

# Solution Space of Perceptron

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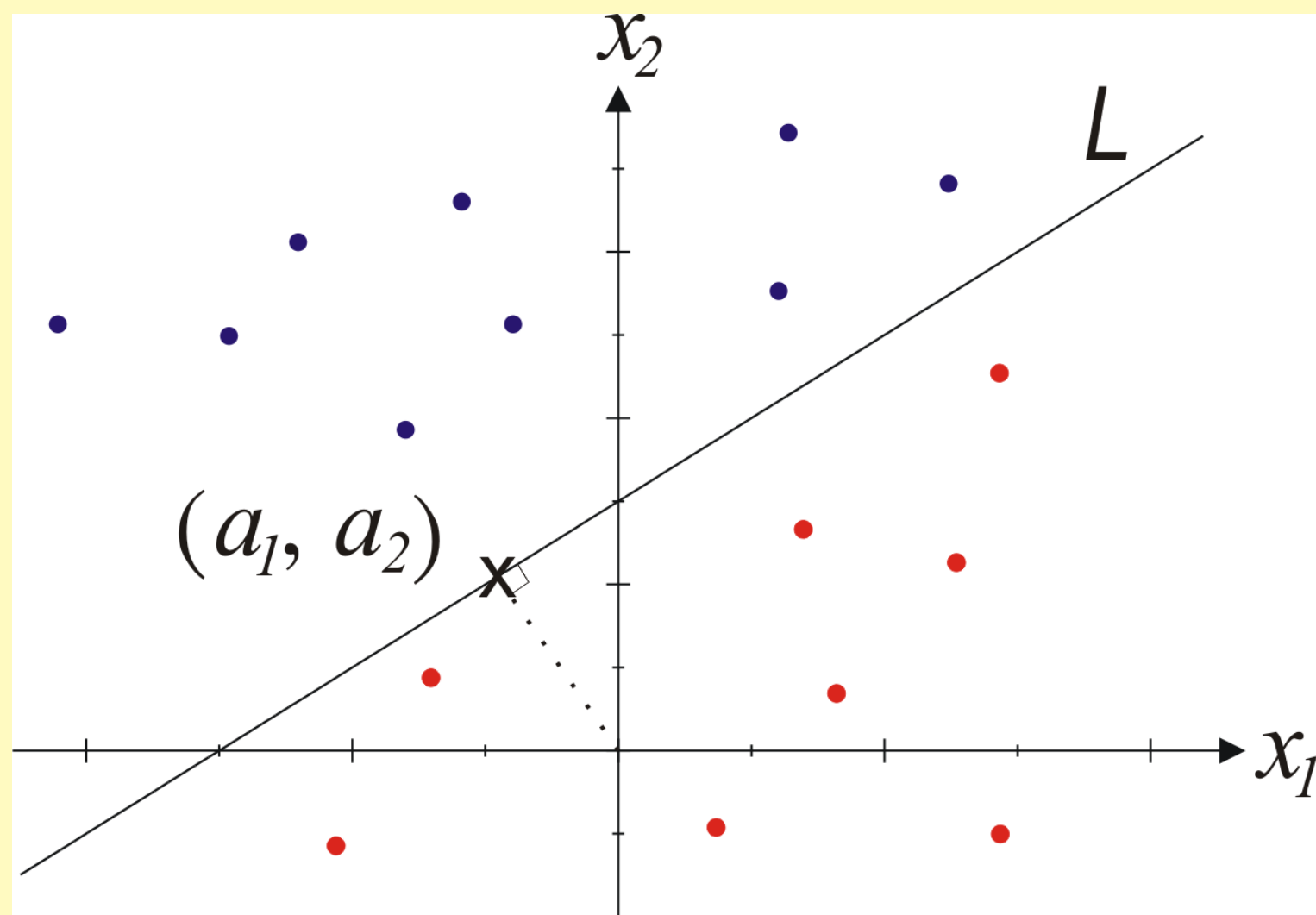


## Contribution

We presented a technique to visualize the global structure of the solution space for perceptron. To our knowledge, this solution space is the only one that can be used to explain various training behaviors of perceptron.

## Method

The decision line in 2D input space can be represented by a perpendicular point.



