Autoregressive Models I

- LLM is an autoregressive model, so before giving details of LLM, we discuss basic concepts of autoregressive models.
- Autoregressive models predict the next component in a sequence by using information from previous inputs in the same sequence.
- A typical example is time series prediction with applications in stock index prediction, electricity load prediction, etc.

Autoregressive Models II

Assume our sequence is

$$z_1, z_2, \ldots$$

 The way to train a model is by using data shown in the following table.

training instance target value

$$z_1, \dots, z_T$$
 z_{T+1} z_{1}, \dots, z_{T+1} \vdots \vdots

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Autoregressive Models III

 In practice, data points occurred long time ago may not be important. We can discard them to make training instances have the same number of values:

training instance target value

$$z_1, \dots, z_T$$
 z_{T+1} z_2, \dots, z_{T+1} z_{T+2} \vdots

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July 16, 2025 3 / 12

LLM Is an Autoregressive Model I

- The next-token prediction of LLM is a case of auto-regressive settings.
- Recall we have the setting shown in the following figure.

July 16, 2025

LLM Is an Autoregressive Model II

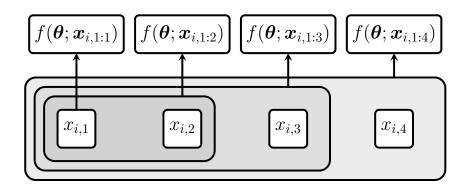


Figure: A sequence of next-token predictions

July 16, 2025

LLM Is an Autoregressive Model III

Note that we aim to have

$$f(\boldsymbol{\theta}; \boldsymbol{x}_{i,1:1}) \approx x_{i,2}$$

 $f(\boldsymbol{\theta}; \boldsymbol{x}_{i,1:2}) \approx x_{i,3}$
 \vdots

- For LLM, the *f* function is complicated.
- Thus, we begin with learning how to train a simple auto-regressive model.
- From the discussion, we will identify important properties to be used for LLM training/prediction.

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July 16, 2025 6 / 12

Training a Simple Autoregressive Model I

• Assume we have the following sequence of data

$$z_1, z_2, \ldots$$

and would like to construct a model for one-step ahead prediction.

 From the observed data, we collect the following (instance, target value) pairs

$$egin{aligned} m{x}_1 &= [z_1, \dots, z_T]^T & y_1 &= z_{T+1} \ m{x}_2 &= [z_2, \dots, z_{T+1}]^T & y_2 &= z_{T+2} \ dots & dots \end{aligned}$$

Training a Simple Autoregressive Model II

- Assume we have collected n training instances.
- We can then solve a simple least-square regression problem to get a model

$$\min_{\boldsymbol{w}} \sum_{i=1}^{n} (y_i - \boldsymbol{w}^T \boldsymbol{x}_i)^2.$$
 (1)

- ullet Here w includes the model weights.
- We notice two important properties here.
- The first property is that we use matrix operations to handle all data together.

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Training a Simple Autoregressive Model III

• Specifically, (1) has an analytic solution:

optimal
$$\boldsymbol{w} = (X^T X)^{-1} X^T \boldsymbol{y},$$

where

$$m{y} = egin{bmatrix} y_1 \ dots \ y_n \end{bmatrix} ext{ and } X = egin{bmatrix} m{x}_1^T \ dots \ m{x}_n^T \end{bmatrix} \in R^{n imes T}.$$

• For simplicity, we assume that X^TX is invertible.

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July 16, 2025 9 / 12

Training a Simple Autoregressive Model IV

- We see that even though y_{T+1} is the target value of the first instance, it is also a feature of the second training instance.
- Our setting allows the model building by efficient matrix operations.
- That is, we handle all training data together, even though there are some auto-regressive relationships between them.
- The reason we can do this is because our prediction function on training data is the same as the one we use for future prediction.

Training a Simple Autoregressive Model V

- In testing, for a vector x containing past information, we use $w^T x$ to get our prediction.
- In training, for any x_i , in (1) we use the same way to hope that w^Tx_i is close to y_i .
- This is the second crucial property we will use in our LLM design.

July 16, 2025

References I