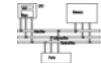


ARM Assembly Programming

Computer Organization and Assembly Languages
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with slides by Peng-Sheng Chen

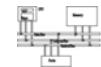
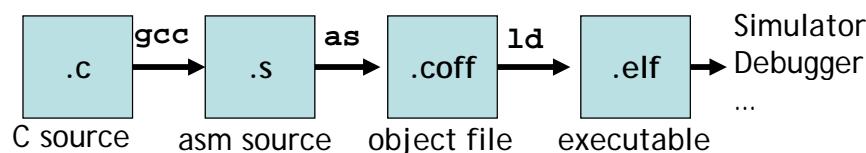


GNU compiler and binutils

- HAM uses GNU compiler and binutils
 - gcc: GNU C compiler
 - as: GNU assembler
 - ld: GNU linker
 - gdb: GNU project debugger
 - insight: a (Tcl/Tk) graphic interface to gdb

Pipeline

- COFF (common object file format)
- ELF (extended linker format)
- Segments in the object file
 - Text: code
 - Data: initialized global variables
 - BSS: uninitialized global variables



GAS program format

```
.file "test.s"
.text
.global main
.type main, %function
main:
    MOV R0, #100
    ADD R0, R0, R0
    SWI #11
.end
```

GAS program format

```
.file "test.s"
.text
export variable → .global main
.type main, %function
main:
    MOV R0, #100
    ADD R0, R0, R0
    SWI #11
signals the end → .end
            ↑
            set the type of a
            symbol to be
            either a function
            or an object
            ↑
            call interrupt to
            end the program
```



ARM assembly program

label	operation	operand	comments
main:	LDR	R1, value	@ load value
	STR	R1, result	
	SWI	#11	
value:	.word	0x0000C123	
result:	.word	0	



Control structures



- Program is to implement algorithms to solve problems. Program decomposition and flow of control are important concepts to express algorithms.
- Flow of control:
 - Sequence.
 - Decision: if-then-else, switch
 - Iteration: repeat-until, do-while, for
- Decomposition: split a problem into several smaller and manageable ones and solve them independently.
(subroutines/functions/procedures)

Decision



- If-then-else
- switch

If statements

```
if [C] then [T] else [E] // find maximum
    if (R0>R1) then R2:=R0
    else R2:=R1

    C
    BNE else
    T
    B endif
else:
    E
endif:
```



If statements

```
if [C] then [T] else [E] // find maximum
    if (R0>R1) then R2:=R0
    else R2:=R1

    C
    BNE else
    T
    B endif
else:
    E
endif:
```

CMP R0, R1
BLE else
MOV R2, R0
B endif
else: MOV R2, R1
endif:



If statements

Two other options:

```
CMP R0, R1
MOVGT R2, R0
MOVLE R2, R1

MOV R2, R0
CMP R0, R1
MOVLE R2, R1
```

```
// find maximum
if (R0>R1) then R2:=R0
else R2:=R1

    CMP R0, R1
    BLE else
    MOV R2, R0
    B endif
else: MOV R2, R1
endif:
```



If statements

```
if (R1==1 || R1==5 || R1==12) R0=1;

    TEQ R1, #1      ...
    TEQNE R1, #5    ...
    TEQNE R1, #12   ...
    MOVEQ R0, #1     BNE fail
```



If statements

```
if (R1==0) zero
else if (R1>0) plus
else if (R1<0) neg

    TEQ    R1, #0
    BMI    neg
    BEQ    zero
    BPL    plus

neg: ...
    B exit
Zero: ...
    B exit
...
```



Multi-way branches

```
CMP R0, #`0'
BCC other @ less than '0'
CMP R0, #`9'
BLS digit @ between '0' and '9'
-----
CMP R0, #`A'
BCC other
CMP R0, #`z'
BLS letter @ between 'A' and 'Z'
-----
CMP R0, #`a'
BCC other
CMP R0, #`z'
BHI other @ not between 'a' and 'z'
letter: ...
```



