Course overview

Digital Image Synthesis Yung-Yu Chuang

with slides by Mario Costa Sousa, Pat Hanrahan and Revi Ramamoorthi

Logistics



- Meeting time: 2:20pm-5:20pm, Thursday
- Classroom: CSIE Room 111
- Instructor: Yung-Yu Chuang (<u>cyy@csie.ntu.edu.tw</u>)
- TA:陳育聖
- Webpage: <u>http://www.csie.ntu.edu.tw/~cyy/rendering</u> id/password
- Mailing list: rendering@cmlab.csie.ntu.edu.tw Please subscribe via

https://cmlmail.csie.ntu.edu.tw/mailman/listinfo/rendering/



- C++ programming experience is required.
- Basic knowledge on algorithm and data structure is essential.
- Knowledge on linear algebra, probability, calculus and numerical methods is a plus.
- Though not required, it is recommended that you have background knowledge on computer graphics.



- 3 programming assignments (60%)
- Class participation (5%)
- Final project (35%)

Textbook



<u>Physically Based Rendering from Theory to Implementation</u>, 2nd ed, by Matt Pharr and Greg Humphreys



- Authors have a lot of experience on ray tracing
- Complete (educational) code, more concrete
- Has been used in many courses and papers
- Implement some advanced or difficult-to-implement methods: subdivision surfaces, Metropolis sampling, BSSRDF, PRT.
- 3rd edition is coming next year!



• To Matt Pharr, Greg Humphreys and Pat Hanrahan for their formalization and reference implementation of the concepts behind physically based rendering, as shared in their book *Physically Based Rendering*.

Physically based rendering has transformed computer graphics lighting by more accurately simulating materials and lights, allowing digital artists to focus on cinematography rather than the intricacies of rendering. First published in 2004, Physically Based Rendering is both a textbook and a complete source-code implementation that has provided a widely adopted practical roadmap for most physically based shading and lighting systems used in film production.





- A programming paradigm proposed by Knuth when he was developing Tex.
- Programs should be written more for people's consumption than for computers' consumption.
- The whole book is a long literate program. That is, when you read the book, you also read the complete program.





- Mix prose with source: description of the code is as important as the code itself
- Allow presenting the code to the reader in a different order than to the compiler
- Easy to make index
- Traditional text comments are usually not enough, especially for graphics
- This decomposition lets us present code a few lines at a time, making it easier to understand.
- It looks more like pseudo code.

LP example



@\section{Selection Sort: An Example for LP}

We use {\it selection sort} to illustrate the concept of {it literate programming}.

Selection sort is one of the simplest sorting algorithms.

It first find the smallest element in the array and exchange it with the element in the first position, then find the second smallest element and exchange it the element in the second position, and continue in this way until the entire array is sorted.

The following code implement the procedure for selection sort assuming an external array [[a]].

```
<<*>>=
<<external variables>>
void selection_sort(int n) {
    <<init local variables>>
    for (int i=0; i<n-1; i++) {
        <<find minimum after the ith element>>
        <<swap current and minimum>>
    }
}
```

LP example



```
<<find minimum after the ith element>>=
min=i;
for (int j=i+1; j<n; j++) {
    if (a[j]<a[min]) min=j;
}
```

```
<<init local variables>>= int min;
```

@ To swap two variables, we need a temporary variable [[t]] which is declared at the beginning of the procedure. <<init local variables>>= int t;

```
@ Thus, we can use [[t]] to preserve the value of [[a[min]] so that the swap operation works correctly.
<<swap current and minimum>>=
t=a[min]; a[min]=a[i]; a[i]=t;
```

```
<<external variables>>= int *a;
```

LP example (tangle)



int *a;

```
void selection_sort(int n) {
      int min;
      int t;
      for (int i=0; i<n-1; i++) {
            min=i;
            for (int j=i+1; j<n; j++) {
                  if (a[j]<a[min]) min=j;</pre>
            }
            t=a[min]; a[min]=a[i]; a[i]=t;
      }
}
```



1 Selection Sort: An Example for LP

We use *selection sort* to illustrate the concept of it literate programming. Selection sort is one of the simplest sorting algorithms. It first find the smallest element in the array and exchange it with the element in the first position, then find the second smallest element and exchange it the element in the second position, and continute in this way until the entire array is sorted. The following code implement the procedure for selection sort assuming an external array **a**.

```
1a
```

 $\langle * 1a \rangle \equiv$

pbrt



- Pbrt is designed to be
 - Complete: includes features found in commercial high-quality renderers.
 - Illustrative: select and implement elegant methods.
 - Physically based
- Efficiency was given a lower priority (the unofficial fork <u>luxrender</u> could be more efficient)
- Source code browser

LuxRender (http://www.luxrender.net)



Home

Development News More...

