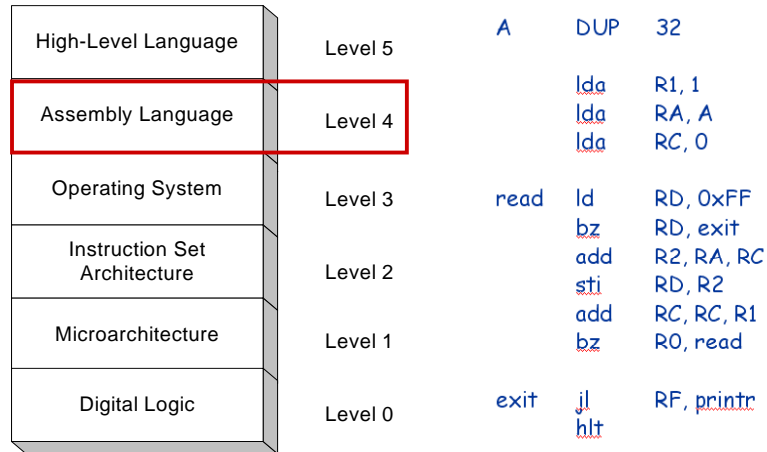


Virtual machines

Abstractions for computers



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TOY assembly

Introduction to Computer Science · Robert Sedgewick and Kevin Wayne · Copyright © 2005 · <http://www.cs.Princeton.EDU/IntroCS>

TOY assembly

Not mapping to instruction	opcode	mnemonic	syntax
• Data directives	0	hlt	hlt
• A DW n: initialize a variable A as n	1	add	add rd, rs, rt
• B DUP n: reserve n words (n is decimal)	2	sub	sub rd, rs, rt
• Support two types of literals, decimal and hexadecimal (0x)	3	and	and rd, rs, rt
• Label begins with a letter	4	xor	xor rd, rs, rt
• Comment begins with ;	5	shl	shl rd, rs, rt
• Case insensitive	6	shr	shr rd, rs, rt
• Program starts with the first instruction it meets	7	lda	lda rd, addr
	8	ld	ld rd, addr
	9	st	st rd, addr
	A	ldi	ldi rd, rt
	B	sti	sti rd, rt
	C	bz	bz rd, addr
	D	bp	bp rd, addr
• Some tricks to handle the starting address 0x10	E	jr	jr rd (rt)
	F	jl	jl rd, addr

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Assembler

Assembler's task:

- Convert mnemonic operation codes to their machine language equivalents
- Convert symbolic operands to their equivalent machine addresses
- Build machine instructions in proper format
- Convert data constants into internal machine representations (data formats)
- Write object program and the assembly listing

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Forward Reference

Definition

- A reference to a label that is defined **later** in the program

Solution

- Two passes
 - First pass: scan the source program for label definition, address accumulation, and address assignment
 - Second pass: perform most of the actual instruction translation

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Assembly version of REVERSE

```

int A[32];          A    DUP    32          10: C020

                                lda    R1, 1          20: 7101
                                lda    RA, A          21: 7A00
i=0;                lda    RC, 0          22: 7C00
Do {
  RD=stdin;         read   ld     RD, 0xFF        23: 8DFF
  if (RD==0) break;  bz     RD, exit        24: CD29
                                add    R2, RA, RC        25: 12AC
  A[i]=RD;          sti    RD, R2          26: BD02
  i=i+1;            add    RC, RC, R1        27: 1CC1
} while (1);        bz     R0, read        28: C023

printr();          exit   jl     RF, printr        29: FF2B
                                hlt
                                2A: 0000
    
```

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Assembly version of REVERSE

```

printr()           ; print reverse
{                 ; array address (RA)
do {              ; number of elements (RC)
  i=i-1;          printr sub   RC, RC, R1    2B: 2CC1
                                add    R2, RA, RC    2C: 12AC
                                ldi    RD, R2      2D: AD02
  print A[i];     st     RD, 0xFF        2E: 9DFF
} while (i>=0);  bp     RC, printr    2F: DC2B
                                bz     RC, printr    30: CC2B
return;          return jr   RF          31: EF00
}
    
```

toyasm < reverse.asm > reverse.toy

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Function Call: A Failed Attempt

Goal: $x \times y \times z$.

