

# Faces and Image-Based Lighting

Digital Visual Effects, Spring 2009

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*with slides by Richard Szeliski, Steve Seitz, Alex Efros, Li-Yi Wei and Paul Debevec*

## Outline

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- Image-based lighting
- 3D acquisition for faces
- Statistical methods (with application to face super-resolution)
- 3D Face models from single images
- Image-based faces
- Relighting for faces

## Rendering

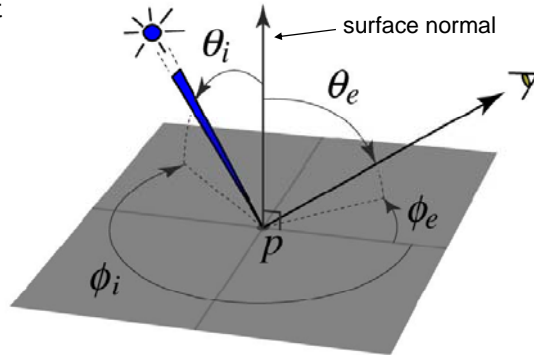
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- Rendering is a function of geometry, reflectance, lighting and viewing.
- To synthesize CGI into real scene, we have to match the above four factors.
- Viewing can be obtained from *calibration* or *structure from motion*.
- Geometry can be captured using *3D photography* or made by hands.
- How to capture lighting and reflectance?

## Image-based lighting

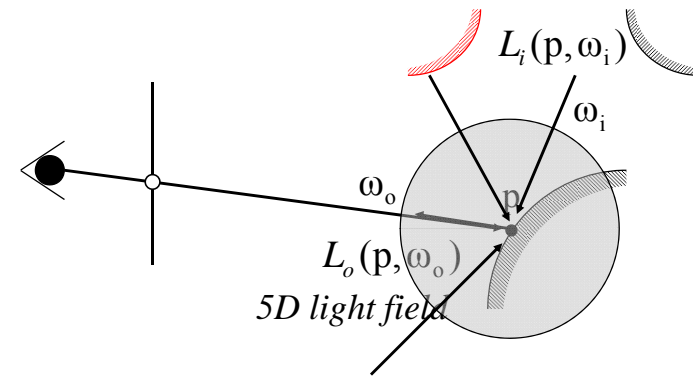
## Reflectance

- The Bidirectional Reflection Distribution Function
  - Given an incoming ray  $(\theta_i, \phi_i)$  and outgoing ray  $(\theta_e, \phi_e)$  what proportion of the incoming light is reflected along out



Answer given by the BRDF:  $\rho(\theta_i, \phi_i, \theta_e, \phi_e)$

## Rendering equation



$$L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{s^2} \rho(p, \omega_o, \omega_i) L_i(p, \omega_i) |\cos \theta_i| d\omega_i$$

## Complex illumination

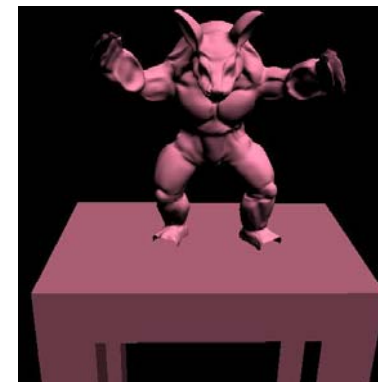
$$L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{s^2} f(p, \omega_o, \omega_i) L_i(p, \omega_i) |\cos \theta_i| d\omega_i$$

$$B(p, \omega_o) = \int_{s^2} f(p, \omega_o, \omega_i) L_d(p, \omega_i) |\cos \theta_i| d\omega_i$$

↑  
 reflectance    lighting

## Point lights

Classically, rendering is performed assuming point light sources

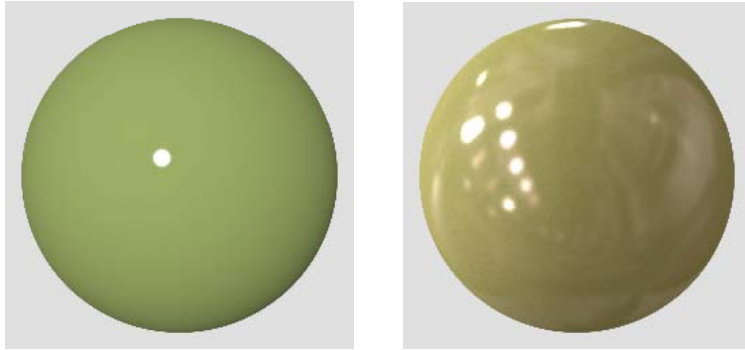


directional source

## Natural illumination

DigiVFX

People perceive materials more easily under natural illumination than simplified illumination.



Images courtesy Ron Dror and Ted Adelson

## Natural illumination

DigiVFX

Rendering with natural illumination is more expensive compared to using simplified illumination



directional source

natural illumination

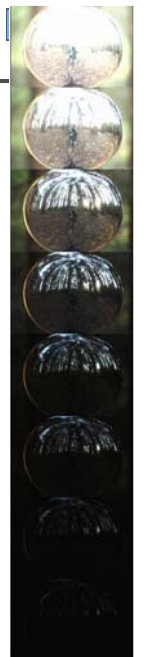
## Environment maps

DigiVFX



Miller and Hoffman, 1984

## Acquiring the Light Probe



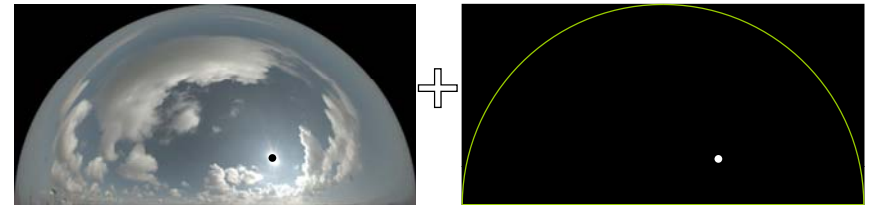
# HDRI Sky Probe

DigiVFX

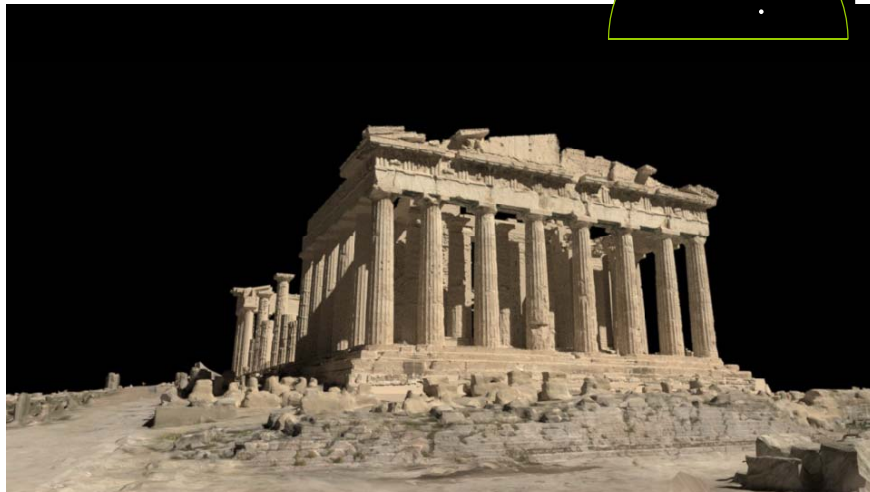
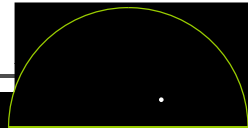


# Clipped Sky + Sun Source

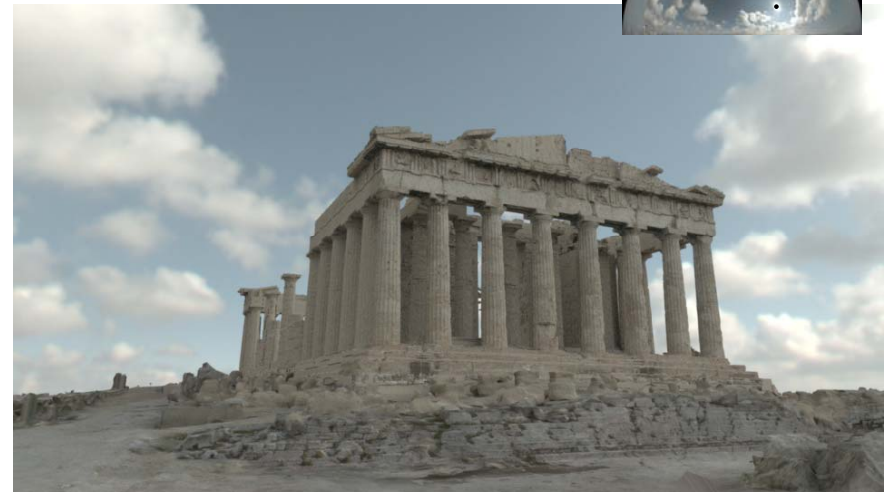
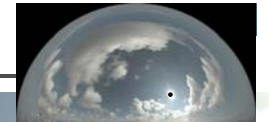
DigiVFX



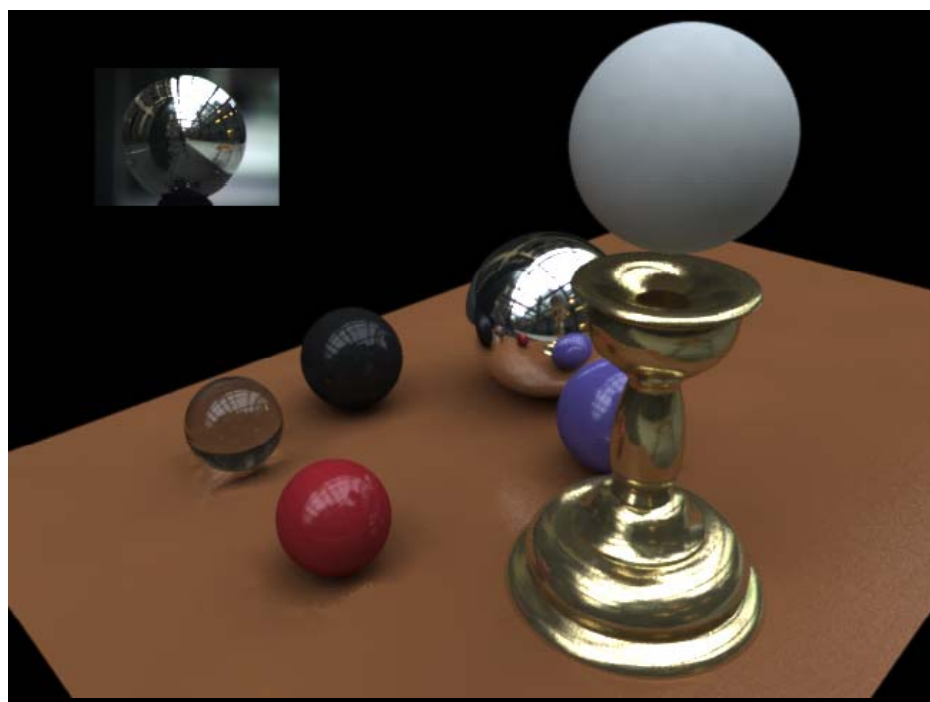
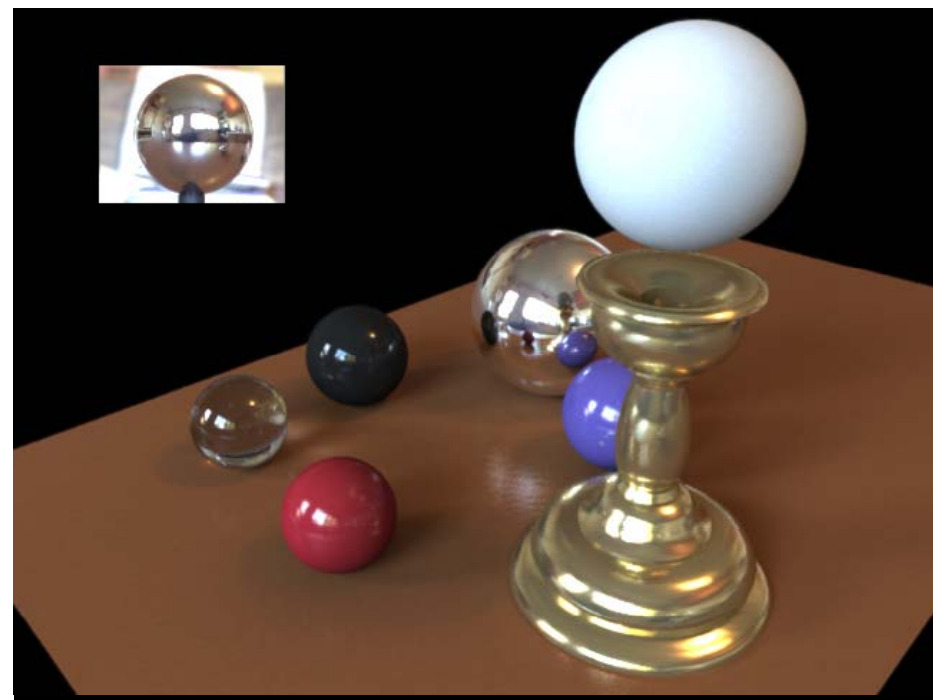
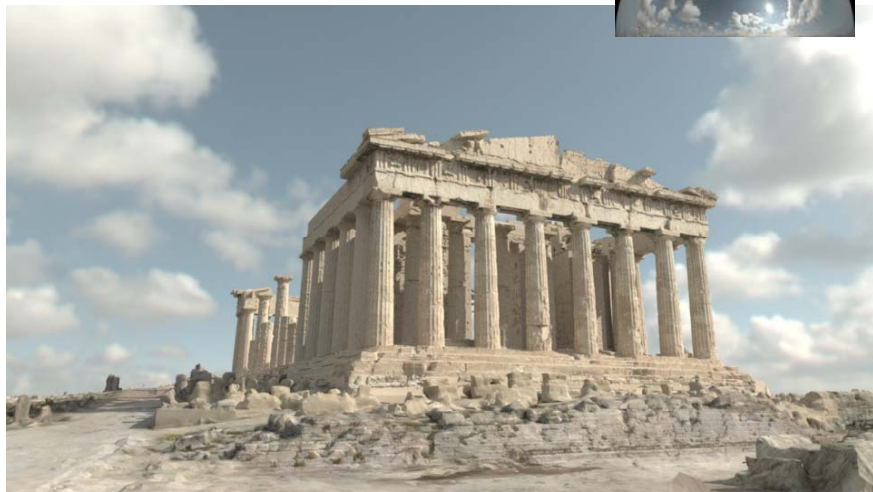
# Lit by sun only



