Graph Cut

Digital Visual Effects, Spring 2009

Yung-Yu Chuang

2009/5/21

with slides by Fredo Durand, Ramesh Raskar



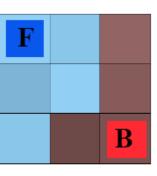
Graph cut



Graph cut



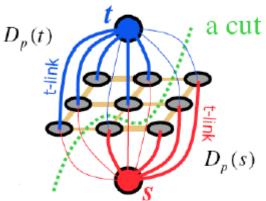
- Interactive image segmentation using graph cut
- Binary label: foreground vs. background
- User labels some pixels
 - similar to trimap, usually sparser
- Exploit
 - Statistics of known Fg & Bg
 - Smoothness of label
- Turn into discrete graph optimization
 - Graph cut (min cut / max flow)



F F B

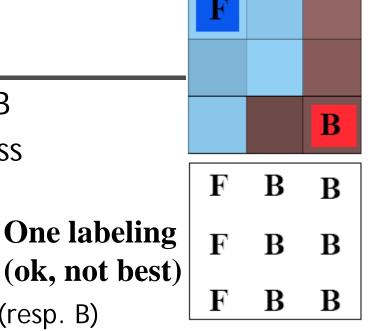
F F B

F B B

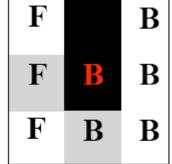


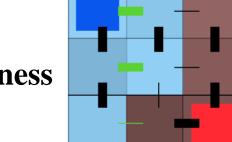
Energy function

- Labeling: one value per pixel, F or B
- Energy(labeling) = data + smoothness
 - Very general situation
 - Will be minimized
- Data: for each pixel
 - Probability that this color belongs to F (resp. B)
 - Similar in spirit to Bayesian matting
- Smoothness (aka regularization): per neighboring pixel pair
 - Penalty for having different label
 - Penalty is downweighted if the two pixel colors are very different
 - Similar in spirit to bilateral filter





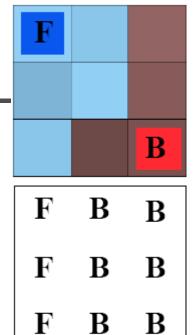


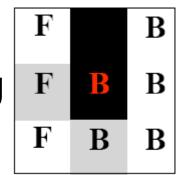


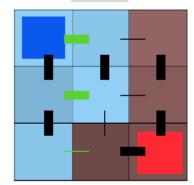
Smoothness

Data term

- A.k.a regional term (because integrated over full region)
- $D(L)=\sum_{i} -\log h[L_{i}](C_{i})$
- Where i is a pixel
 L_i is the label at i (F or B),
 C_i is the pixel value
 h[L_i] is the histogram of the observed Fg
 (resp Bg)
- Note the minus sign



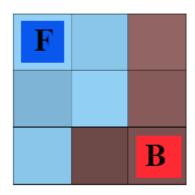




Hard constraints



- The user has provided some labels
- The quick and dirty way to include constraints into optimization is to replace the data term by a huge penalty if not respected.
- D(L_i)=0 if respected
- D(L_i)=K if not respected
 - e.g. K=- #pixels



Smoothness term



В

В

F

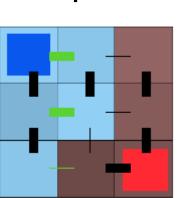
F

F

В

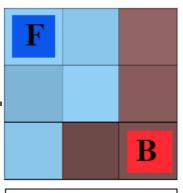
В

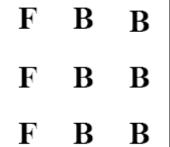
- a.k.a boundary term, a.k.a. regularization
- $S(L)=\sum_{\{j,i\} \text{ in } N} B(C_i,C_j) \delta(L_i-L_j)$
- Where i,j are neighbors
 - e.g. 8-neighborhood (but I show 4 for simplicity)
- $\delta(L_i-L_j)$ is 0 if $L_i=L_j$, 1 otherwise
- B(C_i,C_j) is high when C_i and C_j are similar, low if there is a discontinuity between those two pixels
 - e.g. $\exp(-||C_i-C_j||^2/2\sigma^2)$
 - where σ can be a constant or the local variance
- Note positive sign

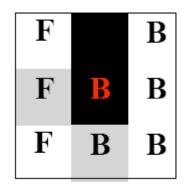


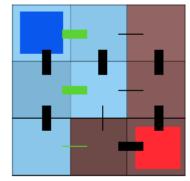
Optimization

- $E(L)=D(L)+\lambda S(L)$
- λ is a black-magic constant
- Find the labeling that minimizes E
- In this case, how many possibilities?
 - 2⁹ (512)
 - We can try them all!
 - What about megapixel images?





