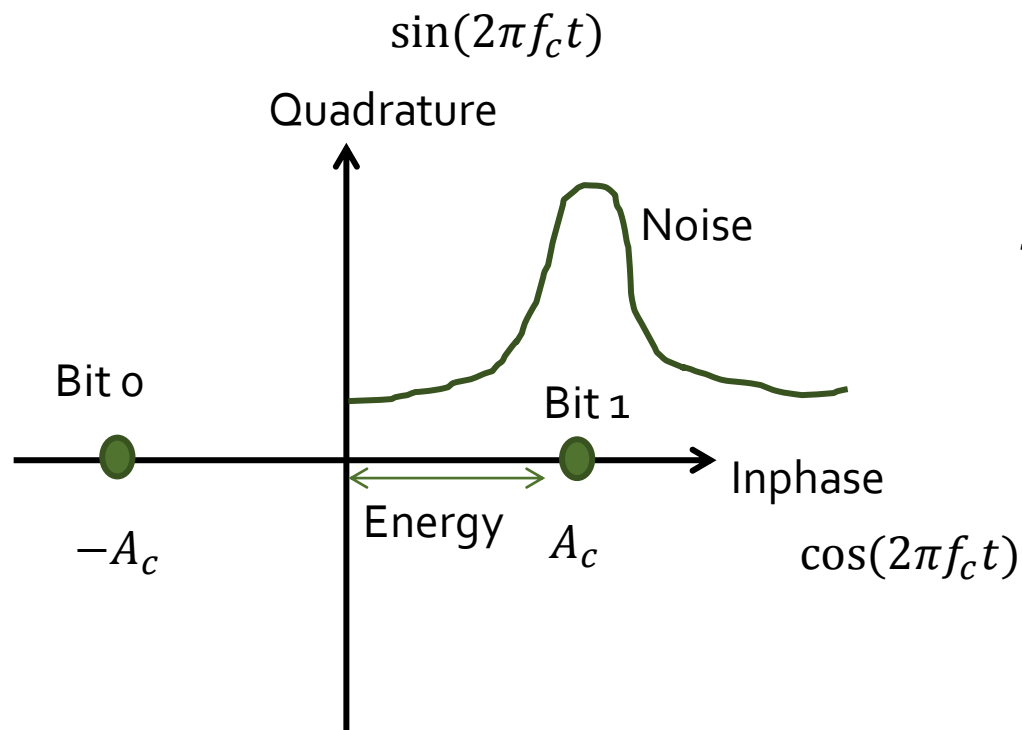
For BPSK, $\rho = -1$

$$P_e = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

For BFSK, $\rho = 0$

$$P_e = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

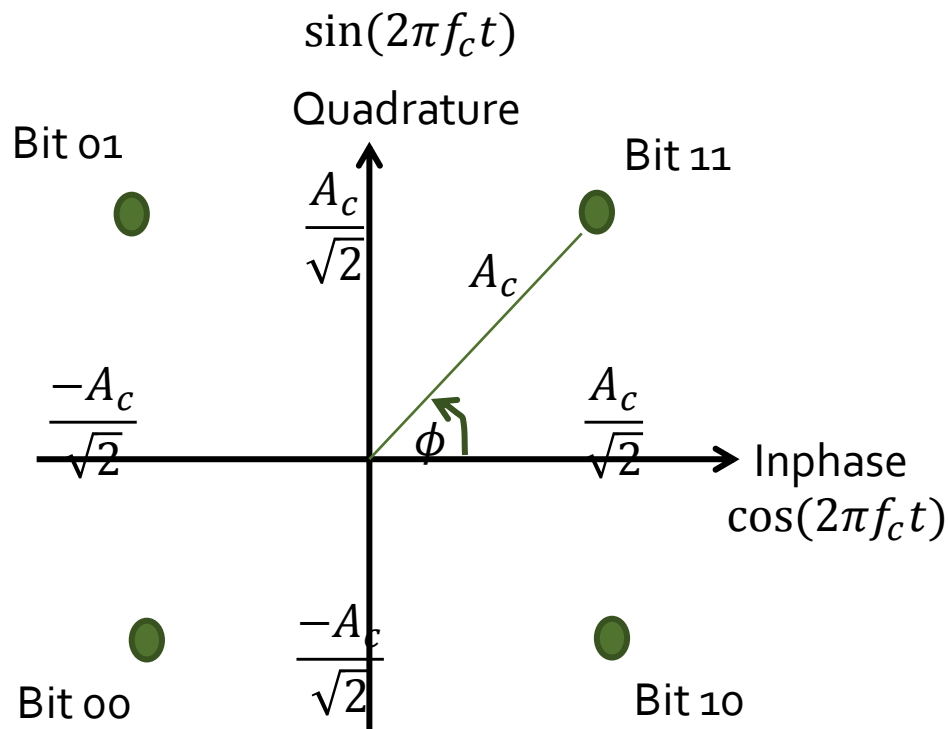
Signal Space - BPSK



