# CSIE 5111: Introduction to Mathematical Logic 

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## Lesson 0: Preliminaries

Theme: Review of some essential mathematical backgrounds.

## 1 Useful notations and facts from discrete mathematics

### 1.1 Equivalence relations

A binary relation $R$ over $X$ is called an equivalence relation, if it satisfies the following conditions.

- Reflexive: $(x, x) \in R$, for every $x \in X$.
- Symmetric: $(x, y) \in R$ if and only if $(y, x)$, for every $x, y \in X$.
- Transitive: for every $x, y, z \in X$, if $(x, y) \in R$ and $(y, z) \in R$, then $(x, z) \in R$.

For $x \in X$, the equivalence class of $x$ in $R$ is defined as:

$$
[x]_{R}:=\{y \mid(x, y) \in R\}
$$

Lemma 0.1 Let $R$ be an equivalence relation over $X$. Then, the following holds:

- $[x]_{R}=[y]_{R}$ if and only if $(x, y) \in R$.
- If $[x]_{R} \neq[y]_{R}$, then $[x]_{R} \cap[y]_{R}=\emptyset$.

Theorem 0.2 Let $R$ be an equivalence relation over $X$. Then, the equivalence classes of $R$ partition $X$, i.e., every member of $X$ belongs to exactly one equivalence class of $R$.

### 1.2 Countable and uncountable sets

Let $\mathbb{N}$ be the set of natural numbers $\{0,1,2, \ldots\}$. A set $X$ is countable, if there is an injective function from $X$ to $\mathbb{N}$. Otherwise, it is called an uncountable set.

Theorem 0.3 The following sets are all countable.
(1) The set $\mathbb{Z}=\{\ldots,-2,-1,0,1,2, \ldots\}$ of integers.
(2) The set $\mathbb{N}^{k}$, for every integer $k \geqslant 1$.
(3) The set $\mathbb{N}^{*}:=\bigcup_{k \geqslant 1} \mathbb{N}^{k}$.

Theorem 0.4 The set $2^{\mathbb{N}}$ is uncountable.

### 1.3 Poset (partially ordered set)

Let $X$ be a set and $R$ be a binary relation on $X$. The set $X$ is a poset (w.r.t. $R$ ), if $R$ is reflexive, anti-symmetric* ${ }^{*}$ and transitive.

Definition 0.5 An element $m \in X$ is a maximal element in a poset $X$ (w.r.t. $R$ ), if for every $x \in X$ and $x \neq m,(m, x) \notin R$.

[^0]Definition 0.6 A subset $C$ of $X$ is a chain in $X$ (w.r.t. $R$ ), if for every $x, y \in C$, either $(x, y) \in R$, or $(y, x) \in R$. A chain $C$ is bounded, if there is $z \in X$ such that for every $x \in C$, $(x, z) \in R$.

The three statements below are equivalent and they are usually taken as "axioms" in mathematics.

Axiom of choice: Let $I$ be a set such that each $i \in I$ is associated with a set $A_{i}$. There is a function $f: I \rightarrow \bigcup A_{i}$ such that for every $i \in I, f(i) \in A_{i}$.
Zorn's lemma: Let $(A, R)$ be a poset such that every chain in $A$ is bounded. There is an element $m \in A$ such that for every $x \in A$ and $x \neq m,(m, x) \notin R$.
Well-ordering theorem: Every set can be well-ordered. That is, for every set $A$, there is a total order relation $R$ on $A$, that is, it satisfies the following conditions:

- Antisymmetry: for every $a, b \in A$, if $(a, b),(b, a) \in R$, then $a=b$;
- Transitive: if $(a, b),(b, c) \in R$, then $(a, c) \in R$;
- Totality: for every $a, b \in A$, either $(a, b) \in R$ or $(b, a) \in R$,
such that for every nonempty subset $B \subseteq A$ has a minimal element (w.r.t. $R$ ).
There is a kind of contradiction here: the axiom of choice is viewed as obviously "correct," while the well-ordering theorem is obviously "false," and there are mixed opinions about Zorn's lemma.


## 2 Basic propositional calculus (Boolean logic)

Throughout this class, T and F are special symbols denoting true and false, respectively. The symbols $\neg, \wedge, \vee, \rightarrow$ and $\leftrightarrow$ denote the negation, and, or, implication and iff operators on $\{\mathrm{T}, \mathrm{F}\}$, respectively, which are defined as follows.

| $p$ | $q$ | $p \wedge q$ |
| :---: | :---: | :---: |
| T | T | T |
| T | F | F |
| F | T | F |
| F | F | F |


| $p$ | $q$ | $p \vee q$ |
| :---: | :---: | :---: |
| T | T | T |
| T | F | T |
| F | T | T |
| F | F | F |


| $p$ | $\neg p$ |
| :---: | :---: |
| T | F |
| F | T |


| $p$ | $q$ | $p \rightarrow q$ |
| :---: | :---: | :---: |
| T | T | T |
| T | F | F |
| F | T | T |
| F | F | T |


| $p$ | $q$ | $p \leftrightarrow q$ |
| :---: | :---: | :---: |
| T | T | T |
| T | F | F |
| F | T | F |
| F | F | T |

Let $P V=\left\{p_{1}, p_{2}, \ldots\right\}$ to be a countable set of propositional variables ${ }^{\dagger}$ Sometimes we also write $p, q$, or $q_{1}, q_{2}, \ldots$ to denotes propositional variables. Elements in $P V$ are also called atomic formulas.

Definition 0.7 A well formed formula (wff) is a formula built up inductively as follows.

- Every propositional variable $p \in P V$ is a wff.

[^1]- If $\alpha$ and $\beta$ are wffs, so are $(\neg \alpha),(\alpha \wedge \beta),(\alpha \vee \beta),(\alpha \rightarrow \beta)$ and $(\alpha \leftrightarrow \beta)$.

Usually we will use the term formula to mean wff.
The negation of a propositional variable $p$ is $\neg p$. A literal is either a propositional variable or its negation. A formula is in conjunctive normal form (CNF), if it is of the form:

$$
\left(\ell_{0,0} \vee \cdots \vee \ell_{0, n_{0}}\right) \wedge\left(\ell_{1,0} \vee \cdots \vee \ell_{1, n_{1}}\right) \wedge \cdots \quad\left(\ell_{k, 0} \vee \cdots \vee \ell_{k, n_{k}}\right),
$$

where each $\ell_{i, j}$ is a literal.
A formula is in disjunctive normal form (DNF), if it is of the form:

$$
\left(\ell_{0,0} \wedge \cdots \wedge \ell_{0, n_{0}}\right) \quad \vee \quad\left(\ell_{1,0} \wedge \cdots \wedge \ell_{1, n_{1}}\right) \quad \vee \quad \cdots \quad \vee \quad\left(\ell_{k, 0} \wedge \cdots \wedge \ell_{k, n_{k}}\right) .
$$

An assignment is a function that maps each propositional variable in $P V$ to either T or F . The value of a formula $\alpha$ under an assignment $w$ is defined inductively as follows.

- $w(\alpha)=w(p)$, if $\alpha$ is propositional variable $p$.
- $w(\neg \alpha)=\neg w(\alpha)$.
- $w(\alpha \wedge \beta)=w(\alpha) \wedge w(\beta)$.
- $w(\alpha \vee \beta)=w(\alpha) \vee w(\beta)$.
- $w(\alpha \rightarrow \beta)=w(\alpha) \rightarrow w(\beta)$.
- $w(\alpha \leftrightarrow \beta)=w(\alpha) \leftrightarrow w(\beta)$.


## Definition 0.8

- An assignment $w$ is a satisfying assignment for a formula $\alpha$, denoted by $w \models \alpha$, if $w(\alpha)=\mathrm{T}$. We also say that $w$ is a model of $\alpha$.
- Likewise, $w$ is a satisfying assignment (or, a model) for a set $X$ of formulas, denoted by $w \models X$, if $w \models \alpha$, for every $\alpha \in X$.
- A formula $\alpha$ is satisfiable, if it has a satisfying assignment, and accordingly, a set $X$ of formulas is satisfiable, if it has a satisfying assignment.
- Two formulas $\alpha$ and $\beta$ are equivalent, if for every assignment $w, w(\alpha)=w(\beta)$.

Sometimes we omit the brackets, when they are irrelevant. For example, $\alpha \wedge(\beta \wedge \gamma)$ and $(\alpha \wedge \beta) \wedge \gamma$ are equivalent, so the brackets can be omitted, and written simply as $\alpha \wedge \beta \wedge \gamma$.

Theorem 0.9 (Distributivity law for $\wedge$ and $\vee$ ) For every formulas $\alpha, \beta, \gamma$, the following holds.

- $\alpha \wedge(\beta \vee \gamma)$ and $(\alpha \wedge \beta) \vee(\alpha \wedge \gamma)$ are equivalent.
- $\alpha \vee(\beta \wedge \gamma)$ and $(\alpha \vee \beta) \wedge(\alpha \vee \gamma)$ are equivalent.

A formula $\alpha$ using only atomic formulas $p_{1}, \ldots, p_{n}$ defines a function $f_{\alpha}:\{\mathrm{T}, \mathrm{F}\}^{n} \rightarrow\{\mathrm{~T}, \mathrm{~F}\}$, where for every $\left(v_{1}, \ldots, v_{n}\right) \in\{\mathrm{T}, \mathrm{F}\}^{n}$

$$
f_{\alpha}\left(v_{1}, \ldots, v_{n}\right)=v \quad \text { if and only if }\left\{\begin{array}{l}
\text { under the assignment } w \\
\text { where } w\left(p_{i}\right)=v_{i}, \text { for each } i=1, \ldots, n, \\
w(\alpha)=v .
\end{array}\right.
$$

Definition 0.10 A set $\Gamma$ of operators is complete, if for every integer $n \geqslant 1$, for every function $g:\{\mathrm{T}, \mathrm{F}\}^{n} \rightarrow\{\mathrm{~T}, \mathrm{~F}\}$, there is a formula $\alpha$ using only operators from $\Gamma$ such that $f_{\alpha}=g$.

## Theorem 0.11

(a) For every function $g:\{\mathrm{T}, \mathrm{F}\}^{n} \rightarrow\{\mathrm{~T}, \mathrm{~F}\}$, there is a formula $\alpha$ in DNF such that $f_{\alpha}=g$.
(b) Similarly, for every function $g:\{\mathrm{T}, \mathrm{F}\}^{n} \rightarrow\{\mathrm{~T}, \mathrm{~F}\}$, there is a formula $\alpha$ in CNF such that $f_{\alpha}=g$.

Corollary 0.12 The set $\{\neg, \wedge, \vee\}$ is complete.

## Exercises

(1) Let $\mathbb{R}$ be the set of real numbers. Define a relation $R$, where $(x, y) \in R$ if and only if $x<y$. Prove that $\mathbb{R}$ is a poset w.r.t. $R \overbrace{}^{7}$
(2) Give an example of a bounded chain in the poset $(\mathbb{R}, \leqslant)$ as defined in question 4.
(3) Give an example of an unbounded chain in the poset $(\mathbb{R}, \leqslant)$.
(4) Let $A$ be a set and $\mathcal{F}$ be a collection of subsets of $A$. Define a relation $R$ on elements of $\mathcal{F}$ :

$$
(x, y) \in R \quad \text { if and only if } x \subseteq y
$$

Prove that $\mathcal{F}$ is a poset w.r.t. $R \underbrace{8}$
(5) Give an example of a poset $(\mathcal{F}, \subseteq)$ in which every chain is bounded.
(6) Give an example of a poset $(\mathcal{F}, \subseteq)$ in which there is an unbounded chain.
(7) Consider a poset $(\mathcal{F}, \subseteq)$ where $\mathcal{F}$ is a collection of subsets of a set $A$. Suppose that for every chain $C$ in $\mathcal{F}$, the set $\bigcup C$ is in $\mathcal{F}$.
Assuming Zorn's lemma, prove that there is an element $M \in \mathcal{F}$ such that there is no $X \in \mathcal{F}$ where $M \subsetneq X$.
(8) Write down the equivalent formulas for $x \leftrightarrow y$ in DNF and CNF.
(9) Write down the formulas in DNF and CNF for the following function $f(p, q, r)$ :

| $p$ | $q$ | $r$ | $f(p, q, r)$ |
| :---: | :---: | :---: | :---: |
| F | F | F | F |
| T | F | F | F |
| F | T | F | F |
| T | T | F | T |
| F | F | T | F |
| T | F | T | T |
| F | T | T | T |
| T | T | T | F |

(10) Prove that $\{\neg, \wedge\}$ and $\{\neg, \vee\}$ are complete.

[^2](11) Define the operators NAND and NOR, denoted by $p \bar{\wedge} q$ and $p \underline{\vee} q$, respectively, as follows.

| $p$ | $q$ | $p \bar{\wedge} q$ |
| :---: | :---: | :---: |
| T | T | F |
| T | F | T |
| F | T | T |
| F | F | T |


| $p$ | $q$ | $p \underline{\vee} q$ |
| :---: | :---: | :---: |
| T | T | F |
| T | F | F |
| F | T | F |
| F | F | T |

That is, $p \bar{\wedge} q$ is equivalent to $\neg(p \wedge q)$ and $p \underline{\vee} q$ is equivalent to $\neg(p \vee q)$. Prove that $\{\bar{\wedge}\}$ and $\{\underline{V}\}$ are complete.
(12) Prove part (b) of Theorem 0.11.

## Appendix: Basic set theoretic notations

## Sets:

- A set is a collection of things, which are called its members or elements.
$a \in X$ (read: $a$ is in $X$, or $a$ belongs to $X$ ) means $a$ is a member or an element of $X . a \notin X$ means that $a$ is not a member of $X$.
- An empty set is denoted by $\emptyset$.
- $X$ is a subset of $Y$, denoted by $X \subseteq Y$, if every element of $X$ is also an element of $Y$. $X$ is a proper subset of $Y$, denoted by $X \subsetneq Y$, if $X \neq Y$ and $X \subseteq Y$.
- For two sets $X$ and $Y$, we write $X \cap Y$ and $X \cup Y$ to denote their intersection and union, respectively.
- Let $X$ be a set whose elements are also sets. Then, $\bigcup X$ and $\bigcap X$ denote the following.

$$
\begin{aligned}
& \bigcup X:=\{a \mid a \text { belongs to an element in } X\} \\
& \bigcap X:=\{a \mid a \text { belongs to every element in } X\}
\end{aligned}
$$

- The cartesian product between two sets $X$ and $Y$ is the following.

$$
X \times Y:=\{(a, b) \mid a \in X \text { and } b \in Y\}
$$

We write $X^{n}$ to denote $X \times \cdots \times X(X$ appears $n$ times $)$.

## Relations:

- A relation $R$ over two sets $X, Y$ is a subset of $X \times Y$.
- A binary relation $R$ over $X$ is a subset of $X \times X$.
- An $n$-ary relation $R$ over $X$ is a subset of $X^{n}$.


## Functions:

- A relation $R$ over $X, Y$ is a function or a mapping, if for every $x \in X$, there is exactly one $y \in Y$ such that $(x, y) \in R$.
In this case, we will say $R$ is a function from $X$ to $Y$, or $R$ maps $X$ to $Y$. We denote it by $R: X \rightarrow Y$.
- We will usually use the letters $f, g, h, \ldots$ to represent functions. As usual, we write $f(x)$ to denote the element $y$ in which $(x, y) \in f$.
- A function $f: X \rightarrow Y$ is an injective function, if for every $y \in Y$, there is at most one $x \in X$ such that $f(x)=y$. An injective functions is also called an injection.
- A function $f: X \rightarrow Y$ is a surjective function, if for every $y \in Y$, there is at least one $x \in X$ such that $f(x)=y$.
- A function $f: X \rightarrow Y$ is a bijection, if it is both injective and surjective.


## Lesson 1: Compactness theorem for propositional calculus

Theme: Logical consequences, compactness theorem and its applications.

## 1 Logical consequences

Definition 1.1 A formula $\alpha$ is a logical consequence of a formula $\beta$, denoted by $\beta \models \alpha$, if every satisfying assignment of $\beta$ is also a satisfying assignment of $\alpha$. If $\alpha \models \beta$ and $\beta \models \alpha$, we write $\alpha==\mid$.

Definition 1.2 We say that $\alpha$ is a logical consequence of a set $X$ of formulas, denoted by $X \models \alpha$, if every satisfying assignment of $X$ is also a satisfying assignment of $\alpha$.

We write $X \not \models \alpha$, if it is not the case that $X \models \alpha$.
Theorem 1.3 $X \models \alpha$ if and only if $X \cup\{\neg \alpha\}$ is not satisfiable.

## 2 Compactness theorem

We say that a set $X$ is finitely satisfiable, if every finite subset of $X$ is satisfiable.
Lemma 1.4 Suppose $X$ is finitely satisfiable. Then, for every formula $\alpha$, at least one of $X \cup\{\alpha\}$ or $X \cup\{\neg \alpha\}$ is finitely satisfiable.

Theorem 1.5 (Compactness theorem for countable set) $A$ set $X$ is satisfiable if and only if it is finitely satisfiable.

Proof. The "only if" direction is trivial. We show the "if" direction. Suppose $X$ is finitely satisfiable. Let $\alpha_{1}, \alpha_{2}, \ldots$ be an enumeration of all possible formulas. For every integer $i \geqslant 0$, we define a set $\Delta_{i}$ as follows.

$$
\begin{aligned}
\Delta_{0} & :=X \\
\Delta_{i} & := \begin{cases}\Delta_{i-1} \cup\left\{\alpha_{i}\right\}, & \text { if } \Delta_{i-1} \cup\left\{\alpha_{i}\right\} \text { is finitely satisfiable } \\
\Delta_{i-1} \cup\left\{\neg \alpha_{i}\right\}, & \text { otherwise }\end{cases}
\end{aligned}
$$

Let $\Delta:=\bigcup_{i \geqslant 0} \Delta_{i}$.
Claim 1 The set $\Delta$ is finitely satisfiable.
Consider the following assignment $w$, where for each atomic formula $p$,

$$
w(p):= \begin{cases}\mathrm{T}, & \text { if } p \in \Delta \\ \mathrm{~F}, & \text { if } \neg p \in \Delta\end{cases}
$$

Claim 2 The assignment $w$ is a satisfying assignment for $\Delta$. That is, $w \models \Delta$.
Since $X \subseteq \Delta, w$ is also a satisfying assignment of $X$. Hence, $X$ is satisfiable. This completes our proof.

## 3 Two applications of compactness theorem

### 3.1 Four-colorability of (infinite) planar graphs

An (undirected) graph $G$ is a pair ( $V, E$ ) with $E$ being a symmetrical binary relation on $V$. That is, $E \subseteq V \times V$, where $(u, v) \in E$ if and only if $(v, u) \in E$. The elements of $V$ are called vertices, and the elements of $E$ are called edges. A subgraph $G^{\prime}$ of $G$ is a graph ( $V^{\prime}, E^{\prime}$ ), where $V \subseteq V^{\prime}$ and $E \subseteq E^{\prime}$.

A graph $G=(V, E)$ is 4-colorable, if there is a function $\xi: V \rightarrow\{1,2,3,4\}$ such that whenever $(u, v) \in E, \xi(u) \neq \xi(v)$.

Lemma 1.6 Let $G$ be a graph. Then, $G$ is 4 -colorable, if and only if every finite subgraph of $G$ is 4-colorable.

Proof. (Sketch) The "only if" direction is trivial. The proof of the "if" direction is as follows. Let $G=(V, E)$.

For each $a \in V$, we have four atomic formulas $p_{a, 1}, p_{a, 2}, p_{a, 3}, p_{a, 4}$. Define the set $X_{G}$ that contains the following formulas for each $a \in V$ :

$$
\begin{aligned}
& p_{a, 1} \vee p_{a, 2} \vee p_{a, 3} \vee p_{a, 4} \\
& \bigwedge_{1 \leqslant i<j \leqslant 4} \neg\left(p_{a, i} \wedge p_{a, j}\right) \\
& \bigwedge_{1 \leqslant i \leqslant 4} \neg\left(p_{a, i} \wedge p_{b, i}\right) \quad \text { where }(a, b) \in E
\end{aligned}
$$

Then, $G$ is 4-colorable if and only if $X_{G}$ is satisfiable. Since every finite subgraph $G^{\prime}$ of $G$ is 4-colorable, $X_{G^{\prime}}$ is satisfiable, for every finite subgraph $G^{\prime}$ of $G$. This means $X_{G}$ is finitely satisfiable (why?). By Theorem $1.5, G$ is 4 -colorable.

Theorem 1.7 below is a well known result whose proof we will not discuss in the class.
Theorem 1.7 (Four color theorem) Every finite planar graph is 4 -colorable 用 $^{2}$
Corollary 1.8 Every (finite or infinite) planar graph is 4-colorable.

### 3.2 The marriage problem

Let $R$ be a relation over $X, Y$. For an element $a \in X$, we define $R(a)=\{b \in Y \mid(a, b) \in R\}$. Likewise, for a subset $X_{0} \subseteq X, R\left(X_{0}\right)=\left\{b \in Y \mid\right.$ there is $a \in X_{0}$ such that $\left.(a, b) \in R\right\}$.