# Lit by sky only



Lit by sun and sky



Real Scene Example

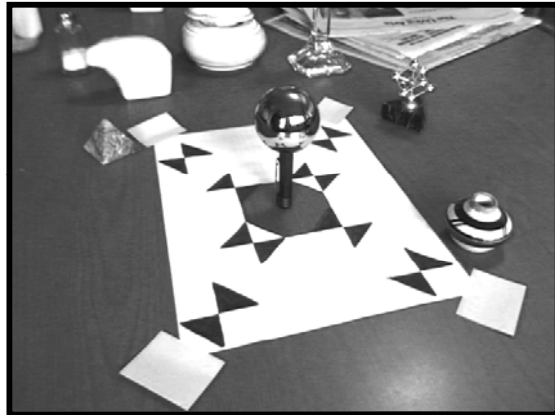
DigiVFX



- Goal: place synthetic objects on table

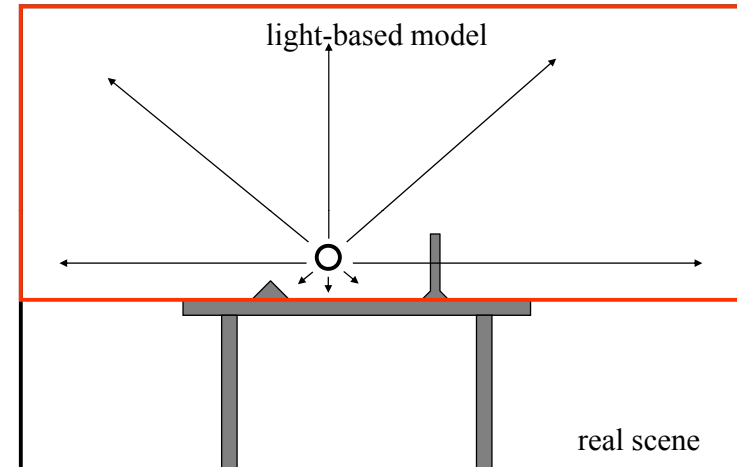
## Light Probe / Calibration Grid

DigiVFX



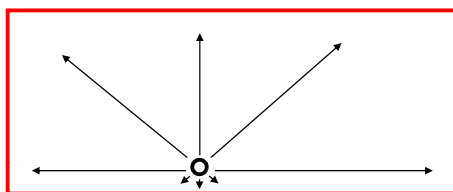
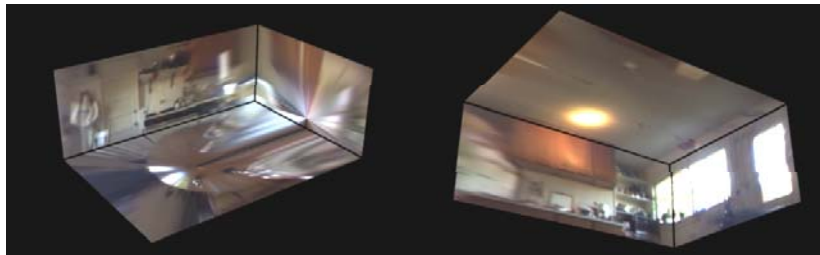
## Modeling the Scene

DigiVFX



## The *Light-Based* Room Model

DigiVFX



## Rendering into the Scene

DigiVFX



- Background Plate

## Rendering into the scene

DigiVFX



- Objects and Local Scene matched to Scene

## Differential rendering

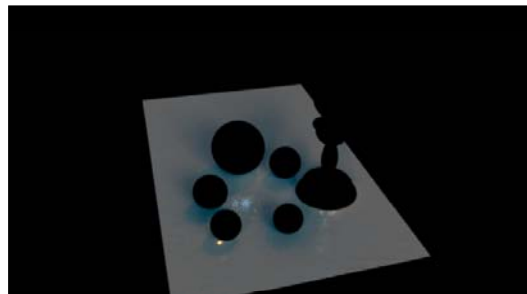
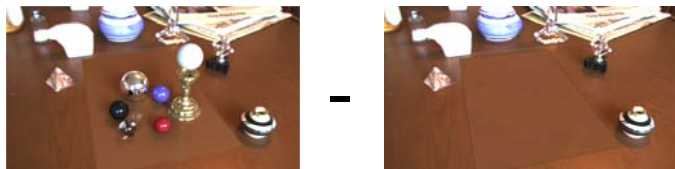
DigiVFX



- Local scene w/o objects, illuminated by model

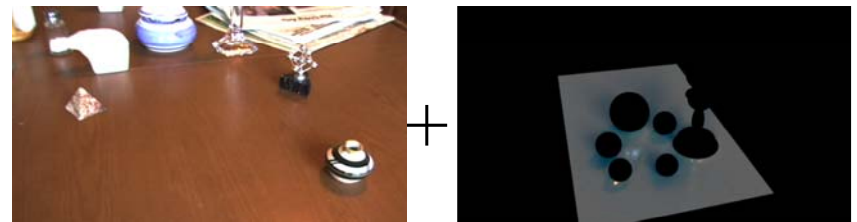
## Differential rendering

DigiVFX



## Differential rendering

DigiVFX

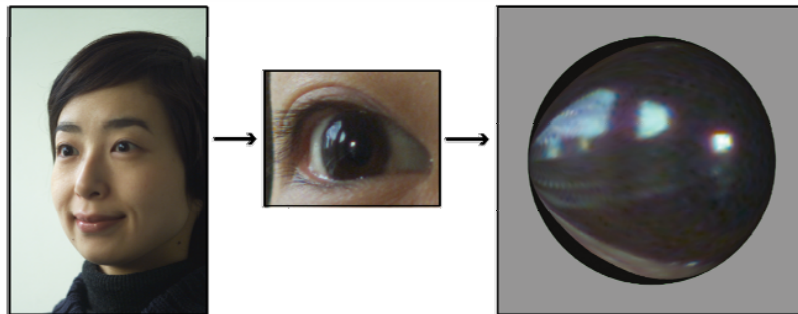




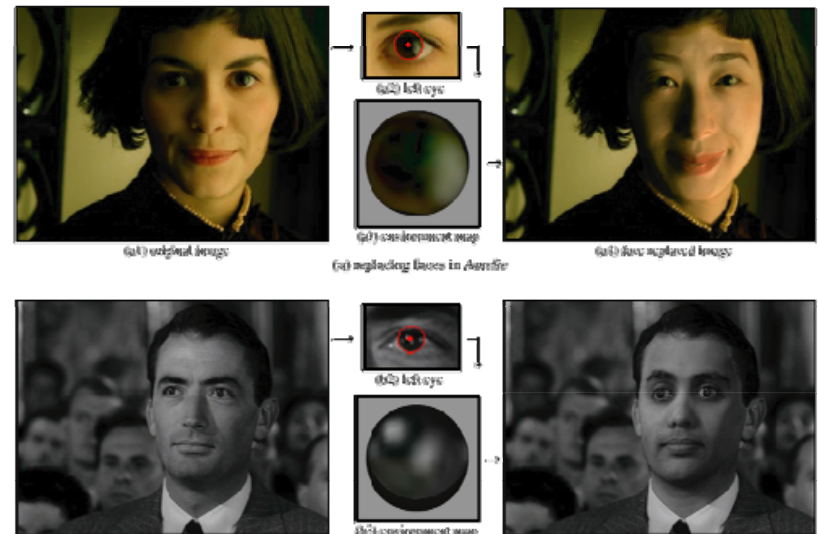
## Environment map from single image?



## Eye as light probe! (Nayar et al)



## Results





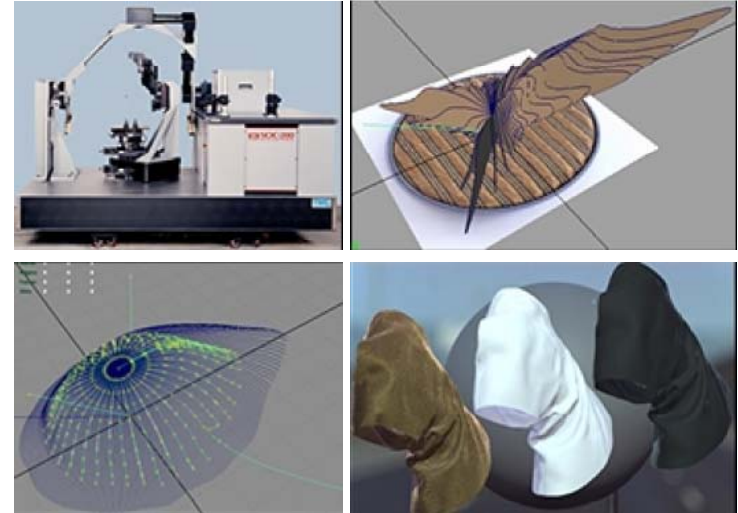
## Application in "Superman returns"

DigiVFX



## Capturing reflectance

DigiVFX



## Application in "The Matrix Reloaded"

DigiVFX



3D acquisition for faces

## Cyberware scanners

DigiVFX



face & head scanner

whole body scanner

## Making facial expressions from photos

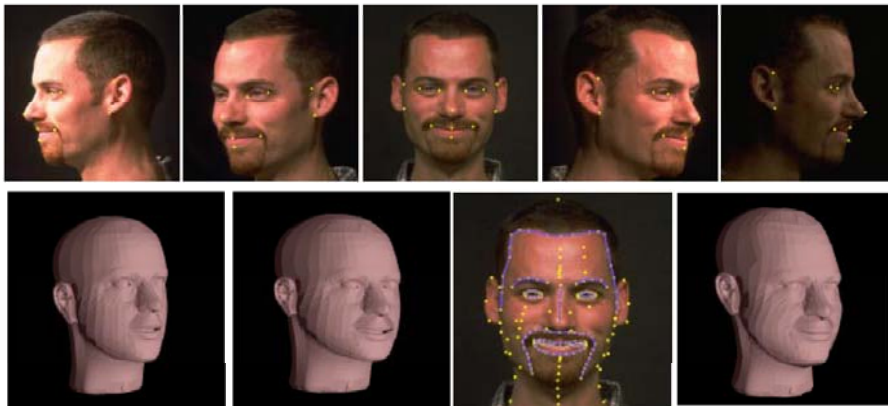
DigiVFX

- Similar to Façade, use a generic face model and view-dependent texture mapping
- Procedure
  1. Take multiple photographs of a person
  2. Establish corresponding feature points
  3. Recover 3D points and camera parameters
  4. Deform the generic face model to fit points
  5. Extract textures from photos