If statements

```
R0=abs(R0)

    TEQ    R0, #0
    RSBMI R0, R0, #0
```



Switch statements

```
switch (exp) {
    e=exp;
    case c1: S1; break; if (e==c1) {S1}
    case c2: S2; break; else
    ...
    case cN: SN; break; if (e==c2) {S2}
    default: SD; else
}
```



Switch statements

```
switch (R0) {  
    case 0: S0; break;  
    case 1: S1; break;  
    case 2: S2; break;  
    case 3: S3; break;  
    default: err;  
}  
  
The range is between 0 and N  
  
Slow if N is large
```

The range is between 0 and N

Slow if N is large

```
        CMP R0, #0  
        BEQ S0  
        CMP R0, #1  
        BEQ S1  
        CMP R0, #2  
        BEQ S2  
        CMP R0, #3  
        BEQ S3  
  
err: ...  
      B exit  
  
S0: ...  
      B exit
```

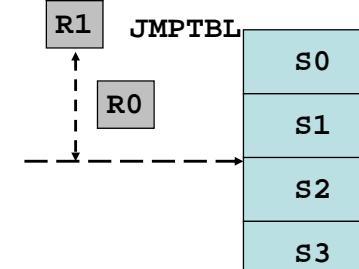


Switch statements

```
ADR R1, JMP_TBL  
CMP R0, #3  
LDR.LS PC, [R1, R0, LSL #2]  
  
err: ...  
      B exit  
  
S0: ...  
  
JMP_TBL:  
  .word S0  
  .word S1  
  .word S2  
  .word S3
```

What if the range is between M and N?

For larger N and sparse values, we could use a hash function.



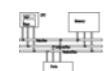
Iteration

- repeat-until
- do-while
- for



repeat loops

```
do { S } while ( C )
```



```
loop:  
  S  
  C  
  BEQ loop  
endw:
```

while loops

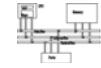
```
while (C) {S}
```

loop: C
 BNE endw
 S
 B loop

loop: S
 BEQ loop
test: C
 BEQ loop

endw:

endw:



while loops

```
while (C) {S}
```

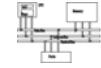
C

B test
loop: S
 BEQ loop
test: C
 BEQ loop

endw:

BNE endw
loop: S
 BEQ loop
test: C
 BEQ loop

endw:



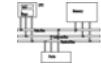
GCD

```
int gcd (int i, int j)
{
    while (i!=j)
    {
        if (i>j)
            i -= j;
        else
            j -= i;
    }
}
```



GCD

```
Loop: CMP R1, R2
      SUBGT R1, R1, R2
      SUBLT R2, R2, R1
      BNE loop
```



for loops

```
for ( I; C ; A ) { S }   for ( i=0; i<10; i++ )
                           { a[i]:=0; }
```

loop:
 I
 C
BNE endfor
 S
 A
B loop
endfor:



for loops

```
for ( I; C ; A ) { S }   for ( i=0; i<10; i++ )
                           { a[i]:=0; }
```

loop:
 I
 C
BNE endfor
 S
 A
B loop
endfor:
MOV R0, #0
ADR R2, A
MOV R1, #0
loop: CMP R1, #10
BGE endfor
STR R0,[R2,R1,LSL #2]
ADD R1, R1, #1
B loop
endfor:



for loops

```
for ( i=0; i<10; i++ )
  { do something; }
```

Execute a loop for a constant of times.

```
MOV R1, #0           MOV R1, #10
loop: CMP R1, #10      loop:
       BGE endfor
       @ do something
       ADD R1, R1, #1
       B loop
endfor:               endfor:
```



Procedures

- Arguments: expressions passed into a function
- Parameters: values received by the function
- Caller and callee

```
void func(int a, int b) callee
{
  ...
}
int main(void) caller
{
  func(100,200);
  ...
}
```



Procedures

```
main:  
    ...  
    BL func        func:  
    ...  
    ...  
    .end          .end
```

- How to pass arguments? By registers? By stack?
By memory? In what order?