Theorem 1.9 below is a standard result in discrete mathematics, and we will not discuss its proof in the class.

Theorem 1.9 (Hall's marriage theorem) For a relation $R$ over $X, Y$, where $X$ is finite, the following are equivalent.

- $R$ contains an injective function $f$, i.e., there is a function $f \subseteq R$ such that $f$ is injective.
- For every subset $X_{0} \subseteq X,\left|X_{0}\right| \leqslant\left|R\left(X_{0}\right)\right|$.

Theorem 1.10 For a relation $R$ over $X, Y$, where $X$ is infinite and for every $a \in X,|R(a)|$ is finite, the following are equivalent.

[^3]- $R$ contains an injective function $f$, i.e., there is a function $f \subseteq R$ such that $f$ is injective.
- For every finite subset $X_{0} \subseteq X,\left|X_{0}\right| \leqslant\left|R\left(X_{0}\right)\right|$.

Proof. (Sketch) The implication from the first to the second item is immediate. The proof for the other direction is almost the same as in Lemma 1.6. Let $R$ be a relation over $X, Y$, where for every $a \in X,|R(a)|$ is finite.

For each $a \in X$, we have atomic formulas $p_{a, b_{1}}, p_{a, b_{2}}, \ldots, p_{a, b_{n}}$, where $R(a)=\left\{b_{1}, \ldots, b_{n}\right\}$. Define the set $X_{R}$ that contains the following formulas for each $a \in X$ :

$$
\begin{aligned}
& \bigvee_{b \in R(a)} p_{a, b} \\
& \neg\left(p_{a, b} \wedge p_{a, c}\right), \quad \text { where } b \neq c
\end{aligned}
$$

$R$ has the desired injection if and only if $X_{R}$ is satisfiable. Using Theorems 1.9 and 1.5, the proof can proceed in a similar manner as in Lemma 1.6.

## Exercises

(0) Is Lemma 1.4 still correct if we allow the set $P V$ of propositional variables to be uncountable?

Our proof for the compactness theorem in the lecture depends on the fact that there are only countably many formulas. If there are uncountably many propositional variables, there are uncountably many formulas, and our proof is no longer valid. Here we are going to present a proof that still holds for uncountably many formulas, i.e., $X$ is satisfiable if and only if $X$ is finitely satisfiable, where $P V$ can be an uncountable set.

As usual, the "only if" part is trivial. The proof for the "if" part is as follows. Let $X$ be finitely satisfiable. Define the collection $\mathcal{F}$ of sets of formulas as follows.

$$
Y \in \mathcal{F} \text { if and only if } X \subseteq Y \text { and } Y \text { is finitely satisfiable. }
$$

(1) Prove that $(\mathcal{F}, \subseteq)$ is a poset.
(2) Let $K$ be a chain in $(\mathcal{F}, \subseteq)$. Prove that $\bigcup K$ is finitely satisfiable.
(3) Prove that there is a maximal set $M \in \mathcal{F}$, i.e., $M$ is a set in $\mathcal{F}$ such that there is no $Y \in \mathcal{F}$ where $M \subsetneq Y$.
Hint: Use Zorn's lemma stated in Lesson 1.
(4) Prove that for every $p \in P V$, either $p$ or $\neg p$ is in $M$.
(5) Prove that $M$ is satisfiable, and hence, so is $X$.

## Lesson 2: Proof system in propositional calculus

Theme: The notion of provability in propositional calculus.

## 1 Proofs in propositional calculus

Let $X$ be a set of formulas and $\alpha$ be a formula. We say that $\alpha$ is provable/derivable from $X$, denoted by $X \vdash \alpha$, if it can be obtained inductively according to the following rules.

$$
\begin{array}{ll}
\text { Initial Segment (IS): } & \alpha \vdash \alpha \\
\text { Monotonicity Rule (MR): } & \frac{X \vdash \alpha}{Y \vdash \alpha} \quad \text { for every } Y \supseteq X \\
\text { And Combine Rule (ACR): } & \frac{X \vdash \alpha \text { and } X \vdash \beta}{X \vdash \alpha \wedge \beta} \\
\text { And Split Rule (ASR): } & \frac{X \vdash \alpha \text { and } X \vdash \beta}{X \vdash \beta} \\
\text { Contradiction Rule (CR): } & \frac{X \vdash \alpha \quad \text { and } X \vdash \neg \alpha}{X \vdash \beta} \\
\text { Negation Rule (NR): } & \frac{X, \alpha \vdash \beta \text { and } X, \neg \alpha \vdash \beta}{X \vdash \beta}
\end{array}
$$

Sometimes we will also say " $\alpha$ can be proved from $X$ " when $X \vdash \alpha$. We write $X \nvdash \alpha$, if it is not the case that $X \vdash \alpha$.

Remark 2.1 To avoid clutter, we write $\alpha \vdash \alpha$ to denote $\{\alpha\} \vdash \alpha$, whereas $X, \alpha \vdash \beta$ means $X \cup\{\alpha\} \vdash \beta$. We also write $\left\{\alpha_{1}, \ldots, \alpha_{n}\right\} \vdash \alpha$ to denote $\alpha_{1}, \ldots, \alpha_{n} \vdash \alpha$ and $\vdash \alpha$ to denote $\emptyset \vdash \alpha$.

Remark 2.2 Note that in the proof system above, we only use the operators $\neg$ and $\wedge$. In the following a formula $\alpha \rightarrow \beta$ is to be interpreted as an abbreviation for $\neg(\alpha \wedge \neg \beta)$, and likewise, $\alpha \vee \beta$ for $\neg(\neg \alpha \wedge \neg \beta)$.

Example 2.3 (Elimination of Negation) $\frac{X, \neg \alpha \vdash \alpha}{X \vdash \alpha}$

1. $X, \neg \alpha \vdash \alpha$.
(Supposition)
2. $X, \alpha \vdash \alpha$.
(Initial Segment and Monotonicity Rule)
3. $X \vdash \alpha$.
(Negation Rule on 1 and 2)

Example 2.4 (Reductio ad Absurdum) $\frac{X, \neg \alpha \vdash \beta \text { and } \quad X, \neg \alpha \vdash \neg \beta}{X \vdash \alpha}$

1. $X, \neg \alpha \vdash \beta$.
(Supposition)
2. $X, \neg \alpha \vdash \neg \beta$.
(Supposition)
3. $X, \neg \alpha \vdash \alpha$.
(Contradiction Rule on 1 and 2)
4. $X, \alpha \vdash \alpha$.
(Initial Segment and Monotonicity Rule)
5. $X \vdash \alpha$.
(Negation Rule on 3 and 4)
Example 2.5 (Cut Rule) $\frac{X \vdash \alpha \text { and } \quad X, \alpha \vdash \beta}{X \vdash \beta}$
6. $X \vdash \alpha$.
(Supposition)
7. $X, \alpha \vdash \beta$.
(Supposition)
8. $X, \neg \alpha \vdash \neg \alpha$.
(Initial Segment and Monotonicity Rule)
9. $X, \neg \alpha \vdash \alpha$.
10. $X, \neg \alpha \vdash \beta$.
11. $X \vdash \beta$.
(Monotonicity Rule on 1)
(Contradiction Rule on 3 and (4)
(Negation Rule on 2 and 5)
Example 2.6 (Elimination of $\rightarrow$ ) $\frac{X \vdash \alpha \rightarrow \beta}{X, \alpha \vdash \beta}$
12. $X \vdash \alpha \rightarrow \beta$.
(Supposition)
13. $X, \alpha, \neg \beta \vdash \alpha$.
(Initial Segment and Monotonicity Rule)
14. $X, \alpha, \neg \beta \vdash \neg \beta$.
15. $X, \alpha, \neg \beta \vdash \alpha \wedge \neg \beta$.
16. $X, \alpha, \neg \beta \vdash \neg(\alpha \wedge \neg \beta)$.
17. $X, \alpha, \neg \beta \vdash \beta$.
(Initial Segment and Monotonicity Rule)
(And Combine Rule on 2 and 3)
(Monotonicity Rule on (1)
18. $X, \alpha, \beta \vdash \beta$.
(Contradiction Rule on 4 and 5)
19. $X, \alpha \vdash \beta$.
(Initial Segment and Monotonicity Rule)
(Negation Rule on 6 and 7)
Example 2.7 (Introduction of $\rightarrow$ ) $\frac{X, \alpha \vdash \beta}{X \vdash \alpha \rightarrow \beta}$
20. $X, \alpha \vdash \beta$.
(Supposition)
21. $X, \alpha, \alpha \wedge \neg \beta \vdash \beta$.
(Monotonicity Rule on 1)
22. $X, \alpha \wedge \neg \beta \vdash \alpha \wedge \neg \beta$.
(Initial Segment and Monotonicity Rule)
23. $X, \alpha \wedge \neg \beta \vdash \alpha$.
24. $X, \alpha \wedge \neg \beta \vdash \beta$.
25. $X, \alpha \wedge \neg \beta \vdash \neg \beta$.
26. $X \vdash \alpha \rightarrow \beta$.
(And Split Rule on (3)
(Cut rule on 4 and 2)
(And Split Rule on 3)
(Reductio ad Absurdum on 5 and 6)

Theorem 2.8 (Finiteness theorem for $\vdash$ ) If $X \vdash \alpha$, then there is a finite set $X_{0} \subseteq X$ such that $X_{0} \vdash \alpha$.

## Exercises

(1) Prove that $\frac{X, \alpha \vdash \neg \alpha}{X \vdash \neg \alpha}$.
(2) Prove that $\frac{X \vdash \alpha \text { and } \quad X \vdash \alpha \rightarrow \beta}{X \vdash \beta}$.
(3) Prove that $\frac{X \vdash \alpha \rightarrow \beta \text { and } X \vdash \beta \rightarrow \gamma}{X \vdash \alpha \rightarrow \gamma}$.
(4) Prove that $\frac{X \vdash \neg \neg \alpha}{X \vdash \alpha}$.
(5) Prove that $\frac{X \vdash \alpha}{X \vdash \neg \neg \alpha}$.
(6) Prove that $\frac{X, \alpha \vdash \beta}{X, \neg \neg \alpha \vdash \beta}$.
(7) Prove that $\frac{X \vdash \alpha \rightarrow \beta}{X \vdash \neg \beta \rightarrow \neg \alpha}$.

Note that $\alpha \rightarrow \beta$ is an abbreviation for $\neg(\alpha \wedge \neg \beta)$, whereas $\neg \beta \rightarrow \neg \alpha$ for $\neg(\neg \beta \wedge \neg \neg \alpha)$.

## Lesson 3: Completeness of propositional calculus

Theme: The equivalence between provability and logical consequences (completeness of propositional calculus).

Definition 3.1 A set $X$ is inconsistent, if there is $\alpha$ such that $X \vdash \alpha$ and $X \vdash \neg \alpha$. Otherwise, we say that $X$ is consistent.

Lemma 3.2 For every set $X$ of formulas and for every formula $\alpha$, the following holds.
(a) $X \vdash \alpha$ if and only if $X \cup\{\neg \alpha\}$ is inconsistent.
(b) $X \vdash \neg \alpha$ if and only if $X \cup\{\alpha\}$ is inconsistent.

Definition 3.3 A set $X$ is maximally consistent, if it is consistent and for every $Y \supsetneq X, Y$ is inconsistent.

Lemma 3.4 Every consistent set $X$ can be extended to a maximally consistent set. That is, for every consistent set $X$, there is a maximally consistent set $Y$ such that $Y \supseteq X$.

Lemma 3.5 A maximally consistent set $X$ has the following property: For every $\alpha$,

$$
X \vdash \neg \alpha \text { if and only if } X \nvdash \alpha
$$

Lemma 3.6 A maximally consistent set $X$ is satisfiable.
Proof. (Sketch) Define the following assignment $w$, where for every atomic proposition $p$ :

$$
w(p):= \begin{cases}\mathrm{T}, & \text { if } X \vdash p \\ \mathrm{~F}, & \text { if } X \vdash \neg p\end{cases}
$$

We have to show that for every $\alpha \in X, w(\alpha)=\mathrm{T}$. It is sufficient to show the following.

$$
X \vdash \alpha \text { if and only if } w(\alpha)=\mathrm{T}
$$

The proof is by induction on $\alpha$.

Theorem 3.7 (Completeness of propositional calculus) $X \vdash \alpha$ if and only if $X \models \alpha$.
Proof. The "only if" direction is straightforward. We prove the "if" direction by showing that $X \nvdash \alpha$ implies $X \not \models \alpha$.

Suppose $X \nvdash \alpha$. This means that $X \cup\{\neg \alpha\}$ is consistent. By Lemma 3.4, we can extend it to a maximally consistent set $Y$. Lemma 3.6 implies $Y$ is satisfiable, and hence, $X \cup\{\neg \alpha\}$ is also satisfiable, which further implies that $X \not \vDash \alpha$ (why?). This completes our proof.

There are six rules in our proof system. Where do we use each of them in our proof of completeness theorem?

## Lesson 4: First-order logic, part 1

Theme: Mathematical structures and the syntax of first-order logic.

For the rest of this course, we fix three pairwise disjoint sets $L_{r}, L_{f}, L_{c}$ of symbols.

- Elements in $L_{r}$ are called relational symbols. Each symbol $R \in L_{r}$ is associated with a positive integer, which is called its arity and denoted by $\operatorname{ar}(R)$.
- Elements in $L_{f}$ are called operation/function symbols. Each symbol $f \in L_{f}$ is associated with a positive integer, which is called its arity and denoted by $\operatorname{ar}(f)$.
- Elements in $L_{c}$ are called constant symbols.

We usually write $R_{1}, R_{2}, \ldots$ for the elements of $L_{r} ; f_{1}, f_{2}, \ldots$ for the elements of $L_{f} ;$ and $c_{1}, c_{2}, \ldots$ for the elements of $L_{c}$.

## 1 Mathematical structures

Definition 4.1 Let $L=\left\{R_{1}, \ldots, R_{m}, f_{1}, \ldots, f_{n}, c_{1}, \ldots, c_{k}\right\}$ be a finite subset of $L_{r} \cup L_{f} \cup L_{c}$. An $L$-structure is $\mathcal{A}=\left(A, R_{1}^{\mathcal{A}}, \ldots, R_{m}^{\mathcal{A}}, f_{1}^{\mathcal{A}}, \ldots, f_{n}^{\mathcal{A}}, c_{1}^{\mathcal{A}}, \ldots, c_{k}^{\mathcal{A}}\right)$, where

- $A$ is a set of elements, called the domain, or the universe of $\mathcal{A}$;
- each $R_{i}^{\mathcal{A}}$ is a relation over $A$ of arity $\operatorname{ar}\left(R_{i}\right)$, i.e., $R_{i}^{\mathcal{A}} \subseteq A^{\operatorname{ar}\left(R_{i}\right)}$;
- each $f_{i}^{\mathcal{A}}$ is a function over $A$ of arity $\operatorname{ar}\left(f_{i}\right)$, i.e., $f: A^{\operatorname{ar}\left(f_{i}\right)} \rightarrow A$;
- each $c_{i}^{\mathcal{A}}$ is an element of $A$.

The set $L$ is called the signature/vocabulary of $\mathcal{A}$. If $A$ is finite, then $\mathcal{A}$ is called a finite structure. Otherwise, it is an infinite structure.

The superscripts $\mathcal{A}$ in $R_{i}^{\mathcal{A}}, f_{i}^{\mathcal{A}}, c_{i}^{\mathcal{A}}$ are to indicate that we are talking about $R_{i}, f_{i}, c_{i}$ in the structure $\mathcal{A}$. When $\mathcal{A}$ is clear from the context, we will usually omit the superscript, and write only $\mathcal{A}=\left(A, R_{1}, \ldots, R_{m}, f_{1}, \ldots, f_{n}, c_{1}, \ldots, c_{k}\right)$. We will usually write $\bar{a}$ to denote $\bar{a}=\left(a_{1}, \ldots, a_{n}\right)$ for some appropriate $n$. For example, we will simply write $\bar{a} \in R$, where we assume that $\bar{a}=\left(a_{1}, \ldots, a_{l}\right)$ and $l$ is the arity of $R$. Likewise, we write $f(\bar{a})$ assuming that $\bar{a}$ is of length $\operatorname{ar}(f)$. We will also write $R(\bar{a})$ to mean $\bar{a} \in R$.

Remark 4.2 Usually structures are denoted by calligraphic fonts $\mathcal{A}, \mathcal{B}, \ldots$, and their domains by the standard Roman letters $A, B, \ldots$

Remark 4.3 In definition 4.1 above, a structure is defined over a finite vocabulary, and that is usually the case. Sometimes though a structure can be defined over an infinite vocabulary, or even uncountably infinite vocabulary.

Definition 4.4 Let $\mathcal{A}$ and $\mathcal{B}$ be two structures over the same vocabulary $L$. The structure $\mathcal{A}$ is called a substructure of $\mathcal{B}$, if the following holds.

- $A \subseteq B$.
- $c^{\mathcal{A}}=c^{\mathcal{B}}$, for every constant symbol $c \in L$.
- $R^{\mathcal{A}}=A^{\operatorname{ar}(R)} \cap R^{\mathcal{B}}$, for every relation symbol $R \in L$.
- $f^{\mathcal{A}}=A^{\operatorname{ar}(f)+1} \cap f^{\mathcal{B}}$, for every function symbol $f \in L$.

The structure $\mathcal{B}$ is called an extension of $\mathcal{A}$.

## Definition 4.5

- A relational structure is an $L$-structure, where $L \subseteq L_{r}$, i.e., without any function or constant.
- An algebraic structure, or in short, an algebra, is an $L$-structure, where $L \subseteq L_{f} \cup L_{c}$, i.e., without any relation.

Example 4.6 Some instances of infinite structures.

- $\mathcal{N}_{0}=(\mathbb{N}, \leqslant)$.
- $\mathcal{R}_{0}=(\mathbb{R}, \leqslant)$.
- $\mathcal{N}_{1}=(\mathbb{N}, 0,+)$.
- $\mathcal{R}_{1}=(\mathbb{R}, 0,+)$.
- $\mathcal{N}_{2}=(\mathbb{N}, 0,1,+, \times)$.
- $\mathcal{R}_{2}=(\mathbb{R}, 0,1,+, \times)$.
- $\mathcal{N}_{3}=(\mathbb{N}, 0,1,+, \times, \leqslant)$.
- $\mathcal{R}_{3}=(\mathbb{R}, 0,1,+, \times, \leqslant)$.

Example 4.7 Some instances of finite structures.

- $\mathcal{Z}_{m}=\left(\mathbb{Z}_{m}, 0,+_{\bmod m}\right)$, where $+\bmod m$ is addition modulo $m$.
- $\mathcal{Z}_{p}^{*}=\left(\mathbb{Z}_{p}, 0,1,+\bmod p, \times \bmod p\right)$, for a prime number $p$, where $\times \bmod p$ is multiplication modulo $p$.
- $\mathcal{B}=(\{\mathrm{T}, \mathrm{F}\}, \wedge, \vee, \rightarrow, \leftrightarrow, \neg)$.

Example 4.8 A graph is a structure $\mathcal{A}=(A, E)$, where $E \subseteq A \times A$. It is usually written as $G=(V, E)$.

Definition 4.9 Let $\mathcal{A}, \mathcal{B}$ be $L$-structures. A homomorphism $h$ from $\mathcal{A}$ to $\mathcal{B}$, denoted by $h: \mathcal{A} \rightarrow$ $\mathcal{B}$, is a function $h: A \rightarrow B$ such that for every $R, f, c \in L$,

- $h\left(f^{\mathcal{A}}(\bar{a})\right)=f^{\mathcal{B}}(h(\bar{a}))$, for every $\bar{a} \in A^{\operatorname{ar}(f)}$,
- $h\left(c^{\mathcal{A}}\right)=c^{\mathcal{B}}$,
- for every $\bar{a} \in A^{\operatorname{ar}(R)}$, if $R^{\mathcal{A}}(\bar{a})$, then $R^{\mathcal{B}}(h(\bar{a}))$.

Here, $h(\bar{a})=\left(h\left(a_{1}\right), \ldots, h\left(a_{l}\right)\right)$, where $\bar{a}=\left(a_{1}, \ldots, a_{l}\right)$.

Definition 4.10 Let $h: \mathcal{A} \rightarrow \mathcal{B}$ be a homomorphism.

- $h$ is a strong homomorphism, if $h$ is a homomorphism and in addition, for every relation $R \in L$, for every $\bar{a} \in A^{\operatorname{ar}(R)}$,
if $R^{\mathcal{B}}(h(\bar{a}))$, then there is $\bar{a}^{\prime} \in A^{\operatorname{ar}(R)}$ such that $h(\bar{a})=h\left(\bar{a}^{\prime}\right)$ and $R^{\mathcal{A}}\left(\bar{a}^{\prime}\right)$.
- $h$ is an embedding, if it is an injective and strong homomorphism.
- $h$ is an isomorphism, if it is a strong and bijective homomorphism.
- $h$ is called automorphism, if $h$ is an isomorphism and $\mathcal{B}=\mathcal{A}$, i.e., $h$ is a bijection from $A$ to $A$ itself.


