

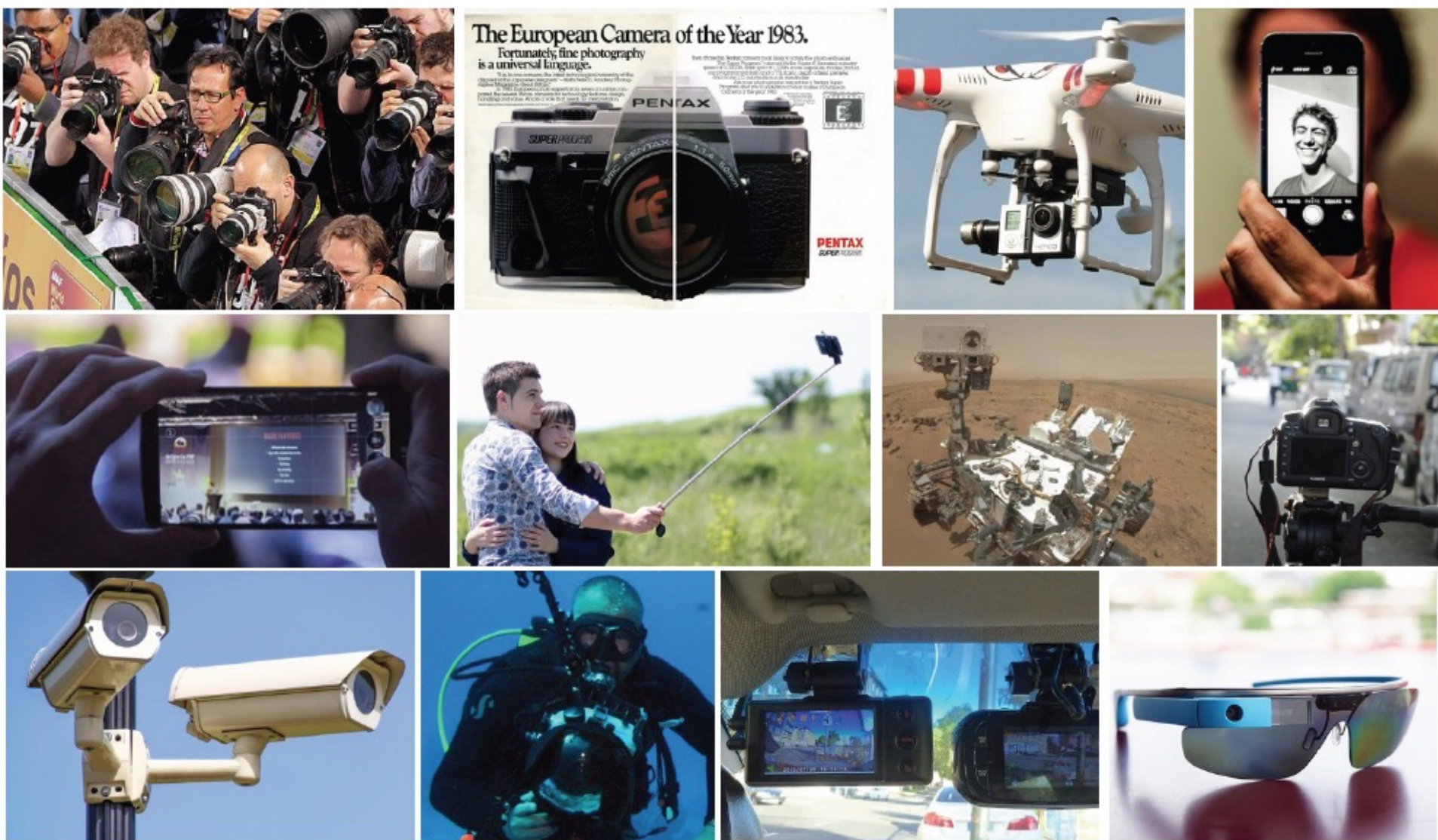
Computational Photography

Digital Visual Effects

Yung-Yu Chuang

*with slides by Fredo Durand, Ramesh Raskar, Sylvain Paris, Soonmin Bae, Amit Agrawal,
Ramesh Raskar*

There are a lot of cameras around us



Photography in the mobile era

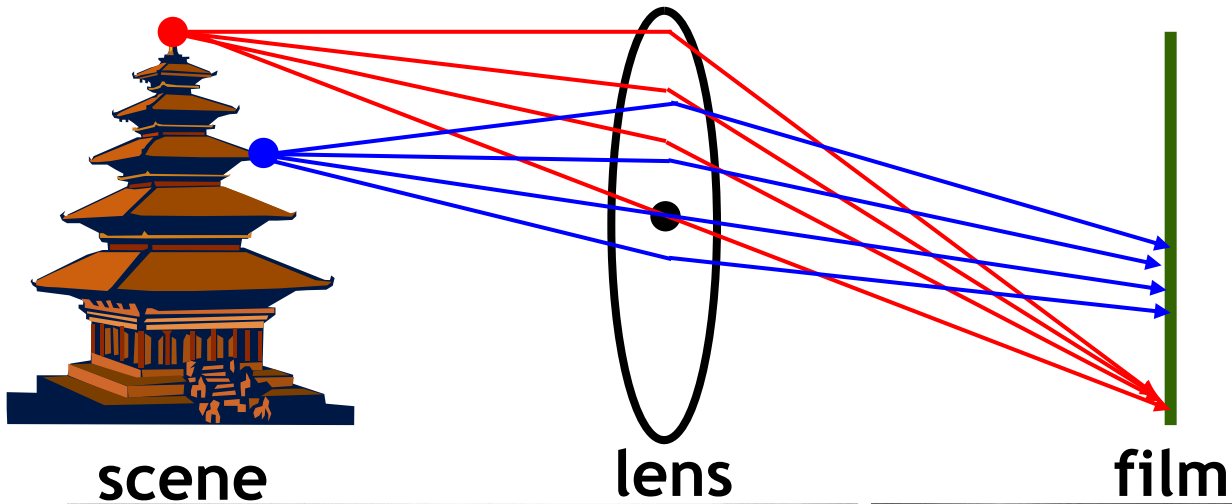


2005

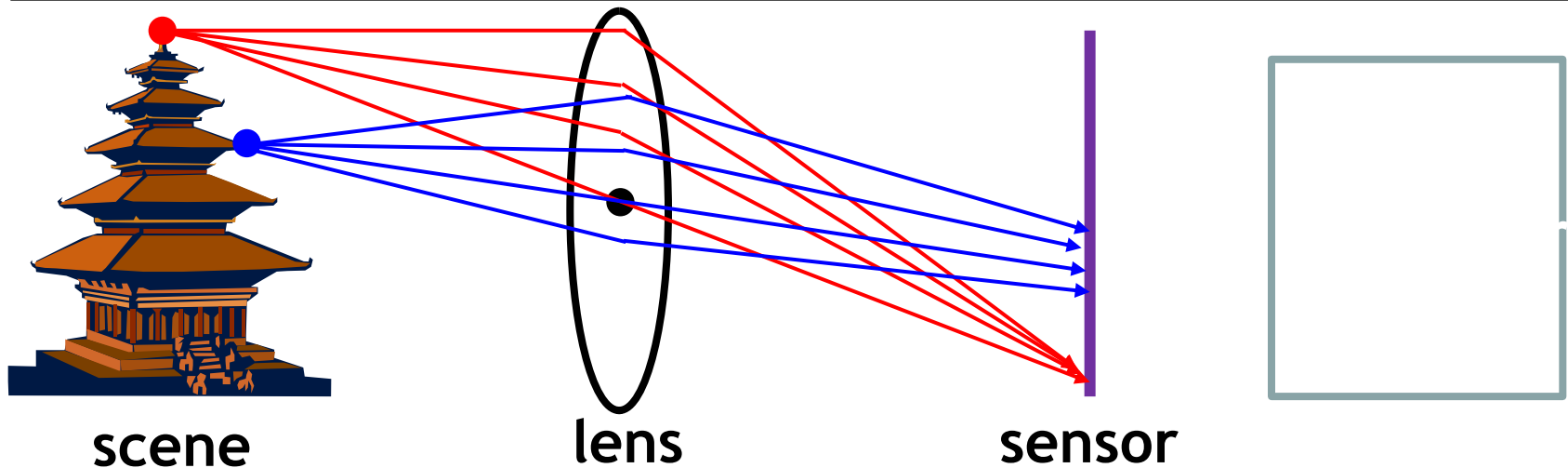


2013

Cameras



Digital cameras



- Cameras can only provide incomplete and imperfect records of the moments at the best.
- Computational photography: photographs are results of computation, rather than simply sensing.