Procedures

```
main: caller  
    @ use R5      func:  
    BL func        ...  
    @ use R5      @ use R5  
    ...  
    ...  
    .end          .end
```

- How to pass arguments? By registers? By stack?
By memory? In what order?
- Who should save R5? Caller? Callee?

callee

Procedures (caller save)

```
main: caller  
    @ use R5      func:  
    @ save R5     ...  
    BL func        @ use R5  
    @ restore R5  
    @ use R5  
    .end          .end
```

- How to pass arguments? By registers? By stack?
By memory? In what order?
- Who should save R5? Caller? Callee?



Procedures (callee save)

```
main: caller  
    @ use R5      func: @ save R5  
    BL func        ...  
    @ use R5      @ use R5  
                @restore R5  
    .end          .end
```

- How to pass arguments? By registers? By stack?
By memory? In what order?
- Who should save R5? Caller? Callee?

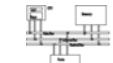
callee

Procedures

```
main: caller
      @ use R5
      BL func          func:
      ...
      @ use R5
      ...
      ...
      .end           .end
```



- How to pass arguments? By registers? By stack? By memory? In what order?
- Who should save R5? Caller? Callee?
- We need a protocol for these.



ARM Procedure Call Standard (APCS)

- ARM Ltd. defines a set of rules for procedure entry and exit so that
 - Object codes generated by different compilers can be linked together
 - Procedures can be called between high-level languages and assembly
- APCS defines
 - Use of registers
 - Use of stack
 - Format of stack-based data structure
 - Mechanism for argument passing

APCS register usage convention



Register	APCS name	APCS role
0	a1	Argument 1 / integer result / scratch register
1	a2	Argument 2 / scratch register
2	a3	Argument 3 / scratch register
3	a4	Argument 4 / scratch register
4	v1	Register variable 1
5	v2	Register variable 2
6	v3	Register variable 3
7	v4	Register variable 4
8	v5	Register variable 5
9	sb/v6	Static base / register variable 6
10	sl/v7	Stack limit / register variable 7
11	fp	Frame pointer
12	ip	Scratch reg. / new sb in inter-link-unit calls
13	sp	Lower end of current stack frame
14	lr	Link address / scratch register
15	pc	Program counter

APCS register usage convention



Register	APCS name	APCS role	
0	a1	Argument 1 / integer result / scratch register	
1	a2	Argument 2 / scratch register	
2	a3	Argument 3 / scratch register	
3	a4	Argument 4 / scratch register	
4	v1	Register variable 1	Used to pass the first 4 parameters
5	v2	Register variable 2	
6	v3	Register variable 3	
7	v4	Register variable 4	
8	v5	Register variable 5	Caller-saved if necessary
9	sb/v6	Static base / register variable 6	
10	sl/v7	Stack limit / register variable 7	
11	fp	Frame pointer	
12	ip	Scratch reg. / new sb in inter-link-unit calls	
13	sp	Lower end of current stack frame	
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APCS register usage convention



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6	v3	Register variable 3
7	v4	Register variable 4
8	v5	Register variable 5
9	sb/v6	Static base / register variable 6
10	sl/v7	Stack limit / register variable 7
11	fp	Frame pointer
12	ip	Scratch reg. / new sb in inter-link-unit calls
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15	pc	Program counter

- Register variables, must return unchanged
- Callee-saved

APCS register usage convention



Register	APCS name	APCS role
0	a1	Argument 1 / integer result / scratch register
1	a2	Argument 2 / scratch register
2	a3	Argument 3 / scratch register
3	a4	Argument 4 / scratch register
4	v1	Register variable 1
5	v2	Register variable 2
6	v3	Register variable 3
7	v4	Register variable 4
8	v5	Register variable 5
9	sb/v6	Static base / register variable 6
10	sl/v7	Stack limit / register variable 7
11	fp	Frame pointer
12	ip	Scratch reg. / new sb in inter-link-unit calls
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14	lr	Link address / scratch register
15	pc	Program counter

Argument passing



- The first four word arguments are passed through R0 to R3.
- Remaining parameters are pushed into stack in the reverse order.
- Procedures with less than four parameters are more effective.