$$s_1(t) = A_c \cos(2\pi f_c t)$$

$$s_0(t) = -A_c \cos(2\pi f_c t)$$

Signal Space - QPSK



$$s_{11}(t) = A_c \cos\left(2\pi f_c t + \frac{\pi}{4}\right)$$

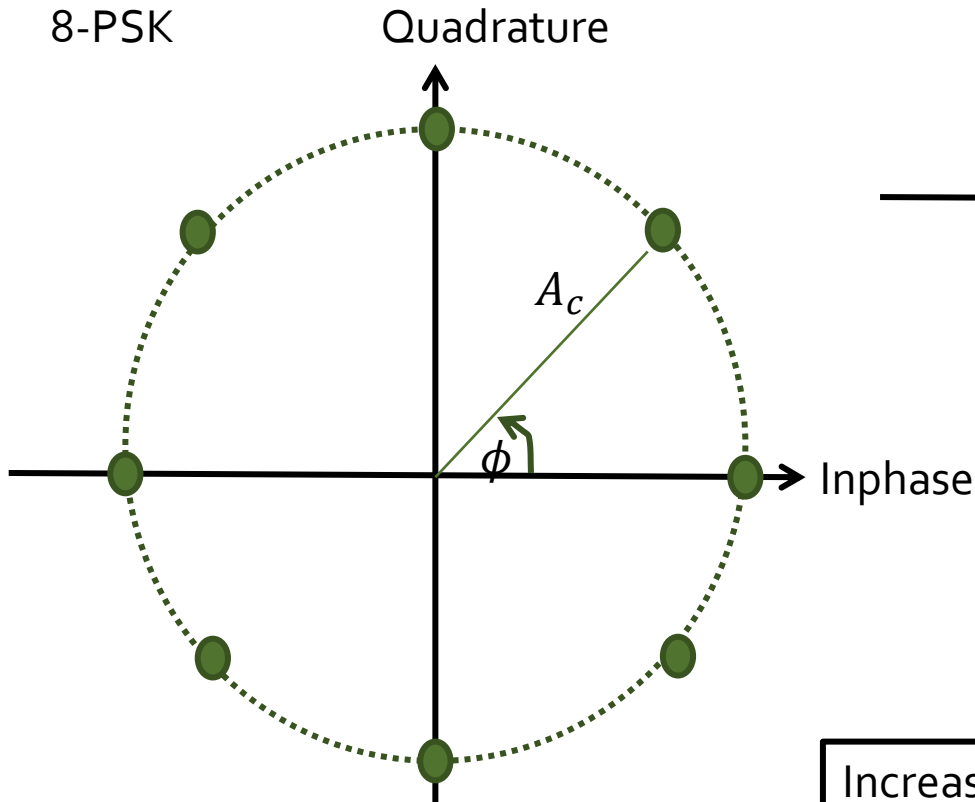
$$s_{01}(t) = A_c \cos\left(2\pi f_c t + \frac{3\pi}{4}\right)$$