Computational photography

wikipedia:

Computational photography refers broadly to computational imaging techniques that enhance or extend the capabilities of digital photography. The output of these techniques is an ordinary photograph, but one that could not have been taken by a traditional camera.

What is computational photography

- Convergence of image processing, computer vision, computer graphics and photography
- Digital photography:
 - Simply mimics traditional sensors and recording by digital technology
 - Involves only simple image processing
- Computational photography
 - More elaborate image manipulation, more computation
 - New types of media (panorama, 3D, etc.)
 - Camera design that take computation into account

Scope

- We can't yet set its precise definition. The following are scopes of what researchers are exploring in this field.
 - Record a richer visual experience
 - Overcome long-standing limitations of conventional cameras
 - Enable new classes of visual signal
 - Enable synthesis impossible photos

Computational photography



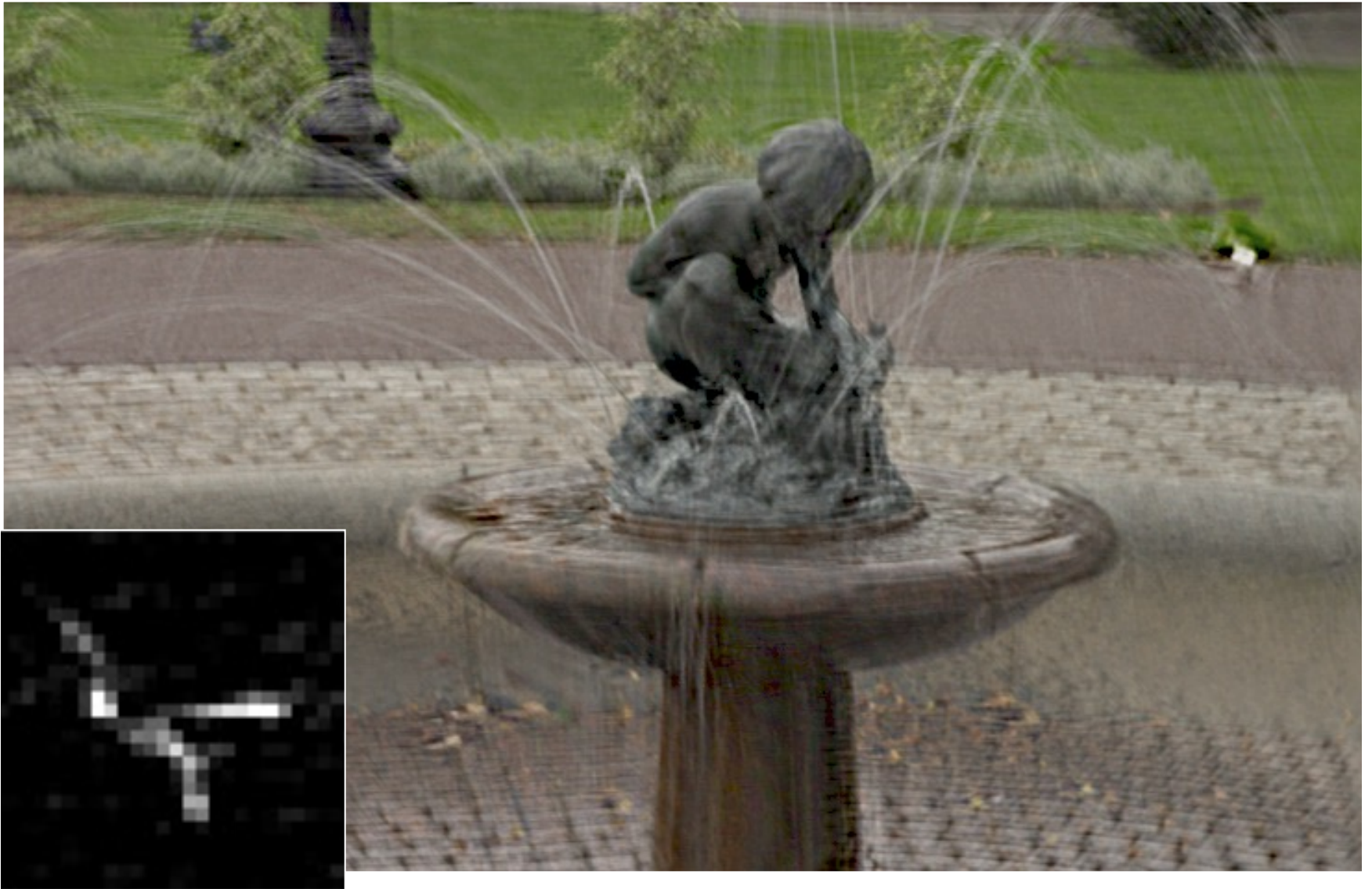
Imperfect photographer



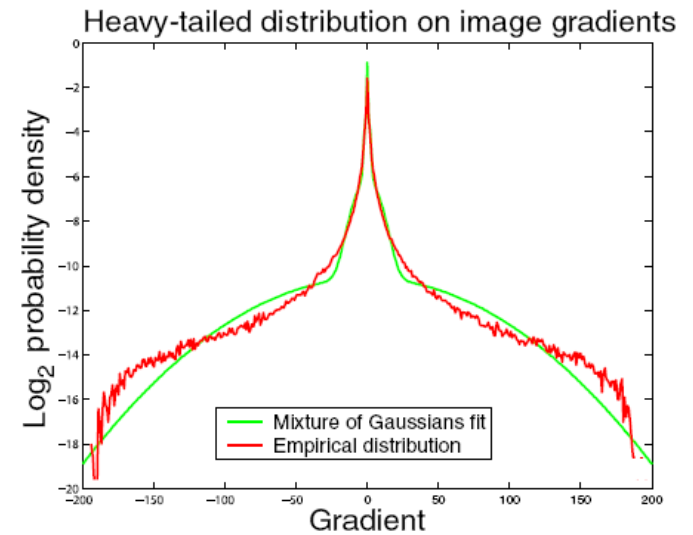
Deblurring



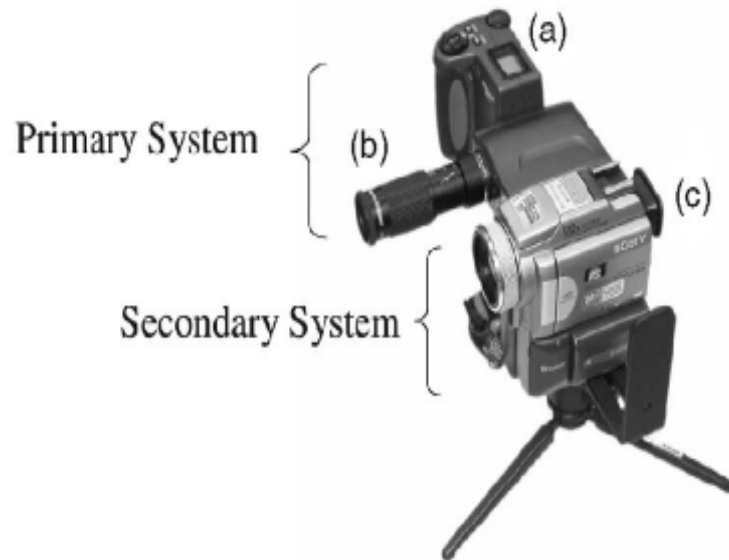
Deblurring



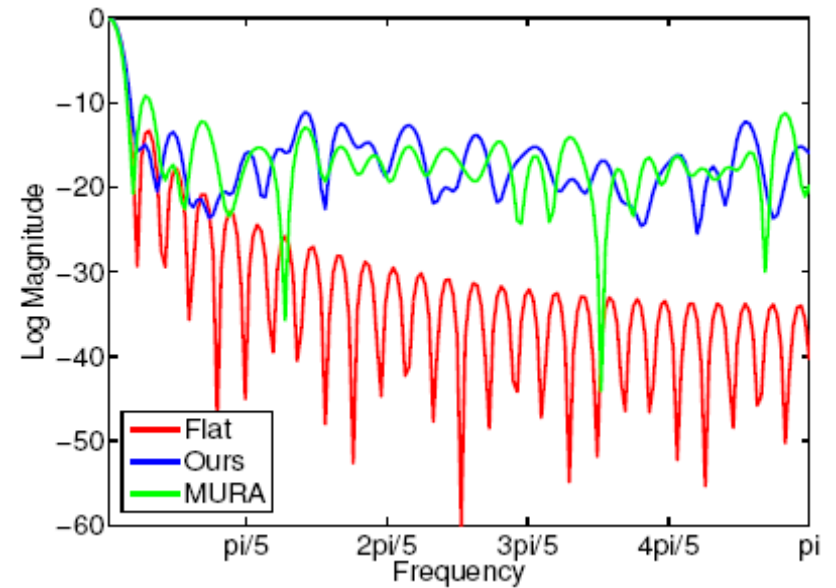
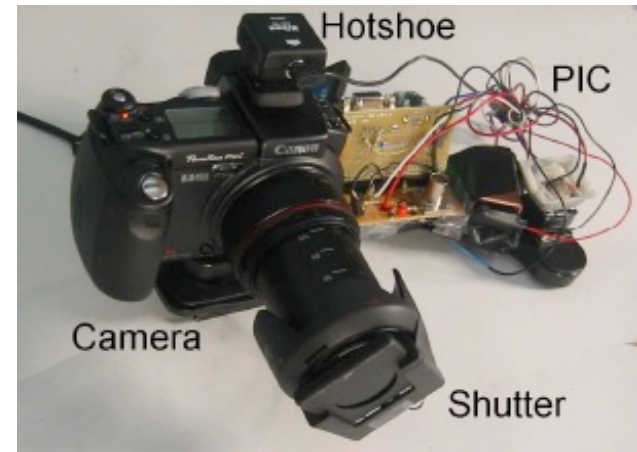
Deblurring