## 2 The syntax of first-order logic

### 2.1 Variables and terms

We reserve a set VAR of first-order variables. We usually write $x_{1}, x_{2}, \ldots, y_{1}, y_{2}, \ldots, z_{1}, z_{2}, \ldots$ to denote elements in VAR. When it is clear from the context, we will simply say variables, instead of first-order variables.

In the following let $L$ be a finite subset of $L_{r} \cup L_{f} \cup L_{c}$. Terms over $L$, or, $L$-terms, are defined inductively as follows.

- A variable $x \in \mathrm{VAR}$ is an $L$-term.
- A constant symbol $c \in L$ is an $L$-term.
- If $f \in L$ is a function symbol of arity $n$, and $t_{1}, \ldots, t_{n}$ are $L$-terms, then $f\left(t_{1}, \ldots, t_{n}\right)$ is an $L$-term.

The variable $x$ and the constant $c$ are called atomic $L$-terms. The set of all $L$-terms is denoted by $\operatorname{Term}(L)$. When there is no confusion, we will omit $L$, and simply write terms, instead of $L$-terms.

The set of variables used in a term $t$ is the set $\operatorname{var}(t)$ defined as follows.

- For a constant symbol $c \in L, \operatorname{var}(c)=\emptyset$.
- For a variable $x \in \operatorname{VAR}, \operatorname{var}(x)=\{x\}$.
- For a term of the form $f\left(t_{1}, \ldots, t_{n}\right)$, $\operatorname{var}\left(f\left(t_{1}, \ldots, t_{n}\right)\right)=\operatorname{var}\left(t_{1}\right) \cup \cdots \cup \operatorname{var}\left(t_{n}\right)$.


### 2.2 First-order formulas

First-order (FO) formulas over the signature/vocabulary $L$ are defined inductively as follows.

- If $s$ and $t$ are terms over $L$, then $(s \approx t)$ is an FO formula over $L$.
- If $t_{1}, \ldots, t_{n}$ are terms over $L$, and $R \in L$ is a relation symbol of arity $n$, then $R\left(t_{1}, \ldots, t_{n}\right)$ is an FO formula over $L$.
- If $\alpha$ and $\beta$ are FO formulas over $L$, then so are $\neg \alpha, \alpha \wedge \beta$ and $\alpha \vee \beta$.
- If $\alpha$ is an FO formula over $L$, and $x \in \mathrm{VAR}$, then $\forall x(\alpha)$ is also an FO formula over $L$.
- If $\alpha$ is an FO formula over $L$, and $x \in \operatorname{VAR}$, then $\exists x(\alpha)$ is also an FO formula over $L$.

FO formulas of the form $s \approx t$ and $R\left(t_{1}, \ldots, t_{n}\right)$ are called atomic FO formulas. The set of all FO formulas over $L$ is denoted by $\mathrm{FO}[L]$. We will write $s \not \approx t$ as an abbreviation for $\neg(s \approx t)$.

To avoid clutter, we will usually write only formulas to mean FO formulas. When the signature $L$ is clear, we will also omit mentioning it. So the word formula means an FO formula over some signature $L$ which can be derived from the context.

The quantifier rank of a formula $\alpha$, denoted by $\operatorname{qr}(\alpha)$, is defined inductively as follows.

- The quantifier rank of an atomic formula is zero.
- $\operatorname{qr}(\neg \beta)=\operatorname{qr}(\beta)$.
- $\operatorname{qr}(\beta \wedge \gamma)=\operatorname{qr}(\beta \vee \gamma)=\max (\operatorname{qr}(\beta), \operatorname{qr}(\gamma))$.
- $\operatorname{qr}(\forall x \beta)=\operatorname{qr}(\exists x \beta)=\operatorname{qr}(\beta)+1$.

The set of free variables of a formula $\alpha$, denoted by free $(\alpha)$, is defined inductively as follows.

- If $\alpha$ is an atomic formula $s \approx t$, then free $(\alpha)=\operatorname{var}(s) \cup \operatorname{var}(t)$.
- If $\alpha$ is an atomic formula $R\left(t_{1}, \ldots, t_{n}\right)$, then $\operatorname{free}(\alpha)=\operatorname{var}\left(t_{1}\right) \cup \cdots \cup \operatorname{var}\left(t_{n}\right)$.
- $\operatorname{free}(\neg \beta)=\operatorname{free}(\beta)$.
- $\operatorname{free}(\beta \wedge \gamma)=\operatorname{free}(\beta \vee \gamma)=\operatorname{free}(\beta) \cup \operatorname{free}(\gamma)$.
- $\operatorname{free}(\forall x \beta)=\operatorname{free}(\exists x \beta)=\operatorname{free}(\beta)-\{x\}$.

Formulas without free variables are called sentences, or closed formulas. Otherwise, they are called open formulas. A formula without any quantifier is called a quantifier free formula.

Sometimes, we will write $\varphi\left(x_{1}, \ldots, x_{n}\right)$ to indicate that the free variables in $\varphi$ are $x_{1}, \ldots, x_{n}$. When $n$ is unspecified, we write $\varphi(\bar{x})$. For formula of the form $\forall x \beta$, we say that $x$ is a bound variable in $\forall x \beta$. Likewise, we say that $x$ is a bound variable in $\exists x \beta$. In both cases, we say that $\beta$ is the scope of $x$, and that $x$ is bounded by a quantifier.

### 2.3 Substitutions

Simple substitutions. Let $t$ be a term and $x$ a variable. Let $s$ be a term. The term $t[s / x]$ is the term obtained by substituting $s$ to the variable $x$ in $t$. Formally, it is defined inductively as follows.

- $x[s / x]=s$ and $y[s / x]=y$, if $y \neq x$.
- $c[s / x]=c$, where $c$ is a constant symbol.
- $f\left(t_{1}, \ldots, t_{n}\right)[s / x]=f\left(t_{1}[s / x], \ldots, t_{n}[s / x]\right)$, where $f$ is a function symbol of arity $n$.

The formula $\alpha[s / x]$ is the formula obtained by substituting the free variable $x$ in $\alpha$ with the term $s$. Formally, it is defined inductively as follows.

- $\left(t_{1} \approx t_{2}\right)[s / x]=\left(t_{1}[s / x] \approx t_{2}[s / x]\right)$.
- $R\left(t_{1}, \ldots, t_{n}\right)[s / x]=R\left(t_{1}[s / x], \ldots, t_{n}[s / x]\right)$.
- $(\neg \alpha)[s / x]=\neg(\alpha[s / x])$.
- $(\alpha \wedge \beta)[s / x]=\alpha[s / x] \wedge \beta[s / x]$.
- $(\alpha \vee \beta)[s / x]=\alpha[s / x] \vee \beta[s / x]$.
- $(\forall y \alpha)[s / x]=\left\{\begin{array}{ll}\forall y \alpha[s / x] & \text { if } y \neq x \\ \forall y \alpha & \text { if } y=x\end{array}\right.$.
- $(\exists y \alpha)[s / x]=\left\{\begin{array}{ll}\exists y \alpha[s / x] & \text { if } y \neq x \\ \exists y \alpha & \text { if } y=x\end{array}\right.$.

Collision-free substitution. A substitution $s / x$ is collision-free in a formula $\alpha$, if the following holds.

- $s / x$ is collision-free in the atomic formulas $t_{1} \approx t_{2}$ and $R\left(t_{1}, \ldots, t_{n}\right)$.
- $s / x$ is collision-free in $\neg \alpha$ if and only if it is collision-free in $\alpha$.
- $s / x$ is collision-free in $\alpha \wedge \beta$ if and only if it is collision-free in both $\alpha$ and $\beta$. Likewise, it is collision free in $\alpha \vee \beta$ if and only if it is collision-free in both $\alpha$ and $\beta$.
- $s / x$ is collision-free in $\forall y \alpha$ if and only if $y \notin \operatorname{var}(s)$ and it is collision-free in $\alpha$.

Likewise, $s / x$ is collision-free in $\exists y \alpha$ if and only if $y \notin \operatorname{var}(s)$ and it is collision-free in $\alpha$.
Simultaneous substitutions. For a formula $\alpha\left(x_{1}, \ldots, x_{n}\right)$ and terms $\bar{t}=\left(t_{1}, \ldots, t_{n}\right), \alpha[\bar{t} / \bar{x}]$ denotes a substitution in which each $x_{i}$ is substituted with $t_{i}$. Such a substitution $\alpha[\bar{t} / \bar{x}]$ is called a simultaneous substitution. It is collision-free, if each $t_{i} / x_{i}$ is collision-free.

## Lesson 5: First-order logic, part 2

Theme: The semantics of first-order logic.

## 1 Valuations

Recall that VAR is a set of variables. Let $\mathcal{A}$ be a structure.

- A valuation in a structure $\mathcal{A}$ is a function val : VAR $\rightarrow A$.
- For $\bar{a}=\left(a_{1}, \ldots, a_{n}\right)$, where each $a_{i} \in A$, and $\bar{x}=\left(x_{1}, \ldots, x_{n}\right)$, where $x_{1}, \ldots, x_{n}$ are all different variables, we write $\operatorname{val}[\bar{x} \mapsto \bar{a}]$ to denote the valuation $\mathrm{val}^{\prime}$, where for every $y \in \mathrm{VAR}$,

$$
\operatorname{val}^{\prime}(y)= \begin{cases}\operatorname{val}(y), & \text { if } y \notin\left\{x_{1}, \ldots, x_{n}\right\} \\ a_{i}, & \text { if } y=x_{i}\end{cases}
$$

Sometimes we write $[\bar{x} \mapsto \bar{a}]$ to denote a valuation val such that $\operatorname{val}\left(x_{i}\right)=a_{i}$.

## 2 Interpretations/models

An interpretation is a pair $(\mathcal{A}, \mathrm{val})$, where $\mathcal{A}$ is a structure and val is a valuation. Quite often, interpretations are also called models.

In an interpretation $(\mathcal{A}, \mathrm{val})$, each term $t$ is associated with an element $t^{\mathcal{A}}[\mathrm{val}]$ defined inductively as follows.

- $x^{\mathcal{A}}[\mathrm{val}]=\operatorname{val}(x)$, where $x \in \operatorname{VAR}$.
- $c^{\mathcal{A}}[\mathrm{val}]=c^{\mathcal{A}}$, where $c$ is a constant symbol.
- $f\left(t_{1}, \ldots, t_{n}\right)^{\mathcal{A}}[\mathrm{val}]=f^{\mathcal{A}}\left(t_{1}^{\mathcal{A}}[\mathrm{val}], \ldots, t_{n}^{\mathcal{A}}[\mathrm{val}]\right)$.
$t^{\mathcal{A}}[\mathrm{val}]$ reads the term $t$ in structure $\mathcal{A}$ according to valuation val.
As usual, when the structure $\mathcal{A}$ is clear from the context, we will simply write $t[\mathrm{val}]$, instead of $t^{\mathcal{A}}[\mathrm{val}]$.

Given an FO formula $\varphi$, and an interpretation $(\mathcal{A}$, val), we define $(\mathcal{A}, \operatorname{val}) \vDash \varphi(\operatorname{read}:(\mathcal{A}$, val) is an interpretation/a model of $\varphi$, or that $\varphi$ holds in $(\mathcal{A}$, val)) inductively as follows.

- $(\mathcal{A}, \mathrm{val}) \vDash s \approx t$, if and only if $s^{\mathcal{A}}[\mathrm{val}]=t^{\mathcal{A}}[\mathrm{val}]$.
- $(\mathcal{A}, \mathrm{val}) \models R\left(t_{1}, \ldots, t_{n}\right)$, if and only if $\left(t_{1}^{\mathcal{A}}[\mathrm{val}], \ldots, t_{n}^{\mathcal{A}}[\mathrm{val}]\right) \in R^{\mathcal{A}}$.
- $(\mathcal{A}$, val $) \vDash \neg \alpha$, if and only if it is not true that $(\mathcal{A}$, val $) \models \alpha$.
- $(\mathcal{A}$, val $) \models \alpha \wedge \beta$, if and only if $(\mathcal{A}$, val $) \models \alpha$ and $(\mathcal{A}$, val $) \models \beta$.
- $(\mathcal{A}$, val $) \models \alpha \vee \beta$, if and only if $(\mathcal{A}$, val $) \models \alpha$ or $(\mathcal{A}$, val $) \models \beta$.
- $(\mathcal{A}$, val $) \vDash \exists x \alpha$, if and only if there is $a \in A$ such that $(\mathcal{A}, \operatorname{val}[x \mapsto a]) \vDash \alpha$.
- $(\mathcal{A}, \operatorname{val}) \models \forall x \alpha$, if and only if for every $a \in A,(\mathcal{A}, \operatorname{val}[x \mapsto a]) \models \alpha$.

We write $(\mathcal{A}$, val) $\not \models \varphi$, when it is not true that $(\mathcal{A}$, val $) \models \varphi$.
Note that whether $(\mathcal{A}$, val $) \models \varphi\left(x_{1}, \ldots, x_{n}\right)$ depends only on $\mathcal{A}$ (obviously!) and the images of $x_{1}, \ldots, x_{n}$ under val. In other words, the value val $(y)$ does not matter for every $y \notin\left\{x_{1}, \ldots, x_{n}\right\}$. To avoid clutter, we write $\left(\mathcal{A}, a_{1}, \ldots, a_{n}\right) \vDash \varphi\left(x_{1}, \ldots, x_{n}\right)$, to mean that $(\mathcal{A}$, val) $\vDash \varphi$, where val is a valuation function that maps each $x_{i}$ to $a_{i}$. In particular, if $\alpha$ is a sentence, the valuation val is dispensable in the determination of $(\mathcal{A}, \mathrm{val}) \models \alpha$. So, for a sentence $\alpha$, we simply write $\mathcal{A} \models \alpha$.

A formula $\varphi$ is satisfiable, if $\varphi$ has an interpretation/model.

## 3 Some examples

Example 5.1 Let $\mathcal{A}=\left(A\right.$, plus $\left.{ }^{\mathcal{A}}, 0^{\mathcal{A}}\right)$ be the structure with signature $\{$ plus, 0$\}$ defined as follows.

- $A=\{0,1,2, \ldots, 8\}$,
- plus is a binary function/operator, where $\operatorname{plus}^{\mathcal{A}}(x, y)=x+y \bmod 9$,
- $0^{\mathcal{A}}=0$.

Here are some formulas that hold/not hold in $\mathcal{A}$.

- $\mathcal{A},(x, y, z) \mapsto(3,5,8) \vDash \operatorname{plus}(x, y) \approx z$. Can I say that $\mathcal{A} \models \operatorname{plus}(3,5) \approx 8$ ?
- $\mathcal{A},(x, y) \mapsto(1,2) \not \models \operatorname{plus}(x, y) \approx 0$.

This is equivalent to say that $\mathcal{A},(x, y) \mapsto(1,2) \vDash \neg(\operatorname{plus}(x, y) \approx 0)$, or, $\mathcal{A},(x, y) \mapsto(1,2) \models$ plus $(x, y) \not \approx 0$.

- $\mathcal{A}, z \mapsto 0 \models \forall x \operatorname{plus}(x, z) \approx x$.
- $\mathcal{A}, z \mapsto 1 \models \forall x \operatorname{plus}(x, z) \not \approx x$. Can I say that $\mathcal{A} \vDash \forall x \operatorname{plus}(x, 1) \not \approx x$ ?
- $\mathcal{A} \equiv \forall x \operatorname{plus}(x, 0) \approx x$.
- $\mathcal{A} \models \forall x \exists y \operatorname{plus}(x, y) \approx 0$.
- $\mathcal{A} \models \forall x(x \not \approx 0 \rightarrow(\exists y x \not \approx y \wedge \operatorname{plus}(x, y) \approx 0))$.

Example 5.2 Let $\mathcal{B}=\left(B, E^{\mathcal{B}}\right)$ be the following structure, where $\operatorname{ar}(E)=2$ :

- $B=\left\{a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right\}$,
- $E^{\mathcal{B}}=\left\{\left(a_{1}, b_{1}\right),\left(a_{2}, b_{2}\right), \ldots,\left(a_{n}, b_{n}\right)\right\}$.

The relation $E^{\mathcal{B}}$ can be illustrated as follows.


Here are some examples of formulas that hold $/$ not hold in $\mathcal{B}$.

- $\mathcal{B},(x, y) \mapsto\left(a_{1}, b_{1}\right) \models E(x, y)$. Can I say $\mathcal{B} \models E\left(a_{1}, b_{1}\right)$ ?
- $\mathcal{B},(x, y) \mapsto\left(a_{1}, b_{3}\right) \not \models E(x, y)$.
- $\mathcal{B} \models \exists x \exists y E(x, y)$.
- $\mathcal{B} \not \vDash \exists x E(x, x)$, which can be rewritten as $\mathcal{B} \models \neg \exists x E(x, x)$
- $\mathcal{B} \models \forall x \exists y(E(x, y) \wedge \forall z(E(x, z) \rightarrow y \approx z))$.

Example 5.3 Let $\mathcal{Z}=\left(\mathbb{Z}, \operatorname{succ}^{\mathcal{Z}}\right.$, plus $\left.^{\mathcal{Z}}, 0^{\mathcal{Z}}\right)$ be the structure with signature $\{$ plus, succ, 0$\}$ defined as follows.

- $\mathbb{Z}=\{\ldots,-2,-1,0,1,2, \ldots\}$,
- $\operatorname{succ}^{\mathcal{Z}}$ is a binary relation, where $(x, y) \in \operatorname{succ}^{\mathcal{Z}}$ if and only if $y=x+1$,
- plus ${ }^{\mathcal{Z}}$ is a binary operator, where $\operatorname{plus}^{\mathcal{Z}}(x, y)=x+y$,
- $0^{\mathcal{Z}}=0$.

Here are some formulas that hold/not hold in $\mathcal{Z}$.

- $\mathcal{Z},(x, y, z) \mapsto(3,5,8) \models \operatorname{plus}(x, y) \approx z$.
- $\mathcal{Z},(x, y) \mapsto(1,2) \not \models \operatorname{plus}(x, y) \approx 0$.
- $\mathcal{Z}, z \mapsto 0 \models \forall x \operatorname{plus}(x, z) \approx x$.
- $\mathcal{Z}, z \mapsto 1 \models \forall x \operatorname{plus}(x, z) \not \approx x$.
- $\mathcal{Z} \models \forall x \operatorname{plus}(x, 0) \approx x$.
- $\mathcal{Z} \models \forall x \exists y \operatorname{plus}(x, y) \approx 0$.
- $\mathcal{Z} \models \forall x \exists y \operatorname{succ}(x, y) \wedge x \not \approx y$.
- $\mathcal{Z} \models \forall x \exists y \operatorname{succ}(x, y) \wedge(\forall z(\operatorname{succ}(x, z) \rightarrow y \approx z))$.
- $\mathcal{Z} \models \forall x \forall y \forall z \forall w((\operatorname{succ}(x, z) \wedge \operatorname{succ}(w, y)) \rightarrow \operatorname{plus}(x, y) \approx \operatorname{plus}(z, w))$.


## 4 Two little theorems

Theorem 5.4 Let $h: \mathcal{A} \rightarrow \mathcal{B}$ be an isomorphism. Then, for every formula $\varphi(\bar{x})$,

$$
(\mathcal{A}, \bar{a}) \models \varphi(\bar{x}) \quad \text { if and only if } \quad(\mathcal{B}, h(\bar{a})) \models \varphi(\bar{x})
$$

(Recall that $\bar{x}$ and $\bar{a}$ stands for a vector of variables and elements, respectively, which we tacitly assume to be of the same length.)

A $\forall$-sentence (read: a universal sentence) is a sentence of the form:

$$
\begin{equation*}
\forall x_{1} \cdots \forall x_{n} \varphi \tag{1}
\end{equation*}
$$

where $\varphi$ is quantifier free. Likewise, an $\exists$-sentence (read: an existential sentence) is a sentence of the form:

$$
\begin{equation*}
\exists x_{1} \cdots \exists x_{n} \varphi \tag{2}
\end{equation*}
$$

where $\varphi$ is quantifier free. As usual, we will simply write $\forall \bar{x} \varphi$ or $\exists \bar{x} \varphi$, instead of Eq. (1) and (2), respectively.

Theorem 5.5 Let $\mathcal{A} \subseteq \mathcal{B}$.

- For every $\forall$-sentence $\psi$, if $\mathcal{B} \models \psi$, then $\mathcal{A} \vDash \psi$.
- For every $\exists$-sentence $\psi$, if $\mathcal{A} \vDash \psi$, then $\mathcal{B} \vDash \psi$.


## Exercise set 1

In the following $E, R, T, S$ are relational symbols, $f, g$ are function symbols and $c, c_{1}, c_{2}, \ldots$ are constant symbols.
(1) Determine the quantifier rank of each of the following formulas.

$$
\begin{aligned}
& \beta_{1}:=\forall x \exists y(z \not \approx y \wedge R(x, y)) \\
& \beta_{2}:=\forall x(x \not \approx y \wedge \exists y R(x, y)) \\
& \beta_{3}:=(\forall z(\exists z z \not \approx y)) \wedge f(z) \approx z \\
& \beta_{4}:=\forall z(z \approx y \wedge \exists z(f(z) \approx g(z))) \\
& \beta_{5}:=\exists y \forall x(R(z, g(z, y)) \wedge T(y) \rightarrow \exists z \forall y x \approx f(x, g(y, z))) \\
& \beta_{6}:=x \not \approx f(c, z) \wedge \forall z \forall x(R(x, c, c, y) \wedge f(x, z) \approx c \wedge \exists y(f(x, y) \wedge g(z, y)))
\end{aligned}
$$

(2) Determine the free variables of each of the formulas above.
(3) Determine the result of each of the following substitutions.

