

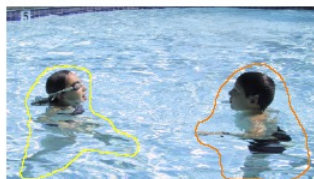
Gradient domain operations

Digital Visual Effects

Yung-Yu Chuang

with slides by Fredo Durand, Ramesh Raskar, Amit Agrawal

Gradient domain operators



sources/destinations



cloning



seamless cloning

Gradient Domain Manipulations

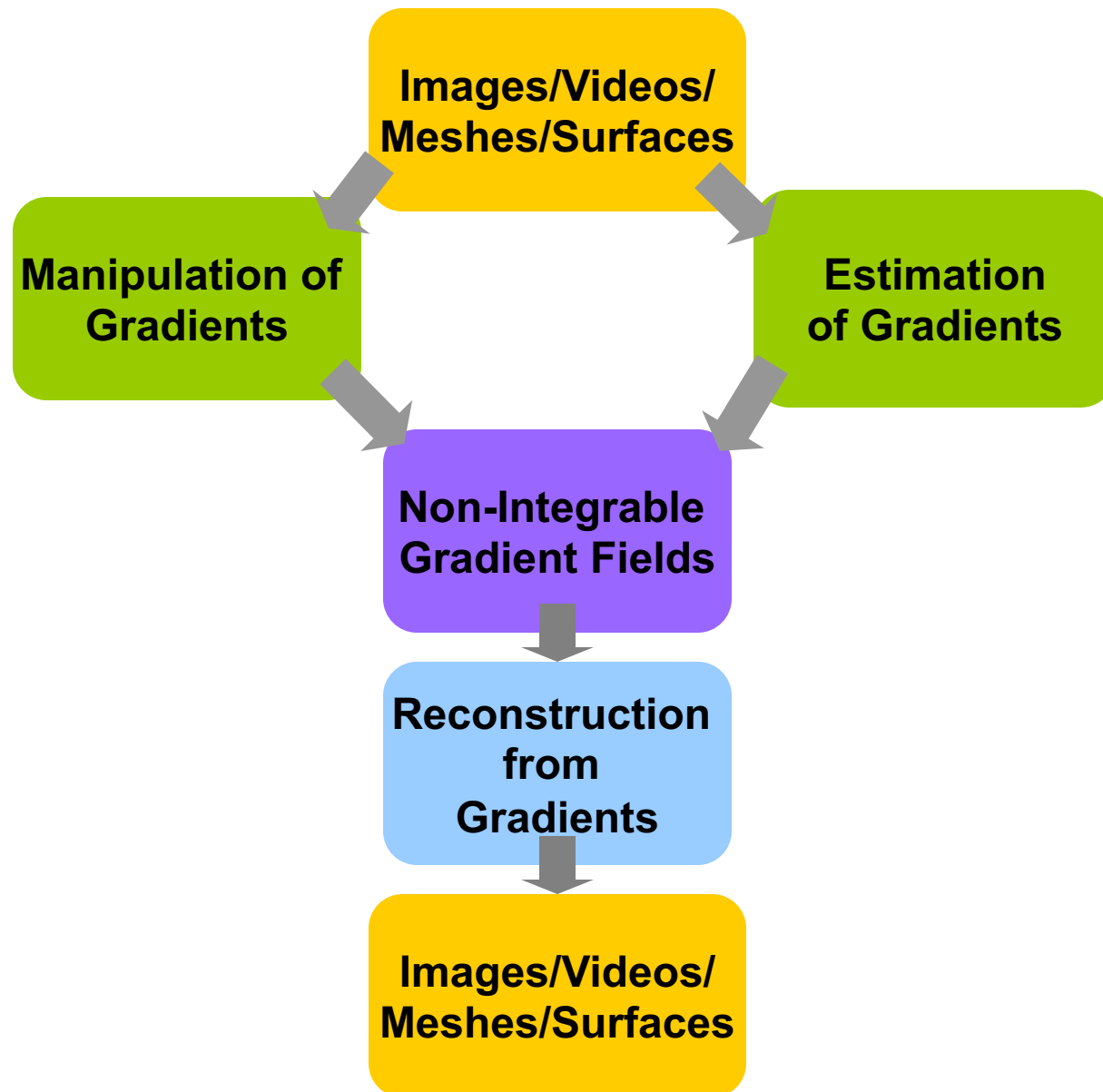
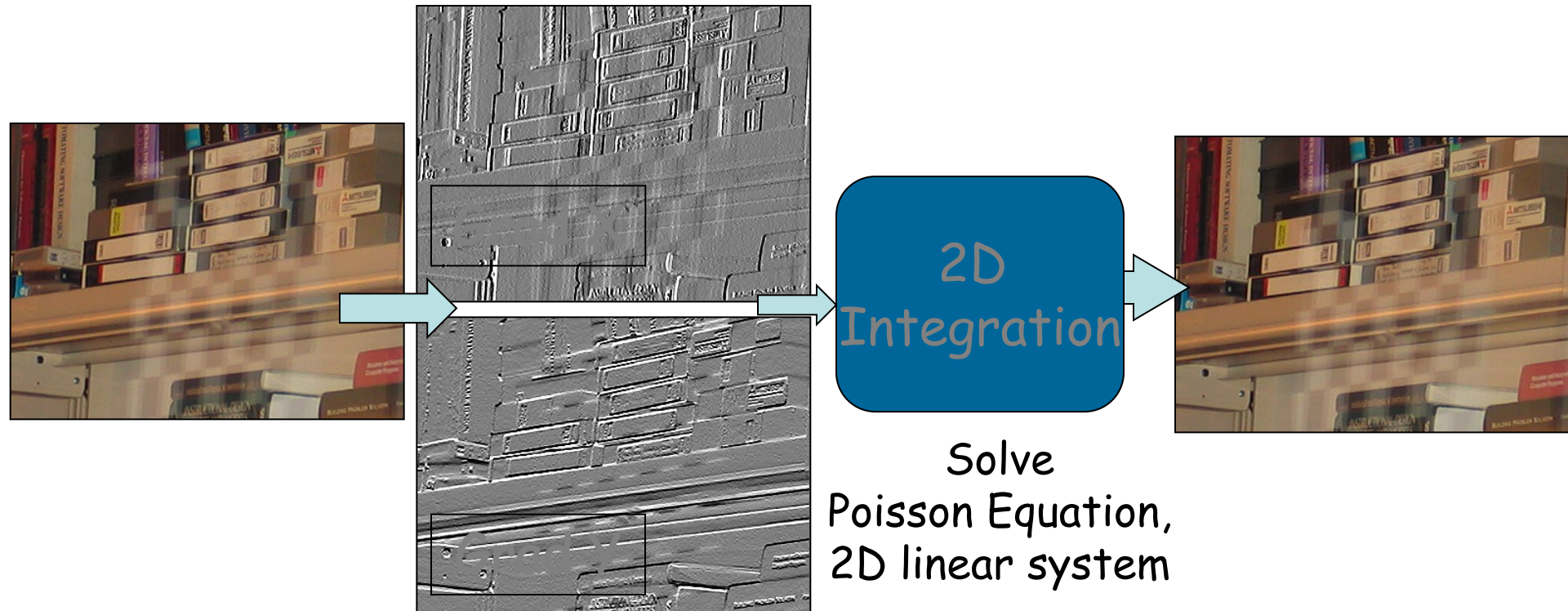
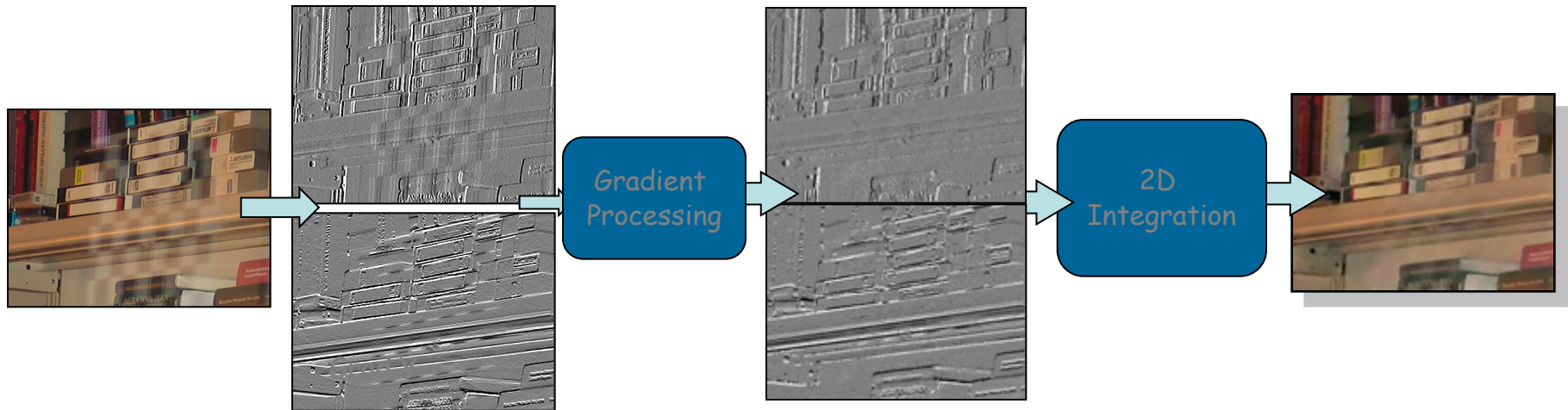


Image Intensity Gradients in 2D



Intensity Gradient Manipulation

A Common Pipeline

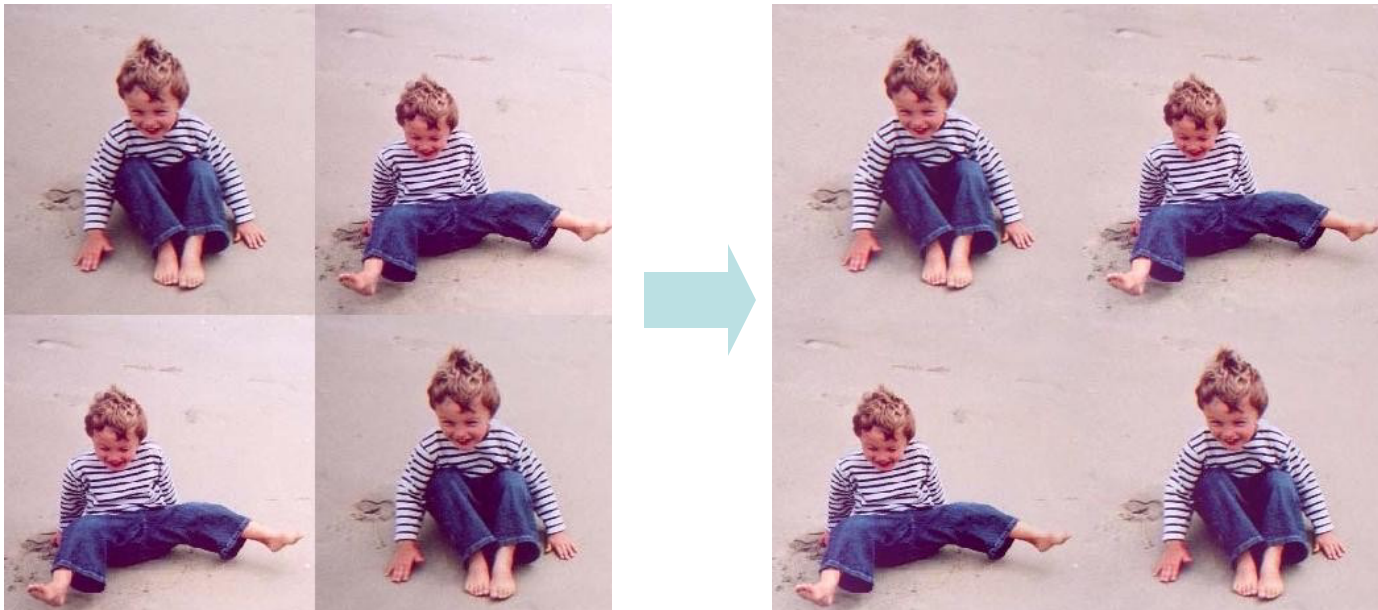


1. Gradient manipulation
2. Reconstruction from gradients

Example Applications



Removing Glass Reflections



Seamless Image Stitching

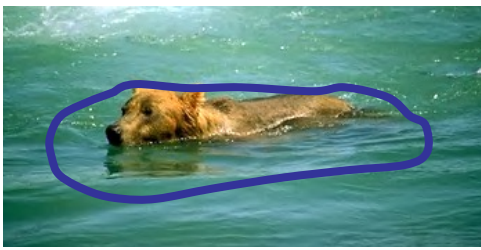


Image Editing



Changing Local Illumination





Original



PhotoshopGrey



Color2Gray

Color to Gray Conversion



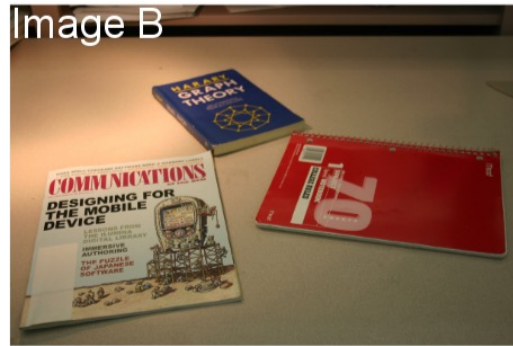
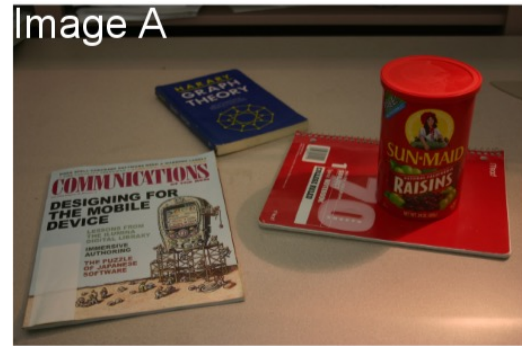
+



