Faces and Image-Based Lighting

Digital Visual Effects, Spring 2008

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2007/6/3

with slides by Richard Szeliski, Steve Seitz, Alex Efros, Li-Yi Wei and Paul Debevec

Announcements



- Project #3 artifacts voting
- Final project:
 - Demo on 6/25 (Wednesday) 13:30pm in this room
 - Reports and videos due on 6/26 (Thursday) 11:59pm

Outline



- Image-based lighting
- 3D acquisition for faces
- Statistical methods (with application to face super-resolution)
- 3D Face models from single images
- Image-based faces
- Relighting for faces

Image-based lighting



Rendering

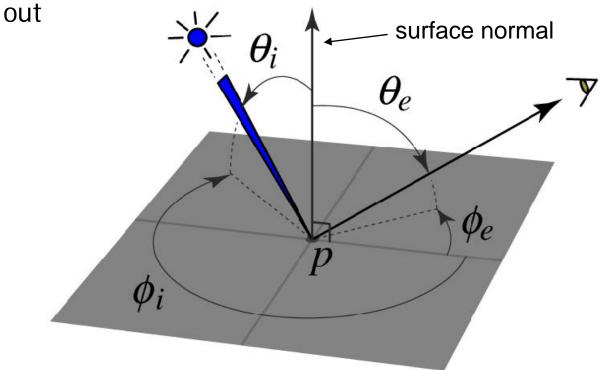
- Rendering is a function of geometry, reflectance, lighting and viewing.
- To synthesize CGI into real scene, we have to match the above four factors.
- Viewing can be obtained from calibration or structure from motion.
- Geometry can be captured using 3D photography or made by hands.
- How to capture lighting and reflectance?

Reflectance



The Bidirectional Reflection Distribution Function

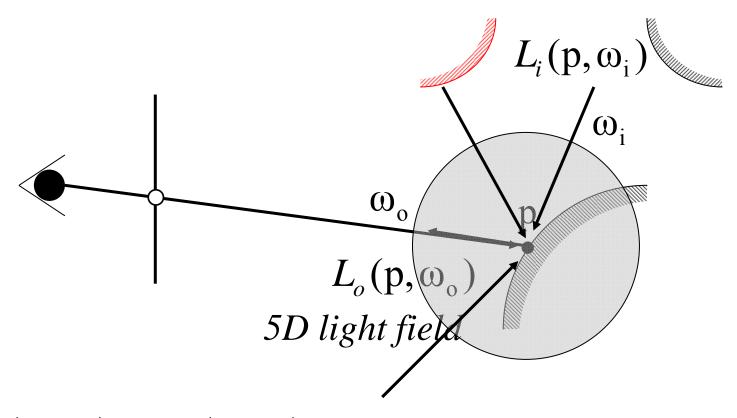
– Given an incoming ray (θ_i, ϕ_i) and outgoing ray (θ_e, ϕ_e) what proportion of the incoming light is reflected along



Answer given by the BRDF: $ho(heta_i,\phi_i,\phi_e,\phi_e)$

Rendering equation





$$L_o(\mathbf{p}, \omega_o) = L_e(\mathbf{p}, \omega_o) + \int_{s^2} \rho(\mathbf{p}, \omega_o, \omega_i) L_i(\mathbf{p}, \omega_i) |\cos \theta_i| d\omega_i$$



Complex illumination

$$L_{o}(\mathbf{p}, \omega_{o}) = L_{e}(\mathbf{p}, \omega_{o})$$

$$+ \int_{s^{2}} f(\mathbf{p}, \omega_{o}, \omega_{i}) L_{i}(\mathbf{p}, \omega_{i}) |\cos \theta_{i}| d\omega_{i}$$

$$B(\mathbf{p}, \omega_{o}) = \int_{s^{2}} f(\mathbf{p}, \omega_{o}, \omega_{i}) L_{d}(\mathbf{p}, \omega_{i}) |\cos \theta_{i}| d\omega_{i}$$

$$reflectance \quad lighting$$





People perceive materials more easily under natural illumination than simplified illumination.



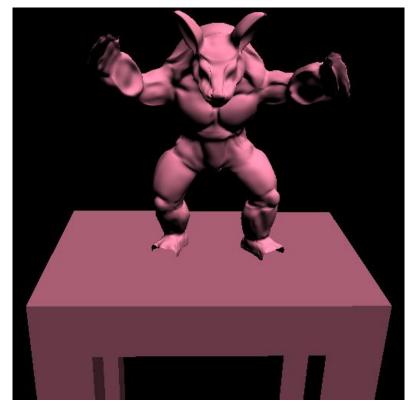


Images courtesy Ron Dror and Ted Adelson





Rendering with natural illumination is more expensive compared to using simplified illumination



