

# Faces and Image-Based Lighting

Digital Visual Effects, Spring 2009

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*with slides by Richard Szeliski, Steve Seitz, Alex Efros, Li-Yi Wei and Paul Debevec*

# Outline

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- Image-based lighting
- 3D acquisition for faces
- Statistical methods (with application to face super-resolution)
- 3D Face models from single images
- Image-based faces
- Relighting for faces

# Image-based lighting

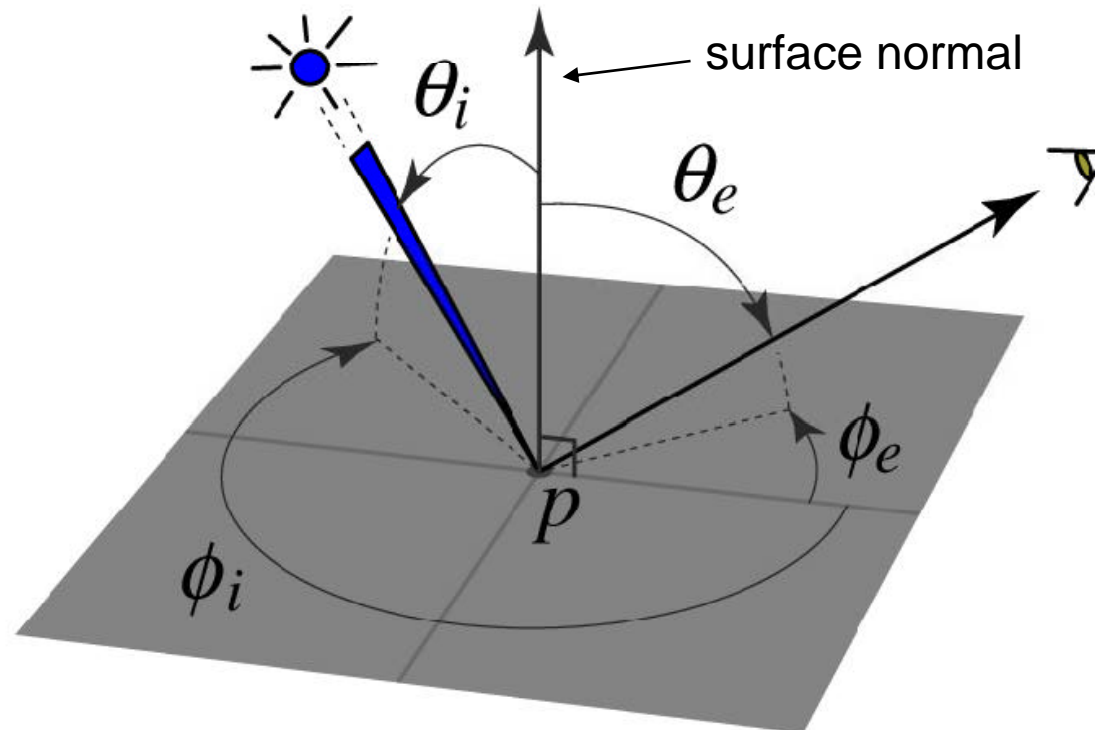
# Rendering

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- Rendering is a function of geometry, reflectance, lighting and viewing.
- To synthesize CGI into real scene, we have to match the above four factors.
- Viewing can be obtained from *calibration* or *structure from motion*.
- Geometry can be captured using *3D photography* or made by hands.
- How to capture lighting and reflectance?

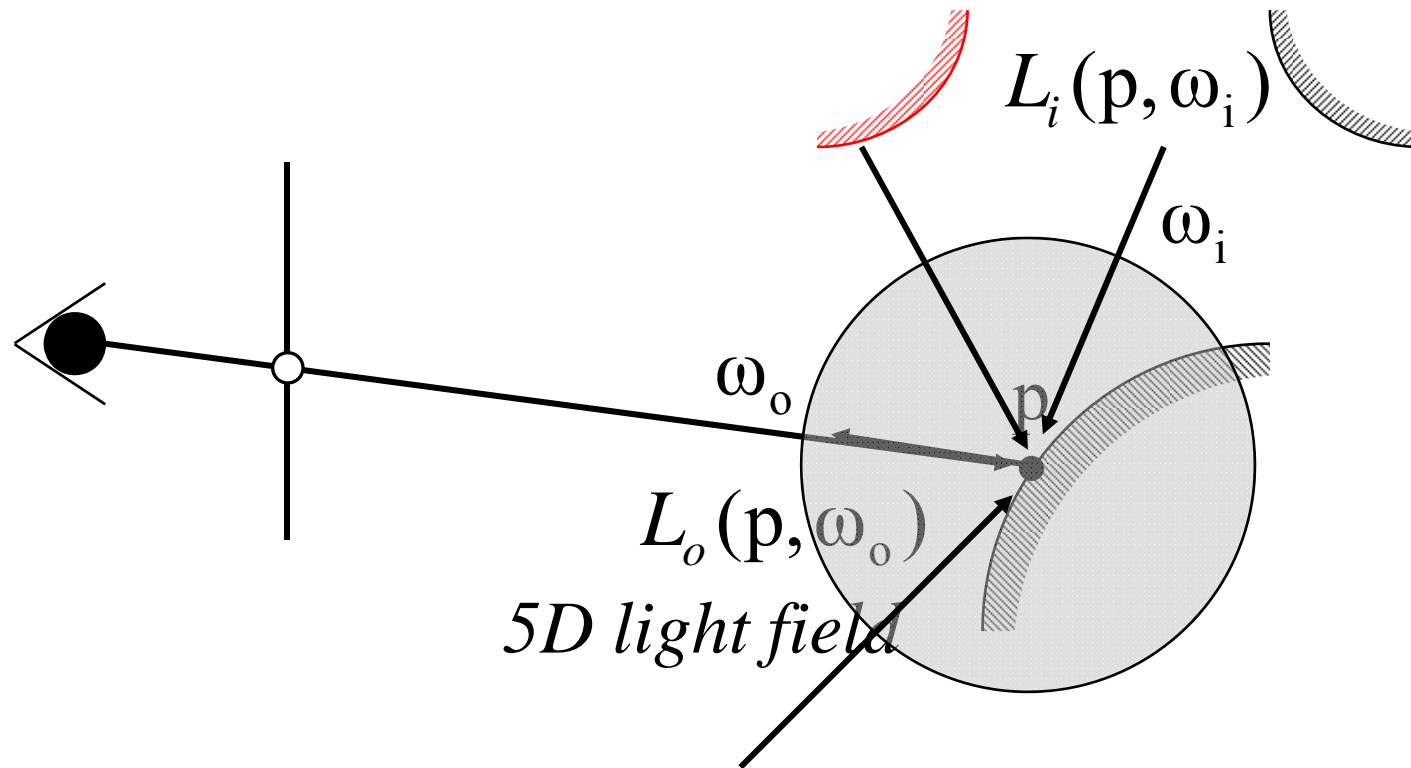
# Reflectance

- The Bidirectional Reflection Distribution Function
  - Given an incoming ray  $(\theta_i, \phi_i)$  and outgoing ray  $(\theta_e, \phi_e)$  what proportion of the incoming light is reflected along out



Answer given by the BRDF:  $\rho(\theta_i, \phi_i, \theta_e, \phi_e)$

# Rendering equation



$$L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{s^2} \rho(p, \omega_o, \omega_i) L_i(p, \omega_i) |\cos \theta_i| d\omega_i$$


# Complex illumination

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$$L_o(\mathbf{p}, \omega_o) = L_e(\mathbf{p}, \omega_o) + \int_{s^2} f(\mathbf{p}, \omega_o, \omega_i) L_i(\mathbf{p}, \omega_i) |\cos \theta_i| d\omega_i$$

$$B(\mathbf{p}, \omega_o) = \int_{s^2} f(\mathbf{p}, \omega_o, \omega_i) L_d(\mathbf{p}, \omega_i) |\cos \theta_i| d\omega_i$$

reflectance      lighting



# Point lights

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Classically, rendering is performed assuming point light sources



directional source



# Natural illumination

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People perceive materials more easily under natural illumination than simplified illumination.



Images courtesy Ron Dror and Ted Adelson

# Natural illumination

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Rendering with natural illumination is more expensive compared to using simplified illumination



directional source



natural illumination

# Environment maps

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Miller and Hoffman, 1984

# Acquiring the Light Probe



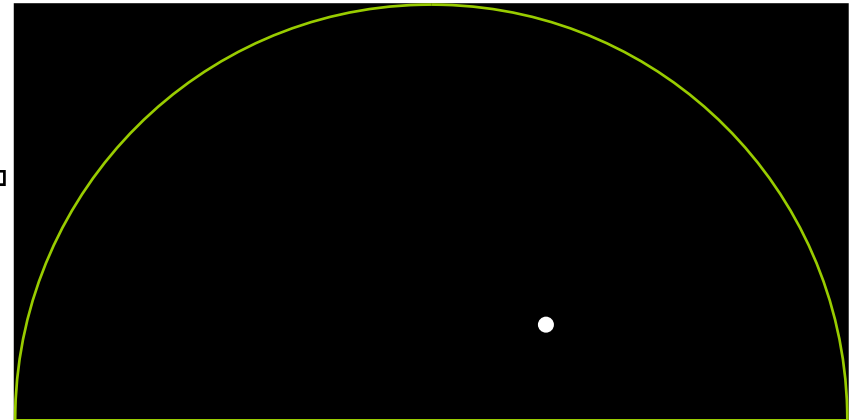
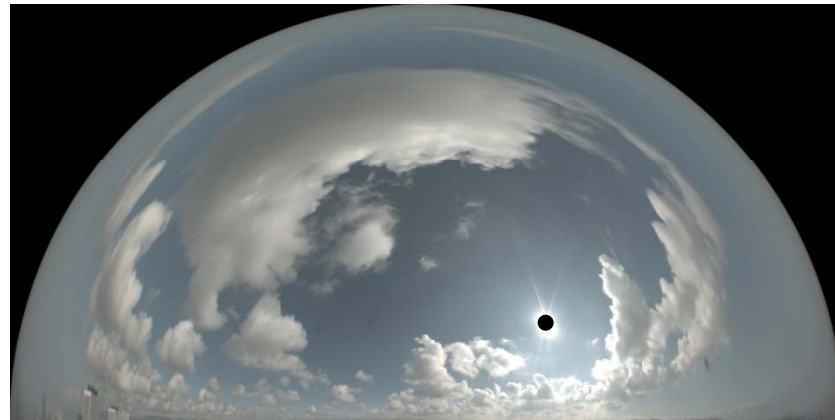
# HDRI Sky Probe

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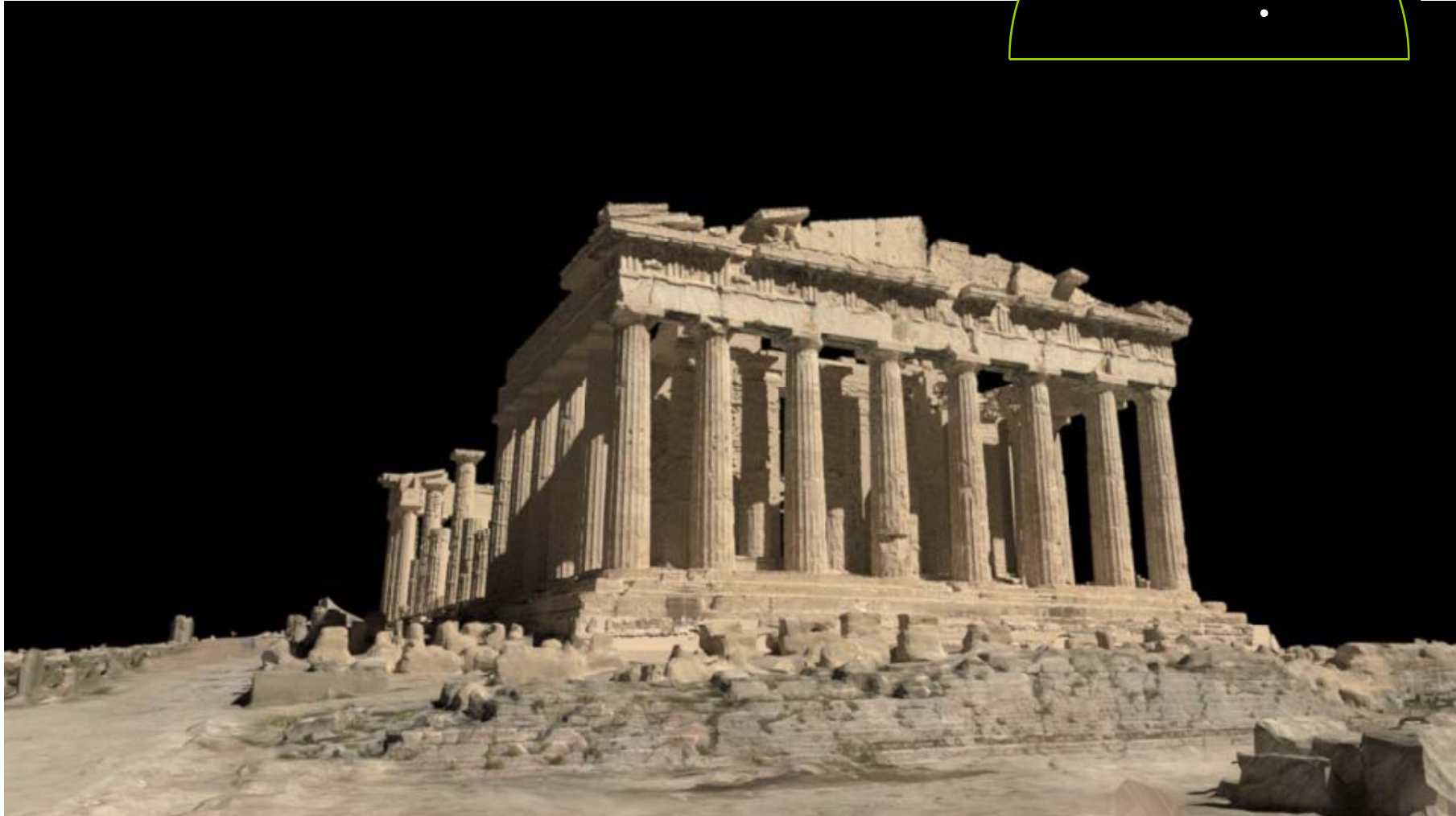
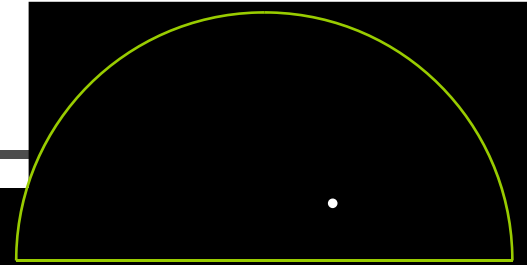
# Clipped Sky + Sun Source

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Lit by sun only

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# Lit by sky only

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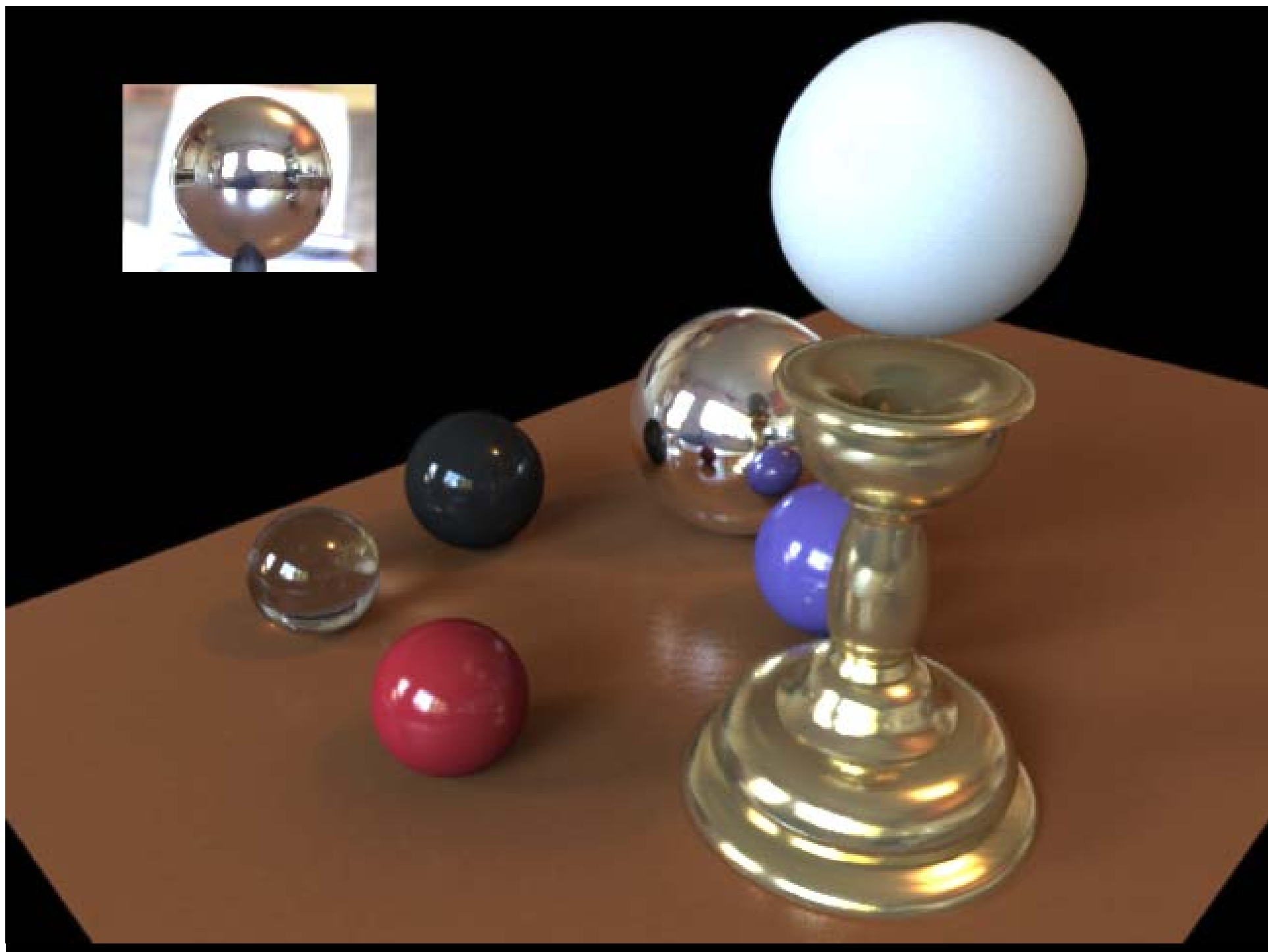
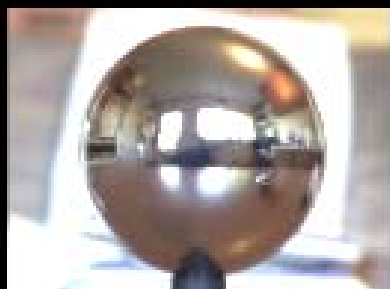


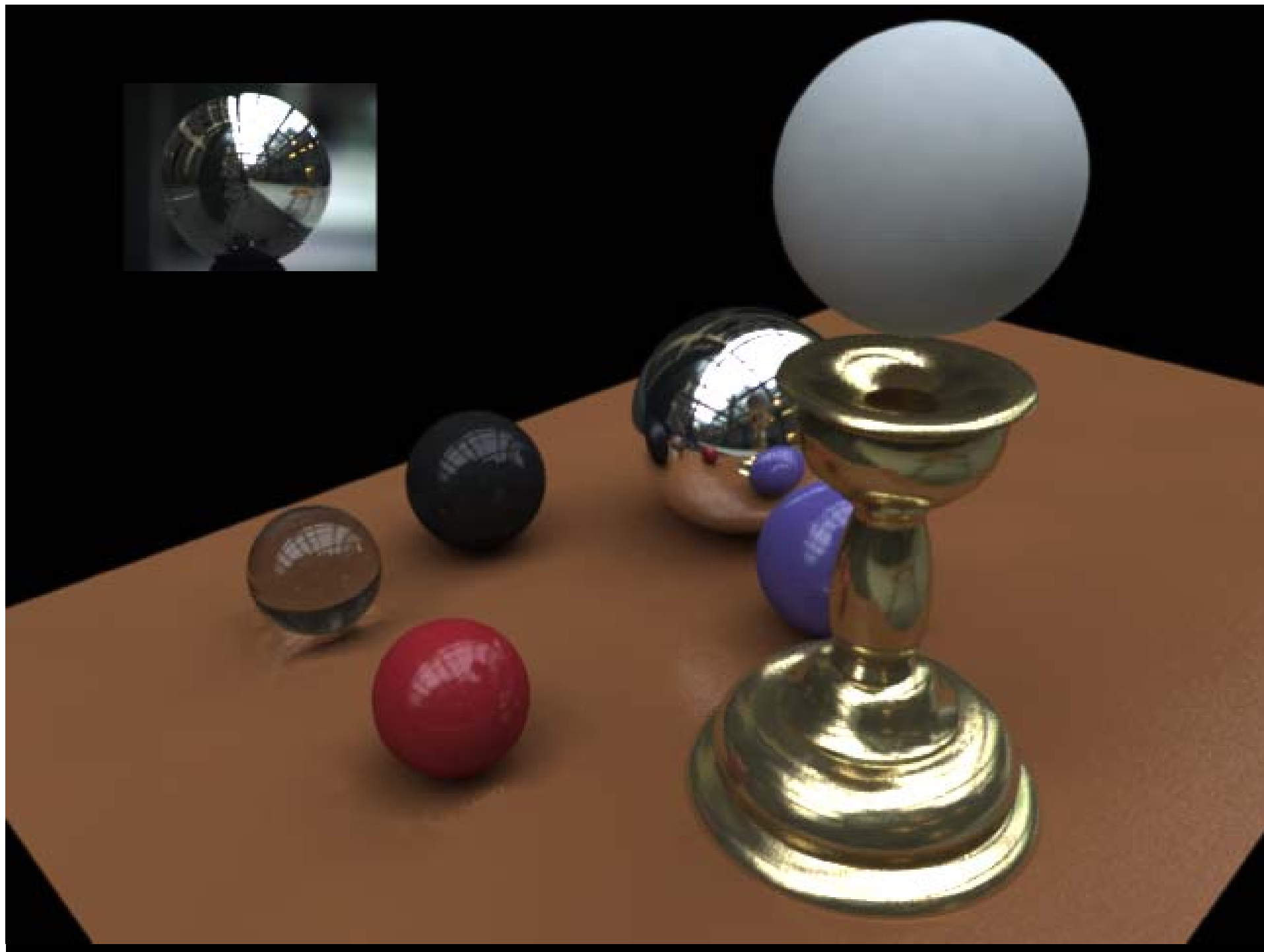


# Lit by sun and sky

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# Real Scene Example

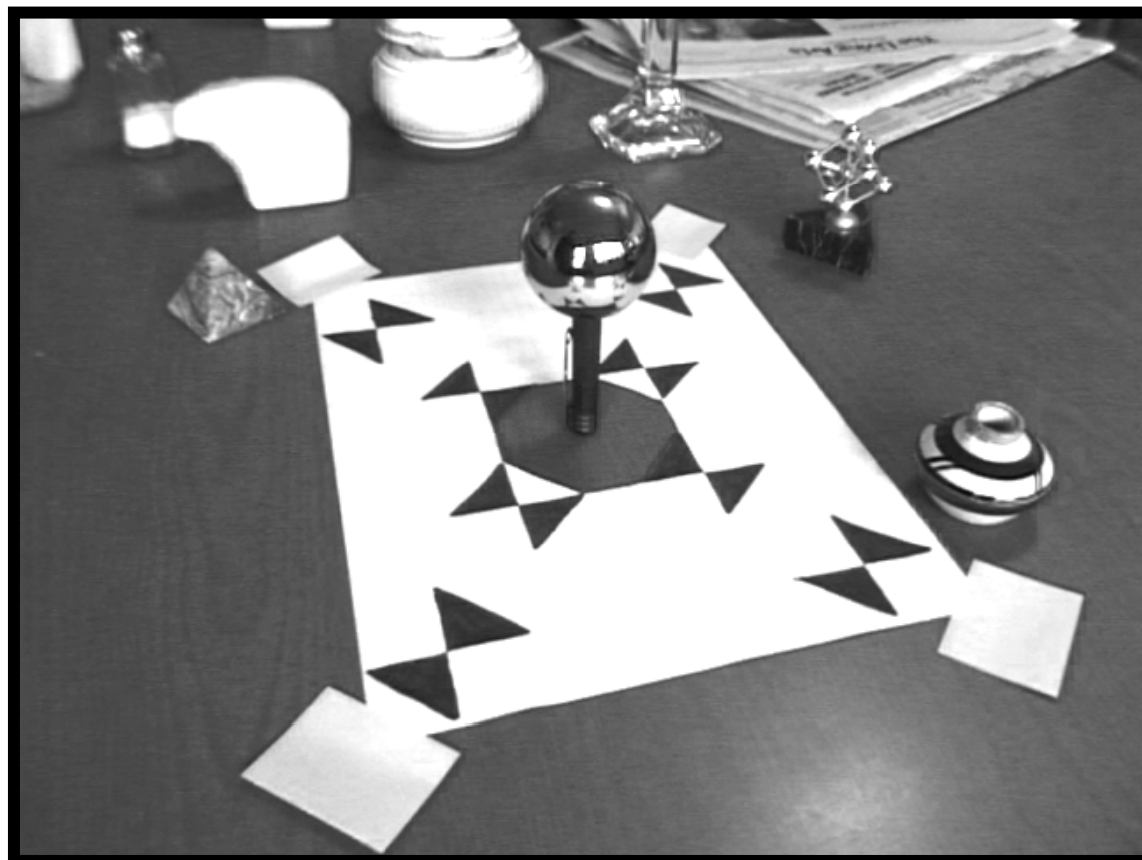
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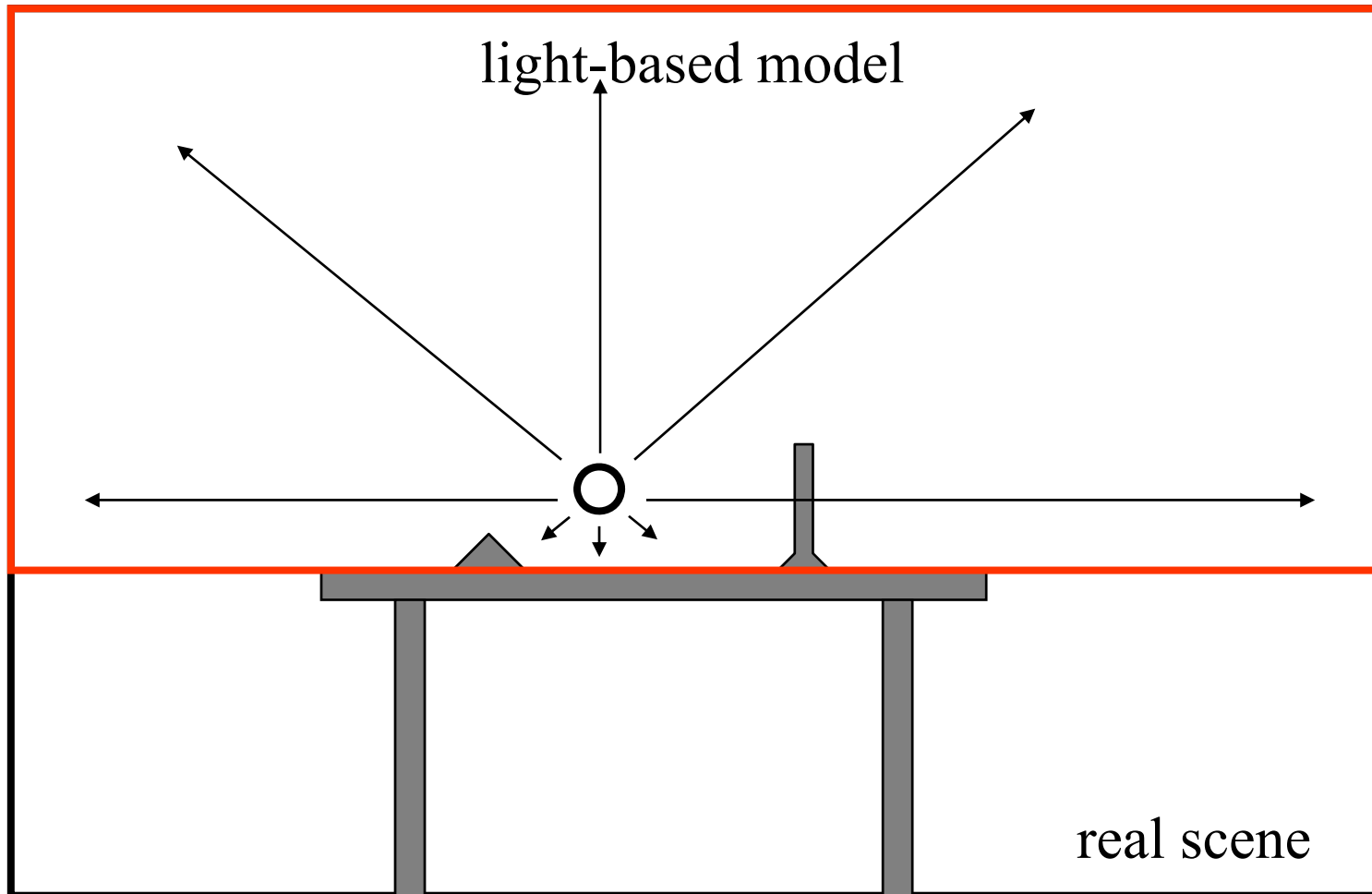
- Goal: place synthetic objects on table