## Reconstruct a 3D model

DigiVFX

input photographs



generic 3D  
face model

pose  
estimation

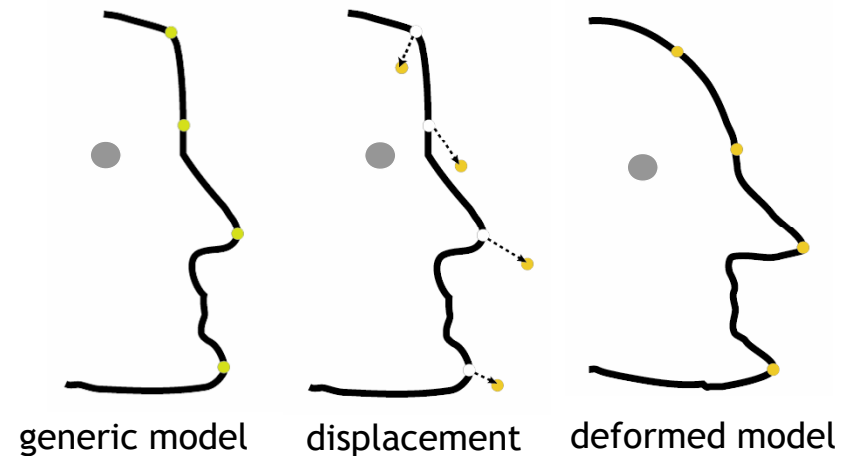
more  
features

deformed  
model

## Mesh deformation

DigiVFX

- Compute displacement of feature points
- Apply scattered data interpolation



generic model

displacement

deformed model

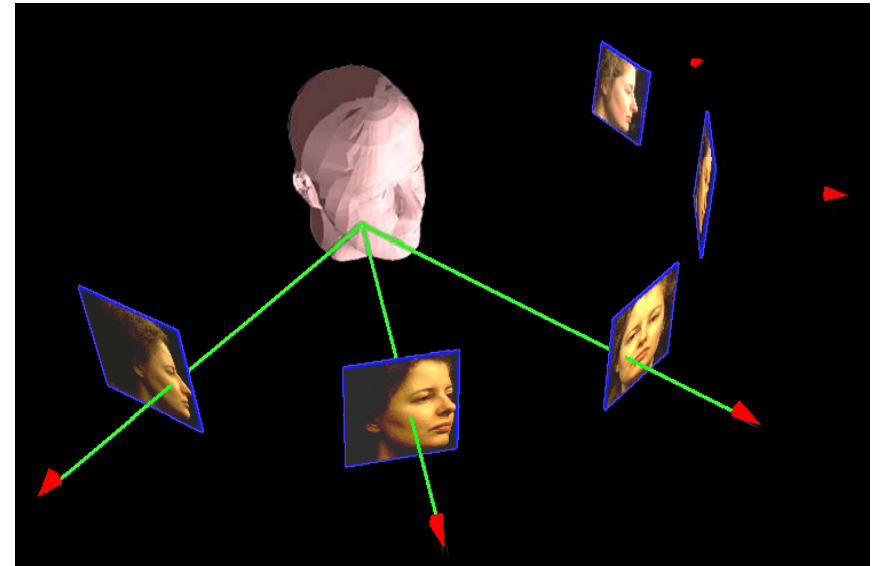
## Texture extraction

DigiVFX

- The color at each point is a weighted combination of the colors in the photos
- Texture can be:
  - view-independent
  - view-dependent
- Considerations for weighting
  - occlusion
  - smoothness
  - positional certainty
  - view similarity

## Texture extraction

DigiVFX



## Texture extraction

DigiVFX



## Texture extraction

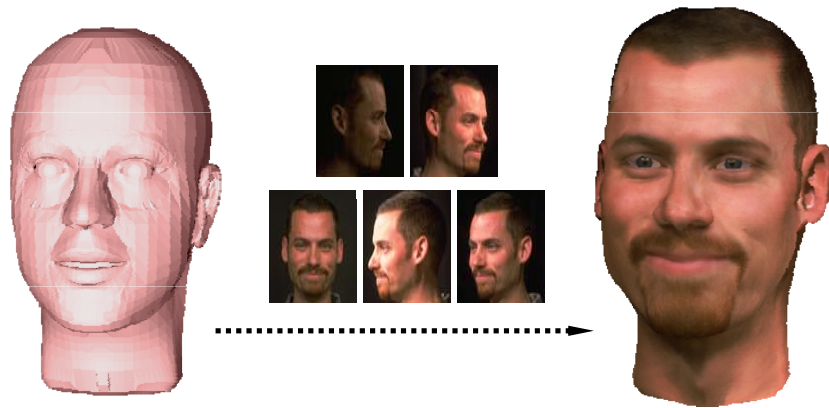
DigiVFX



view-independent

view-dependent

## Model reconstruction



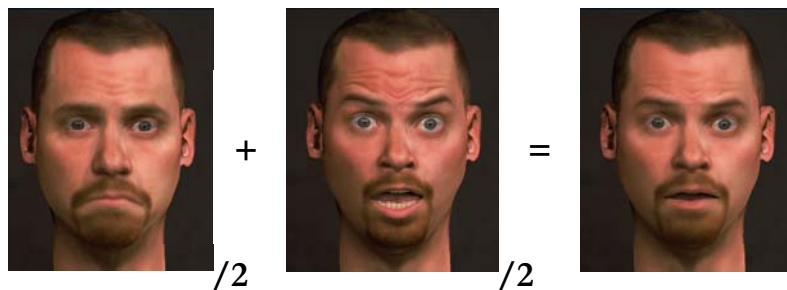
Use images to adapt a generic face model.

## Creating new expressions

- In addition to global blending we can use:
  - Regional blending
  - Painterly interface

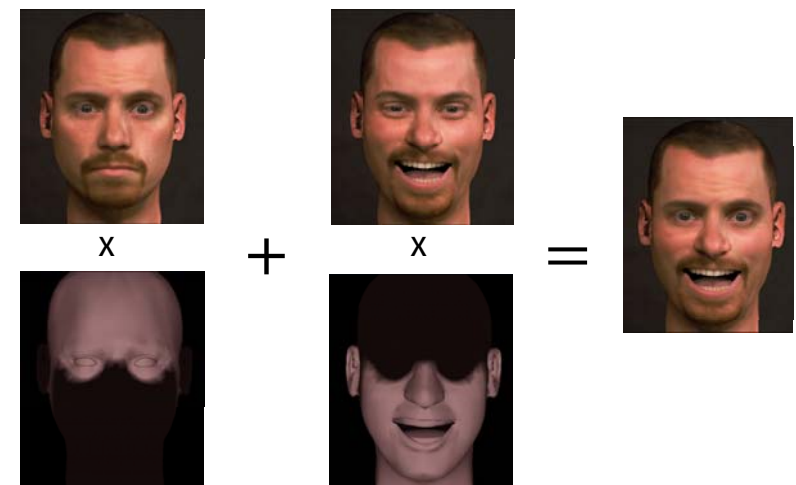
## Creating new expressions

New expressions are created with 3D morphing:



Applying a global blend

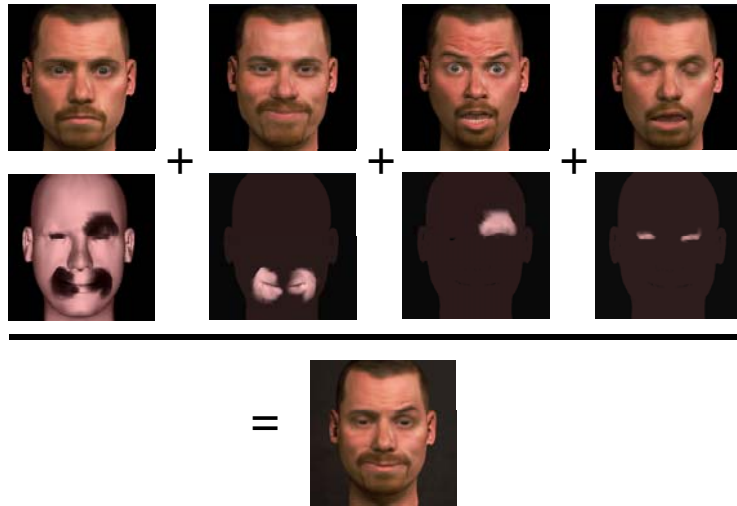
## Creating new expressions



Applying a region-based blend

## Creating new expressions

DigiVFX



Using a painterly interface

## Drunken smile

DigiVFX



## Animating between expressions

DigiVFX

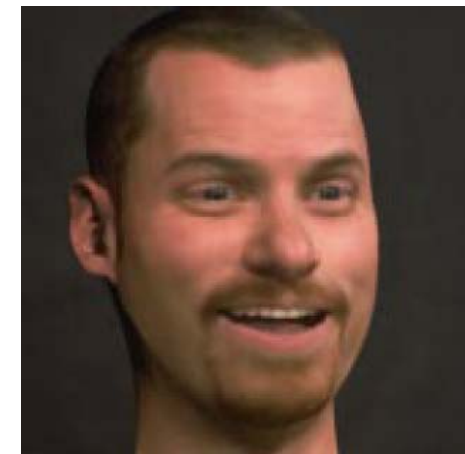
Morphing over time creates animation:



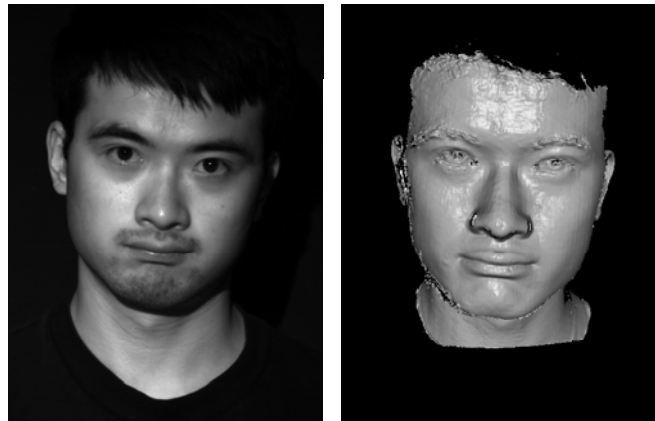
“neutral” → “joy”