directional source



natural illumination

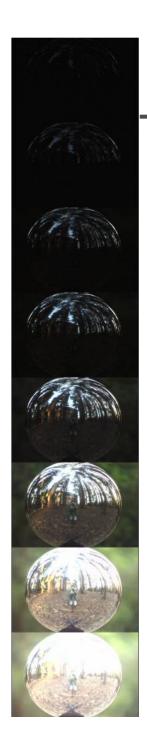
Environment maps







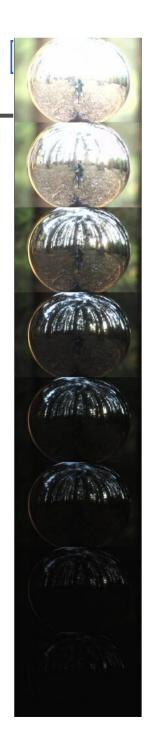
Miller and Hoffman, 1984



Acquiring the Light Probe







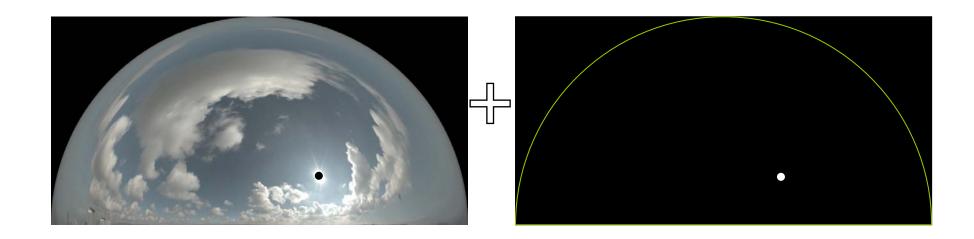
HDRI Sky Probe





Clipped Sky + Sun Source

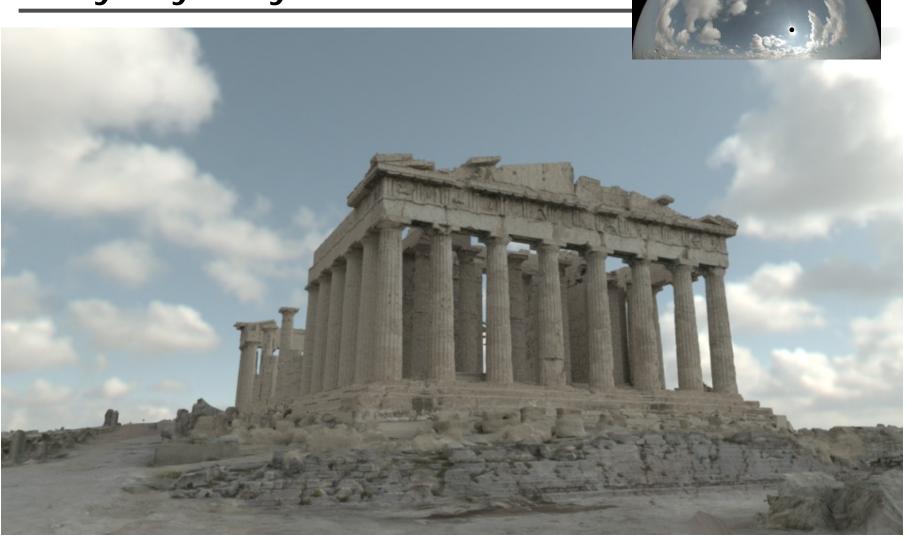




Lit by sun only

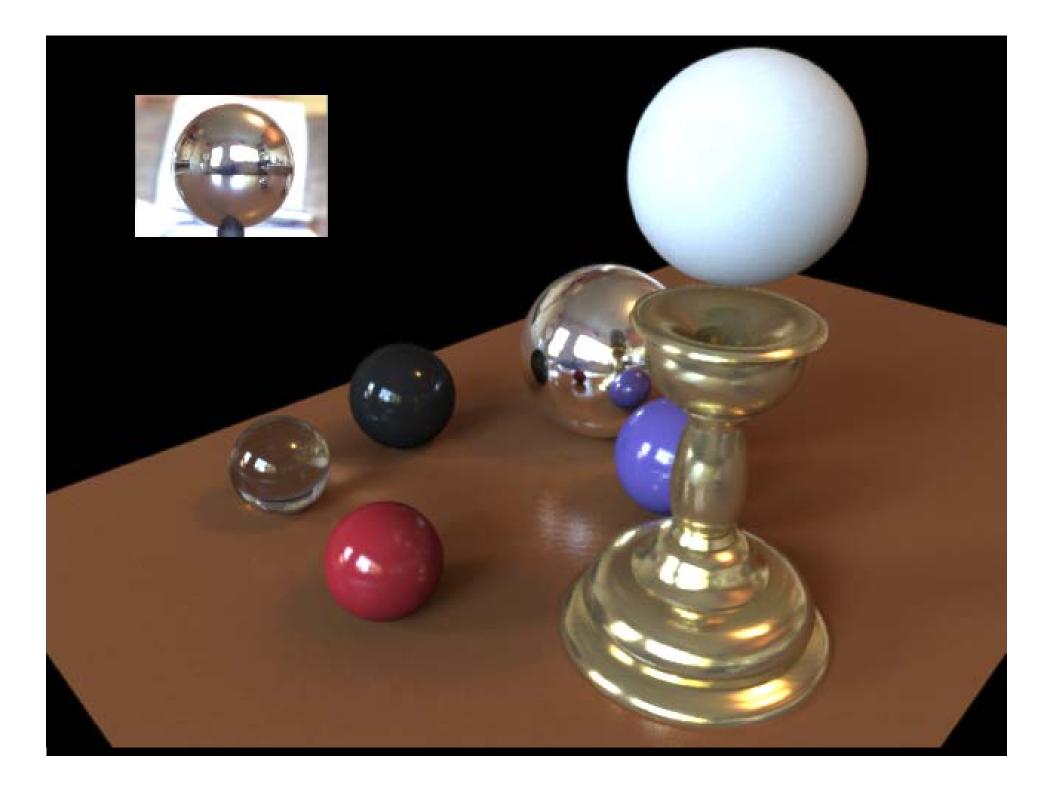


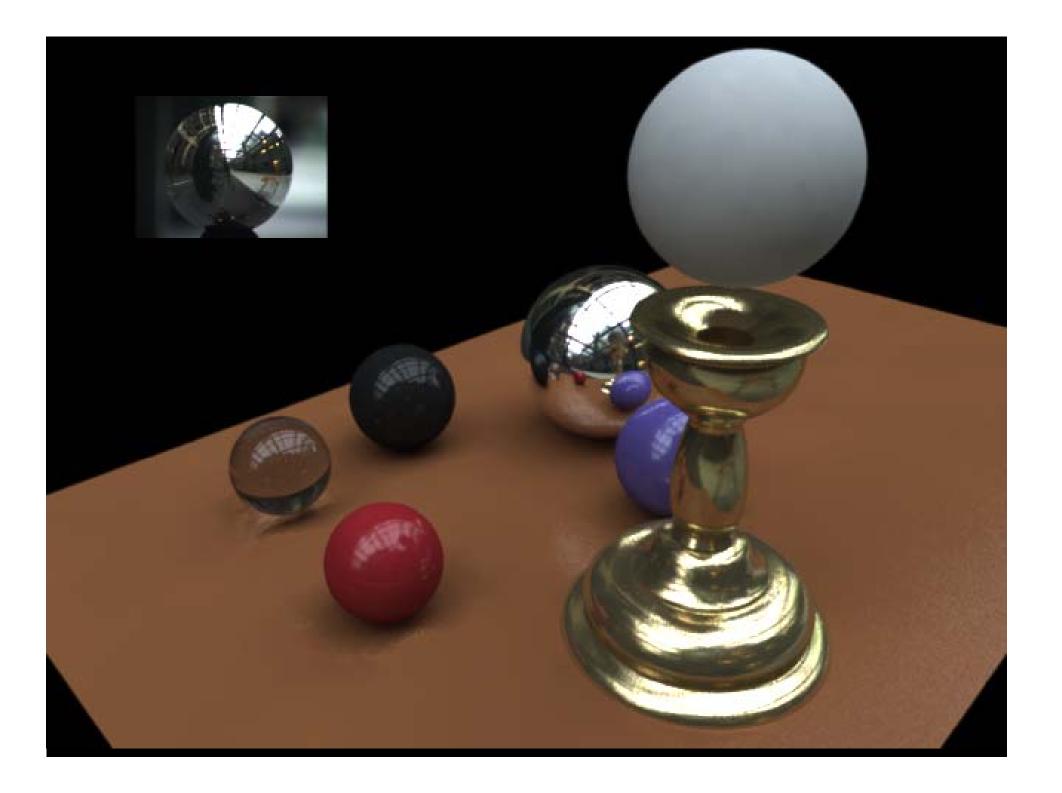
Lit by sky only



Lit by sun and sky









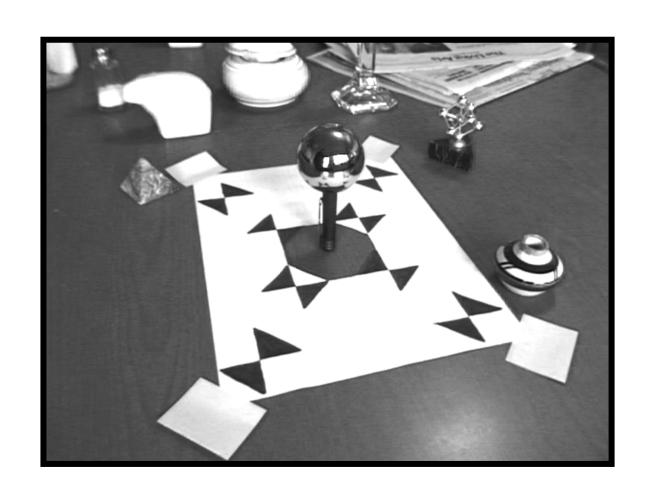




Goal: place synthetic objects on table

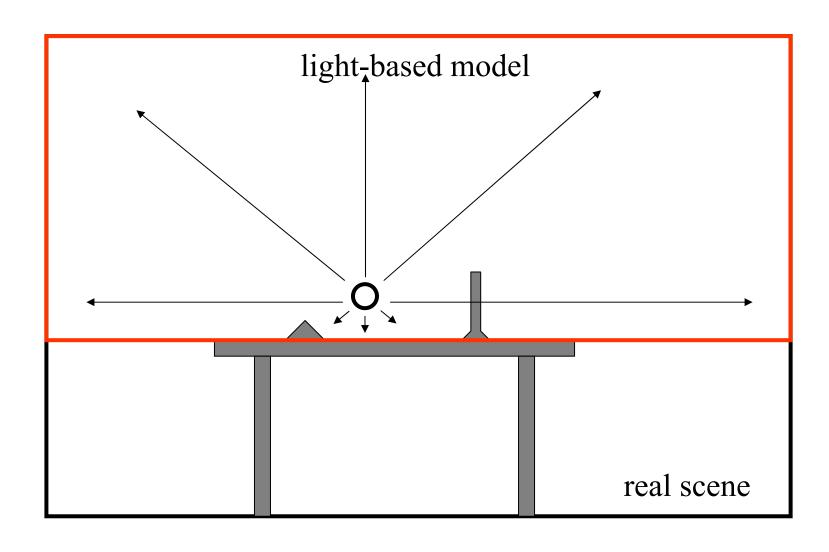


Light Probe / Calibration Grid



Modeling the Scene

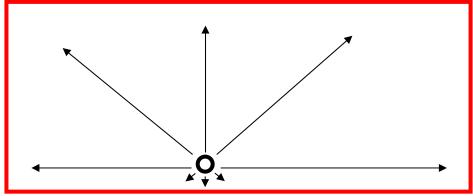






The Light-Based Room Model







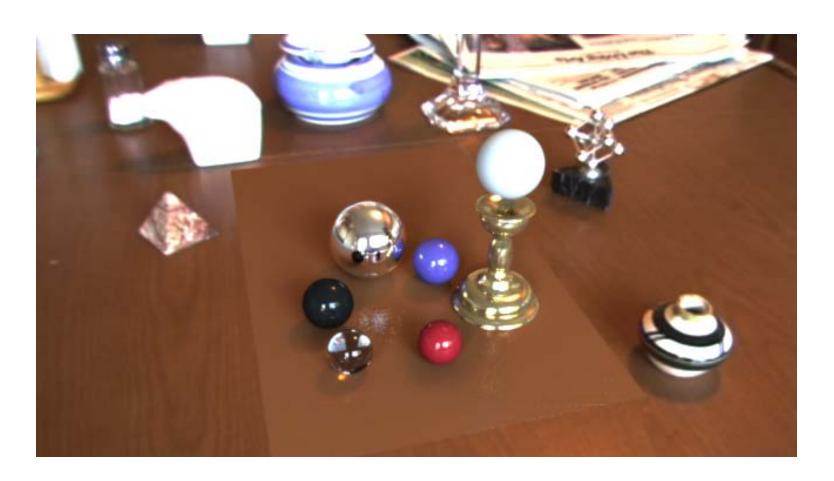
Rendering into the Scene



• Background Plate



Rendering into the scene



• Objects and Local Scene matched to Scene

Differential rendering





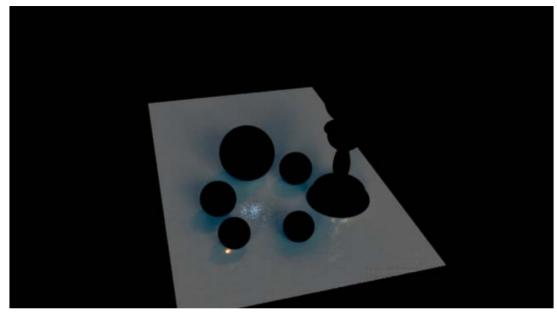
Local scene w/o objects, illuminated by model

Differential rendering



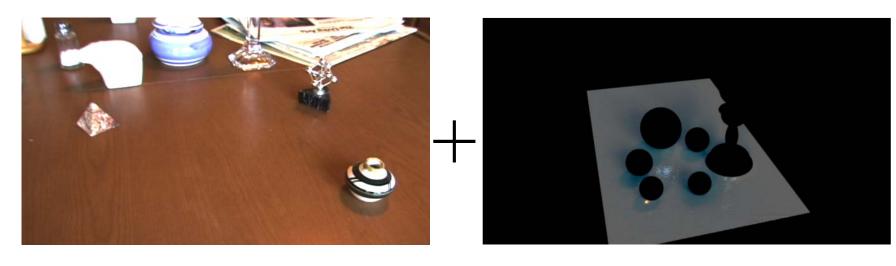




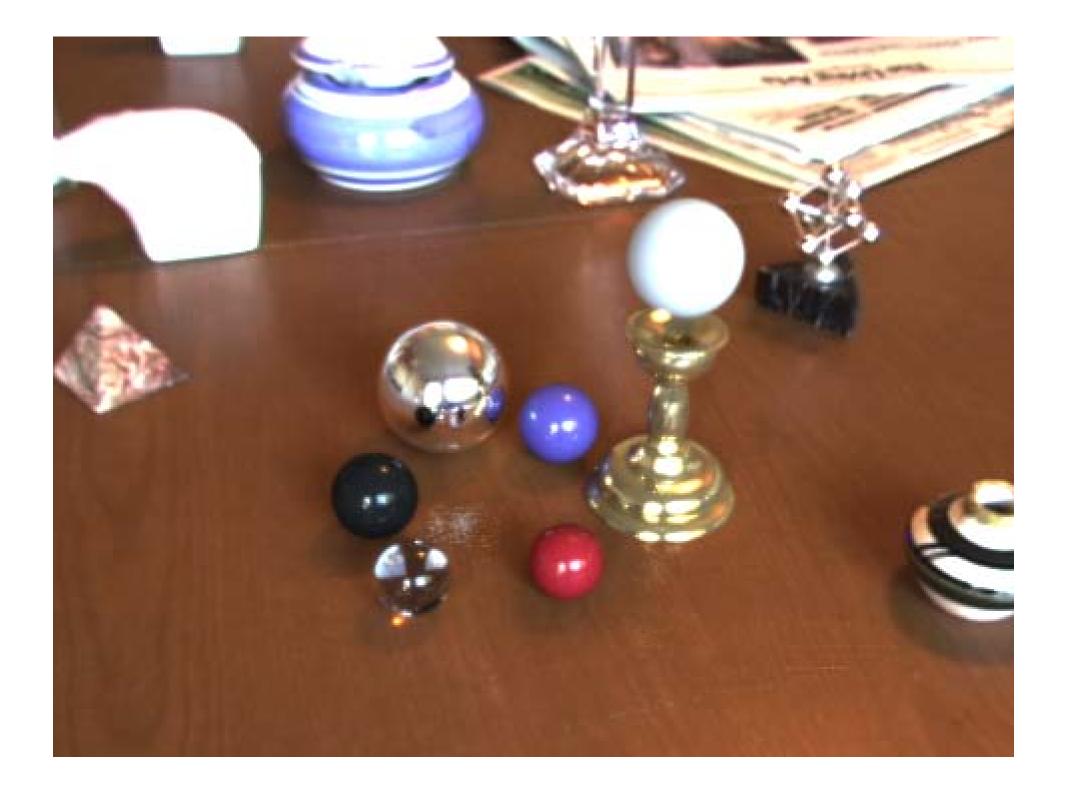


Differential rendering









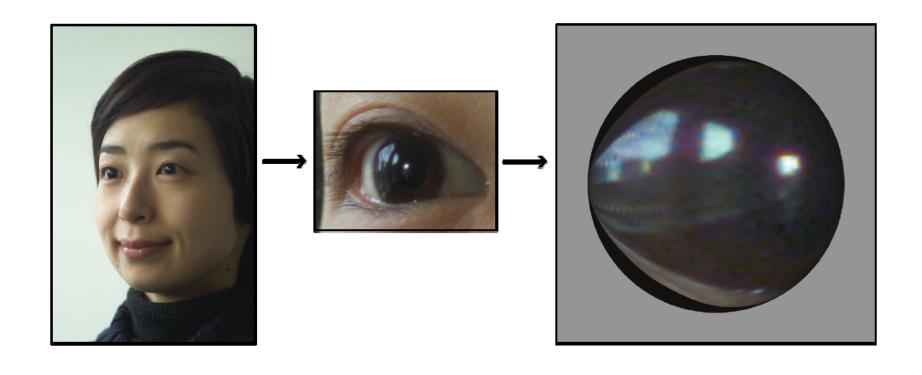
Environment map from single image? DigiVFX





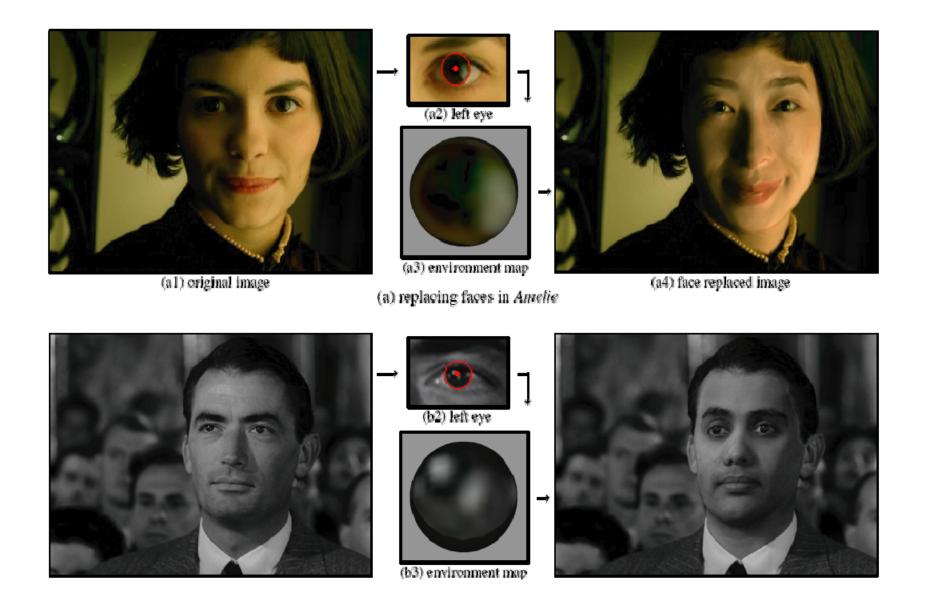


Eye as light probe! (Nayar et al)



Results







Application in "Superman returns"

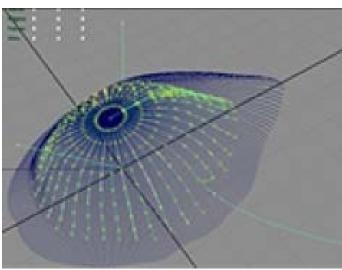




Capturing reflectance



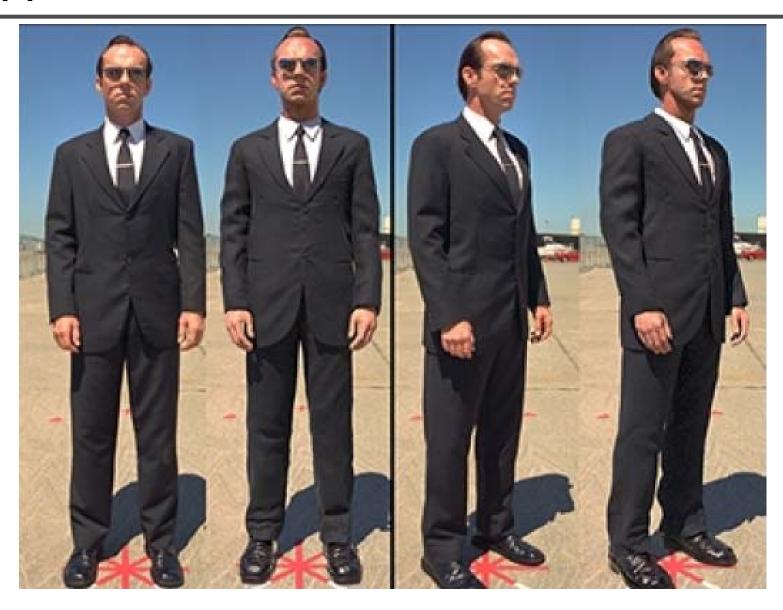






Application in "The Matrix Reloaded" DigiVFX





3D acquisition for faces

Cyberware scanners







face & head scanner

whole body scanner

Making facial expressions from photos

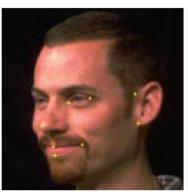
- Similar to Façade, use a generic face model and view-dependent texture mapping
- Procedure
 - 1. Take multiple photographs of a person
 - 2. Establish corresponding feature points
 - 3. Recover 3D points and camera parameters
 - 4. Deform the generic face model to fit points
 - 5. Extract textures from photos





input photographs



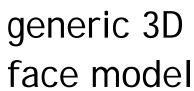














pose estimation



more features

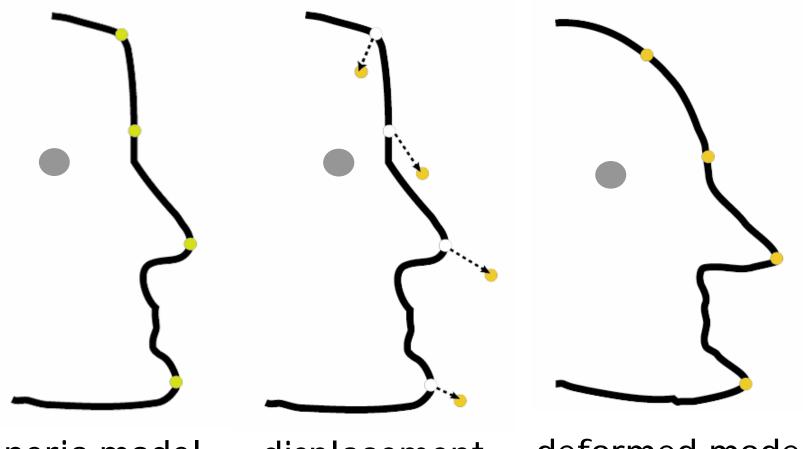


deformed model

Mesh deformation



- Compute displacement of feature points
- Apply scattered data interpolation



generic model

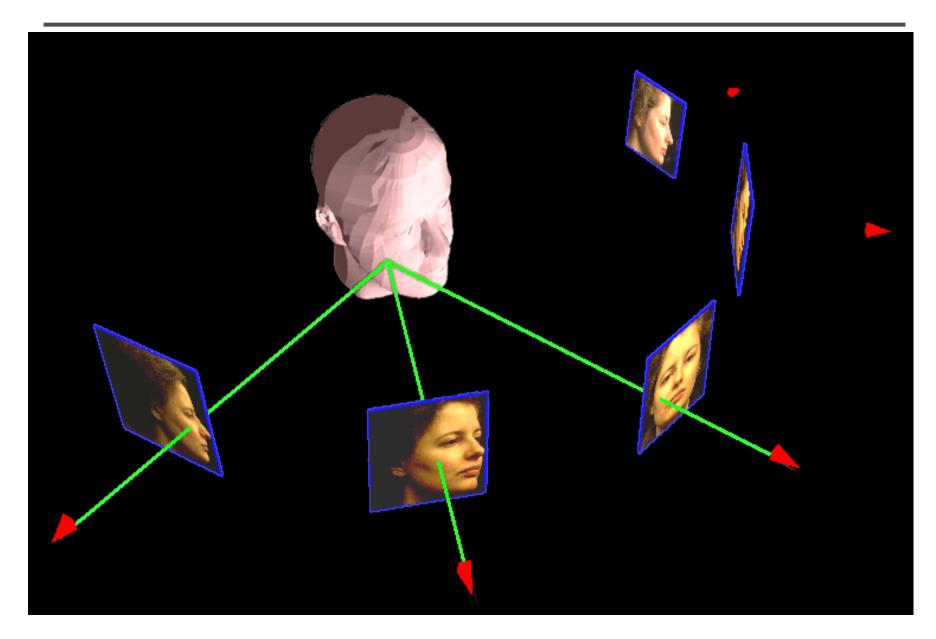
displacement

deformed model



- The color at each point is a weighted combination of the colors in the photos
- Texture can be:
 - view-independent
 - view-dependent
- Considerations for weighting
 - occlusion
 - smoothness
 - positional certainty
 - view similarity