=



High Dynamic Range Compression



Edge Suppression under Significant Illumination Variations



+



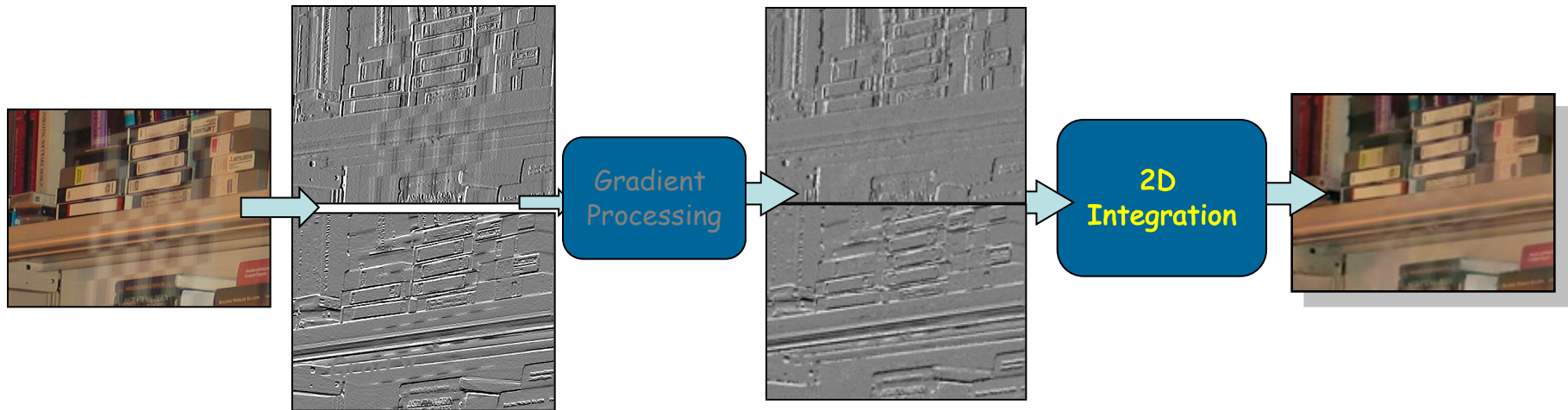
=



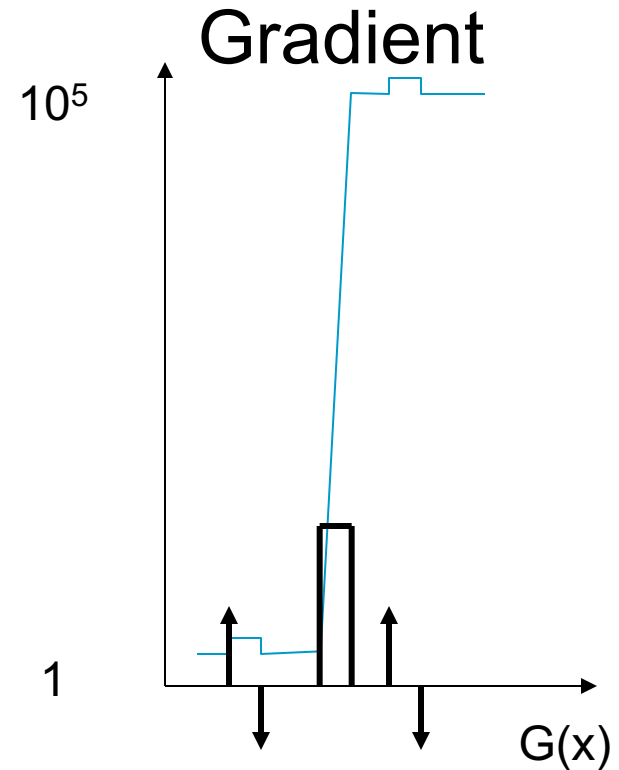
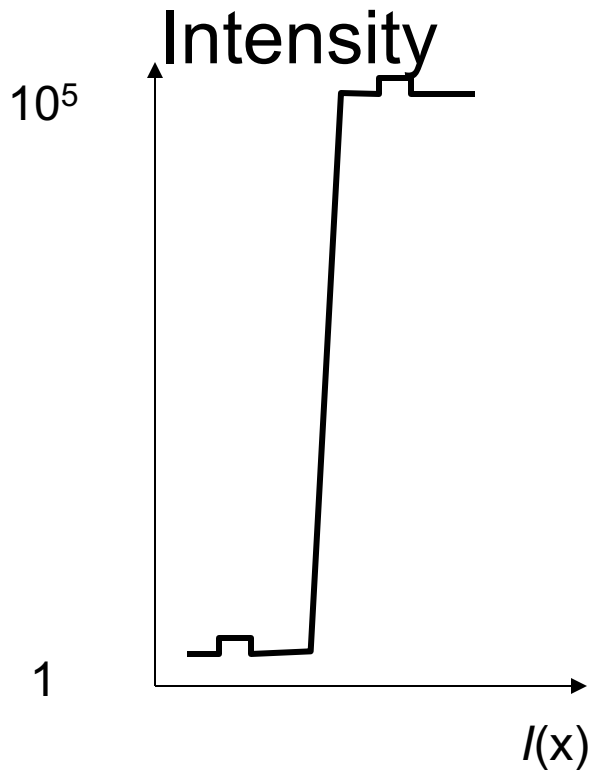
Fusion of day and night images