Overview

New hair support coming

A much improved hair support is being added to LuxRender. The first results are quite promising.

SLG renderer

The SLG renderer branch has just been merged with mainline. This means from now on LuxRender has a full GPU accelerated render mode, it will be available in LuxRender is a physically based and unbiased rendering engine. Based on state of the art algorithms, LuxRender simulates the flow of light according to physical equations, thus producing realistic images of photographic quality.

Get LuxRender

To get started with LuxRender, choose a package:



Community News More...

....

...

New exporter for Carrara

Luxus, a commercial exporter for Carrara to LuxRender, has just been officially released.

LuxRender advertized with Poser 10

A card advertizing Reality and LuxRender is present in every Poser 10 box thanks to RuntimeDNA.

Mitsuba (http://www.mitsuba-renderer.org/)



i About

Mitsuba is a research-oriented rendering system in the style of <u>PBRT</u>, from which it derives much inspiration. It is written in portable C++, implements unbiased as well as biased techniques, and contains heavy optimizations targeted towards current CPU architectures. Mitsuba is extremely modular: it consists of a small set of core libraries and over 100 different plugins that implement functionality ranging from materials and light sources to complete rendering algorithms.

In comparison to other open source renderers, Mitsuba places a strong emphasis on experimental rendering techniques, such as path-based formulations of Metropolis Light Transport and volumetric modeling approaches. Thus, it may be of genuine interest to those who would like to experiment with such techniques that bacents yet

fdx INTEGRATORS

A wide range of rendering techniques are available, including:

- Ambient occlusion
- Direct illumination
- Monte-Carlo path tracer which solves the full Radiative Transfer Equation
- Photon mapper with irradiance gradients
- Adjoint particle tracer
- Bidirectional path tracer
- Instant Radiosity (hardware-accelerated)
- Progressive Photon Mapper
- Stochastic Progressive Photon Mapper
- Path Space Metropolis Light Transport
- Primary Sample Space Metropolis Light Transport
- · Energy redistribution path tracer



- Remove plug-in architecture, but still an <u>extensible</u> architecture
- Add multi-thread support (automatic or -ncores)
- OpenEXR is recommended, not required
- HBV is added and becomes default
- Can be full spectral, do it at compile time
- Animation is supported
- Instant global illumination, extended photon map, extended infinite light source
- Improved irradiance cache

New features of pbrt2



- BSSRDF is added
- Metropolis light transport
- Precomputed radiance transfer
- Support measured BRDF

Reference books





References



- SIGGRAPH proceedings
- SIGGRAPH Asia proceedings
- Proceedings of Eurographics Symposium on Rendering
- Eurographics proceedings
- Most can be found at this link.

Image synthesis (Rendering)



• Create a 2D picture of a 3D world















uses physics to simulate the interaction between matter and light, realism is the primary goal



Realism



- Shadows
- Reflections (Mirrors)
- Transparency
- Interreflections
- Detail (Textures...)
- Complex Illumination
- Realistic Materials
- And many more



Other types of rendering



- Non-photorealistic rendering
- Image-based rendering
- Point-based rendering
- Volume rendering
- Perceptual-based rendering
- Artistic rendering





Introduction to ray tracing





Ray Casting (Appel, 1968)





Ray Casting (Appel, 1968)





Ray Casting (Appel, 1968)













direct illumination



Whitted ray tracing algorithm



- Combines eye ray tracing + rays to light
- Recursively traces rays




1. For each pixel, trace a **primary ray** in direction **V** to the first visible surface.

2. For each intersection, trace **secondary rays**:

- Shadow rays in directions L_i to light sources
- **Reflected ray** in direction **R**.
- **Refracted ray** or **transmitted ray** in direction **T**.