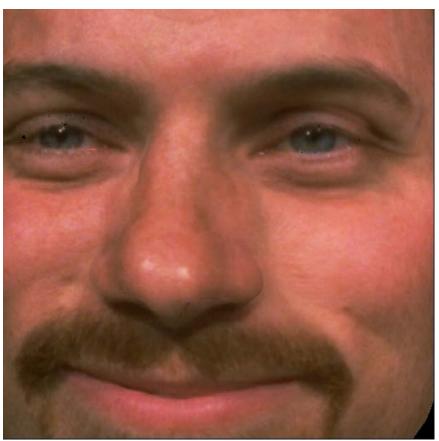










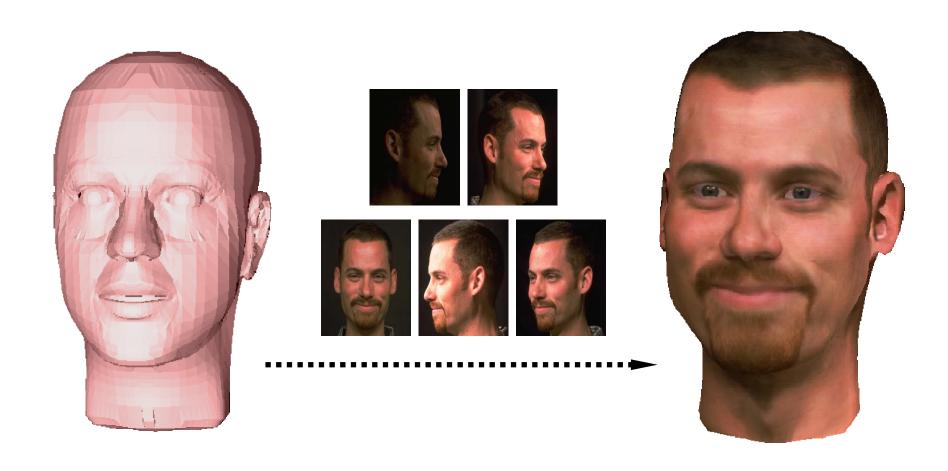


view-independent

view-dependent

Model reconstruction





Use images to adapt a generic face model.



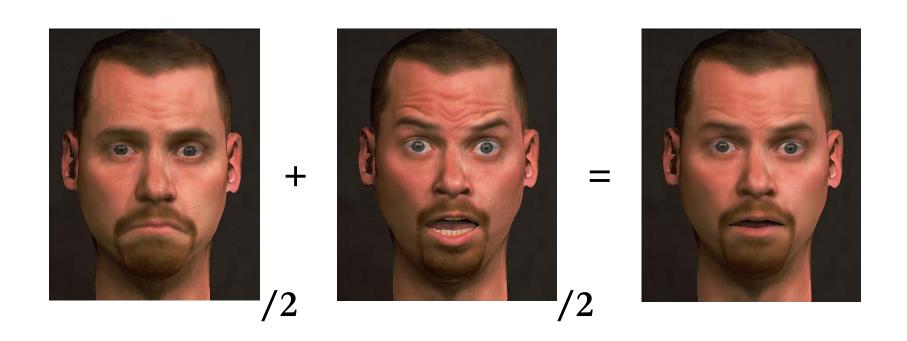
Creating new expressions

- In addition to global blending we can use:
 - Regional blending
 - Painterly interface





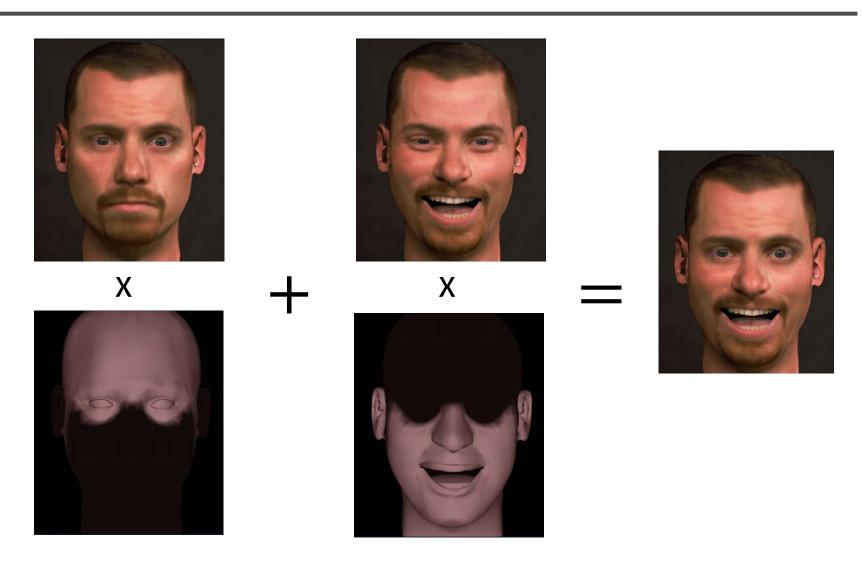
New expressions are created with 3D morphing:



Applying a global blend



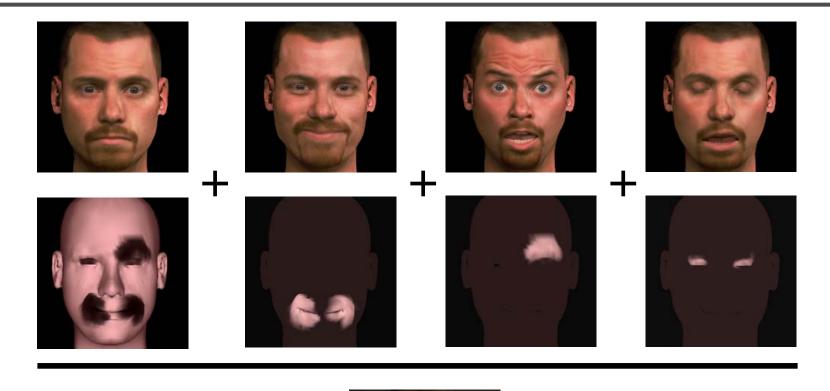




Applying a region-based blend



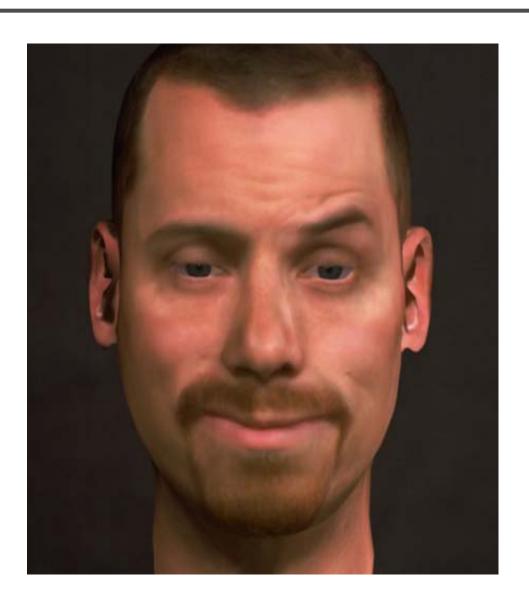
Creating new expressions



Using a painterly interface

Drunken smile







Animating between expressions

Morphing over time creates animation:







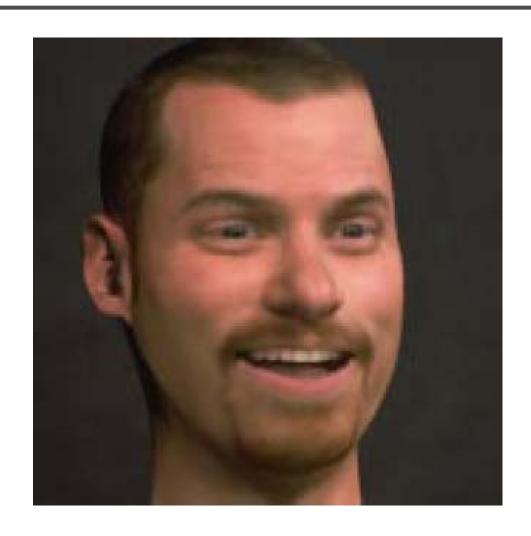


"neutral"

"joy"