Intensity Gradient Manipulation

A Common Pipeline



Intensity Gradient in 1D

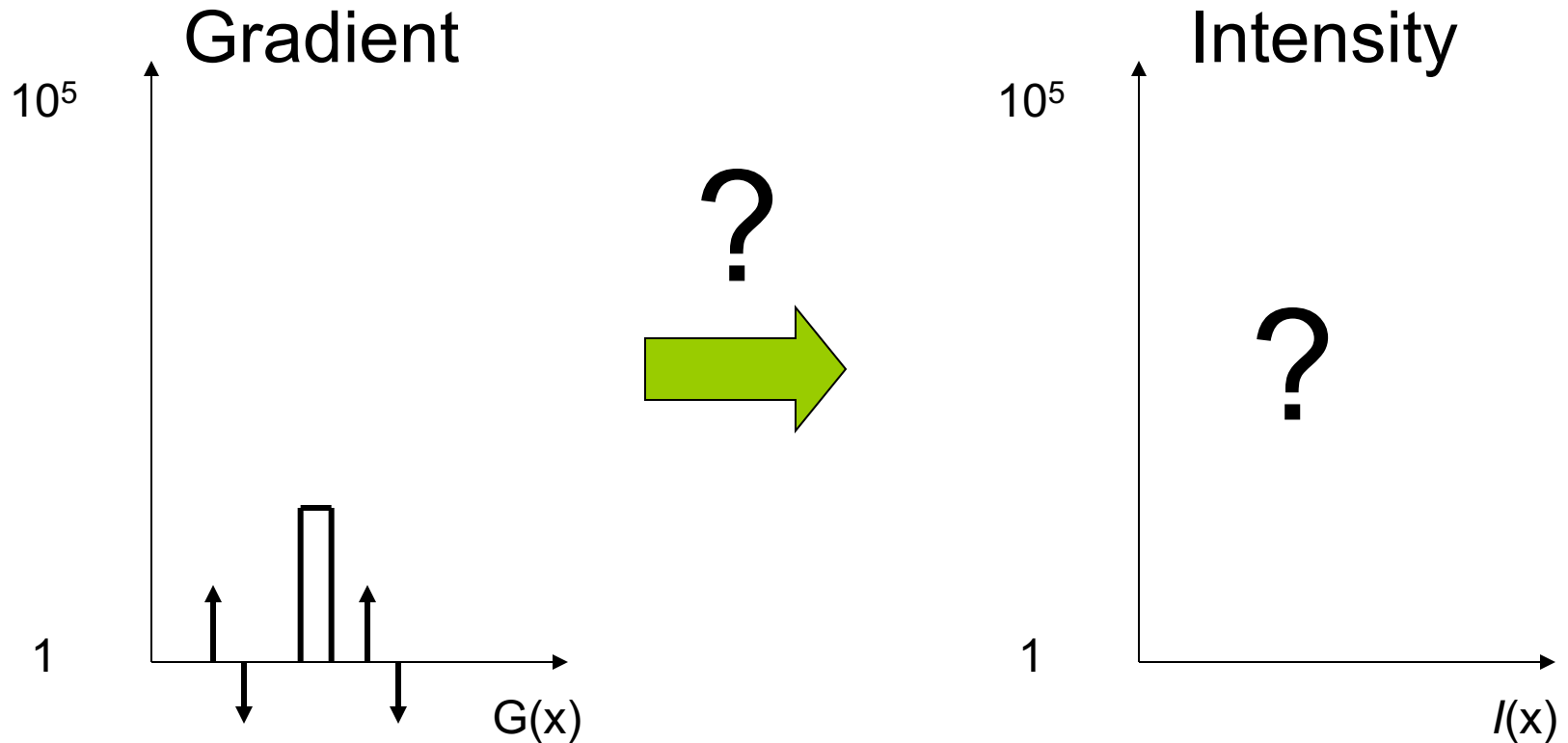


Gradient at x,

$$G(x) = \frac{I(x+1) - I(x)}{1}$$

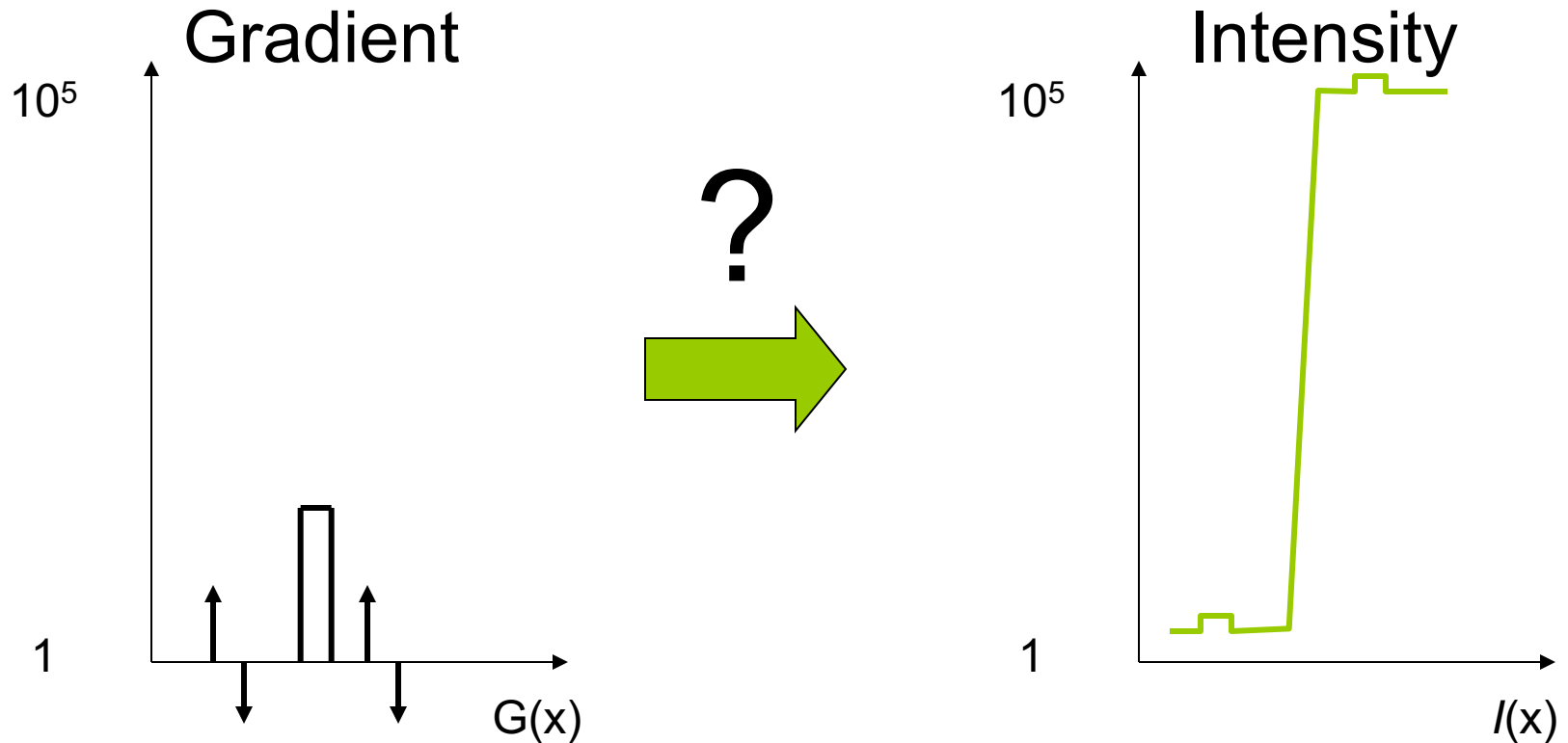
Forward Difference

Reconstruction from Gradients



For n intensity values, about n gradients

Reconstruction from Gradients



1D Integration

$$I(x) = I(x-1) + G(x)$$

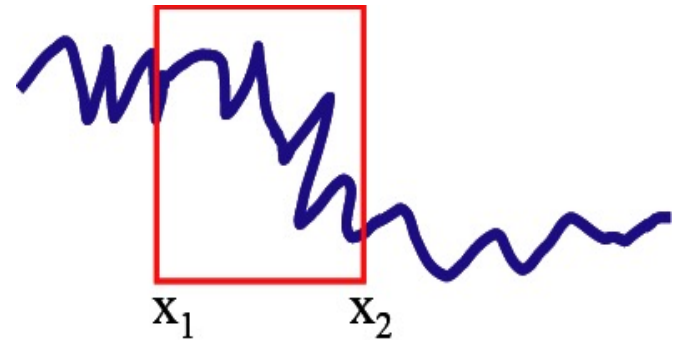
Cumulative sum

1D case with constraints

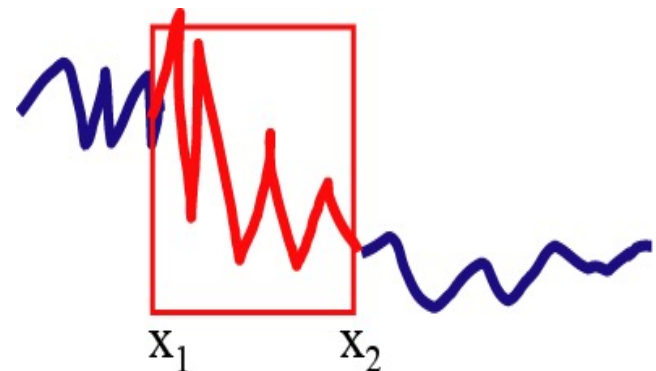
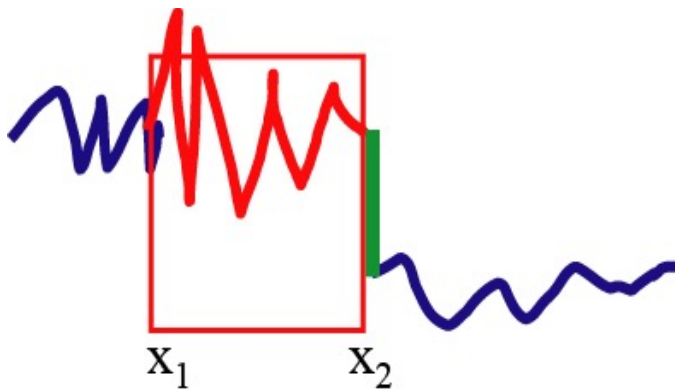
Seamlessly paste



onto

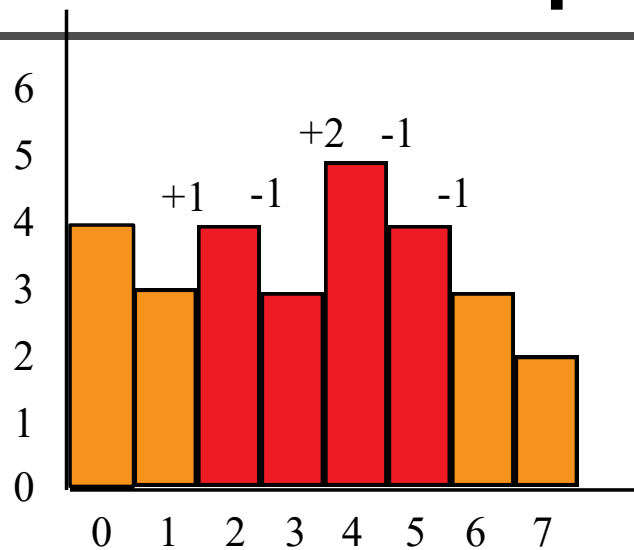


Just add a linear function so that the boundary condition is respected

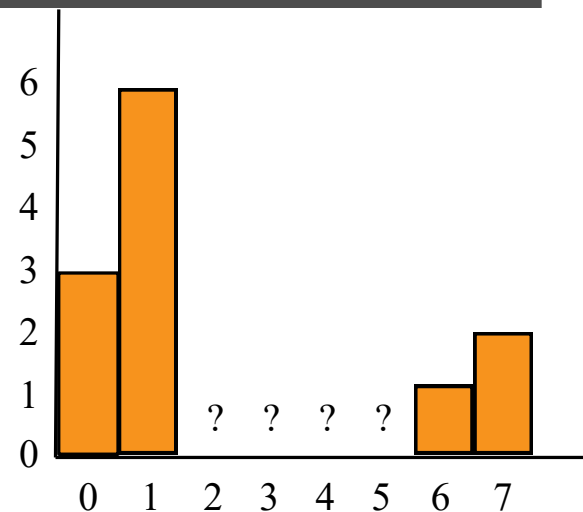


Discrete 1D example: minimization

- Copy



to



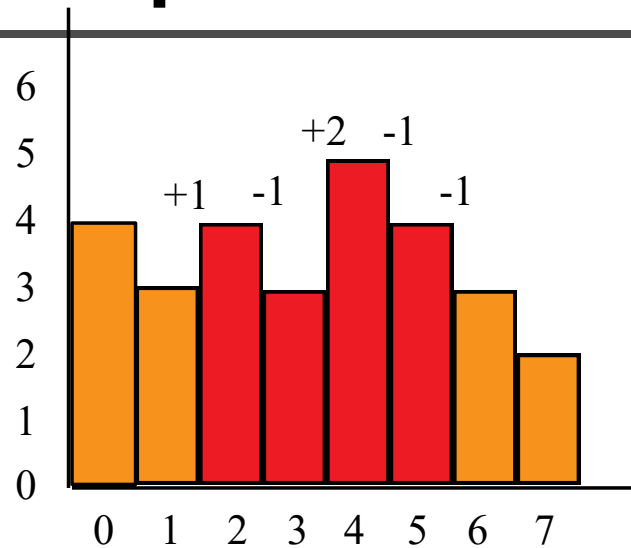
- $\text{Min } ((f_2 - f_1) - 1)^2$
- $\text{Min } ((f_3 - f_2) - (-1))^2$
- $\text{Min } ((f_4 - f_3) - 2)^2$
- $\text{Min } ((f_5 - f_4) - (-1))^2$
- $\text{Min } ((f_6 - f_5) - (-1))^2$



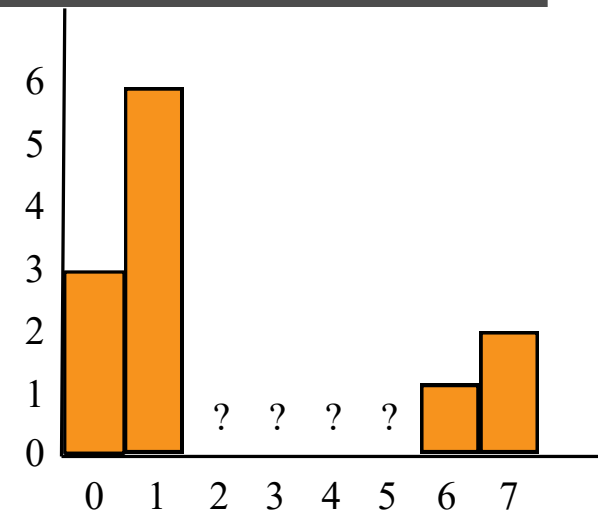
With
 $f_1 = 6$
 $f_6 = 1$

1D example: minimization

- Copy



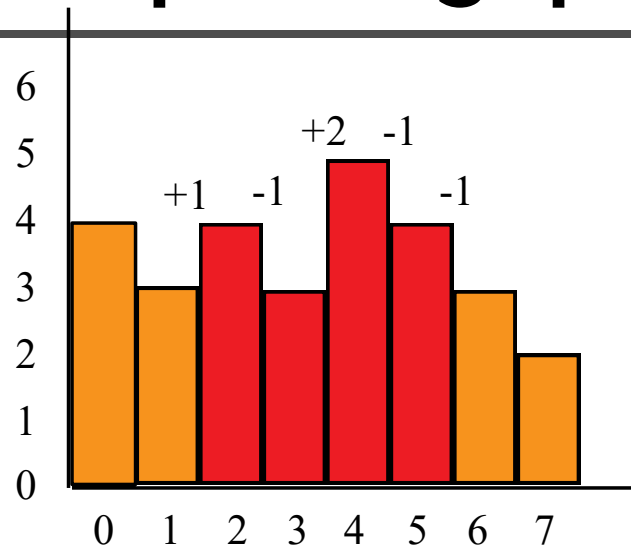
to



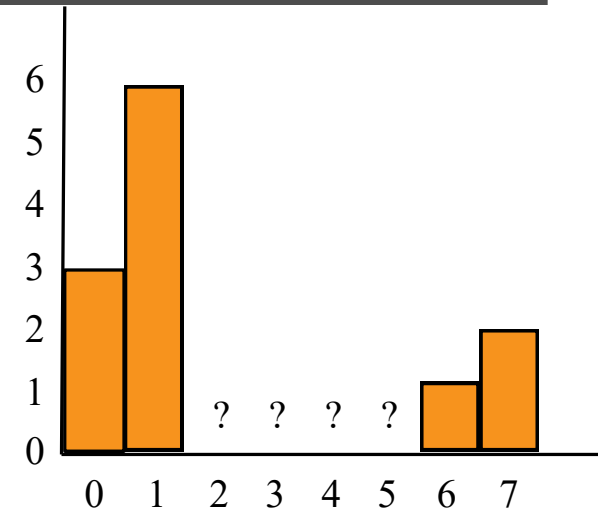
- $\text{Min } ((f_2 - 6) - 1)^2 \implies f_2^2 + 49 - 14f_2$
- $\text{Min } ((f_3 - f_2) - (-1))^2 \implies f_3^2 + f_2^2 + 1 - 2f_3f_2 + 2f_3 - 2f_2$
- $\text{Min } ((f_4 - f_3) - 2)^2 \implies f_4^2 + f_3^2 + 4 - 2f_3f_4 - 4f_4 + 4f_3$
- $\text{Min } ((f_5 - f_4) - (-1))^2 \implies f_5^2 + f_4^2 + 1 - 2f_5f_4 + 2f_5 - 2f_4$
- $\text{Min } ((1 - f_5) - (-1))^2 \implies f_5^2 + 4 - 4f_5$