## Video

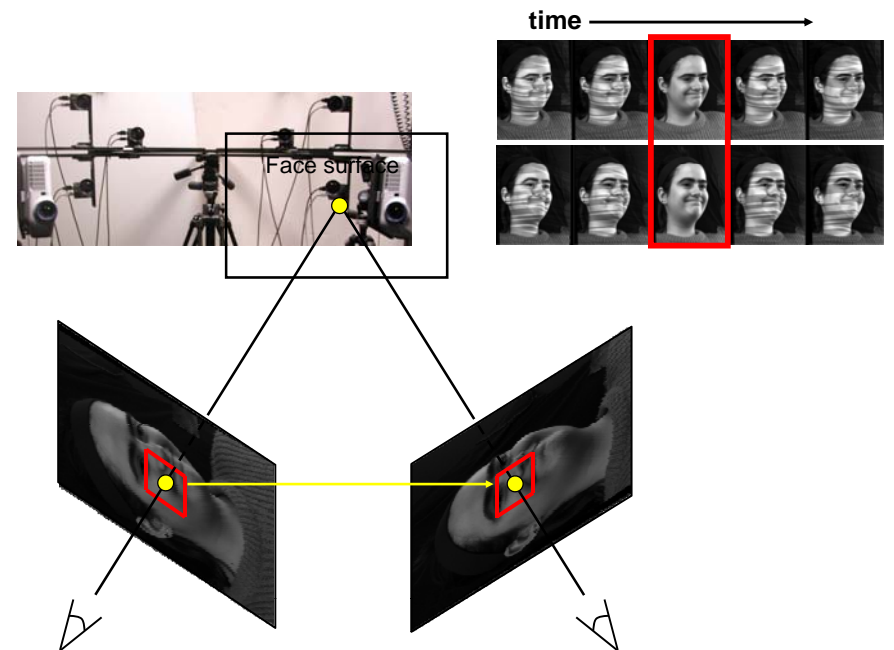
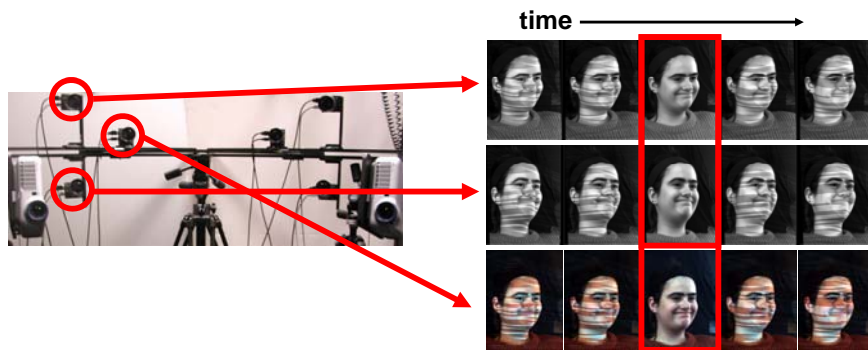
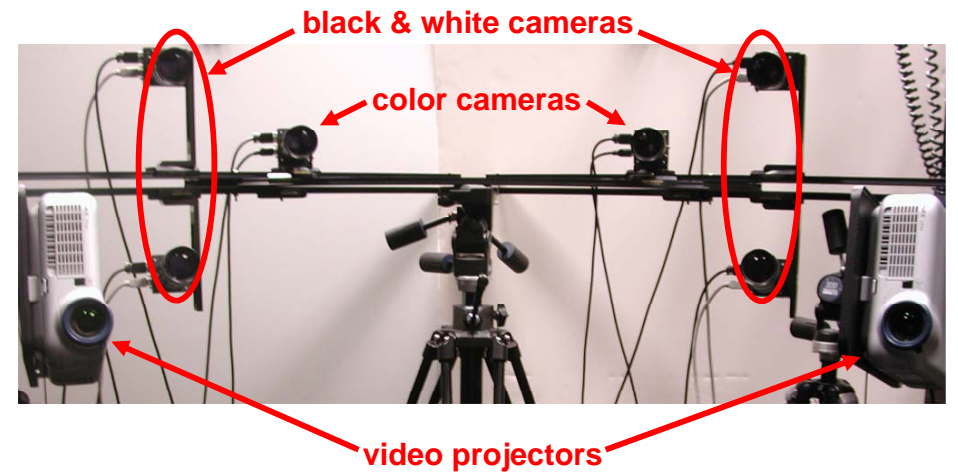
DigiVFX

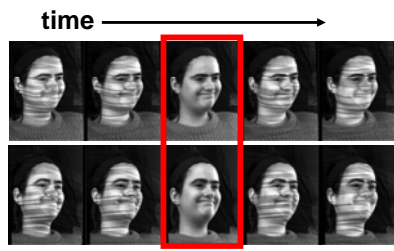


# Spacetime faces

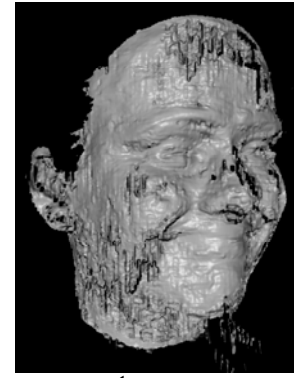
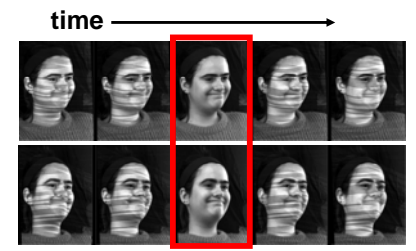