$$s_{00}(t) = A_c \cos\left(2\pi f_c t + \frac{5\pi}{4}\right)$$

$$s_{10}(t) = A_c \cos\left(2\pi f_c t + \frac{7\pi}{4}\right)$$

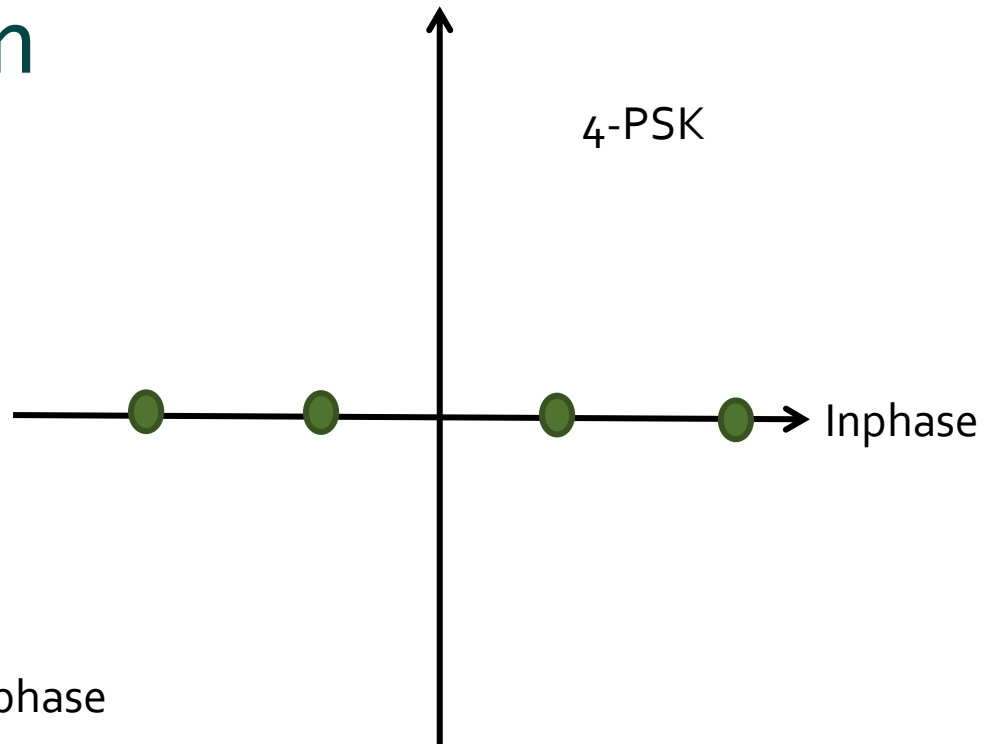
M-ary Modulation