1D example: big quadratic

- Copy



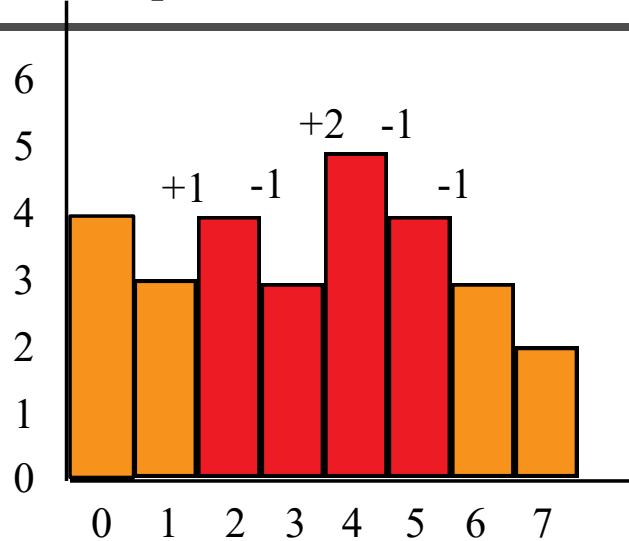
to



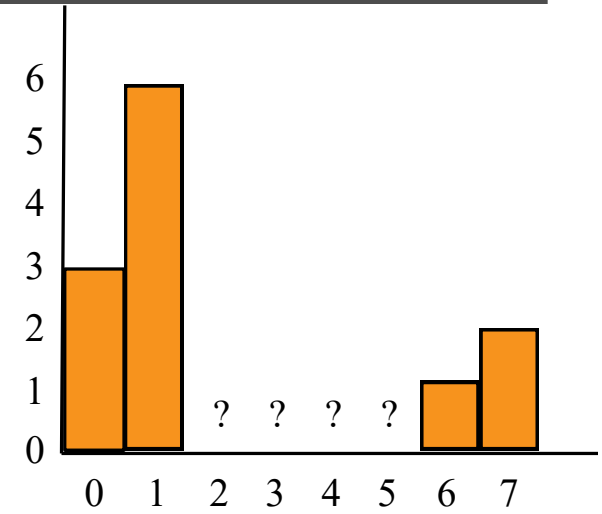
- Min $(f_2^2 + 49 - 14f_2$
 $+ f_3^2 + f_2^2 + 1 - 2f_3f_2 + 2f_3 - 2f_2$
 $+ f_4^2 + f_3^2 + 4 - 2f_3f_4 - 4f_4 + 4f_3$
 $+ f_5^2 + f_4^2 + 1 - 2f_5f_4 + 2f_5 - 2f_4$
 $+ f_5^2 + 4 - 4f_5)$
 Denote it Q

1D example: derivatives

- Copy



to



Min ($f_2^2 + 49 - 14f_2$

+ $f_3^2 + f_2^2 + 1 - 2f_3f_2 + 2f_3 - 2f_2$

+ $f_4^2 + f_3^2 + 4 - 2f_3f_4 - 4f_4 + 4f_3$

+ $f_5^2 + f_4^2 + 1 - 2f_5f_4 + 2f_5 - 2f_4$

+ $f_5^2 + 4 - 4f_5$)

Denote it Q

$$\frac{dQ}{df_2} = 2f_2 + 2f_2 - 2f_3 - 16$$

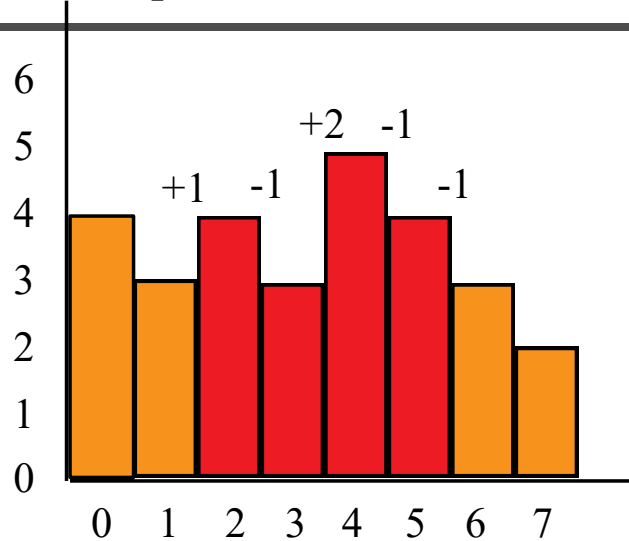
$$\frac{dQ}{df_3} = 2f_3 - 2f_2 + 2 + 2f_3 - 2f_4 + 4$$

$$\frac{dQ}{df_4} = 2f_4 - 2f_3 - 4 + 2f_4 - 2f_5 - 2$$

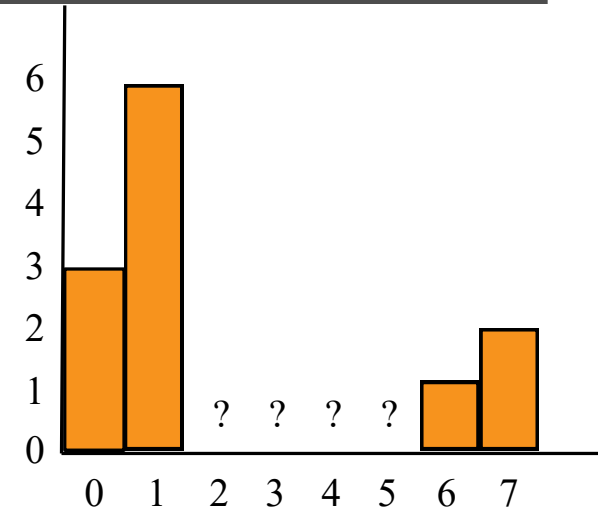
$$\frac{dQ}{df_5} = 2f_5 - 2f_4 + 2 + 2f_5 - 4$$

1D example: set derivatives to zero

- Copy



to



$$\frac{dQ}{df_2} = 2f_2 + 2f_2 - 2f_3 - 16$$

$$\frac{dQ}{df_3} = 2f_3 - 2f_2 + 2 + 2f_3 - 2f_4 + 4$$

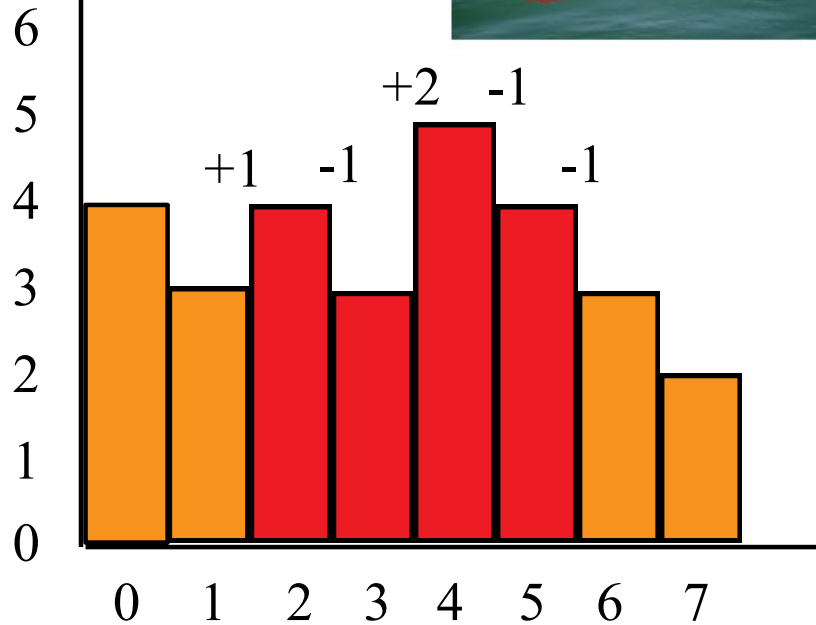
$$\frac{dQ}{df_4} = 2f_4 - 2f_3 - 4 + 2f_4 - 2f_5 - 2$$

$$\frac{dQ}{df_5} = 2f_5 - 2f_4 + 2 + 2f_5 - 4$$

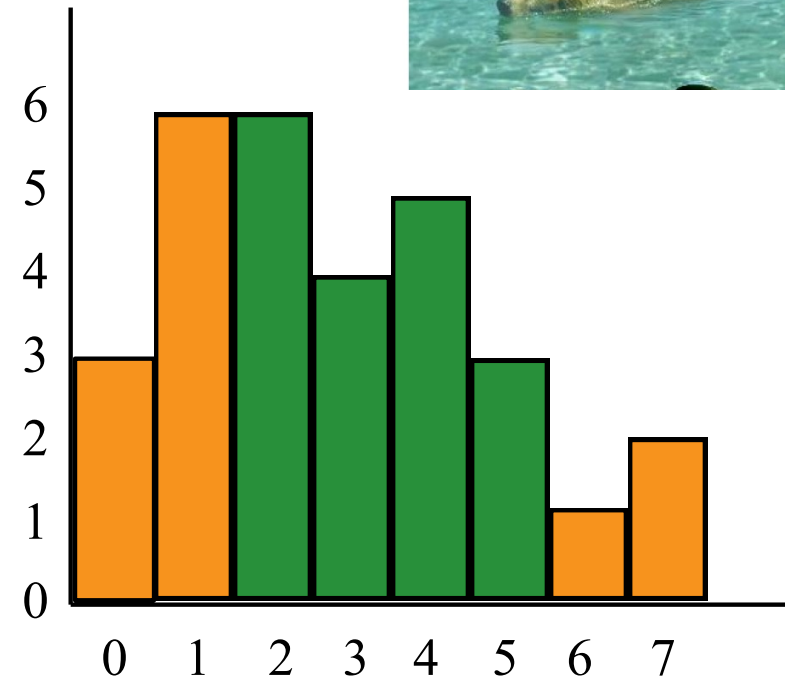
$$\Rightarrow \begin{pmatrix} 4 & -2 & 0 & 0 \\ -2 & 4 & -2 & 0 \\ 0 & -2 & 4 & -2 \\ 0 & 0 & -2 & 4 \end{pmatrix} \begin{pmatrix} f_2 \\ f_3 \\ f_4 \\ f_5 \end{pmatrix} = \begin{pmatrix} 16 \\ -6 \\ 6 \\ 2 \end{pmatrix}$$

1D example

• Copy



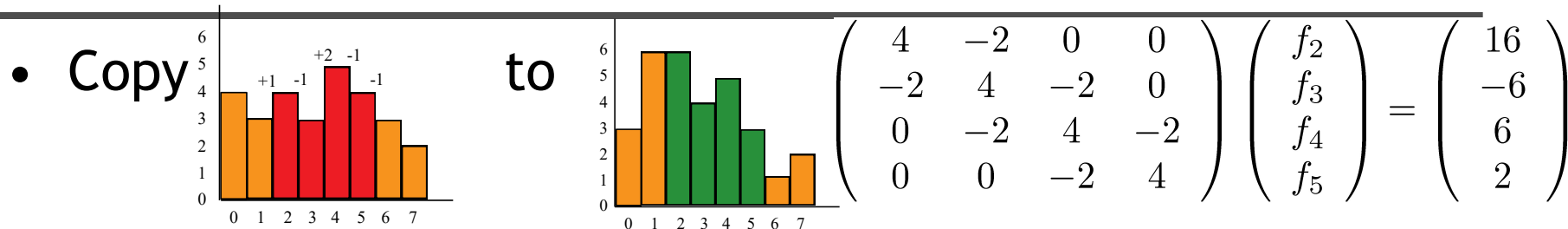
to



$$\begin{pmatrix} 4 & -2 & 0 & 0 \\ -2 & 4 & -2 & 0 \\ 0 & -2 & 4 & -2 \\ 0 & 0 & -2 & 4 \end{pmatrix} \begin{pmatrix} f_2 \\ f_3 \\ f_4 \\ f_5 \end{pmatrix} = \begin{pmatrix} 16 \\ -6 \\ 6 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} f_2 \\ f_3 \\ f_4 \\ f_5 \end{pmatrix} = \begin{pmatrix} 6 \\ 4 \\ 5 \\ 3 \end{pmatrix}$$

1D example: remarks

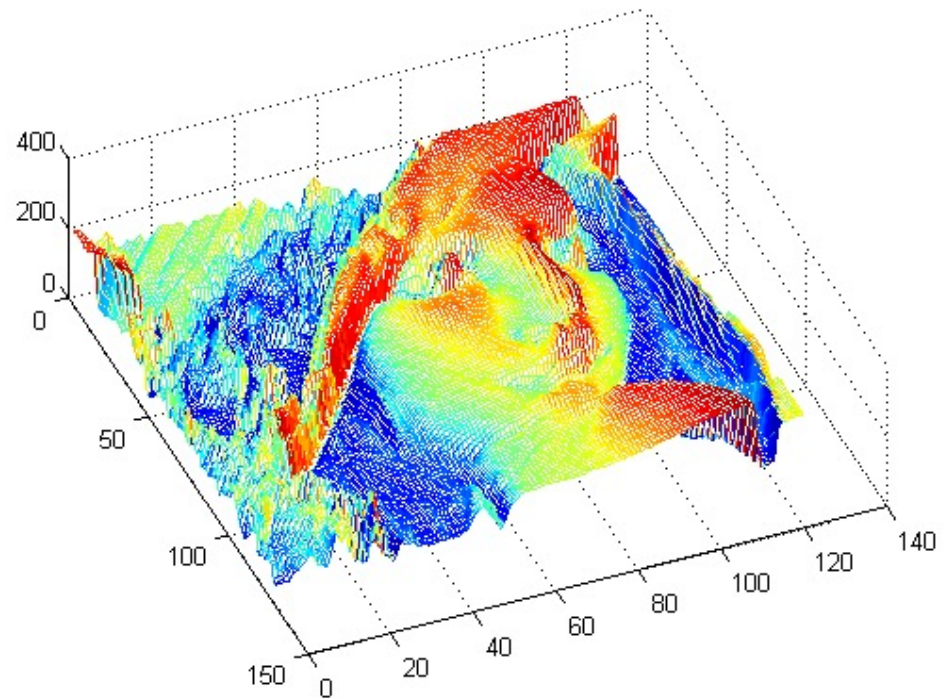


- Matrix is sparse
- Matrix is symmetric
- Everything is a multiple of 2
 - because square and derivative of square
- Matrix is a convolution (kernel -2 4 -2)
- Matrix is independent of gradient field. Only RHS is
- Matrix is a second derivative