- Need two multiplications: $x \times y$, $(x \times y) \times z$.
 - Solution 1: write multiply code 2 times.
 - Solution 2: write a TOY function.

A failed attempt:

- Write multiply loop at 30-36.
- Calling program agrees to store arguments in registers A and B.
- Function agrees to leave result in register C.
- Call function with jump absolute to 30.
- Return from function with jump absolute.

Reason for failure.

- Need to return to a VARIABLE memory address.

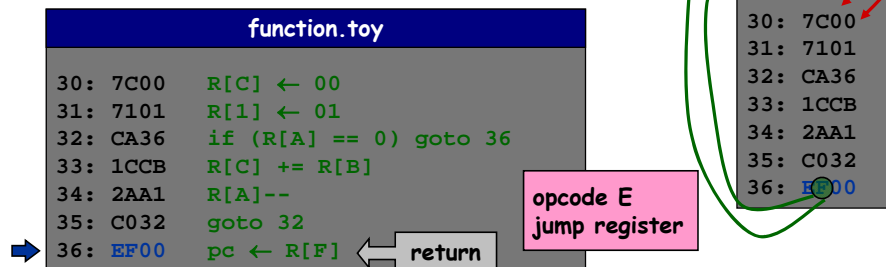
function?	
10:	8AFF
11:	8BFF
12:	C031
13:	1AC0
14:	8BFF
15:	C031
16:	9CFF
17:	0000
30:	7C00
31:	7101
32:	CA36
33:	1CCB
34:	2AA1
35:	C032
36:	C032?

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Multiplication Function

Calling convention.

- Jump to line 30.
- Store a and b in registers A and B.
- Return address in register F.
- Put result $c = a \times b$ in register C.
- Register 1 is scratch.
- Overwrites registers A and B.

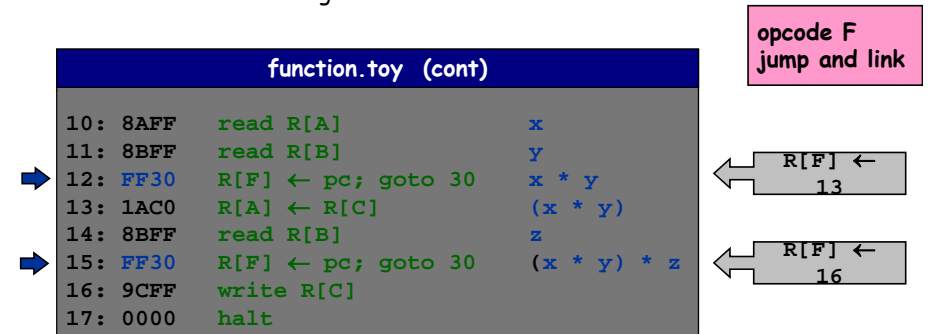


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Multiplication Function Call

Client program to compute $x \times y \times z$.

- Read x, y, z from standard input.
- Note: PC is incremented before instruction is executed.
- value stored in register F is correct return address



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Function Call: One Solution

Contract between calling program and function:

- Calling program stores function parameters in specific registers.
- Calling program stores return address in a specific register.
 - jump-and-link
- Calling program sets PC to address of function.
- Function stores return value in specific register.
- Function sets PC to return address when finished.
 - jump register

What if you want a function to call another function?

- Use a different register for return address.
- More general: store return addresses on a stack.