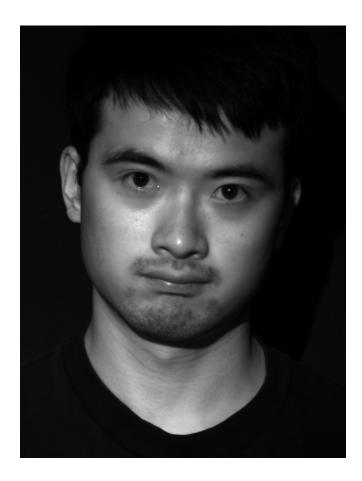
Video





Spacetime faces

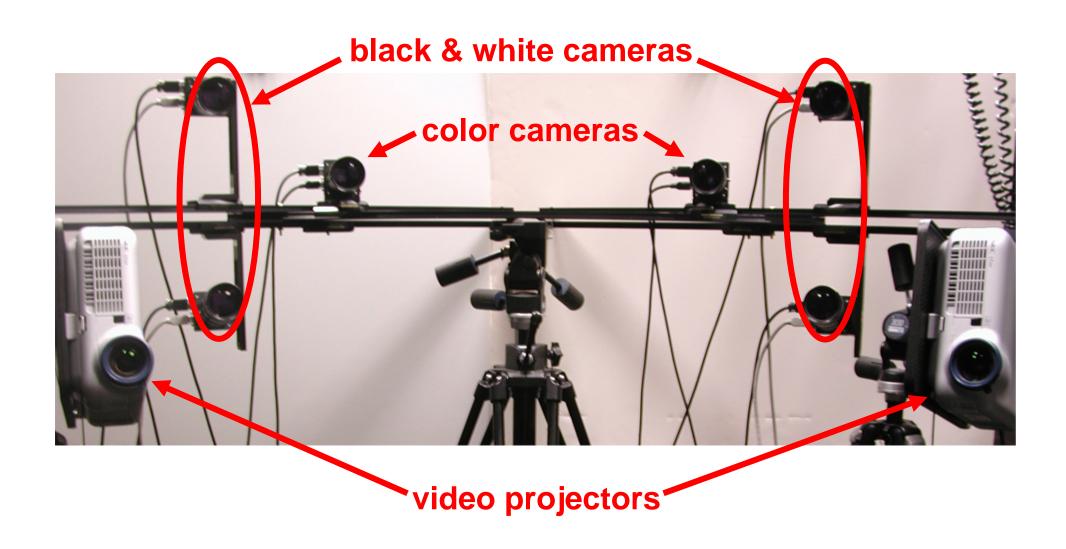


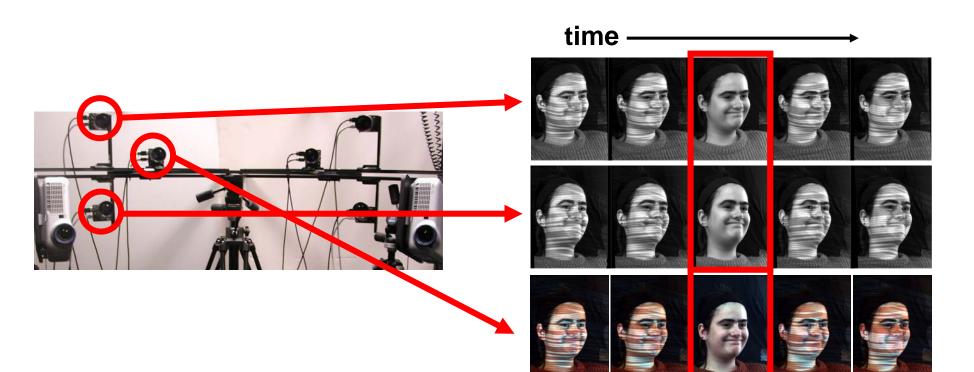


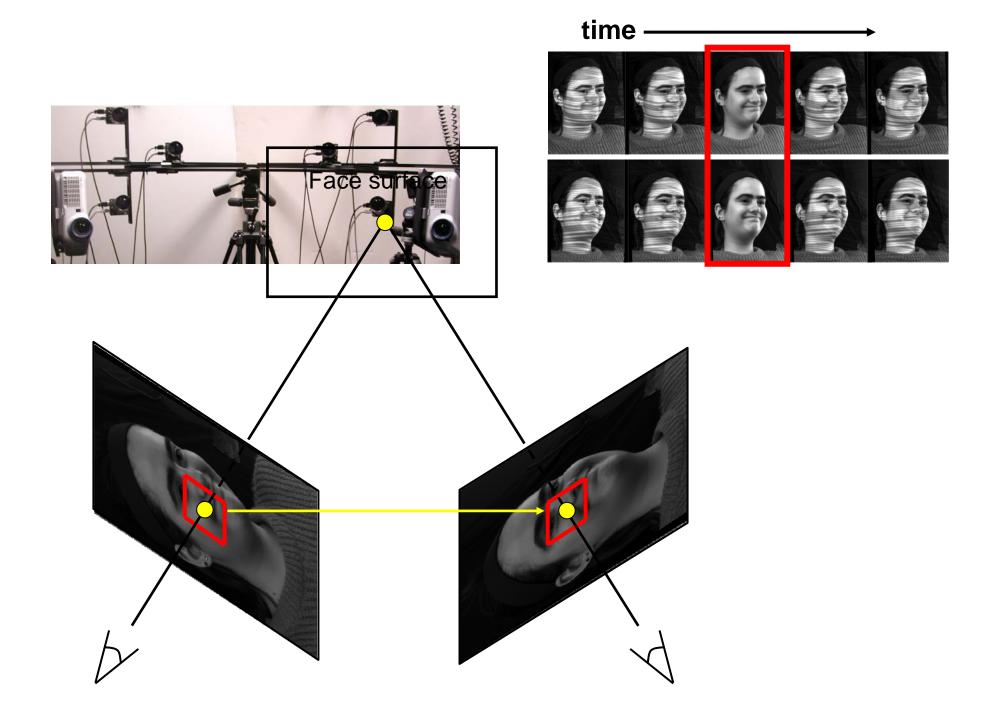


Spacetime faces

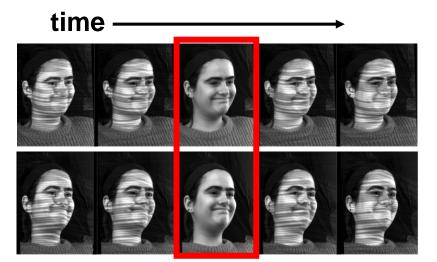




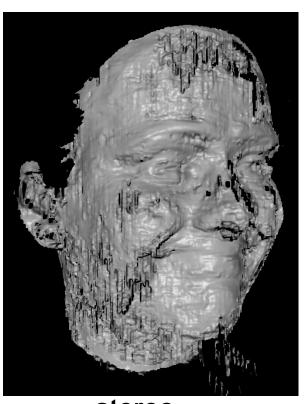




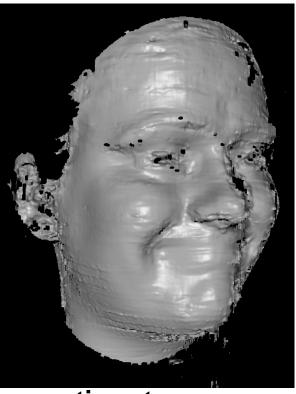
stereo



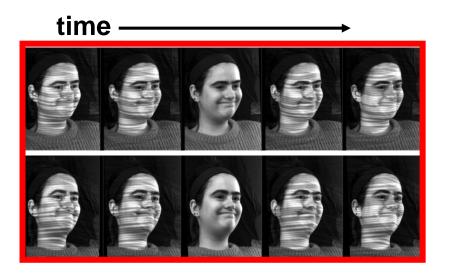
time — Figure 1 - Figu

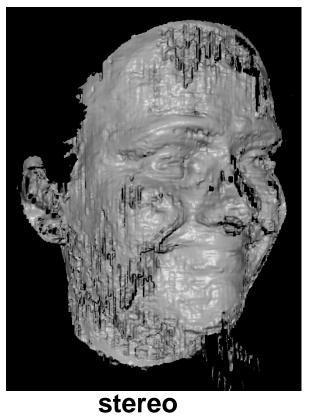


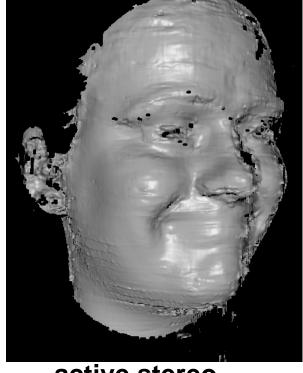


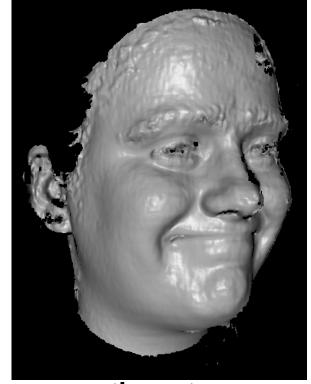


active stereo



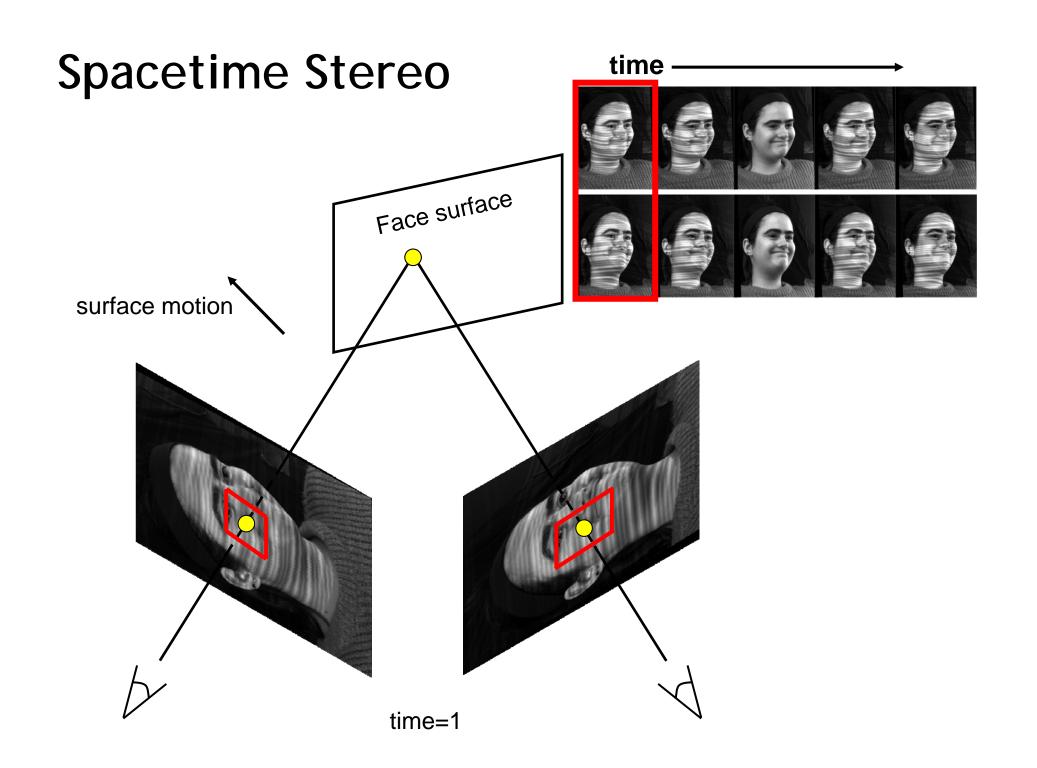


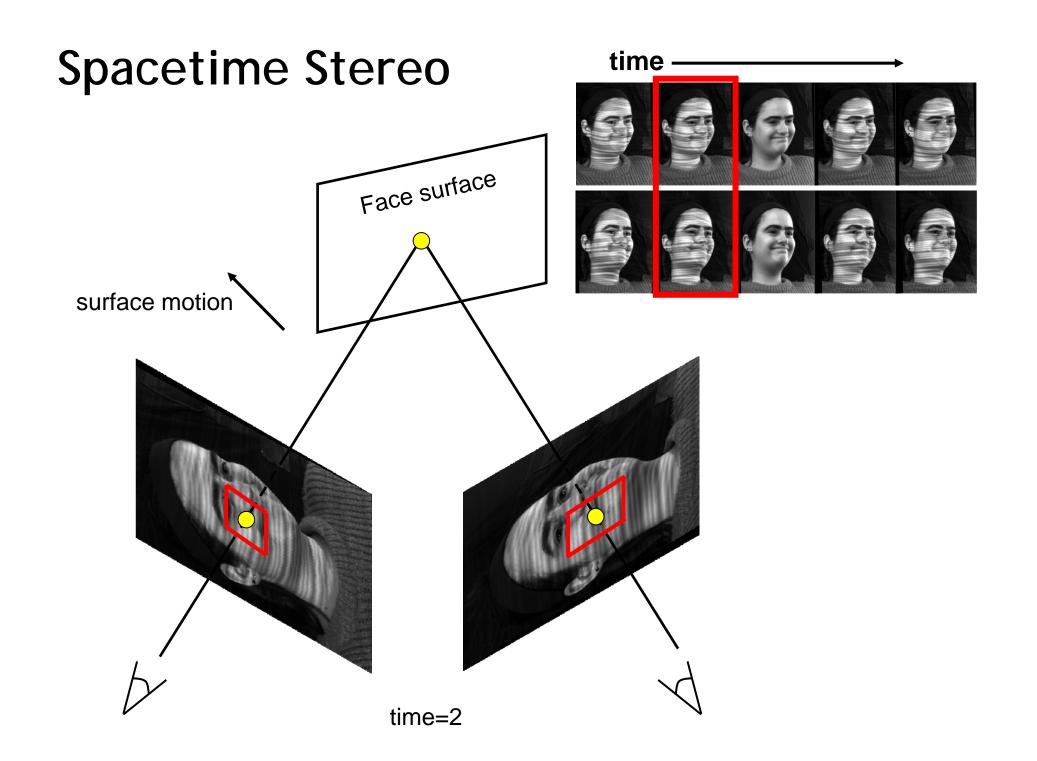


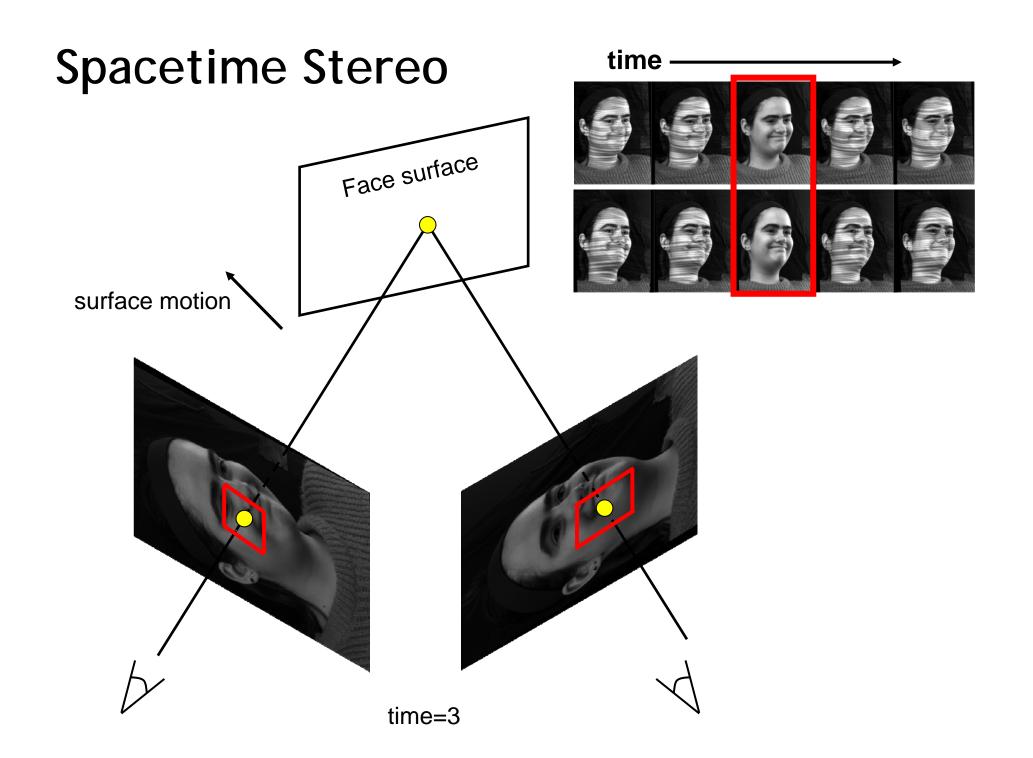


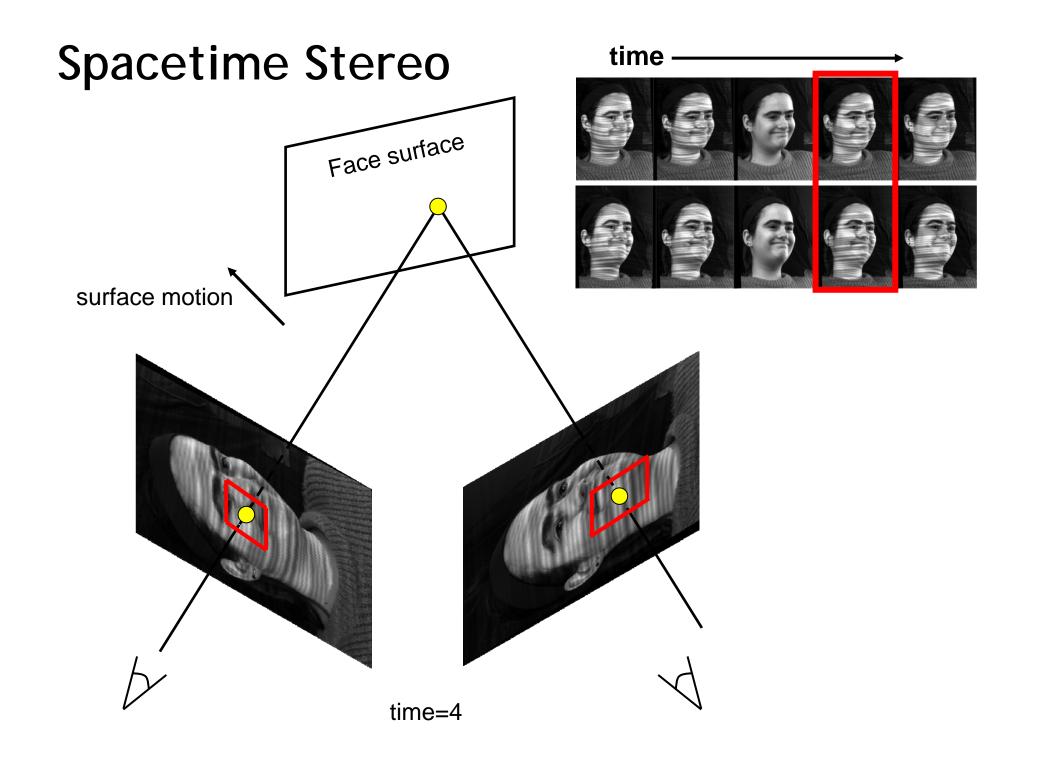
active stereo

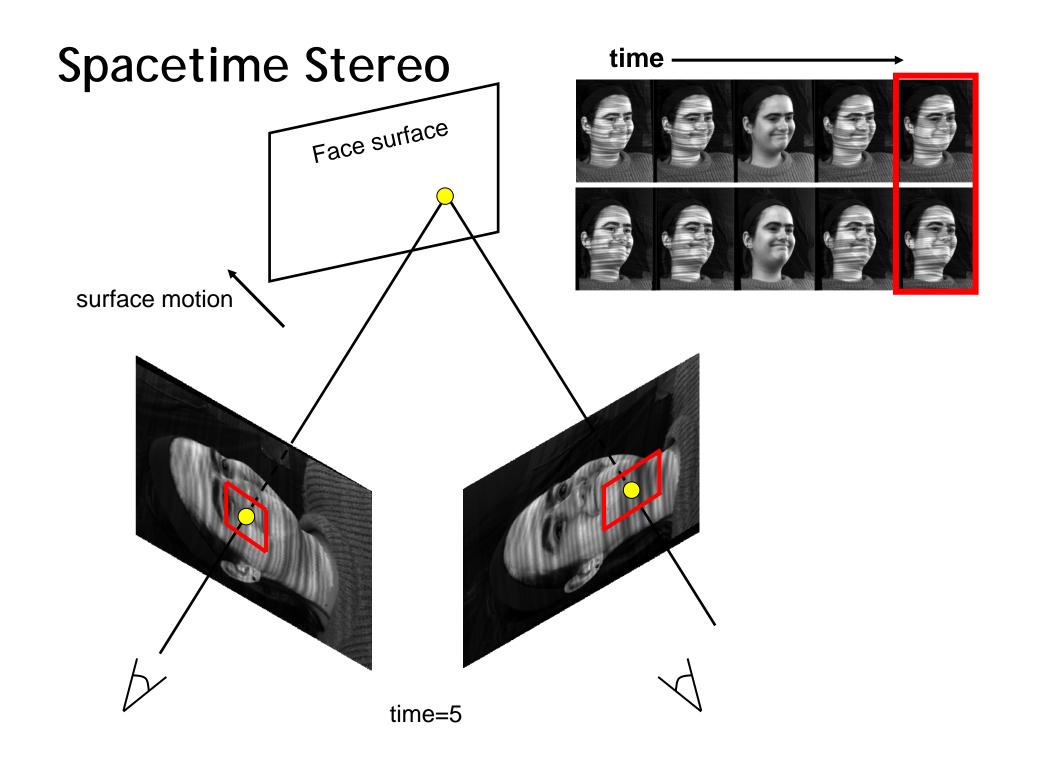
spacetime stereo

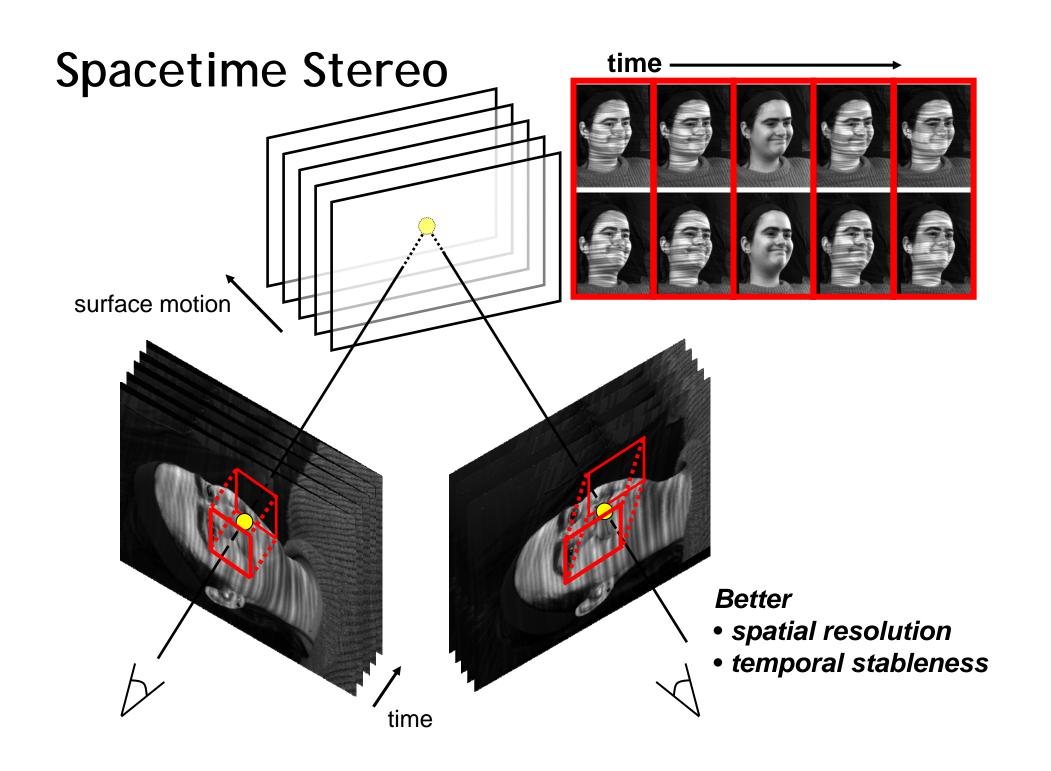








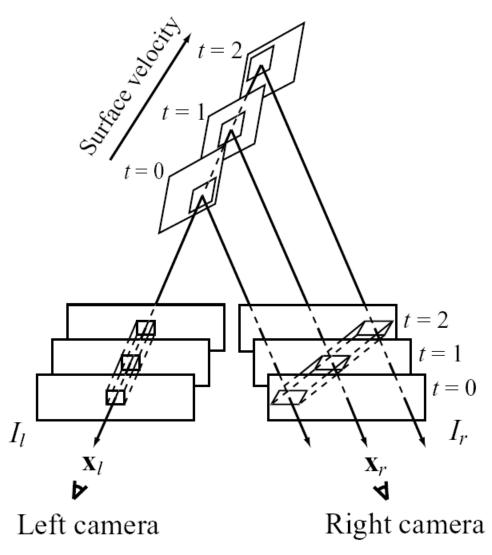






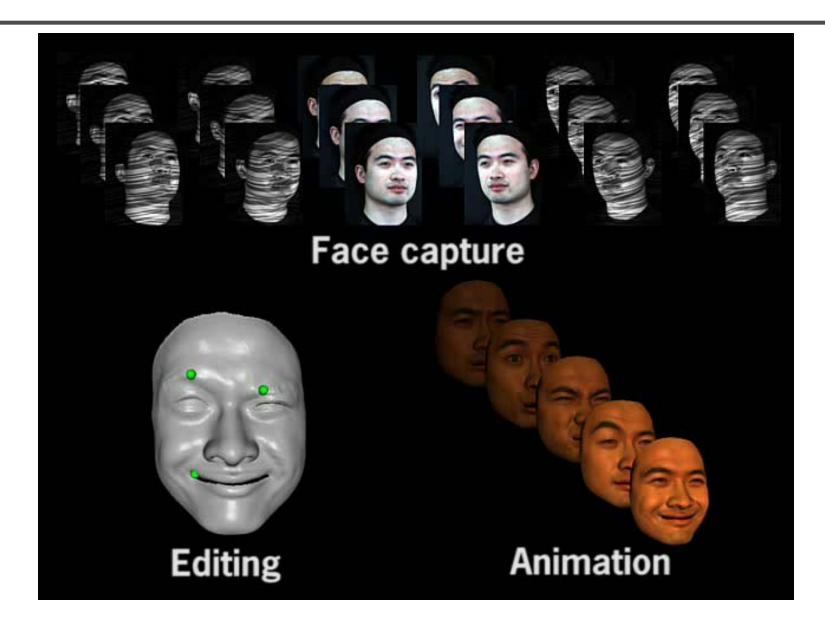
Spacetime stereo matching

A moving oblique surface



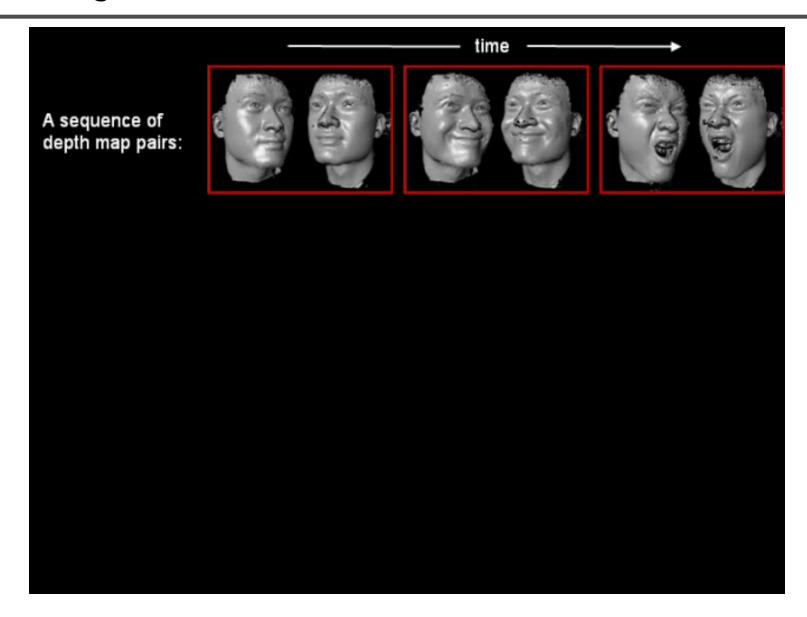
Video





Fitting



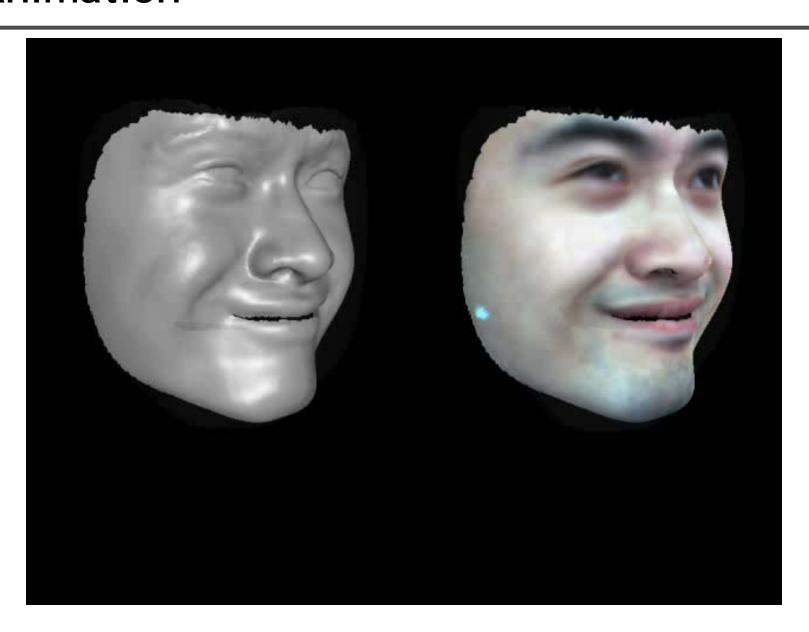






Animation