# Spacetime faces

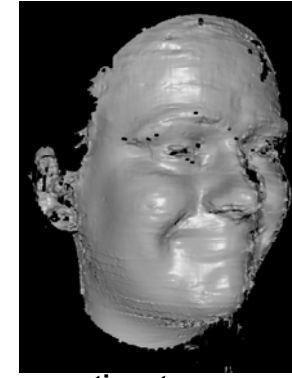




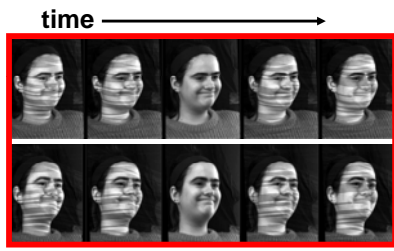
stereo



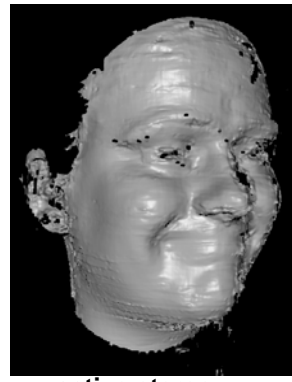
stereo



active stereo



stereo

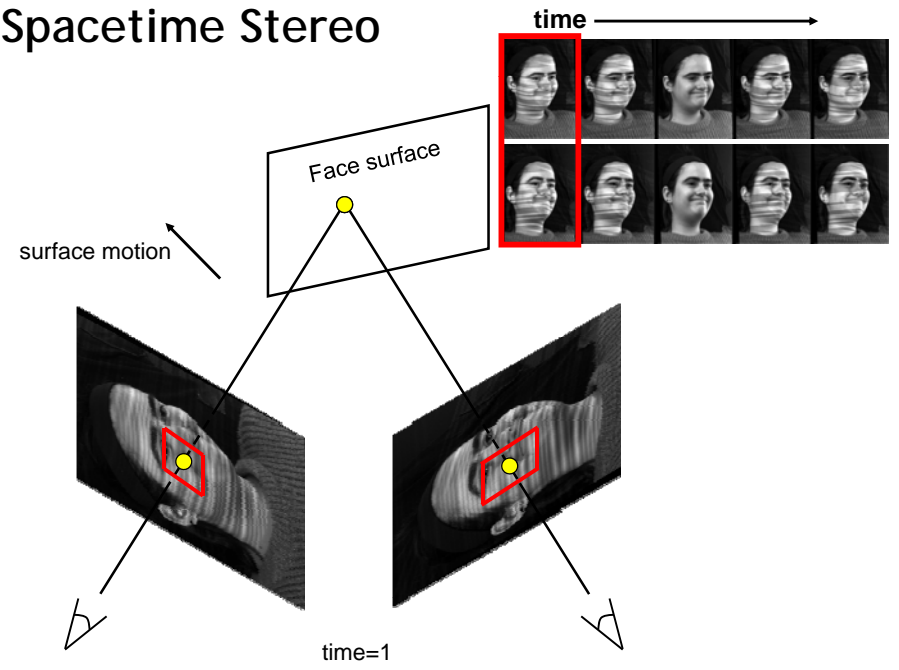


active stereo

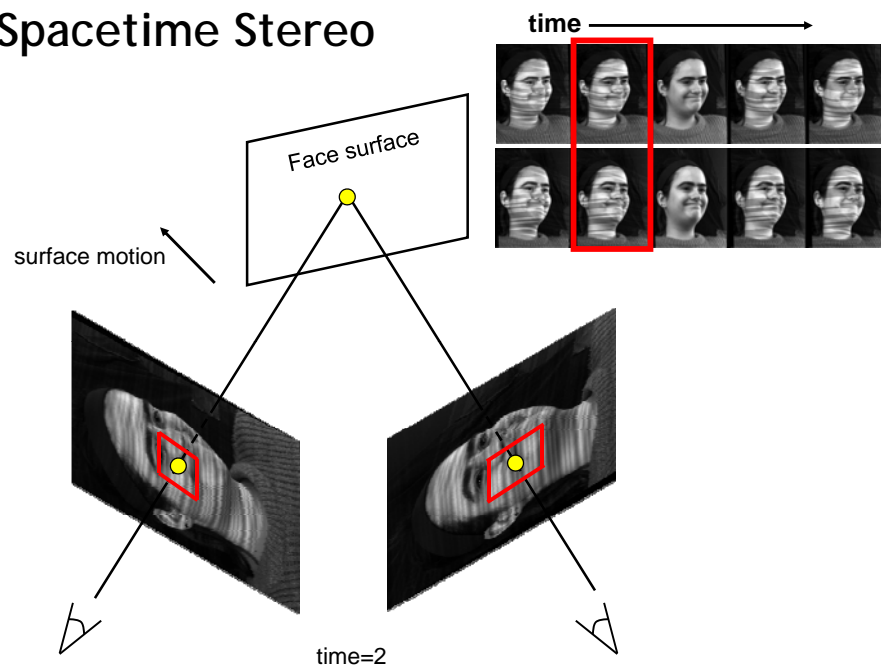


spacetime stereo

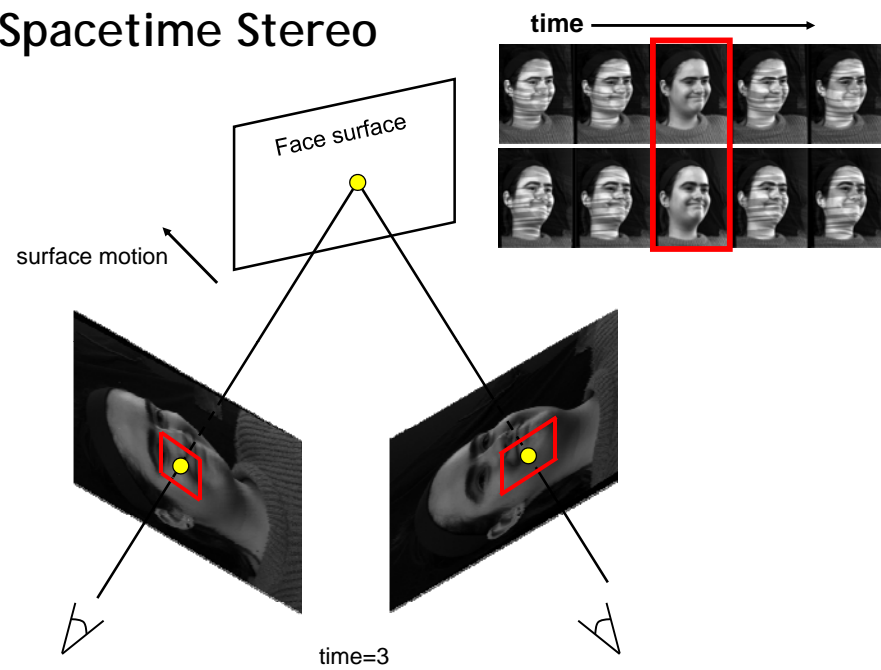
### Spacetime Stereo



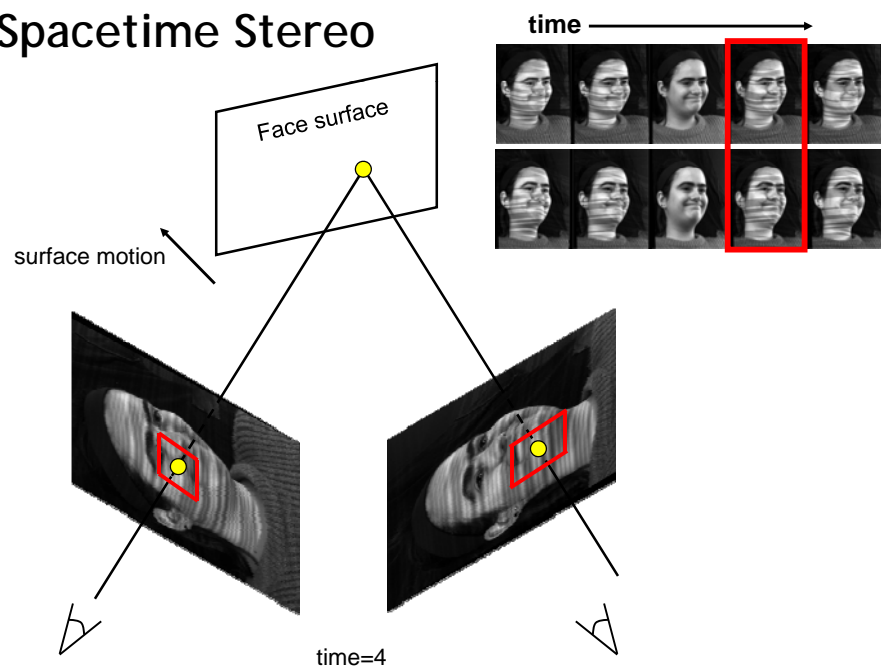
# Spacetime Stereo



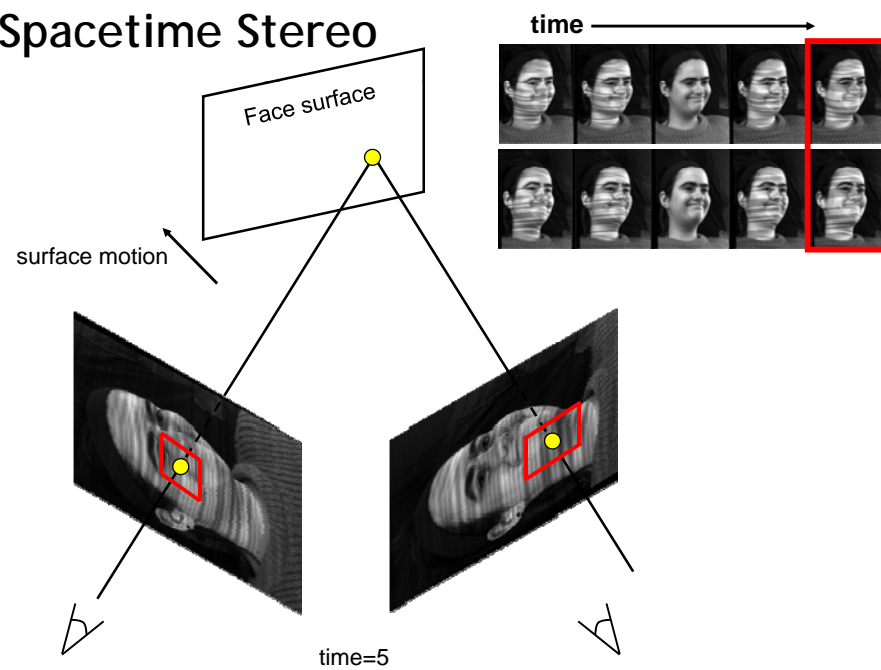
# Spacetime Stereo



# Spacetime Stereo

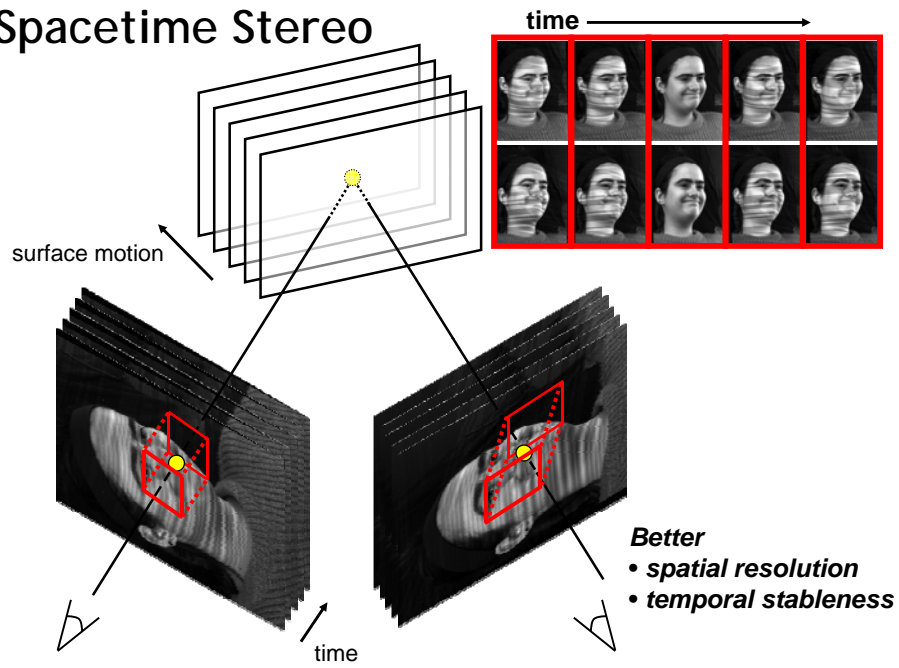


# Spacetime Stereo

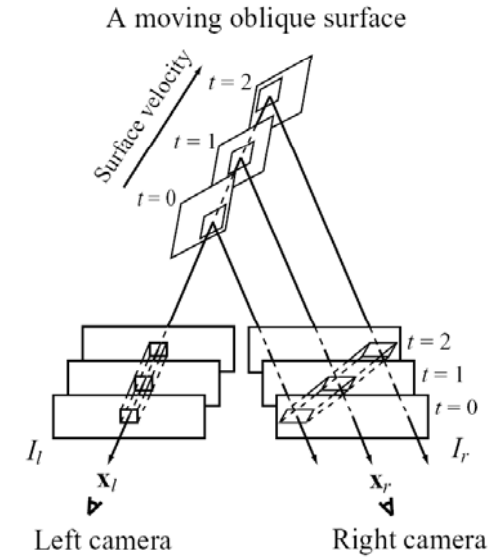




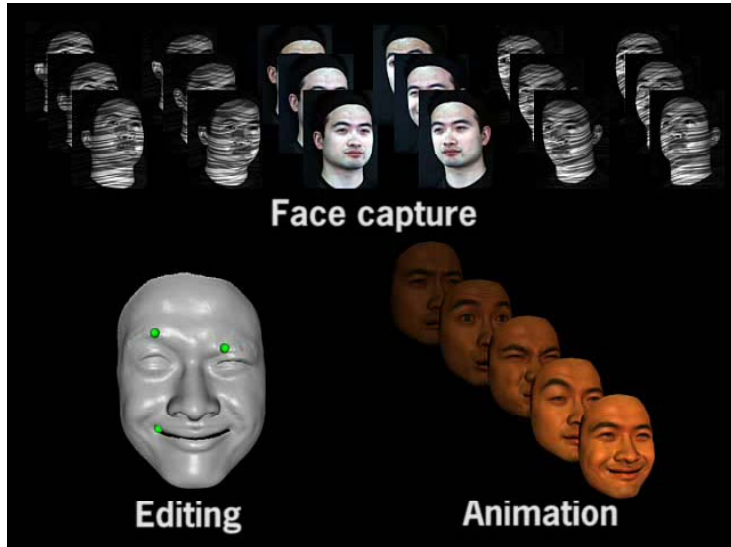
# Spacetime Stereo



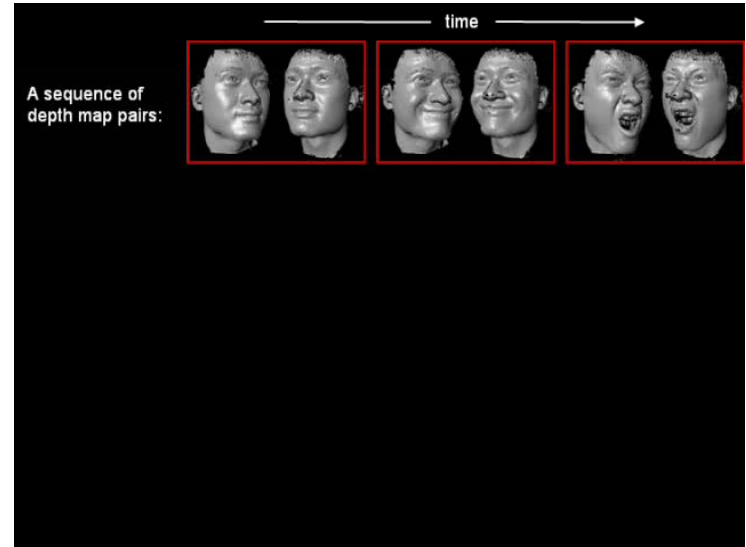
# Spacetime stereo matching



# Video



# Fitting



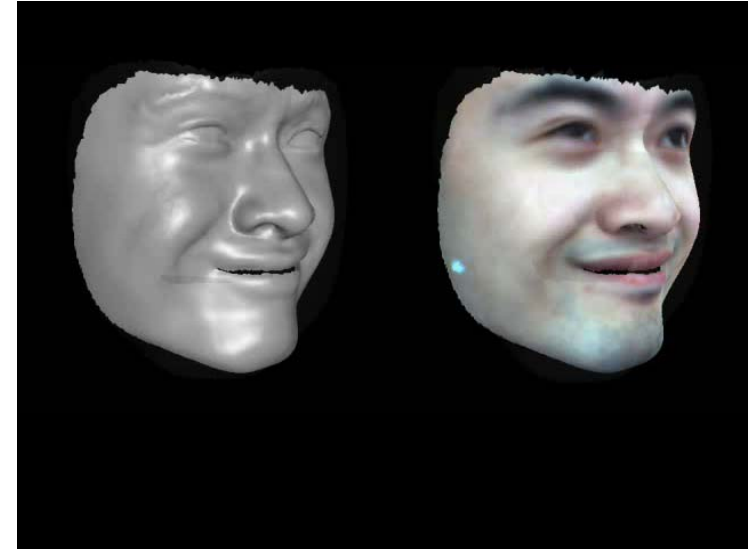
## FaceK

DigiVFX

Face Editing

## Animation

DigiVFX



## 3D face applications: The one

DigiVFX



## 3D face applications: Gladiator

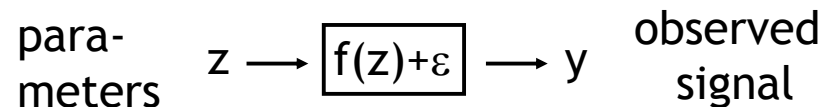
DigiVFX



extra 3M

## Statistical methods

## Statistical methods



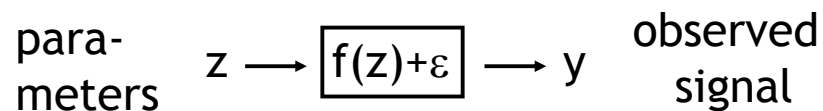
$$z^* = \max_z P(z | y)$$

$$= \max_z \frac{P(y | z)P(z)}{P(y)}$$

$$= \min_z L(y | z) + L(z)$$

Example:  
super-resolution  
de-noising  
de-blocking  
Inpainting  
...

## Statistical methods



$$z^* = \min_z L(y | z) + L(z)$$

data evidence  $\frac{\|y - f(z)\|^2}{\sigma^2}$   $\swarrow$   
 $\nwarrow$  *a-priori* knowledge

## Statistical methods

*There are approximately  $10^{240}$  possible  $10 \times 10$  gray-level images. Even human being has not seen them all yet. There must be a strong statistical bias.*

*Takeo Kanade*

Approximately  $8 \times 10^{11}$  blocks per day per person.

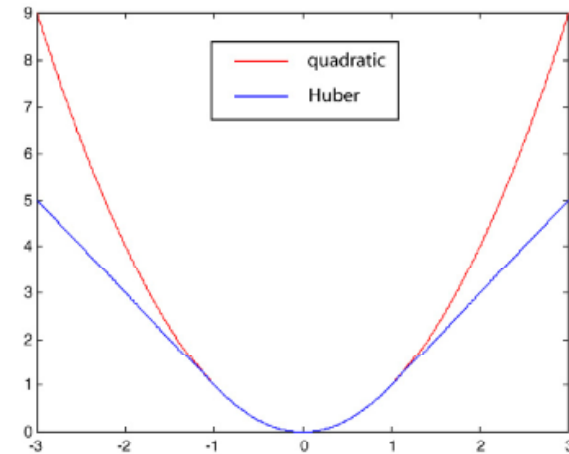
## Generic priors

“Smooth images are good images.”

$$L(z) = \sum_x \rho(V(x))$$

Gaussian MRF  $\rho(d) = d^2$

$$\text{Huber MRF } \rho(d) = \begin{cases} d^2 & |d| \leq T \\ T^2 + 2T(|d| - T) & d > T \end{cases}$$



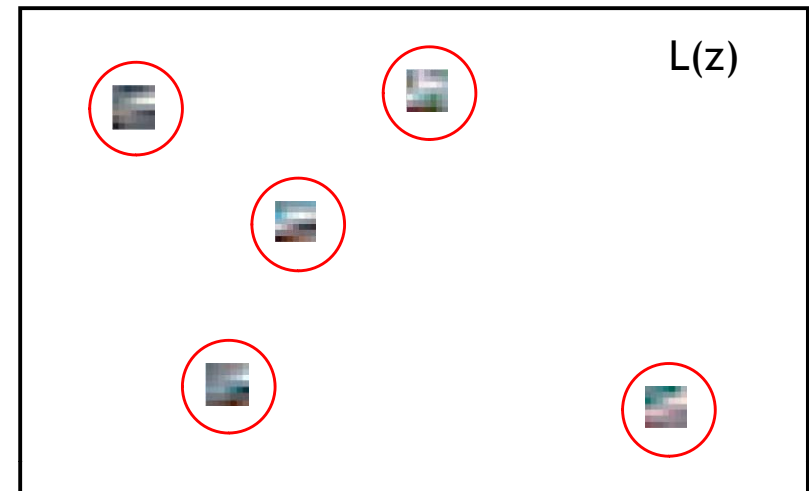
## Example-based priors

“Existing images are good images.”