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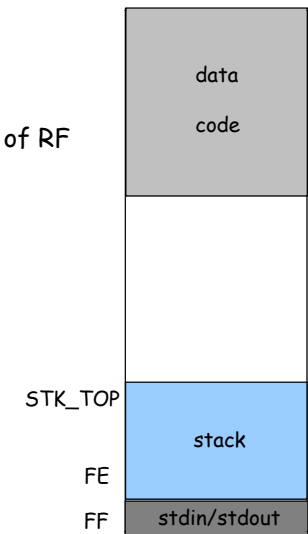
stack

STK_TOP DW 0xFF

; these procedures will use R8, R9
 ; assume return address is in RE, instead of RF
 ; it is the only exception

; push RF into stack

```
push  lda  R8, 1
      ld   R9, STK_TOP
      sub  R9, R9, R8
      st  R9, STK_TOP
      sti  RF, R9
      jr  RE
```



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stack

```

; pop and return [top] to RF
pop   lda    R8, 0xFF
      ld     R9, STK_TOP
      sub   R8, R8, R9
      bz    R8, popexit
      ldi   RF, R9
      lda   R8, 1
      add  R9, R9, R8
      st   R9, STK_TOP
popexit jr   RE
    
```

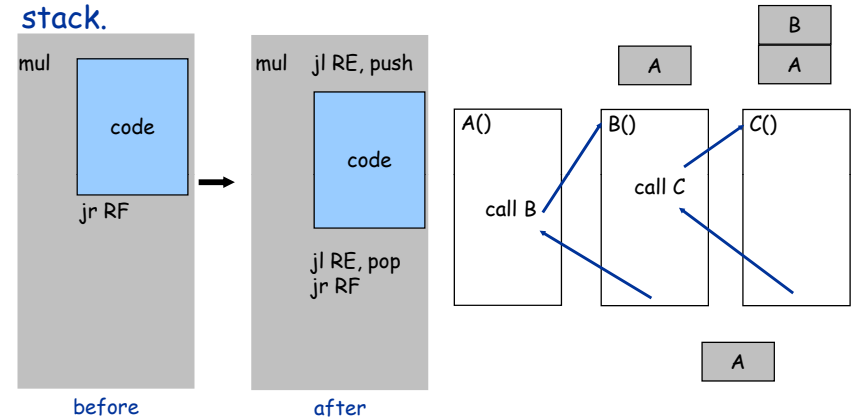
```

; the size of the stack, the result is in R9
stksize lda  R8, 0xFF
        ld   R9, STK_TOP
        sub  R9, R8, R9
        jr   RE
    
```

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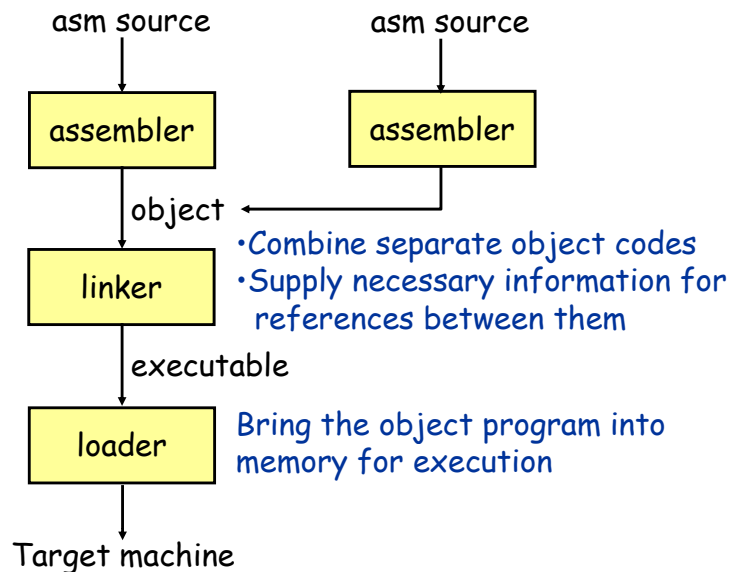
Procedure prototype

With a stack, the procedure prototype is changed. It allows us to have a deeper call graph by using the stack.