3D face applications: The one







3D face applications: Gladiator



extra 3M



para-
meters
$$z \longrightarrow f(z)+\varepsilon \longrightarrow y$$
 observed
signal

$$z^* = \max_{z} P(z \mid y)$$

$$= \max_{z} \frac{P(y \mid z)P(z)}{P(y)}$$

$$= \min_{z} L(y \mid z) + L(z)$$

$$= \min_{z} L(y \mid z) + L(z)$$

Example: super-resolution de-noising de-blocking Inpainting



para-
meters
$$z \longrightarrow f(z)+\varepsilon \longrightarrow y$$
 observed
signal

$$z^* = \min_{z} L(y \mid z) + L(z)$$

$$\text{data} \quad \frac{\|y - f(z)\|^2}{\sigma^2} \quad \text{a-priori}$$

$$\text{evidence} \quad \sigma^2 \quad \text{knowledge}$$



There are approximately 10^{240} possible 10×10 gray-level images. Even human being has not seen them all yet. There must be a strong statistical bias.

Takeo Kanade

Approximately 8X10¹¹ blocks per day per person.



"Smooth images are good images."

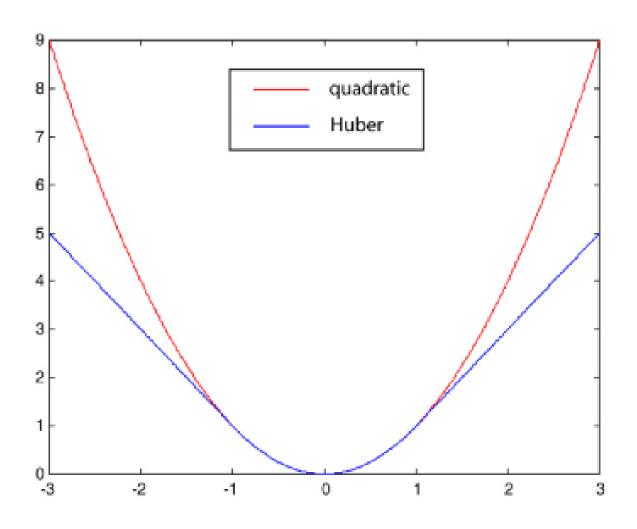
$$L(z) = \sum_{x} \rho(V(x))$$

Gaussian MRF $\rho(d) = d^2$

Huber MRF
$$\rho(d) = \begin{cases} d^2 & |d| \le T \\ T^2 + 2T(|d| - T) & d > T \end{cases}$$











"Existing images are good images."









