Lesson 10. Basic complexity classes

CSIE 3110 - Formal Languages and Automata Theory

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The language HALT is more difficult than $HALT_0$ (even if both are undecidable).

The classification of languages/problems according to their "difficulty" is an important area in computer science.

Classification in this lesson

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The classification according to the number of steps is called *the time complexity*.

The classification according to the number of cells is called *the space complexity*.

• The class of problems decidable by polynomial time DTM and NTM, denoted by **P** and **NP**, respectively.

- The class of problems decidable by polynomial time DTM and NTM, denoted by **P** and **NP**, respectively.
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- The class of problems decidable by polynomial space DTM and NTM, denoted by **PSPACE** and **NPSPACE**, respectively.
- The class of problems decidable by logarithmic space DTM and NTM, denoted by L and NL, respectively.

We will also discuss some basic relations between all these classes.

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Recall

 $\mathbb N$ denotes the set of natural numbers $\{0,1,2,\ldots\}.$

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Let $f, g : \mathbb{N} \to \mathbb{N}$ be functions.

(Def.) f(n) = O(g(n)) means there is $c, n_0 \in \mathbb{N}$ such that for every $n \ge n_0$:

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Recall also that for a word $w \in \Sigma^*$, |w| denotes the length of w.

Polynomial time complexity

(Def.) Let $k \ge 1$ be a fixed integer.

A DTM/NTM \mathcal{M} runs in time $O(n^k)$, if:

There is $c, n_0 \in \mathbb{N}$ such that for every word $w \in \Sigma^*$ with $|w| \ge n_0$, every run of \mathcal{M} on w has length $\le c|w|^k$.

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That is, for every run of \mathcal{M} on w with $|w| \ge n_0$:

 $C_0 \vdash C_1 \vdash \cdots \vdash C_N$ C_N can be acc./rej.

we have $N \leq c |w|^k$.

Intuitively, each \vdash counts as one step (i.e., each time a transition is applied).

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Intuitively, each \vdash counts as one step (i.e., each time a transition is applied).

(Note) The definition is the same for both DTM and NTM.

The only difference is a DTM have only one run on each input word w, whereas an NTM may have many runs.

Polynomial time complexity - continued

(Def.) A DTM/NTM \mathcal{M} decides/accepts a language L in time $O(n^k)$, if:

- \mathcal{M} decides L.
- \mathcal{M} runs in time $O(n^k)$.

Polynomial time complexity - continued

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- \mathcal{M} decides L.
- \mathcal{M} runs in time $O(n^k)$.

(Recall) \mathcal{M} decides a language L, if for every word $w \in \Sigma^*$:

 \mathcal{M} accepts w if and only if $w \in L$

(Def.) For a fixed integer $k \in \mathbb{N}$:

 $DTIME[n^k] := \{L \mid \text{ there is a } \underline{DTM} \ \mathcal{M} \text{ that decides } L \text{ in time } O(n^k) \}$

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(Note) The class P is closed under complement, union and intersection.

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(Def.) For a fixed integer $k \in \mathbb{N}$:

NTIME $[n^k]$:= {L | there is an <u>NTM</u> \mathcal{M} that decides L in time $O(n^k)$ }

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(Note) The class NP is closed under union and intersection.

It is not known whether NP is closed under complement.

The class coNP

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By definition, NP = coNP if and only if NP is closed under complement.

(Note) This is <u>NOT</u> the correct definition of **coNP**:

 $L \in coNP$ if and only if $L \notin NP$

$\textbf{SAT} \in \textbf{NP}$

SAT	
Input: Task:	A propositional formula φ . Output True, if φ has (at least one) satisfying assignment. Otherwise, output False.

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(Algo.) On input formula φ :

- Let x_1, \ldots, x_n be the variables in φ .
- For each *i* = 1, . . . , *n* do:
 - $z := 0 \parallel 1;$
 - If z == 1, assign x_i with True.
 - If z == 0, assign x_i with False.
- Check if the formula φ evaluates to true under the assignment.
- If it evaluates to True, then ACCEPT. If it evaluates to False, then REJECT.

$\overline{\textbf{SAT}} \in \textbf{coNP}$

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Since SAT \in **NP**, $\overline{SAT} \in coNP$.

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 each configuration in every run of M on w has length ≤ c|w|^k.