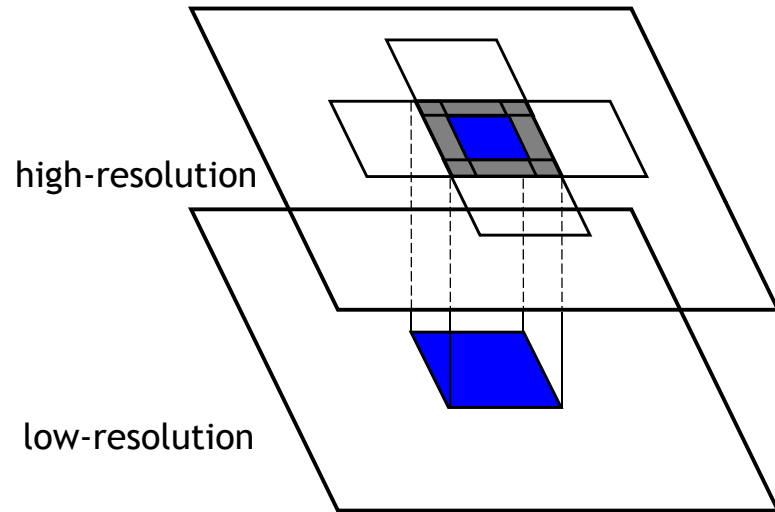


six 200×200  
Images  $\Rightarrow$   
2,000,000  
pairs

## Example-based priors



## Example-based priors



## Model-based priors

“Face images are good images when working on face images ...”

Parametric model

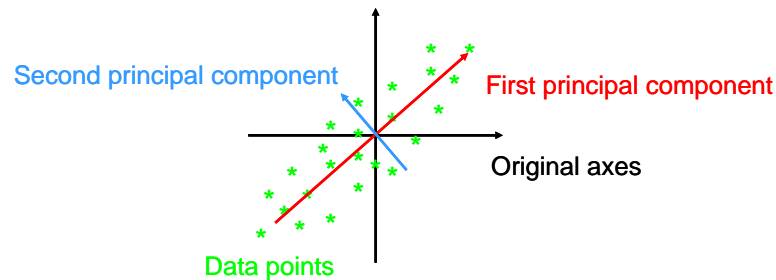
$$Z = WX + \mu \quad L(X)$$

$$z^* = \min_z L(y | z) + L(z)$$

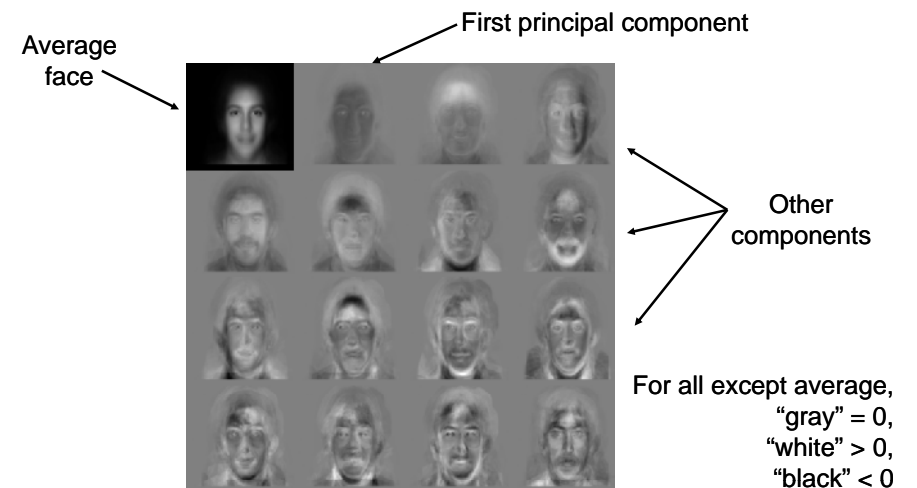
$$\begin{cases} X^* = \min_x L(y | WX + \mu) + L(X) \\ z^* = WX^* + \mu \end{cases}$$

## PCA

- Principal Components Analysis (PCA): approximating a high-dimensional data set with a lower-dimensional subspace



## PCA on faces: “eigenfaces”



## Model-based priors

“Face images are good images when working on face images ...”

Parametric model

$$Z = WX + \mu \quad L(X)$$

$$z^* = \min_z L(y | z) + L(z)$$

$$\begin{cases} X^* = \min_x L(y | WX + \mu) + L(X) \\ z^* = WX^* + \mu \end{cases}$$

## Face models from single images

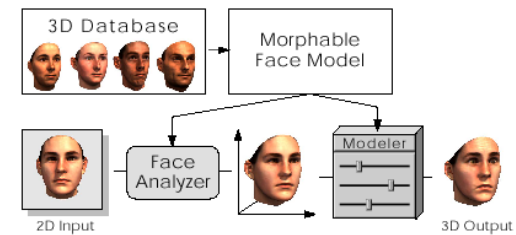
## Super-resolution



(a) Input low  $24 \times 32$  (b) Our results (c) Cubic B-Spline  
(d) Freeman et al. (e) Baker et al. (f) Original high  $96 \times 128$

## Morphable model of 3D faces

- Start with a catalogue of 200 aligned 3D Cyberware scans



- Build a model of *average* shape and texture, and principal *variations* using PCA

# Morphable model

shape exemplars      texture exemplars

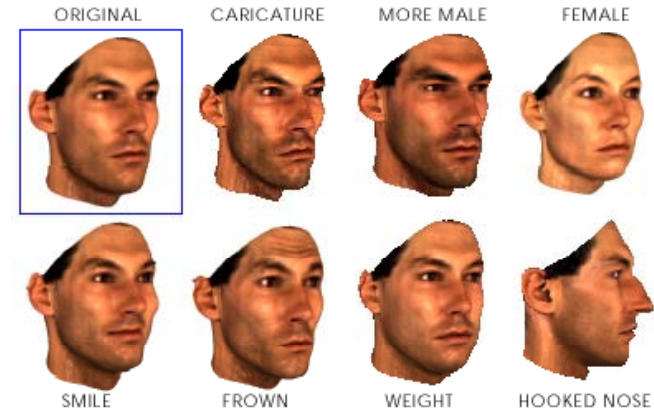
$$S_{model} = \bar{S} + \sum_{i=1}^{m-1} \alpha_i s_i, \quad T_{model} = \bar{T} + \sum_{i=1}^{m-1} \beta_i t_i, \quad (1)$$

$\vec{\alpha}, \vec{\beta} \in \mathbb{R}^{m-1}$ . The probability for coefficients  $\vec{\alpha}$  is given by

$$p(\vec{\alpha}) \sim \exp\left[-\frac{1}{2} \sum_{i=1}^{m-1} (\alpha_i / \sigma_i)^2\right], \quad (2)$$

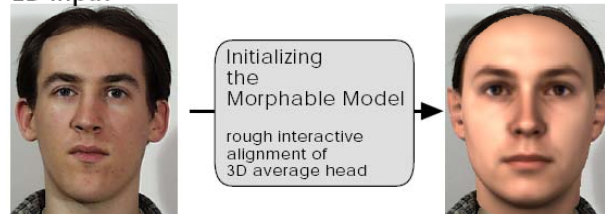
# Morphable model of 3D faces

- Adding some variations



# Reconstruction from single image

2D Input



Automated 3D Shape and Texture Reconstruction

$\alpha_j \beta_j$



Rendering must be similar to the input if we guess right

# Reconstruction from single image

$$E = \frac{1}{\sigma_N^2} E_I + \sum_{j=1}^{m-1} \frac{\alpha_j^2}{\sigma_{S,j}^2} + \sum_{j=1}^{m-1} \frac{\beta_j^2}{\sigma_{T,j}^2} + \sum_j \frac{(\rho_j - \bar{\rho}_j)^2}{\sigma_{\rho,j}^2} \text{ prior}$$

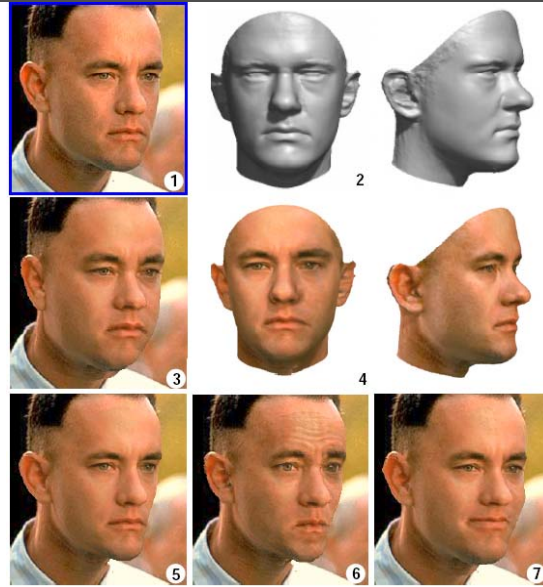
$$E_I = \sum_{x,y} \|\mathbf{I}_{input}(x,y) - \mathbf{I}_{model}(x,y)\|^2$$