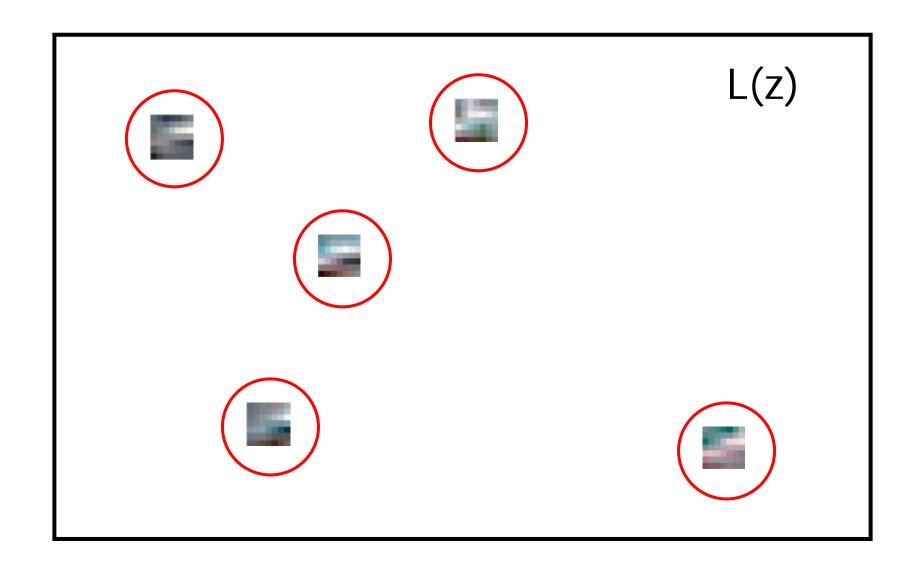




six 200×200 Images \Rightarrow 2,000,000 pairs

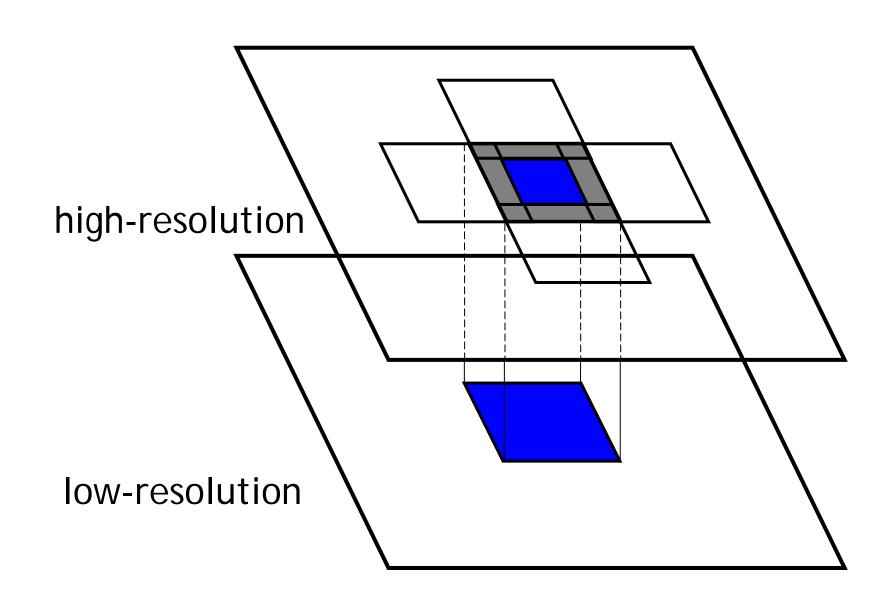
















"Face images are good images when working on face images ..."

Parametric model

$$Z=WX+\mu$$

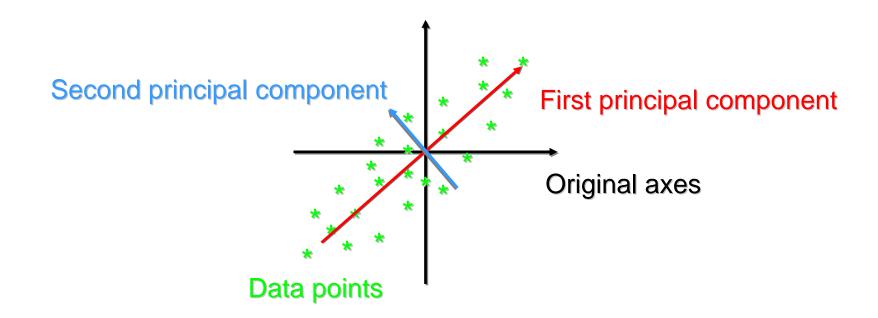
$$z^* = \min_{z} L(y \mid z) + L(z)$$

$$\begin{cases} X^* = \min_{X} L(y \mid WX + \mu) + L(X) \\ Z^* = WX^* + \mu \end{cases}$$

PCA

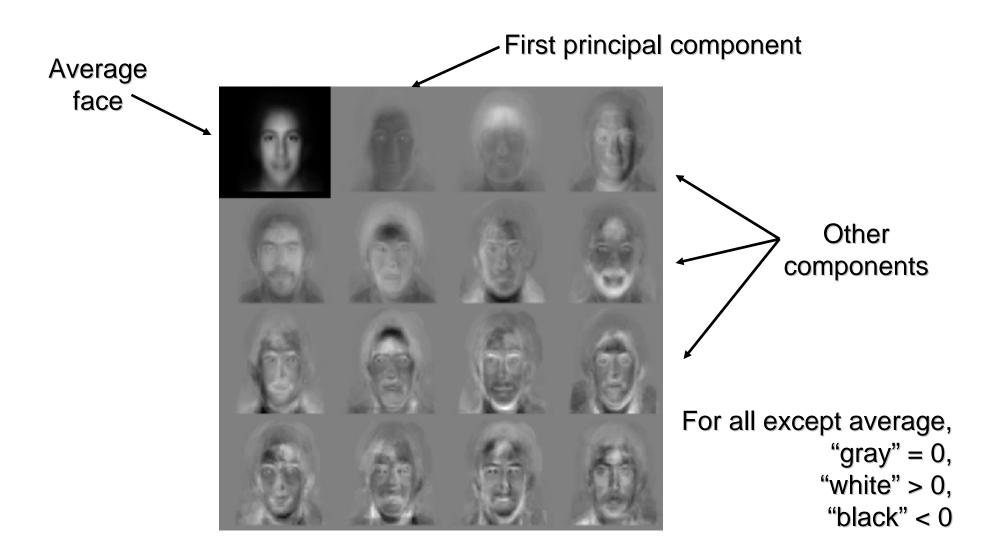


 Principal Components Analysis (PCA): approximating a high-dimensional data set with a lower-dimensional subspace



PCA on faces: "eigenfaces"









"Face images are good images when working on face images ..."

Parametric model

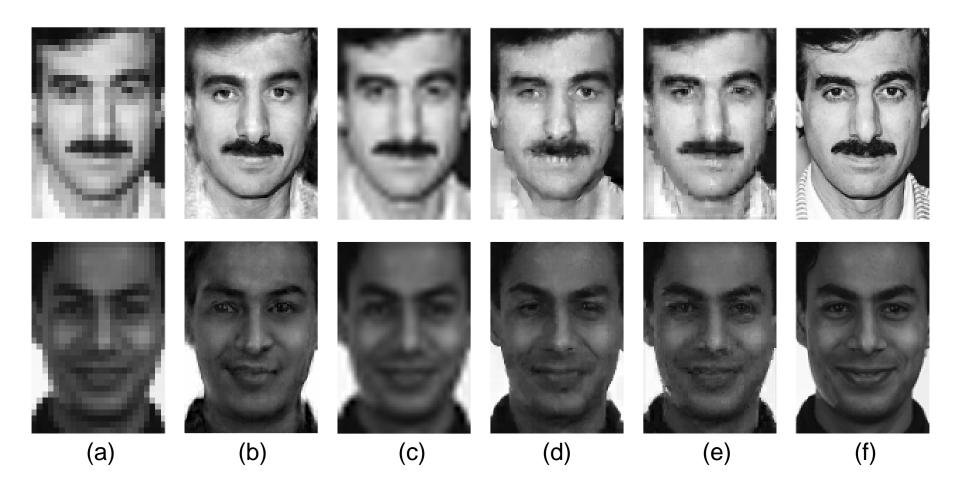
$$Z=WX+\mu$$

$$z^* = \min_{z} L(y \mid z) + L(z)$$

$$\begin{cases} X^* = \min_{X} L(y \mid WX + \mu) + L(X) \\ Z^* = WX^* + \mu \end{cases}$$

Super-resolution





(a) Input low 24×32

(b) Our results (c) Cubic B-Spline

(d) Freeman et al.

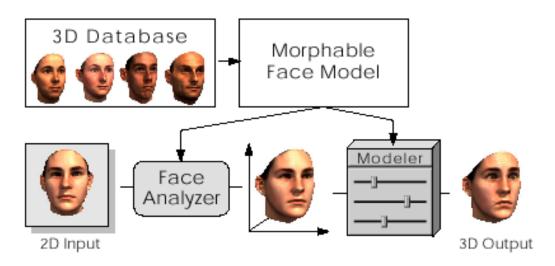
(e) Baker et al. (f) Original high 96×128

Face models from single images



Morphable model of 3D faces

 Start with a catalogue of 200 aligned 3D Cyberware scans



 Build a model of average shape and texture, and principal variations using PCA

Morphable model



shape examplars texture examplars

$$S_{model} = \overline{S} + \sum_{i=1}^{m-1} \alpha_i s_i, \quad T_{model} = \overline{T} + \sum_{i=1}^{m-1} \beta_i t_i, \quad (1)$$

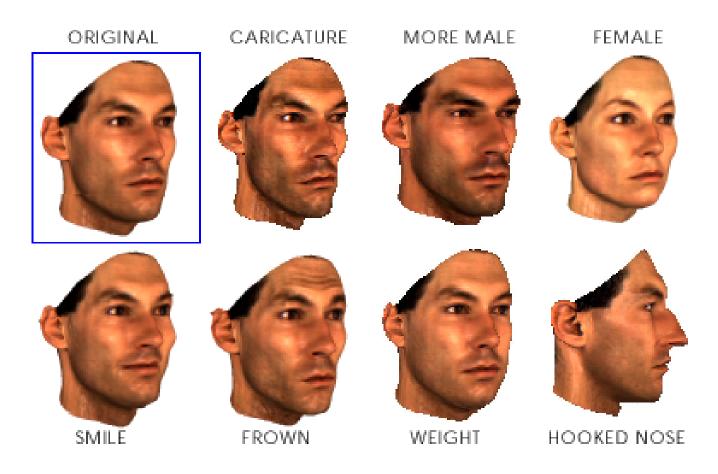
 $\vec{\alpha}, \vec{\beta} \in \Re^{m-1}$. The probability for coefficients $\vec{\alpha}$ is given by

$$p(\vec{\alpha}) \sim exp[-\frac{1}{2} \sum_{i=1}^{m-1} (\alpha_i / \sigma_i)^2],$$
 (2)



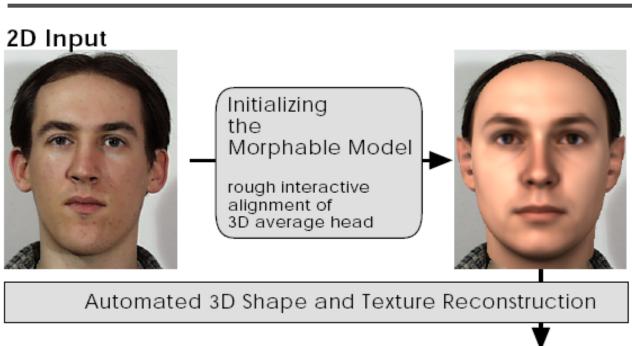
Morphable model of 3D faces

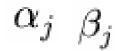
Adding some variations





Reconstruction from single image











Rendering must be similar to the input if we guess right



Reconstruction from single image

$$E = \frac{1}{\sigma_N^2} E_I + \sum_{j=1}^{m-1} \frac{\alpha_j^2}{\sigma_{S,j}^2} + \sum_{j=1}^{m-1} \frac{\beta_j^2}{\sigma_{T,j}^2} + \sum_j \frac{(\rho_j - \bar{\rho}_j)^2}{\sigma_{\rho,j}^2}$$
prior

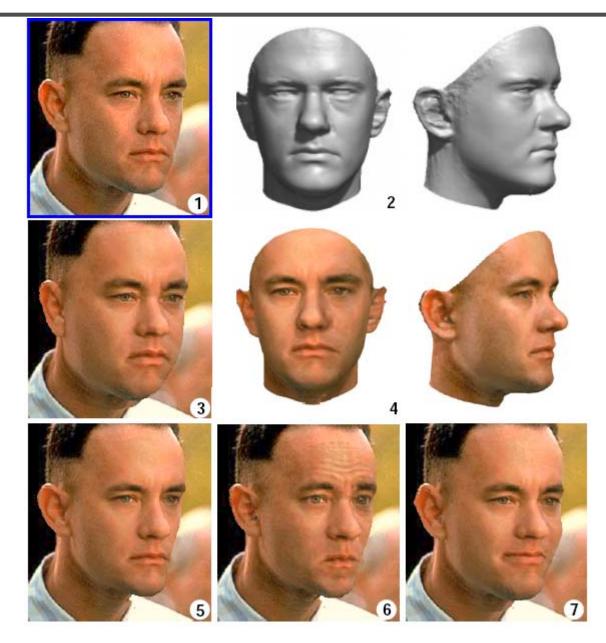
$$E_I = \sum_{x,y} ||\mathbf{I}_{input}(x,y) - \mathbf{I}_{model}(x,y)||^2$$