- $z / f(z, z, x)$ in $\beta_{1}$.
- $y / g(c, c)$ in $\beta_{2}$.
- $z / f(x, y, z)$ in $\beta_{3}$.
- $y / z$ in $\beta_{4}$.
- $z / f(c, z, x)$ in $\beta_{5}$.
- $(x, y, z) /(x, x, x)$ in $\beta_{6}$.

Which substitutions are collision-free?

## Exercise set 2: The notion of congruence

In this exercise, we will study the notion of congruence on structures. Let $Z$ be set, and $\sim$ be an equivalence relation on $Z$. For a positive integer $n$, define a binary relation $\sim^{n}$ on $Z^{n}$ as follows.

$$
\left(a_{1}, \ldots, a_{n}\right) \sim^{n}\left(b_{1}, \ldots, b_{n}\right) \quad \text { if and only if } \quad a_{i} \sim b_{i}, \text { for each } i \in\{1, \ldots, n\} .
$$

(4) Prove that $\sim^{n}$ is an equivalence relation.

The relation $\sim^{n}$ is called the extension of $\sim$ to $Z^{n}$.
(5) Prove that $[\bar{a}]_{\sim_{n}}=\left[a_{1}\right]_{\sim} \times\left[a_{2}\right]_{\sim} \times \cdots \times\left[a_{n}\right]_{\sim}$, where $\bar{a}=\left(a_{1}, \ldots, a_{n}\right)$.

When it is clear from the context, we will simply use the same symbol $\sim$, instead of $\sim^{n}$. That is, we will write $\bar{a} \sim \bar{b}$ to mean the extension of $\sim$ to $Z^{n}$, instead of $\bar{a} \sim^{n} \bar{b}$.

Let $\mathcal{A}$ be an $L$-structure. A congruence in $\mathcal{A}$ is an equivalence relation $\sim$ on $A$ such that for every function symbol $f \in L$, the following holds.

$$
\text { If } \bar{a} \sim \bar{b}, \text { then } f(\bar{a}) \sim f(\bar{b})
$$

(6) Let $\sim$ be a congruence in an $L$-structure $\mathcal{A}$. The factor of $\mathcal{A}$ modulo $\sim$ is a structure $\mathcal{B}$ such that

$$
\text { - } B=A / \sim=\left\{[a]_{\sim} \mid a \in A\right\}
$$

- $\left(\left[a_{1}\right]_{\sim}, \ldots,\left[a_{l}\right]_{\sim}\right) \in R^{\mathcal{B}}$ if and only if $R^{\mathcal{A}} \cap[\bar{a}]_{\sim l} \neq \emptyset$, for every relation symbol $R \in L$ of arity $l$,
- $c_{i}^{\mathcal{B}}=\left[c_{i}^{\mathcal{A}}\right]_{\sim}$,
- $f^{\mathcal{B}}\left(\left[a_{1}\right]_{\sim}, \ldots,\left[a_{l}\right]_{\sim}\right)=\left[f^{\mathcal{A}}\left(a_{1}, \ldots, a_{l}\right)\right]_{\sim}$, for every function symbol $f \in L$ of arity $l$.

Prove that this definition is sound. That is, show that
(i) if $\left[\left(a_{1}, \ldots, a_{l}\right)\right]_{\sim l}=\left[\left(b_{1}, \ldots, b_{l}\right)\right]_{\sim l}$, then $\left(\left[a_{1}\right]_{\sim}, \ldots,\left[a_{l}\right]_{\sim}\right)=\left(\left[b_{1}\right]_{\sim}, \ldots,\left[b_{l}\right]_{\sim}\right)$,
(ii) if $\left(\left[a_{1}\right]_{\sim}, \ldots,\left[a_{l}\right]_{\sim}\right)=\left(\left[b_{1}\right]_{\sim}, \ldots,\left[b_{l}\right]_{\sim}\right)$, then $f^{\mathcal{B}}\left(\left[a_{1}\right]_{\sim}, \ldots,\left[a_{l}\right]_{\sim}\right)=f^{\mathcal{B}}\left(\left[b_{1}\right]_{\sim}, \ldots,\left[b_{l}\right]_{\sim}\right)$.

The factor of $\mathcal{A}$ modulo $\sim$ is denoted by $\mathcal{A} / \sim$.
(7) For a congruence $\sim \operatorname{in} \mathcal{A}$, the canonical homomorphism $\kappa: \mathcal{A} \rightarrow \mathcal{A} / \sim$ is defined by $\kappa(a)=$ $[a]_{\sim}$. Prove that $\kappa$ is a strong and surjective homomorphism.

## Exercise set 3: Skolem normal form

Two formulas $\varphi_{1}$ and $\varphi_{2}$ are equi-satisfiable, if

$$
\varphi_{1} \text { is satisfiable if and only if } \varphi_{2} \text { is satisfiable. }
$$

(8) Consider a sentence $\psi$ over a vocabulary $L$ of the form:

$$
\psi:=\exists x_{1} \cdots \exists x_{n} \varphi
$$

Pick $n$ "new" constant symbols $c_{1}, \ldots, c_{n} \notin L$. Show that $\varphi\left[\left(x_{1}, \ldots, x_{n}\right) /\left(c_{1}, \ldots, c_{n}\right)\right]$ and $\psi$ are equi-satisfiable.
(9) Consider a sentence $\psi$ over a vocabulary $L$ of the form:

$$
\psi:=\forall x_{1} \cdots \forall x_{n} \exists y \varphi
$$

Pick a "new" arity $n$ function symbol $f \notin L$. Show that $\forall x_{1} \cdots \forall x_{n} \varphi\left[y / f\left(x_{1}, \ldots, x_{n}\right)\right]$ and $\psi$ are equi-satisfiable.
(10) Consider a sentence $\psi$ over a vocabulary $L$ of the form:

$$
\psi:=\forall x_{1} \cdots \forall x_{n} \exists y_{1} \cdots \exists y_{m} \varphi
$$

where $\varphi$ does not start with existential quantifiers. Prove that there is a sentence of the form:

$$
\psi^{\prime}:=\forall x_{1} \cdots \forall x_{n} \varphi^{\prime}
$$

such that $\varphi^{\prime}$ does not start with existential quantifiers, and $\psi$ and $\psi^{\prime}$ are equi-satisfiable.
(11) (Skolem normal form) Consider a sentence $\psi$ over a vocabulary $L$ of the form:

$$
\begin{equation*}
\psi:=Q_{1} x_{1} \cdots Q_{n} x_{n} \varphi \tag{3}
\end{equation*}
$$

where each $Q_{i}$ is a quantifier (either $\forall$ or $\exists$ ), and $\varphi$ is quantifier free. Prove that there is $\forall$-sentence $\psi^{\prime}$ (over different vocabulary $L^{\prime}$ ) such that $\psi$ and $\psi^{\prime}$ are equi-satisfiable.
Note 1: The $\forall$-sentence $\psi^{\prime}$ is called the Skolem normal form of $\psi$.
Note 2: Formulas of the form (3) are often called formulas in Prenex Normal Form (PNF). We will show later on that every formula can be converted into PNF.

## Lesson 6: Logical consequences and theories

Theme: Logical consequences and first-order theories.

## 1 Logical consequences

Definition 6.1 Let $X$ be a set of formulas. We write $(\mathcal{A}$, val) $\vDash X$, if ( $\mathcal{A}$, val) $\models \varphi$, for every $\varphi \in X$.

Definition 6.2 A formula $\beta$ is a logical consequence of a formula $\alpha$, denoted by $\alpha \models \beta$, if every model of $\alpha$ is also a model of $\beta$. If $\alpha \models \beta$ and $\beta=\alpha$, we write $\alpha \models=\beta$, or $\alpha \equiv \beta$.

One example is $\forall x \varphi \models \exists x \varphi$. (Recall that the domain of a structure is never empty.)
Definition 6.3 We say that $\alpha$ is a logical consequence of a set $X$ of formulas, denoted by $X \models \alpha$, if every model of $X$ is also a model of $\alpha$. More formally, $X \models \alpha$ means that for every model $(\mathcal{A}, \operatorname{val})$, if $(\mathcal{A}$, val $) \models X$, then $(\mathcal{A}$, val $) \models \alpha$.

We write $X \not \models \alpha$, if it is not the case that $X \models \alpha$.

Definition 6.4 A sentence $\varphi$ is valid, if $\models \varphi$. In other words, $\varphi$ is valid, if $\mathcal{A} \models \varphi$, for every structure $\mathcal{A}{ }^{*}{ }^{*}$

Some conventions to read the notations:

- $(\mathcal{A}, \operatorname{val}) \models X$ is $\operatorname{read}$ as " $(\mathcal{A}, \mathrm{val})$ is a model of $X$."
- $\alpha \models \beta$ is also read as " $\alpha$ implies $\beta$."
- $\alpha \equiv \beta$ is also read as " $\alpha$ and $\beta$ are equivalent."

Theorem 6.5 $X \models \varphi$ if and only if $X \cup\{\neg \varphi\}$ is not satisfiable.
Proposition 6.6 For every formulas $\alpha$ and $\beta$, the following holds.

$$
\begin{aligned}
\neg \forall x \alpha & \equiv \exists x \neg \alpha & & \\
\neg \exists x \alpha & \equiv \forall x \neg \alpha & & \\
\alpha \wedge \forall x \beta & \equiv \forall x(\alpha \wedge \beta) & & \text { when } x \text { is not free in } \alpha \\
\alpha \wedge \exists x \beta & \equiv \exists x(\alpha \wedge \beta) & & \text { when } x \text { is not free in } \alpha
\end{aligned}
$$

Definition 6.7 Every formula is in Prenex Normal Form (PNF), if is is of the form:

$$
Q_{1} x_{1} \cdots Q_{n} x_{n} \varphi
$$

where $\varphi$ is quantifier-free, and each $Q_{i} \in\{\forall, \exists\}$.

Theorem 6.8 Every formula is equivalent to another formula in PNF.

[^4]
## 2 First-order theories

## Definition 6.9

- A set $T$ of sentences is called a theory, if it is closed under logical consequences, i.e., for every sentence $\varphi$, if $T \models \varphi$, then $\varphi \in T$.
- A theory $T$ is complete, if for every sentence $\varphi$, either $\varphi \in T$ or $\neg \varphi \in T$.


## Definition 6.10

- For a set $X$ of sentences, $\operatorname{Model}(X):=\{\mathcal{A} \mid \mathcal{A} \models X\}$.
- For a set $X$ of sentences, $\operatorname{Cn}(X):=\{\varphi \mid X \models \varphi\}$.
- For a set $\mathcal{K}$ of structures, $\operatorname{Th}(\mathcal{K}):=\{\varphi \mid \varphi$ holds in every structure in $\mathcal{K}\}$.

Theorem 6.11 For a set $\mathcal{K}$ of structures, and a set $X$ of sentences, the following holds.

- $\mathcal{K} \subseteq \operatorname{Model}(\operatorname{Th}(\mathcal{K}))$.
- $\operatorname{Th}(\mathcal{K})$ is a theory.
- $C n(X)=\operatorname{Th}(\operatorname{Model}(X))$.

Definition 6.12 A theory $T$ is finitely axiomatizable, if there is a finite set $\Sigma$ such that $T=$ $\operatorname{Cn}(\Sigma)$.

Remark 6.13 If $\operatorname{Cn}(T)$ is finitely axiomatizable, then there is a finite subset $T_{0} \subseteq T$ such that $\operatorname{Cn}\left(T_{0}\right)=\operatorname{Cn}(T)$.

## Exercises

(1) Show that $\exists x \forall y \varphi \not \vDash \forall x \exists y \varphi$.

That is, give a model $\mathcal{A}$ and a formula $\varphi$ such that $\mathcal{A} \vDash \exists x \forall y \varphi$. but $\mathcal{A} \not \vDash \forall x \exists y \varphi$.
(2) Give a set $\mathcal{K}$ of sentences such that $\mathcal{K} \neq \operatorname{Model}(\operatorname{Th}(\mathcal{K}))$.
(3) Let $\mathcal{K}=\{\mathcal{A}\}$, i.e., it consists of only one structure $\mathcal{A}$. Prove that $\operatorname{Th}(\mathcal{K})$ is complete.
(4) Give a set $\mathcal{K}$ of structures such that $\operatorname{Th}(\mathcal{K})$ is not complete.
(5) Let $T$ be a complete theory and let $\mathcal{A} \vDash T$. Prove that for every sentence $\alpha, \mathcal{A} \vDash \alpha$ if and only if $T \models \alpha$.

We denote by $\mathcal{A} \cong \mathcal{B}$, if $\mathcal{A}$ is isomorphic to $\mathcal{B}$, i.e., there is an isomorphism from $\mathcal{A}$ to $\mathcal{B}$. Two structures $\mathcal{A}$ and $\mathcal{B}$ are elementarily equivalent, written as $\mathcal{A} \equiv \mathcal{B}$, if for every sentence $\varphi$,

$$
\mathcal{A} \mid=\varphi \quad \text { if and only if } \mathcal{B} \mid=\varphi .
$$

(6) Prove that if $\mathcal{A} \cong \mathcal{B}$, then $\mathcal{A} \equiv \mathcal{B}$.
(7) Let $\mathcal{K}$ be a set of structures such that for every $\mathcal{A}, \mathcal{B} \in \mathcal{K}$, we have $\mathcal{A} \cong \mathcal{B}$. Prove that $\operatorname{Th}(\mathcal{K})$ is complete.

## Appendix

The converse of question (6) does not hold in general. That is, $\mathcal{A} \equiv \mathcal{B}$ does not necessarily imply $\mathcal{A} \cong \mathcal{B}$. Consider, for example, the following two structures.

- $\mathcal{R}=\left(\mathbb{R},<^{\mathcal{R}}\right)$, where $<^{\mathcal{R}}$ is the standard ordering in $\mathbb{R}$.
- $\mathcal{Q}=\left(\mathbb{Q},<^{\mathcal{Q}}\right)$, where $<^{\mathcal{Q}}$ is the standard ordering in $\mathbb{Q}$.

It is known that $\mathcal{R} \equiv \mathcal{Q}$, but $\mathcal{R}$ is not isomorphic to $\mathcal{Q}$, since $\mathbb{R}$ is uncountable, but $\mathbb{Q}$ is countable.
In general it is not a trivial matter to determine whether two structures are elementarily equivalent. It usually involves a technique called Ehrenfeucht-Fraissé game, which we will not cover in this course.

## Lesson 7: Proof system in first-order logic

Theme: The notion of provability in first-order logic.

## 1 Proofs in first-order logic

Throughout this note, $L$ is a fixed vocabulary. For a formula $\alpha$, we denote by $\operatorname{var}(\alpha)$ to be the set of all variables in $\alpha$ (both free and quantified).

Let $X$ be a set of formulas and $\alpha$ be a formula (over $L$ ). We say that $\alpha$ can be provable from $X$, or $\alpha$ is derivable from $X$, denoted by $X \vdash_{L} \alpha$, if it can be obtained inductively according to the following rules.

$$
\begin{array}{llll}
\text { Initial Rule (IR): } & X & \vdash_{L} \quad \alpha \quad \text { if } \alpha \in X \\
& X & \vdash_{L} \quad t \approx t \quad \text { for every } L \text {-term } t \\
\text { Monotonicity Rule (MR): } & \frac{X \vdash_{L} \alpha}{Y \vdash_{L} \alpha} \quad \text { for every } Y \supseteq X
\end{array}
$$

And Combine Rule (ACR): $\frac{X \vdash_{L} \alpha \text { and } X \vdash_{L} \beta}{X \vdash_{L} \alpha \wedge \beta}$

And Split Rule (ASR): $\quad \frac{X \vdash_{L} \alpha \wedge \beta}{X \vdash_{L} \alpha \text { and } X \vdash_{L} \beta}$

Contradiction Rule (CR): $\frac{X \vdash_{L} \alpha \text { and } X \vdash_{L} \neg \alpha}{X \vdash_{L} \beta} \quad$ for every $\beta$

Negation Rule (NR): $\frac{X, \alpha \vdash_{L} \beta \text { and } X, \neg \alpha \vdash_{L} \beta}{X \vdash_{L} \beta}$

Specialisation Rule (SR): $\frac{X \vdash_{L} \forall x \alpha}{X \vdash_{L} \alpha[t / x]} \quad$ where $[t / x]$ is collision-free in $\alpha$

Generalisation Rule (GR): $\frac{X \vdash_{L} \alpha[y / x]}{X \vdash_{L} \forall x \alpha} \quad$ where $y \notin \operatorname{free}(X) \cup \operatorname{var}(\alpha)$

Equality Rule (ER): $\quad \frac{X \vdash_{L} s \approx t \text { and } X \vdash_{L} \alpha[s / x]}{X \vdash_{L} \alpha[t / x]} \quad$ where $\alpha$ is atomic

We write $X \nvdash_{L} \alpha$, if it is not the case that $X \vdash_{L} \alpha$.
Remark 7.1 When there is no confusion, we will omit writing $L$, and thus, write only $\vdash$, instead of $\vdash_{L}$.

We will also follow the writing convention from the proof system in the propositional calculus. We write $\alpha \vdash \alpha$ to denote $\{\alpha\} \vdash \alpha$, whereas $X, \alpha \vdash \beta$ means $X \cup\{\alpha\} \vdash \beta$. As before, $\vdash \alpha$ to denote $\emptyset \vdash \alpha$.

Theorem 7.2 (Finiteness theorem for $\vdash$ ) If $X \vdash \alpha$, then there is a finite set $X_{0} \subseteq X$ such that $X_{0} \vdash \alpha$.

Example 7.3 $\frac{X \vdash s \approx t \text { and } X \vdash s \approx t^{\prime}}{X \vdash t \approx t^{\prime}}$

1. $X \vdash s \approx t$.
2. $X \vdash s \approx t^{\prime}$.
(supposition)
Let $x \notin \operatorname{var}\left(t^{\prime}\right)$ and $\alpha:=x \approx t^{\prime}$. So (2) is actually $X \vdash \alpha[s / x]$.
3. $X \vdash \alpha[t / x]$.
(Equality Rule on 1 and 22)
$\alpha[t / x]$ is precisely $t \approx t^{\prime}$.
Example 7.4 $\frac{X \vdash s \approx t}{X \vdash t \approx s}$
4. $X \vdash s \approx t$.
5. $X \vdash s \approx s$.
(Initial rule)
6. $X \vdash t \approx s$.
(Example 7.3 on 1 and 2)

Example 7.5 $\frac{X \vdash t \approx s \text { and } \quad X \vdash s \approx t^{\prime}}{X \vdash t \approx t^{\prime}}$

1. $X \vdash t \approx s$.
2. $X \vdash s \approx t^{\prime}$.
3. $X \vdash s \approx t$.
4. $X \vdash t \approx t^{\prime}$.
(supposition)
(supposition)
(Example 7.4 on 1)
(Example 7.3 on 3 and 3)

Example 7.6 $\frac{X \vdash t_{i} \approx s}{X \vdash f\left(t_{1}, \ldots, t_{k}\right) \approx f\left(t_{1}, \ldots, t_{i-1}, s, t_{i+1, \ldots, t_{k}}\right)}$

1. $X \vdash t_{i} \approx s$.
(supposition)
2. $X \vdash f\left(t_{1}, \ldots, t_{k}\right) \approx f\left(t_{1}, \ldots, t_{k}\right)$.
(Initial rule)
Let $x \notin \operatorname{var}\left(t_{1}\right) \cup \cdots \cup \operatorname{var}\left(t_{k}\right) \cup \operatorname{var}(s)$ and $\alpha:=f\left(t_{1}, \ldots, t_{k}\right) \approx f\left(t_{1}, \ldots, t_{i-1}, x, t_{i+1}, \ldots, t_{k}\right)$. So (2) is actually $X \vdash \alpha\left[t_{i} / x\right]$.
3. $X \vdash \alpha[s / x]$.
(Equality Rule on 1 and 22)
$\alpha[s / x]$ is precisely $f\left(t_{1}, \ldots, t_{k}\right) \approx f\left(t_{1}, \ldots, t_{i-1}, s, t_{i+1, \ldots, t_{k}}\right)$.
Example 7.7 $\frac{X \vdash t_{i} \approx s \text { and } X \vdash R\left(t_{1}, \ldots, t_{k}\right)}{X \vdash R\left(t_{1}, \ldots, t_{i-1}, s, t_{i+1, \ldots, t_{k}}\right)}$.