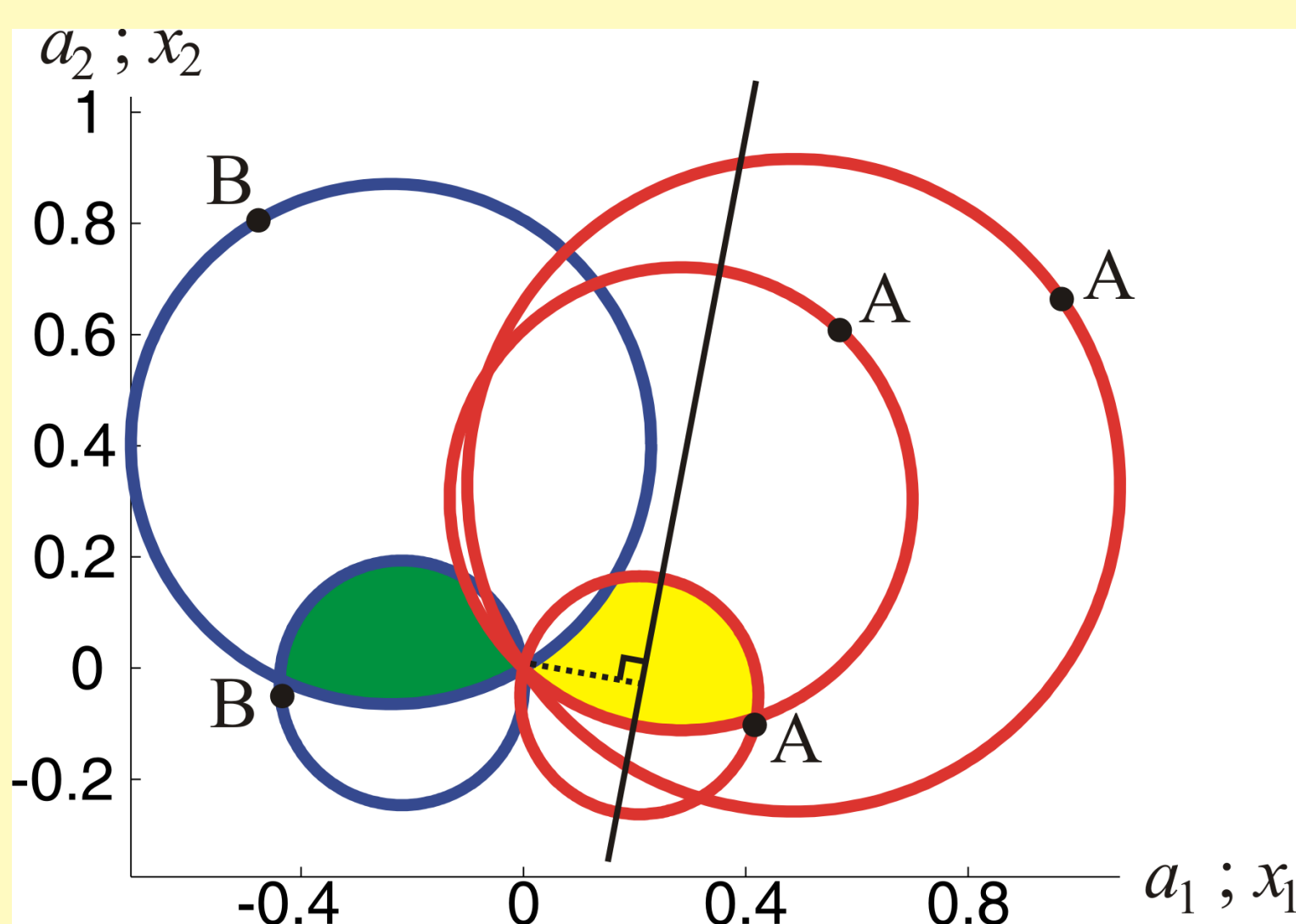
$$L : w_1 x_1 + w_2 x_2 + w_3 = 0$$

$$a_1 = \frac{-w_1 w_3}{w_1^2 + w_2^2} \text{ and } a_2 = \frac{-w_2 w_3}{w_1^2 + w_2^2}$$

Each point  $(a_1, a_2)$  represents two decision lines with different directions.