shape and texture priors are learnt from database

 ρ is the set of parameters for shading including camera pose, lighting and so on

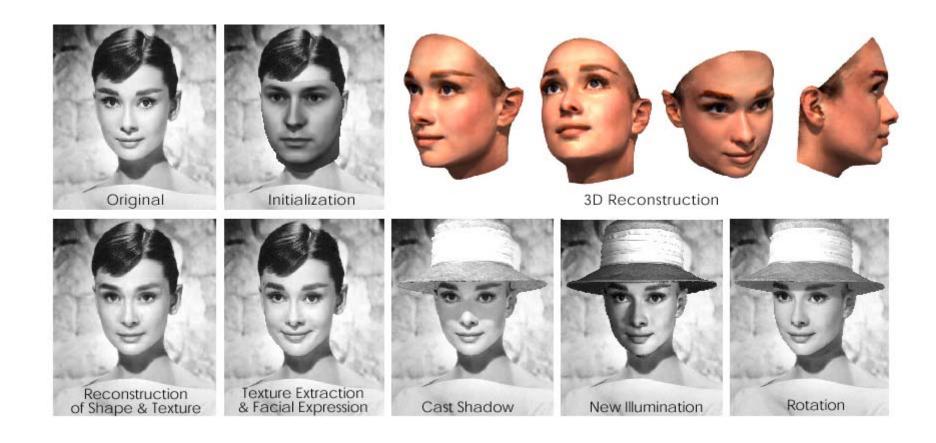


Modifying a single image





Animating from a single image



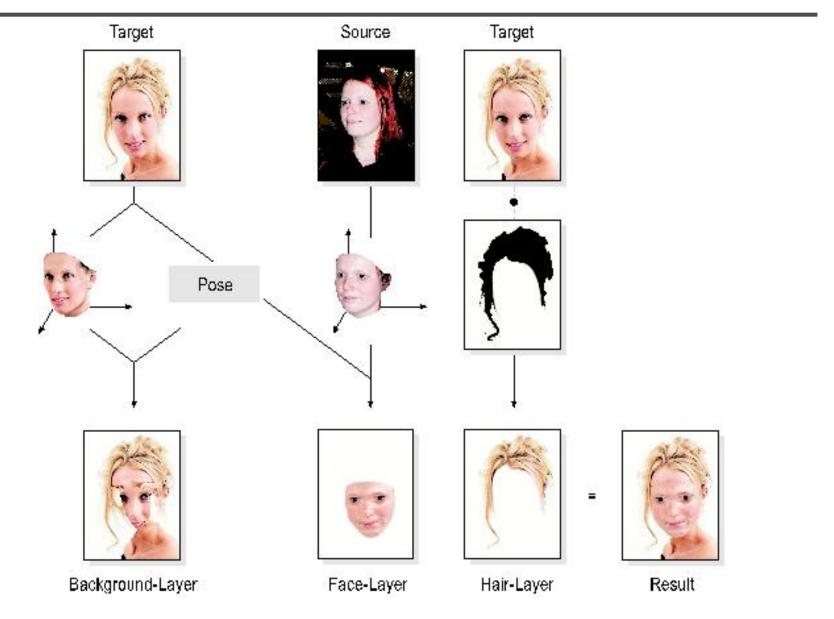


A Morphable Model for the Synthesis of 3D Faces

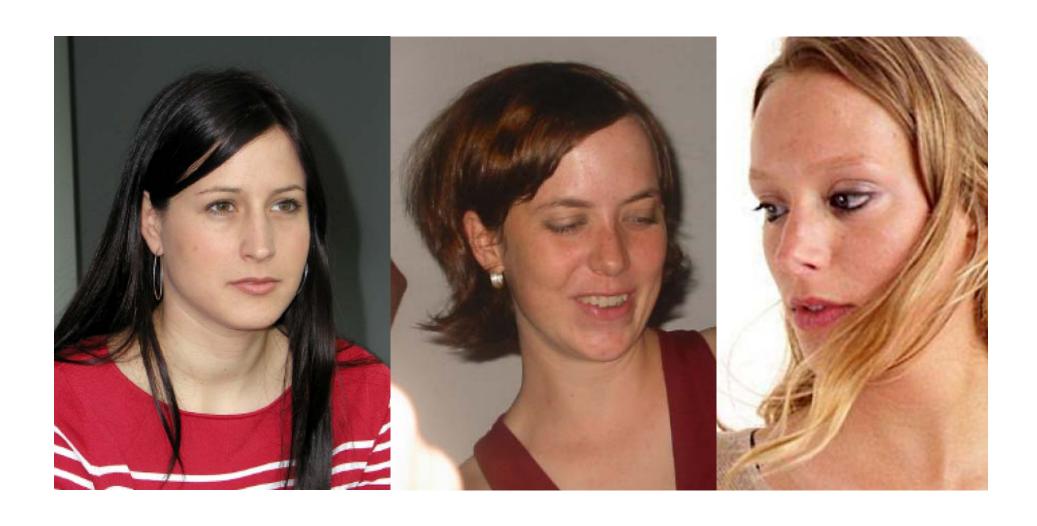
Volker Blanz & Thomas Vetter

MPI for Biological Cybernetics Tübingen, Germany

Digi<mark>VFX</mark>

















































Morphable model for human body

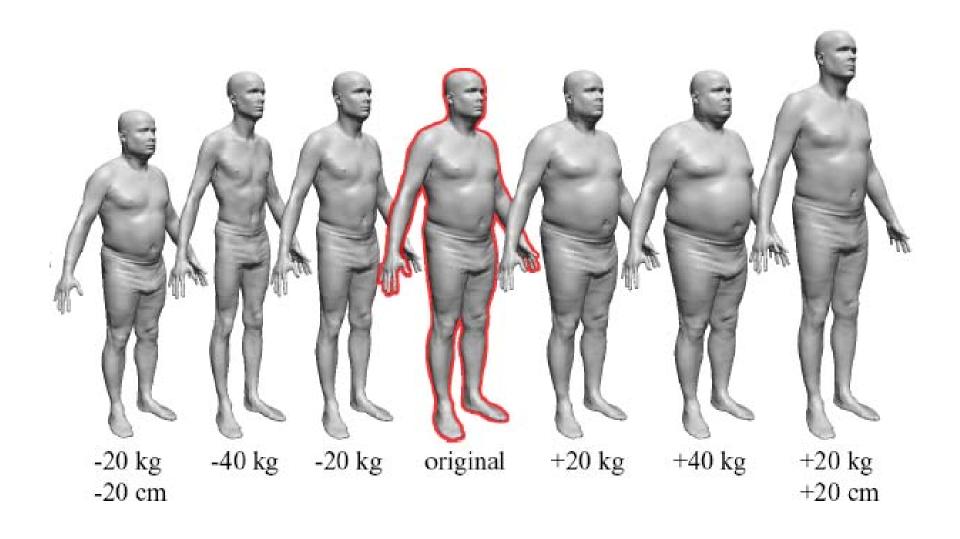
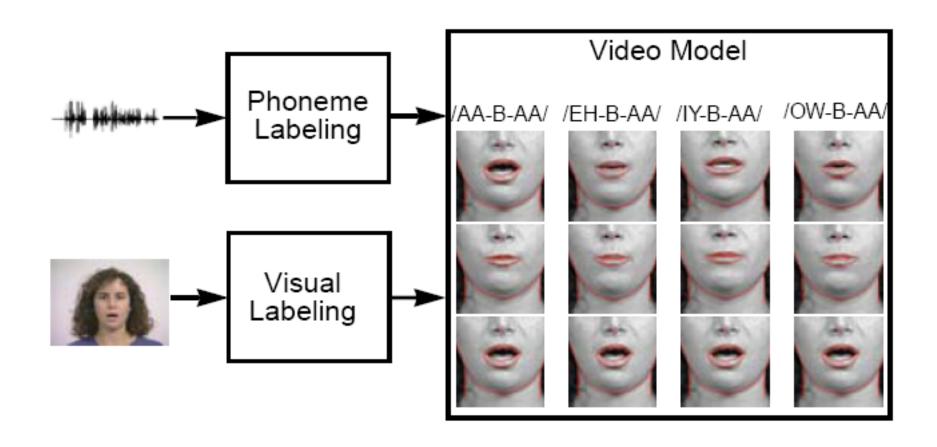


Image-based faces (lip sync.)

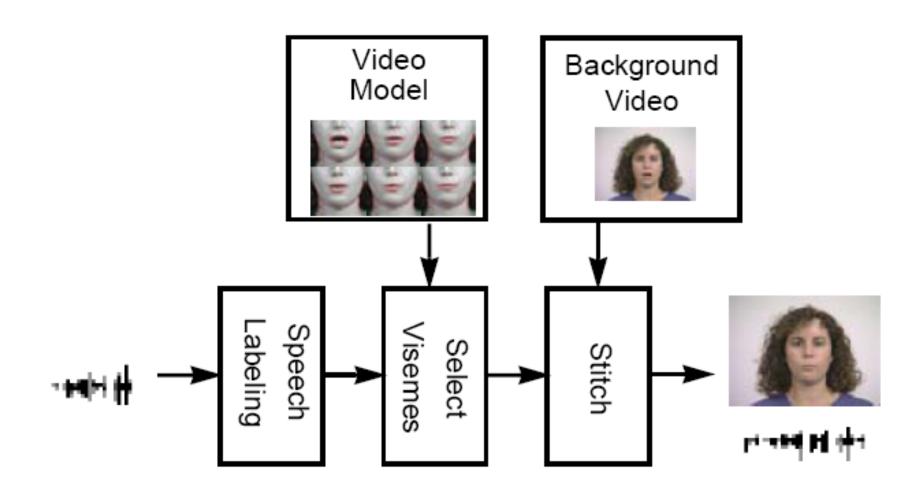
Video rewrite (analysis)





Video rewrite (synthesis)





Results



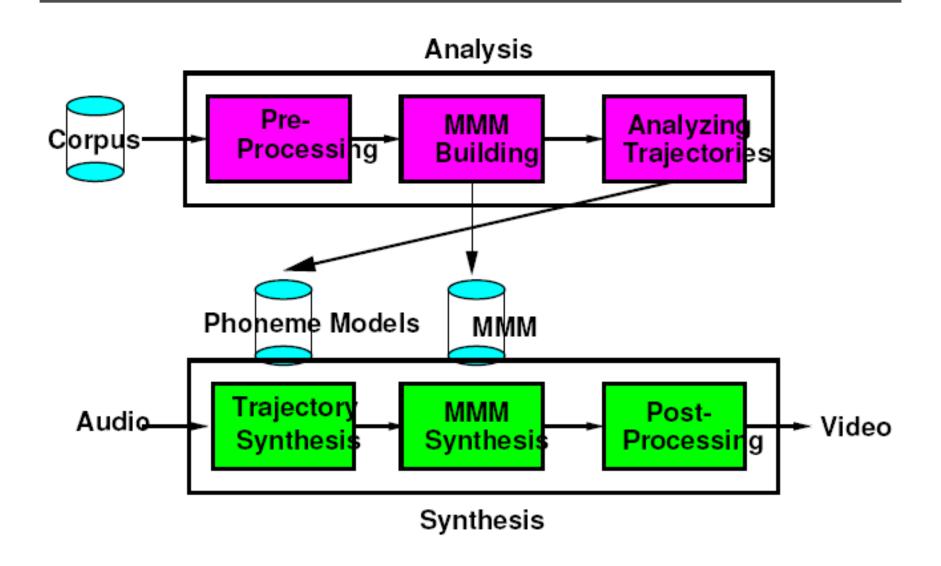
- Video database
 - 2 minutes of JFK
 - Only half usable
 - Head rotation



<u>training video</u><u>Read my lips.</u>I never met Forest Gump.

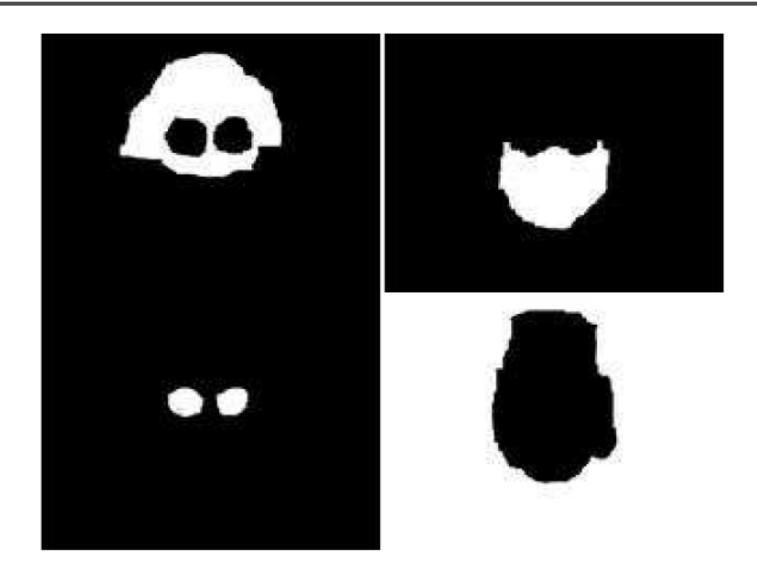


Morphable speech model



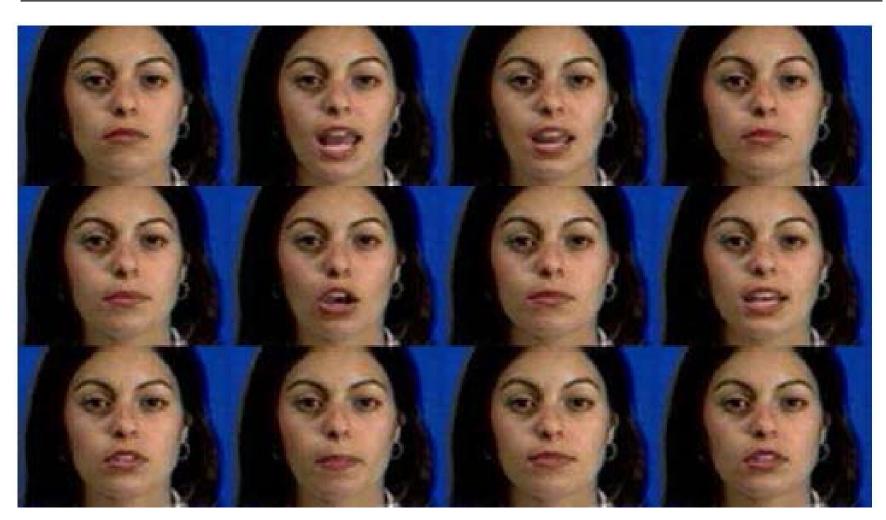
Preprocessing







Prototypes (PCA+k-mean clustering)



We find I_i and C_i for each prototype image.

Morphable model

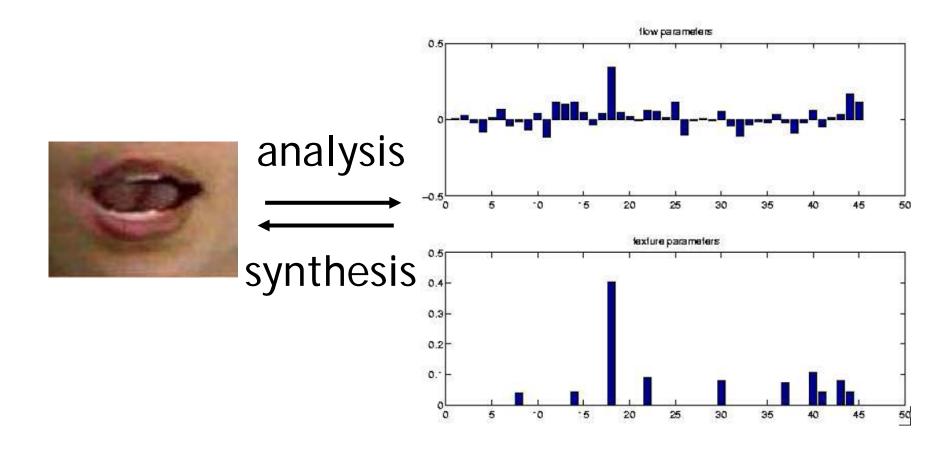


$$I^{morph}(\alpha, \beta) = \sum_{i=1}^{N} \beta_i \mathbf{W}(I_i, \mathbf{W}(\sum_{j=1}^{N} \alpha_j C_j - C_i, C_i))$$

analysis
$$\mathbf{I} \rightleftharpoons \alpha \beta$$
 synthesis

Morphable model





Synthesis



$$E = \underbrace{(y - \mu)^T D^T \Sigma^{-1} D(y - \mu)}_{target \ term} + \lambda \underbrace{y^T W^T W y}_{smoothness}$$