Motion-Based Motion Deblurring



Deblurring



Video stabilization



original video



stabilized video

Imperfect scene

scene

camera

photographer



Flash photography

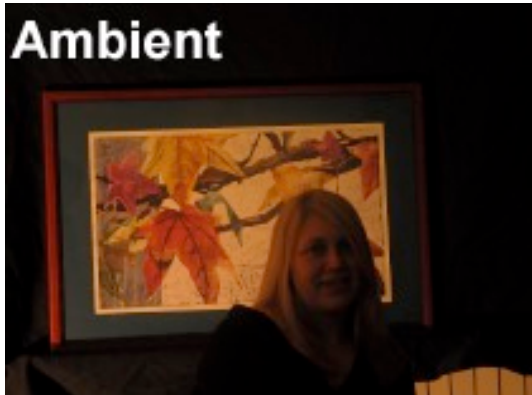


result

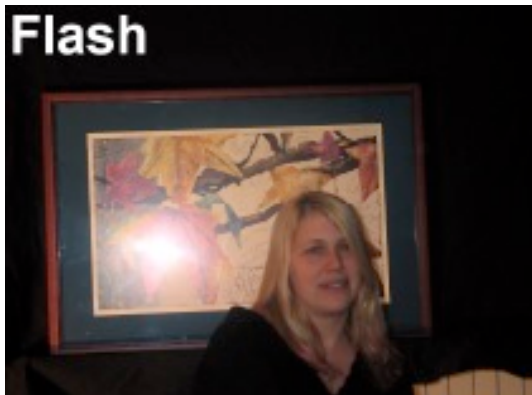


Flash photography

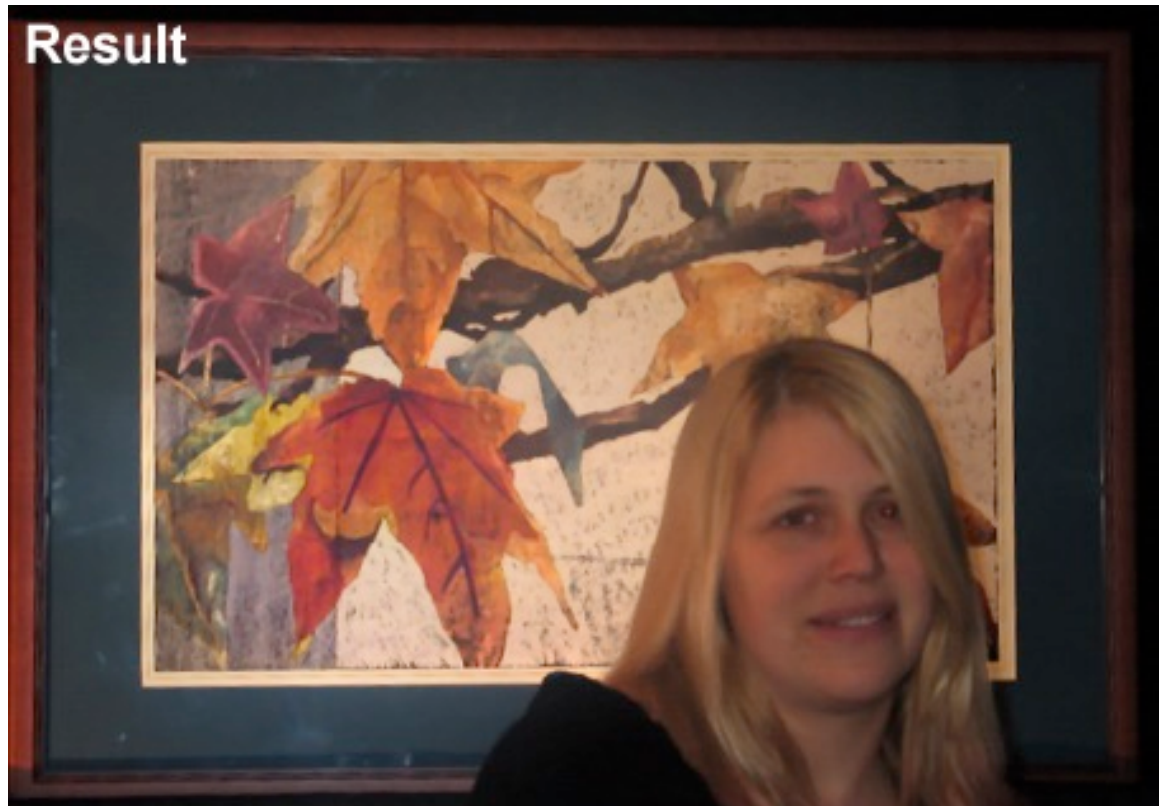