In the following $X \vdash\left(t_{1}, \ldots, t_{k}\right) \approx\left(s_{1}, \ldots, s_{k}\right)$ denotes $X \vdash t_{i} \approx s_{i}$, for each $i \in\{1, \ldots, k\}$.
Example 7.8 $\frac{X \vdash\left(t_{1}, \ldots, t_{k}\right) \approx\left(s_{1}, \ldots, s_{k}\right)}{X \vdash f\left(t_{1}, \ldots, t_{k}\right) \approx f\left(s_{1}, \ldots, s_{k}\right)}$
Example 7.9 $\frac{X \vdash\left(t_{1}, \ldots, t_{k}\right) \approx\left(s_{1}, \ldots, s_{k}\right) \text { and } \quad X \vdash R\left(t_{1}, \ldots, t_{k}\right)}{X \vdash R\left(s_{1}, \ldots, s_{k}\right)}$.
Lemma 7.10 Let $t$ be a term, and $x \notin \operatorname{var}(t)$. Then, the following holds.
(a) $\vdash \exists x t \approx x$. (Here $\exists x t \approx x$ stands for $\neg \forall x t \not \approx x$.)
(b) $\vdash \exists x x \approx x$. (Here $\exists x x \approx x$ stands for $\neg \forall x x \not \approx x$.)

Proof. We prove item (a).

1. $\forall x t \not \approx x \vdash \forall x t \not \approx x$.
2. $\forall x t \not \approx x \vdash(t \not \approx x)[t / x]$.
3. $\forall x t \not \approx x \vdash t \not \approx t$.

$$
((\not \not \not \approx x)[t / x]=t \not \approx t)
$$

4. $\forall x t \not \approx x \vdash t \approx t$.
(Initial Rule)
5. $\forall x t \not \approx x \vdash \neg \forall x t \not \approx x$. (Contradiction Rule on 3 and 4)
6. $\neg \forall x t \not \approx x \vdash \neg \forall x t \not \approx x$.
(Initial Rule)
7. $\vdash \neg \forall x t \not \approx x$.
(Negation Rule on 5 and 6)
Part (b) can be proved in a similar manner starting with $\forall x x \not \approx x \vdash x \not \approx x$ and $\forall x x \not \approx x \vdash x \approx x$.

## 2 Precursors to the soundness of $\vdash$

Proposition 7.11 Let $\alpha$ be a formula, and $y \notin \operatorname{var}(\alpha)$. Then, the following holds.

- $\alpha[y / x][x / y]=\alpha$.
- $\forall z \alpha \equiv \forall y \alpha[y / z]$.

Proposition 7.12 Let $(\mathcal{A}, v a l)$ be an interpretation. Let $t$ be a term. Suppose that $t^{\mathcal{A}}[v a l]=b$.
(a) For every term $s$,

$$
s[t / x]^{\mathcal{A}}[\mathrm{val}]=s^{\mathcal{A}}[\mathrm{val}[x \mapsto b]] .
$$

(b) For every term $s_{1}, s_{2}$,

$$
(\mathcal{A}, \text { val }[x \mapsto b]) \models s_{1} \approx s_{2} \quad \text { if and only if }(\mathcal{A}, \text { val }) \models\left(s_{1} \approx s_{2}\right)[t / x] .
$$

(c) For a relation $R$ and terms $s_{1}, \ldots, s_{m}$,

$$
(\mathcal{A}, \text { val }[x \mapsto b]) \models R\left(s_{1}, \ldots, s_{m}\right) \quad \text { if and only if } \quad(\mathcal{A}, \text { val }) \models R\left(s_{1}, \ldots, s_{m}\right)[t / x] .
$$

Proposition 7.13 Let $(\mathcal{A}, \mathrm{val})$ be an interpretation. Let $\alpha$ be a formula, and $[t / x]$ be collisionfree in $\alpha$. Suppose $t^{\mathcal{A}}[$ val $]=b$. Then, $(\mathcal{A}$, val $[x \mapsto b]) \models \alpha$ if and only if $(\mathcal{A}$, val $) \models \alpha[t / x]$.

Proof. The proof is by induction on $\alpha$. The base case is when $\alpha$ is atomic formula, i.e., of the form $s_{1} \approx s_{2}$ or $R\left(s_{1}, \ldots, s_{n}\right)$. This has been settled in Proposition 7.12 parts (b) and (c).

For the induction step, we have three cases: $\alpha$ is of the form $\neg \beta$, or $\beta \wedge \gamma$, or $\forall z \beta$. The first two cases are easy. We consider the case when $\alpha$ is $\forall z \beta$.

We first prove the "only if" direction. By definition,

$$
\begin{equation*}
(\mathcal{A}, \operatorname{val}[x \mapsto b]) \quad \models \forall z \beta \tag{1}
\end{equation*}
$$

if and only if for every $a \in A$,

$$
\begin{equation*}
(\mathcal{A}, \operatorname{val}[x \mapsto b][z \mapsto a]) \quad \models \beta \tag{2}
\end{equation*}
$$

Now, $[t / x]$ is collision-free in $\alpha$, which by definition, $t$ does not contain $z$ and $[t / x]$ is collision-free in $\beta$. Since $t$ does not contain $z$, we have:

$$
\begin{equation*}
t^{\mathcal{A}}[\operatorname{val}[z \mapsto a]]=t^{\mathcal{A}}[\mathrm{val}]=b \tag{3}
\end{equation*}
$$

CAUTION: if $t$ contains $z$, Equation 3 may not hold. That is why we need $[t / x]$ to be collision-free in $\alpha$.

So by the induction hypothesis on Equation 2, we have that for every $a \in A$ :

$$
\begin{equation*}
(\mathcal{A}, \operatorname{val}[z \mapsto a]) \quad \vDash \beta[t / x] \tag{4}
\end{equation*}
$$

This means that $(\mathcal{A}$, val $) \models \forall z \beta[t / x]$, and therefore,

$$
\begin{equation*}
(\mathcal{A}, \text { val }) \vDash \alpha[t / x] \tag{5}
\end{equation*}
$$

The "if" direction can be proved in a similar manner via $(5) \Rightarrow(4) \Rightarrow(3) \Rightarrow(2)$.

## Exercises

We are going to show that our proof system is sound, as stated formally below.
(Soundness theorem for $\vdash$ ) If $X \vdash \alpha$, then $X \models \alpha$.
We are going to show that each rule in our proof system is sound.
(1) Prove that the Initial Rule (IR) is sound, i.e., for every set $X$,

- $X \models \alpha$, for every $\alpha \in X$.
- $X \models t \approx t$, for every term $t$.
(2) Prove that the Monotonicity Rule (MR) is sound, i.e., for every set $X$, if $X \models \alpha$, then $Y \models \alpha$, for every $Y \supseteq X$.
(3) Prove that the And Combine Rule (ACR) is sound, i.e., for every set $X$, for every formulas $\alpha$ and $\beta$, if $X \models \alpha$ and $X \models \beta$, then $X \models \alpha \wedge \beta$.
(4) Prove that the And Split Rule (ASR) is sound, i.e., for every set $X$, for every formulas $\alpha$ and $\beta$, if $X \models \alpha \wedge \beta$, then $X \models \alpha$ and $X \models \beta$.
(5) Prove that the Contradiction Rule (CR) is sound, i.e., for every set $X$, for every formula $\alpha$, if $X \models \alpha$ and $X \models \neg \alpha$, then $X \models \beta$, for every formula $\beta$.
(6) Prove that the Negation Rule (NR) is sound, i.e., for every set $X$, for every formulas $\alpha$ and $\beta$, if $X, \alpha=\beta$ and $X, \neg \alpha \models \beta$, then $X \models \beta$.
(7) Prove that the Specialisation Rule (SR) is sound, i.e., for every set $X$, for every formula $\alpha$, if $X \models \forall x \alpha$, and $[t / x]$ is collision-free in $\alpha$, then $X \models \alpha[t / x]$.
(8) Prove that the Generalisation Rule (GR) is sound, i.e., for every set $X$, for every formula $\alpha$, for every variable $y \notin \operatorname{free}(X) \cup \operatorname{var}(\alpha)$, if $X \models \alpha[y / x]$, then $X \models \forall x \alpha$.
(9) Prove that the Equality Rule (ER) is sound, i.e., for every set $X$, for every atomic formula $\alpha$, for every terms $s$ and $t$, if $X \models s \approx t$ and $X \models \alpha[s / x]$, then $X \models \alpha[t / x]$.
(10) Finally, conclude that $\vdash$ is sound. That is, for every set $X$, for every formula $\alpha$, if $X \vdash \alpha$, then $X \models \alpha$.

Hint: For questions (7)-(9), use Propositions 7.11, 7.12 and 7.13 .

## Lesson 8: Gödel's completeness theorem*

Theme: Consistent set, Henkin set and the equivalence between the notions of $\vdash$ and $\vDash$.

## 1 Consistent sets

Let $L$ be a vocabulary, and let $X \subseteq \mathrm{FO}[L]$. The set $X$ is inconsistent, if there is a formula $\alpha$ such that $X \vdash \alpha$ and $X \vdash \neg \alpha$. By the contradiction rule, this also means that $X$ is inconsistent if $X \vdash \beta$, for every formula $\beta$.

We say that $X$ is consistent, if $X$ is not inconsistent. It is maximally consistent, if it is consistent and for every set $Y \subseteq \mathrm{FO}[L]$ and $Y \supseteq X, Y$ is inconsistent.

## 2 Constants elimination

Let $c$ be a constant symbol and $z$ be a variable. For a formula $\alpha$, we write $\alpha \frac{z}{c}$ to denote the formula obtained by replacing every constant symbol $c$ in $\alpha$ by $z$. For a set $X$, we write $X \frac{z}{c}$ to denote the set $\left\{\left.\alpha \frac{z}{c} \right\rvert\, \alpha \in X\right\}$.

Lemma 8.1 Suppose $X \vdash_{L} \alpha$. Let c be a constant in $L$, and $L^{\prime}$ denote $L-\{c\}$. Then, there is a finite subset $X_{0} \subseteq X$ and a variable $z \notin \operatorname{var}\left(X_{0}\right) \cup \operatorname{var}(\alpha)$,

$$
X_{0} \frac{z}{c} \vdash_{L^{\prime}} \quad \alpha \frac{z}{c}
$$

Proof. (Sketch) Suppose $X \vdash_{L} \alpha$. By the finiteness theorem of $\vdash$, there is a finite set $X_{0} \subseteq X$ such that $X_{0} \vdash_{L} \alpha$. Let $z \notin \operatorname{var}\left(X_{0}\right) \cup \operatorname{var}(\alpha)$.

Claim $1 X_{0} \frac{z}{c} \vdash_{L^{\prime}} \alpha \frac{z}{c}$.
The claim can be proved by induction on the length of the proof of $X_{0} \vdash_{L} \alpha$.

Lemma 8.2 Suppose $X \vdash \alpha[c / x]$ and $c$ does not appear in $X$ and $\alpha$. Then, $X \vdash \forall x \alpha$.
Proof. Suppose $X \vdash \alpha[c / x]$, where $c$ does not appear in $X$ and $\alpha$.
By Lemma 8.1, there is a finite subset $X_{0} \subseteq X$ such that $X_{0} \frac{z}{c} \vdash \alpha[c / x] \frac{z}{c}$, where $z \notin \operatorname{var}\left(X_{0}\right) \cup$ $\operatorname{var}(\alpha[c / x])$.

Now, since $c$ does not appear in $X, X_{0} \frac{z}{c}=X_{0}$. So,

$$
X_{0} \vdash \alpha[c / x] \frac{z}{c}
$$

Moreover, $c$ does not appear in $\alpha$. So $\alpha[c / x] \frac{z}{c}=\alpha[z / x]$. Thus,

$$
X_{0} \quad \vdash \quad \alpha[z / x]
$$

Since $z$ does not appear in $X_{0}$ and $\alpha$, by generalisation rule, we have $X_{0} \vdash \forall x \alpha$. Lemma 8.2 follows immediately by monotonicity rule.

For a variable $x \in \operatorname{VAR}$ and $\alpha \in \operatorname{FO}[L]$, we define a "new" constant $c_{x, \alpha} \notin L$. We define the following formula $\alpha^{x} \in \mathrm{FO}\left[L \cup\left\{c_{x, \alpha}\right\}\right]$.

$$
\alpha^{x}:=\neg \forall x \alpha \quad \wedge \quad \alpha\left[c_{x, \alpha} / x\right]
$$

[^5]Lemma 8.3 Let $L$ be a vocabulary. Define the set $\Gamma_{L}$ of formulas as follows ${ }^{\dagger}$

$$
\Gamma_{L}:=\left\{\neg \alpha^{x} \mid x \in V A R \text { and } \alpha \in \mathrm{FO}[L]\right\}
$$

If a set $X$ is consistent, then so is $X \cup \Gamma_{L}$.
Proof. Let $X$ be a consistent set. Suppose to the contrary that $X \cup \Gamma_{L}$ is inconsistent. That is, there is $\varphi$ such that

$$
X \cup \Gamma_{L} \vdash \varphi \quad \text { and } \quad X \cup \Gamma_{L} \vdash \neg \varphi
$$

Thus, $X \cup \Gamma_{L} \vdash \mathrm{~F}$, where F denotes $\varphi \wedge \neg \varphi$. By finiteness theorem, there is a finite subset $X_{0} \subseteq X$ such that

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}}, \neg \alpha_{n}^{x_{n}} \vdash \mathrm{~F} . \tag{1}
\end{equation*}
$$

We can assume that $n$ is minimal in the sense that $X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{i}^{x_{i}} \nvdash \mathrm{~F}$, for every $i<n$. By Contradition Rule on (1),

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}}, \neg \alpha_{n}^{x_{n}} \vdash \alpha_{n}^{x_{n}} \tag{2}
\end{equation*}
$$

By Initial Rule and Monotonicity Rule,

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}}, \alpha_{n}^{x_{n}} \vdash \alpha_{n}^{x_{n}} \tag{3}
\end{equation*}
$$

By Negation Rule on (2) and (3),

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}} \vdash \alpha_{n}^{x_{n}} \tag{4}
\end{equation*}
$$

Let us denote by $x:=x_{n}, \alpha:=\alpha_{n}$ and $c:=c_{x, \alpha}$. Thus,

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}} \vdash \neg \forall x \alpha \quad \wedge \quad \alpha\left[c_{x, \alpha} / x\right] \tag{5}
\end{equation*}
$$

By And Split Rule on (5)

$$
\begin{array}{lll}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}} & \vdash & \neg \forall x \alpha \\
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}} & \vdash & \alpha\left[c_{x, \alpha} / x\right] . \tag{7}
\end{array}
$$

Since $c_{x, \alpha}$ does not appear in $X_{0}$ and in each of $\alpha_{i}^{x_{i}}$, by Lemma 8.2 on (7), we have

$$
\begin{equation*}
X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}} \quad \vdash \quad \forall x \alpha \tag{8}
\end{equation*}
$$

But (6) and (8) imply that $X_{0}, \neg \alpha_{1}^{x_{1}}, \ldots, \neg \alpha_{n-1}^{x_{n-1}}$ is inconsistent, which contradicts the assumption that $n$ is minimal.

[^6]
## 3 Henkin sets

Definition 8.4 A set $X \subseteq \mathrm{FO}[L]$ is called a Henkin set, if it satisfies the following properties.
(H1) $X \vdash \neg \alpha$ if and only if $X \nvdash \alpha$. Or, equivalently, $X \vdash \alpha$ if and only if $X \nvdash \neg \alpha$.
(H2) $X \vdash \forall x \alpha$ if and only if $X \vdash \alpha[c / x]$ for every constant $c \in L$.

Proposition 8.5 If $X$ is a Henkin set over vocabulary $L$, then for each L-term $t$, there is a constant $c \in L$ such that $X \vdash t \approx c$.

Proof. Let $X$ be a Henkin set over vocabulary $L$. By Example 7.10, we have $\vdash \neg \forall x t \not \approx x$, when $x \notin \operatorname{var}(t)$. By Monotonicity Rule, $X \vdash \neg \forall x t \not \approx x$. Since $X$ is Henkin, by (H1), we have

$$
X \nvdash \forall x t \not \approx x
$$

By (H2), for some constant $c$,

$$
X \nvdash t \not \approx c
$$

By (H1),

$$
X \vdash t \approx c
$$

This completes our proof of Proposition 8.5.

Lemma 8.6 For every consistent set $X \subseteq \mathrm{FO}[L]$, there is a Henkin set $Y \supseteq X$, where $Y \subseteq$ $\mathrm{FO}[L \cup C]$, for some set $C$ of "new" constants not in $L$.

Proof. Let $X \subseteq \mathrm{FO}[L]$ be a consistent set. For each integer $i \geqslant 0$, we define the sets $\Gamma_{i}, \Delta_{i}, L_{i}$ and $C_{i}$ as follows.

$$
\Delta_{0}:=X \quad L_{0}:=L \quad C_{0}:=\emptyset \quad \Gamma_{0}:=\emptyset
$$

For each $i>0$,

$$
\begin{aligned}
C_{i} & :=\left\{c_{x, \alpha} \mid x \in \mathrm{VAR} \text { and } \alpha \in \mathrm{FO}\left[L_{i-1}\right]\right\} \\
L_{i} & :=L_{i-1} \cup C_{i} \\
\Gamma_{i} & :=\left\{\neg \alpha^{x} \mid \alpha^{x}:=\neg \forall x \alpha \wedge \alpha\left[c_{x, \alpha} / x\right] \text { where } \alpha \in \mathrm{FO}\left[L_{i-1}\right] \text { and } c_{x, \alpha} \in C_{i} \quad\right\} \\
\Delta_{i} & :=\Delta_{i-1} \cup \Gamma_{i}
\end{aligned}
$$

Now, let $\Delta:=\bigcup_{i>0} \Delta_{i}$ and $L^{\prime}:=\bigcup_{i>0} L_{i}$.
Consider the poset $(\mathcal{F}, \subseteq)$, where

$$
\mathcal{F}:=\left\{Z \mid \Delta \subseteq Z \subseteq \mathrm{FO}\left[L^{\prime}\right] \text { and } Z \text { is consistent }\right\}
$$

Claim 2 Let $K$ be a chain in $(\mathcal{F}, \subseteq)$. Then, $\bigcup K$ is consistent.
Proof. (of Claim 2) Proceeds like the one in propositional calculus.
By Zorn's lemma, there is a maximal consistent set $Y \in \mathcal{F}$. We will now show that that $Y$ is Henkin.

Claim $3 Y$ satisfies (H1), i.e., $Y \vdash \neg \alpha$ if and only if $Y \nvdash \alpha$.
Proof. (of Claim 3) For the "only if" direction, suppose $Y \vdash \neg \alpha$. Since $Y$ is consistent, $Y \nvdash \alpha$.
For the "if" direction, suppose $Y \nvdash \alpha$, which means that $\alpha \notin Y$. Since $Y$ is maximal, $Y \cup\{\alpha\}$ is not consistent. So,

$$
Y, \alpha \vdash \neg \alpha .
$$

By Initial Rule,

$$
Y, \neg \alpha \vdash \neg \alpha
$$

By Negation Rule,

$$
Y \vdash \neg \alpha .
$$

This completes our proof of Claim 3 .

Claim $4 Y$ satisfies (H2), i.e., $Y \vdash \forall x \alpha$ if and only if $Y \vdash \alpha[c / x]$ for every constant $c \in L^{\prime}$.
Proof. (of Claim (4) For the "only if" direction, suppose $Y \vdash \forall x \alpha$. Let $c \in L^{\prime}$. Now $[c / x]$ is collision-free in $\alpha$. By Specialisation Rule, $Y \vdash \alpha[c / x]$.

For the "if" direction, suppose $Y \vdash \alpha[c / x]$ for every constant $c \in L^{\prime}$. Let $\alpha \in \mathrm{FO}\left[L_{n}\right]$. So, in particular for $c \in C_{n}$,

$$
\begin{equation*}
Y \vdash \alpha[c / x] . \tag{9}
\end{equation*}
$$

Now, suppose to the contrary that $Y \nvdash \forall x \alpha$. By (H1),

$$
\begin{equation*}
Y \vdash \neg \forall x \alpha . \tag{10}
\end{equation*}
$$

By And Combine Rule on (9) and (10),

$$
\begin{equation*}
Y \vdash \neg \forall x \alpha \wedge \alpha[c / x] \tag{11}
\end{equation*}
$$

Note that the right side of (11) is simply $\alpha^{x}$. So, $Y \vdash \alpha^{x}$.
However, $\neg \alpha^{x} \in Y$. So, $Y \vdash \neg \alpha^{x}$, which means $Y$ is inconsistent. This contradicts the fact that $Y \in \mathcal{F}$, which means that $Y$ is consistent. Therefore, $Y \vdash \forall x \alpha$, and this completes the proof of Claim 4.

Claims 3 and 4 state that $Y$ is Henkin, and this completes our proof of Lemma 8.6.

Lemma 8.7 Every Henkin set is satisfiable.
Proof. This will be proved in the exercise.

## 4 The completeness theorem for FO

Theorem 8.8 (Gödel's completeness theorem) $X \models \alpha$ if and only if $X \vdash \alpha$.
Proof. The "if" direction is the soundness theorem. For the "only if" direction, we show if $X \nvdash \alpha$, then $X \not \vDash \alpha$. Suppose $X \nvdash \alpha$. Then, $X \cup\{\neg \alpha\}$ is consistent ${ }^{\prime}$. By Lemmas 8.6 and 8.7, there is a Henkin set $Y \supseteq X \cup\{\neg \alpha\}$ and $Y$ is satisfiable. This means $X \cup\{\neg \alpha\}$ is satisfiable, and therefore, $X \not \models \alpha$.