# Light Probe / Calibration Grid

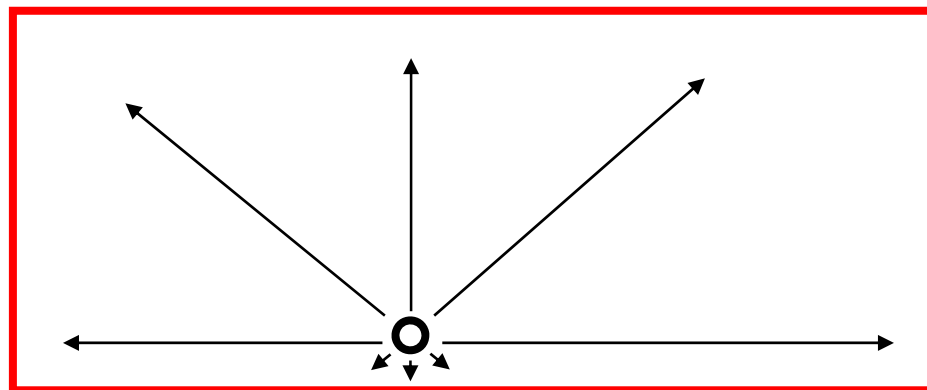
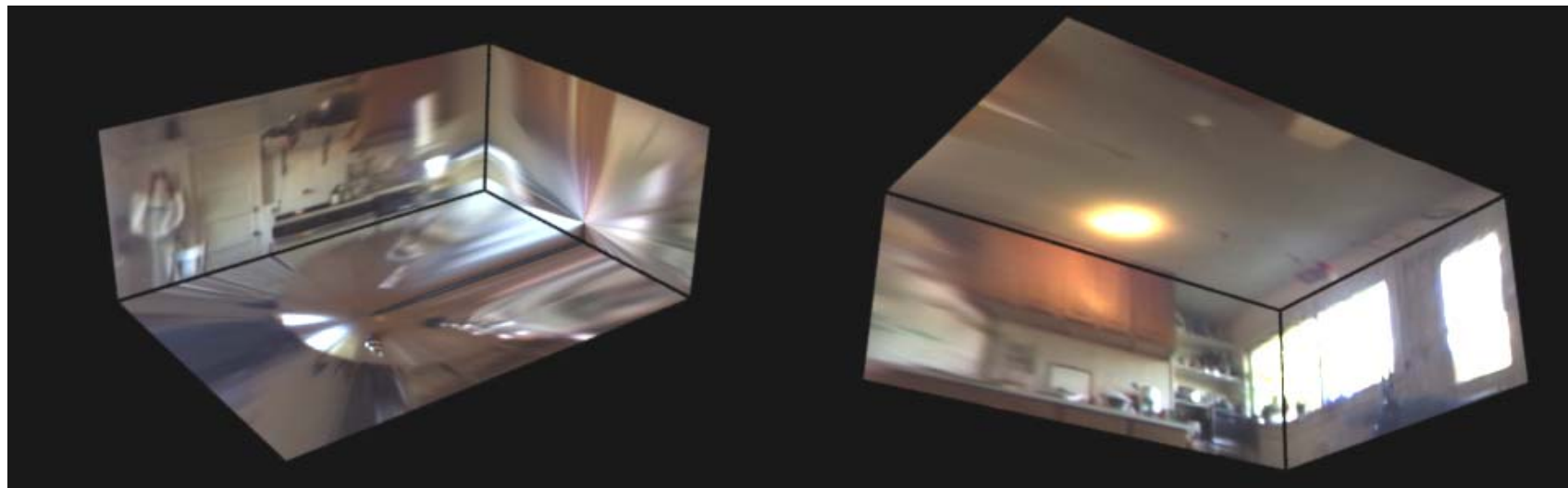
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# Modeling the Scene



# The *Light-Based* Room Model



# Rendering into the Scene

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- Background Plate



# Rendering into the scene

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- Objects and Local Scene matched to Scene

# Differential rendering

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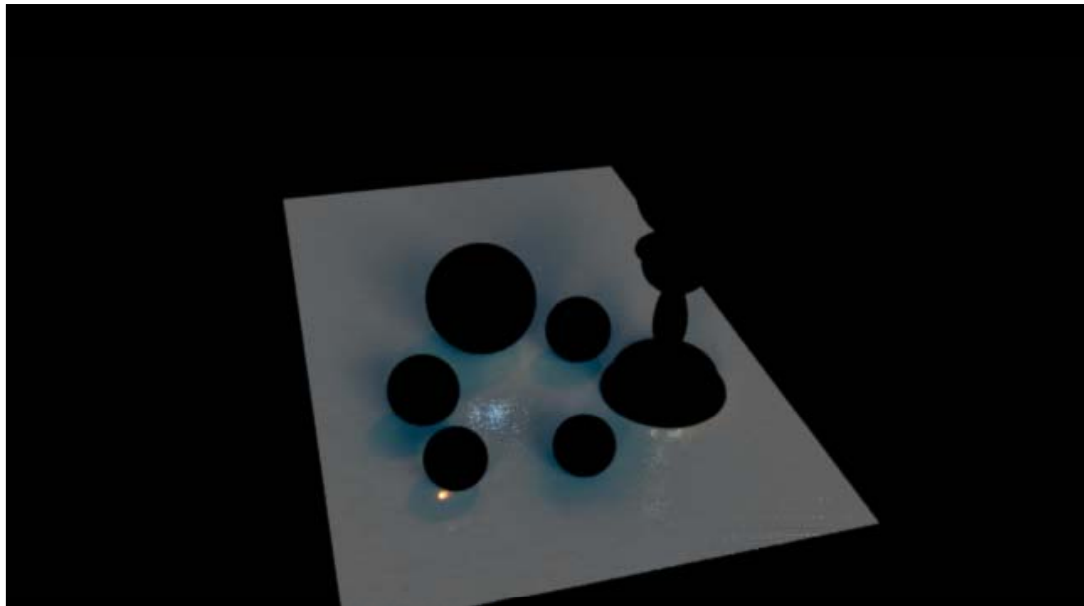
- Local scene w/o objects, illuminated by model

# Differential rendering

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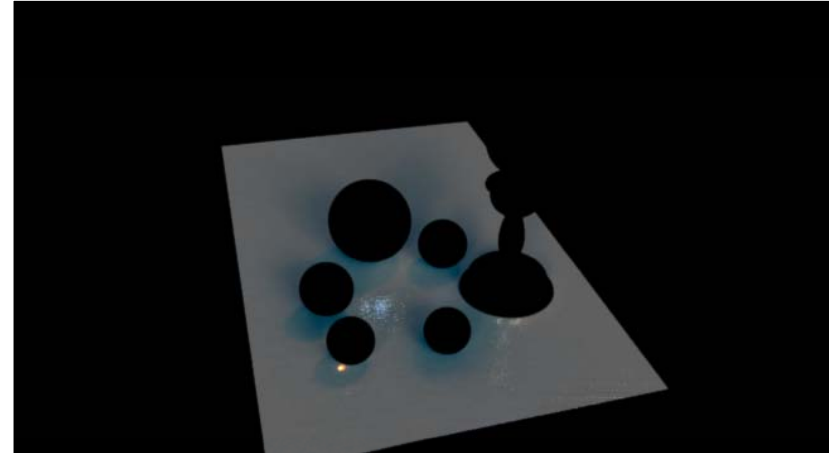
-



# Differential rendering



+





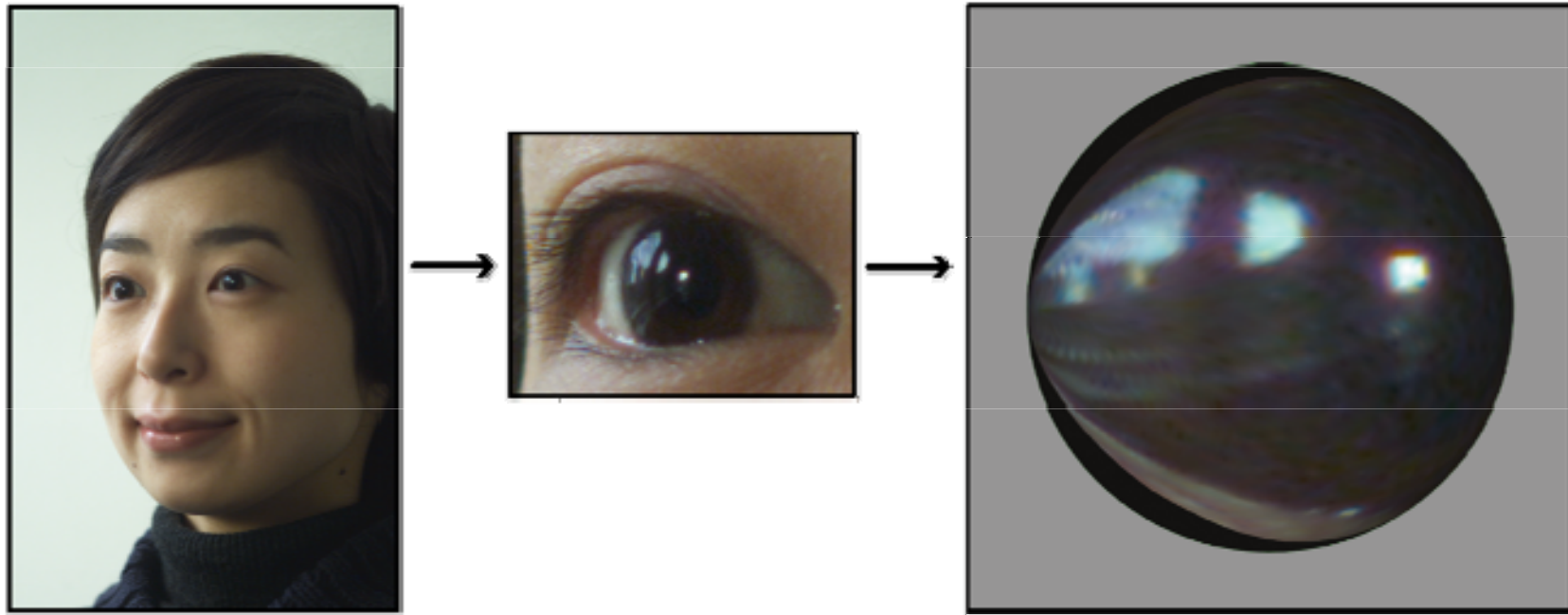
# Environment map from single image?

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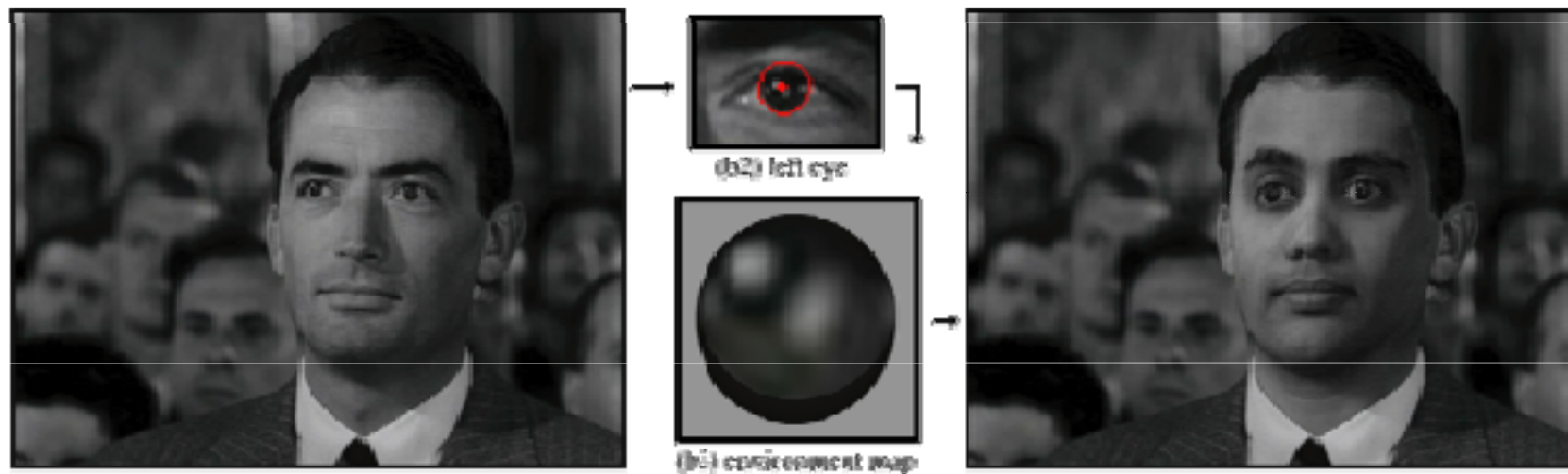
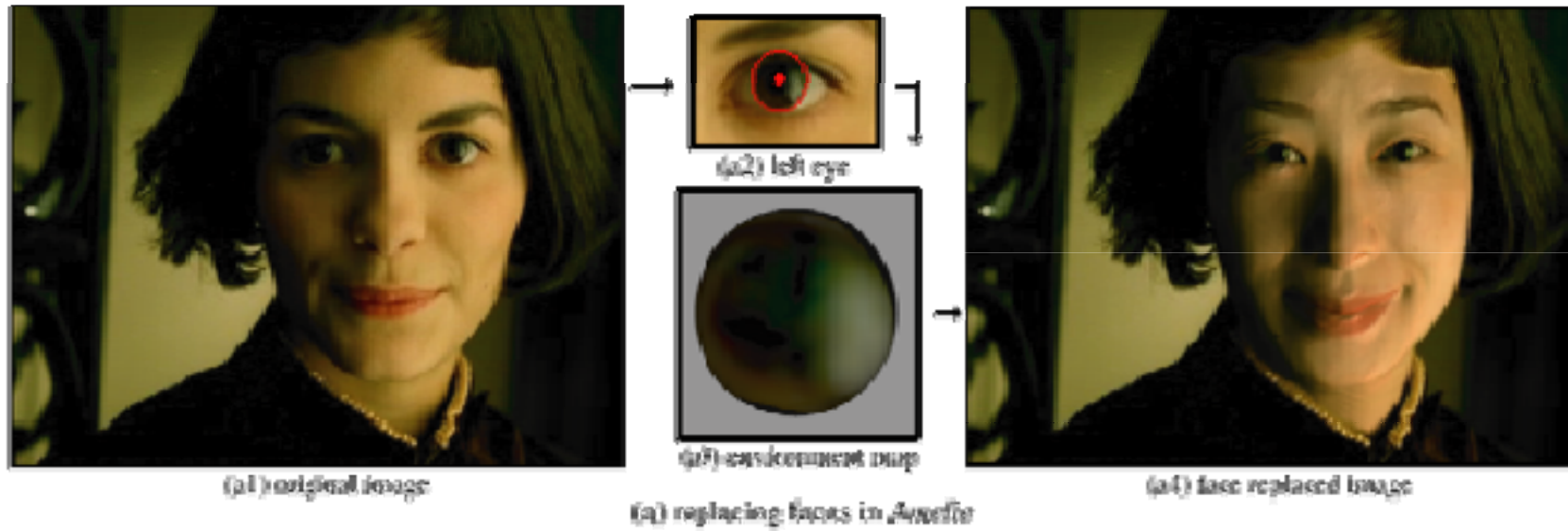


# Eye as light probe! (Nayar et al)

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# Results



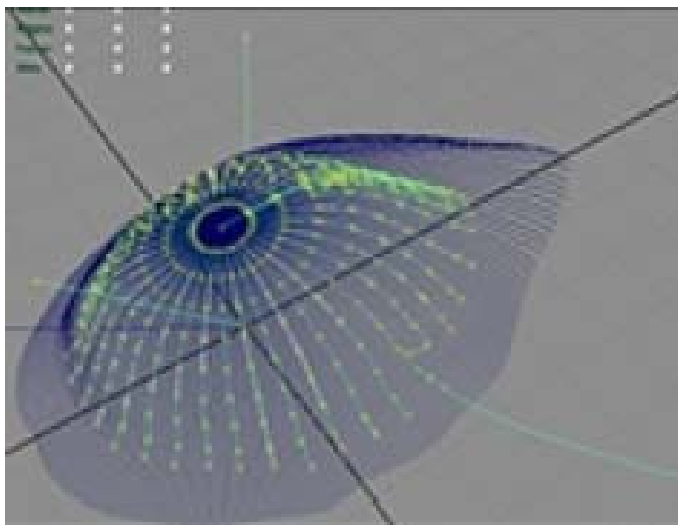


# Application in "Superman returns"

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# Capturing reflectance



# Application in "The Matrix Reloaded"



# 3D acquisition for faces

# Cyberware scanners

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face & head scanner



whole body scanner

# Making facial expressions from photos

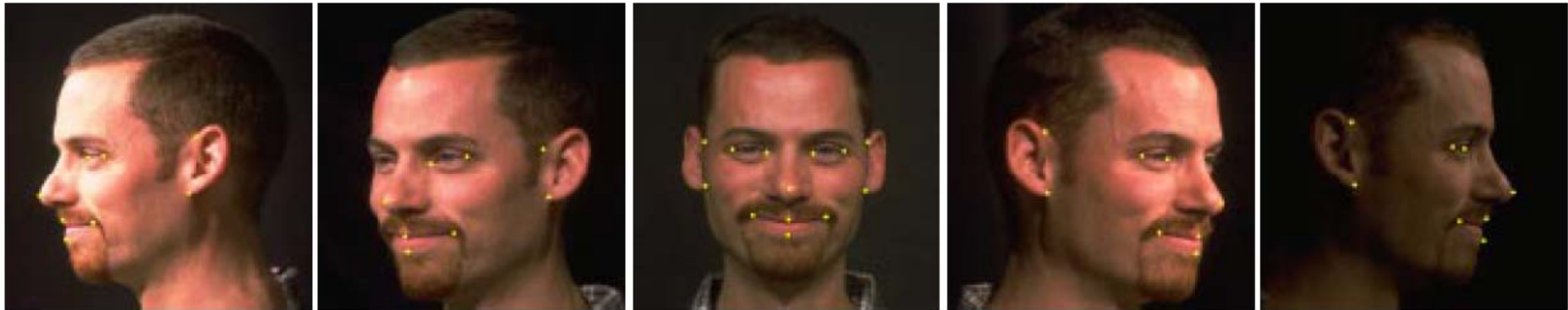
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- Similar to Façade, use a generic face model and view-dependent texture mapping
- Procedure
  1. Take multiple photographs of a person
  2. Establish corresponding feature points
  3. Recover 3D points and camera parameters
  4. Deform the generic face model to fit points
  5. Extract textures from photos

# Reconstruct a 3D model

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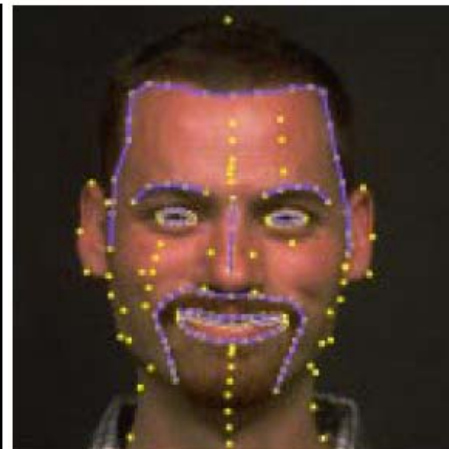
input photographs



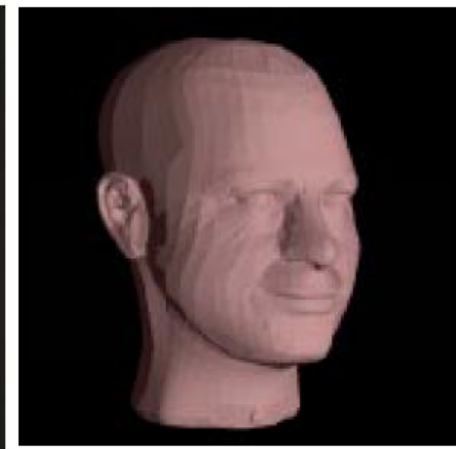
generic 3D  
face model



pose  
estimation



more  
features

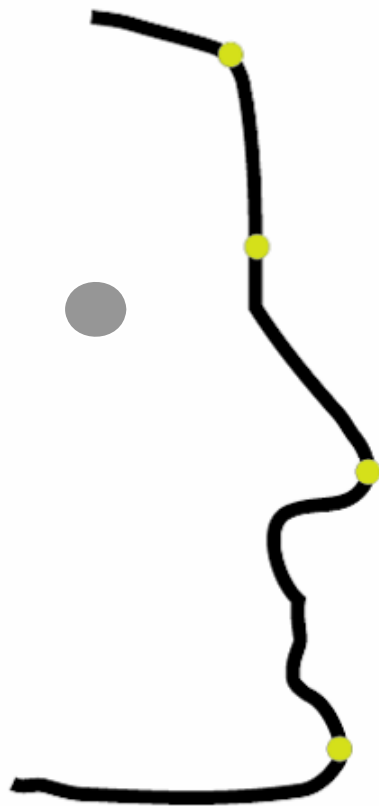


deformed  
model

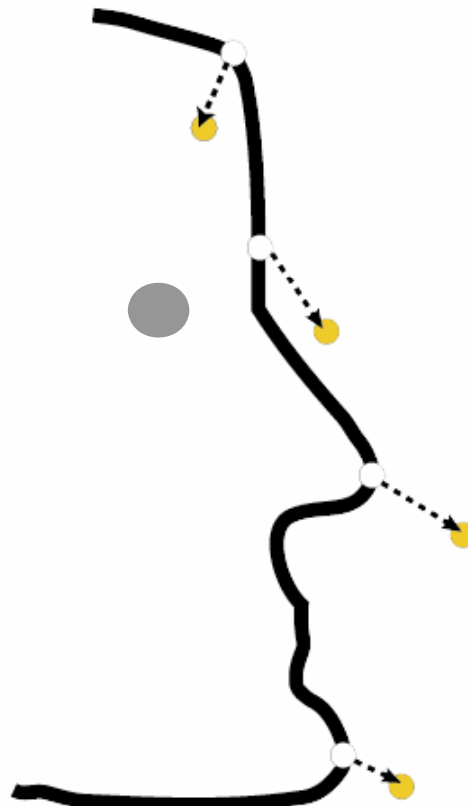
# Mesh deformation

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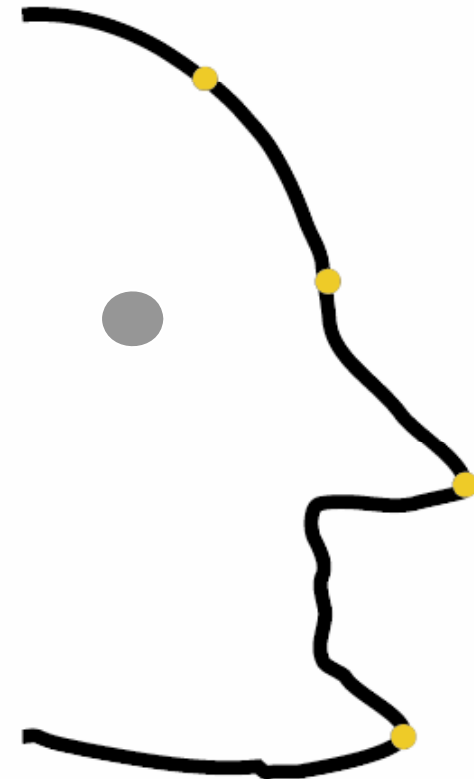
- Compute displacement of feature points
- Apply scattered data interpolation



generic model



displacement



deformed model

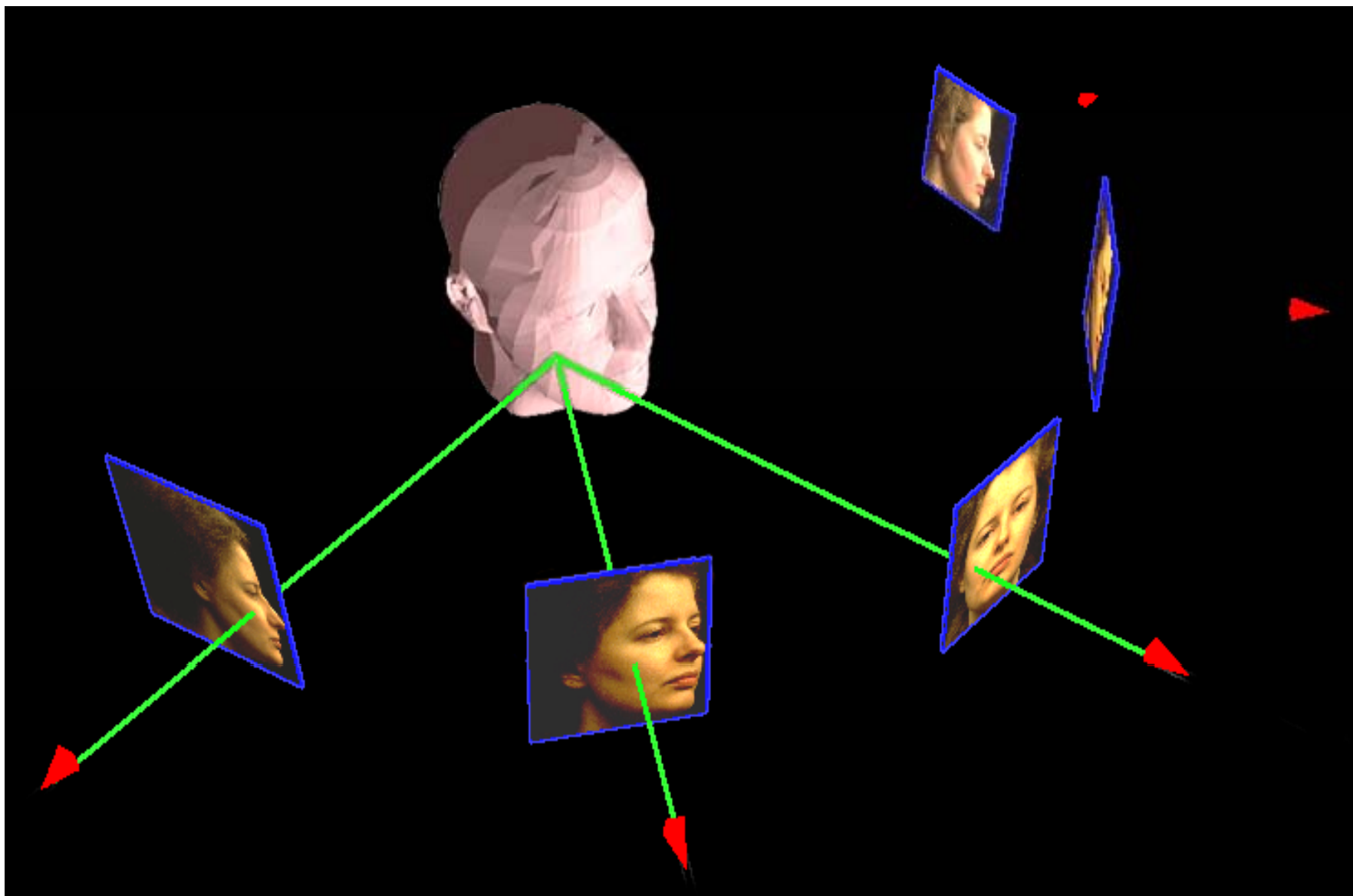


# Texture extraction

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- The color at each point is a weighted combination of the colors in the photos
- Texture can be:
  - view-independent
  - view-dependent
- Considerations for weighting
  - occlusion
  - smoothness
  - positional certainty
  - view similarity

# Texture extraction



# Texture extraction

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# Texture extraction

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view-independent



view-dependent

# Model reconstruction

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Use images to adapt a generic face model.