Ambient



Flash



Result



Flash photography

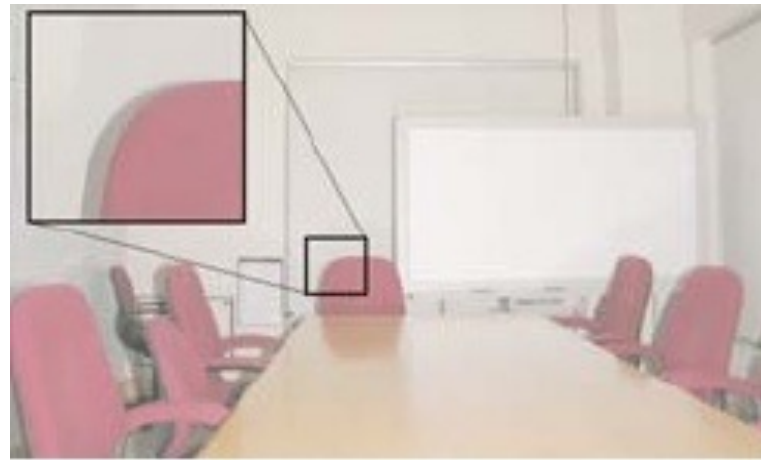
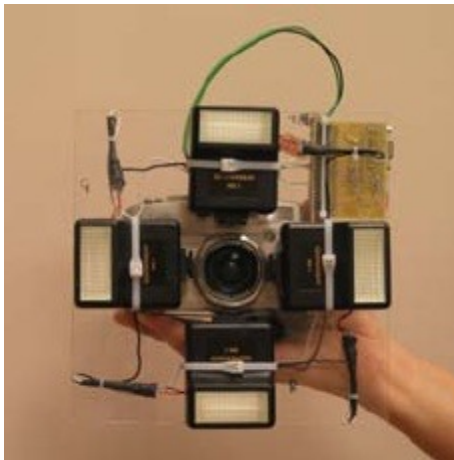
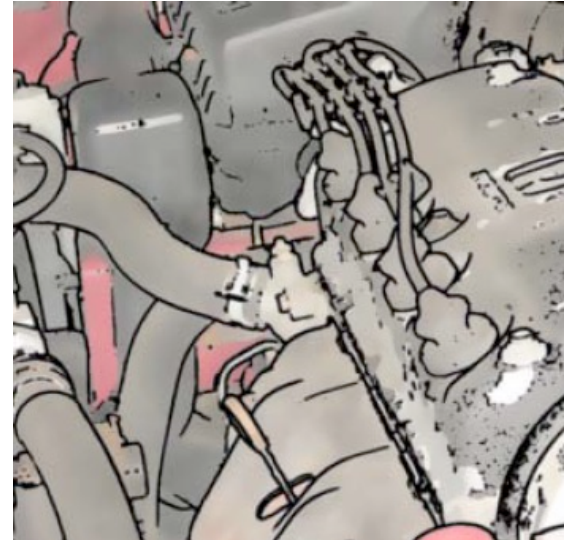


Image Inpainting

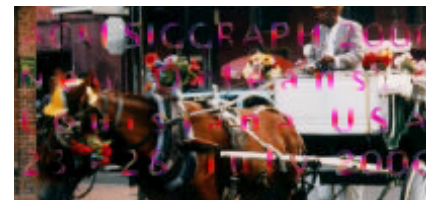


Image Inpainting

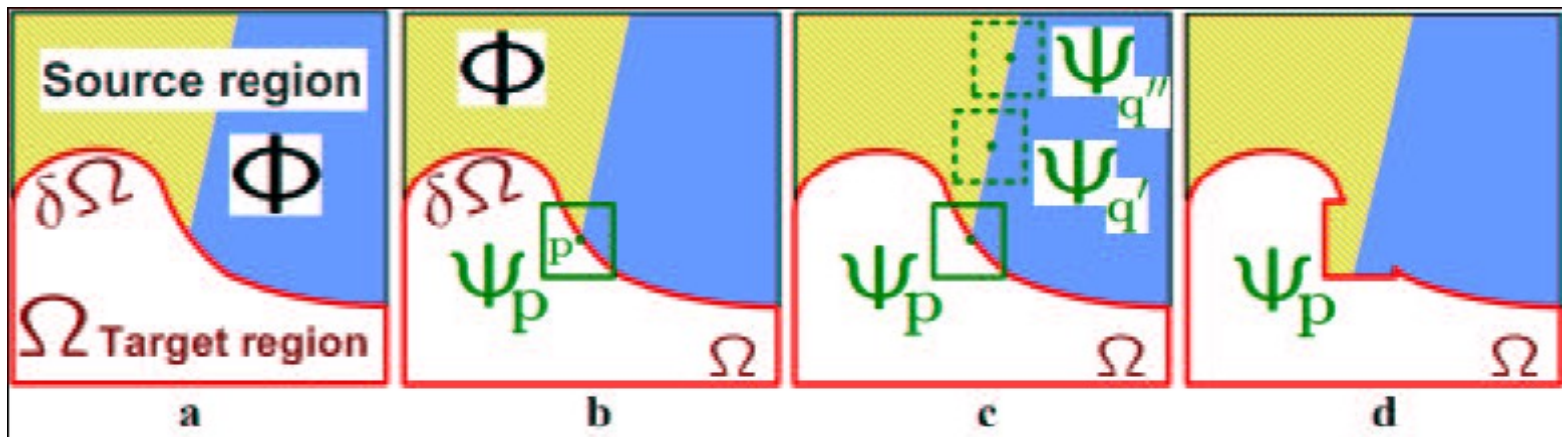
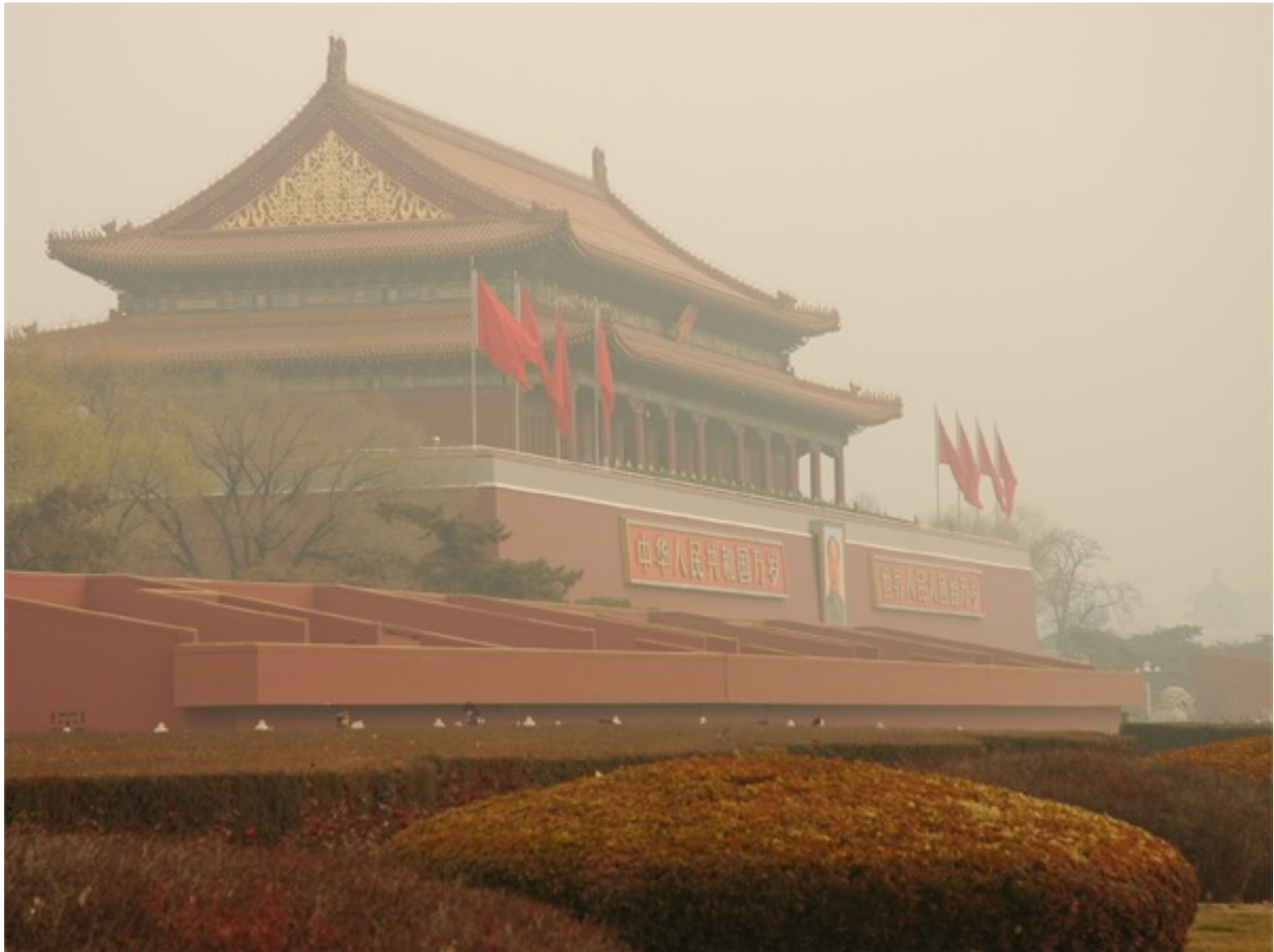