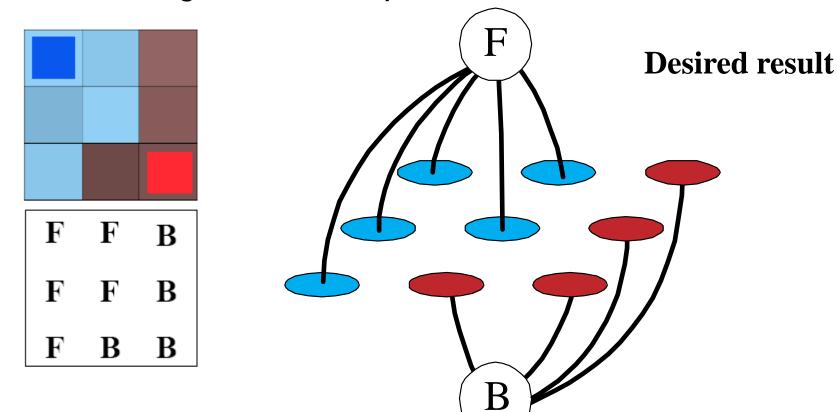






Labeling as a graph problem

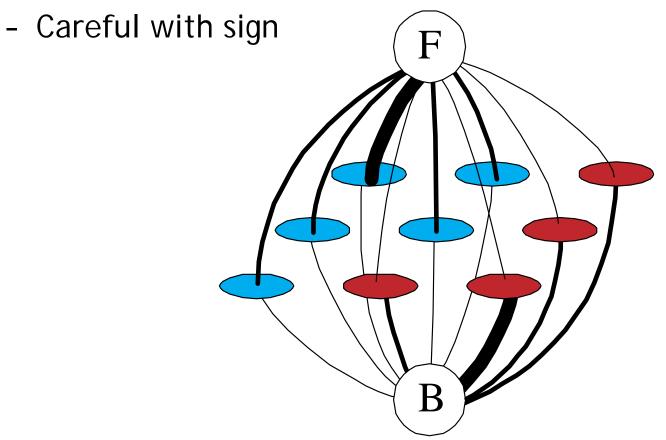
- Each pixel = node
- Add two nodes F & B
- Labeling: link each pixel to either F or B



Data term



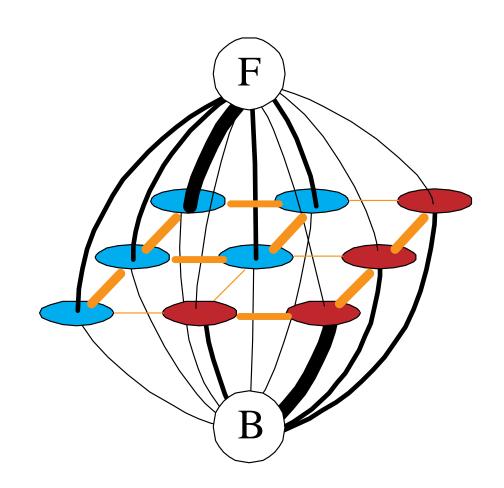
- Put one edge between each pixel and F & G
- Weight of edge = minus data term
 - Don't forget huge weight for hard constraints







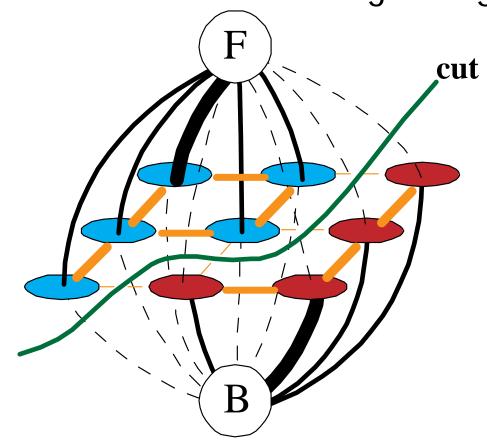
- Add an edge between each neighbor pair
- Weight = smoothness term