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Assembly programming flow



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Linking

Many programs will need multiply. Since multiply will be used by many applications, could we make multiply a library?

Toyasm has an option to generate an object file so that it can be later linked with other object files.

That is why we need linking. Write a subroutine mul3 which multiplies three numbers in RA, RB, RC together and place the result in RD.

Three files:

- stack.obj: implementation of stack, needed for procedure
- mul.obj: implementation of multiplication.
- multest.obj: main program and procedure of mul3

```
toylink multest.obj mul.obj stack.obj > multest.toy
```

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object file (multest.asm)

```

A      DW      3
B      DW      4
C      DW      5

; calculate A*B*C
main   ld      RA, A
       ld      RB, B
       ld      RC, C
       jl     RF, mul3
       st     RD, 0xFF
       hlt

; RD=RA*RB*RC
; return address is in RF
mul3   jl     RE, push

       lda     RD, 0
       add    RD, RC, RO
       jl     RF, mul
       add    RA, RC, RO
       add    RB, RD, RO
       jl     RF, mul
       add    RD, RC, RO

       jl     RE, pop
       jr     RF
    
```

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object file (mul.obj)

```

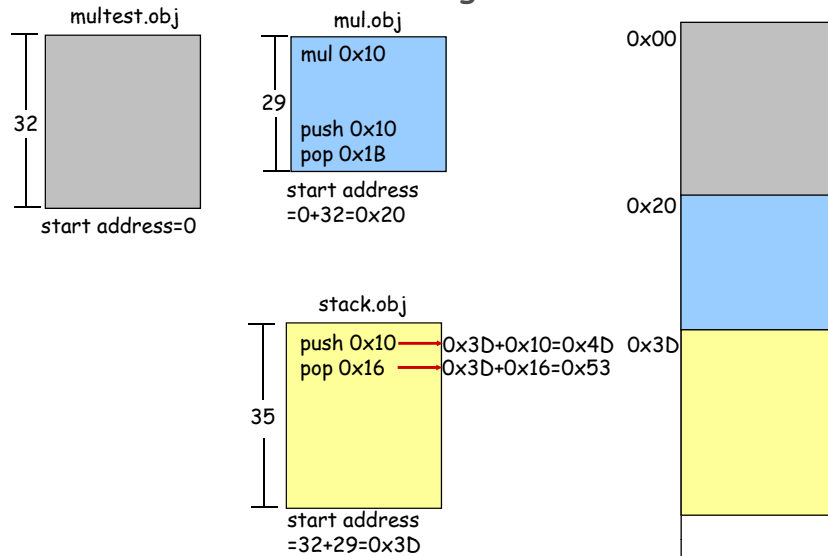
SIXTEEN DW 16 // size 29
// export 4
export table // SIXTEEN 0x00
// mul 0x10
// m_loop 0x14
// m_end 0x1A
// literal 2 17 18
// lines 14
00: 0010
10: FE00 // need to fill in
11: 7C00 // address of push
12: 7101 // once we know it
13: 8200
14: 2221
15: 53A2
16: 64B2
17: 3441
18: C41A
19: 1CC3
1A: D214 // need to fill in
1B: FE00 // address of pop
1C: EFO0 // once we know it

// import 2
import table // push 1 0x10
// pop 1 0x1B
    
```