2D example: images

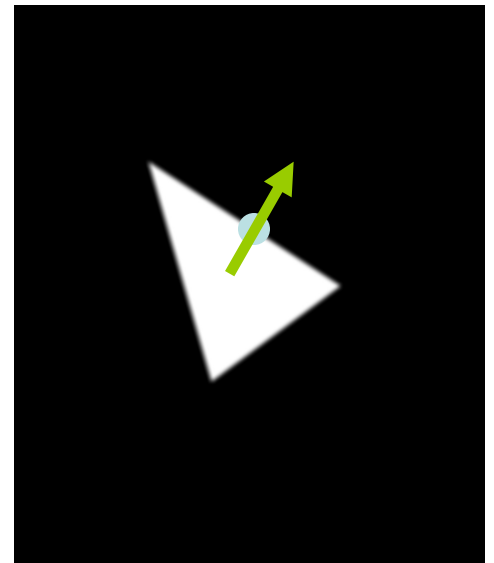
- Images as scalar fields

- $\mathbb{R}^2 \rightarrow \mathbb{R}$



Gradients

- Vector field (gradient field)
 - Derivative of a scalar field
- Direction
 - Maximum rate of change of scalar field
- Magnitude
 - Rate of change



Example



Image
 $I(x,y)$



I_x



I_y

Gradient at x,y as Forward Differences

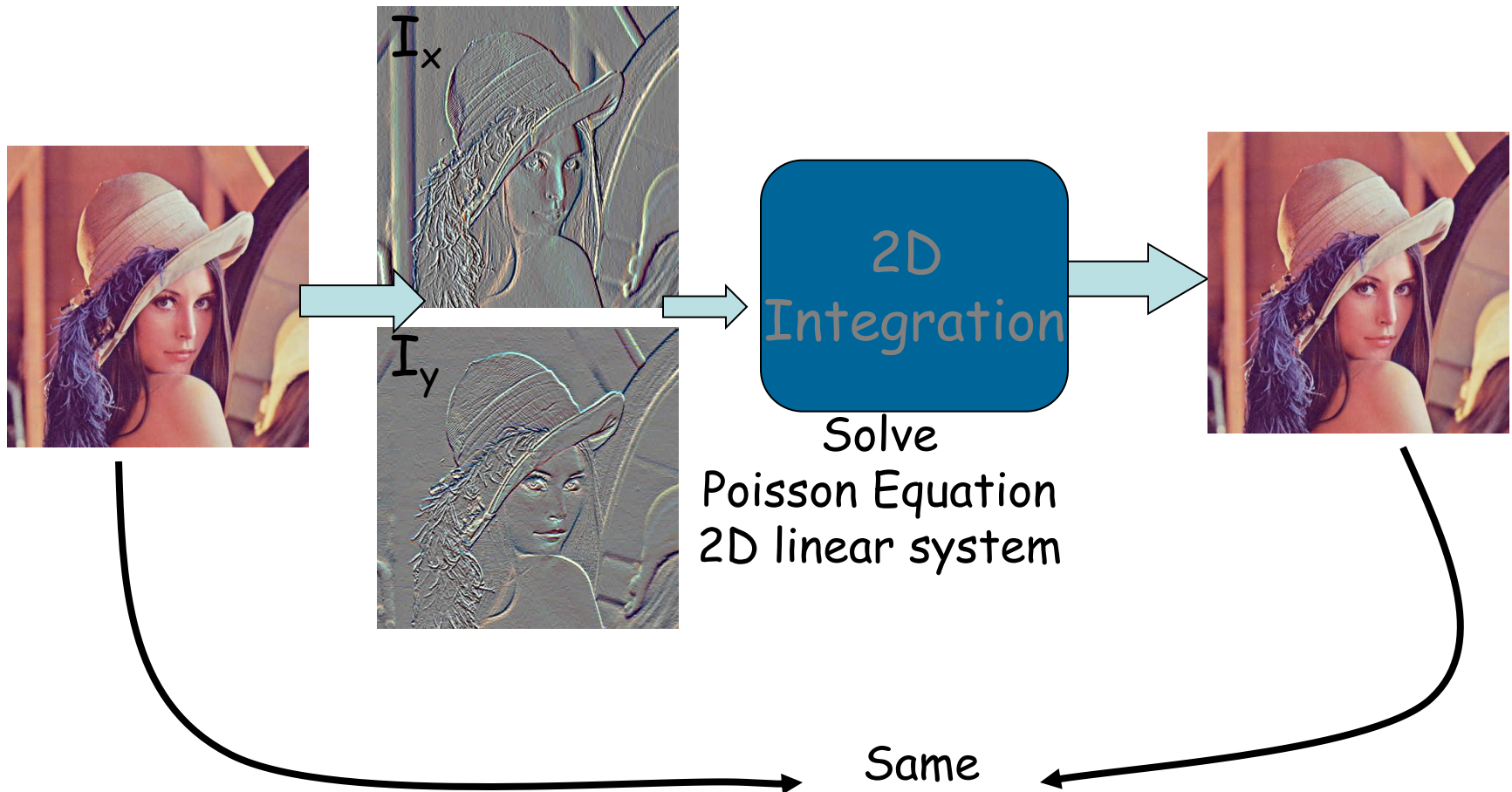
$$G_x(x,y) = I(x+1, y) - I(x,y)$$

$$G_y(x,y) = I(x, y+1) - I(x,y)$$

$$G(x,y) = (G_x, G_y)$$

Reconstruction from Gradients

Sanity Check: Recovering Original Image

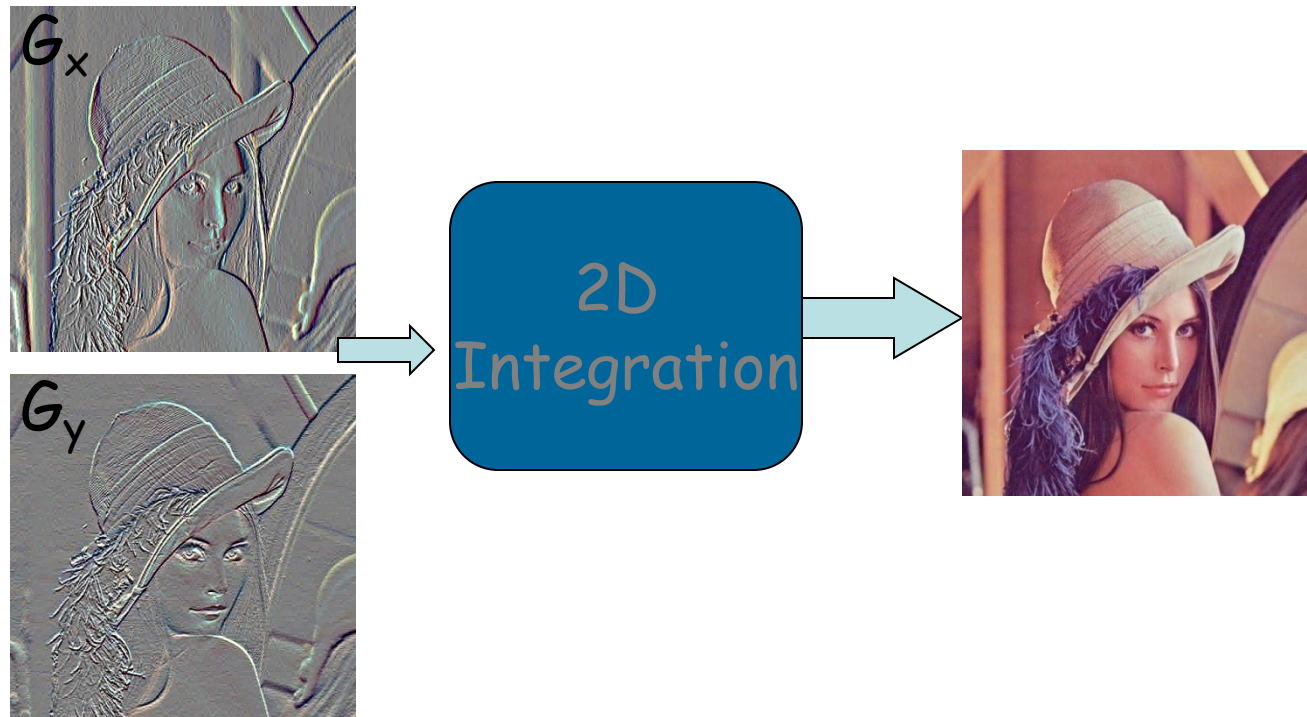


Reconstruction from Gradients

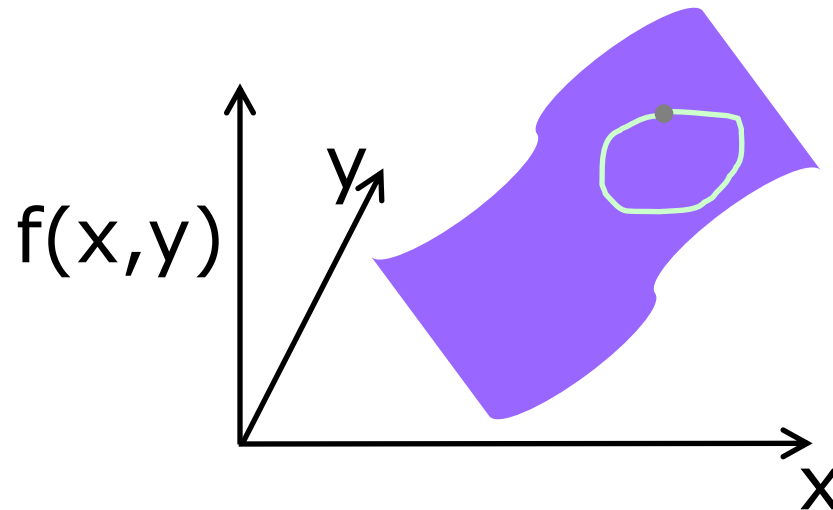
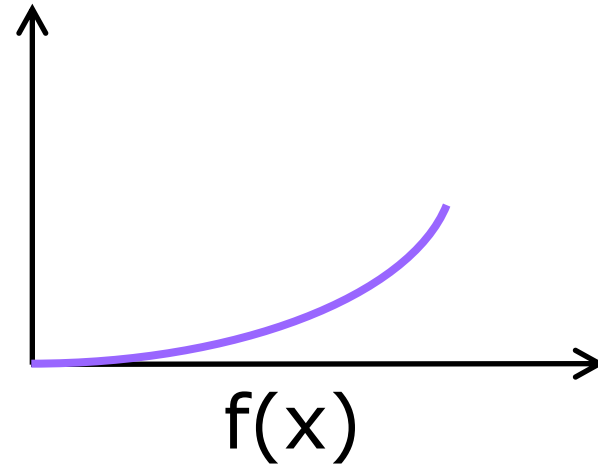
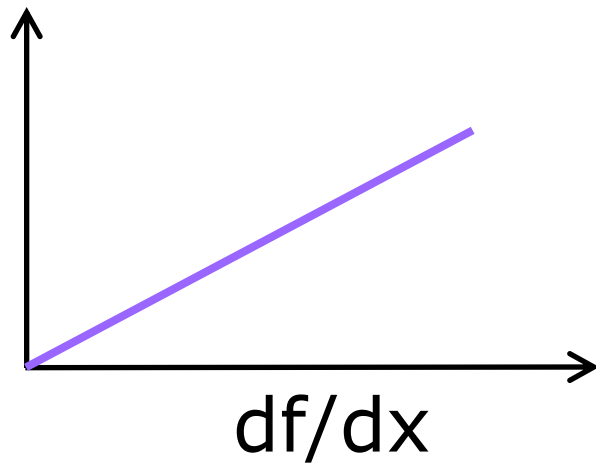
Given $G(x,y) = (G_x, G_y)$

How to compute $I(x,y)$ for the image ?

For n^2 image pixels, $2 n^2$ gradients !