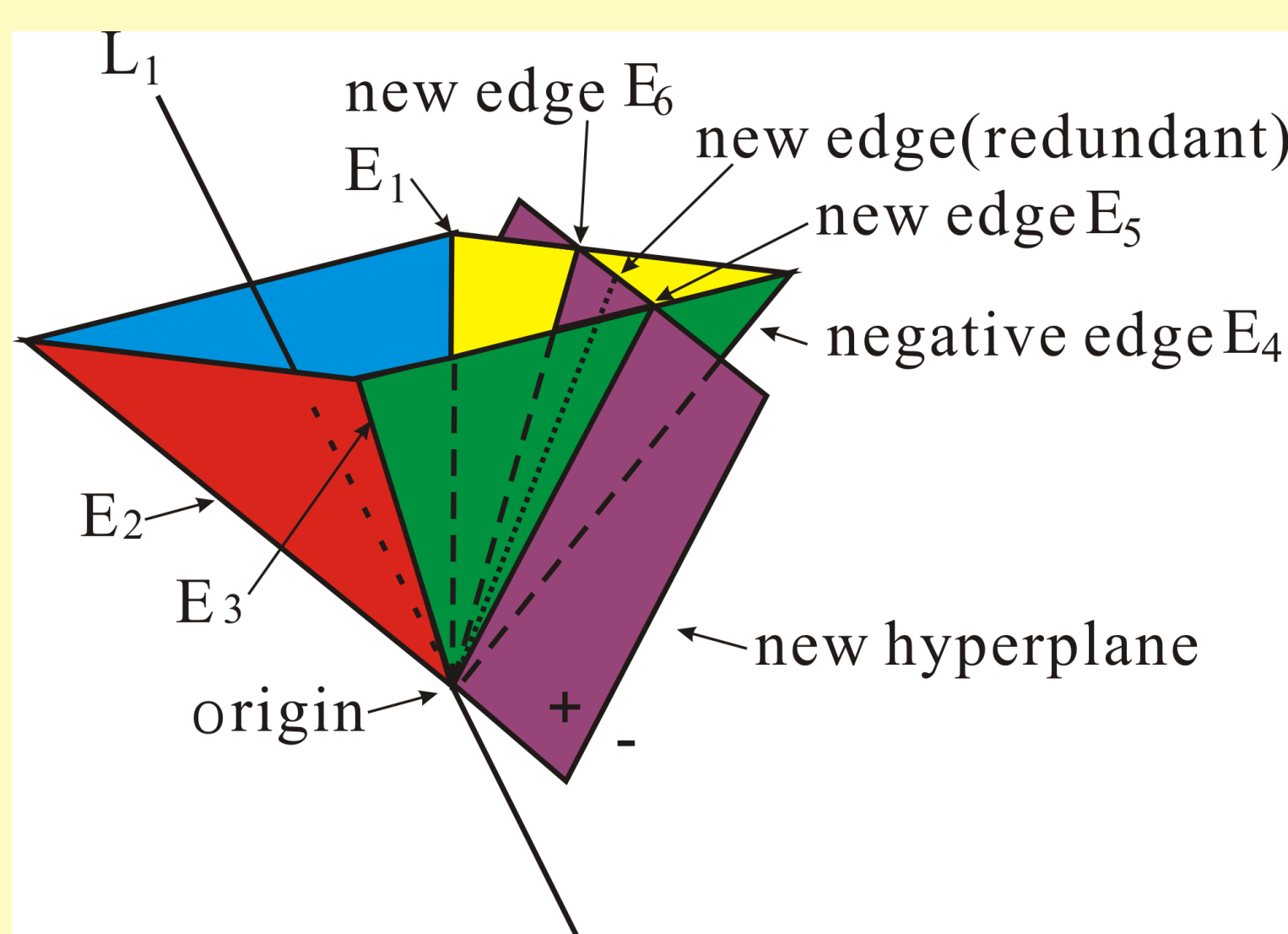
$$S \left[ \frac{a_1}{a_1^2 + a_2^2} x_1 + \frac{a_2}{a_1^2 + a_2^2} x_2 - 1 \right] = 0, S = \pm 1$$