# Creating new expressions

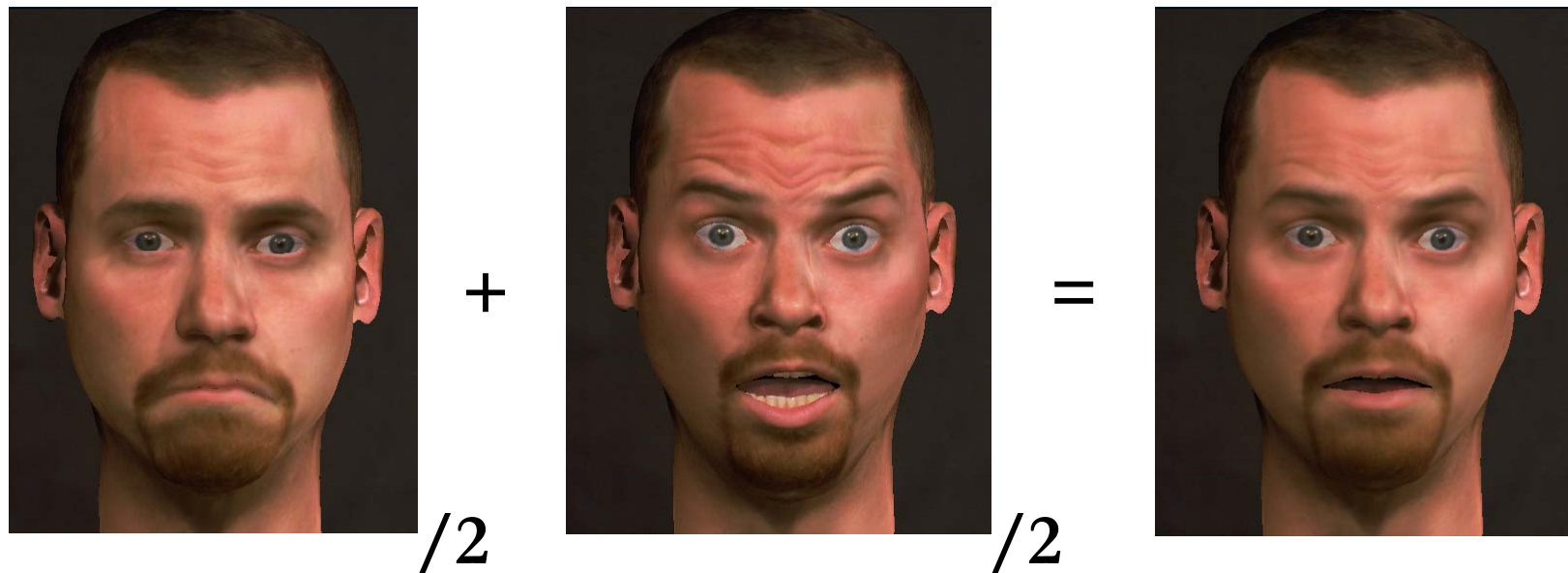
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- In addition to global blending we can use:
  - Regional blending
  - Painterly interface

# Creating new expressions

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New expressions are created with 3D morphing:



Applying a global blend

# Creating new expressions

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X



X

+

=

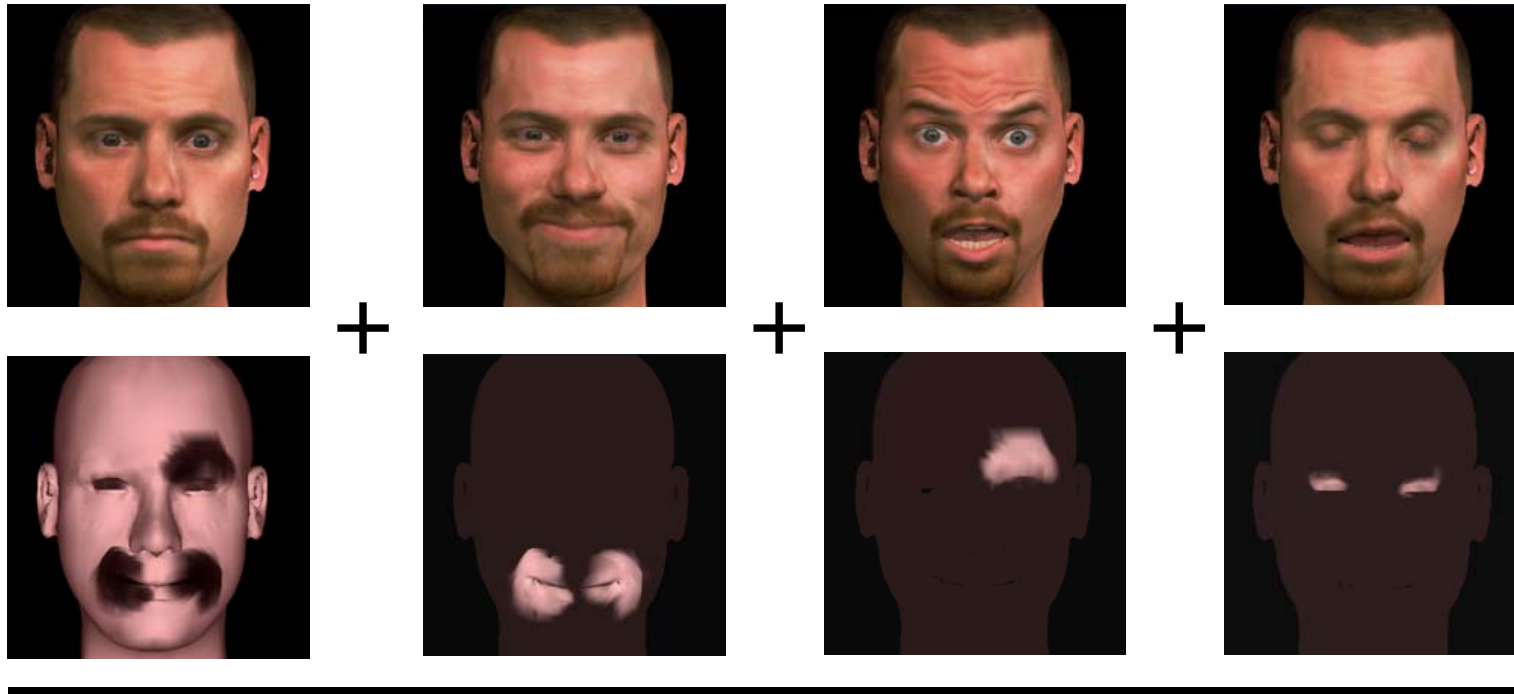


Applying a region-based blend

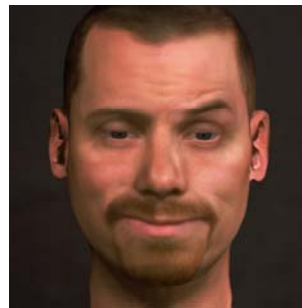


# Creating new expressions

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Using a painterly interface

# Drunken smile

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# Animating between expressions

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Morphing over time creates animation:



“neutral”



“joy”

# Video

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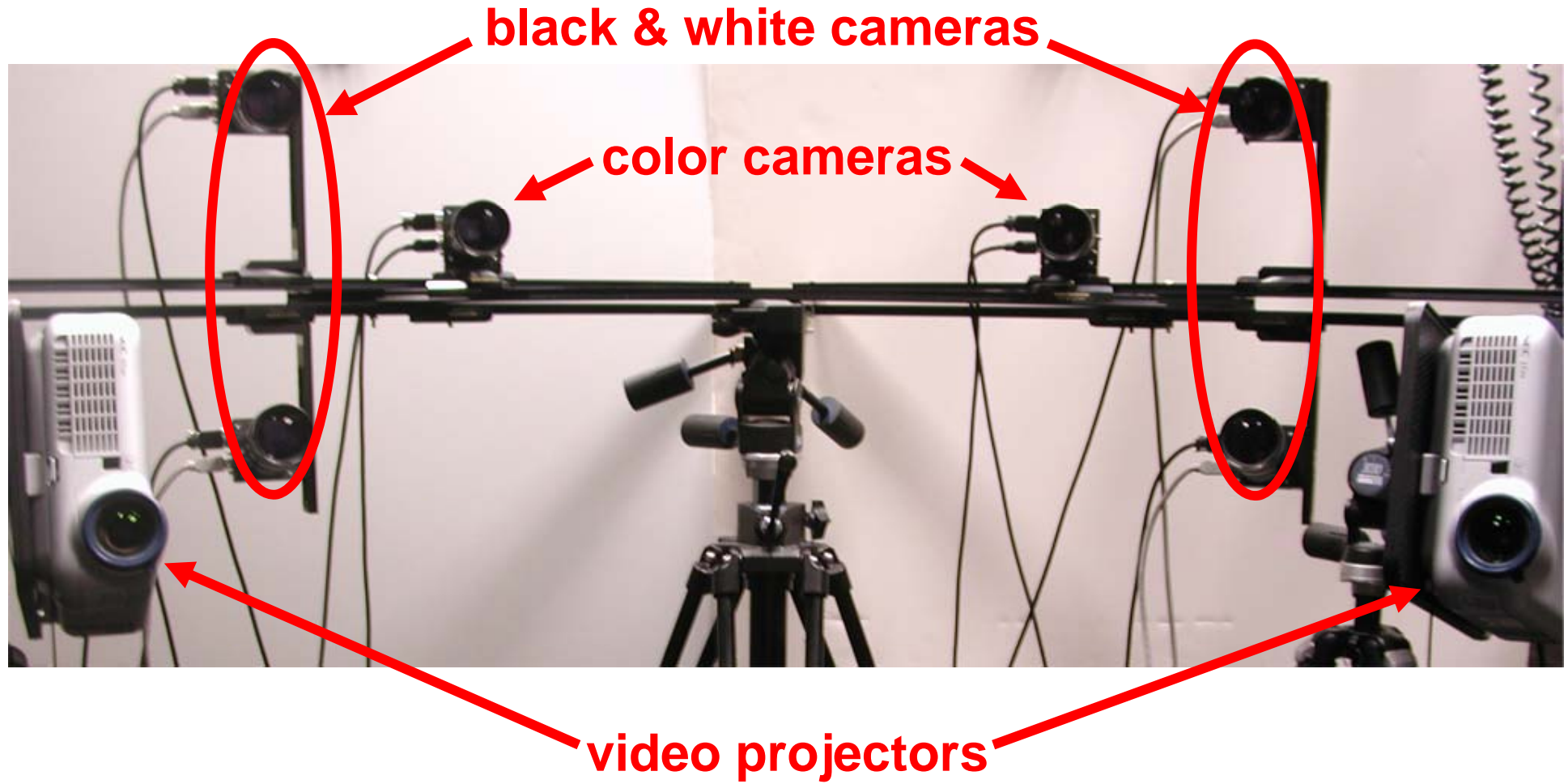
# Spacetime faces

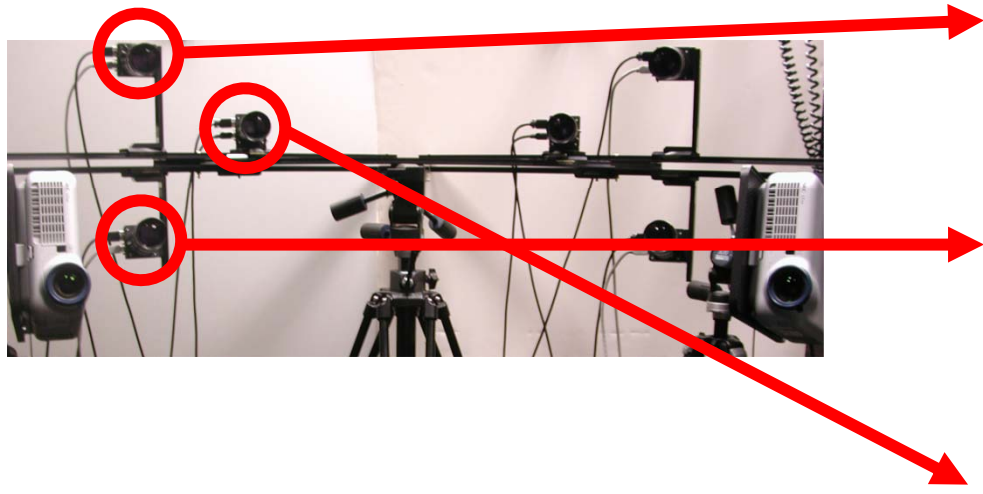
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# Spacetime faces

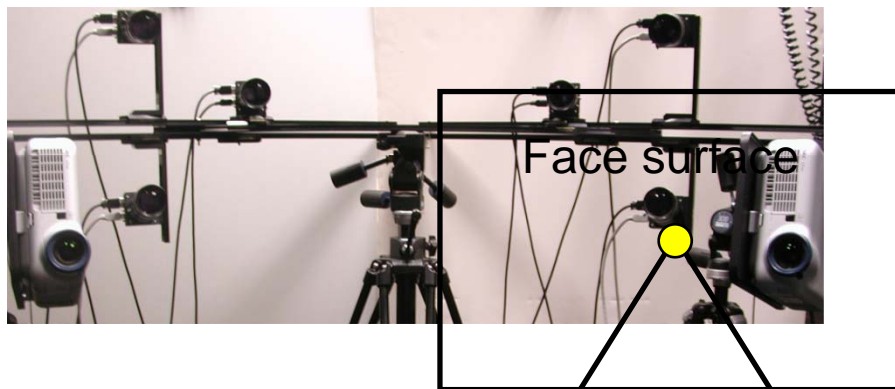
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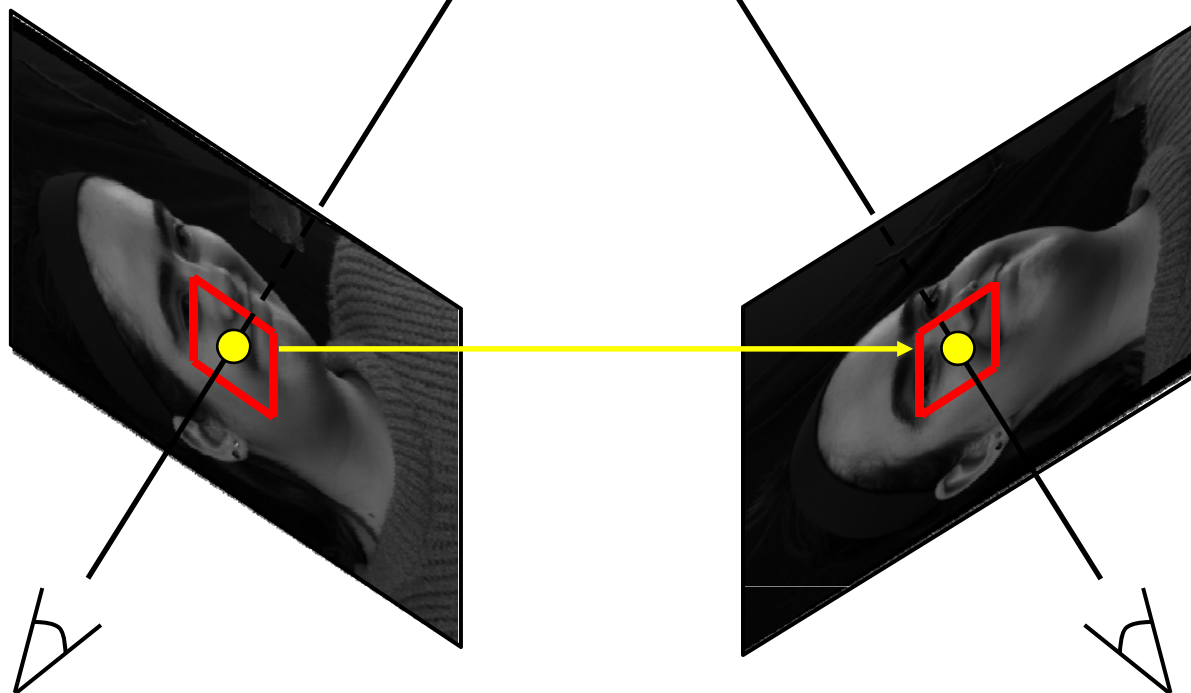