2D Integration is non-trivial



Reconstruction depends on chosen path

Reconstruction from Gradient Field G

- Look for image I with gradient closest to G in the least squares sense.
- I minimizes the integral: $\iint F(\nabla I, G) dx dy$

$$F(\nabla I, G) = \|\nabla I - G\|^2 = \left(\frac{\partial I}{\partial x} - G_x \right)^2 + \left(\frac{\partial I}{\partial y} - G_y \right)^2$$

$$\rightarrow \frac{\partial^2 I}{\partial x^2} + \frac{\partial^2 I}{\partial y^2} = \frac{\partial G_x}{\partial x} + \frac{\partial G_y}{\partial y}$$

Solve $\frac{\partial^2 I}{\partial x^2} + \frac{\partial^2 I}{\partial y^2} = \frac{\partial G_x}{\partial x} + \frac{\partial G_y}{\partial y}$

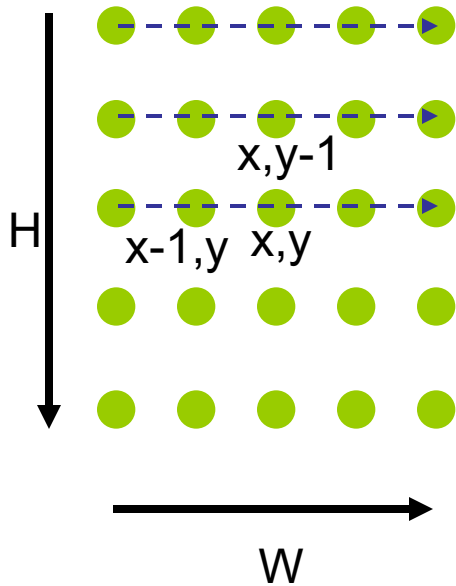
$$G_x(x, y) - G_x(x-1, y) + G_y(x, y) - G_y(x, y-1)$$

$$I(x+1, y) + I(x-1, y) + I(x, y+1) + I(x, y-1) - 4I(x, y)$$

$$\begin{bmatrix} \dots & 1 & \dots & 1 & -4 & 1 & \dots & 1 & \dots \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} = \begin{bmatrix} \end{bmatrix}$$

Linear System

$$-4I(x, y) + I(x, y+1) + I(x, y-1) + I(x+1, y) + I(x-1, y) = u(x, y)$$



$$[\underbrace{. \quad 1 \quad . \quad . \quad . \quad 1}_{H} \quad -4 \quad 1 \quad . \quad . \quad . \quad 1 \quad .]$$

H

H

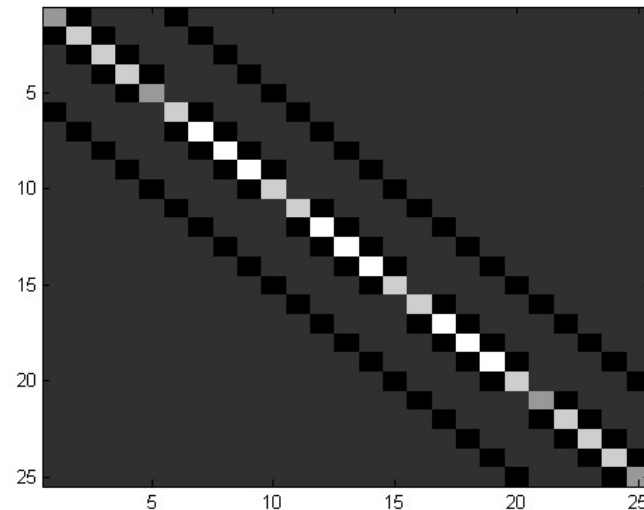
$$\begin{bmatrix} . \\ . \\ . \\ . \\ . \\ I(x, y-1) \\ I(x, y) \\ I(x, y+1) \\ . \\ . \\ . \\ . \\ I(x+1, y) \\ . \\ . \end{bmatrix} = u(x, y) \begin{bmatrix} . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \\ . \end{bmatrix}$$

A

x

b

A matrix

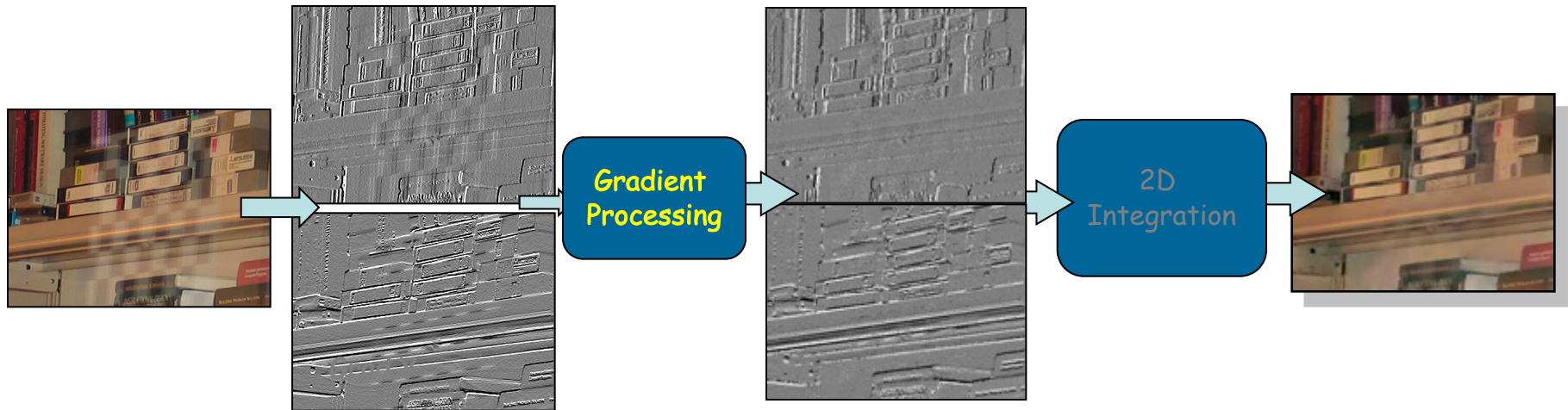


Solving Linear System

- Image size $N \times N$
- Size of $A \sim N^2$ by N^2
- Impractical to form and store A
- Direct Solvers
- Basis Functions
- Multigrid
- Conjugate Gradients

Intensity Gradient Manipulation

A Common Pipeline

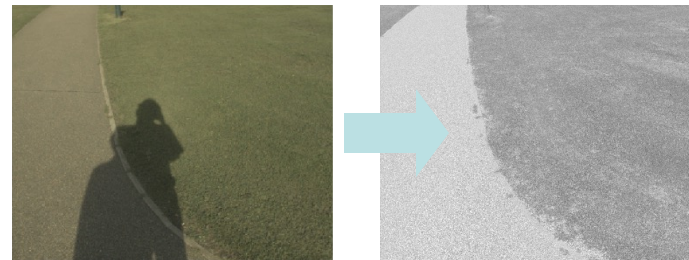


Gradient Domain Manipulations: Overview

- (A) Per pixel
- (B) Corresponding gradients in two images
- (C) Corresponding gradients in multiple images
- (D) Combining gradients along seams

A. Per Pixel Manipulations

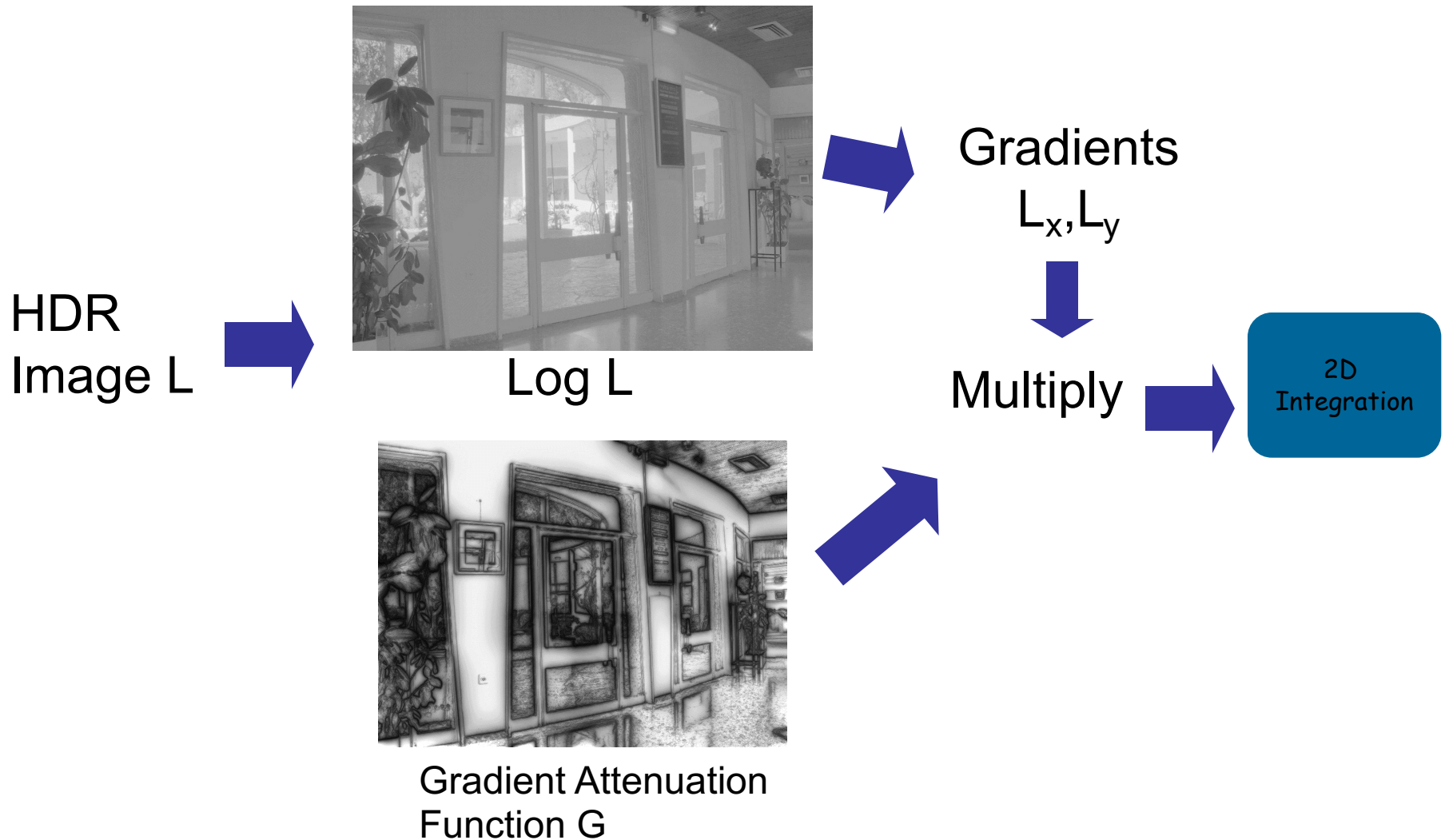
- Non-linear operations
 - HDR compression, local illumination change
- Set to zero
 - Shadow removal, intrinsic images, texture de-emphasis