These are literals.
No need to relocate

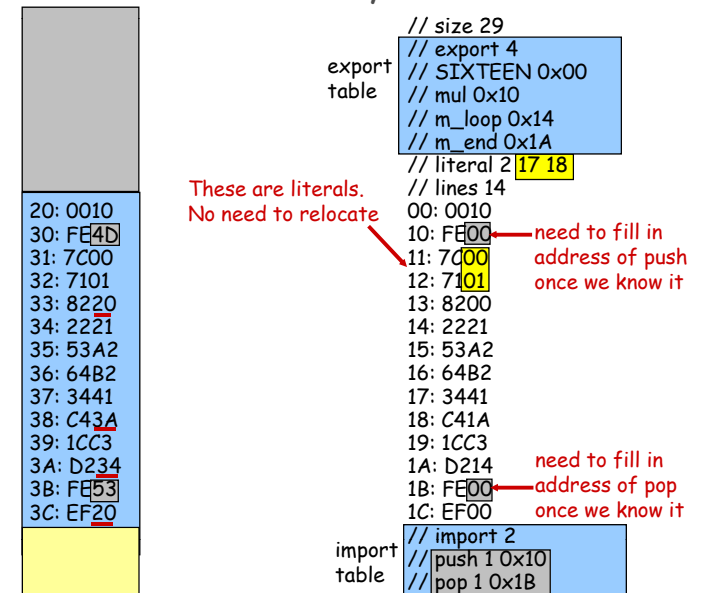
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Linking



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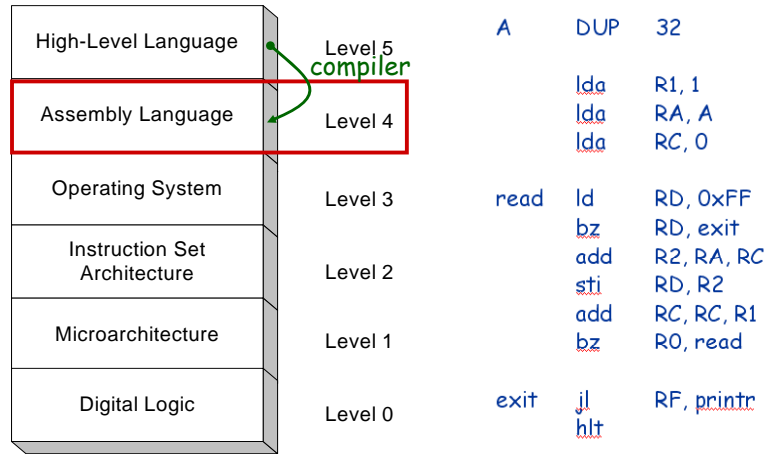
Resolve external symbols



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Virtual machines

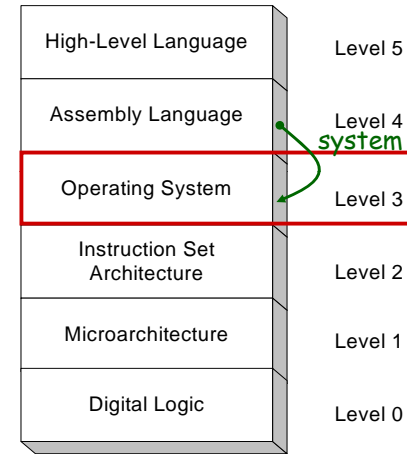
Abstractions for computers



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Virtual machines

Abstractions for computers



Operating system is a resource allocator

- Managing all resources (memory, I/O, execution)
- Resolving requests for efficient and fair usage

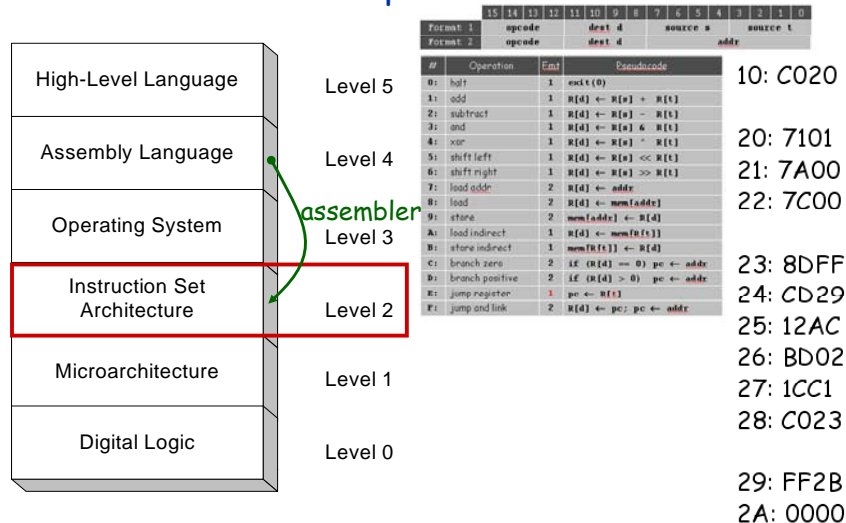
Operating system is a control program

- Controlling execution of programs to prevent errors and improper use of the computer