Return value

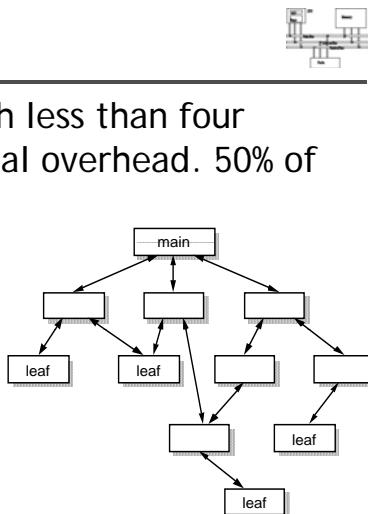


- One word value in R0
- A value of length 2~4 words (R0-R1, R0-R2, R0-R3)

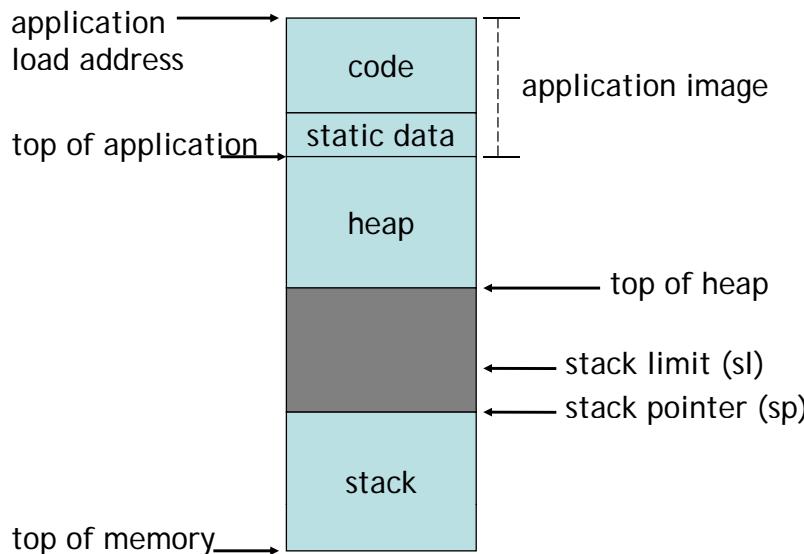
Function entry/exit

- A simple leaf function with less than four parameters has the minimal overhead. 50% of calls are to leaf functions

```
BL leaf1
...
leaf1: ...
...
MOV PC, LR @ return
```



Standard ARM C program address space



Function entry/exit

- Save a minimal set of temporary variables

```
BL leaf2
...
leaf2: STMFD sp!, {regs, lr} @ save
...
LDMFD sp!, {regs, pc} @ restore and
@ return
```

Accessing operands

- A procedure often accesses operands in the following ways
 - An argument passed on a register: no further work
 - An argument passed on the stack: use stack pointer (R13) relative addressing with an immediate offset known at compiling time
 - A constant: PC-relative addressing, offset known at compiling time
 - A local variable: allocate on the stack and access through stack pointer relative addressing
 - A global variable: allocated in the static area and can be accessed by the static base relative (R9) addressing

Procedure

main:

```
LDR R0, #0
```

...

```
BL func
```

...

low

high

stack



Procedure

func: STMFD SP!, {R4-R6, LR} low

```
SUB SP, SP, #0xC
```

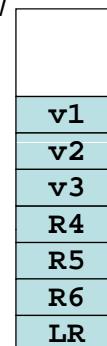
...

```
STR R0, [SP, #0] @ v1=a1
```

...

```
ADD SP, SP, #0xC
```

```
LDMFD SP!, {R4-R6, PC}
```



high

stack