Min cut



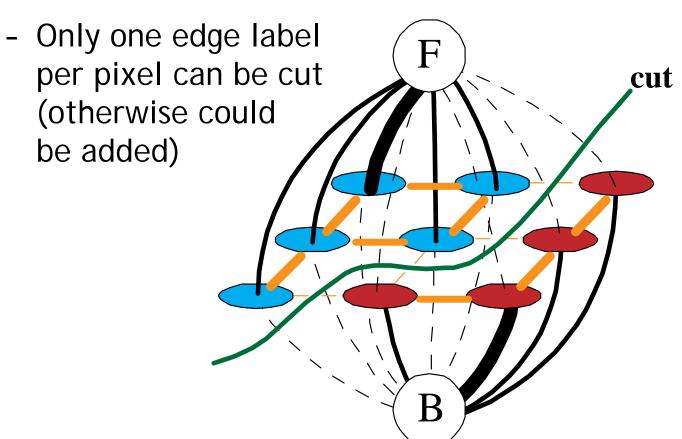
- Energy optimization equivalent to min cut
- Cut: remove edges to disconnect F from B
- Minimum: minimize sum of cut edge weight





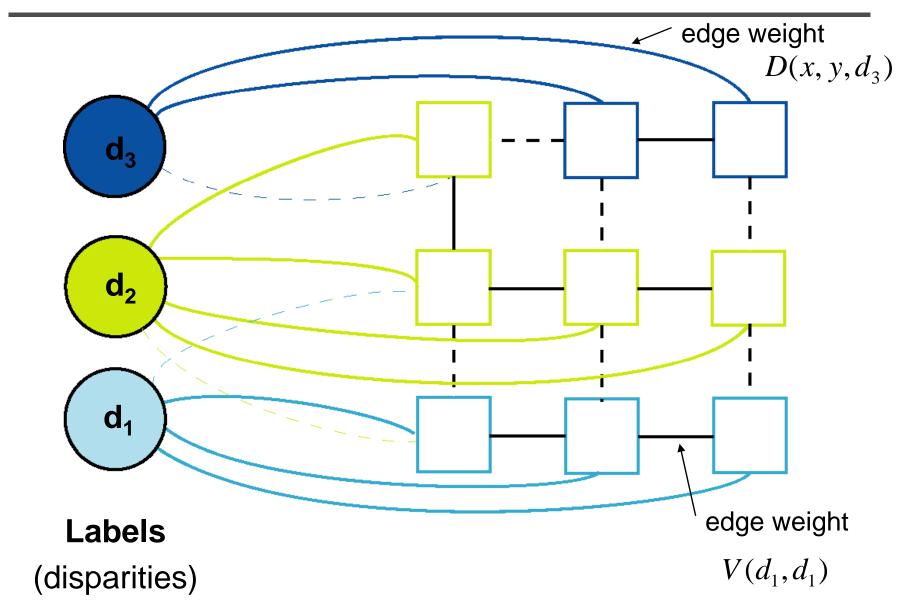
Min cut <=> labeling

- In order to be a cut:
 - For each pixel, either the F or G edge has to be cut
- In order to be minimal



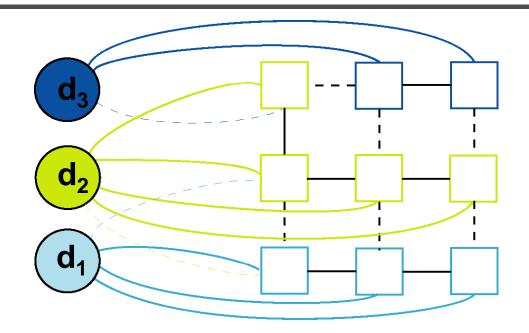


Energy minimization via graph cuts





Energy minimization via graph cuts

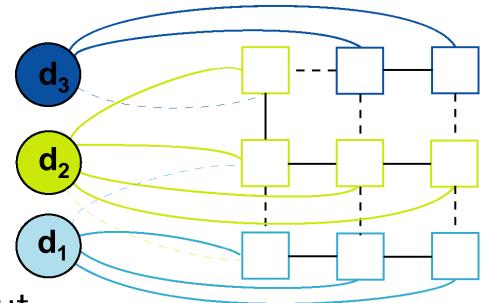


Graph Cost

- Matching cost between images
- Neighborhood matching term
- Goal: figure out which labels are connected to which pixels