8-PSK



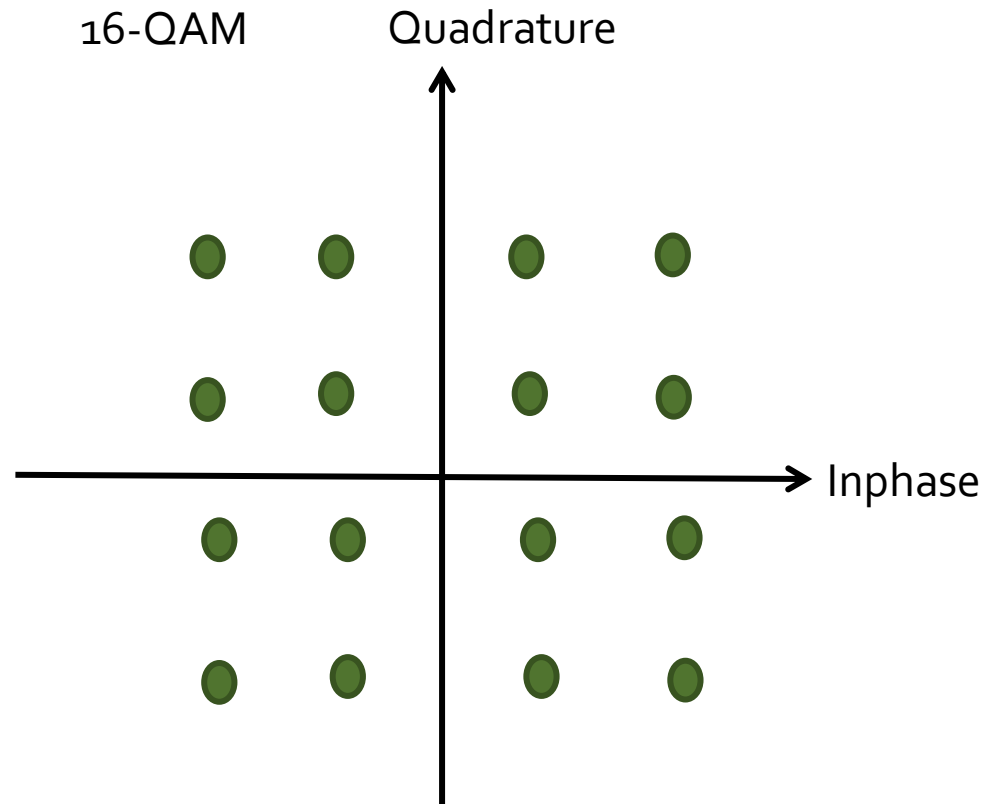
Quadrature

4-PSK

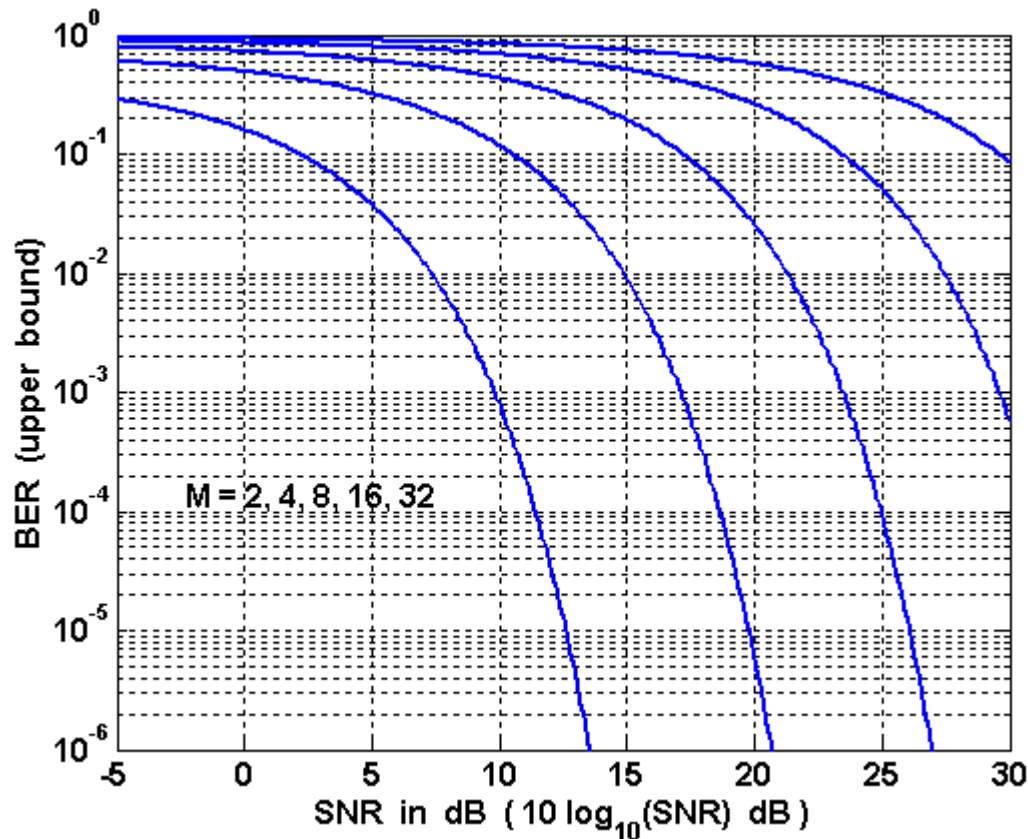


Increasing M would increase the data rate
(given the same signal bandwidth)