time →



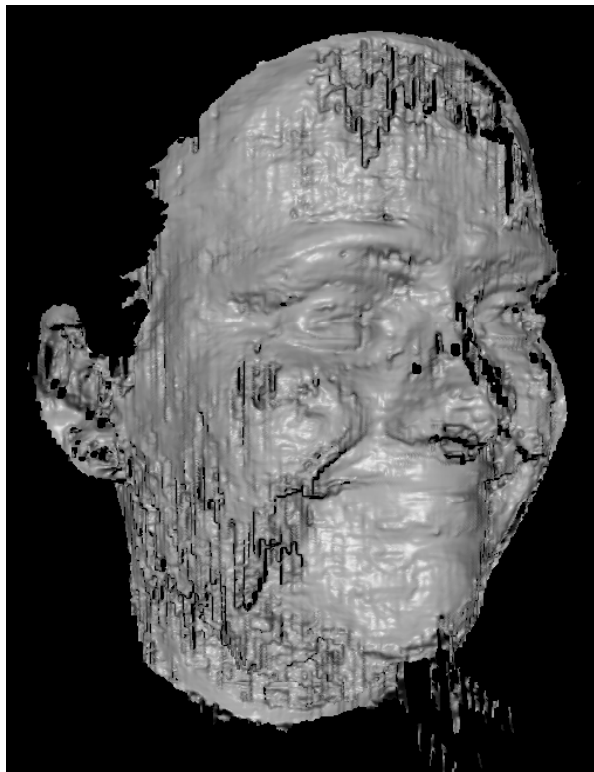


time →



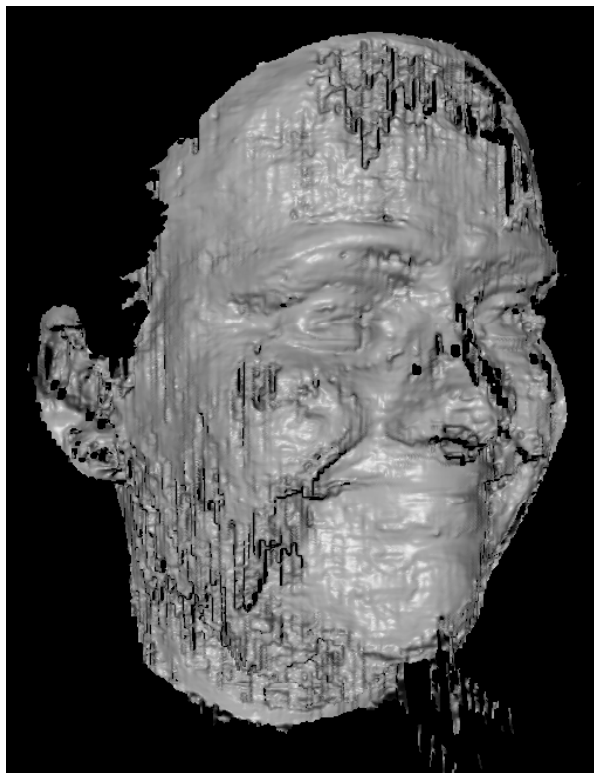


time →

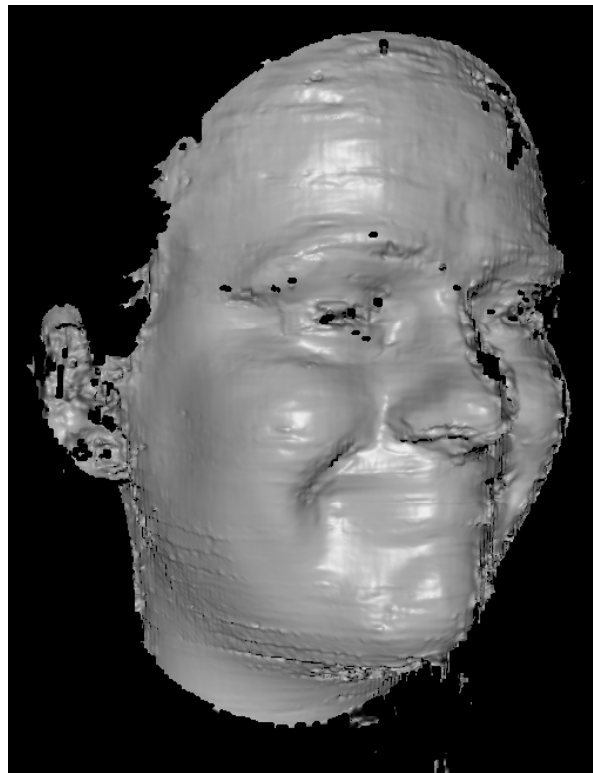


stereo

time →

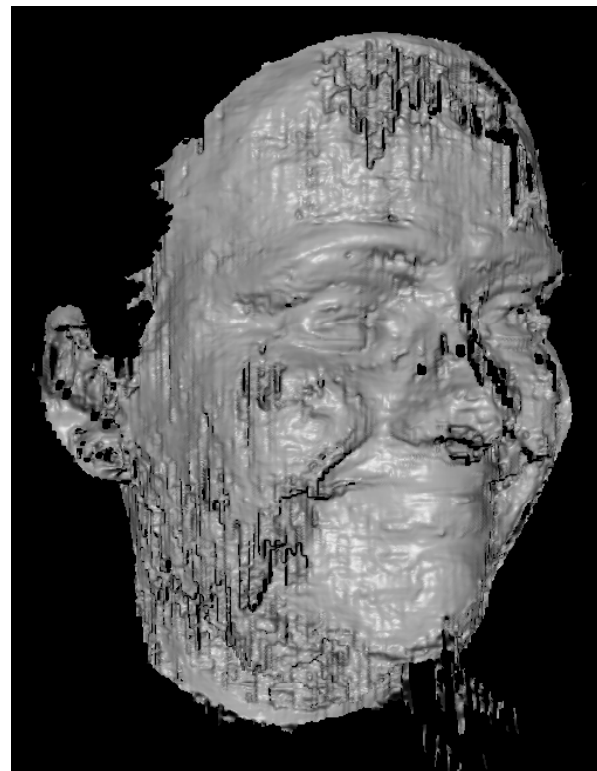


stereo

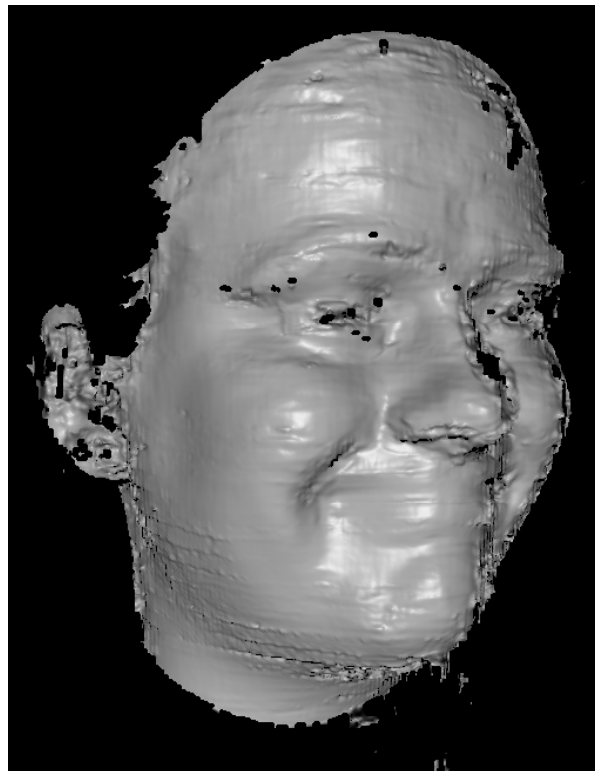


active stereo

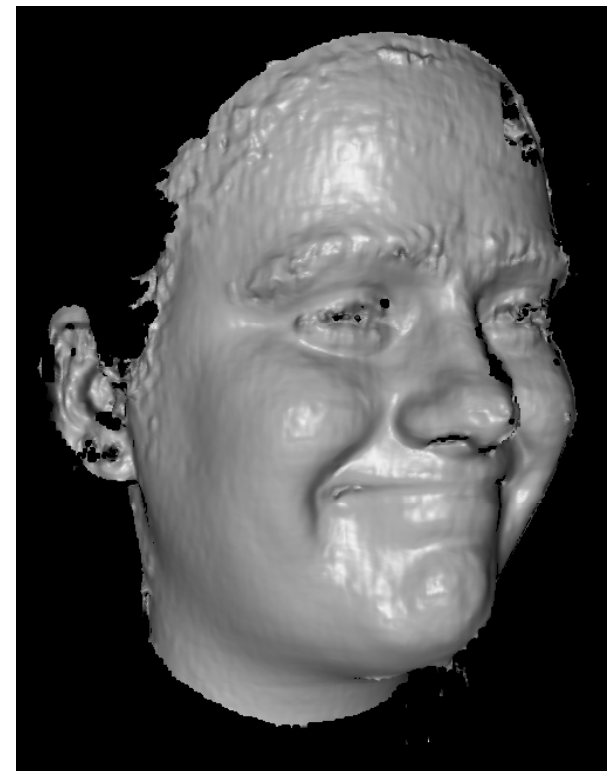
time →



stereo

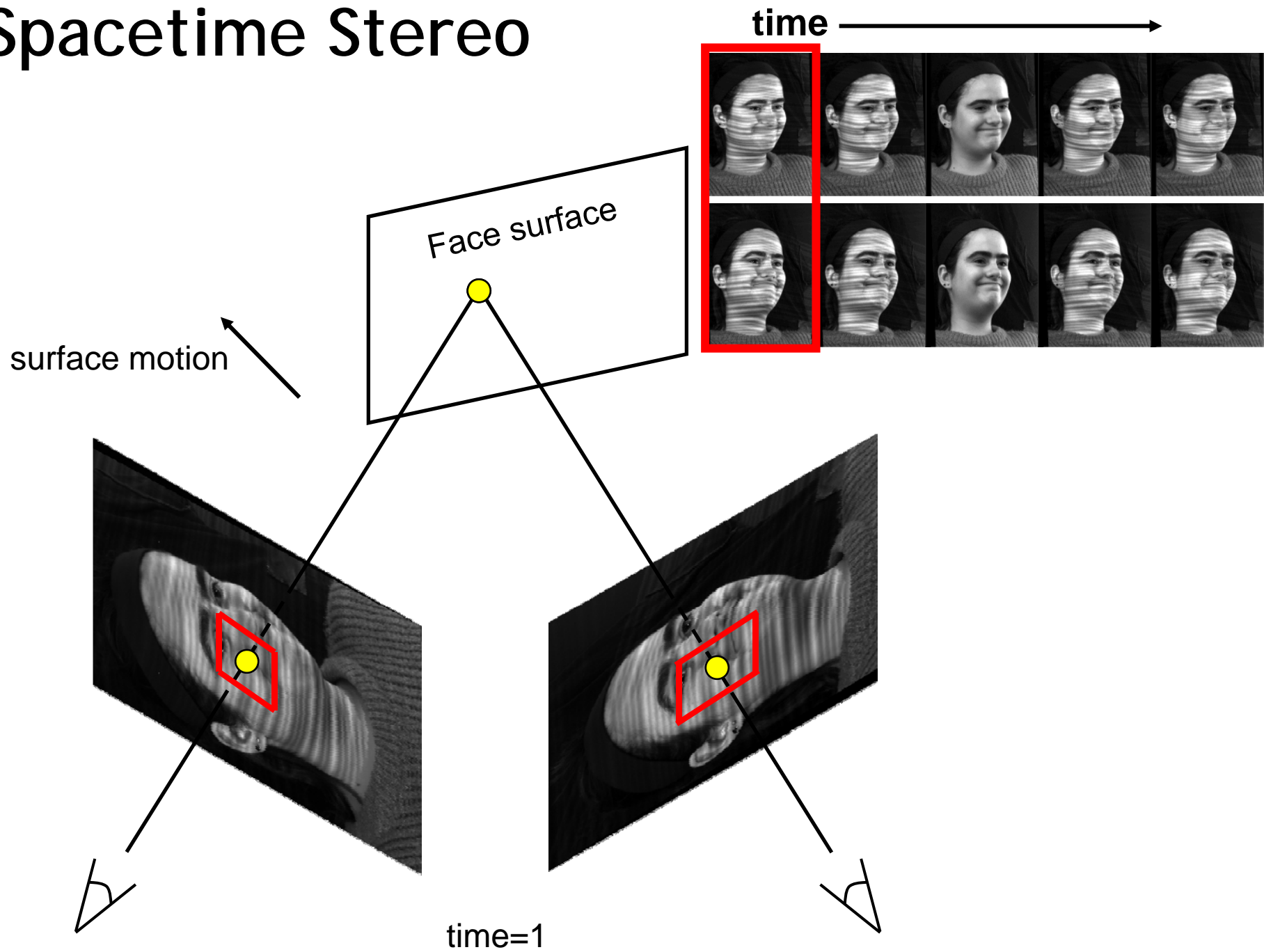


active stereo

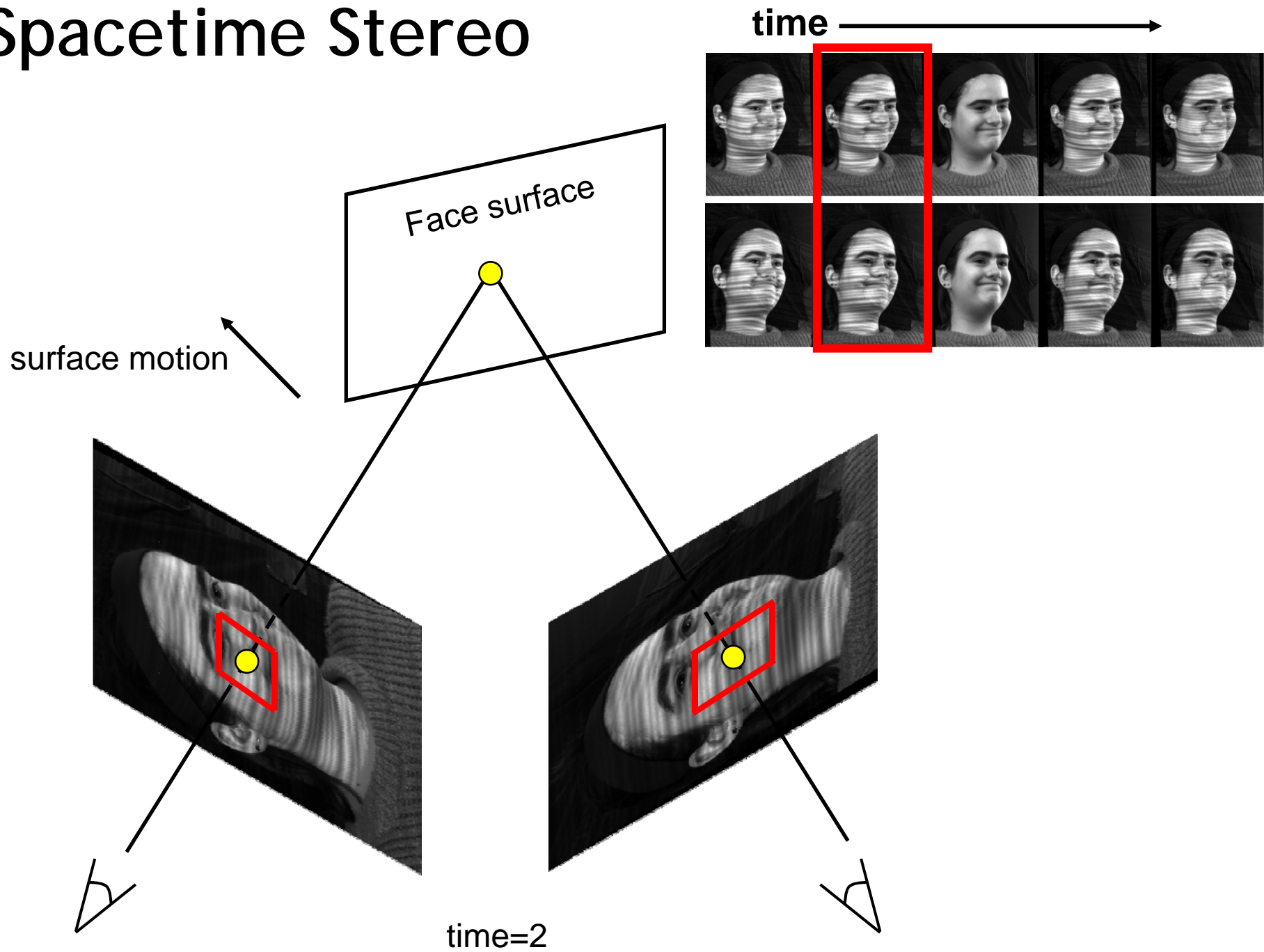


spacetime stereo

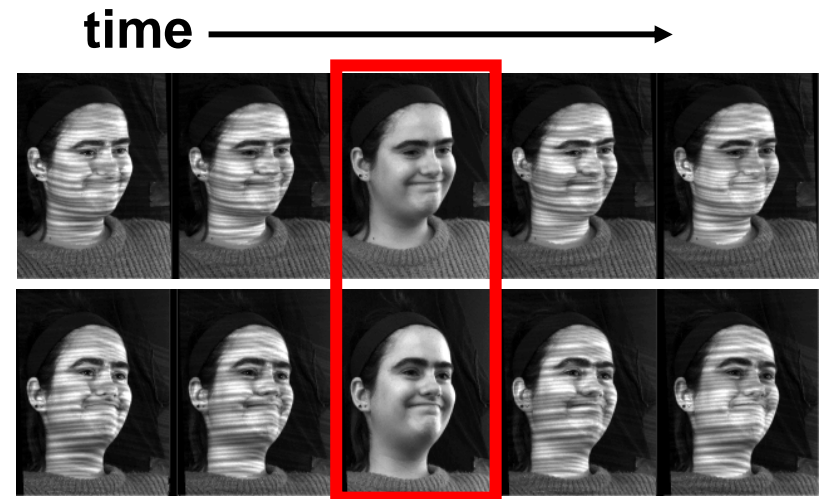
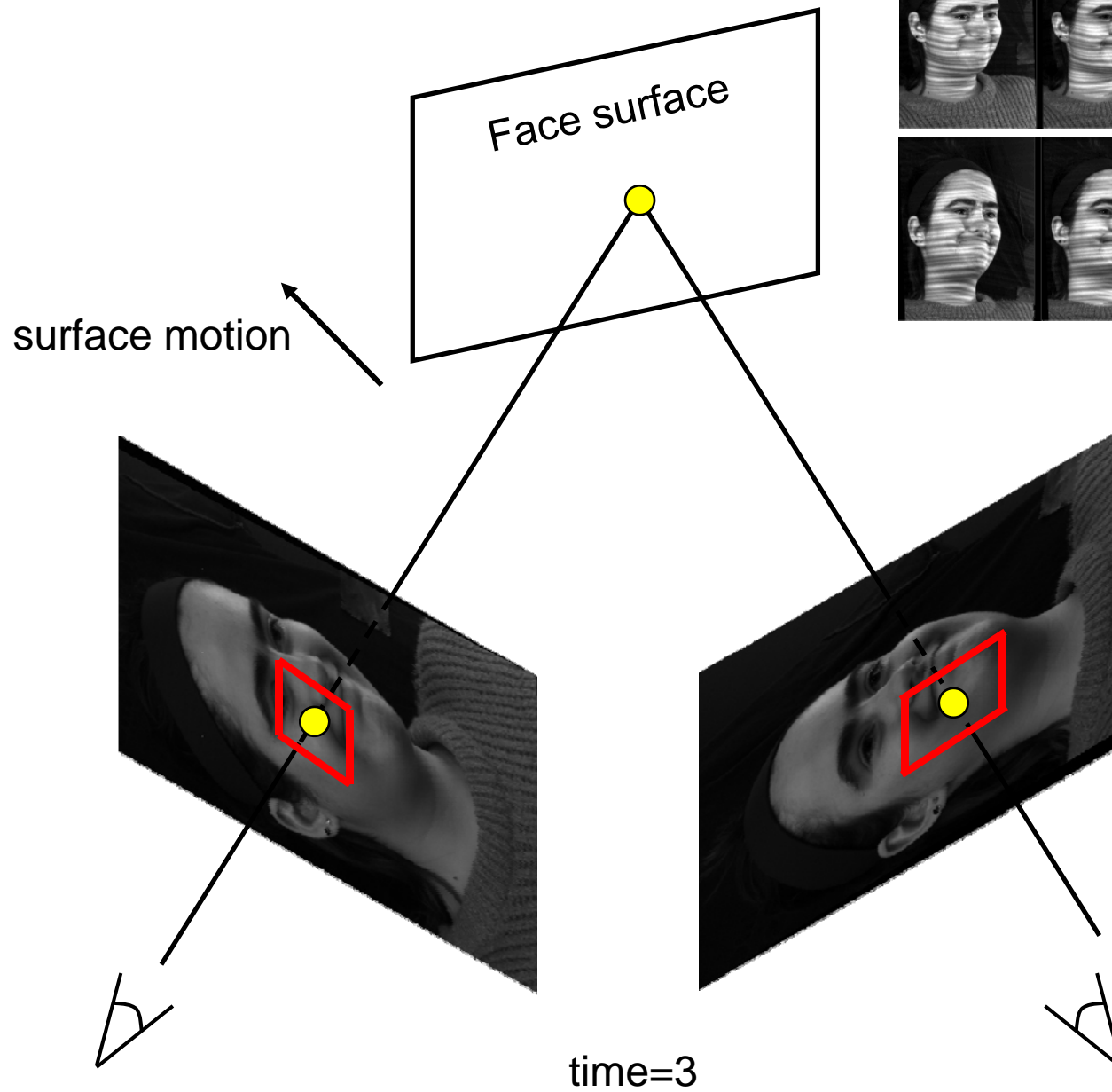
# Spacetime Stereo



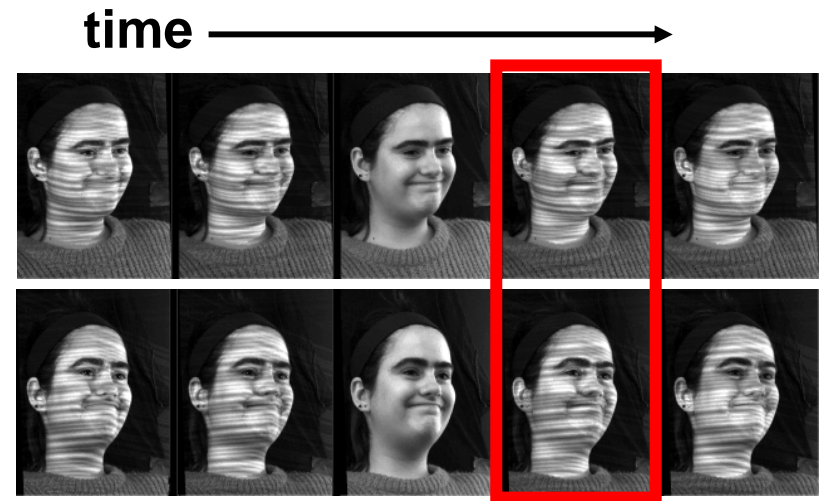
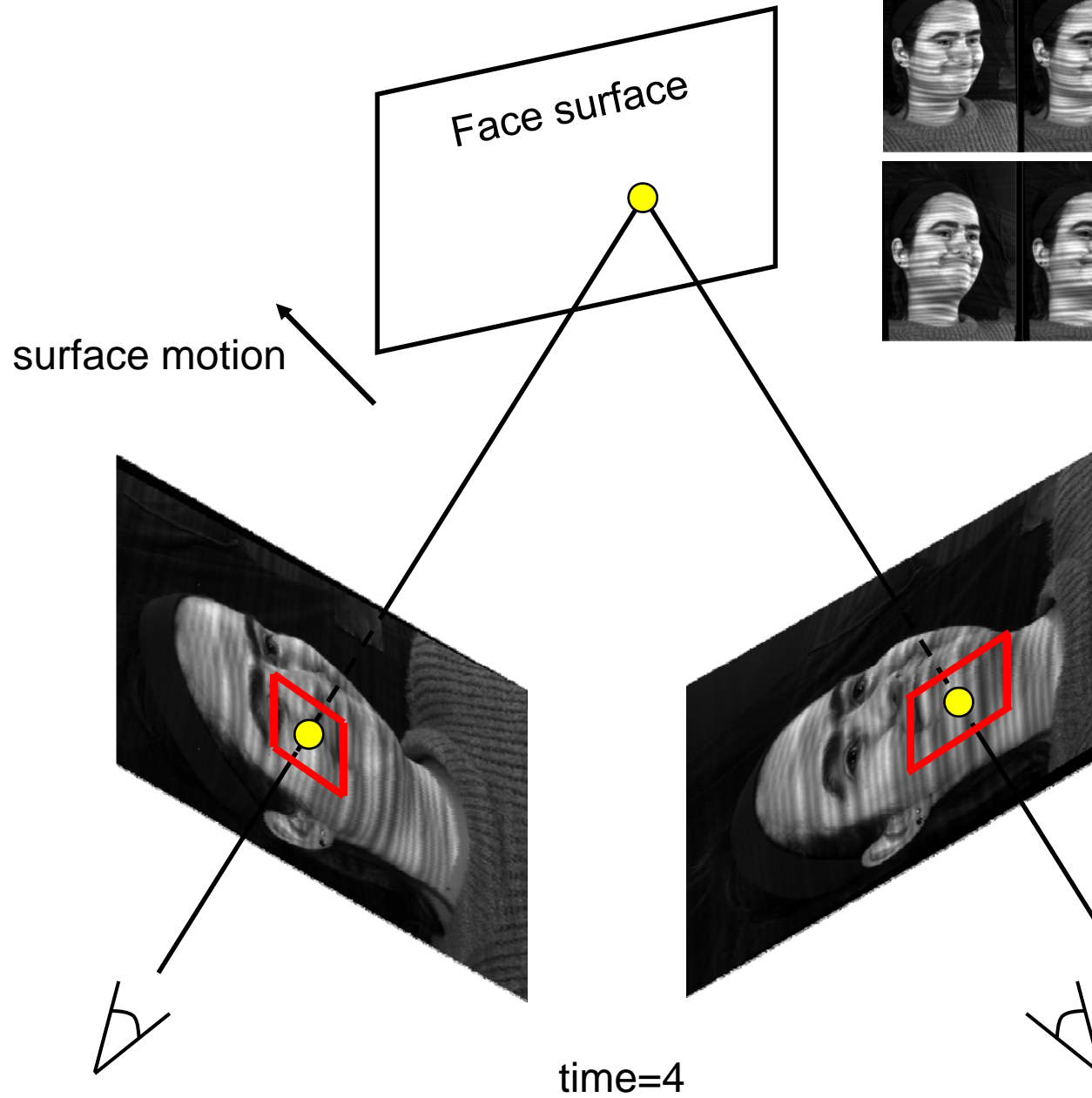
# Spacetime Stereo



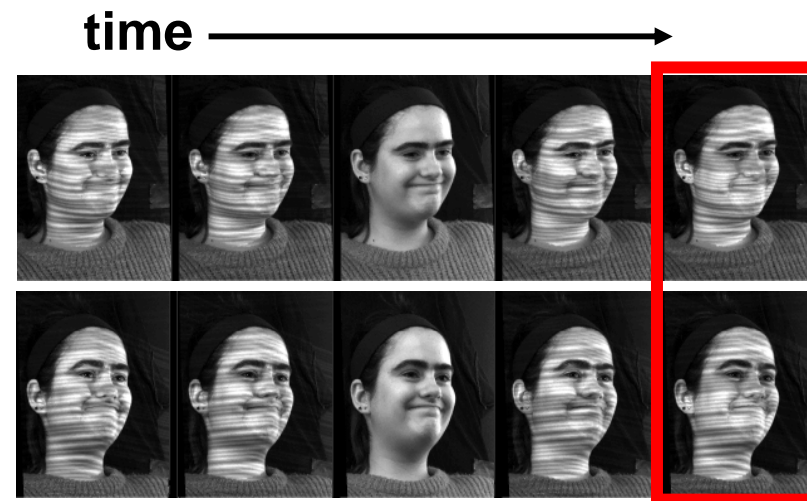
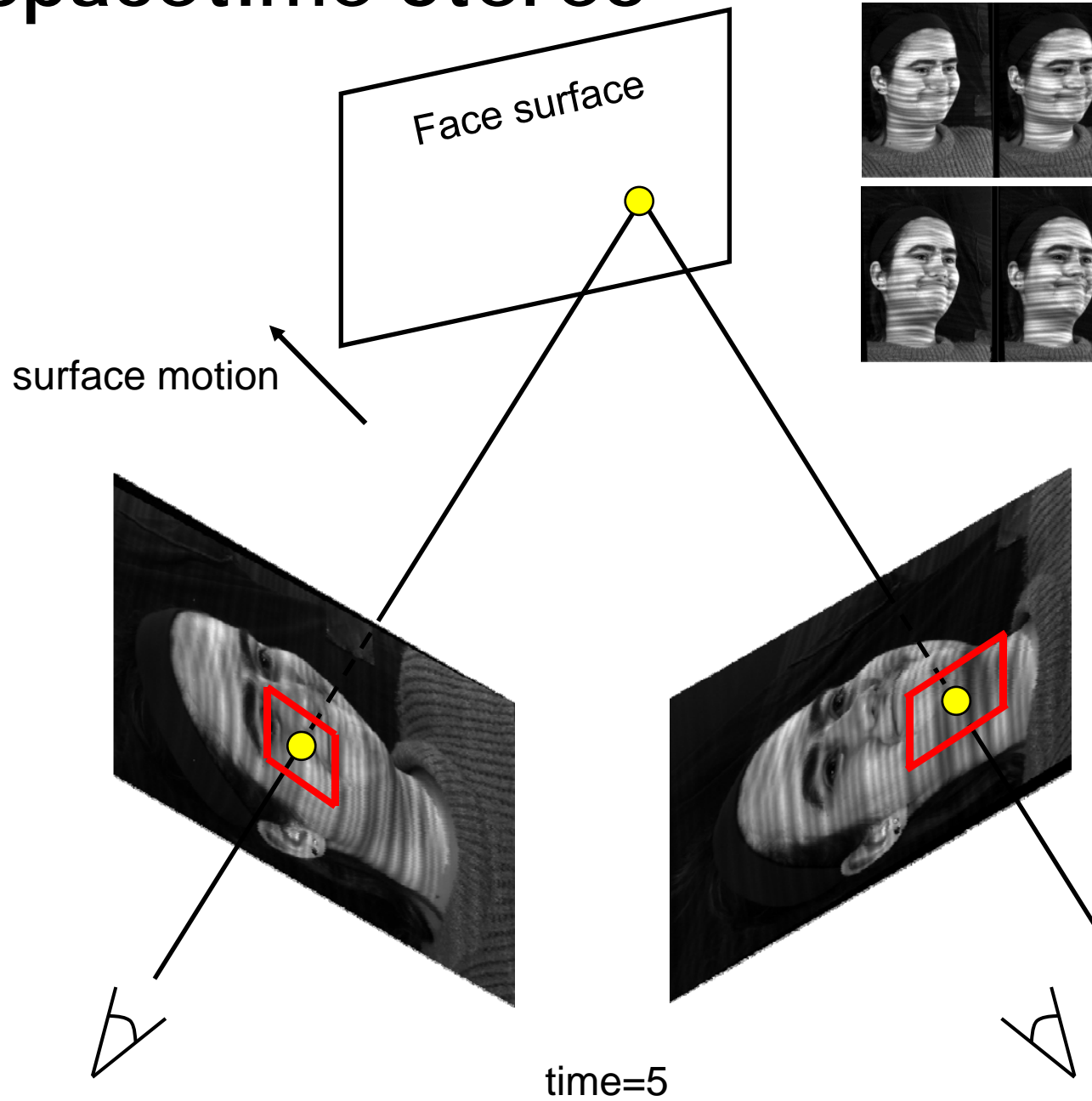
# Spacetime Stereo