Energy minimization via graph cuts



- Graph Cut
 - Delete enough edges so that
 - each pixel is (transitively) connected to exactly one label node
 - Cost of a cut: sum of deleted edge weights
 - Finding min cost cut equivalent to finding global minimum of energy function

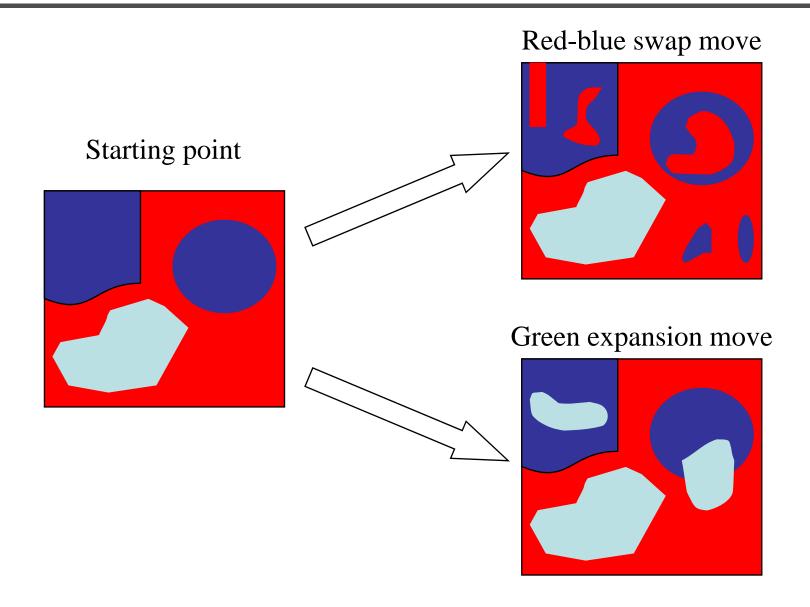


Computing a multiway cut

- With 2 labels: classical min-cut problem
 - Solvable by standard flow algorithms
 - polynomial time in theory, nearly linear in practice
 - More than 2 terminals: NP-hard [Dahlhaus *et al.*, STOC '92]
- Efficient approximation algorithms exist
 - Within a factor of 2 of optimal
 - Computes local minimum in a strong sense
 - even very large moves will not improve the energy
 - Yuri Boykov, Olga Veksler and Ramin Zabih, <u>Fast Approximate Energy Minimization via Graph Cuts</u>, International Conference on Computer Vision, September 1999.

Move examples

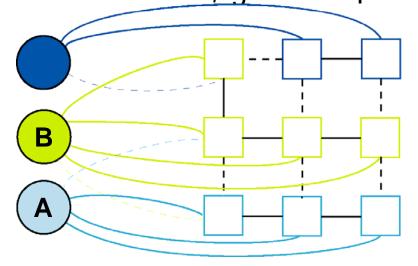




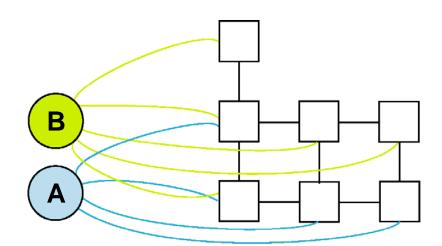


The swap move algorithm

- 1. Start with an arbitrary labeling
- 2. Cycle through every label pair (A,B) in some order
 - 2.1 Find the lowest *E* labeling within a single *AB*-swap
 - 2.2 Go there if *E* is lower than the current labeling
- 3. If *E* did not decrease in the cycle, we're done Otherwise, go to step 2



Original graph



AB subgraph (run min-cut on this graph)