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Virtual machines

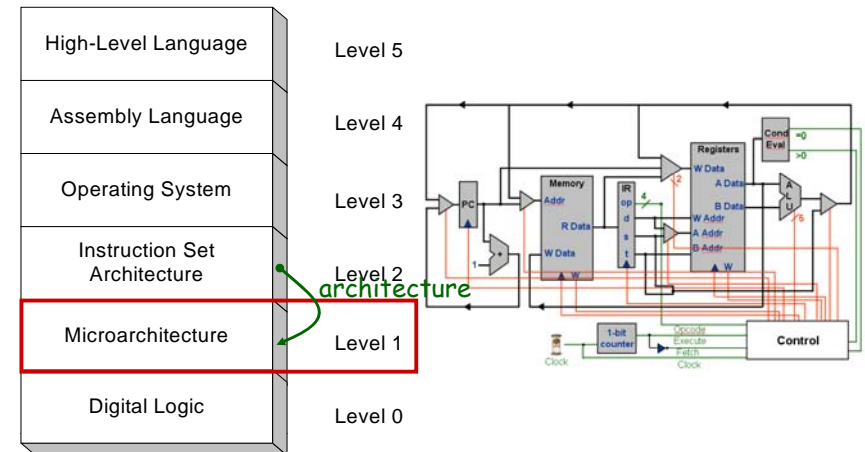
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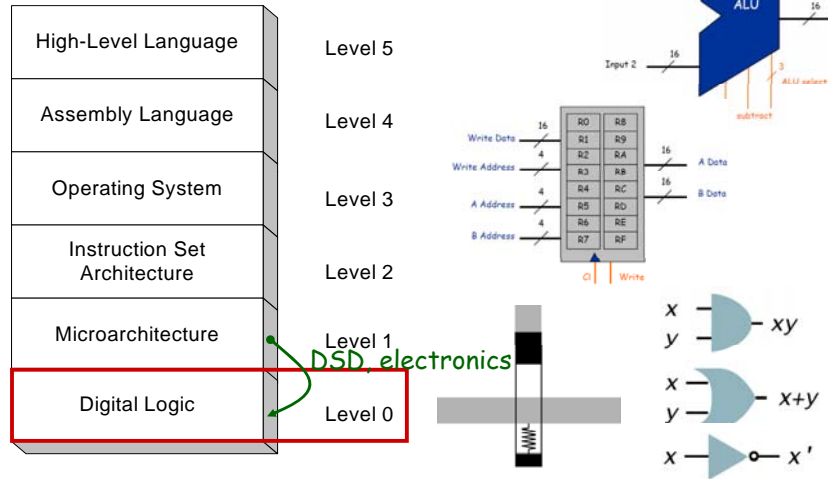
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Virtual machines

Abstractions for computers



Assignment #2

Assigned: 11/03/2008

Due: 11:59pm 11/16/2008

Part 1 (50%): write a procedure BCD to convert a hexadecimal number into a BCD (Binary-Coded Decimal). The input number is placed in RA. The result should be placed in RB. The return address is in RF. (Hint: you need to implement division)

Part 2 (30%): write a procedure CNT0 to count 0's in an array. The address of the array is placed at RA. The size of the array is specified by RC. The result should be placed in RB. The return address is in RF.

Part 3 (20%): write a program to read a series of numbers specified by the user from stdin until the input is 0x0000. Count the number of 0-bits in the input array and display this number using BCD in stdout.