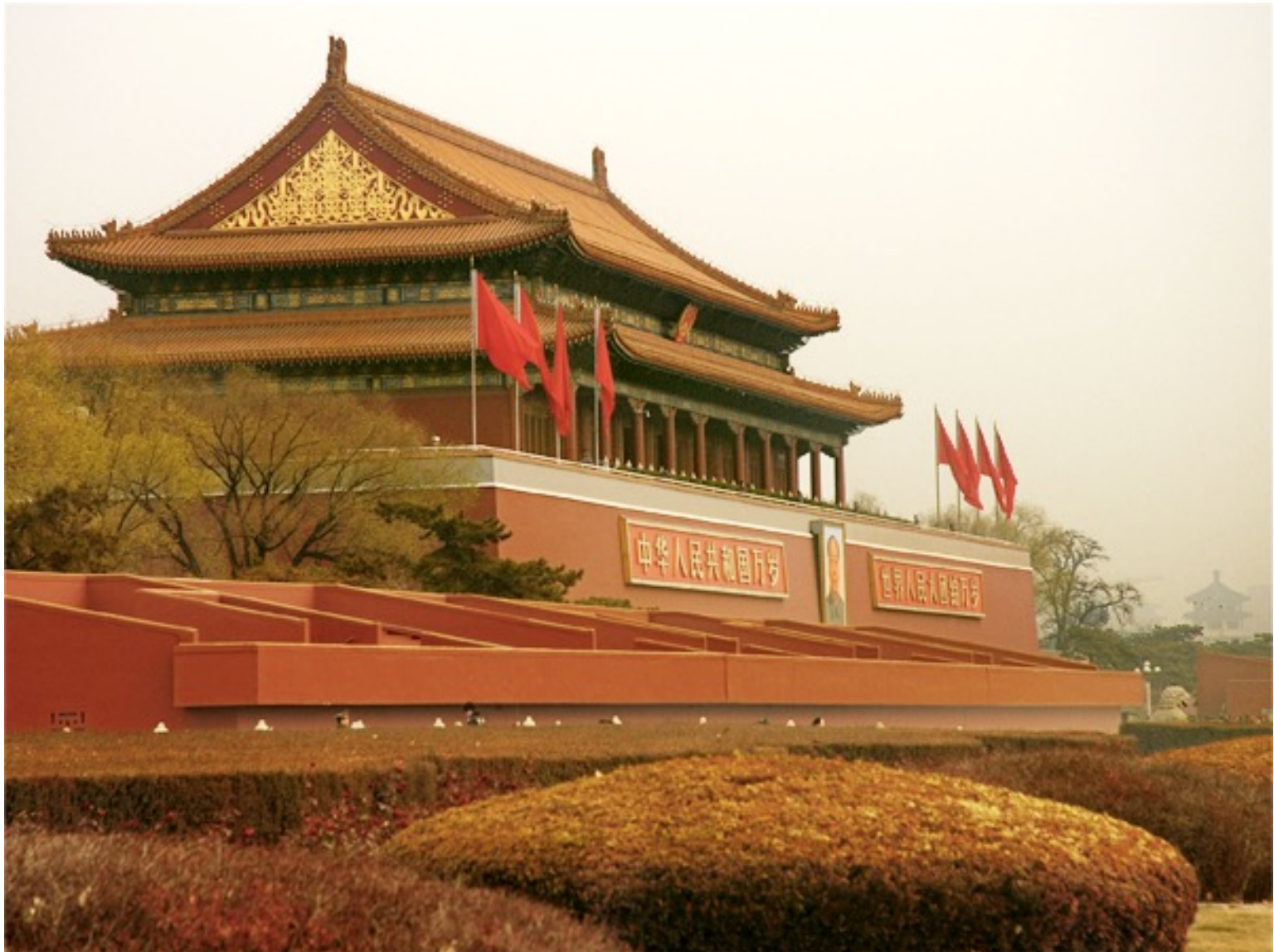
Image Inpainting



Dehazing



Dehazing



Sky replacement

Input image



Sky replacement

Input image



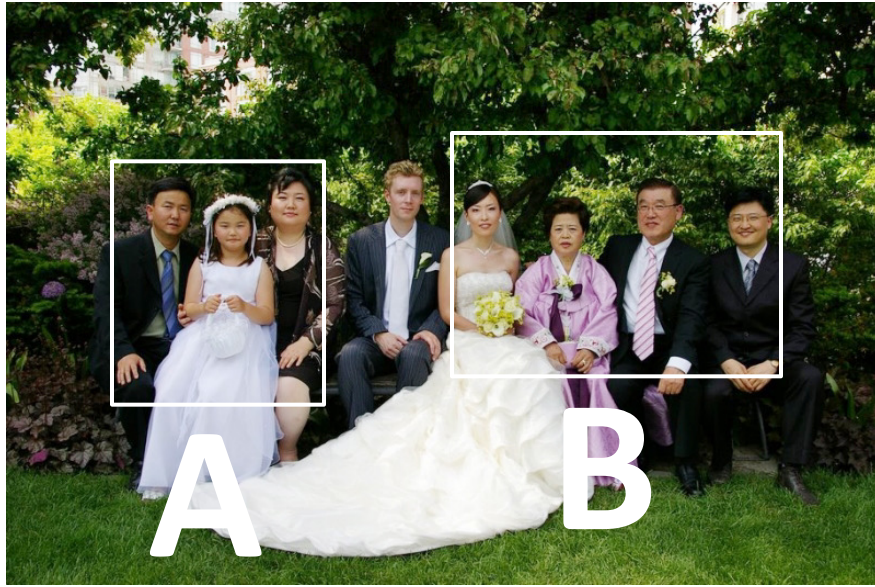
Inpainting



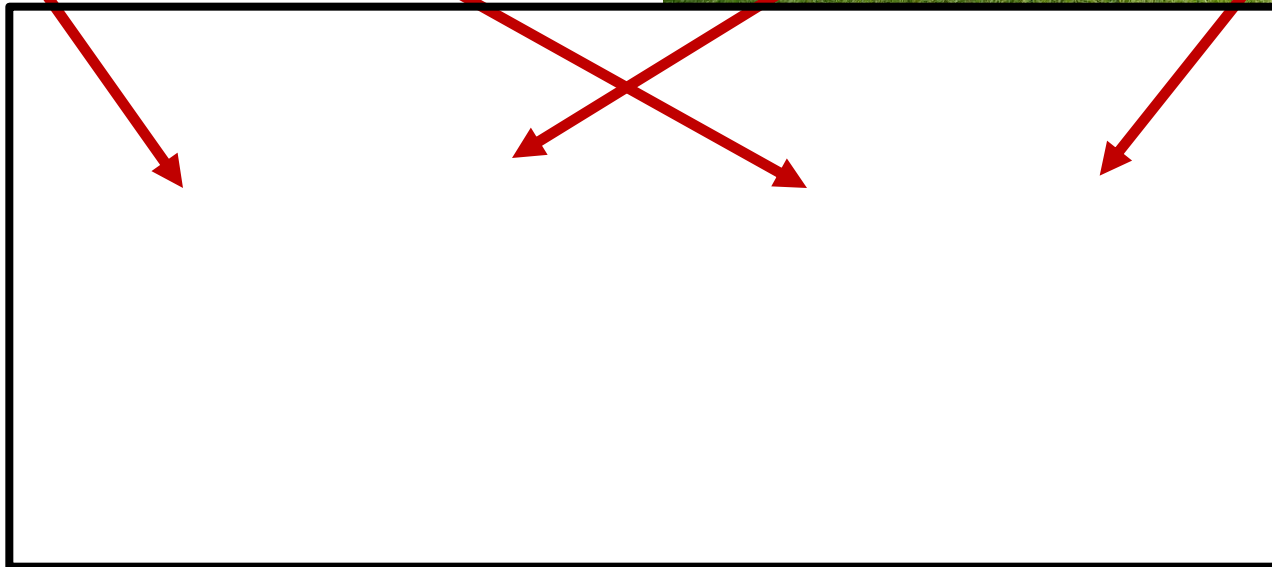
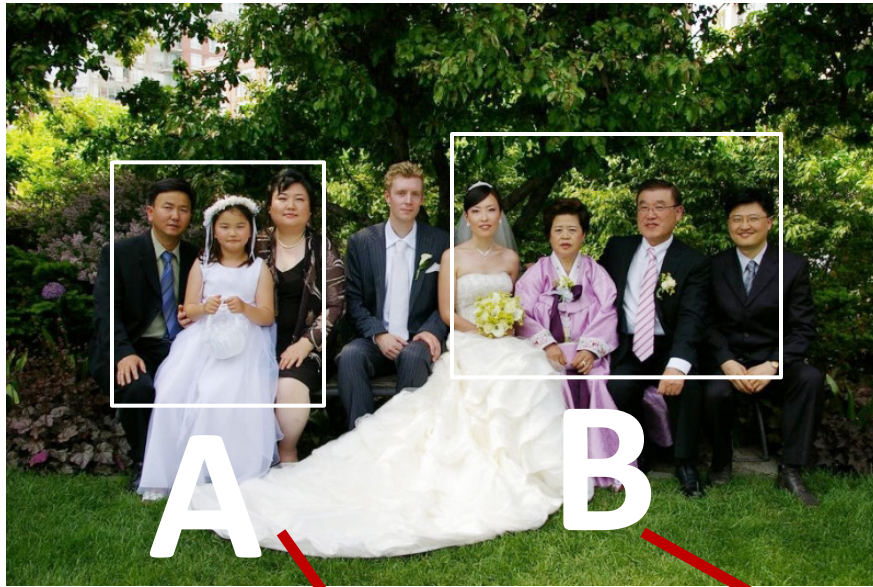
Re-composition