Shading



If $I(P_0, \mathbf{u})$ is the intensity seen from point P along direction \mathbf{u}

$$I(P_0, \mathbf{u}) = I_{direct} + I_{reflected} + I_{transmitted}$$

where

 I_{direct} = Shade(N, L, u, R) (e.g. Phong shading model)

$$I_{reflected} = k_r I(P, \mathbf{R})$$

$$I_{transmitted} = k_t I(P, \mathbf{T})$$
Typically, we set $k_r = k_s$ and k_t

$$I_{\mathbf{P}_o}$$







Components of a ray tracer



- Cameras
- Films
- Lights
- Ray-object intersection
- Visibility
- Surface scattering
- Recursive ray tracing



- Minimal ray tracer contest on *comp.graphics*, 1987
- Write the shortest Whitted-style ray tracer in C with the minimum number of tokens. The scene is consisted of spheres. (specular reflection and refraction, shadows)
- Winner: 916 tokens
- Cheater: 66 tokens (hide source in a string)
- Almost all entries have six modules: main, trace, intersect-sphere, vector-normalize, vector-add, dot-product.



typedef struct{double x,y,z}vec;vec U,black,amb={.02,.02,.02};struct sphere{ vec cen,color; double rad,kd,ks,kt,kl,ir}*s,*best,sph[]={0.,6.,.5,1.,1.,1.,.9, .05,.2,.85,0.,1.7,-1.,8.,-.5,1.,.5,.2,1., .7,.3,0.,.05,1.2,1.,8.,-.5,.1,.8,.8, 1.,.3,.7,0.,0.,1.2,3.,-6.,15.,1.,.8,1.,7.,0.,0.,0.,.6,1.5,-3.,-3.,12., .8,1., 1.,5.,0.,0.,0.,.5,1.5,};yx;double u,b,tmin,sqrt(),tan();double vdot(A,B)vec A ,B;{return A.x *B.x+A.y*B.y+A.z*B.z;}vec vcomb(a,A,B)double a;vec A,B;{B.x+=a* A.x;B.y+=a*A.y;B.z+=a*A.z; return B;}vec vunit(A)vec A;{return vcomb(1./sqrt(vdot(A,A)),A,black);}struct sphere*intersect (P,D)vec P,D;{best=0;tmin=1e30;s=sph+5;while(s-->sph)b=vdot(D,U=vcomb(-1.,P,s->cen)), u=b*b-vdot(U,U)+s->rad*s ->rad,u=u>0?sqrt(u):1e31,u=b-u>1e-7?b-u:b+u,tmin=u>=1e-7&& u<tmin?best=s,u: tmin;return best;}vec trace(level,P,D)vec P,D;{double d,eta,e;vec N,color; struct sphere*s,*l;if(!level--)return black;if(s=intersect(P,D));else return amb;color=amb;eta= s->ir;d= -vdot(D,N=vunit(vcomb(-1.,P=vcomb(tmin,D,P),s->cen)));if(d<0)N=vcomb(-1.,N,black), eta=1/eta,d= -d;l=sph+5;while(l-->sph)if((e=l ->kl*vdot(N,U=vunit(vcomb(-1.,P,l->cen))))>0&& intersect(P,U)==I)color=vcomb(e,I->color,color);U=s->color;color.x*=U.x;color.y*=U.y;color.z *=U.z;e=1-eta* eta*(1-d*d);return vcomb(s->kt,e>0?trace(level,P,vcomb(eta,D,vcomb(eta*dsqrt (e),N,black))):black,vcomb(s->ks,trace(level,P,vcomb(2*d,N,D)),vcomb(s->kd, color,vcomb (s->kl,U,black))));}main(){printf("%d %d\n",32,32);while(yx<32*32) U.x=yx%32-32/2,U.z=32/2yx++/32,U.y=32/2/tan(25/114.5915590261),U=vcomb(255., trace(3,black,vunit(U)),black),printf ("%.0f %.0f %.0f\n",U);}/*minray!*/