## Solution Space

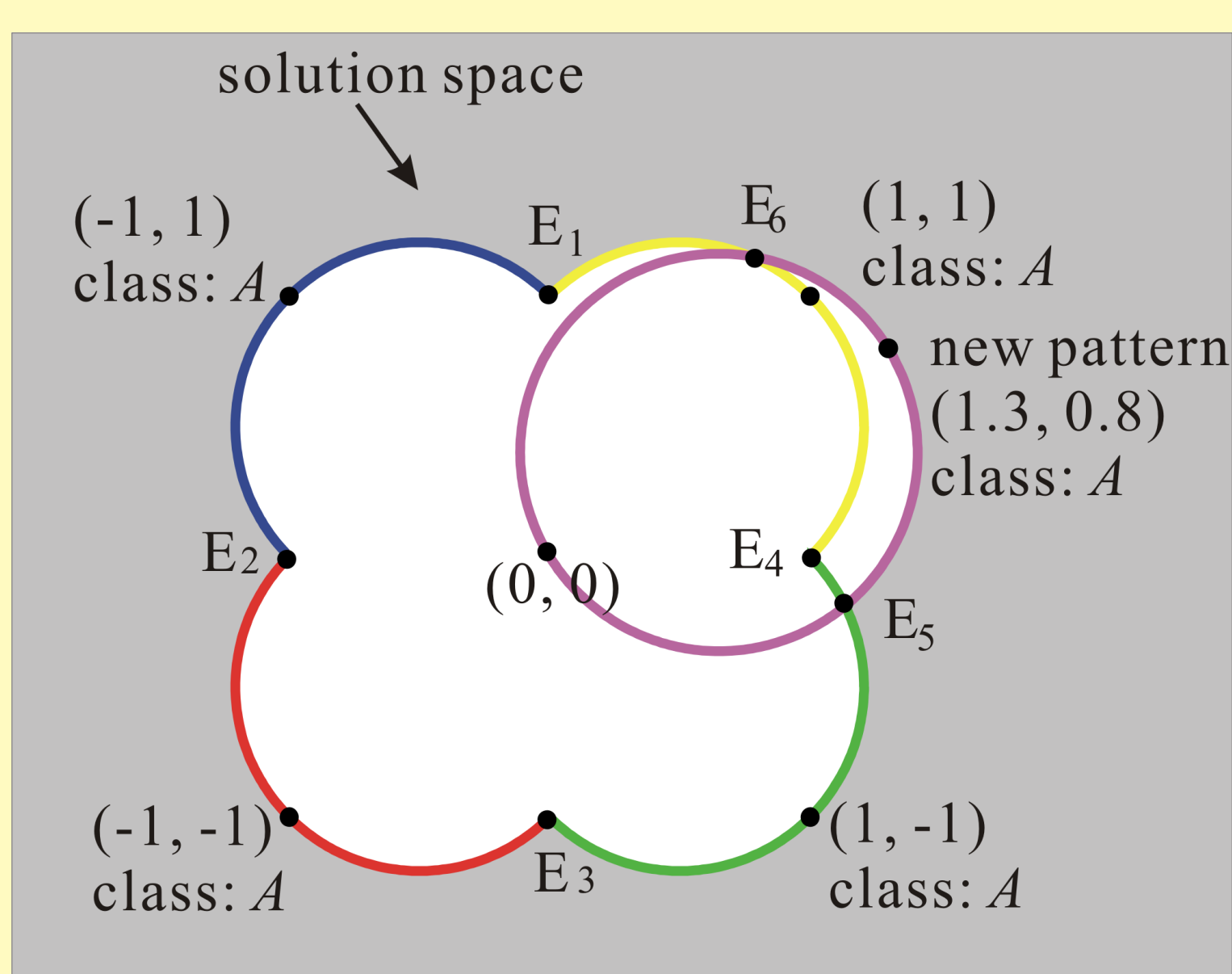


## Correspondence