High Dynamic Range Imaging



Gradient Domain Compression



Illumination Invariant Image



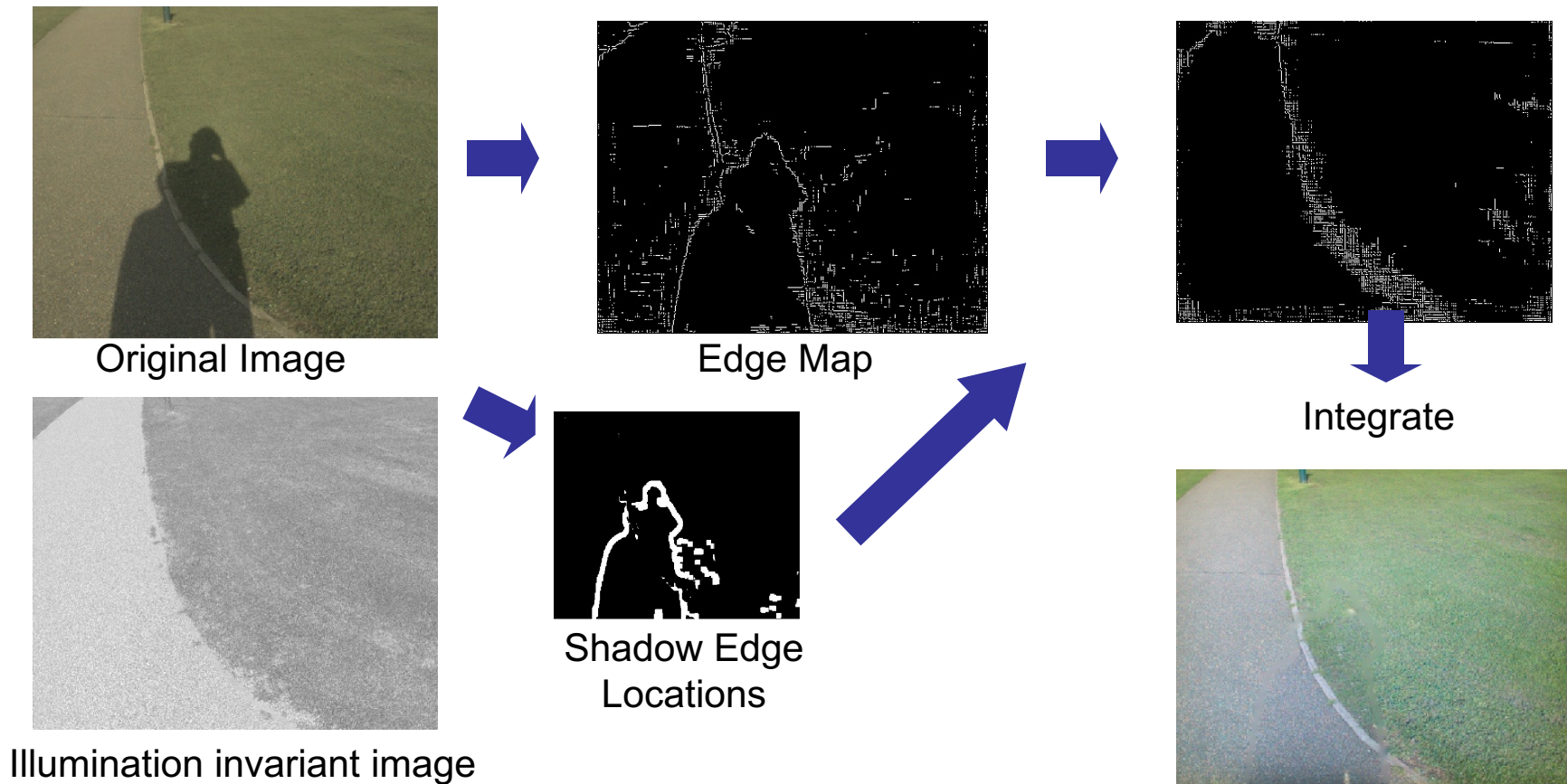
Original Image



Illumination invariant image

- Assumptions
 - Sensor response = delta functions R , G , B in wavelength spectrum
 - Illumination restricted to Outdoor Illumination

Shadow Removal Using Illumination Invariant Image



Gradient Domain Manipulations: Overview

- (A) Per pixel
- (B) Corresponding gradients in two images
- (C) Corresponding gradients in multiple images
- (D) Combining gradients along seams