Re-composition



Re-composition



Re-composition



Imperfect cameras



The problems with cameras



Noise



real scene



image

Resolution



real scene



image

Dynamic range

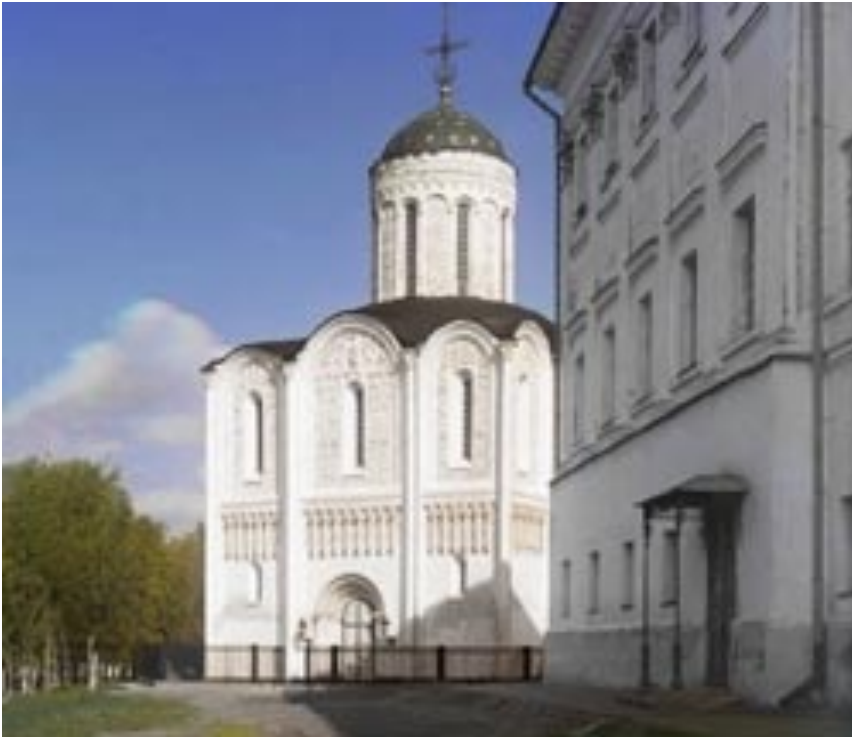


real scene