M-ary Modulation



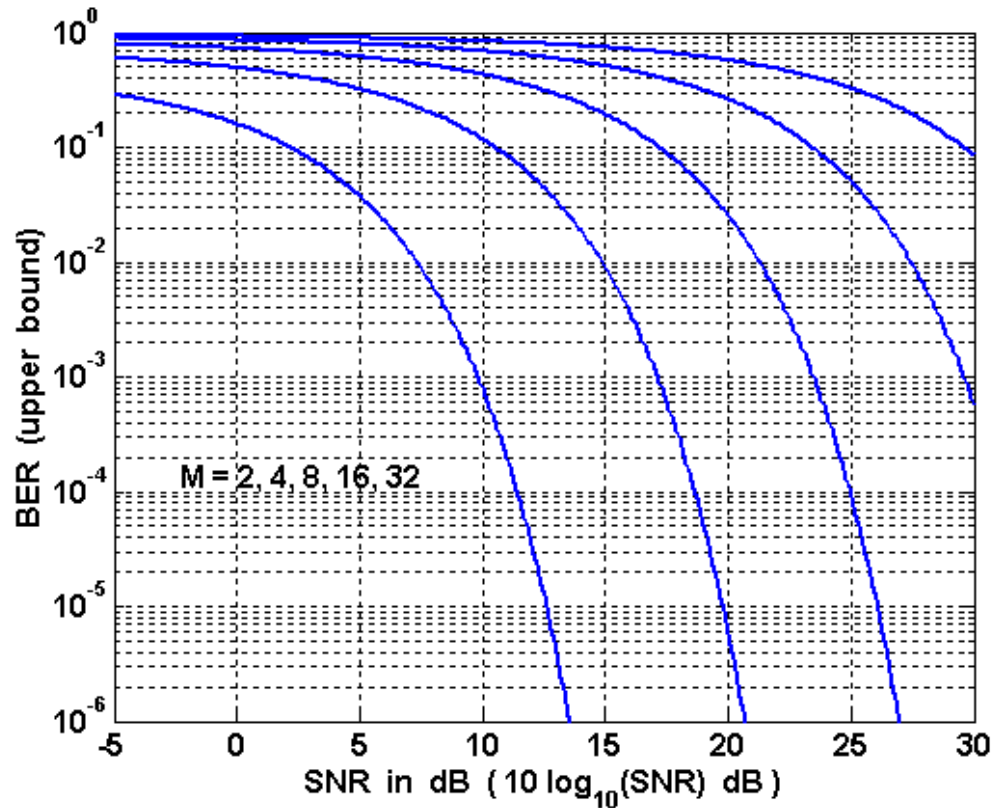
M-PAM BER versus SNR



$$SNR = \frac{\overline{E_b}}{\sigma_n^2}$$

$$BER \leq P_e \leq 2 \times \left(1 - \frac{1}{M}\right) \times Q \left(\sqrt{\frac{3 \times SNR}{M^2 - 1}} \right)$$

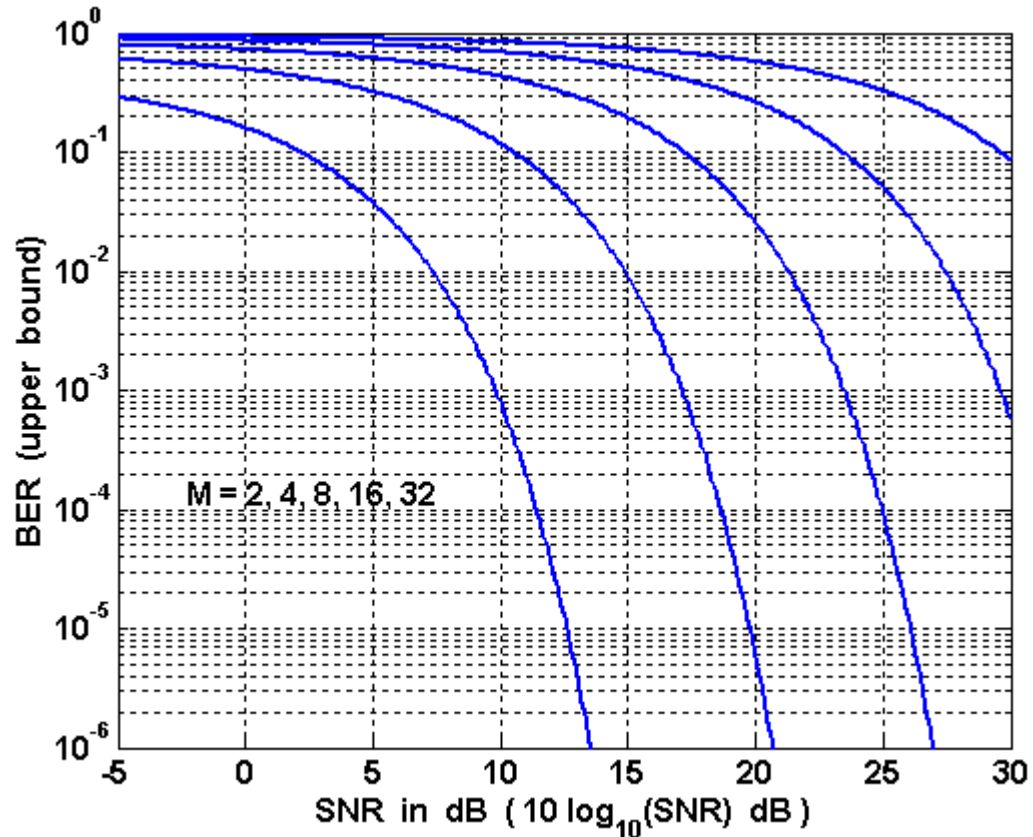
M-QAM BER versus SNR



$$BER \leq P_e \leq 4 \times \left(1 - \frac{1}{\sqrt{M}}\right) \times Q\left(\sqrt{\frac{3 \times \text{SNR}}{M - 1}}\right)$$

$$BER \leq P_e \leq 4 \times \left(1 - \frac{1}{\sqrt{2M}}\right) \times Q\left(\sqrt{\frac{3 \times \text{SNR}}{31 \times \frac{M}{32} - 1}}\right)$$

M-PSK BER versus SNR



$$BER \leq P_e \leq 2 \times Q \left(\sqrt{2 \times SNR} \times \sin \left(\frac{\pi}{M} \right) \right)$$