[^7]
## Exercises

In questions (1)-(8) below we are going to show that every Henkin set is satisfiable. Let $Y$ be a Henkin set and $C$ be the set of all the constants that appear in $Y$. We associate each constant $c \in C$ with an element $a_{c}$. Different constants $c \neq c^{\prime}$ are associated with different elements $a_{c} \neq a_{c^{\prime}}$. Consider the set $U$.

$$
U:=\left\{a_{c} \mid c \in C\right\}
$$

Define a relation $\sim$ on $U$ as follows.

$$
a_{c} \sim a_{c^{\prime}} \quad \text { if and only if } \quad Y \vdash c \approx c^{\prime}
$$

(1) Prove that $\sim$ is an equivalence relation on $U$. (Note this is not a trivial question.)

Let $\left[a_{c}\right]$ denote the equivalence class of $a_{c}$ w.r.t. $\sim$. The structure $\mathcal{A}=\left(A, R_{1}, \ldots, f_{1}, \ldots, c_{1}, \ldots\right)$ is defined as follows.

- $A=\left\{\left[a_{c}\right] \mid a_{c} \in U\right\}$.
- $c_{i}=\left[a_{c_{i}}\right]$.
- $R_{i}\left(\left[a_{c_{1}}\right], \ldots,\left[a_{c_{n}}\right]\right)$ if and only if $Y \vdash R\left(c_{1}, \ldots, c_{n}\right)$.
- $f_{i}\left(\left[a_{c_{1}}\right], \ldots,\left[a_{c_{n}}\right]\right)=\left[a_{c}\right]$, if $Y \vdash f_{i}\left(c_{1}, \ldots, c_{n}\right) \approx c$.
(2) Prove that the definition of $R_{i}$ is well defined.

That is, if $\left(\left[a_{c_{1}}\right], \ldots,\left[a_{c_{n}}\right]\right)=\left(\left[a_{d_{1}}\right], \ldots,\left[a_{d_{n}}\right]\right)$, then,

$$
Y \vdash R\left(c_{1}, \ldots, c_{n}\right) \quad \text { if and only if } \quad Y \vdash R\left(d_{1}, \ldots, d_{n}\right)
$$

(3) Prove that the definition of $f_{i}$ is well defined.

That is,

- for every $c_{1}, \ldots, c_{n} \in C$, there is $c$ such that $Y \vdash f_{i}\left(c_{1}, \ldots, c_{n}\right) \approx c$, and
- if $\left(\left[a_{c_{1}}\right], \ldots,\left[a_{c_{n}}\right]\right)=\left(\left[a_{d_{1}}\right], \ldots,\left[a_{d_{n}}\right]\right)$, then $f_{i}\left(\left[a_{c_{1}}\right], \ldots,\left[a_{c_{n}}\right]\right)=f_{i}\left(\left[a_{d_{1}}\right], \ldots,\left[a_{d_{n}}\right]\right)$.

Consider the following valuation val : VAR $\rightarrow A$, where $\operatorname{val}(x)=\left[a_{c}\right]$, where $Y \vdash x \approx c$.
(4) Prove that val is well defined.
(5) Prove that for every term $t$, if $Y \vdash t \approx c$, then $t^{\mathcal{A}}[\mathrm{val}]=\left[a_{c}\right]$.

Next, we will show that $Y$ is satisfiable, i.e., $(\mathcal{A}$, val $) \models \alpha$, for every $\alpha \in Y$.
(6) Prove that $(\mathcal{A}$, val $) \mid=s \approx t$, for every atomic formula $s \approx t \in Y$.
(7) Prove that $(\mathcal{A}, \mathrm{val}) \vDash R\left(s_{1}, \ldots, s_{n}\right)$, for every atomic formula $R\left(s_{1}, \ldots, s_{n}\right) \in Y$.
(8) Prove that $(\mathcal{A}, \mathrm{val}) \mid=\alpha$, for every $\alpha \in Y$, and hence, $Y$ is satisfiable.

Compactness theorem states that $X$ is satisfiable if and only if $X$ is finitely satisfiable.
(9) Use the completeness theorem to prove the compactness theorem for FO.

## Lesson 9: Löwenheim-Skolem theorem and categorical sets

Theme: Cardinalities of first-order structures.

## 1 Cardinal numbers

- Two sets $A$ and $B$ have the same cardinality, if there is a bijection from $A$ to $B$, denoted by $|A|=|B|$.
- In the same spirit, $|A| \leqslant|B|$, if there is an injective function from $A$ to $B$.
- $|A|<|B|$, if $|A| \leqslant|B|$ and $|A| \neq|B|$.

For $i \in\{0,1,2, \ldots\}$, we define $\aleph_{i}$ and $\beth_{i}$ as follows.

- Both $\aleph_{0}$ and $\beth_{0}$ denote $\mathbb{N}$.
- For each $i \geqslant 1, \aleph_{i}$ denotes the minimal set such that $\left|\aleph_{i}\right|>\left|\aleph_{i-1}\right|$.
- For each $i \geqslant 1, \beth_{i}$ denotes $2^{\beth_{i-1}}$.

Abusing the notation, we will often regard each $\aleph_{i}$ and $\beth_{i}$ as "cardinalities." So, when we write $A=\aleph_{i}$ and $A=\beth_{i}$, we mean $|A|=\left|\aleph_{i}\right|$ and $|A|=\left|\beth_{i}\right|$, respectively. Likewise, such abuse also applies for $<$ and $\leqslant$ comparisons.

Theorem 9.1 (Cantor's theorem) $|A|<\left|2^{A}\right|$, for every set $A$.
Cantor's theorem implies that the sequence $\beth_{0}, \beth_{1}, \beth_{2}, \ldots$ will never end, which in turn implies that the sequence $\aleph_{0}, \aleph_{1}, \aleph_{2}, \ldots$ will also never end. The so called Continuum Hypothesis (CH) states the following.

$$
\aleph_{1}=\beth_{1}
$$

## 2 Löwenheim-Skolem theorem

Theorem 9.2 (Löwenheim-Skolem theorem) If $X \subseteq \mathrm{FO}[L]$ is satisfiable, and $L$ is countable, then $X$ is satisfied by a countable structure.

Theorem 9.3 (Downward Löwenheim-Skolem theorem) If $X \subseteq \mathrm{FO}[L]$ is satisfiable, and $L$ is of cardinality $\lambda$, then $X$ is satisfied by a structure with cardinality $\leqslant \lambda$.

Theorem 9.4 (Upward Löwenheim-Skolem-Tarski theorem) If $X \subseteq \mathrm{FO}[L]$ is satisfiable, and $L$ is of cardinality $\lambda$, then for every cardinal number $\kappa \geqslant \lambda$, there is a structure with cardinality $\kappa$ that satisfies $X$.

## Corollary 9.5

(a) Let $X \subseteq \mathrm{FO}[L]$, where $L$ is countable. If $X$ has an infinite model, then $X$ has models of every infinite cardinality.
(b) Let $\mathcal{A}$ be an infinite structure for a countable vocabulary $L$. Then, for every infinite cardinal $\lambda$, there is a structure $\mathcal{B}$ of cardinality $\lambda$, such that $\mathcal{A} \equiv \mathcal{B}$.

## 3 Categorical sets

A set $X$ is categorical, if every two models of $X$ is isomorphic.
Proposition 9.6 If $X$ has an infinite model, then $X$ is not categorical.
A theory $T$ is $\aleph_{0}$-categorical, if all infinite countable models of $T$ are isomorphic. A theory $T$ is $\kappa$-categorical, if all models of $T$ of cardinality $\kappa$ are isomorphic.

Theorem 9.7 (Loś-Vaught Test) Let $T$ be a theory over a countable vocabulary. Assume that $T$ has no finite models.
(a) If $T$ is $\aleph_{0}$-categorical, then $T$ is complete.
(b) If $T$ is $\kappa$-categorical for some infinite cardinal $\kappa$, then $T$ is complete.

## 4 The ZFC system

The ZFC system (Zermelo-Fraenkel-Axiom of Choice) is a set of axioms that describe mathematics being founded entirely on set theory. The vocabulary has only one binary relation $\varepsilon$, which intuitively represents the standard relation $\epsilon$.

The ZFC system consists of the following axioms.
Extensionality axiom: $\forall x \forall y(\forall z(z \varepsilon x \leftrightarrow z \varepsilon y) \rightarrow x \approx y)$.
Intuitively, this means that if $x$ and $y$ have the same members, then $x$ and $y$ are the same.
Separation axioms: $\forall x_{1} \cdots \forall x_{n} \forall x \exists y \forall z\left(z \varepsilon y \quad \leftrightarrow \quad\left(z \varepsilon x \wedge \varphi\left(z, x_{1}, \ldots, x_{n}\right)\right)\right)$.
The formula $\varphi$ is over the vocabulary $\{\varepsilon\}$. Intuitively, it means that for a set $x$, and a "property" $\varphi$, there is a set $y$ that contains precisely the elements in $x$ that satisfies $\varphi$.
Pairing axiom: $\forall x \forall y \exists z \forall w(w \varepsilon z \quad \leftrightarrow \quad(w \approx x \vee w \approx y))$.
Intuitively, it means that for every two sets $x$ and $y$, the set $\{x, y\}$ exists.
Union axiom: $\forall x \exists y \forall z(z \varepsilon y \quad \leftrightarrow \quad \exists w(w \varepsilon x \wedge z \varepsilon w))$.
Intuitively, it means that for every set $x$, the set $\bigcup x$ exists.
Power set axiom: $\forall x \exists y \forall z(z \varepsilon y \quad \leftrightarrow \quad \forall w(w \varepsilon z \rightarrow w \varepsilon x))$.
Intuitively, it means that for every set $x$, the set $2^{x}$ exists.
Infinity axiom: $\exists x(\underline{\emptyset \varepsilon x} \wedge \forall y(y \varepsilon x \rightarrow \underline{y \cup\{y\} \varepsilon x}))$
Intuitively, it means that there is an infinite set containing $\hat{0}, \hat{1}, \hat{2}, \ldots$, where $\hat{0}$ stands for $\emptyset$, $\hat{1}$ stands for $\{\emptyset\}$, and $\hat{n}=\{\hat{1}, \ldots, \widehat{n-1}\}$.
Note that both $\emptyset \varepsilon x$ and $\underline{y \cup\{y\} \varepsilon x}$ are abbreviations, where $\underline{\emptyset \varepsilon x}$ represents " $\emptyset \in x$," i.e., $\exists y(\forall z \neg(z \varepsilon y) \wedge y \varepsilon x)$, and $\underline{y \cup\{y\} \varepsilon x}$ represents " $y \cup\{y\} \in x$," which can be written in a similar manner.
Replacement axioms: $\forall x_{1} \cdots \forall x_{n}$
$\forall x \exists^{=1} y \varphi\left(x, y, x_{1}, \ldots, x_{n}\right) \quad \rightarrow \quad \forall u \exists v \forall y\left(y \varepsilon v \leftrightarrow \exists x\left(\varphi\left(x, y, x_{1}, \ldots, x_{n}\right) \wedge x \varepsilon u\right)\right)$
Intuitively, this means that if for parameters $x_{1}, \ldots, x_{n}$, the formula $\varphi\left(x, y, x_{1}, \ldots, x_{n}\right)$ defines a map $x \mapsto y$, then the range of a set is again a set.

Axiom of choice: $\forall x$

$$
\left(\begin{array}{l}
\left.\underline{\emptyset \nexists x} \wedge \forall u \forall v\binom{u \varepsilon x \wedge v \varepsilon x \wedge u \nsim v}{\rightarrow \underline{u \cap v \approx \emptyset}}\right) \rightarrow \exists y \forall w\left(w \varepsilon x \rightarrow \exists^{=1} z(\underline{z \varepsilon w \cap y)})\right)
\end{array}\right.
$$

This states axiom of choice. As before, those underline represent abbreviations of first-order formula describing their respective intuitive meanings.

Remark 9.8 Assuming the consistency of ZFC, the following holds.

- $\mathrm{ZFC}+\mathrm{CH}$ is consistent (Gödel 1940).
- $\mathrm{ZFC}+\neg \mathrm{CH}$ is consistent (Cohen 1963).

That is, both CH and its negation cannot be proved from ZFC, provided that ZFC is consistent.

## 5 Skolem paradox

It is generally accepted that ZFC is consistent, although there is no way to prove it. In the following we are going to show an application of Löwenheim-Skolem theorem that yields a seemingly absurd result, called Skolem paradox.

Assuming its consistency, by Löwenheim-Skolem theorem, ZFC has a countable structure $\mathcal{A}=\left(A, \varepsilon^{\mathcal{A}}\right)$. By the infinity axiom, there is an element $x \in A$ such that $x$ is an infinite set. By power set axiom, $2^{x} \in A$. Now, by Cantor's theorem, we know that $2^{x}$ is uncountable. However, since $A$ is countable, the set of elements related to $2^{x}$ (by relation $\varepsilon$ ) must be countable too (since they all must come from $A$ ). Does this mean that Cantor's theorem and LöwenheimSkolem theorem contradict each other? Or, that ZFC is inconsistent?

## Lesson 10: Gödel's incompleteness theorem, part. 1*

Theme: Robinson arithmetic and its arithmetization.

In this lesson and the next, we are only dealing with logic over vocabulary $\{\tilde{0}, \operatorname{Succ},+, \cdot\}$, where $\tilde{0}$ is a constant symbol intended to represent the number zero; Succ is a unary function intended to represent +1 , i.e., $\operatorname{Succ}(x)=x+1$; and finally, + and $\cdot$ are intended to represent the standard addition and multiplication operands.

## 1 Robinson arithmetic

Robinson's arithmetic is a theory Q derived from the following axioms.
(Q1) $\forall x(\operatorname{Succ}(x) \not \approx 0)$.
(Q2) $\forall x \forall y(\operatorname{Succ}(x) \approx \operatorname{Succ}(y) \rightarrow x \approx y)$.
(Q3) $\forall x(x \not \approx \tilde{0} \rightarrow \exists y x \approx \operatorname{Succ}(y))$.
(Q4) $\forall x(x+\tilde{0} \approx x)$.
(Q5) $\forall x \forall y(x+\operatorname{Succ}(y) \approx \operatorname{Succ}(x+y))$.
(Q6) $\forall x(x \cdot \tilde{0} \approx \tilde{0})$.
(Q7) $\forall x \forall y(x \cdot \operatorname{Succ}(y) \approx(x \cdot y)+x)$.
Note that by its definition, Q is a finitely axiomatizable theory, and that Q is a proper subtheory of $\operatorname{Th}(\mathcal{N})$, where $\mathcal{N}$ is the standard structure $\mathcal{N}=(\mathbb{N}, 0$, Succ,,$+ \cdot)$. What we call number theory usually refers to $\operatorname{Th}(\mathcal{N})$. Note that $\operatorname{Th}(\mathcal{N})$ is much stronger than Q . For example, $\forall x x \not \approx \operatorname{Succ}(x)$ is not provable in Q .

In the following, we will often write $x \leqslant y$ as an abbreviation for $\exists z x+z \approx y$, and $x<y$ for $x \leqslant y \wedge x \not \approx y$.

Remark 10.1 For the rest of this lesson and the next, the proof system will always be in a theory $T \supseteq$ Q, with the sentences (Q1)-(Q7) above being included as axioms of $T$.

## 2 Arithmetization

We denote the set Symb $=\left\{\neg, \wedge, \forall,(),, \approx, \tilde{0}\right.$, Succ $\left.,+, \cdot, x_{0}, x_{1}, x_{2}, \ldots\right\}$ In principle, we can assume that every formula is a string with symbols from Symb, and every proof is a sequence of formulas with a comma in between two formulas.

In this section we are going to see how to encode a formula $\varphi$ as a number, and hence, a proof as a number too. For this purpose, we assign each symbol $s \in \operatorname{Symb} \cup\{$,$\} a number \sharp$ s as follows.

| s | $\neg$ | $\wedge$ | $\forall$ | $($ | $)$ | $\approx$ | $\tilde{0}$ | Succ | + | . | , | $x_{0}$ | $x_{1}$ | $x_{2}$ | $\ldots$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\sharp \mathrm{~s}$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | $\ldots$ |

Let $\left\{p_{0}, p_{1}, \ldots\right\}$ be the set of all prime numbers with $p_{0}<p_{1}<\cdots$.

[^8]For a string $\operatorname{str}=s_{0} \cdots s_{n}$ with each symbol $s_{i}$ coming from Symb $\cup\{$,$\} , the Gödel number of$ str, denoted by $\sharp$ str is the number:

$$
\sharp s t r \quad:=p_{0}^{\sharp s_{0}} p_{1}^{\sharp s_{1}} \cdots p_{n}^{\sharp s_{n}}
$$

The Gödel numbers of a formula $\varphi$ and a proof $\xi$ are defined as $\sharp \varphi$ and $\sharp \xi$, respectively, where $\varphi$ and $\xi$ are viewed as a string of symbols coming from Symb $\cup\{$,$\} .$

## Remark 10.2

- We can write a computer program IsFormula for the following task.
- Input: A positive number $N$.
- Output: Output True, if $N$ "represents" a formula, i.e., $N$ is the Gödel number of a formula. Otherwise, output False.

Likewise, we can write a program ISSENTENCE that checks whether an input number $N$ represents a sentence.

- We can write a computer program IsProofq for the following task.
- Input: A positive number $N$.
- Output: Output True, if $N$ represents a proof in Q. Otherwise, output False.
- We can write a computer program IsProof $\mathrm{OF}_{\mathrm{Q}}$ for the following task.
- Input: Two positive numbers $N$ and $M$.
- Output: Output True, if $N$ represents a proof, $M$ represents a formula, and $N$ is a proof of $M$ in Q . Otherwise, output False.

Definition 10.3 Let $T$ be a theory such that $T=\mathrm{Cn}(\Sigma)$. We say that $T$ is recursively axiomatizable, if there is a computer program IsAxiom $_{T}$ for the following task.

- Input: A positive number $N$.
- Output: Output True, if $N$ represents an axiom in $T$, i.e., $N$ represents a sentence $\Sigma$. Otherwise, output False.


## Remark 10.4

- We can write a computer program IsProof $_{\text {PF }}^{T}$ for the following task.
- Input: Two positive numbers $N$ and $M$.
- Output: Output True, if $N$ represents a proof in $T, M$ represents a formula, and $N$ is a proof of $M$ in $T$. Otherwise, output False.


## 3 A sketch proof of the incompleteness theorem

Gödel's incompleteness theorem states that for every consistent and recursively axiomatizable theory $T \supseteq Q$, there is a sentence $\Psi$ such that neither $\Psi$ nor $\neg \Psi$ are provable in $T$.

For an integer $N \geqslant 0$, let $\underline{N}$ denote the following term:

$$
\underline{N}:=\underbrace{\operatorname{Succ} \cdots \operatorname{Succ}}_{N \text { times }}(\tilde{0})
$$

Now, suppose that instead of being a computer program, the boolean function $\operatorname{IsPROOFOF}_{T}(y, x)$ is a first-order formula that indicates $y$ is a proof of $x$ in $T$. So, for every sentence $\varphi$,

$$
\begin{equation*}
T \vdash \varphi \quad \text { if and only if } T \vdash \exists y \operatorname{IsProofOF}_{T}(y, \sharp \varphi) . \tag{1}
\end{equation*}
$$

Consider a sentence $\Psi$ such that

$$
\begin{equation*}
T \vdash \Psi \leftrightarrow\left(\forall y \neg \operatorname{IsPROOFOF}_{T}(y, \underline{\sharp \Psi})\right) \tag{2}
\end{equation*}
$$

which is an abbreviation for:

$$
\begin{align*}
& T \vdash \Psi \rightarrow\left(\forall y \neg \operatorname{IsPROOFOF}_{T}(y, \sharp \Psi)\right)  \tag{3}\\
& T \vdash\left(\forall y \neg \operatorname{IsPROOFOF}_{T}(y, \underline{\sharp \Psi)}) \rightarrow \Psi\right. \tag{4}
\end{align*}
$$

From Equation (4), we can derive $\rfloor^{\dagger}$

$$
\begin{equation*}
T \vdash \neg \Psi \rightarrow \neg\left(\forall y \neg \operatorname{IsPROOFOF}_{T}(y, \sharp \Psi)\right) \tag{5}
\end{equation*}
$$

We now argue that neither $T \vdash \Psi$ nor $T \vdash \neg \Psi$.

- Suppose $T \vdash \Psi$.

Applying modus ponens on $T \vdash \Psi$ and Equation (3), we have ${ }^{\ddagger}$

$$
T \vdash \forall y \neg \operatorname{IsPROOFOF}_{T}(y, \underline{\sharp \Psi})
$$

which by Equation (1), means $\Psi$ is not provable in $T$, contradicting supposition $T \vdash \Psi$.

- Suppose $T \vdash \neg \Psi$.