Another business card raytracer



#include <stdlib.h> // card > aek.ppm #include <stdio.h> #include <math.h> typedef int i;typedef float f;struct v{ f x,y,z;v operator+(v r){return v(x+r.x ,y+r.y,z+r.z);}v operator*(f r){return v(x*r,y*r,z*r);}f operator%(v r){return $x*r.x+y*r.y+z*r.z; v(){}v operator^(v r$){return v(v*r.z-z*r.v,z*r.x-x*r.z,x*r. y-y*r.x);}v(f a,f b,f c){x=a;y=b;z=c;}v operator!(){return*this*(1/sqrt(*this%* this));}};i G[]={247570,280596,280600, 249748,18578,18577,231184,16,16};f R(){ return(f)rand()/RAND_MAX;}i T(v o,v d,f &t,v&n){t=1e9;i m=0;f p=-0.z/d.z;if(.01 <p)t=p,n=v(0,0,1),m=1;for(i k=19;k--;) for(i j=9;j--;)if(G[j]&1<<k){v p=o+v(-k</pre> ,0,-j-4);f b=p%d,c=p%p-1,q=b*b-c;if(q>0){f s=-b-sqrt(q);if(s<t&&s>.01)t=s,n=!(p+d*t),m=2;}}return m;}v S(v o,v d){f t ;v n;i m=T(o,d,t,n);if(!m)return v(.7, .6,1)*pow(1-d.z,4);v h=o+d*t,1=!(v(9+R(),9+R(),16)+h*-1),r=d+n*(n%d*-2);f b=1% n;if(b<0||T(h,1,t,n))b=0;f p=pow(1%r*(b >0),99);if(m&1){h=h*.2;return((i)(ceil(h.x)+ceil(h.y))&1?v(3,1,1):v(3,3,3))*(b *.2+.1);}return v(p,p,p)+S(h,r)*.5;}i main(){printf("P6 512 512 255 ");v g=!v (-6,-16,0),a=!(v(0,0,1)^g)*.002,b=!(g^a)*.002,c=(a+b)*-256+g;for(i y=512;y--;) for(i x=512;x--;){v p(13,13,13);for(i r =64;r--;){v t=a*(R()-.5)*99+b*(R()-.5)* 99;p=S(v(17,16,8)+t,!(t*-1+(a*(R()+x)+b *(y+R())+c)*16))*3.5+p;}printf("%c%c%c" ,(i)p.x,(i)p.y,(i)p.z);}}



That's it?



• In this course, we will study how state-of-art ray tracers work.





Issues



- Better Lighting + Forward Tracing
- Texture Mapping
- Sampling
- Modeling
- Materials
- Motion Blur, Depth of Field, Blurry Reflection/Refraction
 - Distributed Ray-Tracing
- Improving Image Quality
- Acceleration Techniques (better structure, faster convergence)





00061 uint32_t splitAxis, firstPrimOffset, nPrimitives;

00062 };



$L_{o}(\mathbf{p}, \omega_{o}) = L_{e}(\mathbf{p}, \omega_{o})$ + $\int_{c^2} f(\mathbf{p}, \omega_0, \omega_i) L_i(\mathbf{p}, \omega_i) |\cos \theta_i| d\omega_i$

0001		
0002	/*	
0003		pbrt source code Copyright(c) 1998-2010 Matt Pharr and Greg Humphreys.
0004		
0005		This file is part of pbrt.
0006		
0007		obrt is free software; you can redistribute it and/or modify
0008		it under the terms of the GNU General Public License as published by
0000		the Free Software Foundation: either version 2 of the License or
0010		(at your option) any later version. Note that the text contents of
0010		the book "Devicelly Bared Dendering" are institutioned under the
0011		Che book Physically based Kendering are thost licensed under the
0012		GNU GPL.
0013		and the second
0014		port is distributed in the nope that it will be useful,
0015		but WITHOUT ANY WARRANTY; without even the implied warranty of
0016		MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the
0017		GNU General Public License for more details.
0018		
0019		You should have received a copy of the GNU General Public License
0020		along with this program. If not, see <http: licenses="" www.gnu.org=""></http:> .
0021		
0022	*/	
0023		
0024		
0025	11	accelerators/byb.con*
0025	#10	niuda "etdafy h"
0020	#10	clude "accelerators (byb.b"
002/	#10	clude "probas k"
0028	#10	clude "probes.n"
0029	#10	ciude paramsec.n
0030		
0031	11	BVHAccel Local Declarations
0032	stri	uct BVHPrimitiveInfo {
0033		BVHPrimitiveInfo() { }
0034		BVHPrimitiveInfo(int pn, const BBox &b)
0035		: primitiveNumber(pn), bounds(b) {
0036		centroid = .5f * b.pMin + .5f * b.pMax;
0037		}
0038		int primitiveNumber;
0039		Point centroid:
0040		BBox bounds:
0041	3.1	,
0041		
0042		
0043	-	and Didde. I diede f
0044	stri	nct pruppingwode (
0045		// BVHBUIIdNode Public Methods
0046		<pre>BVHBuildNode() { children[0] = children[1] = NULL; }</pre>
0047		<pre>void InitLeaf(uint32_t first, uint32_t n, const BBox &b) {</pre>
0048		firstPrimOffset = first;
0049		nPrimitives = n;
0050		bounds = b;
0051		}
0052		<pre>void InitInterior(uint32 t axis, BVHBuildNode *c0, BVHBuildNode *c1) {</pre>
0053		children[0] = c0:
0054		children[1] = c1;
0055		bounds = Union(c0-Shounds, c1-Shounds);
0055		colitavia = ovie:
0000		spiriting 0
0057		nPrimitives = 0;
0058		3
0059		BBox bounds;
0060		BVHBuildNode *children[2];