# Spacetime Stereo

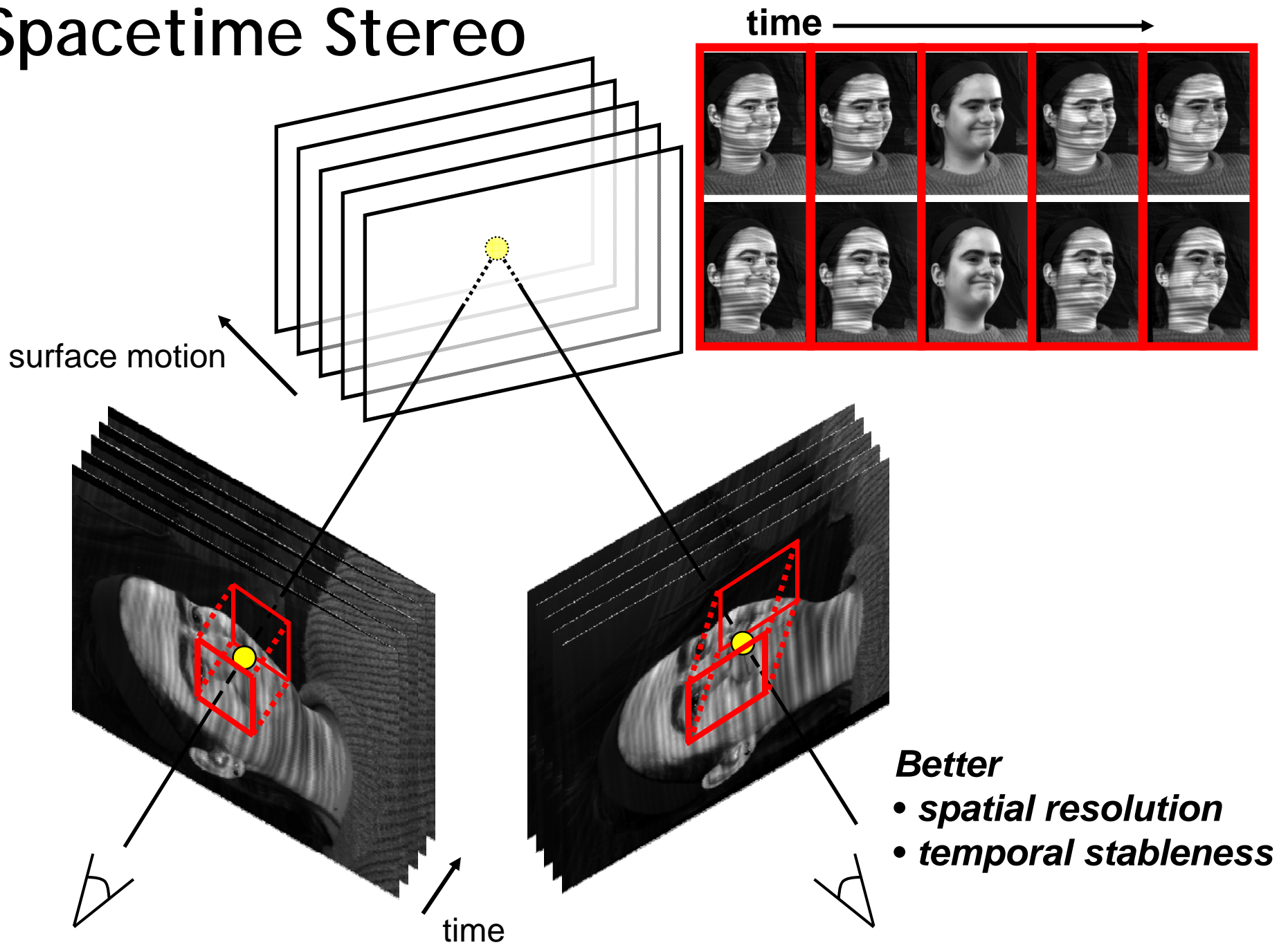


# Spacetime Stereo



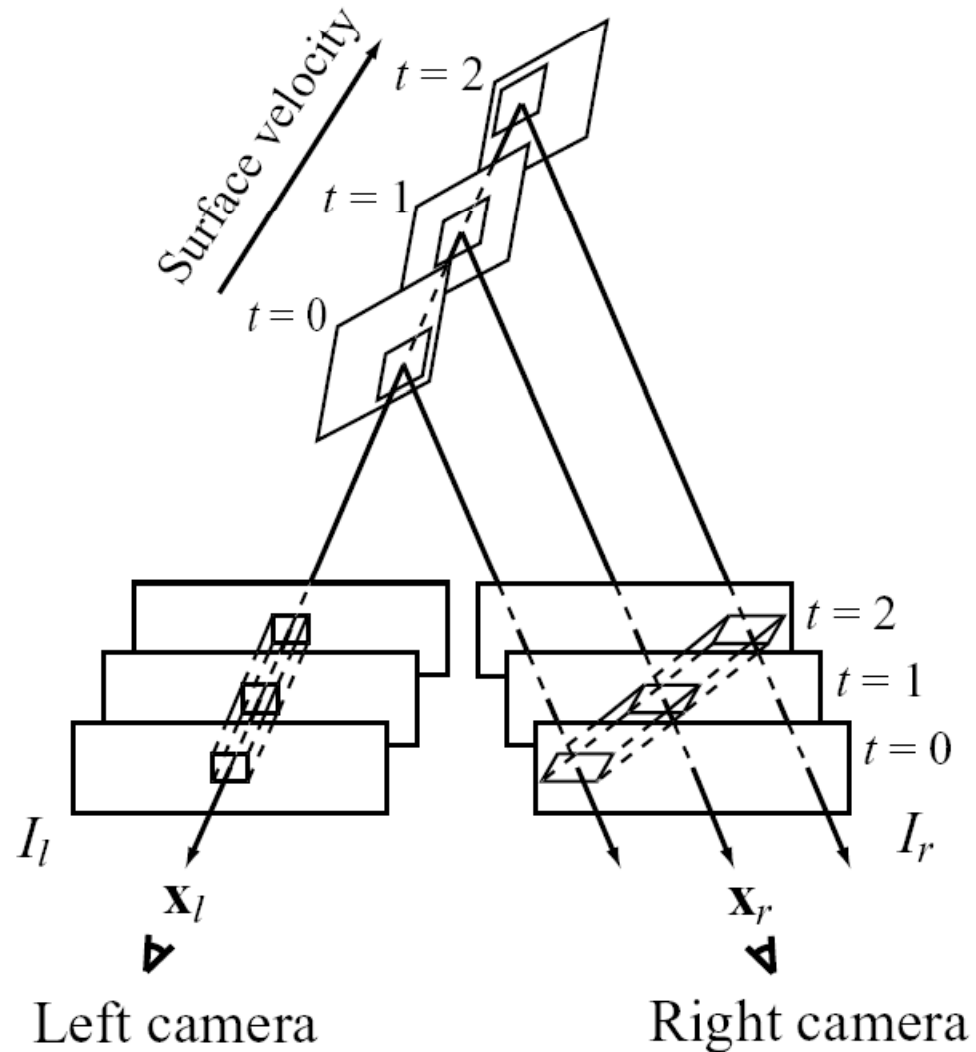


# Spacetime Stereo

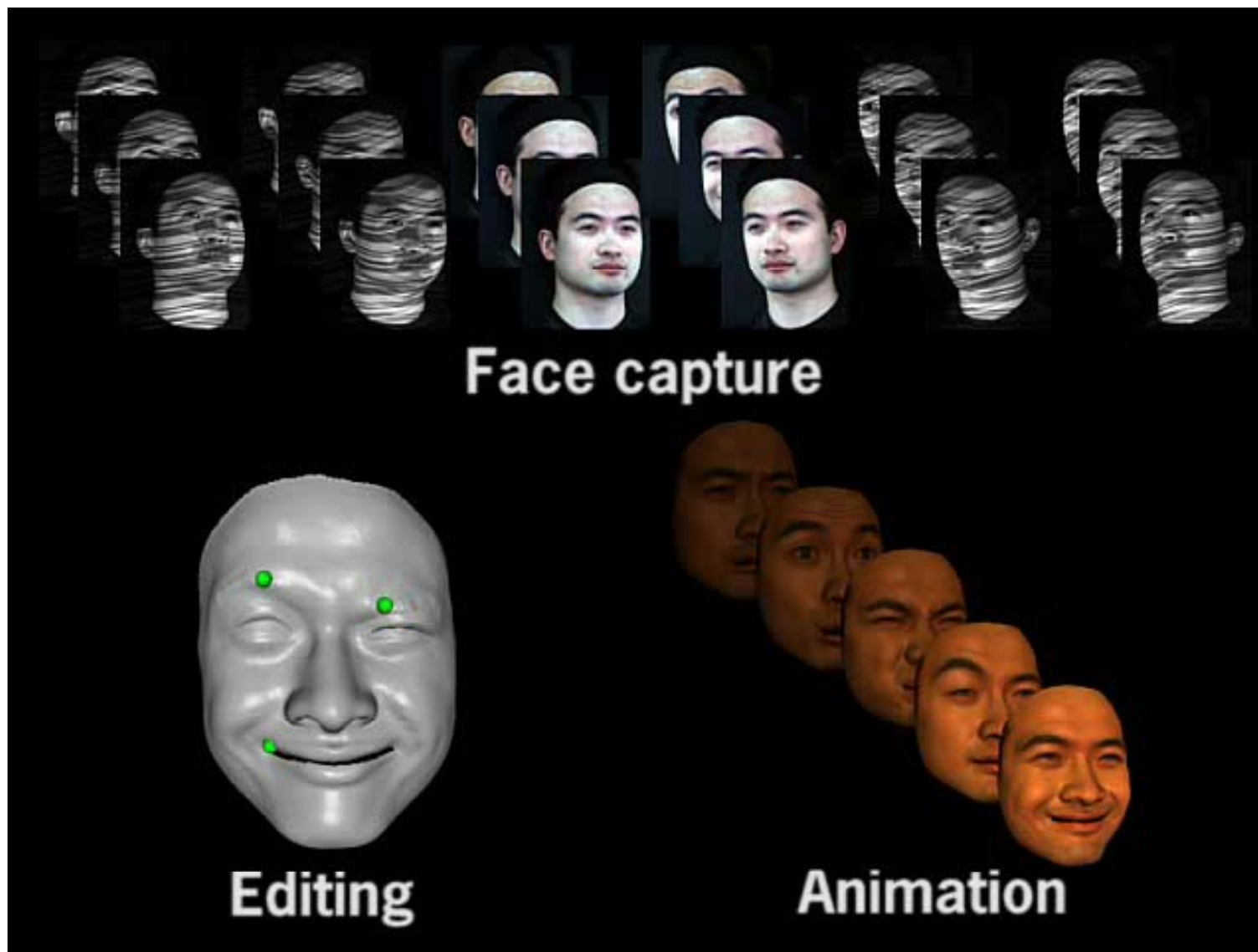


# Spacetime stereo matching

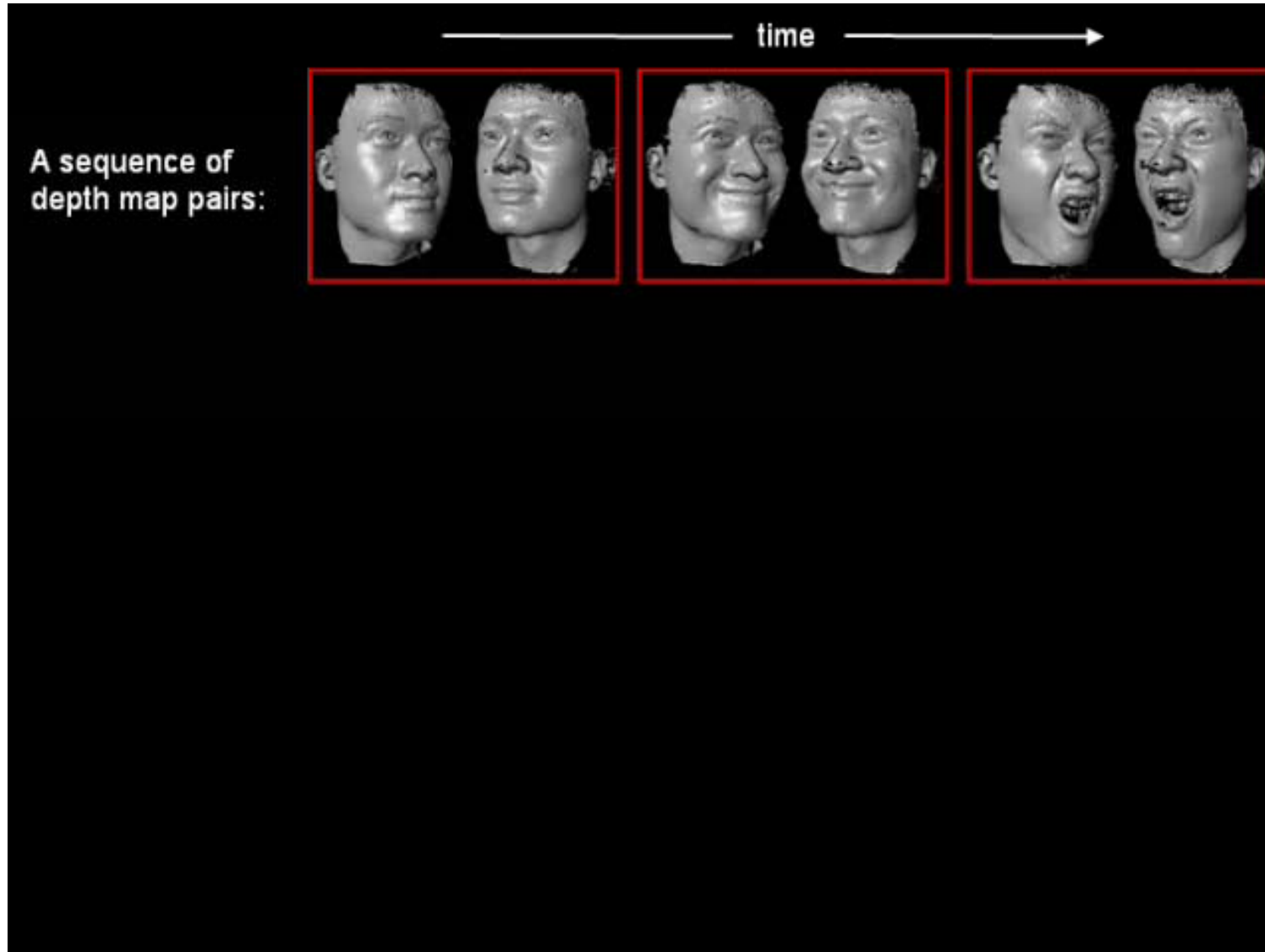
A moving oblique surface



# Video

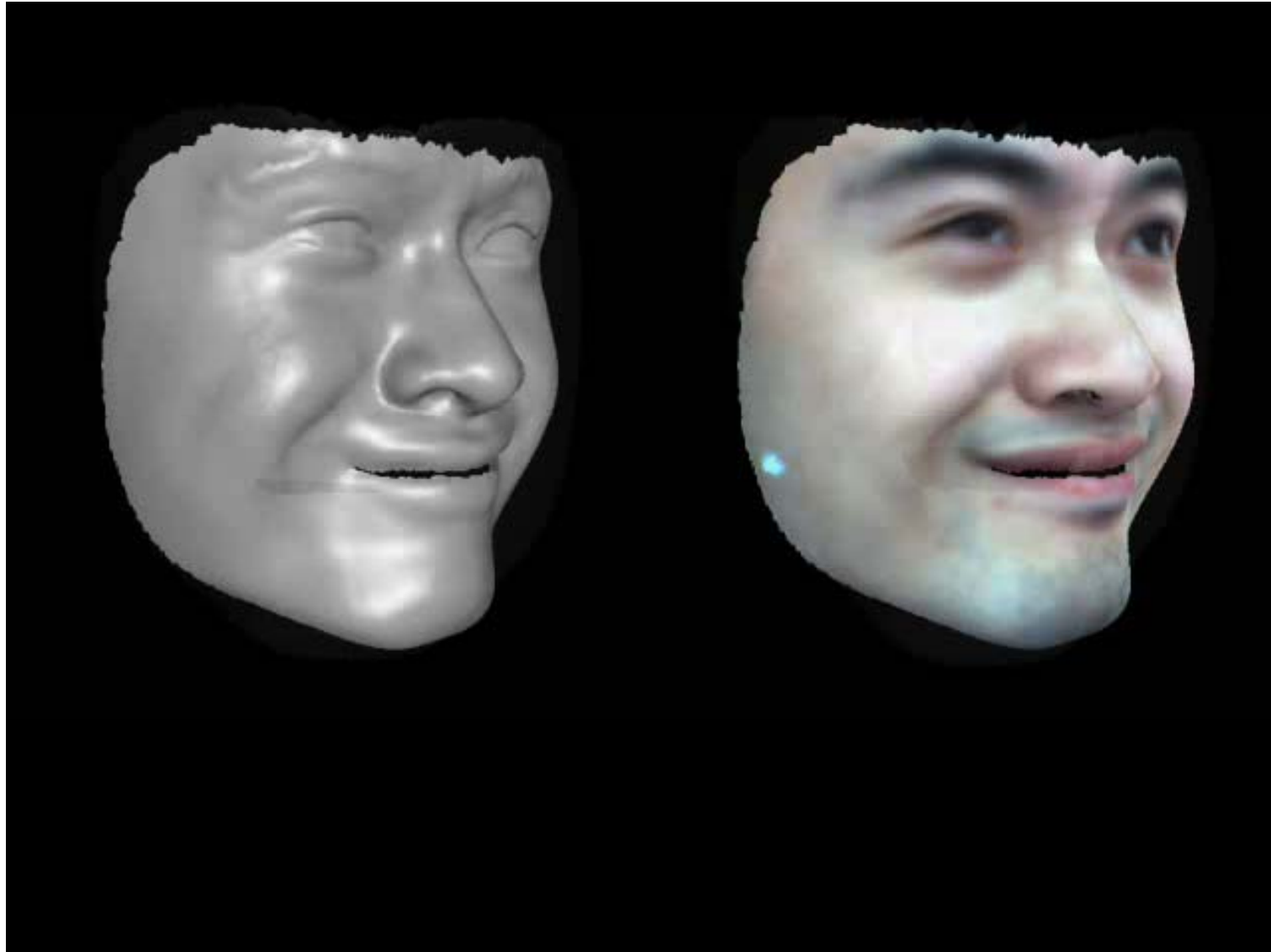


# Fitting



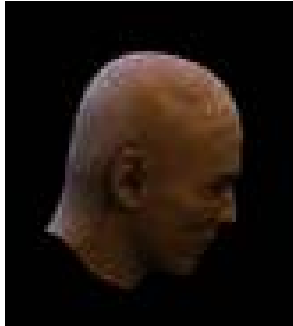
## Face Editing

# Animation



# 3D face applications: The one

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# 3D face applications: Gladiator

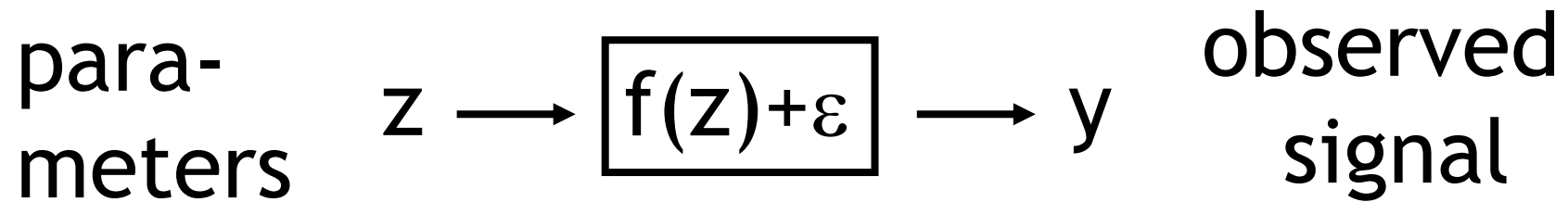
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extra 3M



# **Statistical methods**

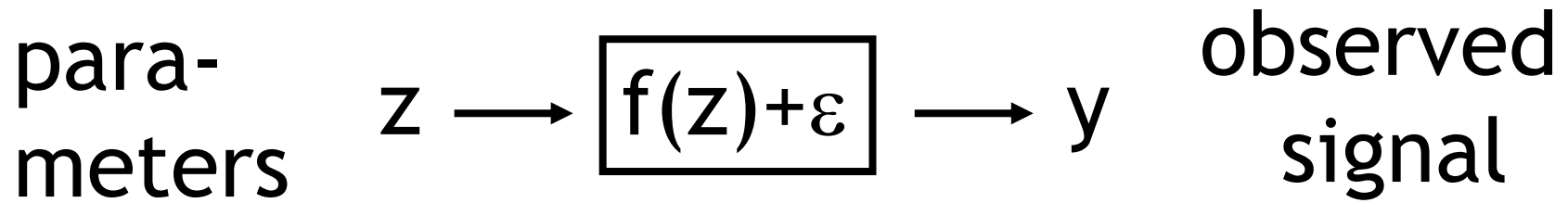


$$\begin{aligned} z^* &= \max_z P(z | y) \\ &= \max_z \frac{P(y | z)P(z)}{P(y)} \\ &= \min_z L(y | z) + L(z) \end{aligned}$$

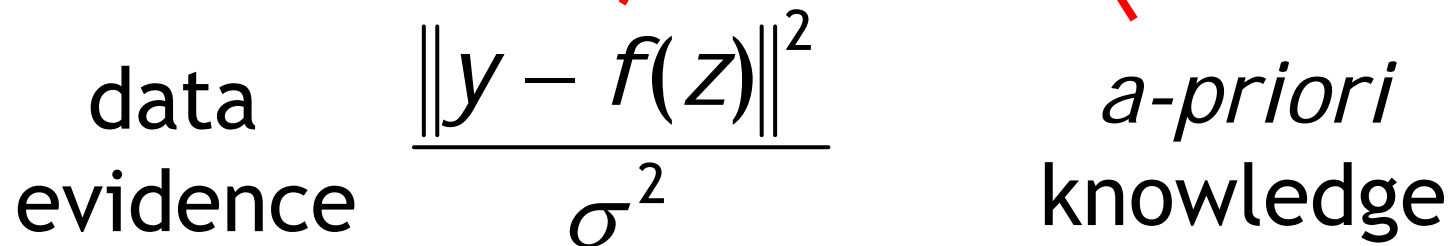
Example:  
super-resolution  
de-noising  
de-blocking  
Inpainting

...

# Statistical methods



$$z^* = \min_z L(y | z) + L(z)$$



# Statistical methods

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*There are approximately  $10^{240}$  possible  $10 \times 10$  gray-level images. Even human being has not seen them all yet. There must be a strong statistical bias.*

*Takeo Kanade*

Approximately  $8 \times 10^{11}$  blocks per day per person.

# Generic priors

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“Smooth images are good images.”

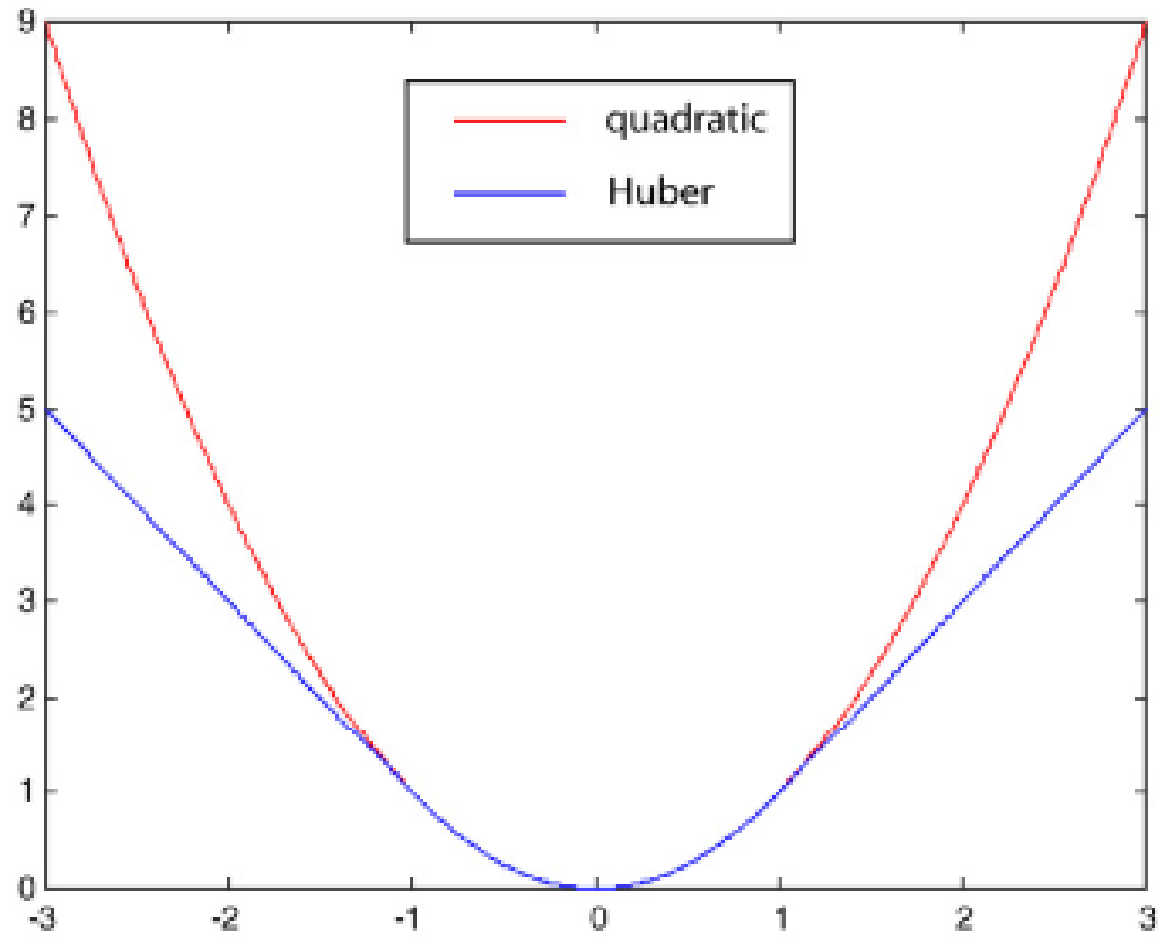
$$L(z) = \sum_x \rho(V(x))$$

Gaussian MRF  $\rho(d) = d^2$

Huber MRF  $\rho(d) = \begin{cases} d^2 & |d| \leq T \\ T^2 + 2T(|d| - T) & d > T \end{cases}$

# Generic priors

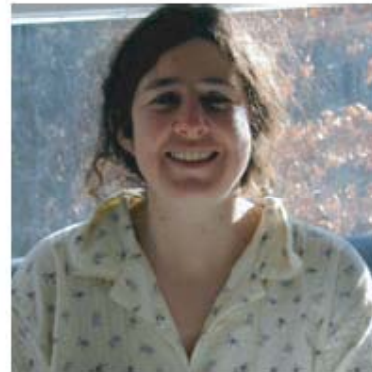
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# Example-based priors

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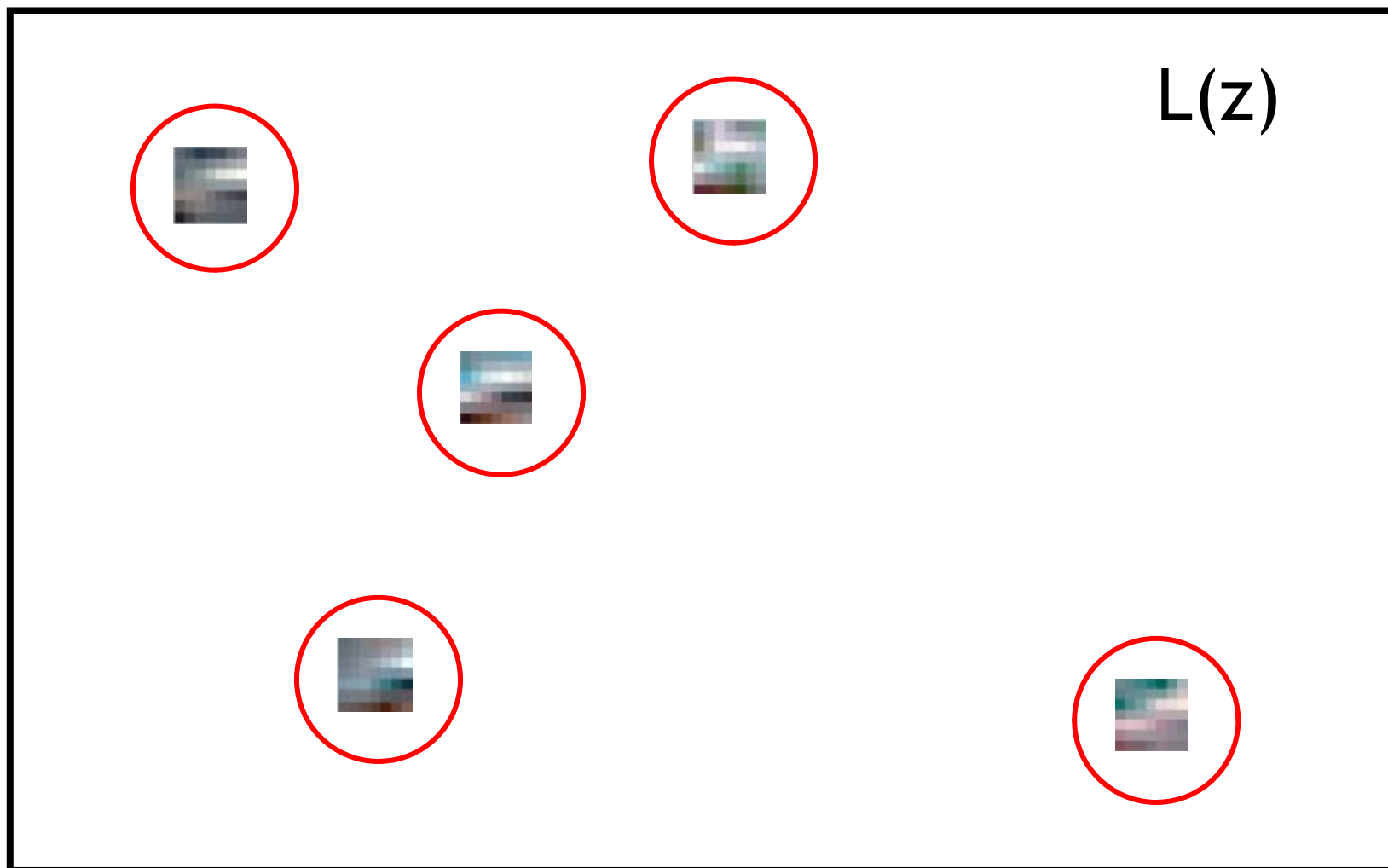
“Existing images are good images.”



six  $200 \times 200$   
Images  $\Rightarrow$   
2,000,000  
pairs

# Example-based priors

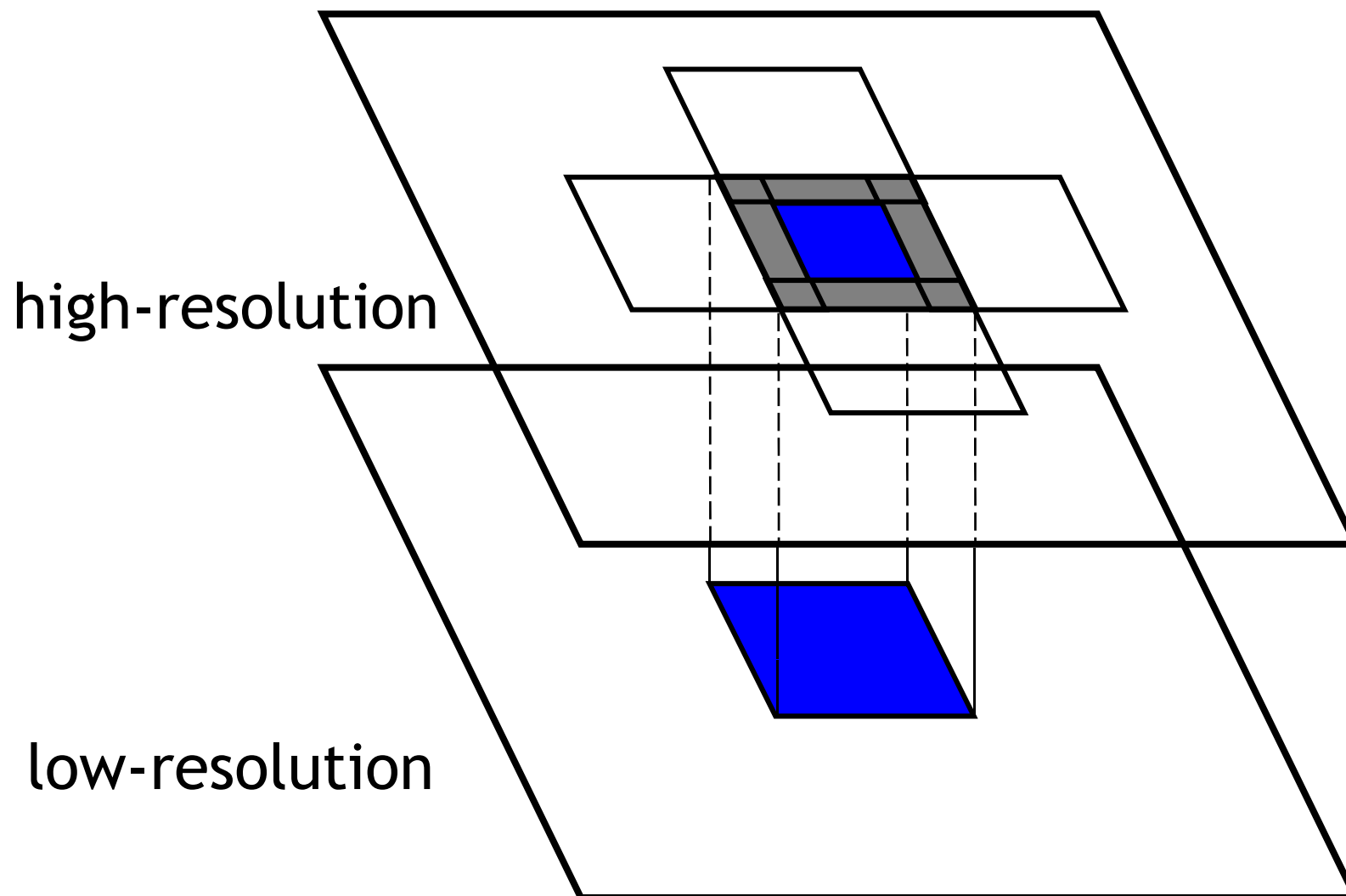
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# Example-based priors

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# Model-based priors

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“Face images are good images when working on face images ...”