Applying modus ponens on $T \vdash \neg \Psi$ and Equation (5),

$$
T \vdash \neg \forall y \neg \operatorname{IsPROOFOF}_{T}(y, \sharp \Psi)
$$

which is equivalent to

$$
T \vdash \exists y \operatorname{IsProofoF}_{T}(y, \sharp \Psi)
$$

By Equation (1), it means $T \vdash \Psi$, contradicting the consistency of $T$.
Therefore, neither $\Psi$ nor $\neg \Psi$ are provable in $T$, hence the incompleteness of $T$.
In this lesson and the next, we focus on the following two tasks in order to complete our proof above.
(a) Find the formula for $\operatorname{IsProofOF}_{T}(y, x)$ using the vocabulary $\{\tilde{0}, \operatorname{Succ},+, \cdot\}$.
(b) Find the statement $\Psi$.

[^9]
## Appendix: The formal definition of recursive functions

We will formalize the notion of recursive functions, which are equivalent to the notion of computable functions. Recall that $\mathbb{N}=\{0,1,2, \ldots\}$. Let $\mathbf{F}_{n}$ be the set of all functions from $\mathbb{N}^{n}$ to $\mathbb{N}$, and let $\mathbf{F}:=\bigcup_{n \geqslant 1} \mathbf{F}_{n}$.
$\mu$-recursive functions, or shortly, recursive functions, are functions that are built inductively as follows.

- Base case: All three kinds of functions below are recursive.

Constant function: $f\left(v_{1}, \ldots, v_{n}\right)=0$.
Successor function (on the $i$-component): $f\left(v_{1}, \ldots, v_{n}\right)=\operatorname{Succ}\left(v_{i}\right)$.
Projection function (to the $i$-component): $f\left(v_{1}, \ldots, v_{n}\right)=v_{i}$.

- Induction step: All the functions built up from recursive functions using one of the rules below are recursive functions.

Composition (Oc). If $h \in \mathbf{F}_{m}$ and $g_{1}, \ldots, g_{m} \in \mathbf{F}_{n}$ are recursive, then the following function $f$ is also recursive. For every $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in \mathbb{N}^{n}$,

$$
f(\bar{a}):=h\left(g_{1}(\bar{a}), \ldots, g_{m}(\bar{a})\right) .
$$

We usually write $h\left[g_{1}, \ldots, g_{m}\right]$ to denote the function $f$ constructed above.
Primitive recursion ( $\mathbf{O p}$ ). If $g \in \mathbf{F}_{n}$ and $h \in \mathbf{F}_{n+2}$ are recursive functions, then so is $f \in \mathbf{F}_{n+1}$, defined as follows. For every $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in \mathbb{N}^{n}$,

$$
\begin{aligned}
f(\bar{a}, 0) & :=g(\bar{a}) \\
f(\bar{a}, \operatorname{Succ}(b)) & :=h(\bar{a}, b, f(\bar{a}, b))
\end{aligned}
$$

$\mu$ operation $(\mathbf{O} \mu)$. Let $g \in \mathbf{F}_{n+1}$ be such that for every $\bar{a} \in \mathbb{N}^{n}$, there is $b \in \mathbb{N}$, where $g(\bar{a}, b)=0$. If $g$ is computable, then so is the following function $f$. For every $\bar{a}=$ $\left(a_{1}, \ldots, a_{n}\right) \in \mathbb{N}^{n}$,

$$
f(\bar{a}):=\text { the smallest } b \text { such that } g(\bar{a}, b)=0
$$

We write $f(\bar{a}):=\mu b[g(\bar{a}, b)=0]$ to denote the function $f$ as constructed above.
A recursive function obtained without using the $\mathbf{O} \mu$ rule is called a primitive recursive function.

## Example 10.5

- The function $f_{\text {add }}(a, b)=a+b$ is recursive by an application of $\mathbf{O p}$ rule.

$$
f_{\text {add }}(a, 0):=a \quad \text { and } \quad f_{\text {add }}\left(a, \operatorname{Succ}(b):=\operatorname{Succ}\left(f_{\text {add }}(a, b)\right)\right.
$$

- The functions $f_{\text {mul }}(a, b)=a \cdot b$ and $f_{\text {exp }}(a, b)=a^{b}$ are recursive.

$$
\begin{aligned}
& f_{\text {mul }}(a, 0):=0 \quad \text { and } \quad f_{\text {mul }}(a, \operatorname{Succ}(b)):=f_{\text {add }}\left(b, f_{\text {mul }}(a, b)\right) \\
& f_{\text {exp }}(a, 0):=\operatorname{Succ}(0) \quad \text { and } \quad f_{\text {exp }}(a, \operatorname{Succ}(b)):=f_{\text {mul }}\left(a, f_{\text {exp }}(a, b)\right)
\end{aligned}
$$

- The function $f_{a b s}(a, b):=|a-b|$ is recursive.
- The function $f_{\text {div }}(a, b):=0$, if $b$ divides $a$, and 1 , otherwise, is recursive.
- The function $f_{\text {prime }}(n):=p_{n}$, where $p_{n}$ is the $n^{\text {th }}$ prime number, is recursive.

Theorem 10.6 (Church-Turing thesis) If a function $f$ is computable (by a "computer program"), then it is also (i) computable in $\lambda$-calculus; (ii) computable by a Turing machine; (iii) $\mu$-recursive.

In fact, the notions of $\lambda$-calculus, Turing machines, and $\mu$-recursive are all equivalent. That is, a function is computable in $\lambda$-calculus if and only if it is computable by a Turing machine if and only if it is $\mu$-recursive.

In his original paper Gödel showed the following.

- An explicit construction of the primitive recursive function for $\operatorname{IsProof} \operatorname{OF}(x, y)$ as specified in Remark 10.4 .
- For every primitive recursive function $f: \mathbb{N}^{n} \rightarrow \mathbb{N}$, there is a formula $\alpha\left(x_{1}, \ldots, x_{n}, y\right)$ over vocabulary $\{$ Succ,,,$+ \cdot \tilde{0}\}$ such that

$$
\begin{equation*}
f\left(a_{1}, \ldots, a_{n}\right)=b \text { if and only if } T \vdash \alpha\left(\underline{a_{1}}, \ldots, \underline{a_{n}}, \underline{b}\right) \tag{6}
\end{equation*}
$$

An explicit formula for IsProofof is conceptually not difficult, but long and tedious. In this class, having convinced ourselves that we can write a computer program for $\operatorname{ISProofOF}(x, y)$, we can invoke Church-Turing thesis to arrive at the conclusion that $\operatorname{IsProofOF}(x, y)$ is recursive. On the other hand, converting a recursive function $f$ to a formula $\alpha$ as specified in Equation (6) involves a very nice piece of mathematics and this will be our focus in our next lesson.

[^10]
## Lesson 11: Gödel's incompleteness theorem, part. 2

Theme: Representability of recursive functions, fixed point lemma and Gödel's first incompleteness theorem.

## 1 Some preliminary results on Robinson's arithmetic Q

Recall that all our formulas are over the vocabulary $L_{a r}=\{\tilde{0}, \operatorname{Succ},+, \cdot\}$, and that for every integer $n \geqslant 0$, we write $\underline{n}$ to denote the term $\operatorname{Succ}^{n}(\tilde{0})$, i.e., applying Succ on $\tilde{0}$ for $n$ number of times. For a vector $\bar{a}=\left(a_{1}, \ldots, a_{n}\right)$ of integers, we will write $\underline{\bar{a}}$ to denote $\left(\underline{a_{1}}, \ldots, \underline{a_{n}}\right)$.

By a straightforward induction on $n$ and $m$, it is not that difficult to show that for every integers $n, m \geqslant 0$, the following holds.
$(\mathrm{C} 1) \mathrm{Q} \vdash(\operatorname{Succ}(\underline{m})+\underline{n}) \approx(\underline{m}+\operatorname{Succ}(\underline{n}))$.
$(\mathrm{C} 2) \mathrm{Q} \vdash(\underline{m}+\underline{n}) \approx \underline{m+n}$.
(C3) $\mathrm{Q} \vdash(\underline{m} \cdot \underline{n}) \approx \underline{m \cdot n}$.
(C4) $\mathrm{Q} \vdash \underline{n} \not \approx \underline{m}$, for every $n \neq m$.
(C5) $\mathrm{Q} \vdash \underline{m} \leqslant \underline{n}$, for every $m \leqslant n$.
Recall that our vocabulary $L_{a r}$ does not include $\leqslant$. The formula $\underline{m} \leqslant \underline{n}$ is actually an abbreviation for $\exists z \underline{m}+z \approx \underline{n}$.
(C6) $\mathrm{Q} \vdash \neg(\underline{m} \leqslant \underline{n})$, for every $m \nless n$.
(C7) $\mathrm{Q}, x \leqslant \underline{n} \vdash(x \approx \tilde{0}) \vee(x \approx \underline{1}) \vee \cdots \vee(x \approx \underline{n})$.
(C8) $\mathrm{Q} \vdash(x \leqslant \underline{n}) \vee(\underline{n} \leqslant x)$.
All these statements show that the natural meaning of the standard operations like addition and multiplication are provable in $\mathbf{Q}$, and hence, in any extension $T \supseteq \mathbf{Q}$.

## Definition 11.1

- A formula $\varphi$ is called a $\Delta_{0}$-formula, if all its quantifiers are bounded quantifiers, i.e., of the form $(\forall x \leqslant t) \alpha$, where $t$ is a term over $L_{a r}$.
Intuitively $(\forall x \leqslant t) \alpha$ states "for every $x \leqslant t$, the formula $\alpha$ holds."
- A formula $\varphi$ is called a $\Sigma_{1}$-formula, if it is of the form $\exists \bar{x} \psi$, where $\psi$ is a $\Delta_{0}$-formula.
- A formula $\varphi$ is called a $\Pi_{1}$-formula, if it is of the form $\forall \bar{x} \psi$, where $\psi$ is a $\Delta_{0}$-formula.

Proposition 11.2 Let $t$ be a term over $L_{\text {ar }}$ with free variables $x_{1}, \ldots, x_{n}$. For a valuation val $: V A R \rightarrow \mathbb{N}$, consider the substitution sub $:=\left[x_{1} / \underline{\operatorname{val}\left(x_{1}\right)}, \ldots, x_{n} / \underline{\text { val }\left(x_{n}\right)}\right]$. Then,

$$
\begin{array}{ll}
t^{\mathcal{N}}[v a l]=m & \text { if and only if } \quad Q \vdash t[s u b] \approx \underline{m} \\
t^{\mathcal{N}}[v a l] \leqslant m & \text { if and only if } \quad Q \vdash t[s u b] \leqslant \underline{m}
\end{array}
$$

Proof. By straightforward induction on $t$ together with (C1)-(C8) above.
Theorem 11.3 below will be very useful. It states that in order to check whether a $\Delta_{0}$-sentence $\varphi$ is provable in $Q$, it is sufficient to check whether it holds in $\mathcal{N}$. In other words, instead of looking for a proof of $\varphi$, we simply checks whether it holds in $\mathcal{N}$, which is a more convenient and intuitive system to work with.

Theorem 11.3 For every $\Delta_{0}$-formula $\varphi(\bar{x})$, where $\bar{x}=\left(x_{1}, \ldots, x_{n}\right)$, the following holds. For every $\bar{a}=\left(a_{1}, \ldots, a_{n}\right) \in \mathbb{N}^{n}$ :

$$
\mathcal{N} \vDash \varphi(\underline{\bar{a}}) \quad \text { if and only if } Q \vdash \varphi(\underline{\bar{a}}) .
$$

Proof. The proof is by induction on $\varphi$. The base case, when the atomic formula of the form $s \approx t$, can be deduced directly from Proposition 11.2 .

The induction step consists of three cases.
Case 1: $\varphi(\bar{x})$ is $\neg \alpha(\bar{x})$.
$\mathcal{N} \models \varphi(\bar{a})$ if and only if $\mathcal{N} \not \models \alpha(\bar{a})$, if and only if $\mathrm{Q} \nvdash \alpha(\underline{\bar{a}})$, if and only if $\mathrm{Q} \vdash \varphi(\underline{\bar{a}})$, with the second "if and only if" coming from the induction hypothesis.
Case 2: $\varphi(\bar{x})$ is $\alpha_{1}(\bar{x}) \wedge \alpha_{2}(\bar{x})$.
$\mathcal{N} \models \varphi(\bar{a})$ if and only if $\mathcal{N} \models \alpha_{1}(\bar{a}) \wedge \alpha_{2}(\bar{a})$, if and only if $\mathcal{N} \models \alpha_{1}(\bar{a})$ and $\mathcal{N} \models \alpha_{2}(\bar{a})$, if and only if $\mathrm{Q} \vdash \alpha_{1}(\underline{\bar{a}})$ and $\mathrm{Q} \vdash \alpha_{2}(\underline{\bar{a}})$, if and only if $\mathrm{Q} \vdash \varphi(\underline{\bar{a}})$, with the third "if and only if" coming from the induction hypothesis.
Case 3: $\varphi(\bar{x})$ is $\forall z \leqslant t \alpha(\bar{x}, z)$.
Let val denote the valuation that maps $x_{i}$ to $a_{i}$, and sub denote the substitution that substitute $x_{i}$ with $\underline{a_{i}}$. Let $M=t^{\mathcal{N}}[$ val $]$. By Proposition 11.2 , we have $\mathrm{Q} \vdash t \approx \underline{M}$. $\mathcal{N} \models \varphi(\bar{a})$ if and only if for every $m \leqslant M$,

$$
\mathcal{N},[\operatorname{val}, z \mapsto m] \quad \models(\bar{a}, z),
$$

which holds, if and only if for every $m \leqslant M$,

$$
\mathrm{Q} \vdash \alpha[s u b, z / \underline{m}],
$$

which holds, if and only if

$$
\mathrm{Q}, z \leqslant \underline{M} \vdash \alpha[s u b, z],
$$

which holds, if and only if

$$
\mathrm{Q} \vdash(\forall z \leqslant \underline{M}) \alpha(\bar{x}, z),
$$

which holds, if and only if

$$
\mathrm{Q} \vdash(\forall z \leqslant t) \alpha(\bar{x}, z) .
$$

The third "if and only if" comes from the induction hypothesis, while the fourth is from (C5) and (C7). The fifth comes from the fact that $(\forall z \leqslant \underline{M}) \alpha(\bar{x}, z)$ is an abbreviation of $\forall z(z \leqslant \underline{M} \rightarrow \alpha(\bar{x}, z))$. The last one comes from $\mathrm{Q} \vdash t \approx \underline{M}$.

## 2 Representable functions

In the following let $\bar{x}$ be a vector of variables, and $\bar{a}$ be a vector of natural numbers with the same length as $\bar{x}$.

Representable functions in a theory $T \supseteq \mathbf{Q}$. A function $f: \mathbb{N}^{k} \rightarrow \mathbb{N}$ is called representable in a theory $T \supseteq \mathbf{Q}$, if there is a formula $\varphi(\bar{x}, y)$ such that $f(\bar{a})=m$ if and only if $T \vdash \varphi(\underline{\bar{a}}, \underline{m})$. Note that this is equivalent to saying that $f(\bar{a})=m$ if and only if $T \vdash y \approx \underline{m} \leftrightarrow \varphi(\underline{\bar{a}}, y)$.

It is $\Sigma_{1}$-representable, if the formula $\varphi(\bar{x})$ is $\Sigma_{1}$-formula, and the formula $\varphi$ is called the representation formula for $f$.

Likewise, a relation $R \subseteq \mathbb{N}^{k}$ is called representable in a theory $T \supseteq \mathrm{Q}$, if there is a formula $\varphi(\bar{x})$ such that if $\bar{a} \in R$, then $T \vdash \varphi(\underline{\bar{a}})$; and if $\bar{a} \notin R$, then $T \vdash \neg \varphi(\underline{\bar{a}})$.

Arithmetical functions (functions representable in $\mathcal{N}$ ). A function $f: \mathbb{N}^{k} \rightarrow \mathbb{N}$ is called arithmetical, or representable in $\mathcal{N}$, if there is a formula $\varphi(\bar{x}, y)$ such that $f(\bar{a})=m$ if and only if $\mathcal{N} \vDash \varphi(\underline{\bar{a}}, \underline{m})$. The notions of $\Sigma_{1}$-representable and $\Pi_{1}$-representable are defined similarly as above.

## 3 Representability of recursive functions

In this section we will show the following theorem.
Theorem 11.4 Every recursive function $f$ is representable by a $\Sigma_{1}$-formula in $Q$.
The proof consists of two steps:
(1) We show that $f$ is representable in $\mathcal{N}$ by a $\Sigma_{1}$-formula, as well as by a $\Pi_{1}$-formula.
(2) We show that it can be represented by a $\Sigma_{1}$-formula in Q .

Representing $f$ in $\mathcal{N}$. The proof is by induction on $f$. The base case is as follows.

- $f$ is the constant zero function, i.e., $f(\bar{x})=0$.

Then, $\varphi(\bar{x}, y):=y \approx \tilde{0}$ is a $\Delta_{0}$-formula representing $f$.

- $f$ is the successor function of one of its component, i.e., $f(\bar{x})=\operatorname{Succ}\left(x_{i}\right)$.

Then, $\varphi(\bar{x}, y):=y \approx \operatorname{Succ}\left(x_{i}\right)$ is a $\Delta_{0}$-formula representing $f$.

- $f$ is the projection function to one of its components, i.e., $f(\bar{x})=x_{i}$.

Then, $\varphi(\bar{x}, y):=y \approx x_{i}$ is a $\Delta_{0}$-formula representing $f$.
The induction step is as follows.

- Functions obtained from applying the composition rule Oc.

Let $f=h\left[g_{1}, \ldots, g_{m}\right]$ be a function from $\mathbb{N}^{n} \rightarrow \mathbb{N}$, i.e., each $g_{i}: \mathbb{N}^{n} \rightarrow \mathbb{N}$ and $h: \mathbb{N}^{m} \rightarrow \mathbb{N}$.
By the induction hypothesis, let $\alpha$ and $\gamma_{i}$ be $\Sigma_{1}$-formulas representing $h$ and $\gamma_{i}$, respectively.
Both $\Sigma_{1}$-formula $\varphi_{1}$ and $\Pi_{1}$-formula $\varphi_{2}$ below represent $f$ in $\mathcal{N}$.

$$
\begin{aligned}
\varphi_{1}(\bar{x}, z) & :=\exists y_{1} \cdots \exists y_{m} \bigwedge_{1 \leqslant i \leqslant m} \gamma_{i}\left(\bar{x}, y_{i}\right) \wedge \alpha\left(y_{1}, \ldots, y_{m}, z\right) \\
\varphi_{2}(\bar{x}, z) & :=\forall u\left(\varphi_{1}(\bar{x}, u) \rightarrow u \approx z\right)
\end{aligned}
$$

- Functions obtained from applying the primitive recursive rule $\mathbf{O p}$.

This is the most challenging part. See the appendix for the details.

- Functions obtained from applying the rule $\mathbf{O} \mu$.

Let $\bar{x}=\left(x_{1}, \ldots, x_{n}\right)$, and let $f(\bar{x}):=\mu y[g(\bar{x}, y)=0]$. By the induction hypothesis, there is a $\Sigma_{1}$-formula $\alpha_{1}(\bar{x}, y, z)$, and $\Pi_{1}$-formula $\alpha_{2}(x, t, z)$ representing $g$ in $\mathcal{N}$.

$$
\begin{array}{ll}
\alpha_{1}(\bar{x}, y, z):=\exists \bar{v} \psi_{1}(\bar{x}, y, z, \bar{v}) & \text { where } \psi_{1} \text { is a } \Delta_{0} \text {-formula } \\
\alpha_{2}(\bar{x}, y, z):=\forall \bar{w} \psi_{2}(\bar{x}, y, z, \bar{w}) & \\
\text { where } \psi_{2} \text { is a } \Delta_{0} \text {-formula }
\end{array}
$$

Consider the formula $\varphi_{1}$ below.

$$
\begin{aligned}
\varphi_{1}(\bar{x}, y) & :=\alpha_{1}(\bar{x}, y, \tilde{0}) \wedge(\forall z<y) \neg \alpha_{2}(\bar{x}, z, \tilde{0}) \\
& :=\exists \bar{v} \psi_{1}(\bar{x}, y, z, \bar{v}) \wedge(\forall z<y) \exists \bar{w} \neg \psi_{2}(\bar{x}, z, \tilde{0}, \bar{w})
\end{aligned}
$$

We have the following identity (can be easily proved) in $\mathcal{N}$ :

$$
\mathcal{N} \models(\forall z<y) \exists u \psi \equiv \exists u^{\prime}(\forall z<y) \neg\left(\forall u<u^{\prime}\right) \neg \psi
$$

Therefore, the following $\Sigma_{1}$-formula $\varphi_{1}^{\prime}$ is equivalent to $\varphi_{1}$ in $\mathcal{N}$.

$$
\begin{aligned}
\varphi_{1}^{\prime}(\bar{x}, y) & :=\exists \bar{v} \psi_{1}(\bar{x}, y, z, \bar{v}) \wedge \exists \bar{w}^{\prime}(\forall z<y) \psi_{2}^{\prime}(\bar{x}, z, \tilde{0}) \quad \text { where } \psi_{2}^{\prime} \text { is } \Delta_{0} \text {-formula } \\
& :=\exists \bar{v} \exists \bar{w}^{\prime}\left(\psi_{1}(\bar{x}, y, z, \bar{v}) \wedge(\forall z<y) \psi_{2}^{\prime}(\bar{x}, z, \tilde{0})\right)
\end{aligned}
$$

Thus, $\varphi_{1}^{\prime}$ is the desired $\Sigma_{1}$-formula representing $f$ in $\mathcal{N}$.
A $\Pi_{1}$-formula $\varphi_{2}$ representing $f$ can be obtained as follows.

$$
\varphi_{2}(\bar{x}, y):=\forall u\left(\varphi_{1}^{\prime}(\bar{x}, u) \rightarrow u \approx y\right)
$$

Representing $f$ in $\mathbf{Q}$. Note that if $f$ is representable in $\mathbf{Q}$, then by monotonicity rule, it is representable in $T \supseteq$ Q.