image

Color



real scene

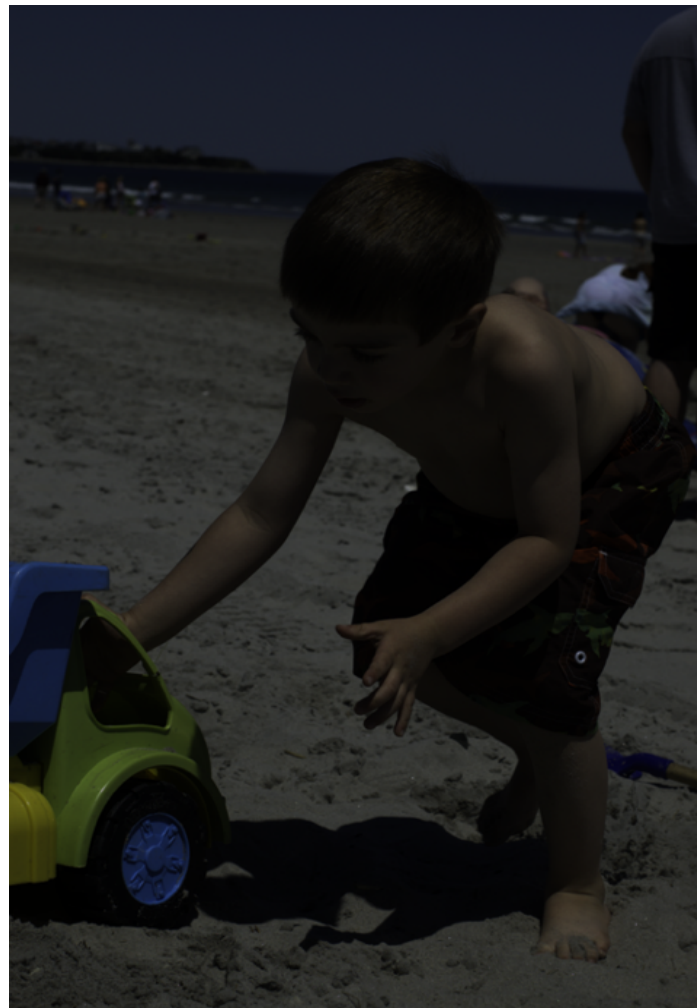


image

Non-linear response



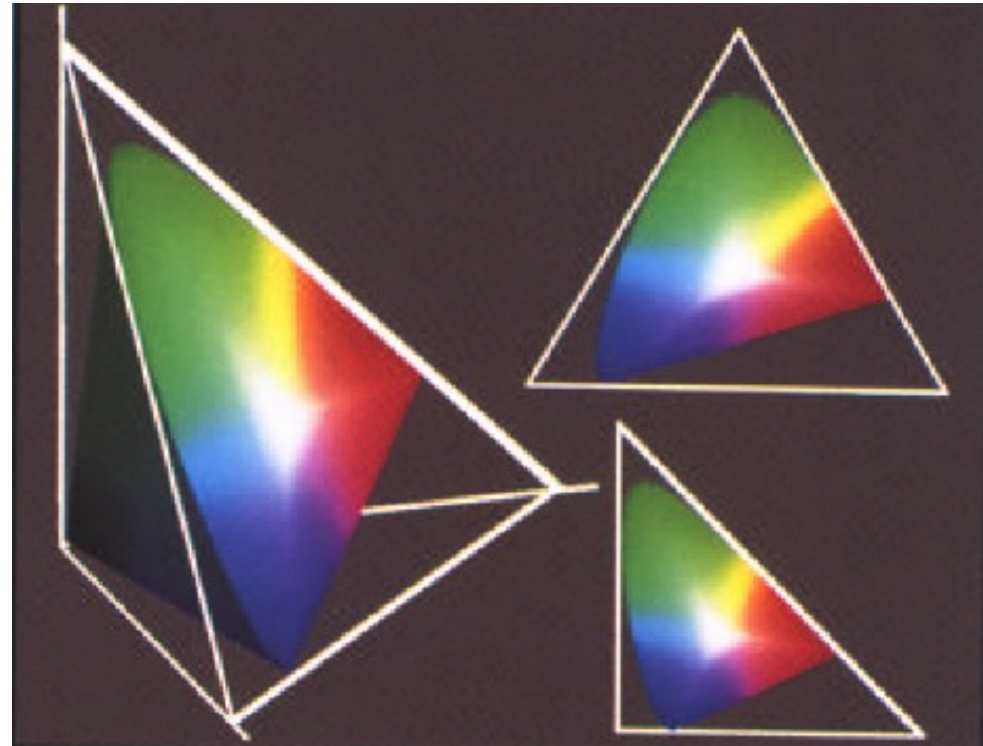
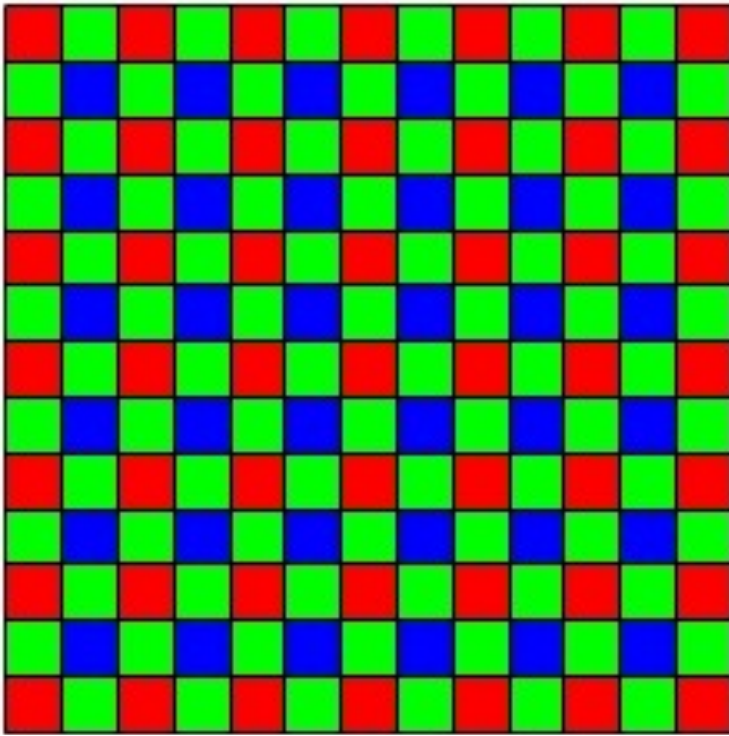
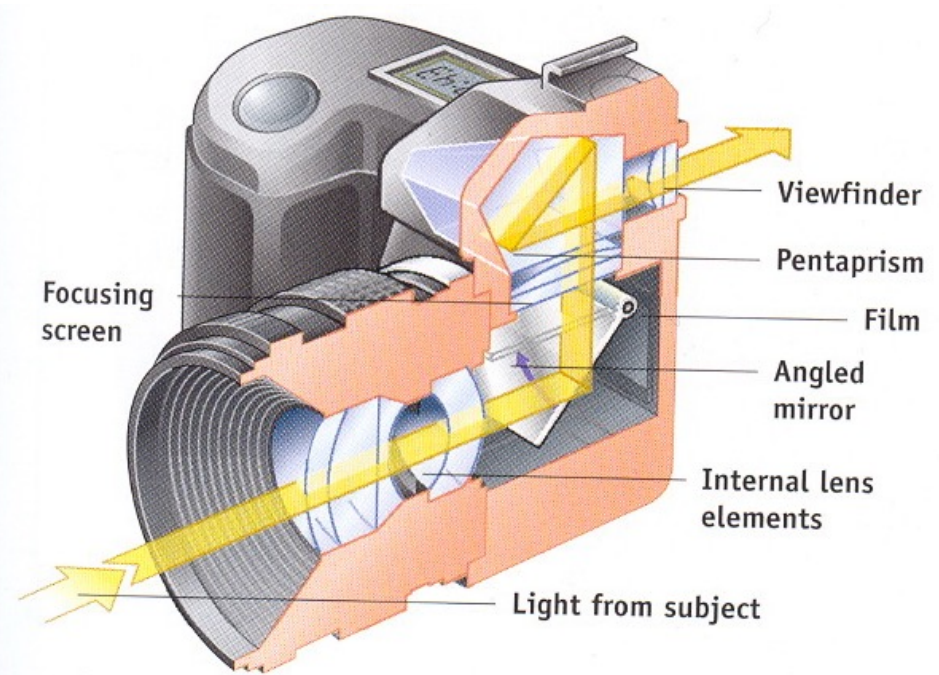
real scene