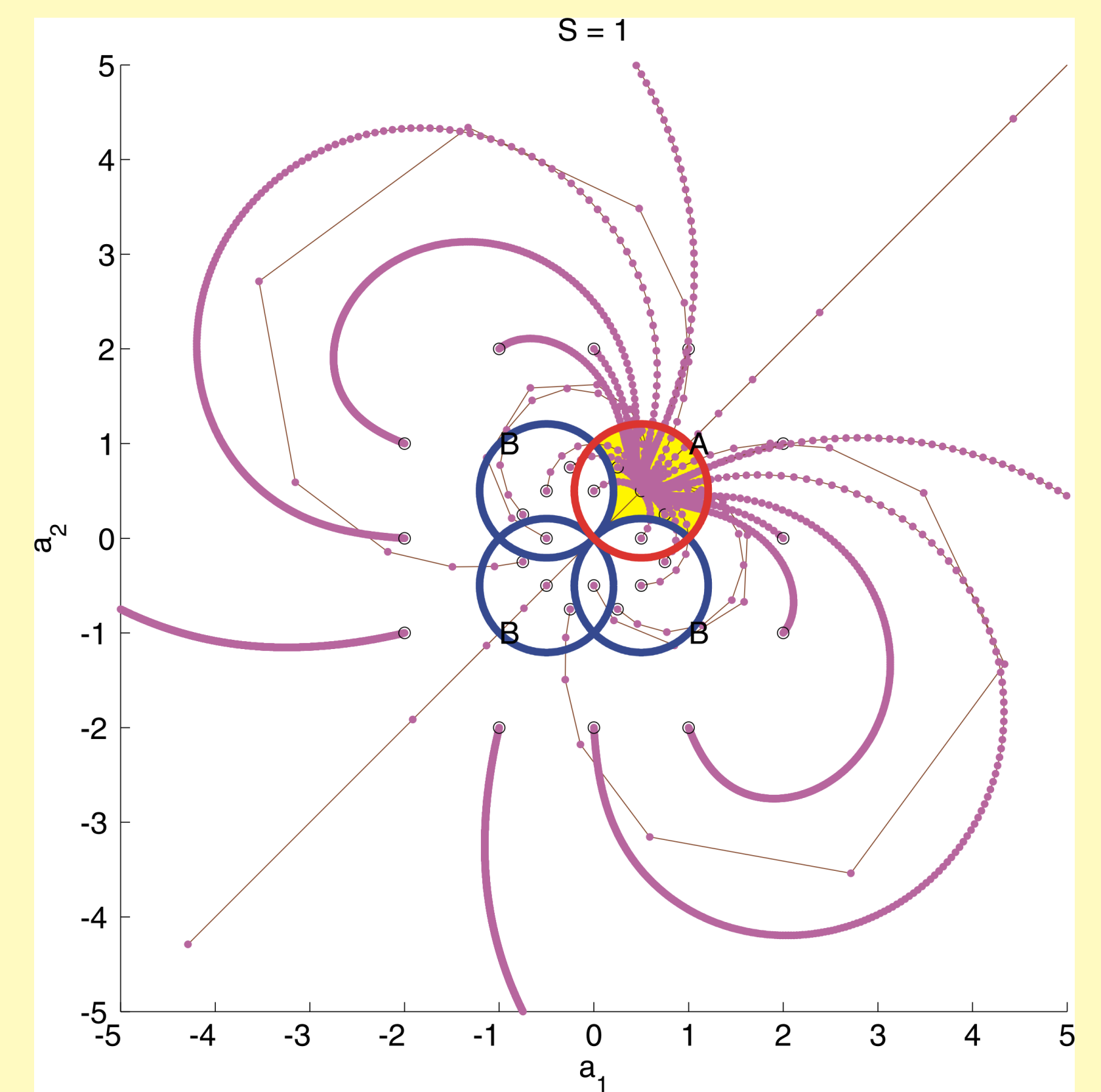
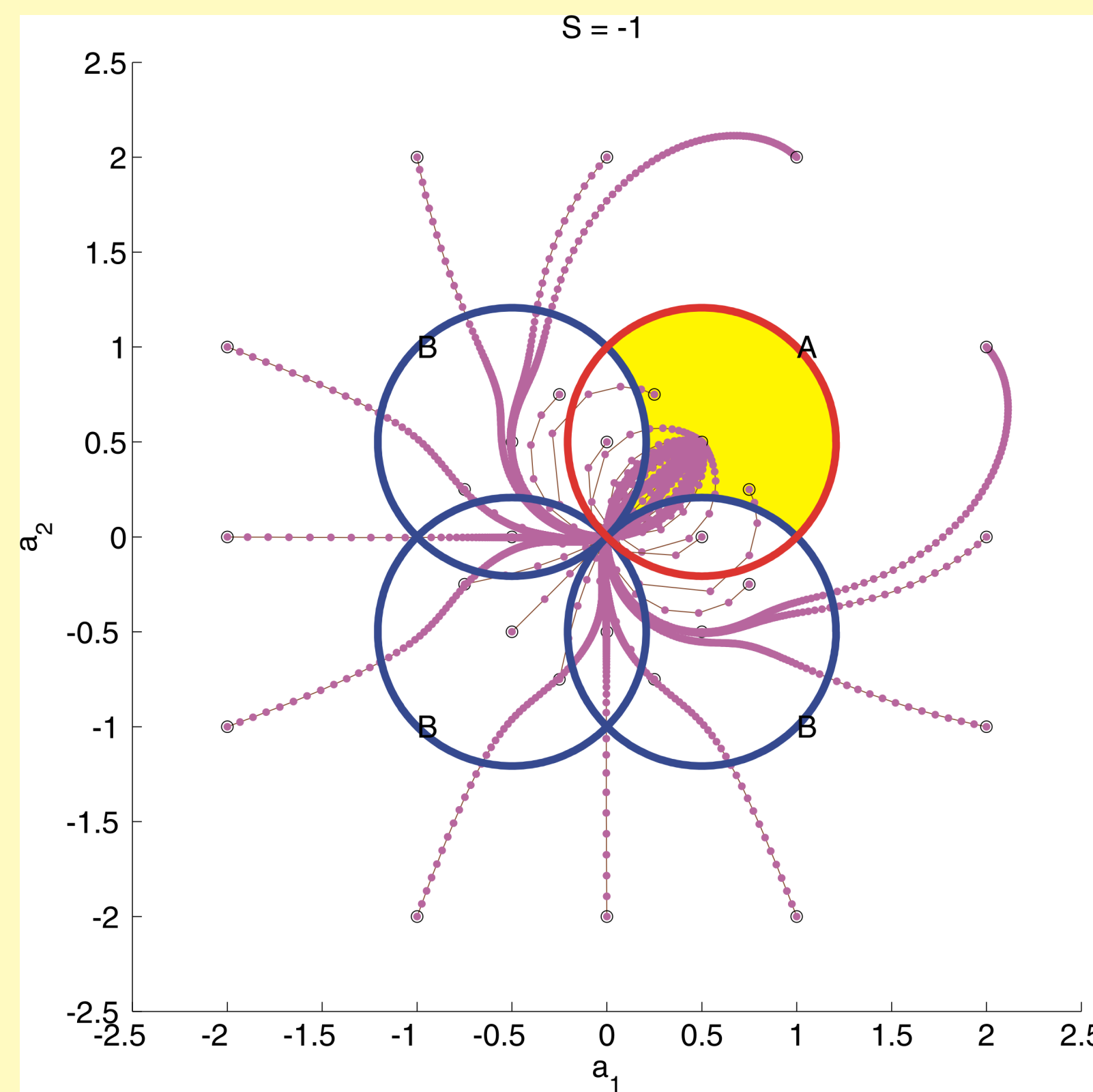
Weight Space:



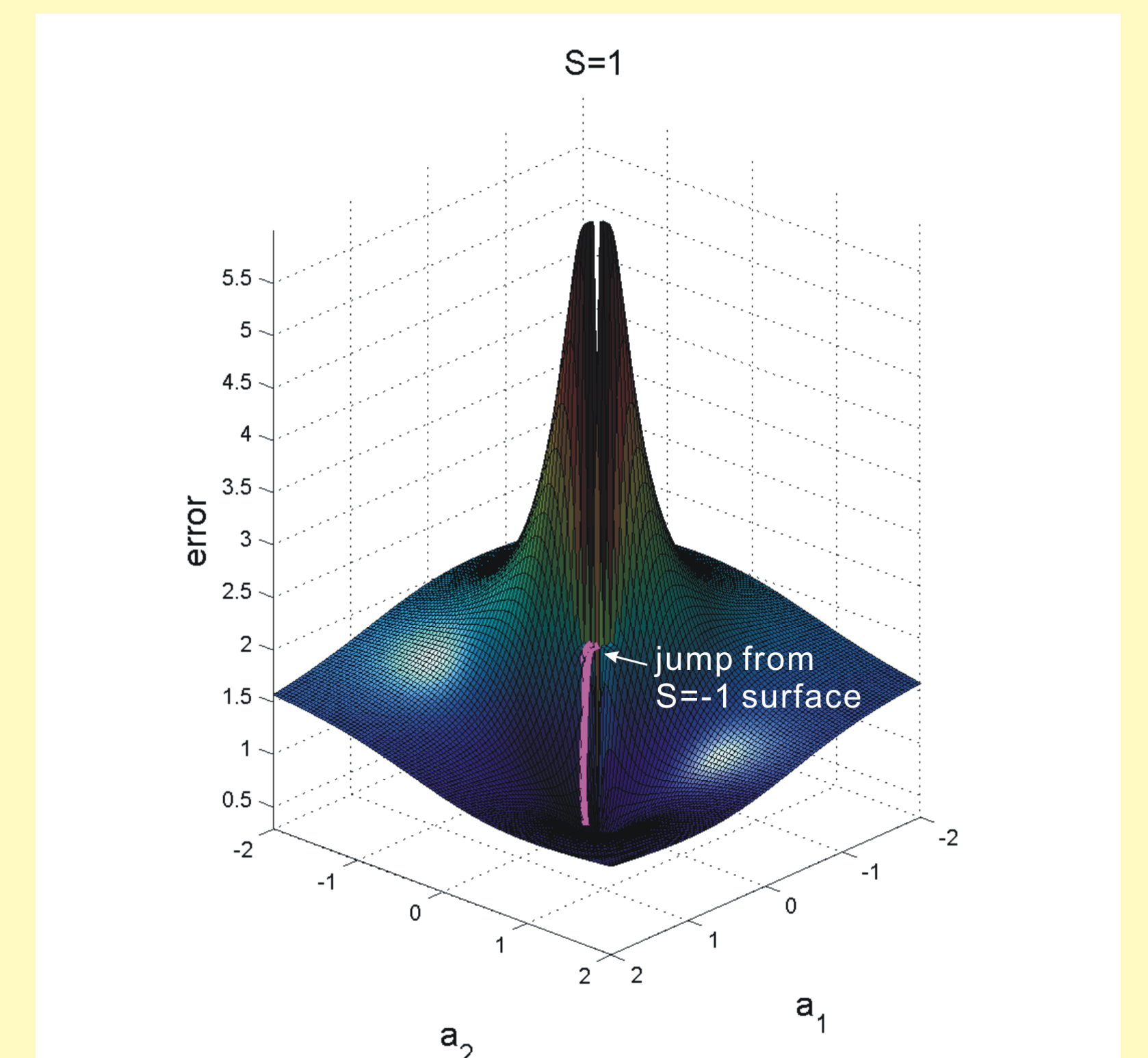
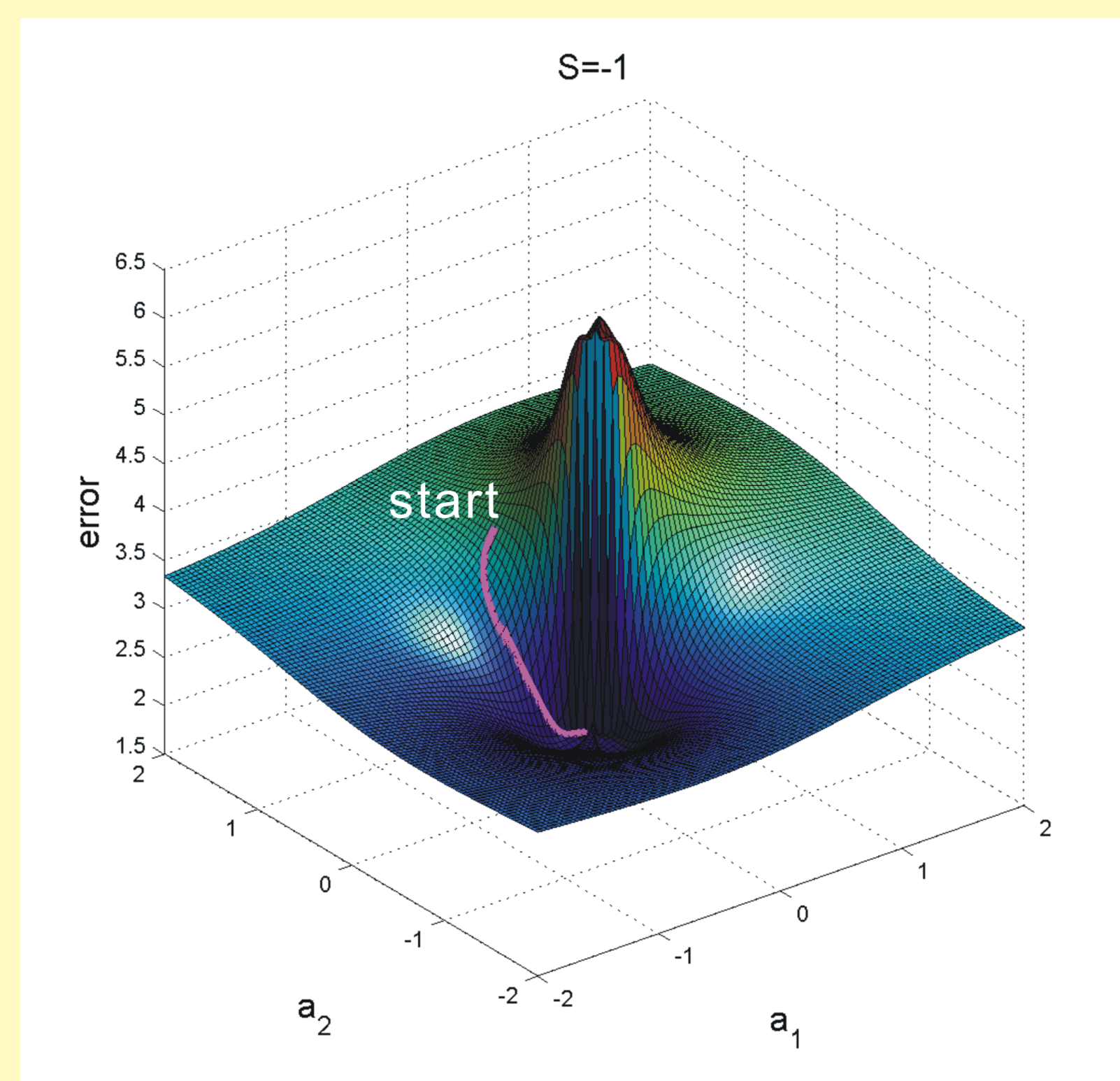
Input Space:



## Training Path



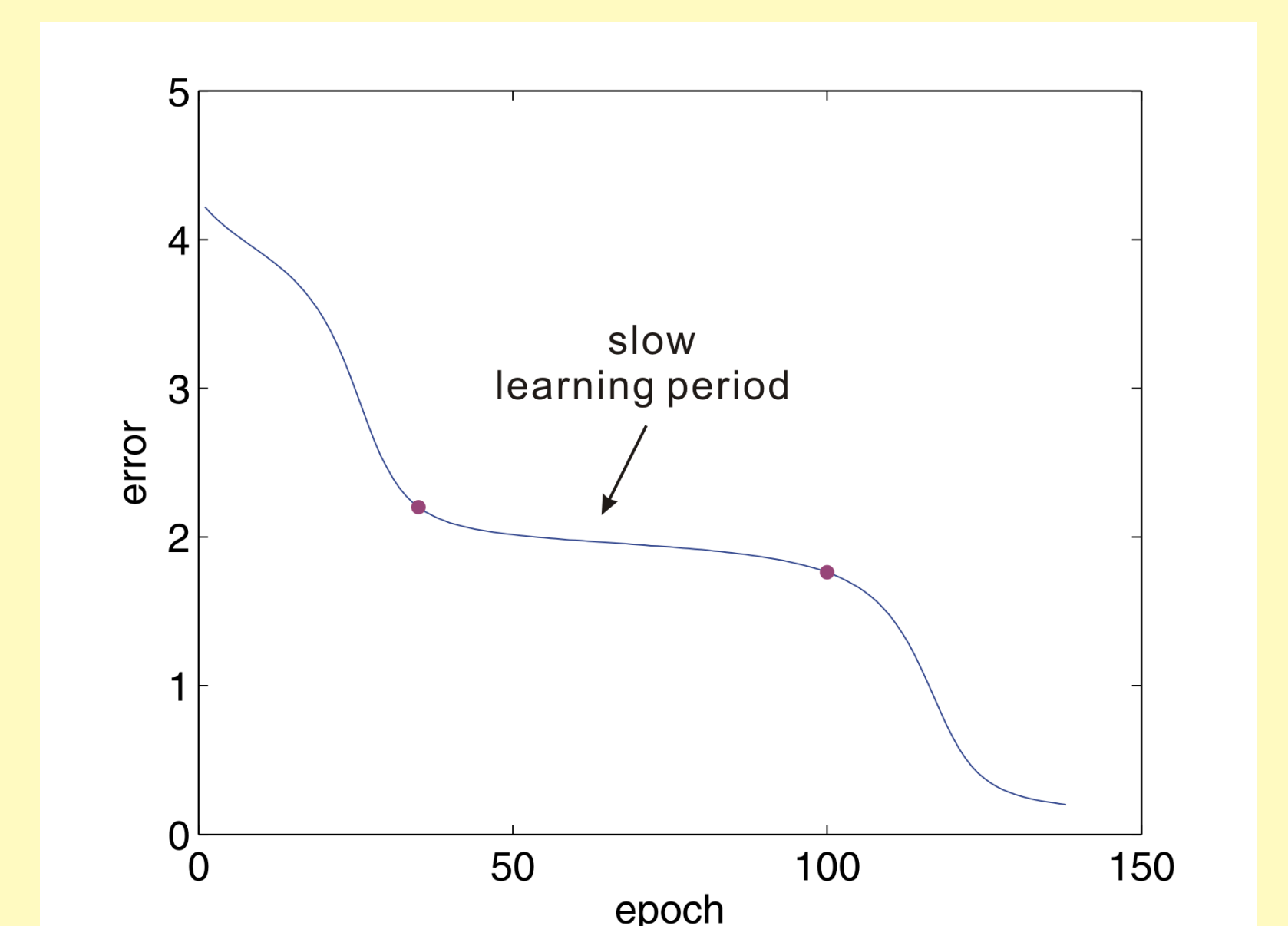
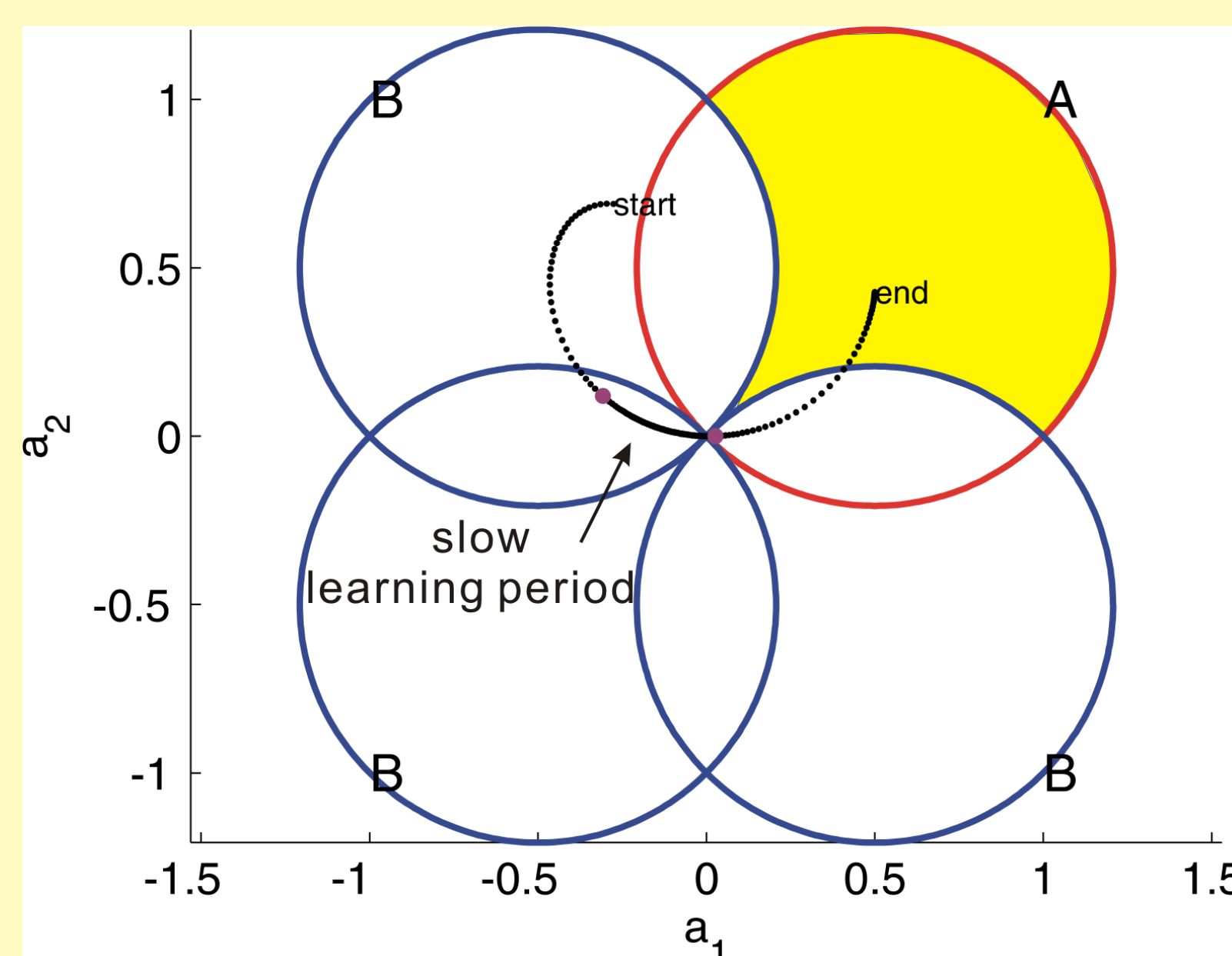
## Error Surfaces



## Learning Behavior

Above figures show that if the solution space only exists at  $S=1$  space and the initial weights are at  $S=-1$  space, the training path needs to pass the origin to change space. It means  $w_3$  changes from positive value to negative value. Compare the learning behaviors of two different initial weights,  $W_a = [1, -2.5, 2]$  and  $W_b = 0.5W_a = [0.5, -1.25, 1]$ , we'll find the bigger absolute value of  $w_3$  causes slower learning period when changing from positive value to negative value. This can explain why the weights of the perceptron to be trained are typically initialized at small random values.

Initial Weights:  $W_a = [1, -2.5, 2]$



Initial Weights:  $W_b = [0.5, -1.25, 1]$