Let $f: \mathbb{N}^{n} \rightarrow \mathbb{N}$ be a recursive function, and let $\varphi(\bar{x}, y):=\exists \bar{z} \psi(\bar{x}, y, \bar{z})$ be its representing formula in $\mathcal{N}$, where $\psi$ is $\Delta_{0}$-formula. That is, for every $\bar{a} \in \mathbb{N}^{n}$,

$$
f(\bar{a})=b \text { if and only if } \mathcal{N} \models \varphi(\underline{\bar{a}}, \underline{b}) .
$$

We have to show that for every $\bar{a} \in \mathbb{N}^{n}$,

$$
f(\bar{a})=b \text { if and only if } \mathrm{Q} \vdash \varphi(\underline{a}, \underline{b}) .
$$

We start with the "if" part. Suppose $f(\bar{a})=b$. Since $\varphi$ represents $f$, for some $\bar{w}$,

$$
\mathcal{N} \models \psi(\underline{\bar{a}}, \underline{b}, \underline{\bar{w}})
$$

Since $\psi$ is $\Delta_{0}$-formula, by Theorem 11.3 , we have $\mathrm{Q} \vdash \psi(\bar{a}, \underline{b}, \underline{w})$, and hence, $\mathrm{Q} \vdash \exists \bar{z} \psi(\underline{a}, \underline{b}, \bar{z})$.
Now, we show the "only if" part. Suppose for some $\bar{w}, Q \vdash \psi(\underline{\bar{a}}, \underline{b}, \underline{w})$. Since $\mathcal{N} \models \mathrm{Q}$, we have that $\mathcal{N} \models \psi(\underline{\bar{a}}, \underline{b}, \underline{\bar{w}})$, and thus, $\mathcal{N} \models \exists \bar{z} \psi(\underline{\bar{a}}, \underline{b}, \bar{z})$. Therefore, $\mathcal{N} \models \varphi(\underline{\bar{a}}, \underline{b})$. Since $\varphi$ represents $f$, we have $f(\bar{a})=b$. This completes the proof of Theorem 11.4 .

## 4 Fixed point lemma and Gödel's first incompleteness theorem

Recall that in order to prove Gödel's incompleteness theorem, we have to show that:

- Every recursive function is representable in Q.
- For a consistent and recursively axiomatizable theory $T \supseteq \mathbf{Q}$, there is a sentence $\Psi$ such that $T \vdash \Psi \leftrightarrow\left(\forall y \neg \operatorname{IsProofor}_{T}(y, \sharp \Psi)\right)$,

We describe how to achieve the first part in the previous section. We will now describe how to achieve the second part.

For a variable $x$, define the function $\operatorname{SubS}_{x}: \mathbb{N}^{2} \rightarrow \mathbb{N}$ as follows.

$$
\operatorname{SubS}_{x}(N, m):=K
$$

where $K$ is "the formula" obtained by substituting variable $x$ with the term $\underline{m}$ in "formula" $N$. Here, "the formulas" $K$ and $N$ refer to the formulas whose Gödel's numbers are $K$ and $N$, respectively. It is not that difficult to think of a computer program for $\operatorname{SUBS}_{x}$. So, it is also a recursive function, and can be represented in a theory $\mathbf{Q}$, and hence, in any extension $T \supseteq \mathbf{Q}$. Let $\Lambda_{\mathrm{SUBS}_{x}}\left(v_{1}, v_{2}, v_{3}\right)$ be a $\Sigma_{1}$-formula representing $\operatorname{SUBS}_{x}$.

Lemma 11.5 (Fixed point lemma) Let $T \supseteq Q$. For every formula $\alpha(z)$ over vocabulary $\{\tilde{0}$, Succ,,$+ \cdot\}$, there is a formula $\gamma$ such that $T \vdash \gamma \leftrightarrow \alpha(\sharp \gamma)$.

Proof. Due to the definition of $\Lambda_{\text {SUBS }_{x}}\left(v_{1}, v_{2}, v_{3}\right)$, for every formula $\varphi$,

$$
T \vdash \Lambda_{\operatorname{SUBS}_{x}}(\sharp \varphi, \underline{n}, y) \leftrightarrow y \approx \sharp \varphi[x / \underline{n}]
$$

If we plug in $n$ with $\sharp \varphi$ itself,

$$
\begin{equation*}
T \vdash \Lambda_{\mathrm{SuBs}_{x}}(\underline{ }(\underline{\varphi}, \sharp \varphi, y) \leftrightarrow y \approx \sharp \varphi[x / \sharp \varphi] \tag{1}
\end{equation*}
$$

Let $\beta(x)$ be the following formula.

$$
\beta(x):=\forall y\left(\Lambda_{\operatorname{SUBS}_{x}}(x, x, y) \rightarrow \alpha[z / y]\right)
$$

Consider $\gamma:=\beta[x / \sharp \beta]$. That is,

$$
\gamma=\forall y\left(\Lambda_{\operatorname{SUBS}_{x}}(\sharp \beta, \sharp \beta, y) \rightarrow \alpha[z / y]\right)
$$

By (11),

$$
T \vdash \gamma \leftrightarrow \forall y(y \approx \sharp \beta[x / \sharp \beta] \rightarrow \alpha[z / y])
$$

Since $\gamma=\beta[x / \sharp \beta]$,

$$
\begin{aligned}
& T \vdash \gamma \quad \leftrightarrow y(y \approx \sharp \gamma \rightarrow \alpha[z / y]) \\
& T \vdash \gamma \leftrightarrow \alpha(\sharp \gamma)
\end{aligned}
$$

This completes the proof of fixed point lemma.
To wrap up, we state and prove formally Gödel's incompleteness theorem.

Theorem 11.6 (Gödel's incompleteness theorem) For every consistent and recursively axiomatizable theory $T \supseteq Q$, there is a sentence $\Psi$ such that neither $T \vdash \Psi$ nor $T \vdash \neg \Psi$.

Proof. Since $T$ is recursively axiomatizable theory, we have a "computer program" on an input proof $y$, output $x$, which represents the conclusion of the proof $y$. By Church-Turing thesis, every "computer program" is equivalent to a recursive function, and by Theorem 11.4 a recursive function can be represented in $\Sigma_{1}$-formula in $T \supseteq$ Q. Thus, we have a $\Sigma_{1}$-formula $\operatorname{IsProofof}_{T}(y, x)$ which states that $y$ is a proof of $x$. In particular, we also have the following formula.

$$
\operatorname{Provable}_{T}(x):=\exists y \operatorname{IsProofof}_{T}(y, x)
$$

such that

$$
T \vdash \varphi \leftrightarrow \operatorname{Provable}_{T}(\underline{(\sharp)}
$$

Consider the negation of $\operatorname{Provable}_{T}(x)$, i.e., $\neg \operatorname{Provable}_{T}(x)$. By fixed-point lemma, there is $\Psi$ such that

$$
T \vdash \Psi \leftrightarrow \neg \operatorname{Provable}_{T}(\underline{\sharp \Psi})
$$

which is simply

$$
T \vdash \Psi \leftrightarrow \forall y \neg \operatorname{IsPROOFOF}_{T}(y, \sharp \Psi)
$$

Following the argument in Section 3 in Lesson 10, neither $\Psi$ nor $\neg \Psi$ are provable in $T$.

## Appendix: Representing the Op rule

The proof consists of two steps.

- First, we construct a function $G: \mathbb{N}^{2} \rightarrow \mathbb{N}$ representable with $\Delta_{0}$-formula such that for every $n$, for every sequence $c_{0}, \ldots, c_{n}$, there is $c$ such that for all $i=0, \ldots, n$, we have $G(c, i)=c_{i}$.
- Using the function $G$ constructed, we can represent the $\mathbf{O p}$ rule with a $\Sigma_{1}$-formula.

Intuitively, the function $G$ "encodes" every sequence element $\left(c_{0}, \ldots, c_{n}\right) \in \mathbb{N}^{*}=\bigcup_{i \geqslant 1} \mathbb{N}^{i}$ as a number $c$ such that to retrieve an element $c_{i}$, we simply "access" $G(c, i)$.

Constructing the function $G$. Consider the following bijection $\wp: \mathbb{N}^{2} \rightarrow \mathbb{N}$.

$$
\wp(a, b):=a+\sum_{i=1}^{a+b} i=a+\frac{1}{2}(a+b)(a+b+1)
$$

Note that $a, b \leqslant \wp(a, b)$, for every $a, b$. It is trivial that $\wp$ can be represented by a $\Delta_{0}$-formula.
Let $F: \mathbb{N}^{3} \rightarrow \mathbb{N}$ be the following function.

$$
F(a, b, i):=\text { the remainder of } a \text { divided by } 1+(1+i) b
$$

It is not that difficult to show that the function $F$ is represented by a $\Delta_{0}$-formula.
Let $\operatorname{Proj}_{x}$ and $\operatorname{Proj}_{y}$ be the following functions. For every $m \in \mathbb{N}$, if $\wp^{-1}(m)=(a, b)$,

$$
\operatorname{Proj}_{x}(m):=a \text { and } \operatorname{Proj}_{y}(m):=b
$$

Consider the following function $G: \mathbb{N}^{2} \rightarrow \mathbb{N}$.

$$
G(c, i):=F\left(\operatorname{Proj}_{x}(c), \operatorname{Proj}_{y}(c), i\right)
$$

The function $G$ can be represented with a $\Delta_{0}$-formula as follows.

$$
G(c, i)=m \quad \text { if and only if } \quad(\exists x \leqslant c)(\exists y \leqslant c)(\underline{\wp(a, b)=c} \wedge \underline{F(a, b, i)=m})
$$

The underlined parts denote abbreviations of the formulas that represent $\wp(a, b)=c$ and $F(a, b, i)=m$, respectively.

We will show that $G$ is our desired function. In the following we write $a \mid b$ to denote that $a$ divides $b$, i.e., when $b$ is divided by $a$, there is no remainder. For two positive integers $a, b$, we say that $a$ and $b$ are coprime, if there is no prime $p$ that divides both $a$ and $b$.

Lemma 11.7 (Euclid) If $a$ and $b$ are coprime, then there are $x, y \in \mathbb{N}$ such that $a x+1=b y$.
Theorem 11.8 (Chinese remainder theorem) Let $c_{0}, \ldots, c_{k}, d_{0}, \ldots, d_{k}$ such that $c_{i}<d_{i}$. Let $d_{1}, \ldots, d_{k}$ be pairwise coprime. Then, there exists an integer $a \in \mathbb{N}$ such that $\operatorname{rem}\left(a, d_{i}\right)=c_{i}$, i.e. the remainder of a divided by $d_{i}$ is $c_{i}$.

Theorem 11.9 For every $n$, for every sequence $c_{0}, \ldots, c_{n}$, there exist $a, b$ such that for all $i=$ $0, \ldots, n$, we have $F(a, b, i)=c_{i}$.

Since $G(\wp(a, b), i)=F(a, b, i)$, we have that for every sequence $c_{0}, \ldots, c_{n}$, there is $c$, which is $\wp(a, b)$ and greater than each $c_{i}$, such that for all $i=0, \ldots, n$, we have $G(c, i)=c_{i}$.

Proof. Let $c_{0}, \ldots, c_{n}$ be a sequence of natural numbers. Consider the following two numbers $M$ and $K$.

- $M:=\max \left(n, c_{0}, \ldots, c_{n}\right)$.
- $b:=\operatorname{lcm}(1, \ldots, M)$, where "lcm" is least common multiplier.

Let $d_{i}:=1+(1+i) b$, for each $i=0, \ldots, n$. Note that $d_{i}>c_{i}$.
We claim that $d_{0}, \ldots, d_{n}$ are pairwise coprime. Suppose to the contrary that there is a prime $p$ that divides both $d_{i}$ and $d_{j}$. Thus, $p \mid d_{i}-d_{j}=(i-j) b$. So, either $p \mid(i-j)$ or $p \mid b$.

Now, $i, j \leqslant M$, since $b$ is the least common multiplier of all integers between 1 and $M$, we have $(i-j) \mid b$. This means that $p \mid b$. By definition of $d_{i}, b \mid\left(d_{i}-1\right)$, which means $p \mid\left(d_{i}-1\right)$. This is absurd, since $p \mid d_{i}$. So, there is such prime $p$ that divides $d_{i}$ and $d_{j}$. In other words, $d_{0}, \ldots, d_{n}$ are coprime.

By Theorem 11.8, there is $a$ such that $\operatorname{rem}\left(a, d_{i}\right)=c_{i}$. By the definition of the function $F$, we have $F(a, b, i)=c_{i}$. By the construction, it is obvious that $\wp(a, b)>c_{i}$.

Representing functions obtained from applying Op rule. Let $g \in \mathbf{F}_{n}$ and $h \in \mathbf{F}_{n+2}$ be recursive functions.

- Let $g$ be represented by a $\Sigma_{1}$-formula $\alpha_{1}$, as well as a $\Pi_{1}$-formula $\alpha_{2}$.
- Let $h$ be represented by a $\Sigma_{1}$-formula $\beta_{1}$, as well as a $\Pi_{1}$-formula $\beta_{2}$.

Suppose $f \in \mathbf{F}_{n+1}$ is the function obtained via the $\mathbf{O p}$ rule as follows. For every $\bar{a} \in \mathbb{N}^{n}$,

$$
f(\bar{a}, 0):=g(\bar{a}) \quad \text { and } \quad f(\bar{a}, \operatorname{Succ}(b)):=h(\bar{a}, b, f(\bar{a}, b))
$$

The following formula represents $f$.

$$
\varphi(\bar{x}, y, z):=\left(y \approx \tilde{0} \rightarrow \alpha_{1}(\bar{x}, z)\right) \wedge \quad \exists z^{\prime}\left(\forall y^{\prime}<y\right)\left(\underline{G\left(z^{\prime}, \operatorname{Succ}\left(y^{\prime}\right)\right)=h\left(\bar{x}, y^{\prime}, G\left(z^{\prime}, y^{\prime}\right)\right)}\right)
$$

Intuitively, the variable $z^{\prime}$ is such that for every $i \leqslant y, G\left(z^{\prime}, i\right)=f(\bar{x}, i)$.
Now, $\varphi(\bar{x}, y, z)$ can be rewritten into:

$$
\begin{aligned}
\varphi(\bar{x}, y, z):= & \left(y \approx \tilde{0} \rightarrow \alpha_{1}(\bar{x}, z)\right) \wedge \\
& \exists z^{\prime}\left(\forall y^{\prime}<y\right)\left(\forall u<z^{\prime}\right)\left(\forall v<z^{\prime}\right) \\
& \left(\underline{G\left(z^{\prime}, \operatorname{Succ}\left(y^{\prime}\right)\right)=u} \wedge \underline{G\left(z^{\prime}, y^{\prime}\right)=v} \rightarrow \beta_{1}\left(\bar{x}, y^{\prime}, u_{2}, u_{1}\right)\right)
\end{aligned}
$$

By pulling all the existential quantifiers from $\beta_{1}$ and $\exists z^{\prime}$ to the front of the formula, we obtain a $\Sigma_{1}$-formula. A $\Pi_{1}$-formula can be obtained via:

$$
\varphi^{\prime}(\bar{x}, y, z):=\forall w \varphi(\bar{x}, y, w) \rightarrow w \approx z
$$

## Lesson 12: Decision problems in FO

Theme: The complexity of some standard decision problems in FO.

From Gödel's incompleteness theorem, it is immediate that the following problem $\operatorname{SAT}(\mathcal{N})$ is undecidable, where $\mathcal{N}$ is the structure $\mathcal{N}=(\mathbb{N}, 0$, succ,,$+ \cdot)$.

$$
\text { SAT }(\mathcal{N})
$$

Input: An FO sentence $\varphi$ over the vocabulary $L_{a r}=\{\tilde{0}$, Succ,,,$+ \cdot\}$.
Task: Output True, if $\mathcal{N} \models \varphi$. Otherwise, output False.
Theorem 12.1 The problem $\operatorname{SAT}(\mathcal{N})$ is undecidable.
Consider the following evaluation problems.

## EVAL(FO)

Input: An FO sentence $\varphi$ and a finite structure $\mathcal{A}$.
Task: Output True, if $\mathcal{A} \models \varphi$. Otherwise, output False.
$\operatorname{EVAL}(\varphi)$, where $\varphi$ is an FO sentence
Input: A finite structure $\mathcal{A}$.
Task: $\quad$ Output True, if $\mathcal{A} \equiv \varphi$. Otherwise, output False.

## Theorem 12.2

- The problem EVAL(FO) is PSPACE-complete.
- For every FO sentence $\varphi$, the problem $\operatorname{EVAL}(\varphi)$ is in Ptime.

Recall that a sentence $\varphi$ is satisfiable, if there is a model $\mathcal{A}$ such that $\mathcal{A} \models \varphi$. A sentence is finitely satisfiable, if there is a finite model $\mathcal{A}$ such that $\mathcal{A} \models \varphi$. We will consider the following two problems.

## SAT(FO)

Input: An FO sentence $\varphi$.
Task: Output True, if $\varphi$ is satisfiable. Otherwise, output False.

```
FIN-SAT(FO)
Input: An FO sentence }\varphi\mathrm{ .
Task: Output True, if \varphi is finitely satisfiable. Otherwise, output False.
```


## Theorem 12.3

- Both SAT(FO) and FIN-SAT(FO) are undecidable.
- SAT(FO) is co-r.e (co-recursive enumerable).
- FIN-SAT(FO) is r.e (recursive enumerable).


[^0]:    *A binary relation $R$ on $X$ is anti-symmetric, if the following holds: for every $a, b \in X$, if both $(a, b)$ and $(b, a)$ are in $R$, then $a=b$.

[^1]:    ${ }^{\dagger}$ For simplicity, we only consider $P V$ a countable set. Although in general such assumption is not necessary, it will simplify our discussions a lot.

[^2]:    ${ }^{\ddagger}$ The poset $\mathbb{R}$ w.r.t. the relation $\leqslant$ is usually written as $(\mathbb{R}, \leqslant)$.
    ${ }^{\S}$ The poset $\mathcal{F}$ w.r.t. the relation $\subseteq$ is usually written as ( $\mathcal{F}, \subseteq$ ).

[^3]:    *A graph $G=(V, E)$ is planar, if there is a function $f: V \rightarrow \mathbb{R}^{2}$, and there is curve between every two points $f(u)$ and $f(v)$, whenever $(u, v) \in E$, such that no two curves "cross" each other.

[^4]:    *Recall that $\models \varphi$ is the abbreviation for $\emptyset \models \varphi$.

[^5]:    *Similar material can be obtained from Section 3.2 in the textbook A Concise Introduction to Mathematical Logic (3rd ed.) by Wolfgang Rautenberg.

[^6]:    ${ }^{\dagger}$ Note that $\Gamma_{L}$ is a set of formulas over the vocabulary $L \cup\left\{c_{x, \alpha} \mid \alpha \in \mathrm{FO}[L], x \in \mathrm{VAR}\right\}$.

[^7]:    ${ }^{\ddagger}$ Lemma 3.2 can be easily proved for a set $X$ of first-order formulas.

[^8]:    *Some of the material is taken from the textbook A Concise Introduction to Mathematical Logic (3rd ed.) by Wolfgang Rautenberg.

[^9]:    ${ }^{\dagger}$ Recall that in Lesson 4 we show if $X \vdash \alpha \rightarrow \beta$, then $X \vdash \neg \beta \rightarrow \neg \alpha$, which is called contrapositive.
    ${ }^{\ddagger}$ Recall that in Lesson 4 we show if $X \vdash \alpha \rightarrow \beta$ and $X \vdash \alpha$, then $X \vdash \beta$, which is called modus ponens.

[^10]:    ${ }^{\text {§}}$ Kurt Gödel, Über formal unentscheidbare Sätze der Principia Mathematica und verwandter Systeme I (On formally undecidable propositions of Principia Mathematica and related systems I), Monatshefte für Mathematik and Physik, 38:173-198 (1931).
    ${ }^{\mathbf{I}}$ To be exact, expressing $\mathbf{O c}$ and $\mathbf{O} \mu$ rules in formulas over $\{\tilde{0}$, Succ,,$+ \cdot\}$ is not difficult. The main difficulty is in expressing the $\mathbf{O p}$.