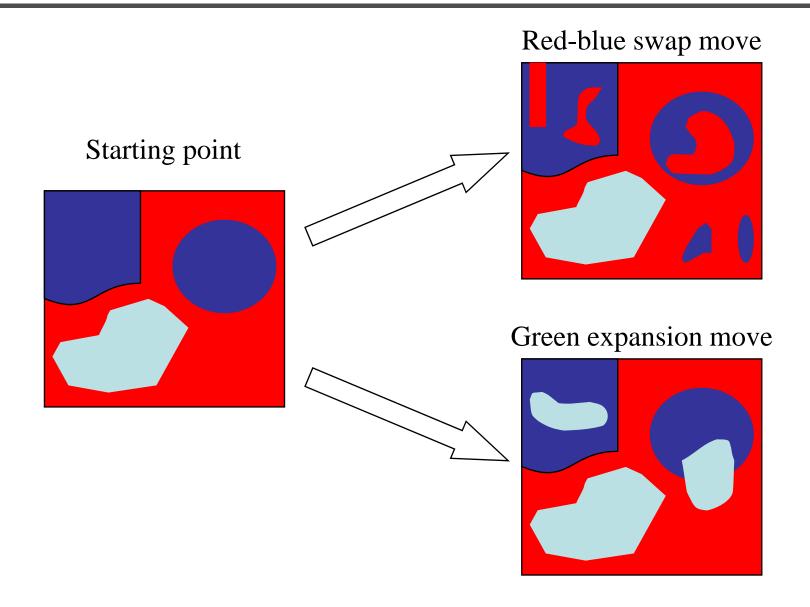


The expansion move algorithm

- 1. Start with an arbitrary labeling
- 2. Cycle through every label A in some order
 - 2.1 Find the lowest *E* labeling within a single *A*-expansion
 - 2.2 Go there if it *E* is lower than the current labeling
- 3. If *E* did not decrease in the cycle, we're done Otherwise, go to step 2

Move examples







GrabCut Interactive Foreground Extraction using Iterated Graph Cuts

Carsten Rother Valorian Colmogorov Andrew Blake



Microsoft Research Cambridge-UK

Demo



• <u>video</u>

Interactive Digital Photomontage Digivex



Combining multiple photos

Find seams using graph cuts

Combine gradients and integrate

























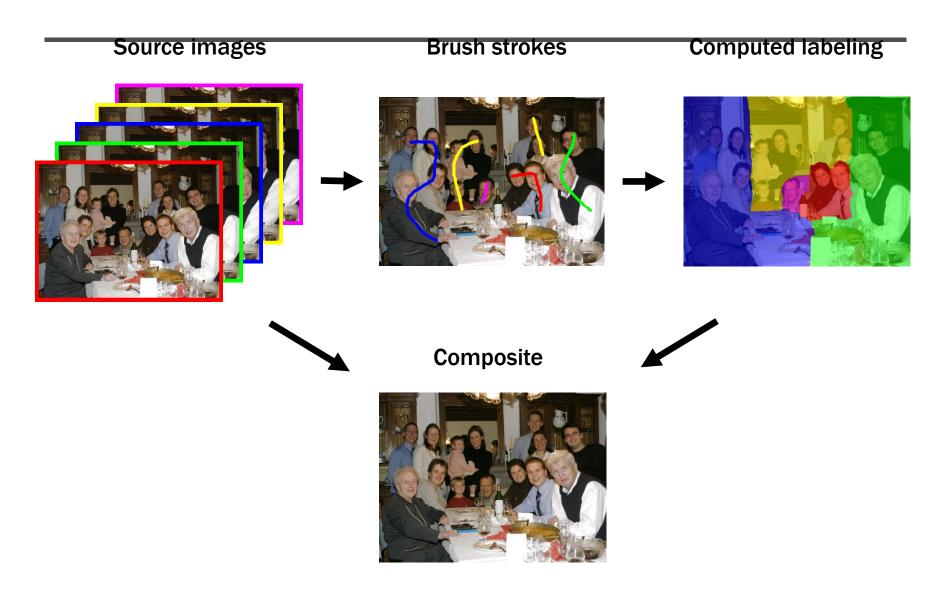




set ofaotiginals

photeimed tage







Brush strokes



Computed labeling





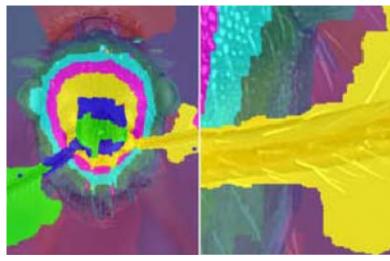
Extended depth of field









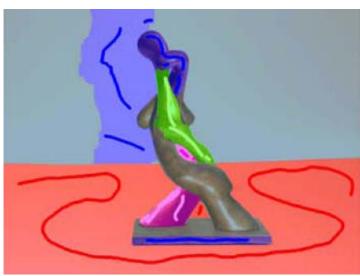




Relighting































Demo



• <u>video</u>