shape and texture priors are learnt from database

pis the set of parameters for shading including camera pose, lighting and so on

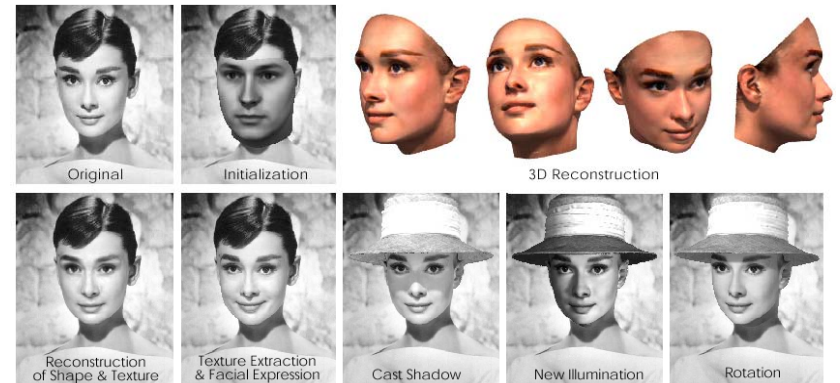
## Modifying a single image

DigiVFX



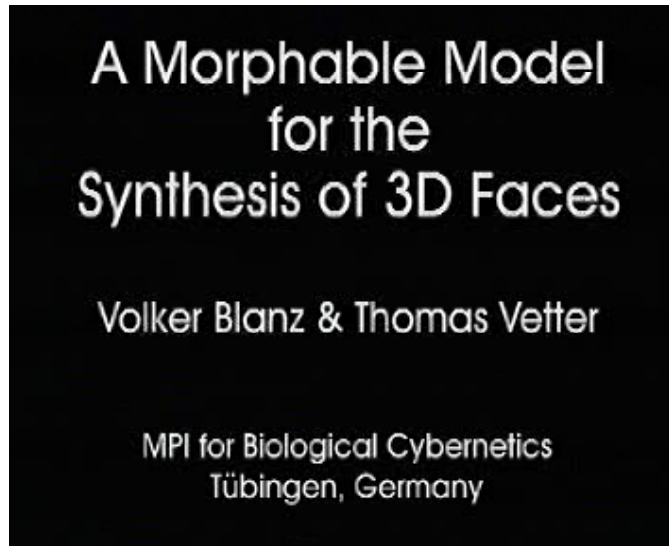
## Animating from a single image

DigiVFX



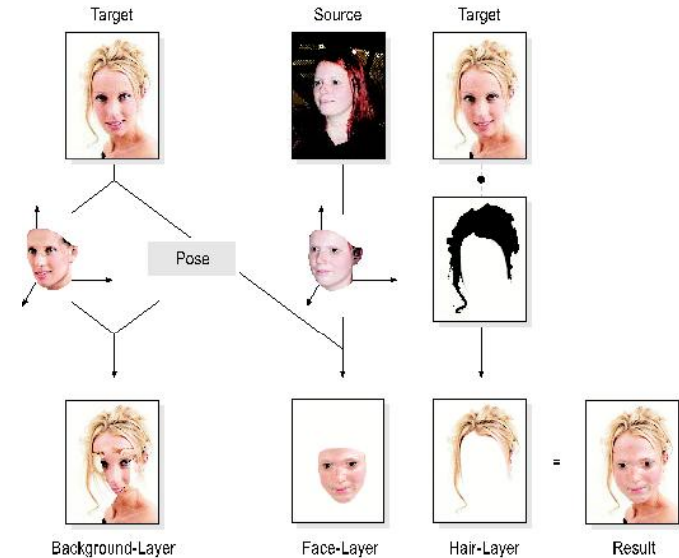
## Video

DigiVFX



## Exchanging faces in images

DigiVFX





## Exchange faces in images

DigiVFX



## Exchange faces in images

DigiVFX



## Exchange faces in images

DigiVFX



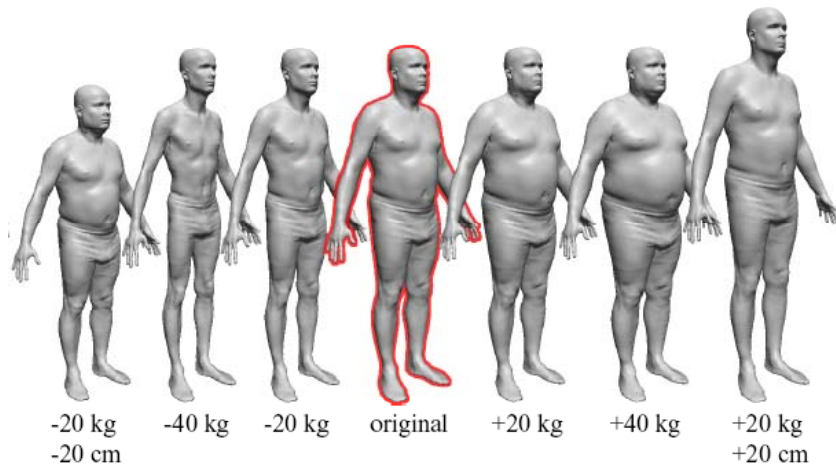
## Exchange faces in images

DigiVFX



## Morphable model for human body

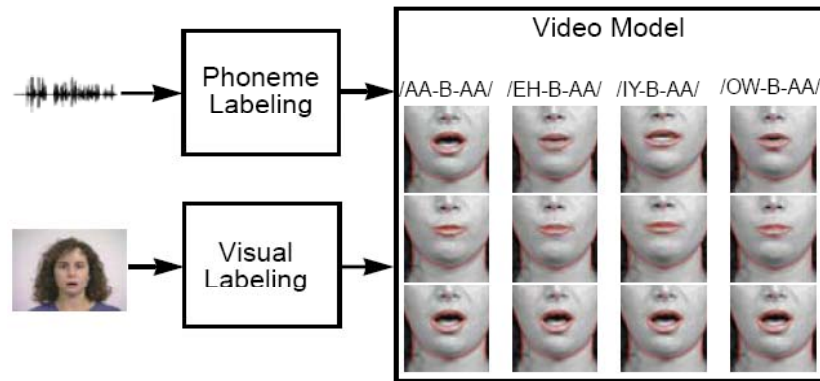
DigiVFX



## Image-based faces (lip sync.)

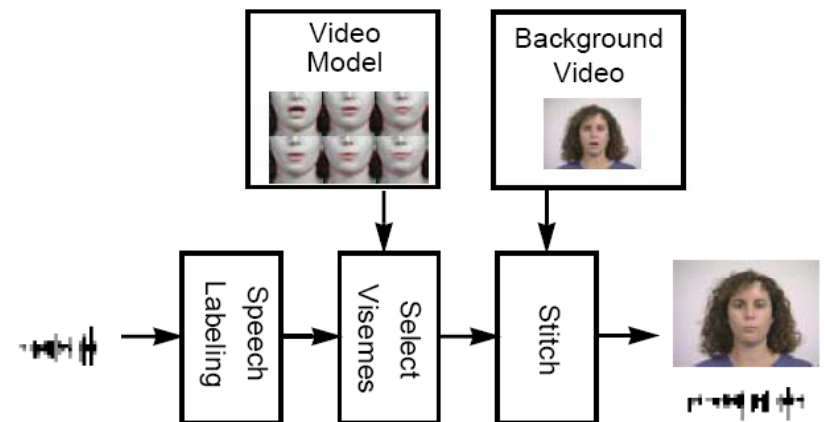
## Video rewrite (analysis)

DigiVFX



## Video rewrite (synthesis)

DigiVFX



## Results

DigiVFX

- Video database

- 2 minutes of JFK
  - Only half usable
  - Head rotation



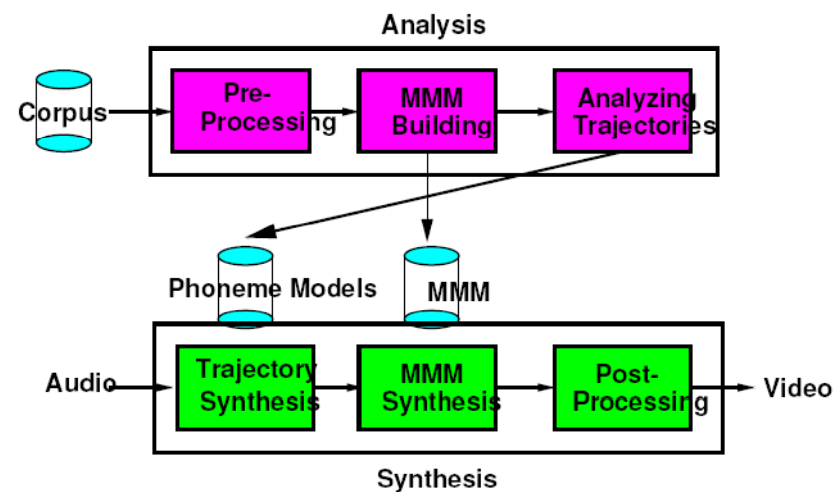
[training video](#)

[Read my lips.](#)

[I never met Forest Gump.](#)

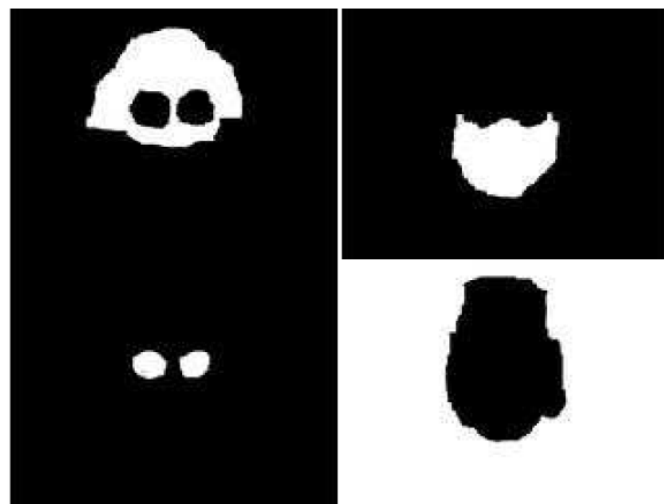
## Morphable speech model

DigiVFX



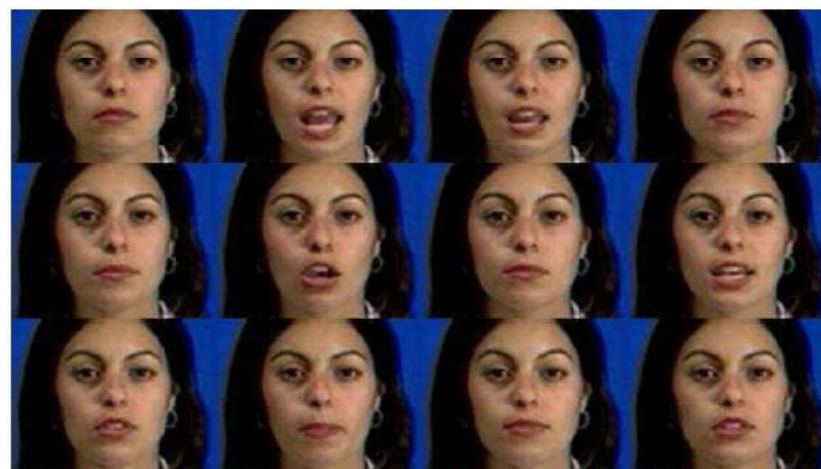
## Preprocessing

DigiVFX



## Prototypes (PCA+k-mean clustering)

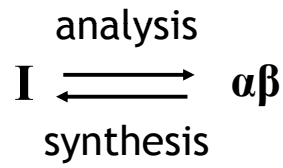
DigiVFX



We find  $I_i$  and  $C_i$  for each prototype image.

# Morphable model

$$I^{morph}(\alpha, \beta) = \sum_{i=1}^N \beta_i \mathbf{W}(I_i, \mathbf{W}(\sum_{j=1}^N \alpha_j C_j - C_i, C_i))$$

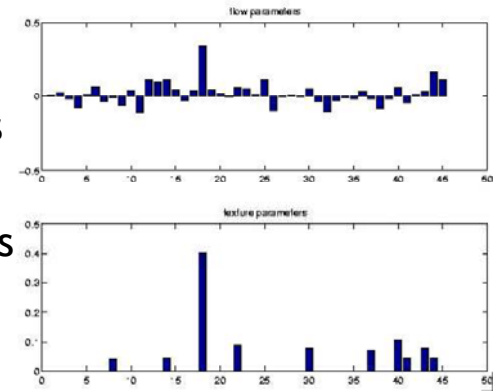


# Morphable model



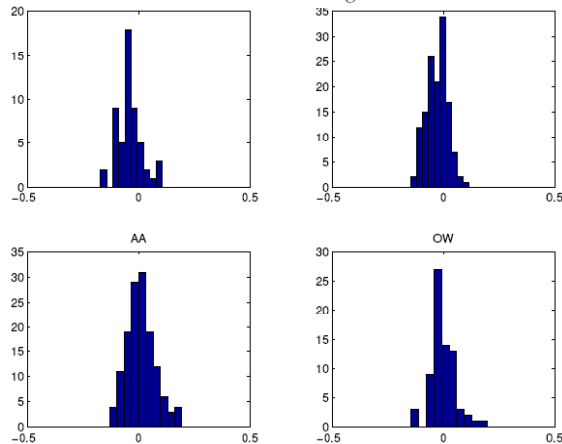
analysis

synthesis



# Synthesis

$$E = \underbrace{(y - \mu)^T D^T \Sigma^{-1} D (y - \mu)}_{\text{target term}} + \lambda \underbrace{y^T W^T W y}_{\text{smoothness}}$$