90064	
00065	struct CompareToMid {
00066	CompareToMid(int d, float m) { dim = d; mid = m; }
00067	int dim:
00068	float mid;
00069	<pre>bool operator()(const BVHPrimitiveInfo &a) const {</pre>
00070	return a.centroid[dim] < mid:
00071	}
00072):
00073	
00074	
00075	struct ComparePoints (
00076	ComparePoints(int d) { dim = d: }
0077	int dim:
00078	hool operator()(const BVHDrimitivaTofo &a
0070	const BVMPcimitiveInfo &b) const /
00075	noture a contraid[dim] (h contraid[dim])
00000	recurr a centroratanij v presicioratanij,
00001	
00002	li -
20000	
00084	shout Concertable (
00085	struct Compare lobucket {
00000	CompareTobucket(int split, int num, int d, const bbox &D)
18000	: centrolabounds(b)
00088	{ splitBucket = split; nBuckets = num; dim = d; }
90089	bool operator()(const BVHPrimitiveIn+o &p) const;
96696	
00091	int splitBucket, nBuckets, dim;
00092	const BBox ¢roidBounds
00093	33
00094	
00095	
00096	<pre>bool CompareToBucket::operator()(const BVHPrimitiveInfo &p) const {</pre>
00097	<pre>int b = nBuckets * ((p.centroid[dim] - centroidBounds.pMin[dim])</pre>
00098	<pre>(centroidBounds.pMax[dim] - centroidBounds.pMin[dim]));</pre>
00099	if (b == nBuckets) b = nBuckets-1;
00100	Assert(b >= 0 && b < nBuckets);
00101	return b <= splitBucket;
00102	}
00103	
00104	
00105	struct LinearBVHNode {
00106	BBox bounds;
00107	union {
00108	uint32_t primitivesOffset; // leaf
00109	uint32_t secondChildOffset; // interior
00110	};
00111	
00112	uint8_t nPrimitives; // 0 -> interior node
00113	uint8_t axis; // interior node: xyz
00114	<pre>uint8_t pad[2]; // ensure 32 byte total size</pre>
00115	33
00116	
00117	
00118	static inline bool IntersectP(const BBox &bounds, const Ray &ray,
00119	const Vector &invDir, const uint32_t dirIsNeg[3]) {
00120	// Check for ray intersection against \$x\$ and \$v\$ slabs