Photography Artifacts: Flash Hotspot

Ambient



Flash



**Flash
Hotspot**

Reflections due to Flash

Underexposed

Ambient



Reflections

Flash



Self-Reflections and Flash Hotspot

Ambient

Flash



Ambient



Flash



Result



Reflection Layer



Intensity Gradient Vectors in Flash and Ambient Images

Same gradient
vector direction

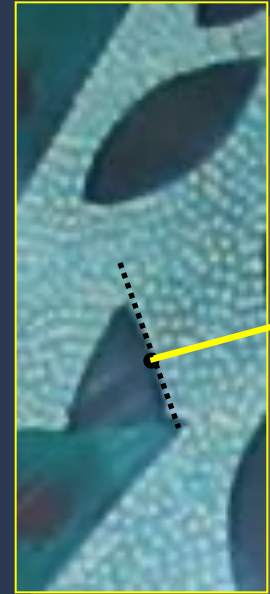
Flash Gradient Vector

Ambient Gradient Vector

Ambient

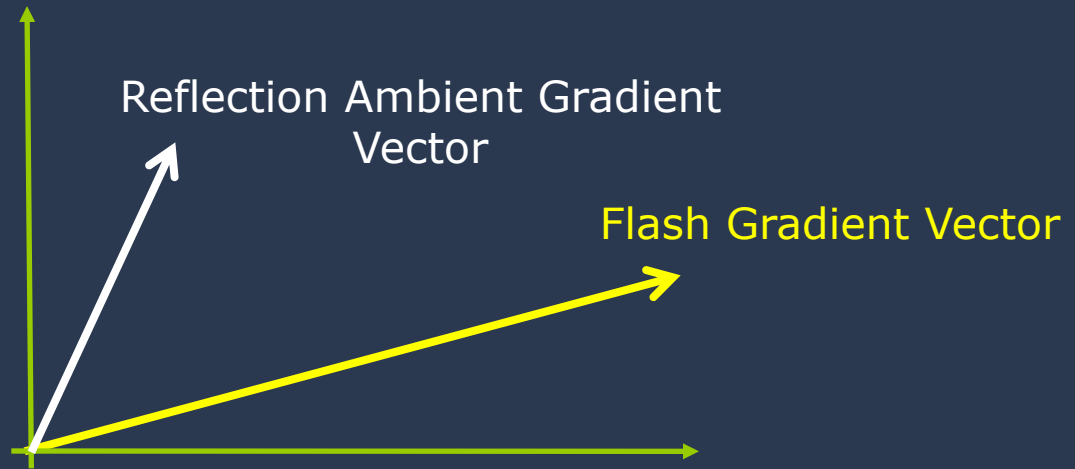


Flash



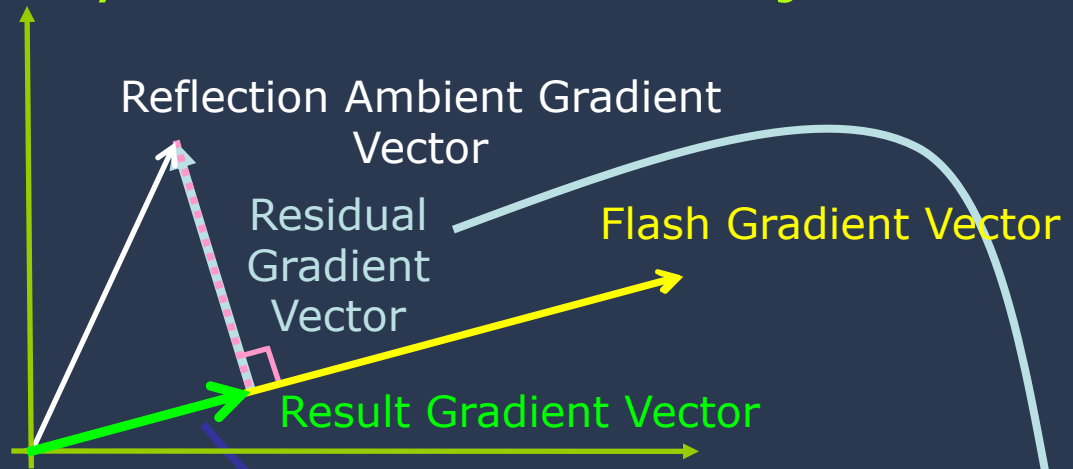
No reflections

Different gradient
vector directions



With reflections

Intensity Gradient Vector Projection



Ambient



Flash



Result



Residual



Ambient



Flash



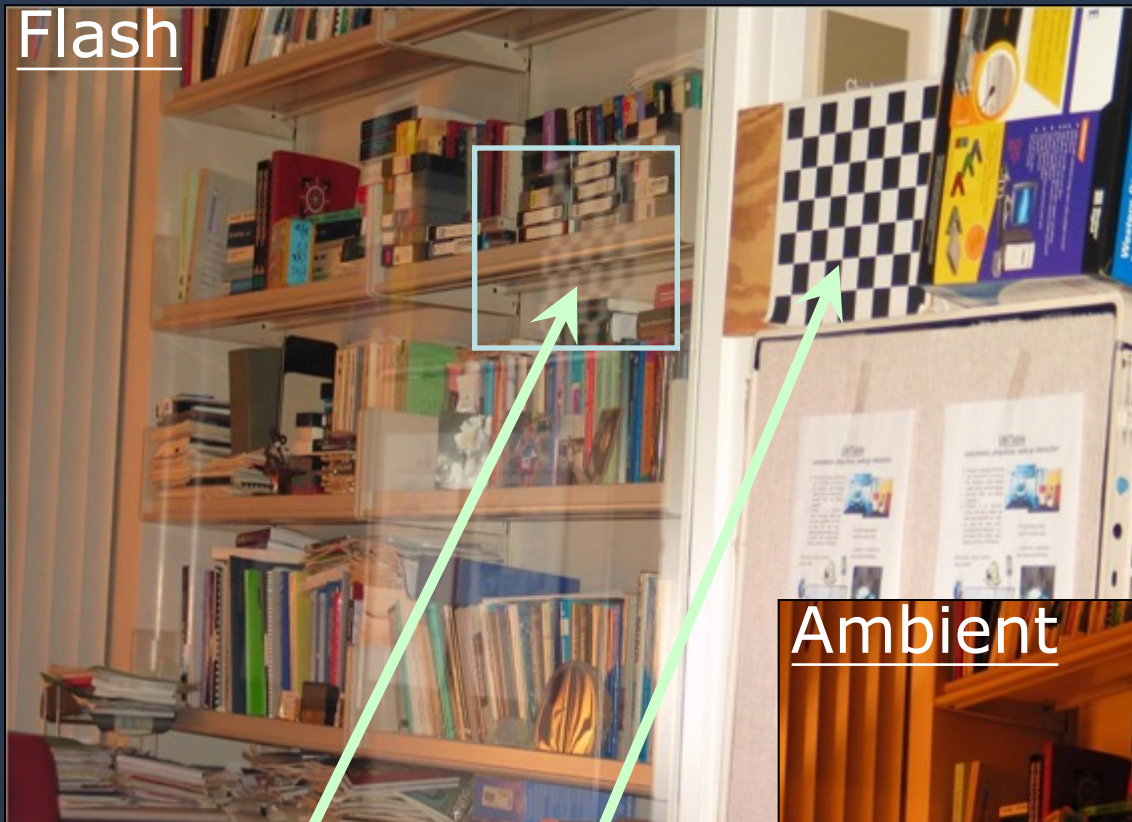
Projection =
Result



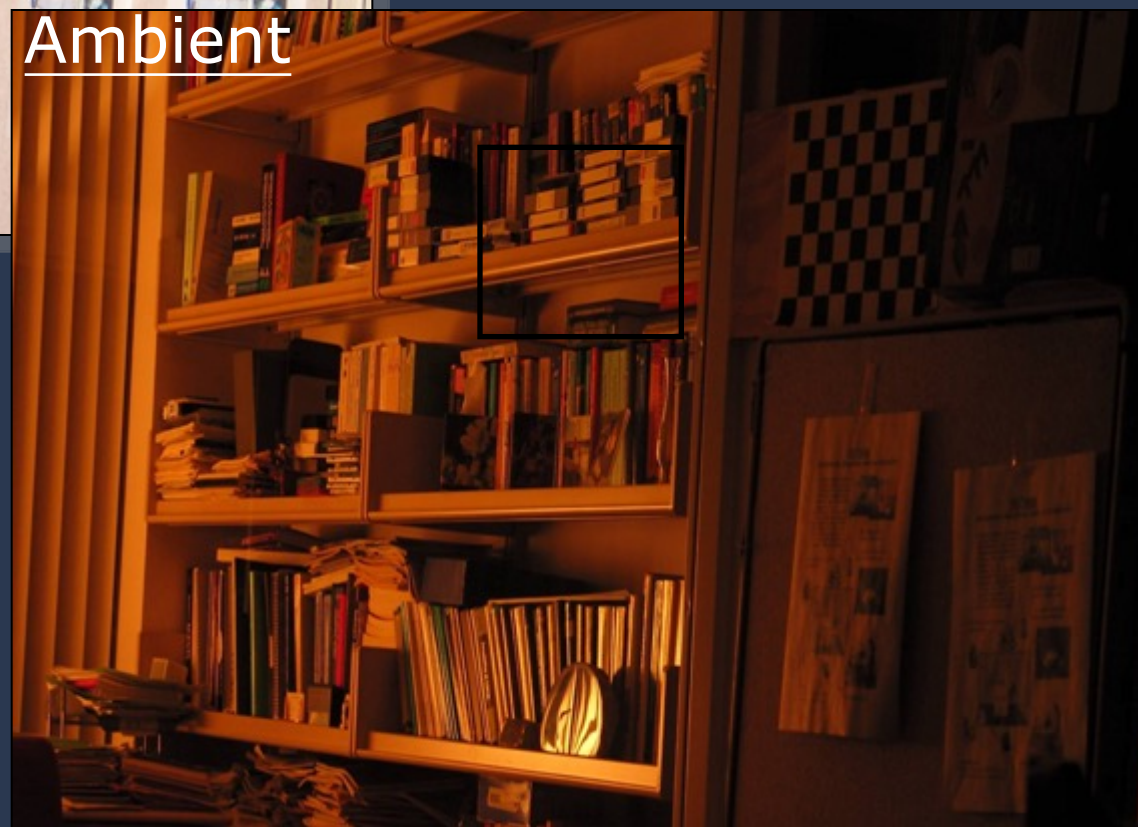
Residual =
Reflection Layer



Flash



Ambient



Forward Differences

Gradient Difference

Checkerboard

Residual X

Residual Y

Checkerboard

removed

Result X

Intensity Gradient

Vector Projection

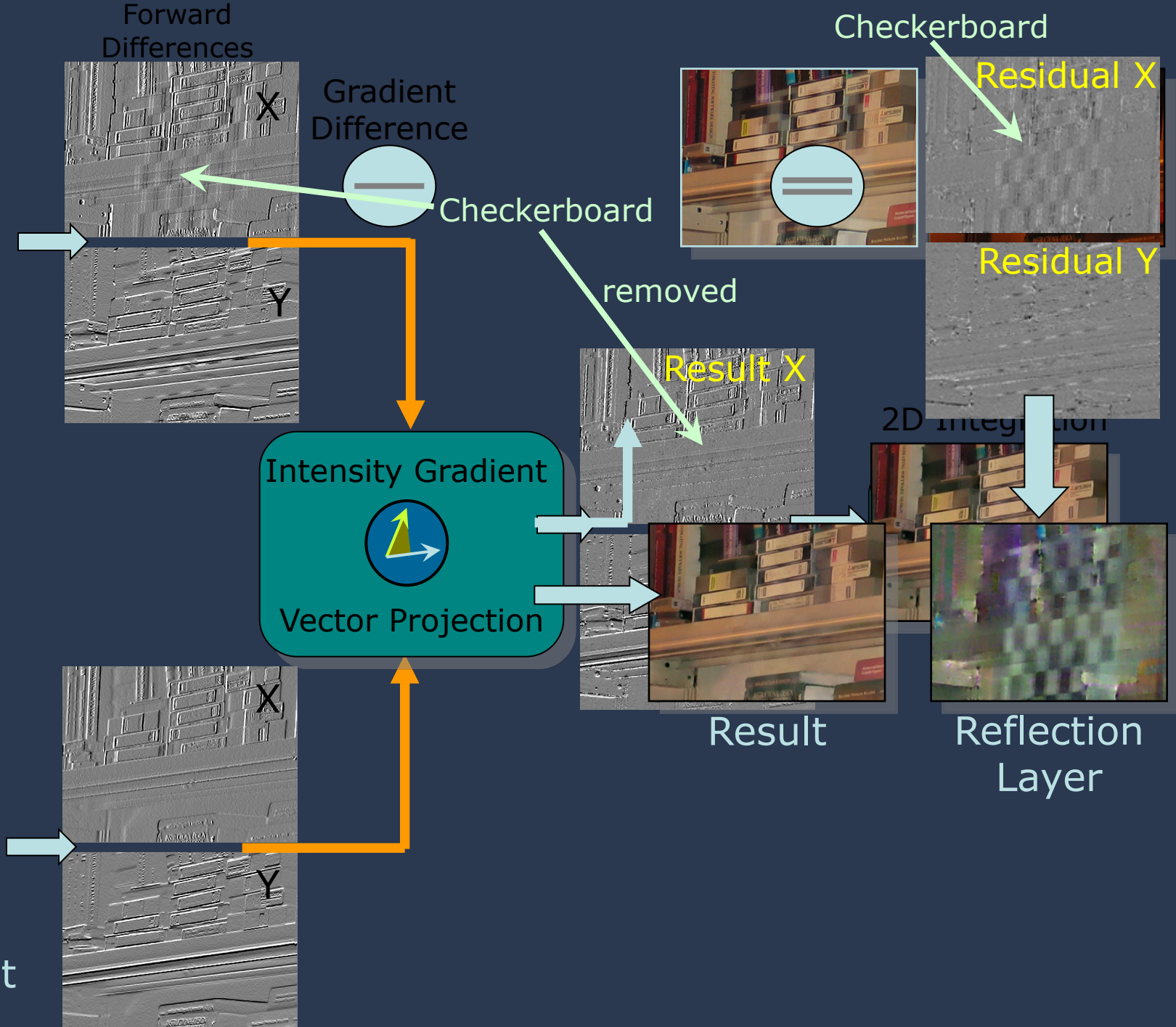
2D Integration

Result

Reflection Layer

Flash

Ambient



Poisson Image Editing

- Precise selection: tedious and unsatisfactory
- Alpha-Matting: powerful but involved
- **Seamless cloning**: loose selection but no seams?

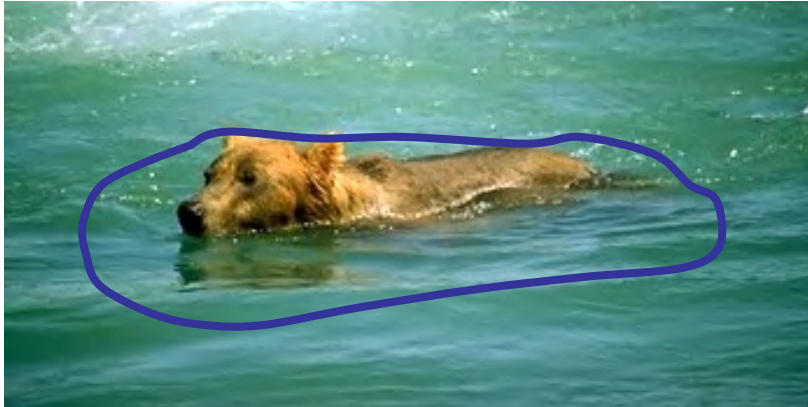


Conceal



Copy Background gradients (user strokes)

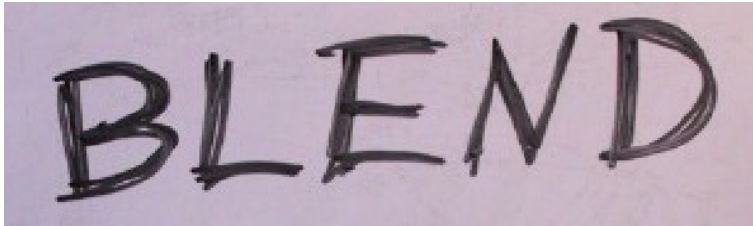
Compose



Source Images

Target Image

Transparent Cloning



$$\mathbf{v} = \frac{\nabla f^* + \nabla g}{\sqrt{w_1^2 + w_2^2}}$$

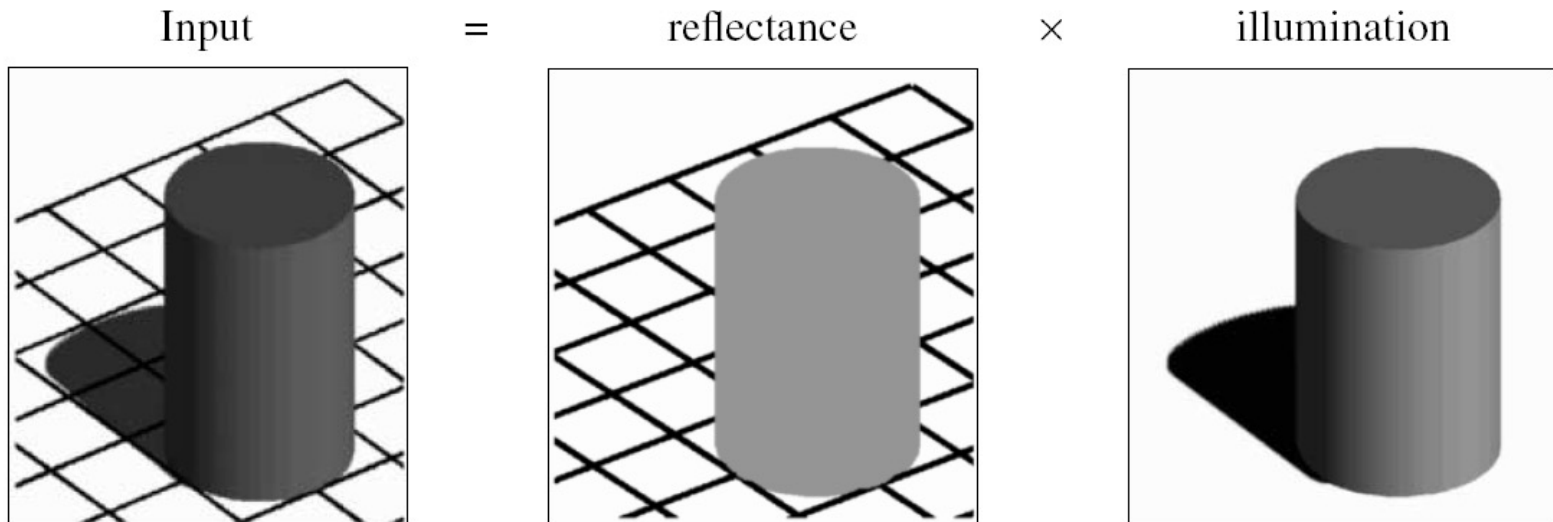
Largest variation from source and destination at each point

Gradient Domain Manipulations: Overview

- (A) Per pixel
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- (D) Combining gradients along seams

Intrinsic images

- $I = L * R$
- L = illumination image
- R = reflectance image



Intrinsic images

- Use multiple images under different illumination
- Assumption
 - Illumination image gradients = Laplacian PDF
 - Under Laplacian PDF, Median = ML estimator
- At each pixel, take **Median of gradients across images**
- Integrate to remove shadows



frame 1



frame 11



ML reflectance

Shadow free
Intrinsic Image



$$\text{Result} = \text{Illumination Image} * (\text{Label in Intrinsic Image})$$

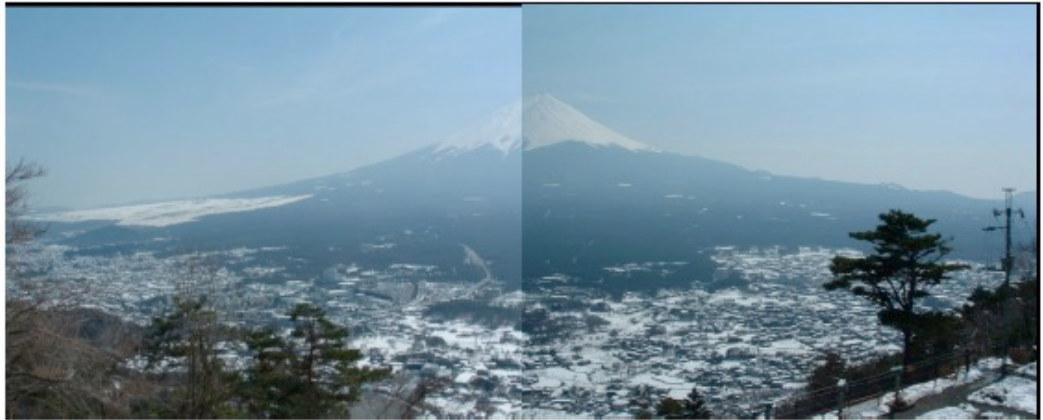
Gradient Domain Manipulations: Overview

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Seamless Image Stitching



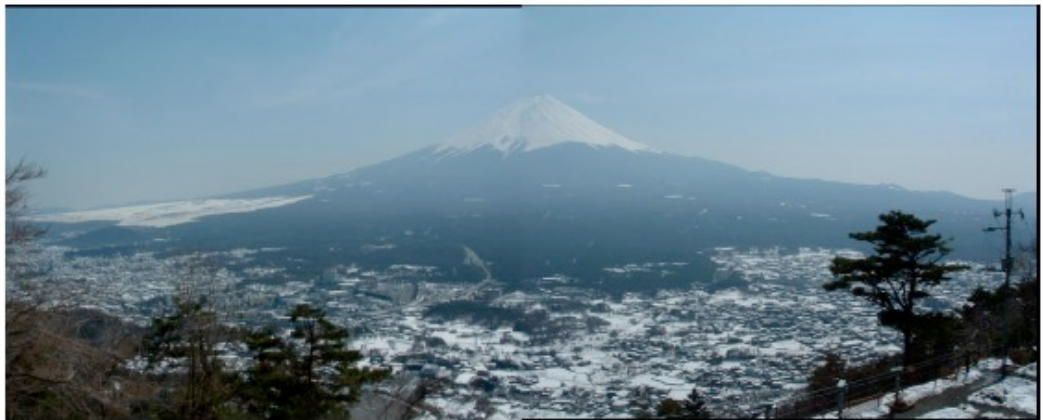
Input image I_1



Pasting of I_1 and I_2



Input image I_2



Stitching result

Anat Levin, Assaf Zomet, Shmuel Peleg and Yair Weiss, "Seamless Image Stitching in the Gradient Domain", ECCV 2004