Parametric  
model

$$Z = WX + \mu \quad L(X)$$

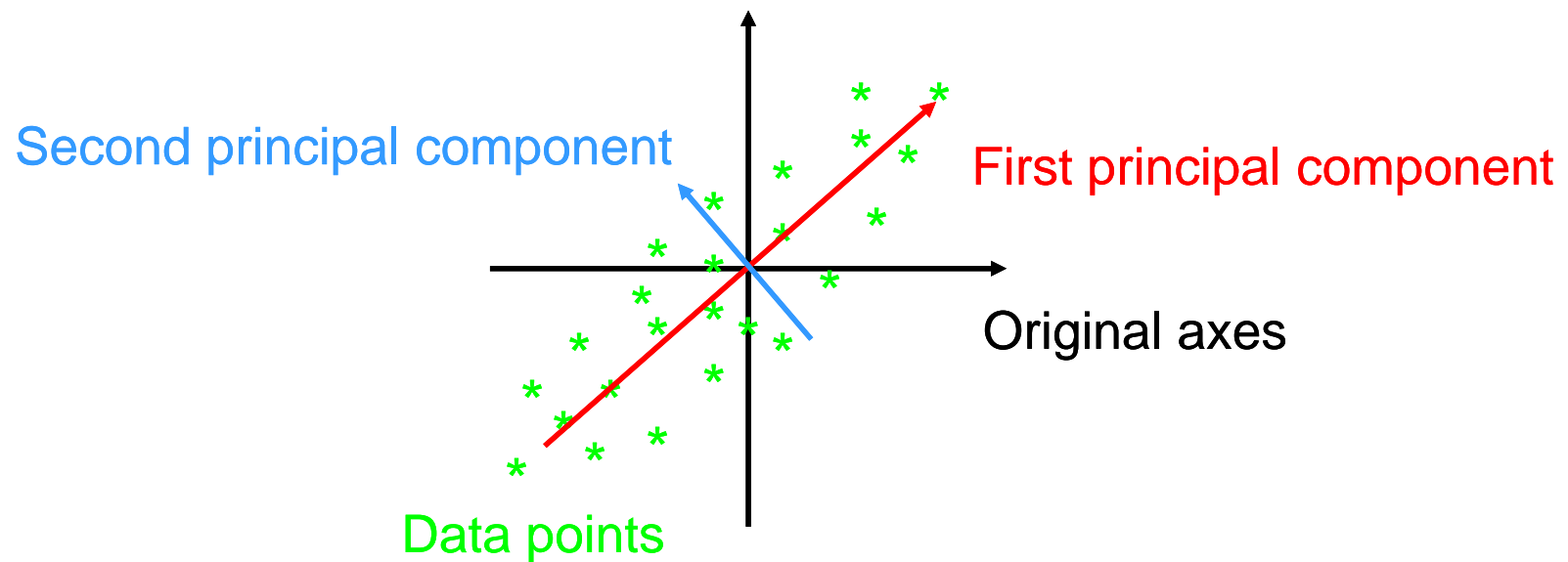
$$z^* = \min_z L(y | z) + L(z)$$

$$\begin{cases} X^* = \min_x L(y | WX + \mu) + L(X) \\ z^* = WX^* + \mu \end{cases}$$

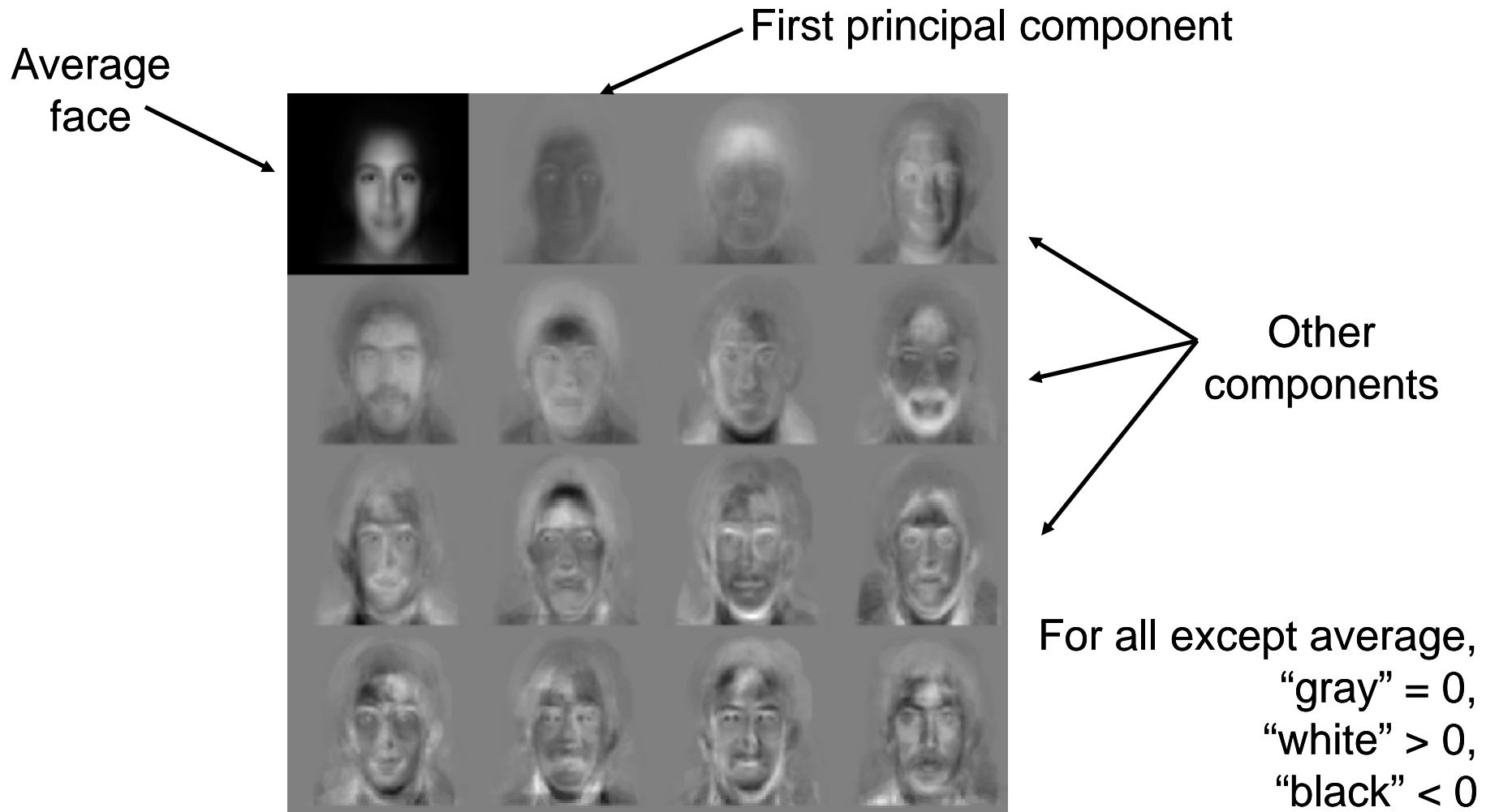
# PCA

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- Principal Components Analysis (PCA): approximating a high-dimensional data set with a lower-dimensional subspace



# PCA on faces: “eigenfaces”



# Model-based priors

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“Face images are good images when working on face images ...”

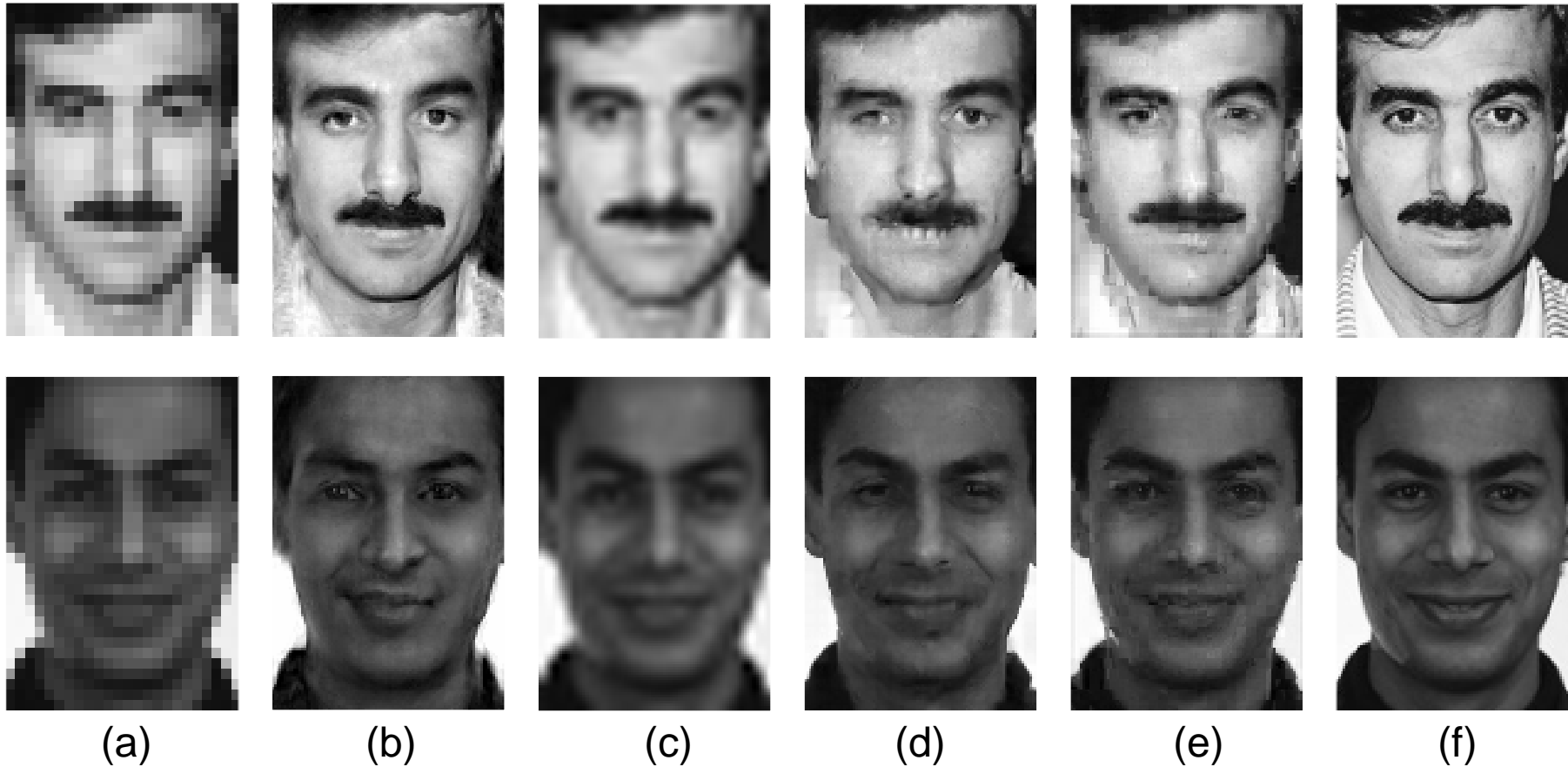
Parametric  
model

$$Z = WX + \mu \quad L(X)$$

$$z^* = \min_z L(y | z) + L(z)$$

$$\begin{cases} X^* = \min_x L(y | WX + \mu) + L(X) \\ z^* = WX^* + \mu \end{cases}$$

# Super-resolution



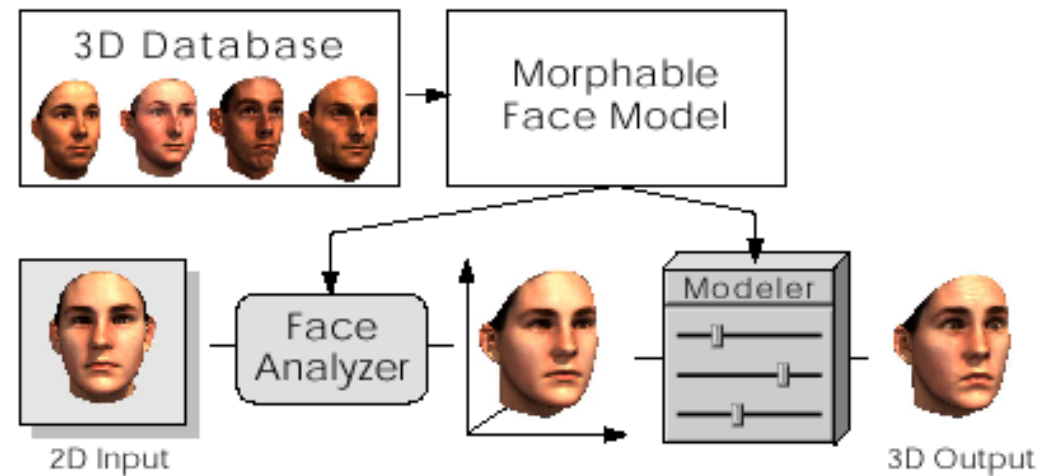
(a) Input low  $24 \times 32$  (b) Our results (c) Cubic B-Spline  
(d) Freeman et al. (e) Baker et al. (f) Original high  $96 \times 128$

# Face models from single images

# Morphable model of 3D faces

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- Start with a catalogue of 200 aligned 3D Cyberware scans



- Build a model of *average* shape and texture, and principal *variations* using PCA



# Morphable model

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shape exemplars

texture exemplars

$$S_{model} = \bar{S} + \sum_{i=1}^{m-1} \alpha_i s_i, \quad T_{model} = \bar{T} + \sum_{i=1}^{m-1} \beta_i t_i, \quad (1)$$

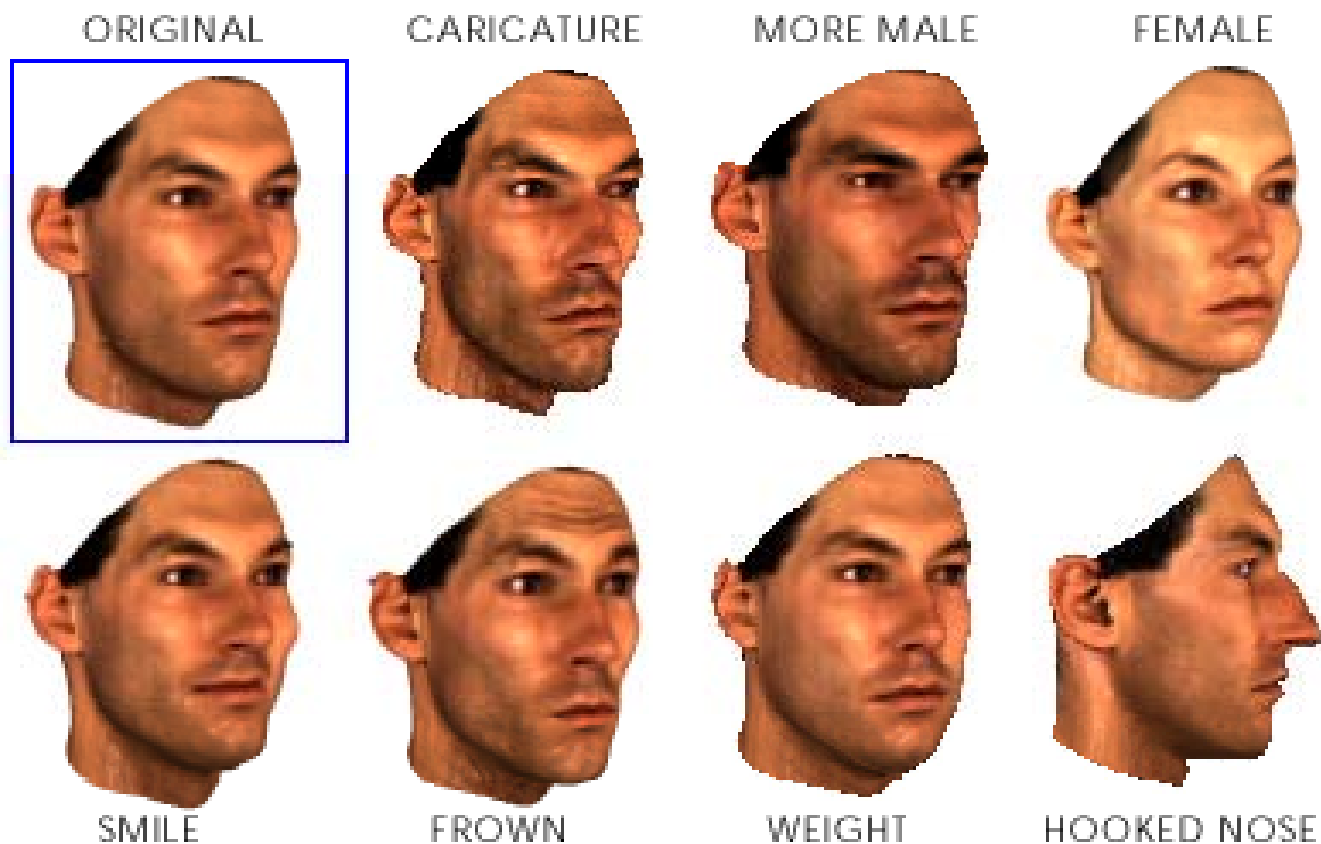
$\vec{\alpha}, \vec{\beta} \in \mathfrak{R}^{m-1}$ . The probability for coefficients  $\vec{\alpha}$  is given by

$$p(\vec{\alpha}) \sim \exp\left[-\frac{1}{2} \sum_{i=1}^{m-1} (\alpha_i / \sigma_i)^2\right], \quad (2)$$

# Morphable model of 3D faces

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- Adding some variations



# Reconstruction from single image

2D Input

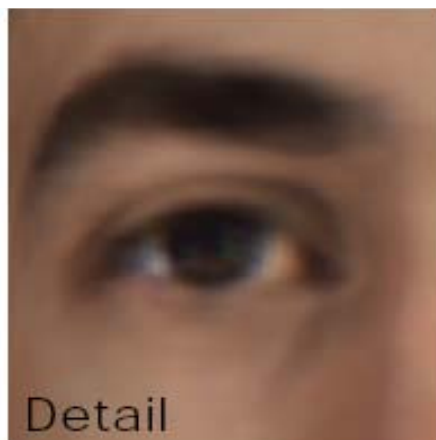


Initializing the Morphable Model  
rough interactive alignment of 3D average head



Automated 3D Shape and Texture Reconstruction

$\alpha_j \beta_j$



Rendering must be similar to the input if we guess right

# Reconstruction from single image

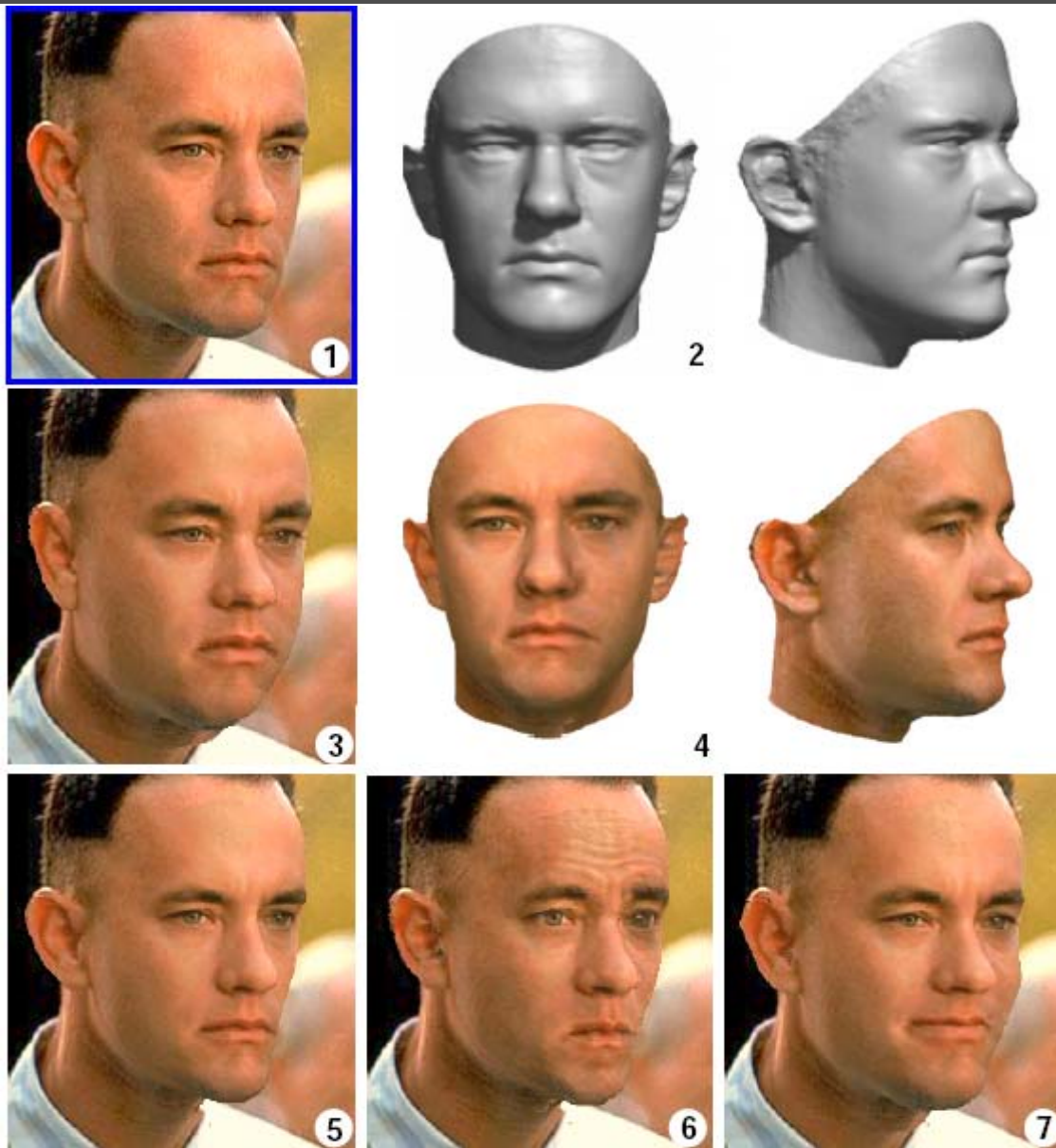
$$E = \frac{1}{\sigma_N^2} E_I + \sum_{j=1}^{m-1} \frac{\alpha_j^2}{\sigma_{S,j}^2} + \sum_{j=1}^{m-1} \frac{\beta_j^2}{\sigma_{T,j}^2} + \sum_j \frac{(\rho_j - \bar{\rho}_j)^2}{\sigma_{\rho,j}^2} \text{ prior}$$

$$E_I = \sum_{x,y} \|\mathbf{I}_{input}(x,y) - \mathbf{I}_{model}(x,y)\|^2$$

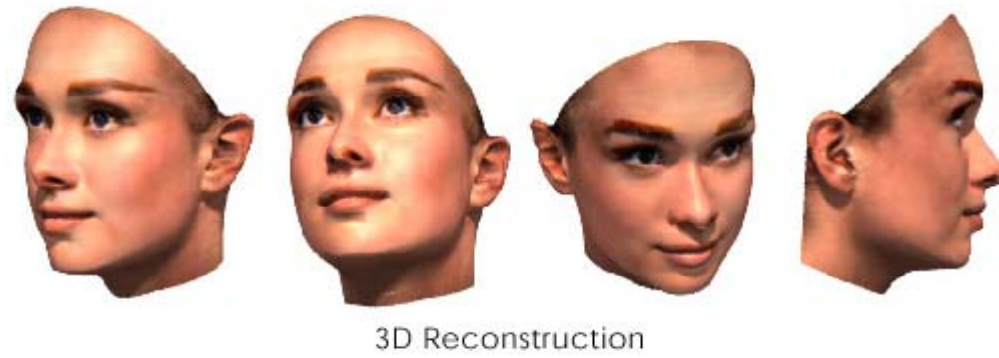
shape and texture priors are learnt from database

$\rho$  is the set of parameters for shading including camera pose, lighting and so on

# Modifying a single image



# Animating from a single image



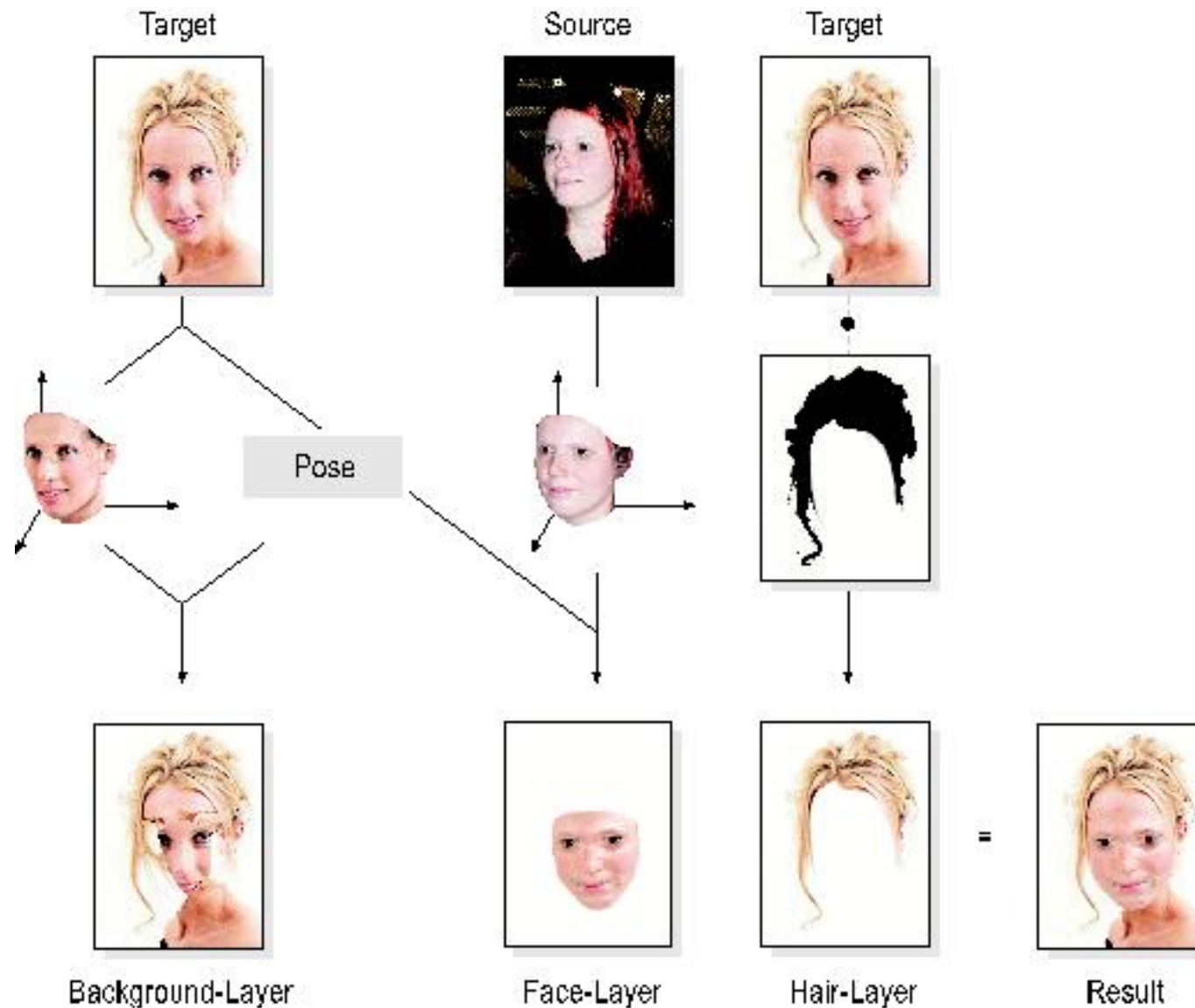
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# A Morphable Model for the Synthesis of 3D Faces

Volker Blanz & Thomas Vetter

MPI for Biological Cybernetics  
Tübingen, Germany

# Exchanging faces in images





# Exchange faces in images

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# Exchange faces in images

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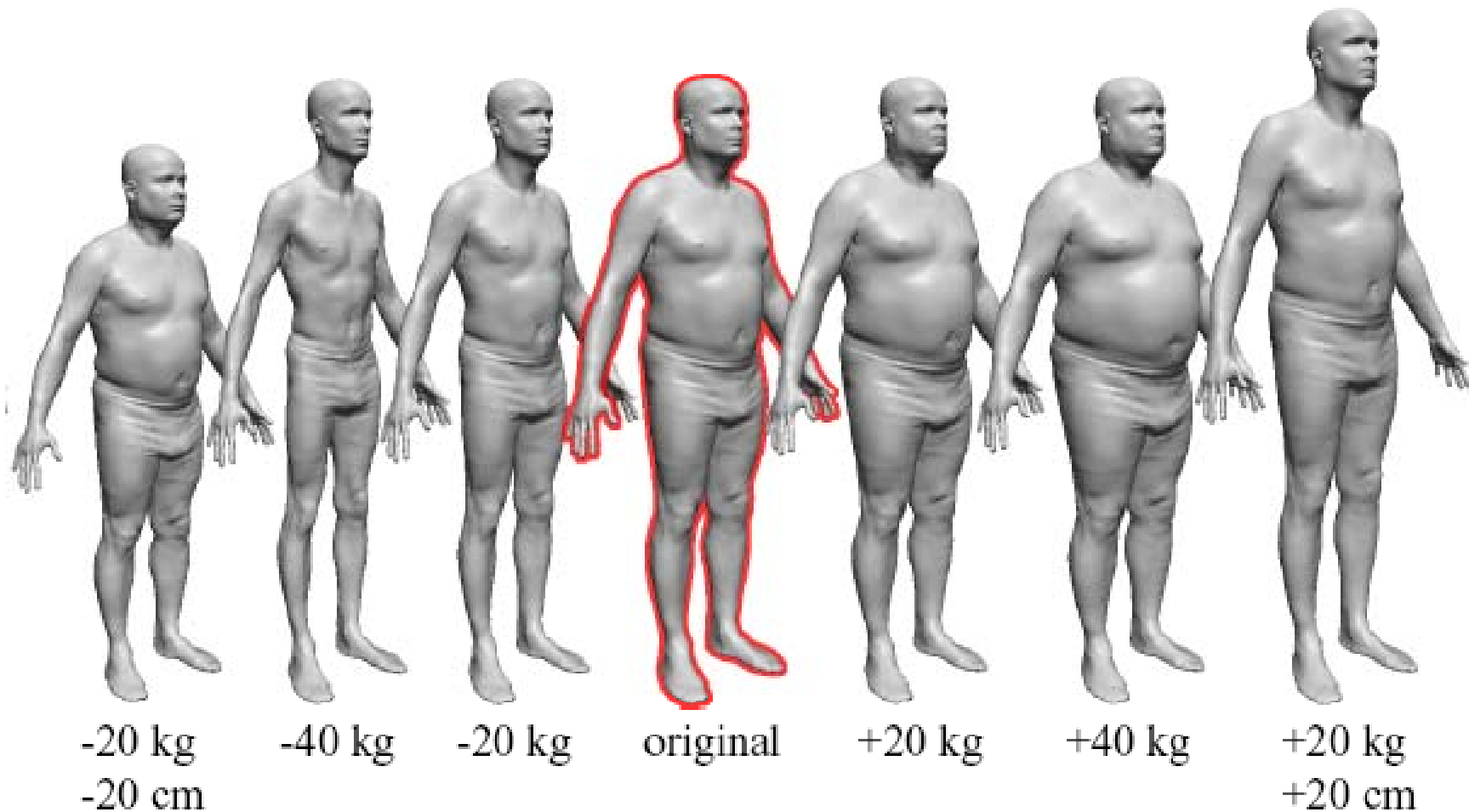
# Exchange faces in images