00121	<pre>float tmin = (bounds[dirIsNeg[0]].x - ray.o.x) * invDir.x;</pre>
00122	<pre>float tmax = (bounds[1-dirIsNeg[0]].x - ray.o.x) * invDir.x;</pre>
00123	<pre>float tymin = (bounds[dirIsNeg[1]].v - rav.o.v) * invDir.v;</pre>
00124	<pre>float tymax = (bounds[1-dirIsNeg[1]].y - ray.o.y) * invDir.y;</pre>
00125	if ((tmin > tvmax) (tvmin > tmax))
00126	return false:
00127	if (tymin > tmin) tmin = tymin:
00128	if (tymax (tmax) tmax = tymax:
00120	21 (cymus c cmus) cmus - cymus,
00125	// Charly for any interpretion project fof slab
00130	// check for ray incersection against \$25 Stab
00151	float tzmin = (bounds[dirisweg[2]].z - ray.o.z) * invDir.z;
00132	fioat tzmax = (bounds[i-dirisNeg[2]].z - ray.o.z) * invuir.z;
00133	<pre>if ((tmin > tzmax) (tzmin > tmax))</pre>
00134	return false;
00135	if (tzmin > tmin)
00136	tmin = tzmin;
00137	if (tzmax < tmax)
00138	tmax = tzmax;
00139	return (tmin < ray.maxt) && (tmax > ray.mint);
00140	}
00141	
00142	
00143	
00144 /	// BVHAccel Method Definitions
00145 8	BVHAccel::BVHAccel(const vector <reference<primitive> > &p.</reference<primitive>
00146	uint32 t mp, const string &sm) {
00147	maxPrimsInNode = min(255u, mp);
00148	for (uint32 t i = 0; i < $p_size()$; ++i)
00140	p[i]->FullyPefine(primitives):
00150	if (m == "cab") colitMathod = CDLTT CAH:
00151	alco if (sm == "middle") splitMethod = SPLIT_MTDDLE:
00151	else if (sm == "acusl") splitMethod = Split FOUND COUNTS:
00152	else if (sm == equal) sprichechou = smrif_counts;
00155	erse (
00154	warning("bvn spiit method \"%s\" unknown. Using \"san\".",
00155	sm.c_str());
00156	splitmethod = SPLII_SAH;
00157	}
00158	
00159	if (primitives.size() == 0) {
00160	nodes = NULL;
00161	return;
00162	}
00163	// Build BVH from _primitives_
00164	<pre>PBRT_BVH_STARTED_CONSTRUCTION(this, primitives.size());</pre>
00165	
00166	<pre>// Initialize _buildData_ array for primitives</pre>
00167	vector <bvhprimitiveinfo> buildData;</bvhprimitiveinfo>
00168	<pre>buildData.reserve(primitives.size());</pre>
00169	<pre>for (uint32 t i = 0; i < primitives.size(); ++i) {</pre>
00170	<pre>BBox bbox = primitives[i]->WorldBound();</pre>
00171	<pre>buildData.push back(BVHPrimitiveInfo(i, bbox));</pre>
00172	}
00173	,
00174	// Perunsively build BVH tree for primitives
00175	Memory/constructy build/const
00175	vieto tete Nete
00176	uincsz_t cotainodes = 0;
001//	vector <kererence<primitive> > orderedPrims;</kererence<primitive>
00178	orderedPrims.reserve(primitives.size());
00179	BVHBuildNode "root = recursiveBuild(buildArena, buildData, 0,
00180	primitives.size(), &totalNodes,

fleat this - (hounded disTelles[0]] v now e v) # isuDi

Complex lighting





Complex lighting





Refraction/dispersion











Realistic materials





Translucent objects





Texture and complex materials





Even more complex materials





Complex material (luxrender)





Depth of field (luxrender)





Motion blur (luxrender)





Refraction (Luxrender)





Applications

- Movies
- Interactive entertainment
- Industrial design
- Architecture
- Culture heritage









IKEA



 Today (2014), around 60-75% of all IKEA's product (single product) images are CG. About 35% of all IKEA Communication's non-product images are fully CG.





• They use 3DStudio Max and V-Ray.



Animation production pipeline







TREATMENT

story

text treatment

storyboard







look and feel

voice

Animation production pipeline







layout



animation



modeling/articulation





final touch

shading/lighting

rendering





Pixar in a Box





Ray tracing finally catches up















http://www.fxguide.com/featured/manuka-weta-digitals-new-renderer/

Hyperion (Disney)




Pixar Renderman Timeline



25 Years of Pixar's RenderMan THE COMMERCIAL YEARS From 1990 to 1996 Pixar created many innovative 3D commercials for television. PIXAR's knick knack while developing its rendering technology - Photorealistic RenderMan. RenderMan* 1989 1988 1990 1991 1994 1992 1993 **RI SPEC 3.0 PUBLISHED** PIXAR'S RENDERMAN 3.0 PIXAR'S RENDERMAN 3.1 PIXAR'S RENDERMAN 3.2 PIXAR'S RENDERMAN 3.3 ACHEIVEMENT AWARD PIXAR'S RENDERMAN 3.5 Stochastic Sampling · 64 Bit Processeor Support The Netrender System Scientific & Engineering Achieve- RIB (RenderMan Interface Sylectream) · Pixar "Looks" Support With the first use of the word REYES Algorithm Constructive Solid Geometry Zthreshold Shadow Opacity ment Award from the Academy of Filterstep "RenderMan," the RenderMan Micropolygons Vector RenderMan Better Memory Utilization Motion Picture Arts and Sciences. Interface Specification was the culmination of years of Pixar's rendering development and set the standard for describing PIXAR'S RENDERMAN 3.4 30 data. Trim Curves "The original motivation to do the research Extreme Displacement Vertex Motion Blur TIN that led to these technological discoveries was to expand the range of possibilities for storytellers" ED CATMULL . . President of Walt Disney and ... **Pixar Animation Studios** O Disney/Pixar 2013

Monster University





The blue umbrella





Homework #0



- Download and install pbrt2.
- Run several examples
- Set it up in a debugger environment so that you can trace the code
- Optionally, create your own scene