image

Cameras

- Image formation
- Color and color perception



HDR



Exposure blending

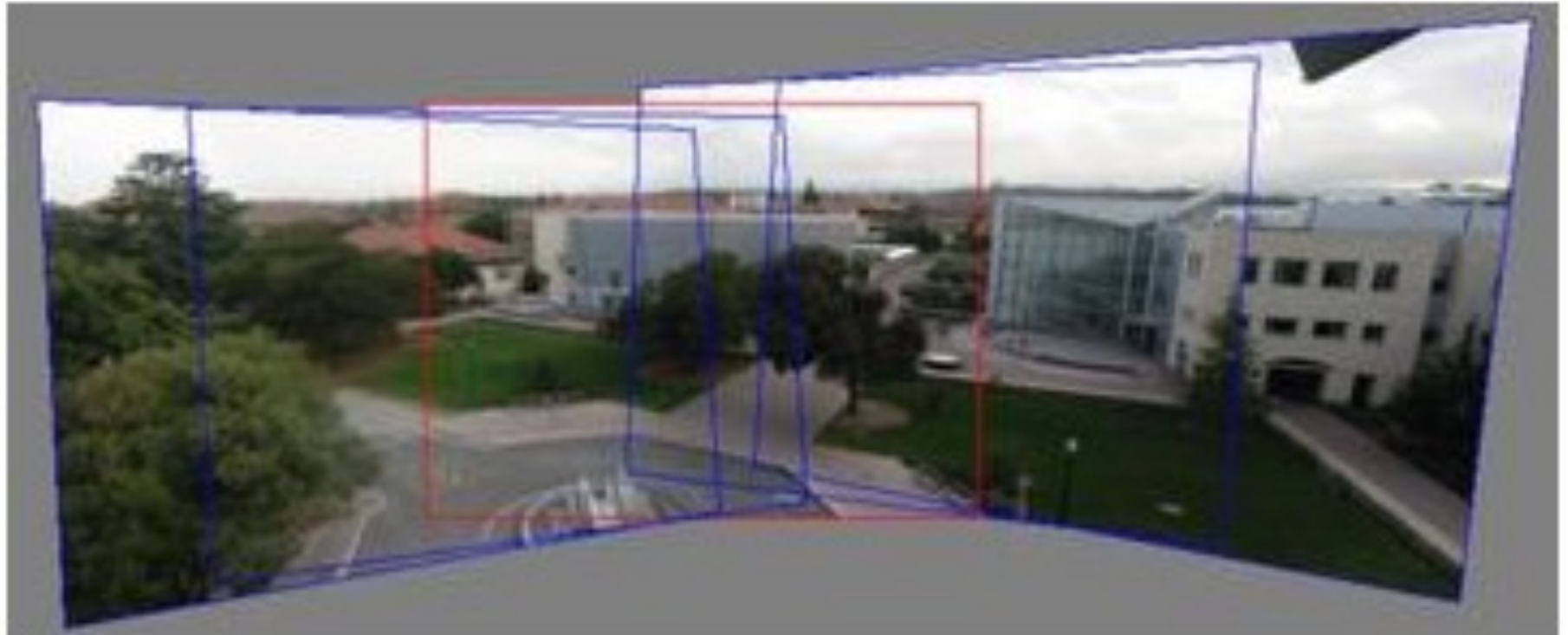


Input sequence



Our composite result

Stitching



Retargeting



Retargeting



scaling



content-aware resizing

Vignette calibration



Vignette calibration



Vignette calibration



De-noising



Super-resolution



original

Super-resolution



bicubic

Super-resolution



ICCV 2010

Computational camera

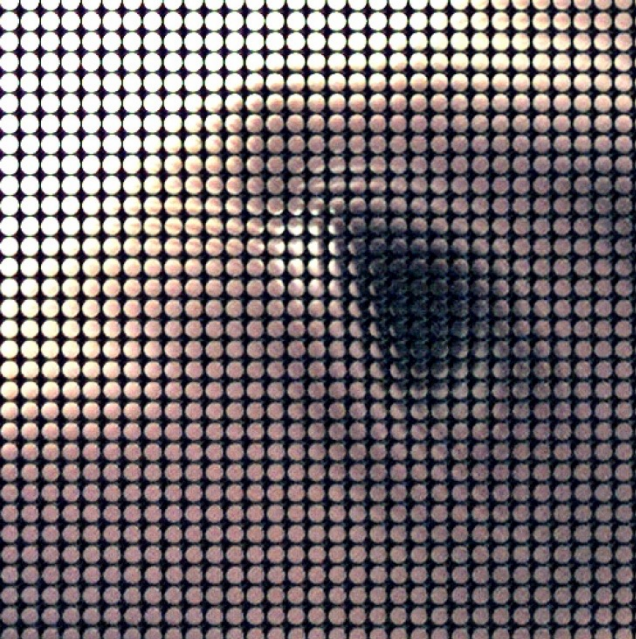
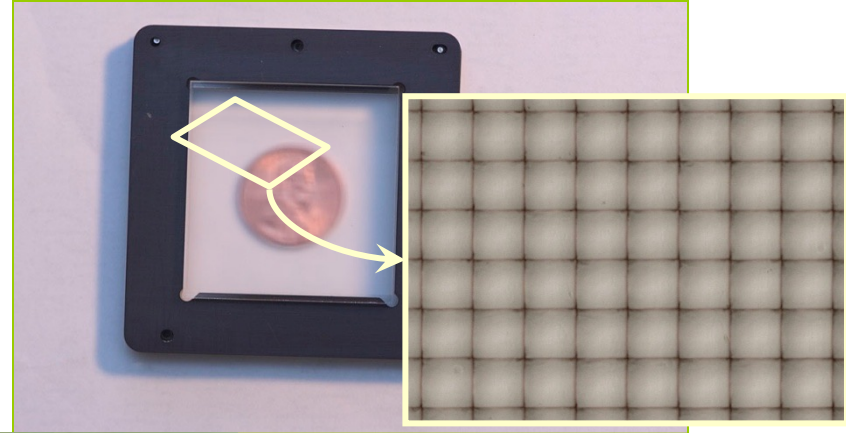
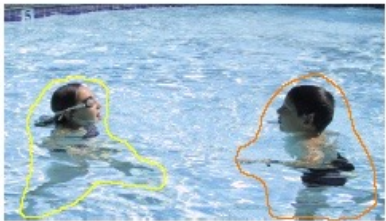


Image manipulation

- Gradient image manipulation



sources/destinations



cloning



seamless cloning

Image manipulation

- Non-parametric image synthesis, inpainting, analogies



input images

quilting results



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A

A'

B

B'

Figure 1 An image analogy. Our problem is to compute a new “analogous” image B' that relates to B in “the same way” as A' relates to A . Here, A , A' , and B are inputs to our algorithm, and B' is the output. The full-size images are shown in Figures 10 and 11.

Lazy snapping



Grab Cut



Tools

- Graph cuts,
 - Segmentation and mosaicing
- Gradient domain operations,
 - Tone mapping, fusion and matting
- Bilateral filters,
 - Denoising, image enhancement
- Deep learning