# Exchange faces in images

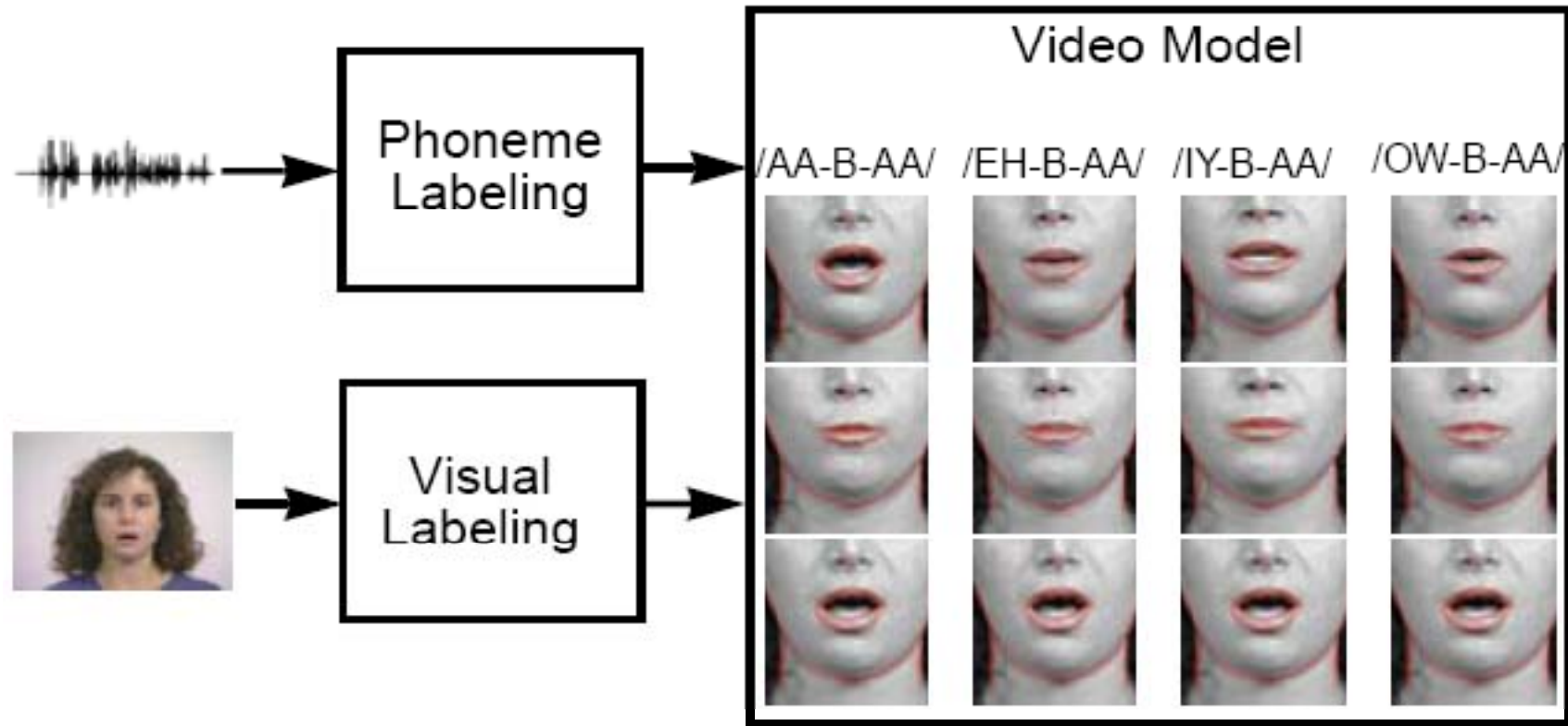


# Morphable model for human body

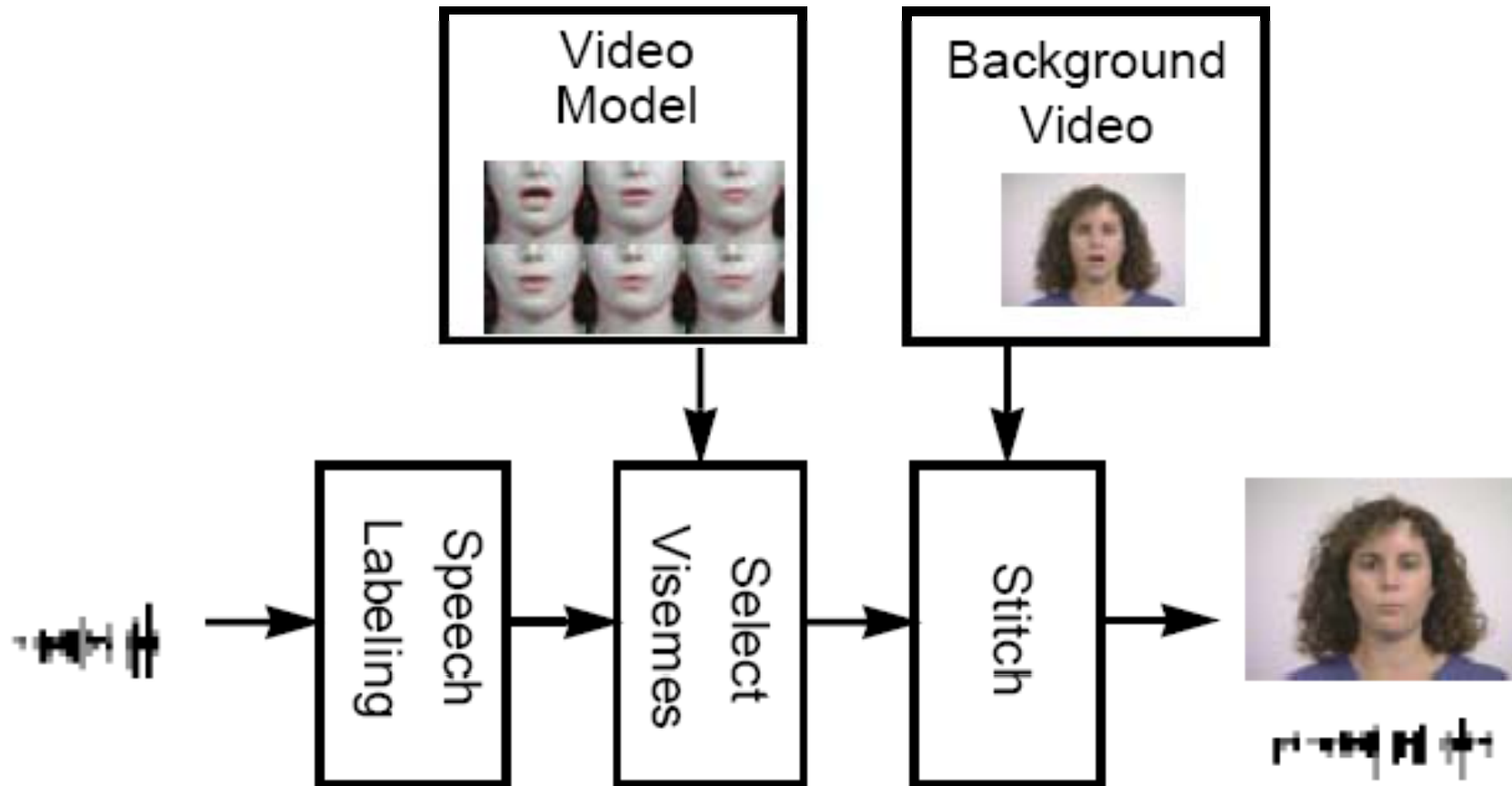


# Image-based faces (lip sync.)

# Video rewrite (analysis)



# Video rewrite (synthesis)





# Results

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- Video database
  - 2 minutes of JFK
    - Only half usable
    - Head rotation

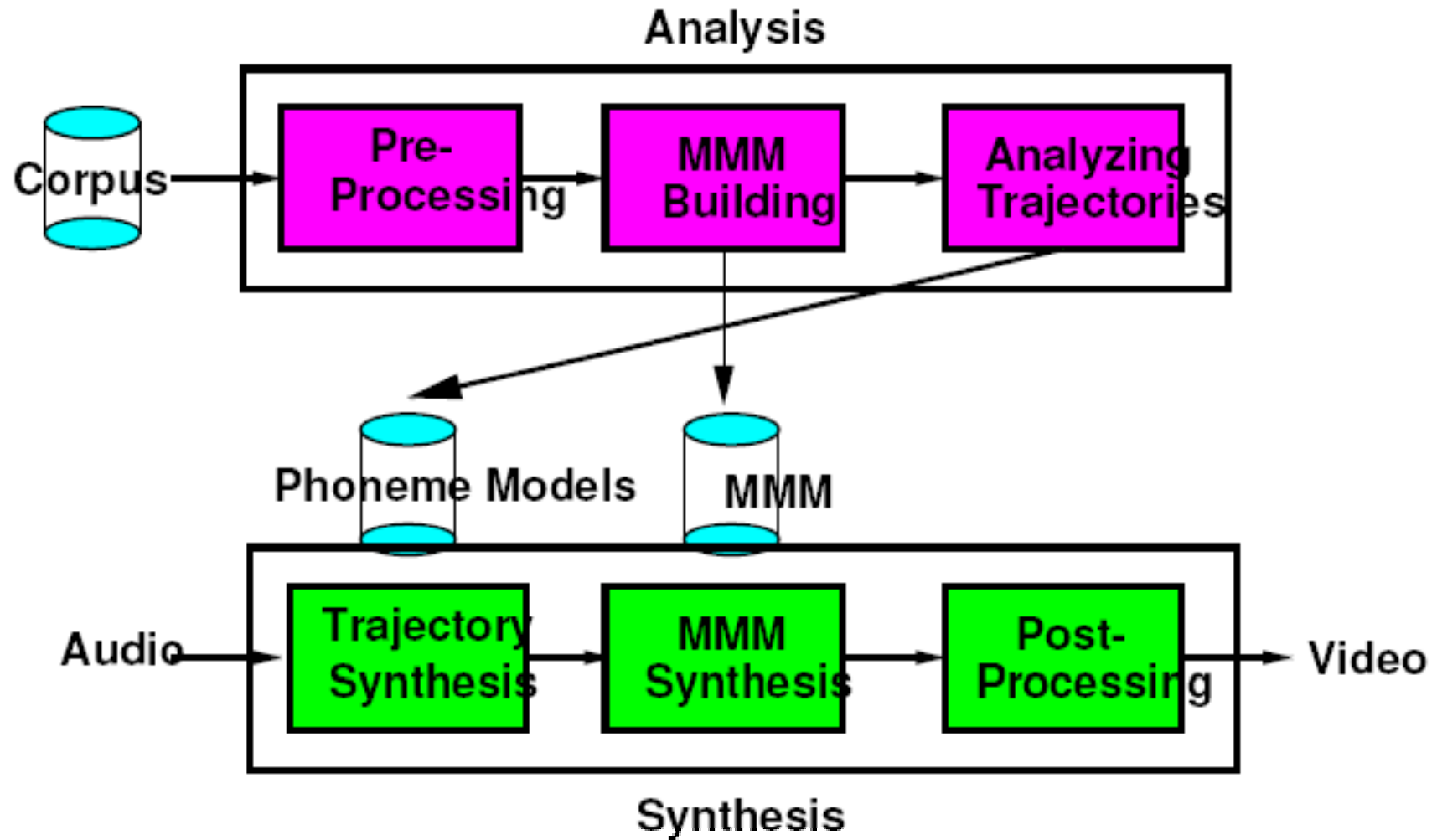


training video

Read my lips.

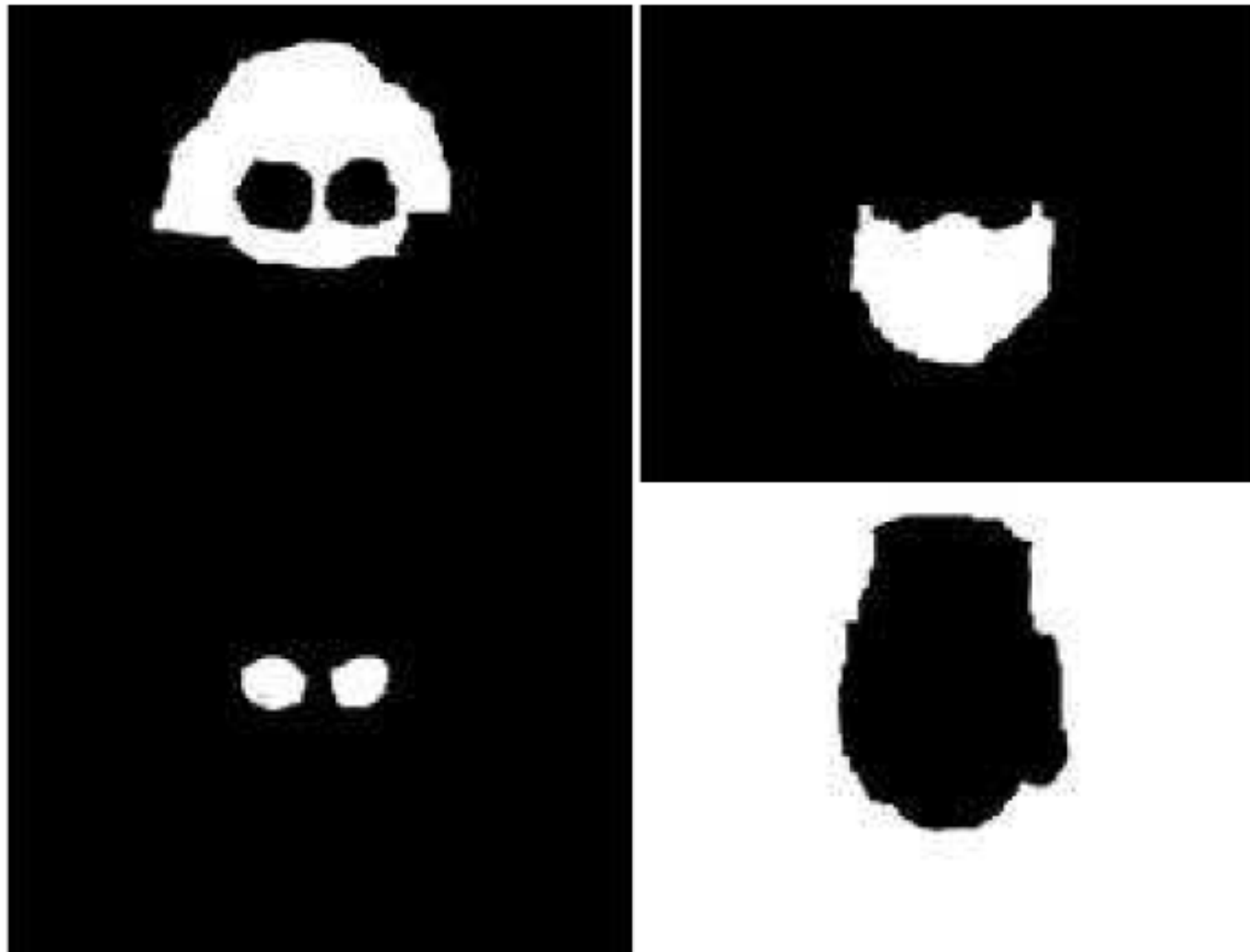
I never met Forest Gump.

# Morphable speech model



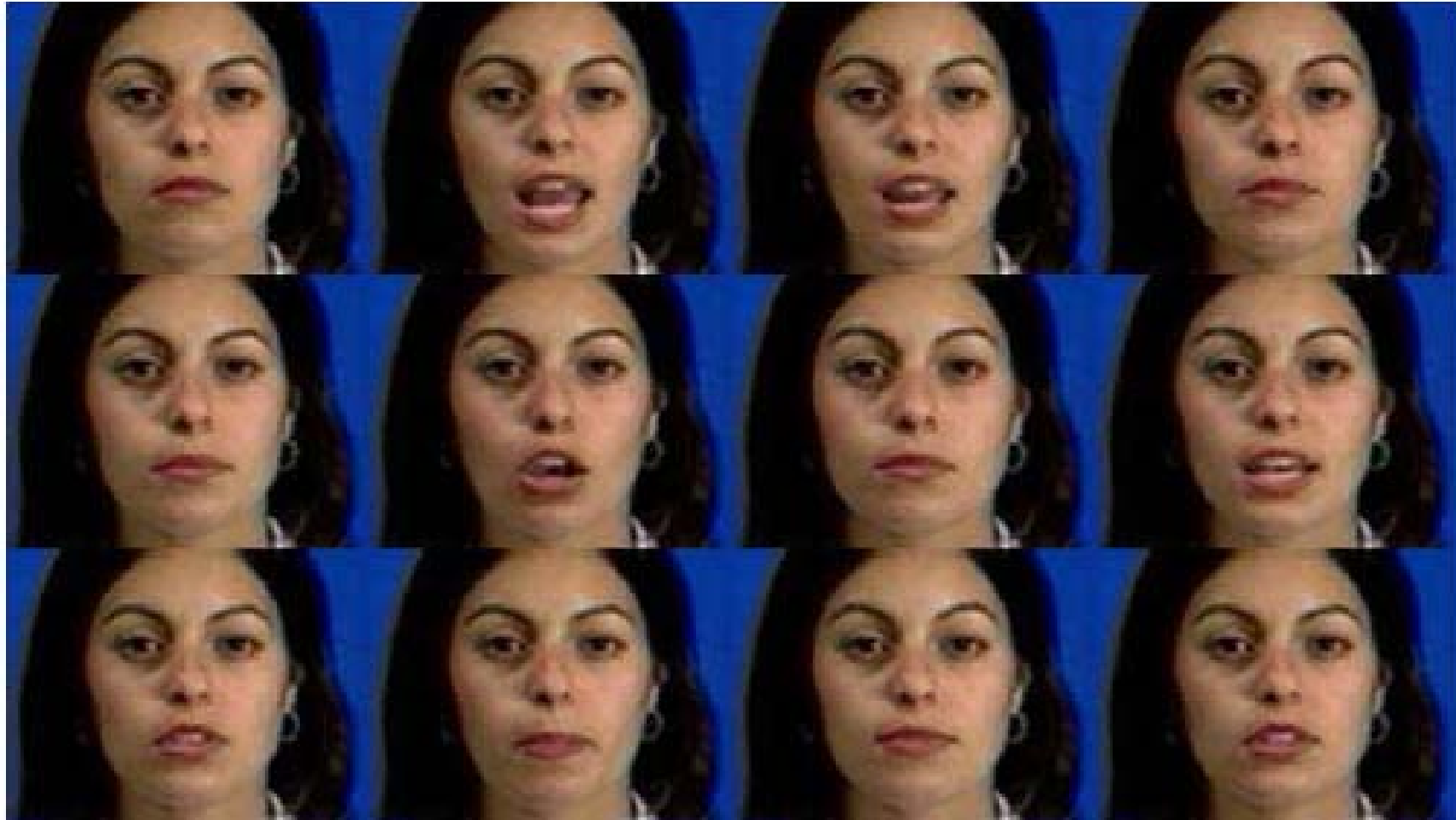
# Preprocessing

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# Prototypes (PCA+k-mean clustering)

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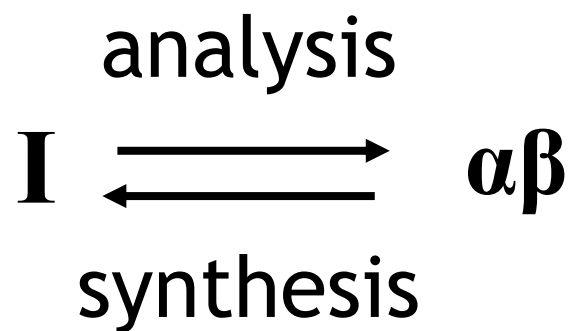


We find  $I_i$  and  $C_i$  for each prototype image.

# Morphable model

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$$I^{morph}(\alpha, \beta) = \sum_{i=1}^N \beta_i \mathbf{W}(I_i, \mathbf{W}(\sum_{j=1}^N \alpha_j C_j - C_i, C_i))$$



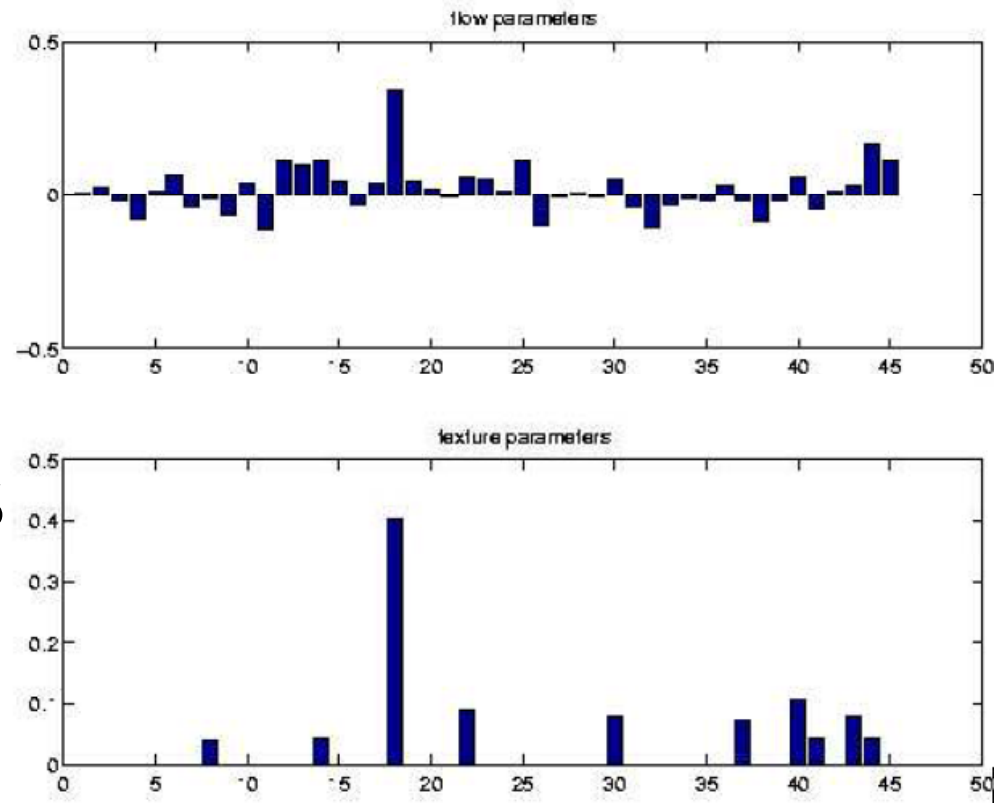
# Morphable model



analysis



synthesis

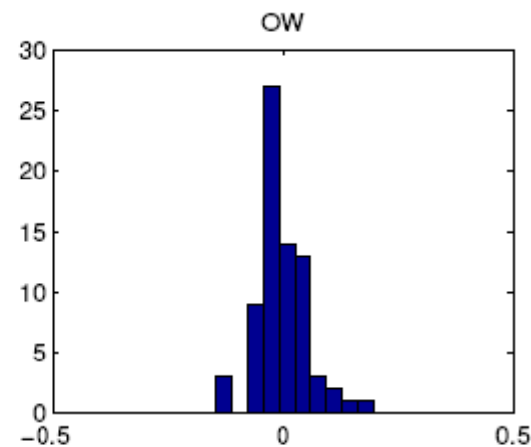
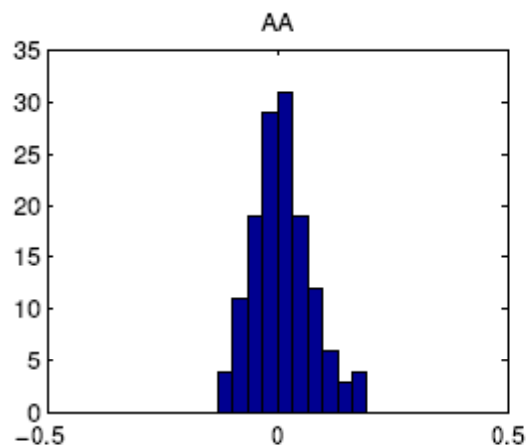
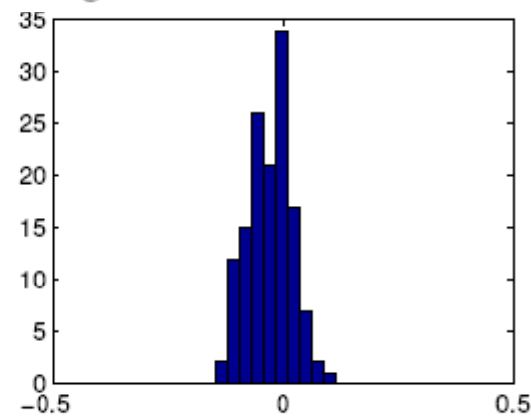
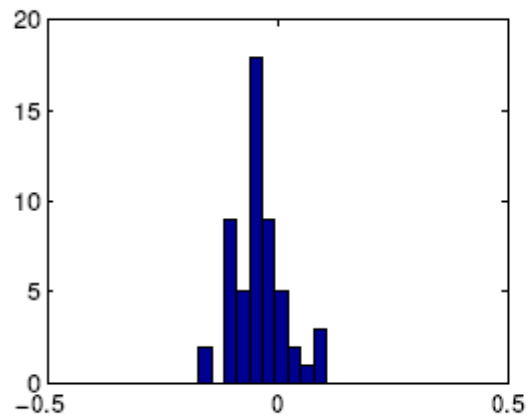


# Synthesis

$$E = \underbrace{(y - \mu)^T D^T \Sigma^{-1} D (y - \mu)}_{\text{target term}} + \lambda \underbrace{y^T W^T W y}_{\text{smoothness}}$$