# Results



## Results

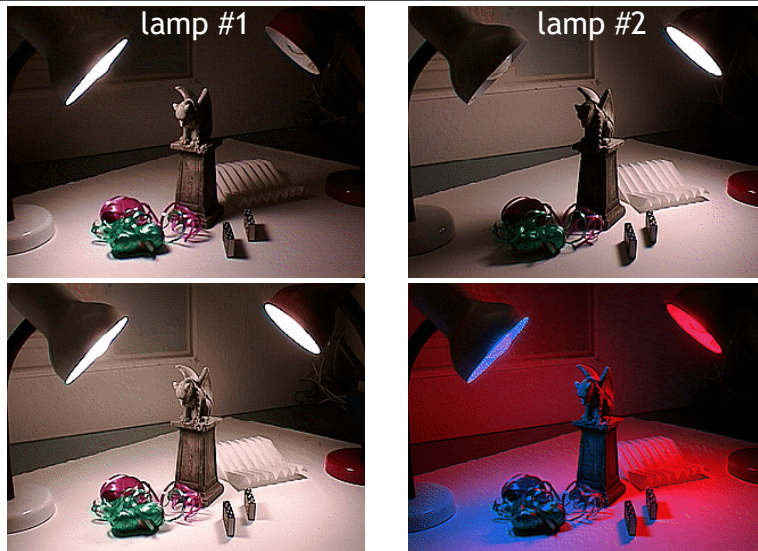
DigiVFX



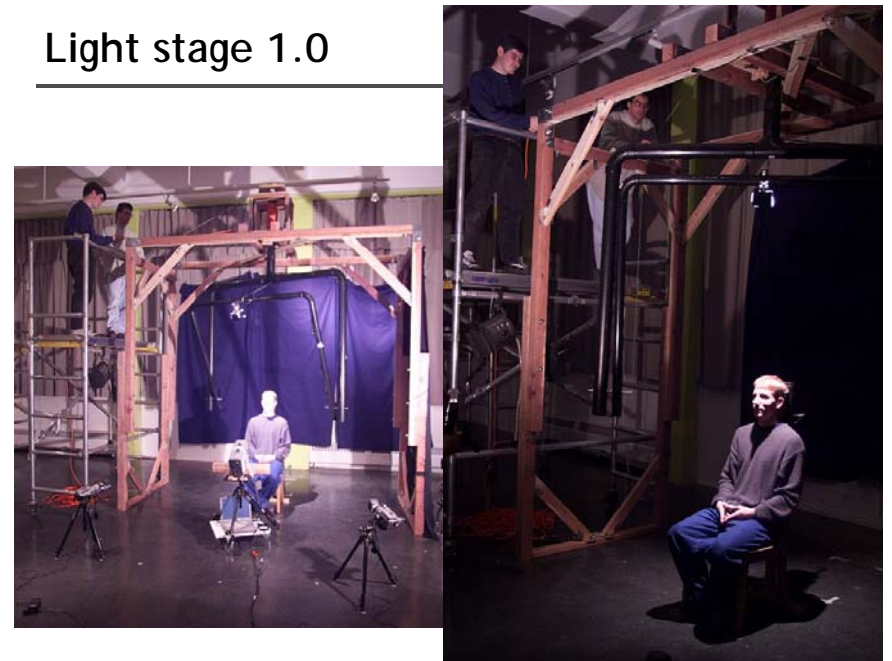
## Relighting faces

## Light is additive

DigiVFX



## Light stage 1.0



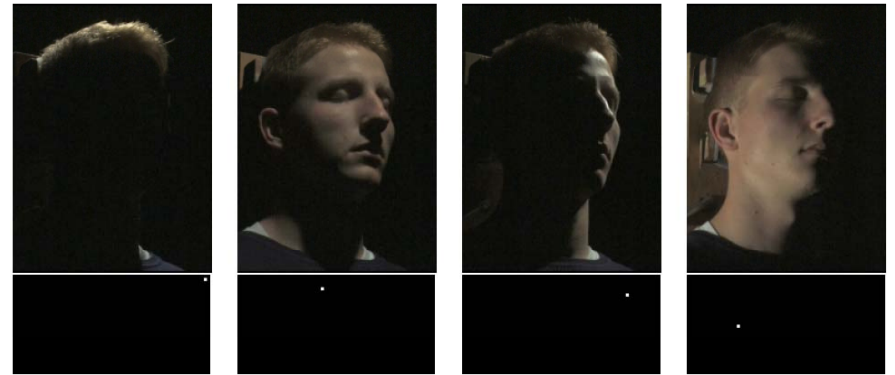
## Light stage 1.0

DigiVFX



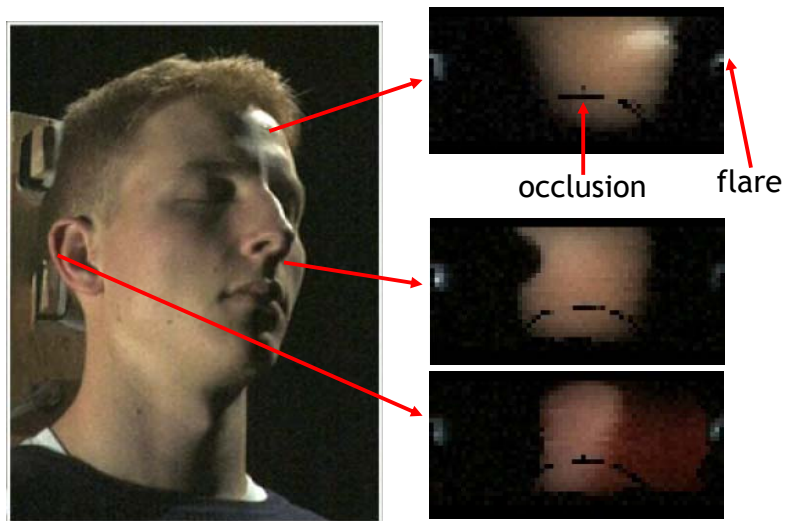
## Input images

DigiVFX



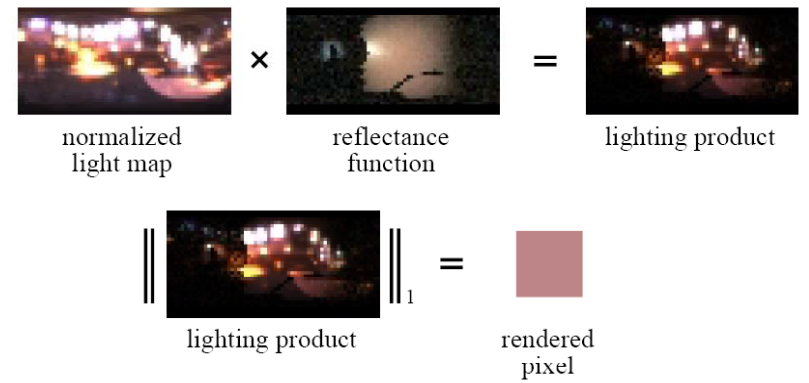
## Reflectance function

DigiVFX



## Relighting

DigiVFX



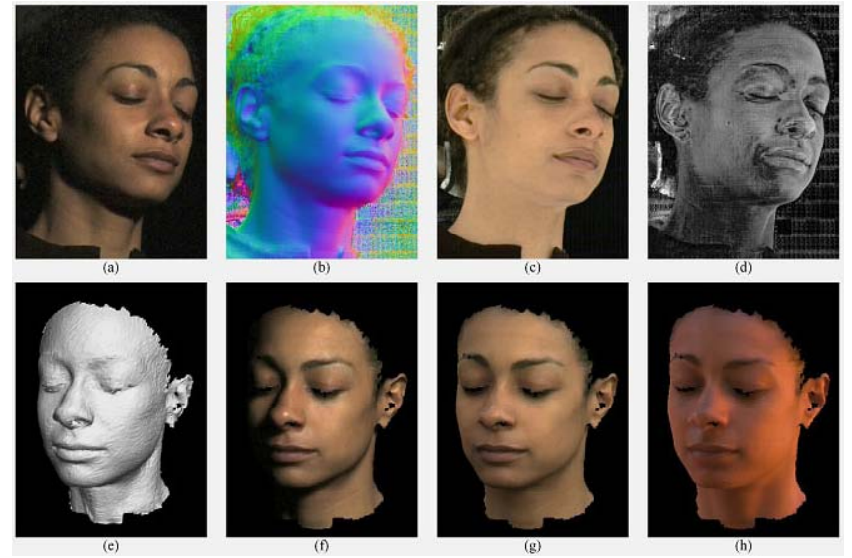
## Results

DigiVFX



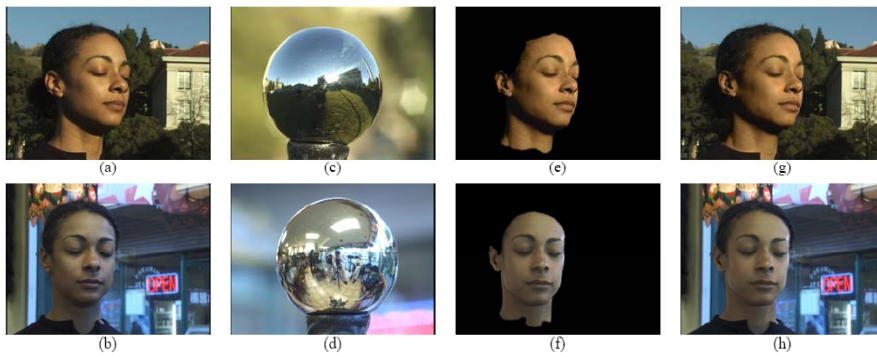
## Changing viewpoints

DigiVFX



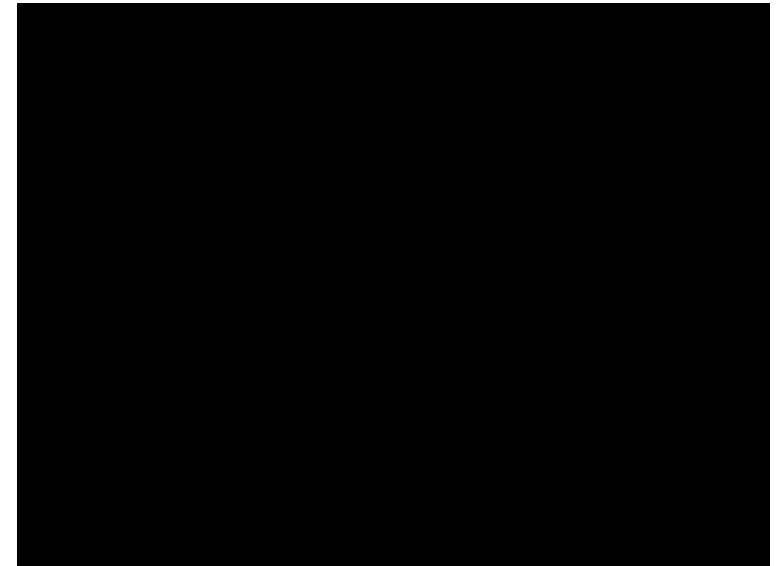
## Results

DigiVFX



## Video

DigiVFX



## 3D face applications: Spiderman 2

DigiVFX



## Spiderman 2

DigiVFX



real

synthetic

## Spiderman 2

DigiVFX



video

## Light stage 3

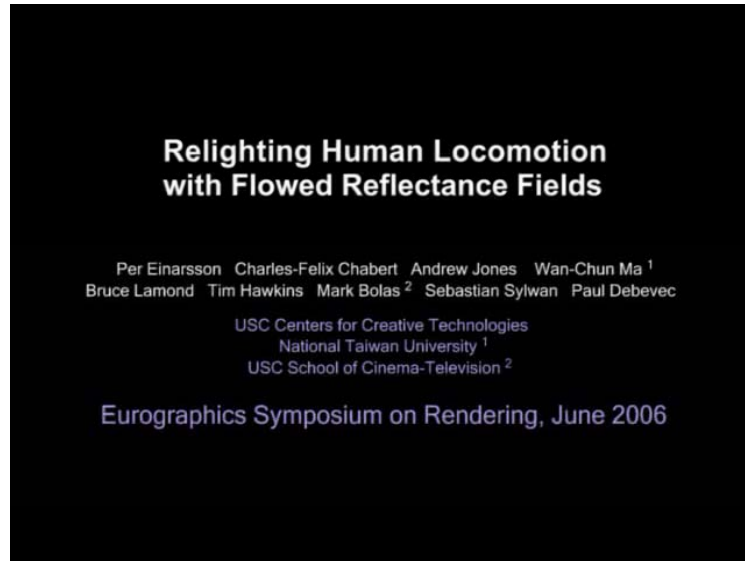
DigiVFX





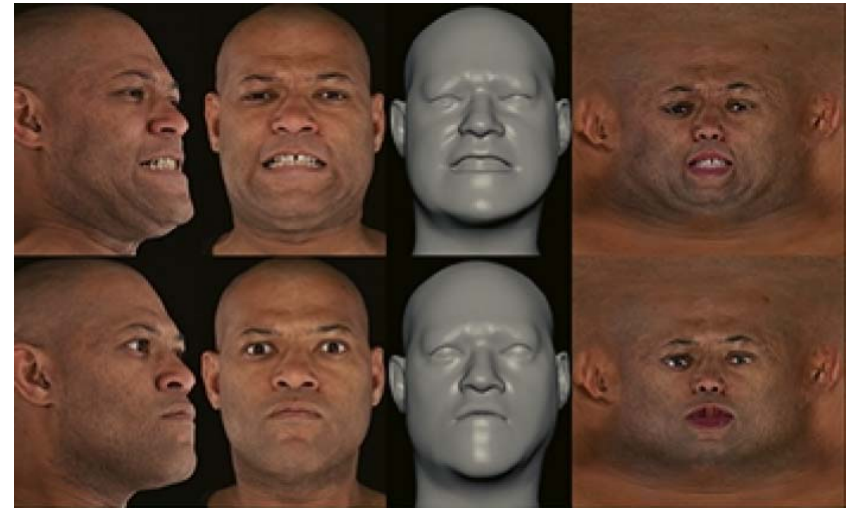
## Light stage 6

DigiVFX



## Application: The Matrix Reloaded

DigiVFX



## Application: The Matrix Reloaded

DigiVFX



## References

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