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the length $|C_i| \leq c |w|^k$, for each $i = 0, \ldots, N$.

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NPSPACE :=
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(Def.) coNPSPACE := $\{L \mid \Sigma^* - L \in NPSPACE\}$

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- If $L \in \text{NSPACE}[n^k]$, then $\Sigma^* L \in \text{NSPACE}[n^k]$.
- NSPACE $[n^k] \subseteq \text{DSPACE}[n^{2k}].$

Thus,

PSPACE = NPSPACE = coNPSPACE

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In literature we usually only use **PSPACE**.

The notations NPSPACE and coNPSPACE are hardly used.

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By definition:

$P \subseteq NP \subseteq PSPACE$

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In literature we usually only use **PSPACE**.

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By definition:

$P \subseteq NP \subseteq PSPACE$

We do not know whether any of the inclusion is strict.

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The class L

(Def.) A language L is in L, if there is a 2-tape DTM \mathcal{M} that decides L and there is $c \in \mathbb{N}$ such that for every input word w:

- The first tape always contains only the input word w.
 That is, M can only read the first tape, but <u>never</u> changes the content of the first tape.
- \mathcal{M} uses space $\leq c \cdot \log(|w|)$ in its second tape.

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- \mathcal{M} uses space $\leq c \cdot \log(|w|)$ in its second tape.

(Note) The 2-tape DTM requirement is not strict. It can be replaced with multiple tape DTM with the condition that the TM does not change the content of the first tape and the number of cells used in the other tapes is $\leq c \cdot \log(|w|)$.

The class NL and coNL

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(Def.)

 $\textbf{coNL} \ := \ \{L \mid \boldsymbol{\Sigma}^* - L \in \textbf{NL}\}$

(Deterministic/non-deterministic time/space hierarchy theorem) For every $k \ge 1$ and $\epsilon > 0$:

 $\begin{array}{l} \text{DTIME}[n^k] \subsetneq \text{DTIME}[n^{k+\epsilon}] \\ \text{DSPACE}[n^k] \subsetneq \text{DSPACE}[n^{k+\epsilon}] \end{array}$

It is known that:

$$\begin{split} & \operatorname{NTIME}[n^k] \subsetneq \operatorname{NTIME}[n^{k+\epsilon}] \\ & \operatorname{NSPACE}[n^k] \subsetneq \operatorname{NSPACE}[n^{k+\epsilon}] \end{split}$$

(Deterministic/non-deterministic time/space hierarchy theorem) For every $k \ge 1$ and $\epsilon > 0$:

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It is known that:

• $NL \subseteq P$.

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Because $L \subseteq DSPACE[n] \subsetneq DSPACE[n^2] \subseteq PSPACE$.

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It is known that:

- $NL \subseteq P$.
- NL = coNL.
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Because $L \subseteq DSPACE[n] \subsetneq DSPACE[n^2] \subseteq PSPACE$.

• Likewise, $NL \subsetneq PSPACE$.

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It is known that:

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Because $L \subseteq DSPACE[n] \subsetneq DSPACE[n^2] \subseteq PSPACE$.

• Likewise, $NL \subsetneq PSPACE$.

Likewise, $\mathsf{NL} \subseteq \mathrm{NSPACE}[n] \subseteq \mathrm{DSPACE}[n^2] \subsetneq \mathrm{DSPACE}[n^3] \subseteq \mathsf{PSPACE}$.

What is known and not known so far - continued

Putting all the pieces together:

$\mathsf{L}\ \subseteq\ \mathsf{NL}\ \subseteq\ \mathsf{P}\ \subseteq\ \mathsf{NP}\ \subseteq\ \mathsf{PSPACE}$

Since L $\,\subsetneq\,$ PSPACE and NL $\subsetneq\,$ PSPACE, at least one of the inclusions is strict.

What is known and not known so far - continued

Putting all the pieces together:

$\mathsf{L}\ \subseteq\ \mathsf{NL}\ \subseteq\ \mathsf{P}\ \subseteq\ \mathsf{NP}\ \subseteq\ \mathsf{PSPACE}$

Since L \subseteq **PSPACE** and **NL** \subseteq **PSPACE**, at least one of the inclusions is strict.

The question: Which one?

End of Lesson 10