*target term*

*smoothness*



# Results

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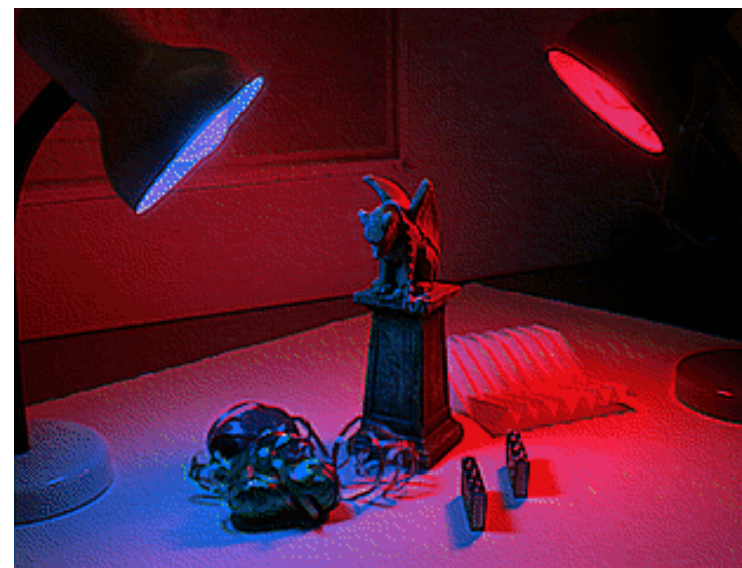
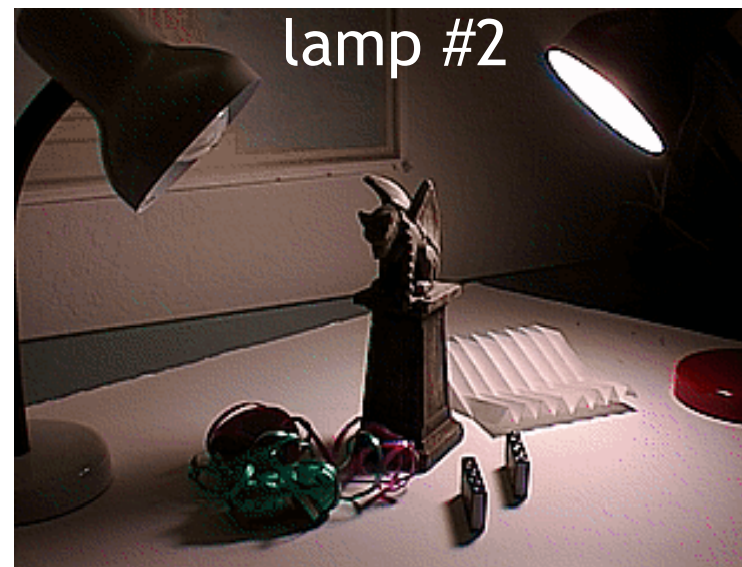
# Results

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# Relighting faces

# Light is additive



# Light stage 1.0

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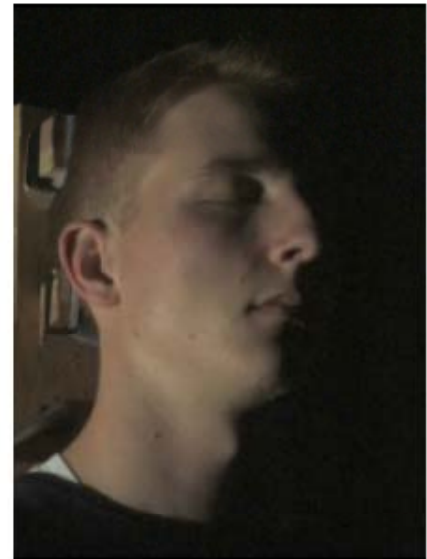
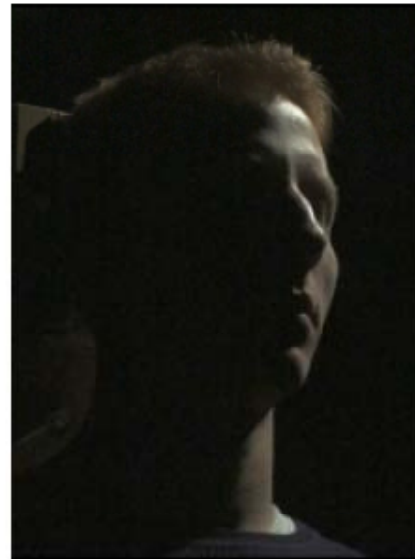
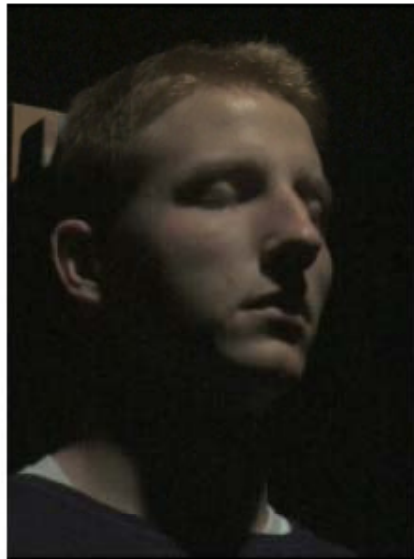
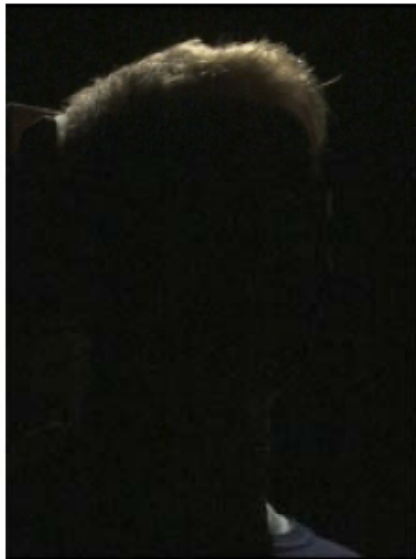


# Light stage 1.0

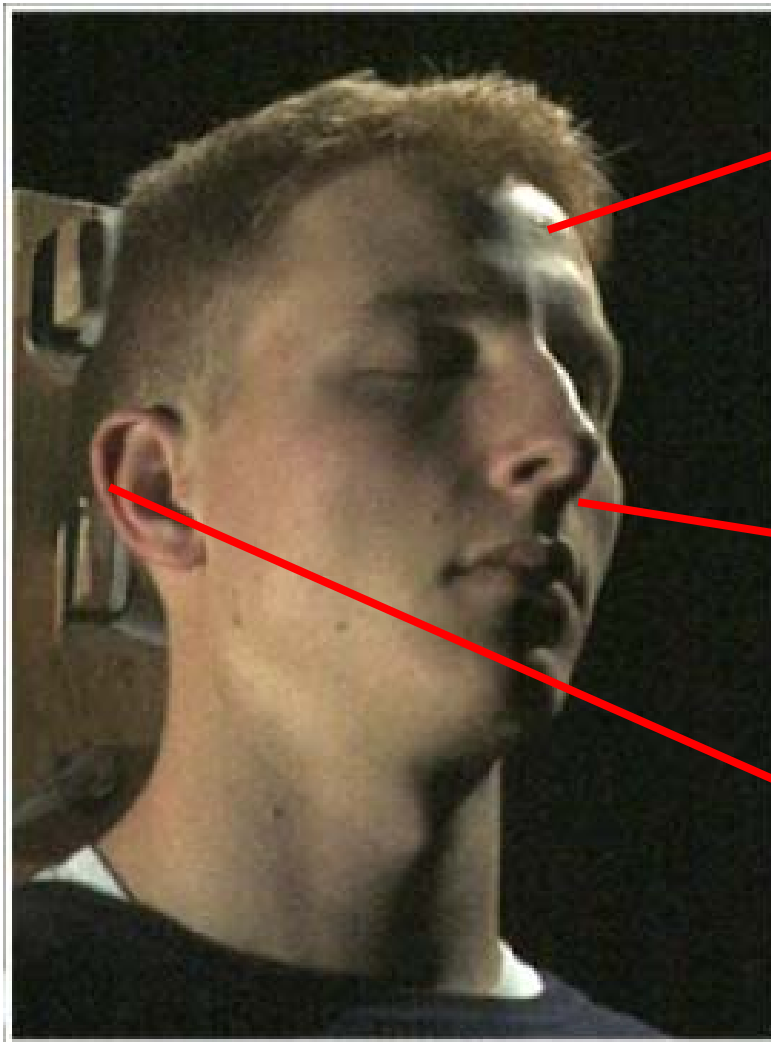


# Input images

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# Reflectance function



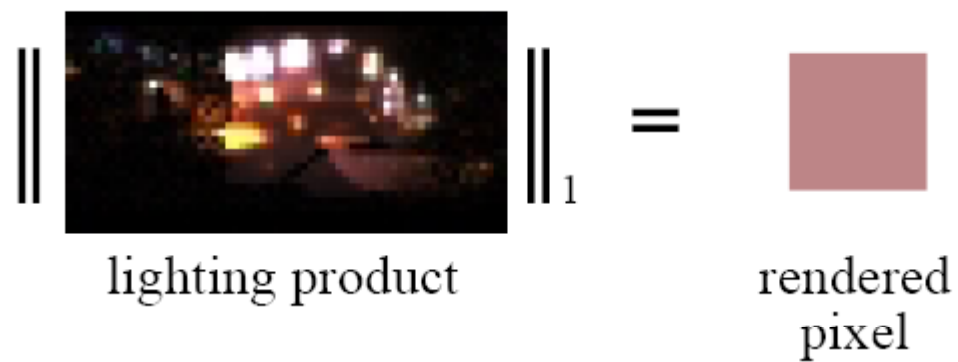
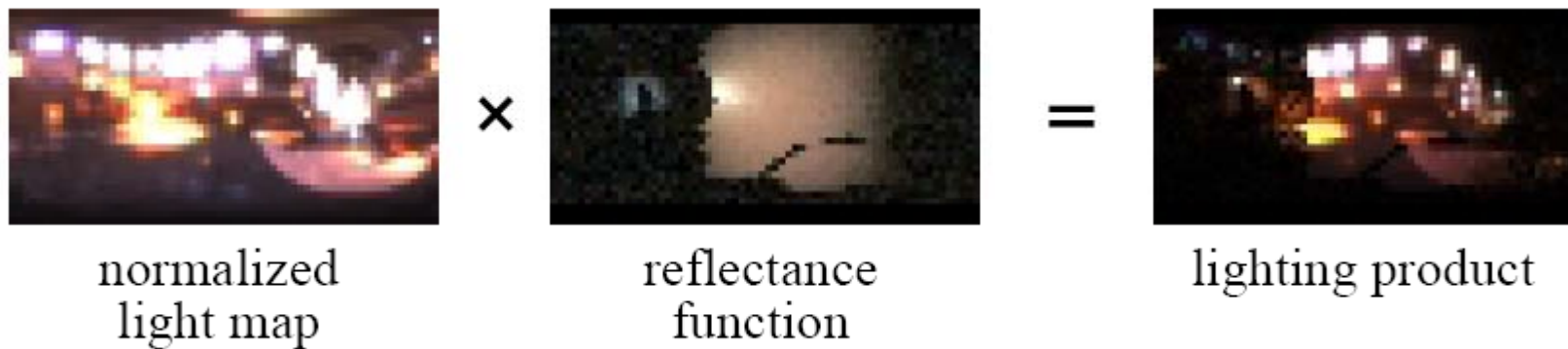
occlusion

flare



# Relighting

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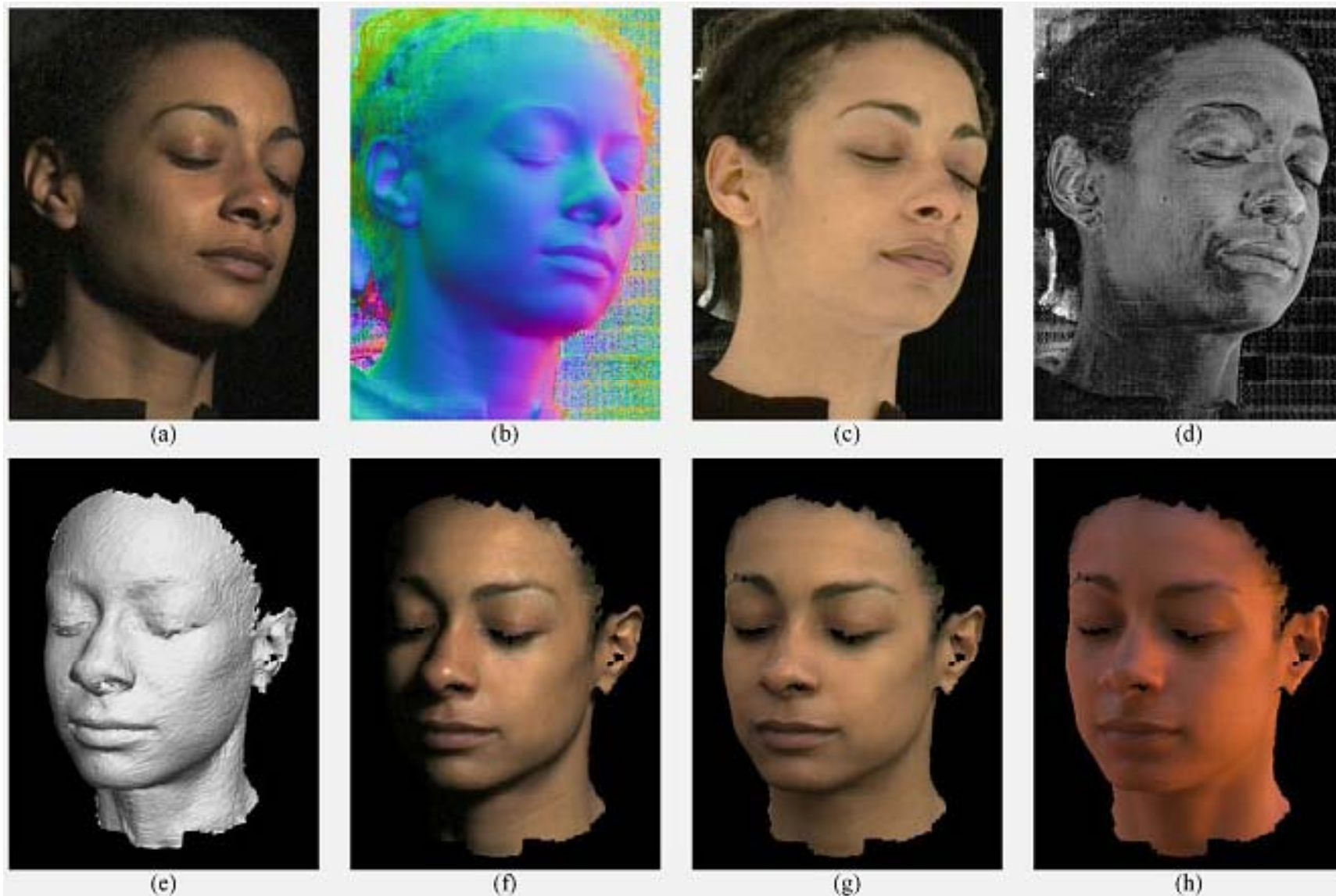




# Results

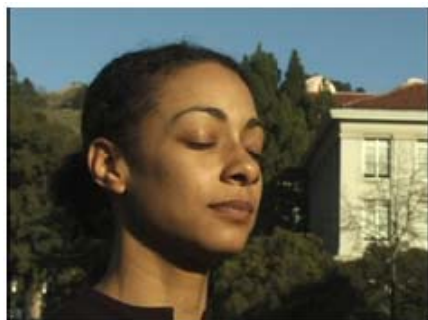


# Changing viewpoints



# Results

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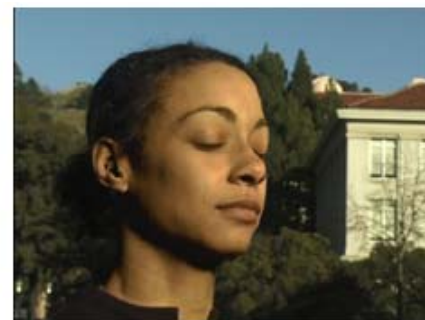
(a)



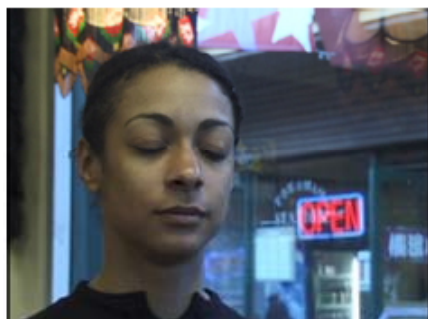
(c)



(e)



(g)



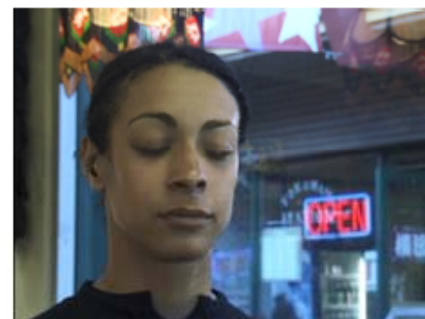
(b)



(d)



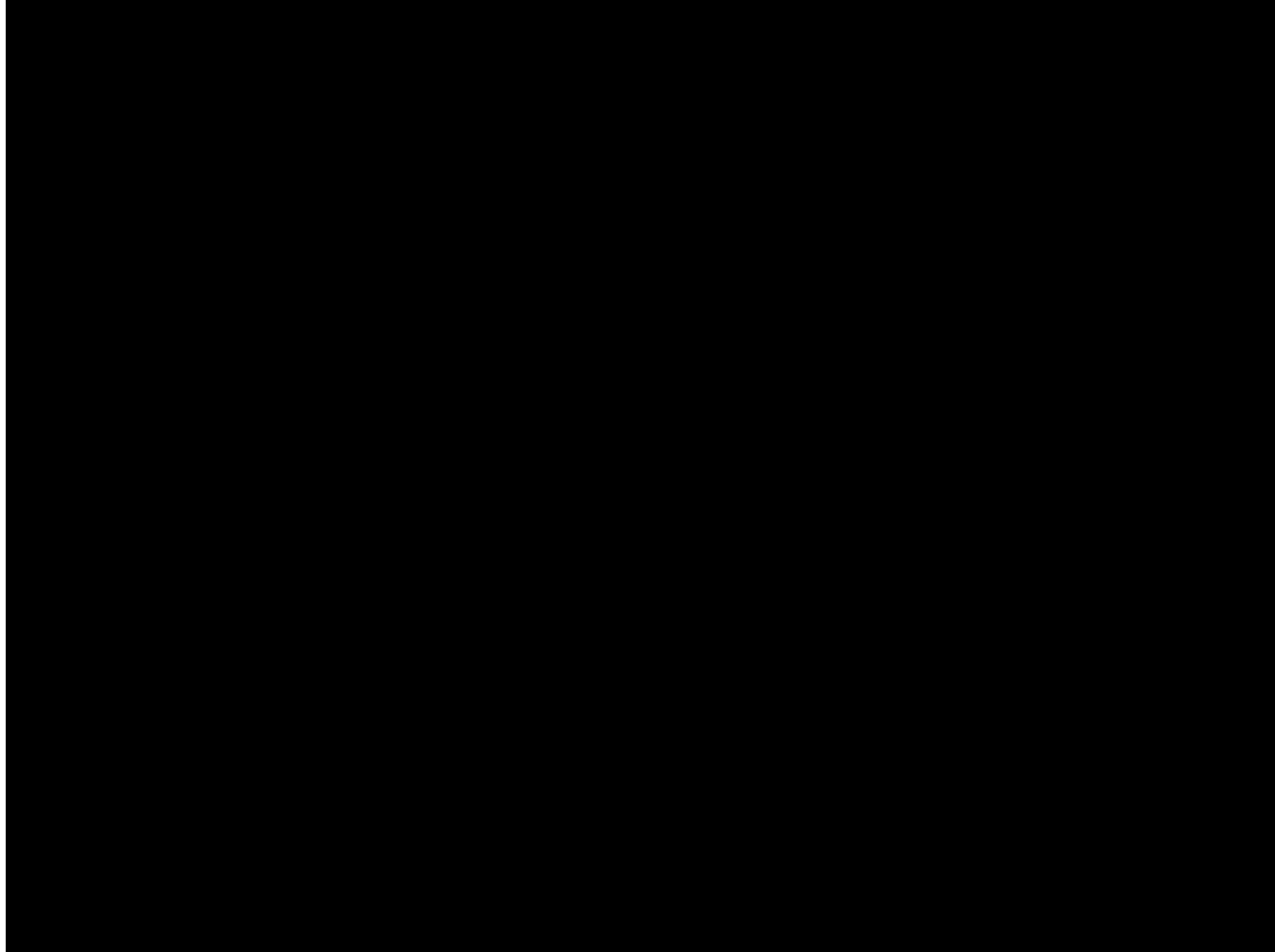
(f)



(h)

# Video

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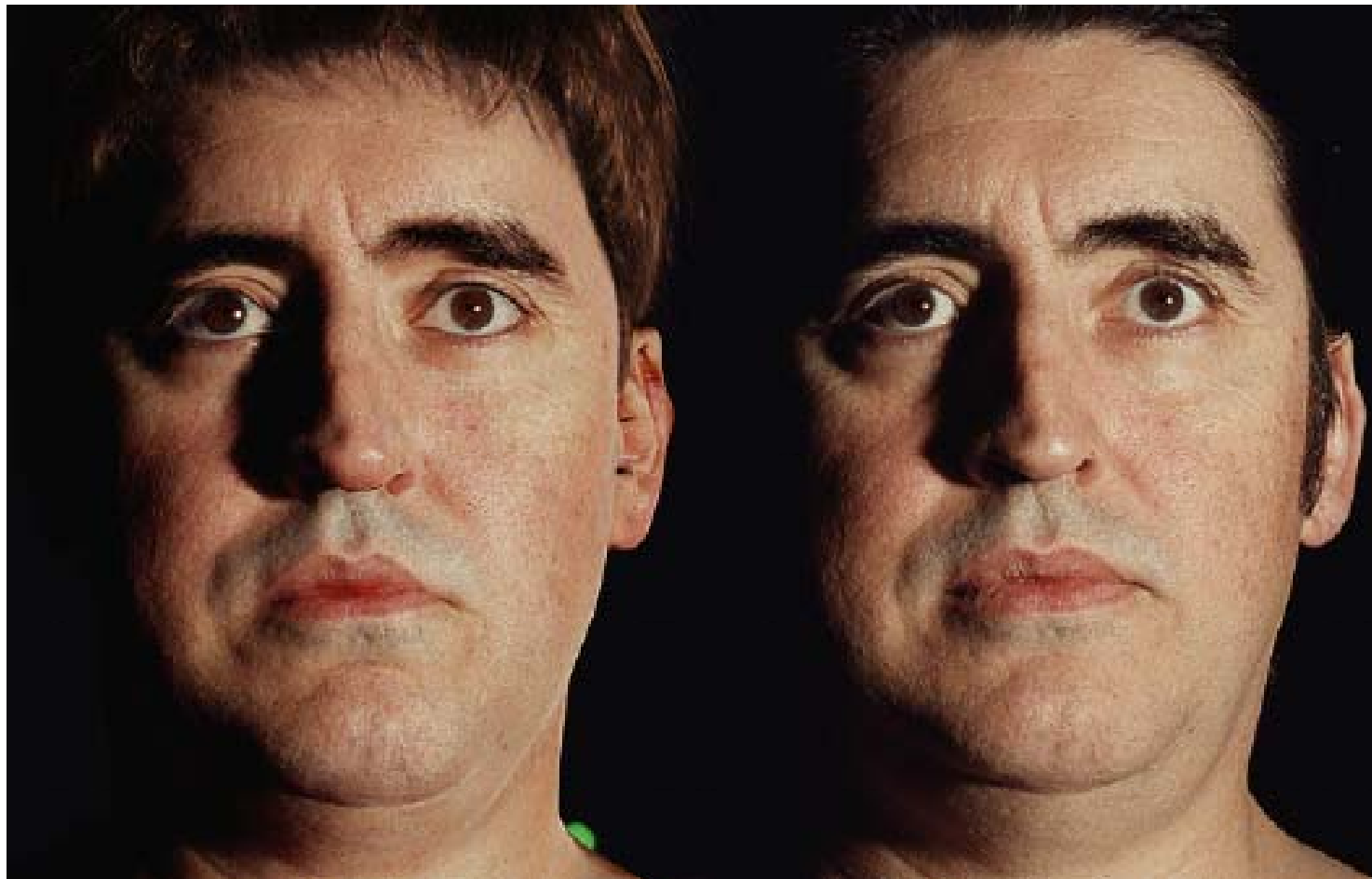


# 3D face applications: Spiderman 2



# Spiderman 2

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real

synthetic

# Spiderman 2

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video

# Light stage 3

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## Relighting Human Locomotion with Flowed Reflectance Fields

Per Einarsson Charles-Felix Chabert Andrew Jones Wan-Chun Ma <sup>1</sup>  
Bruce Lamond Tim Hawkins Mark Bolas <sup>2</sup> Sebastian Sylwan Paul Debevec

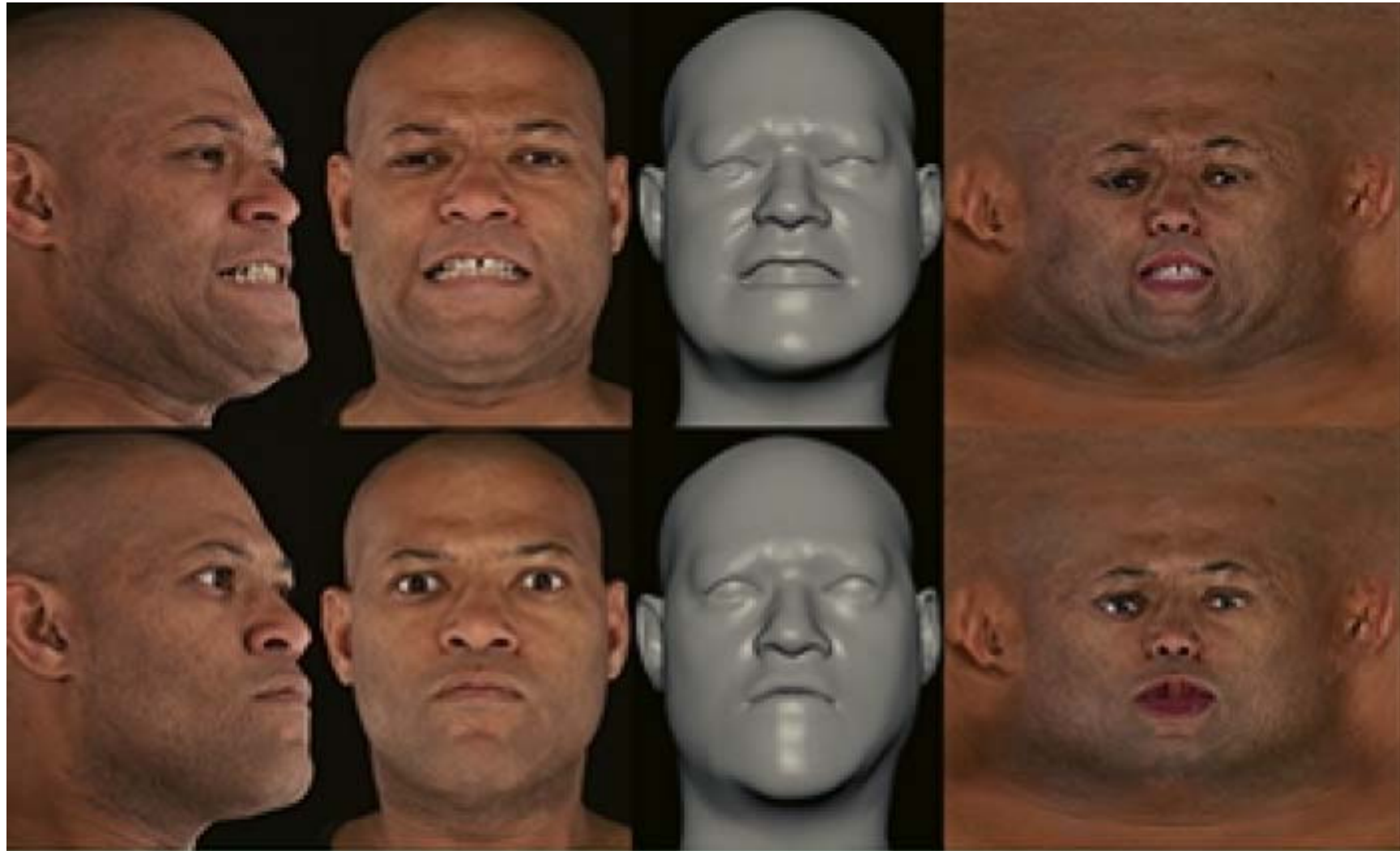
USC Centers for Creative Technologies

National Taiwan University <sup>1</sup>

USC School of Cinema-Television <sup>2</sup>

Eurographics Symposium on Rendering, June 2006

# Application: The Matrix Reloaded



# Application: The Matrix Reloaded

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