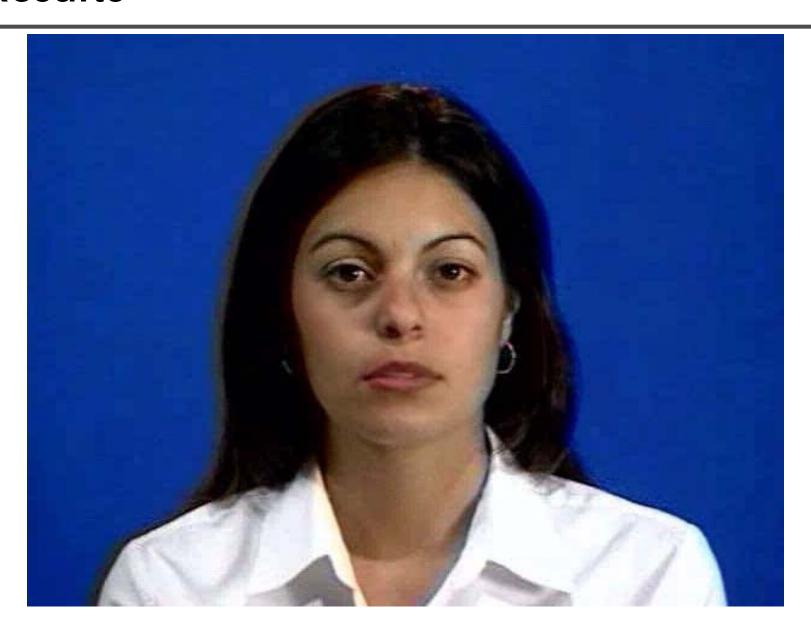
Results





Results





Relighting faces



Light is additive









Light stage 1.0





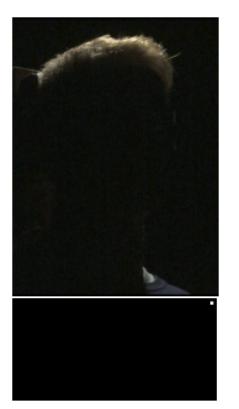






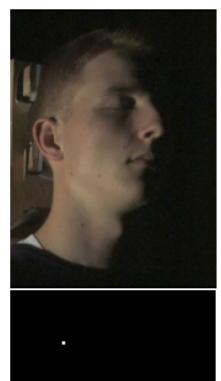
Input images





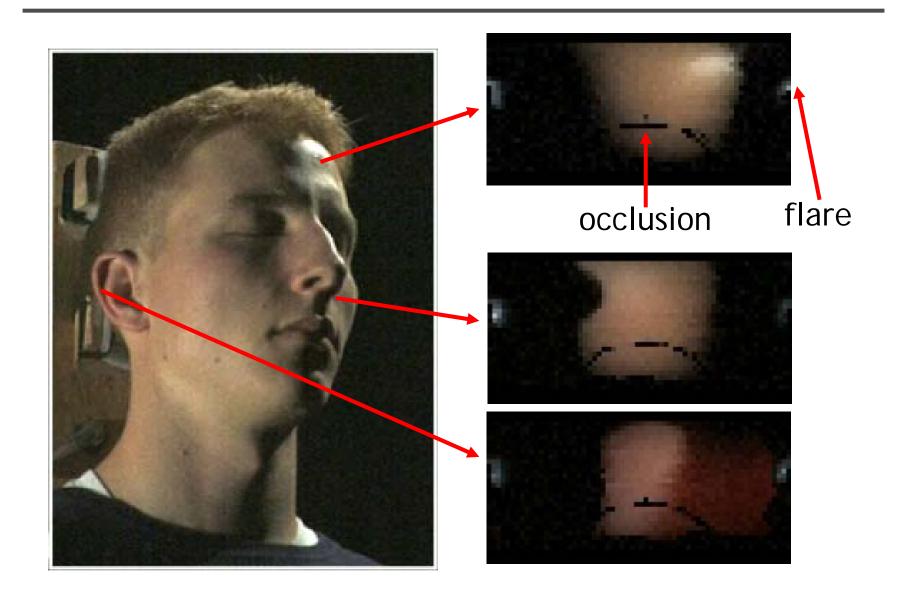






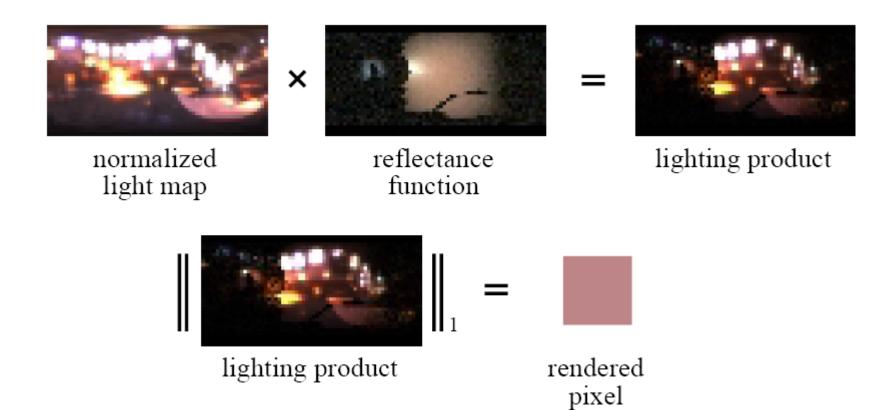
Reflectance function





Relighting





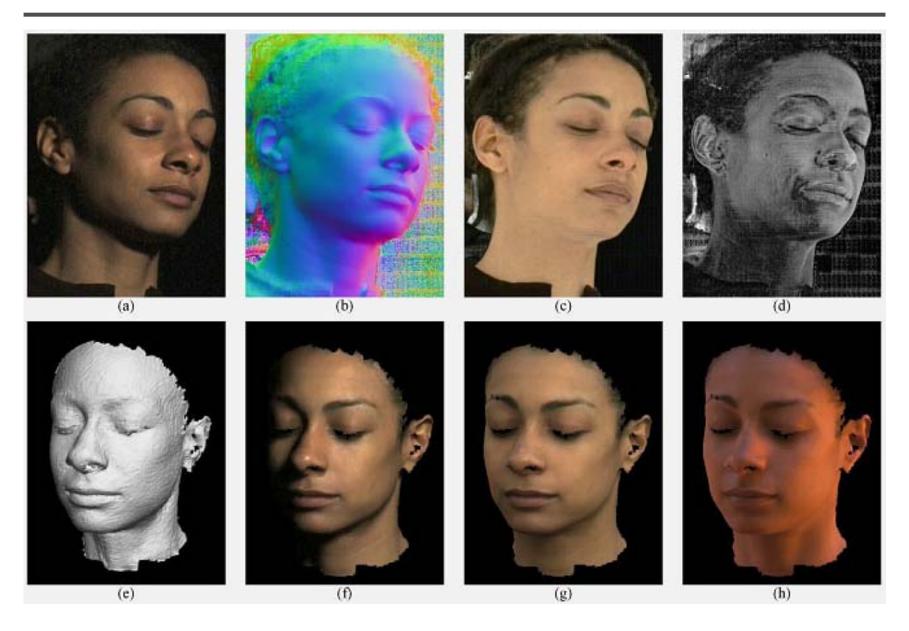
Results





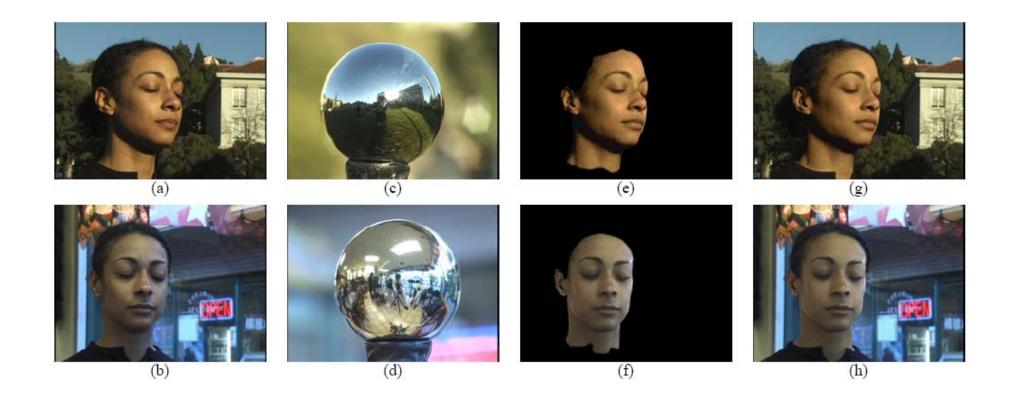


Changing viewpoints



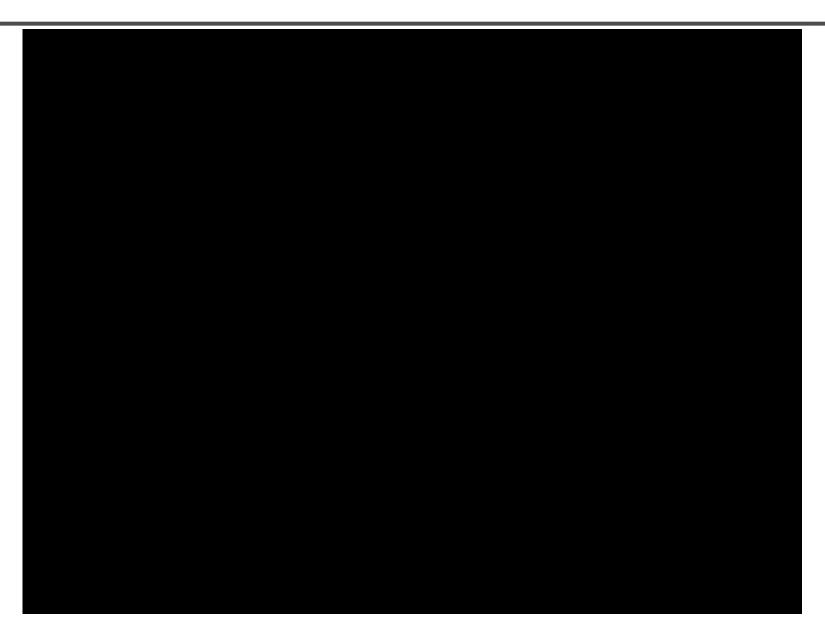
Results











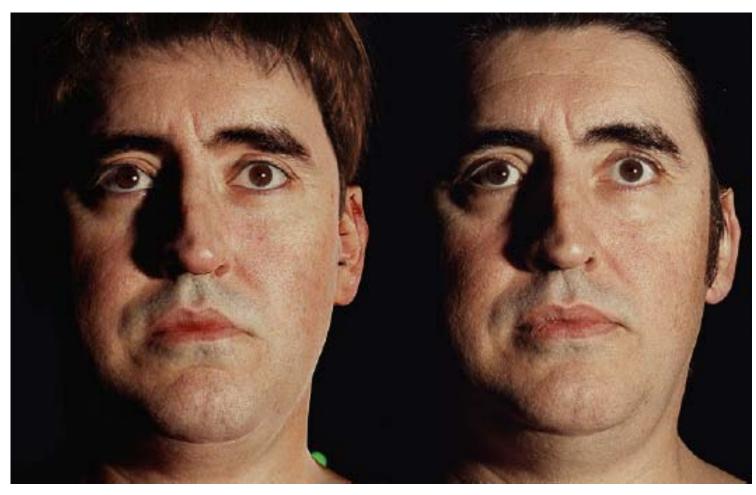


3D face applications: Spiderman 2



Spiderman 2





real

synthetic

Spiderman 2

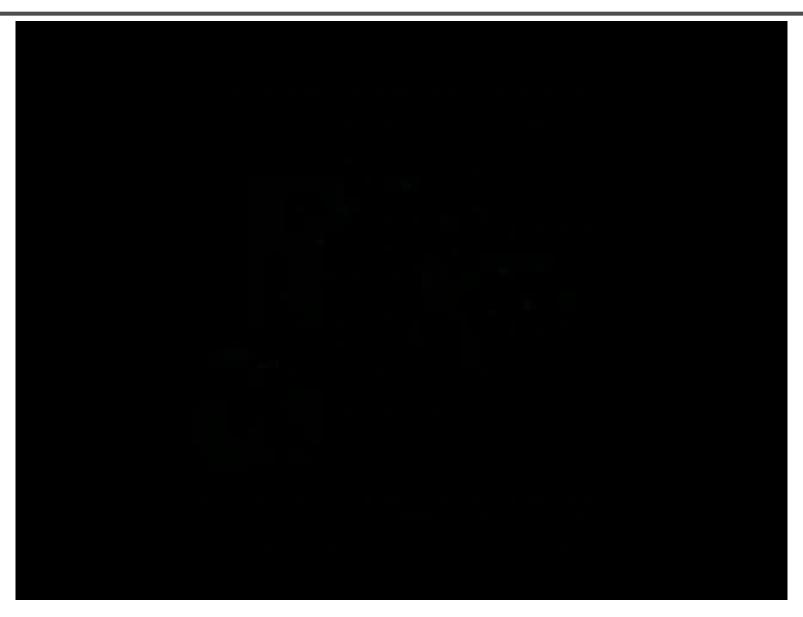




video







Light stage 6



Relighting Human Locomotion with Flowed Reflectance Fields

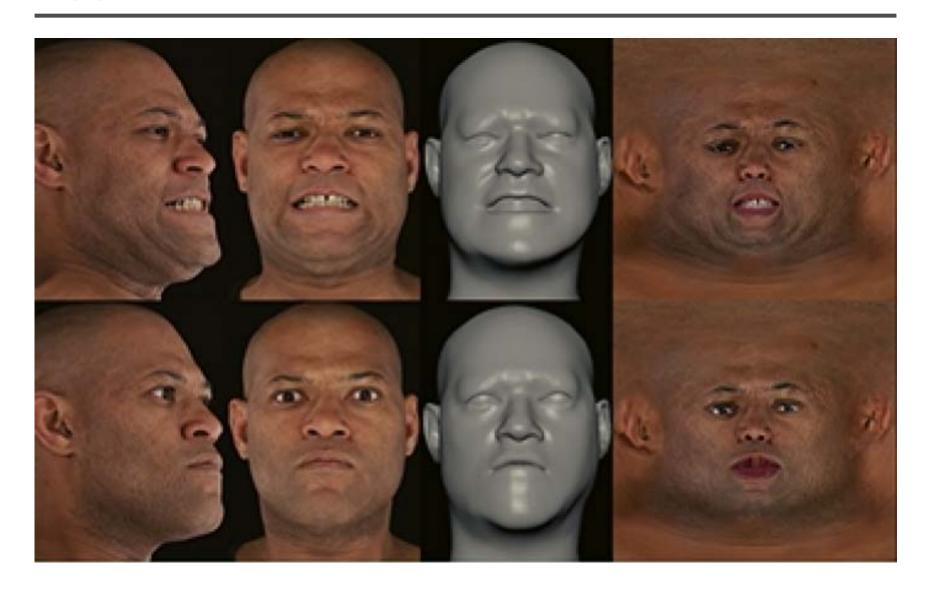
Per Einarsson Charles-Felix Chabert Andrew Jones Wan-Chun Ma ¹
Bruce Lamond Tim Hawkins Mark Bolas ² Sebastian Sylwan Paul Debevec

USC Centers for Creative Technologies National Taiwan University ¹ USC School of Cinema-Television ²

Eurographics Symposium on Rendering, June 2006



Application: The Matrix Reloaded





Application: The Matrix Reloaded



DigiVFX

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