

# Active Learning by Learning

Hsuan-Tien Lin (林軒田)

htlin@csie.ntu.edu.tw

Department of Computer Science  
& Information Engineering

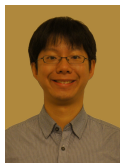
National Taiwan University  
(國立台灣大學資訊工程系)



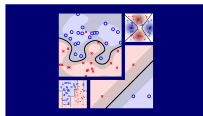
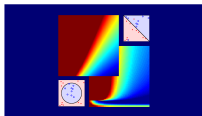
joint work with Wei-Ning Hsu, presented in AAAI 2015  
**special thanks to TAAI's scholarship for Wei-Ning's AAAI trip**

# About Me

## Hsuan-Tien Lin



- Associate Professor, Dept. of CSIE, National Taiwan University
- Leader of the Computational Learning Laboratory
- Co-author of the textbook “*Learning from Data: A Short Course*” (often **ML best seller on Amazon**)
- Instructor of the NTU-Coursera Mandarin-teaching ML Massive Open Online Courses
  - “*Machine Learning Foundations*”:  
[www.coursera.org/course/ntumlone](http://www.coursera.org/course/ntumlone)
  - “*Machine Learning Techniques*”:  
[www.coursera.org/course/ntumltwo](http://www.coursera.org/course/ntumltwo)



# Apple Recognition Problem

## Note: Slide Taken from my “ML Techniques” MOOC

- need **apple classifier**: is this a picture of an apple?
- gather photos under CC-BY-2.0 license on Flickr (**thanks to the authors below!**) and **label them as apple/other for learning**

(APAL stands for Apple and Pear Australia Ltd)



Dan Foy

https://flic.kr/p/jNQ55



APAL

https://flic.kr/p/jzP1VB



adrianbartel

https://flic.kr/p/bdy2hZ



ANdrzej cH.

https://flic.kr/p/51DKA8



Stuart Webster

https://flic.kr/p/9C3Ybd



nachans

https://flic.kr/p/9XD7Ag



APAL

https://flic.kr/p/jzRe4u



Jo Jakeman

https://flic.kr/p/7jwTgP



APAL

https://flic.kr/p/jzPYNr



APAL

https://flic.kr/p/jzScif

# Apple Recognition Problem

## Note: Slide Taken from my “ML Techniques” MOOC

- need **apple classifier**: is this a picture of an apple?
- gather photos under CC-BY-2.0 license on Flickr (**thanks to the authors below!**) and **label them as apple/other for learning**



Mr. Roboto.

<https://flickr.kr/p/i5BN85>



Richard North

<https://flickr.kr/p/bHhPkB>



Richard North

<https://flickr.kr/p/d8tGou>



Emilian Robert Vicol

<https://flickr.kr/p/bpmGXW>



Nathaniel McQueen

<https://flickr.kr/p/pZv1Mf>



Crystal

<https://flickr.kr/p/kaPYp>



jfh686

<https://flickr.kr/p/6vjRFH>



skyseeker

<https://flickr.kr/p/2MynV>



Janet Hudson

<https://flickr.kr/p/7QDBbm>

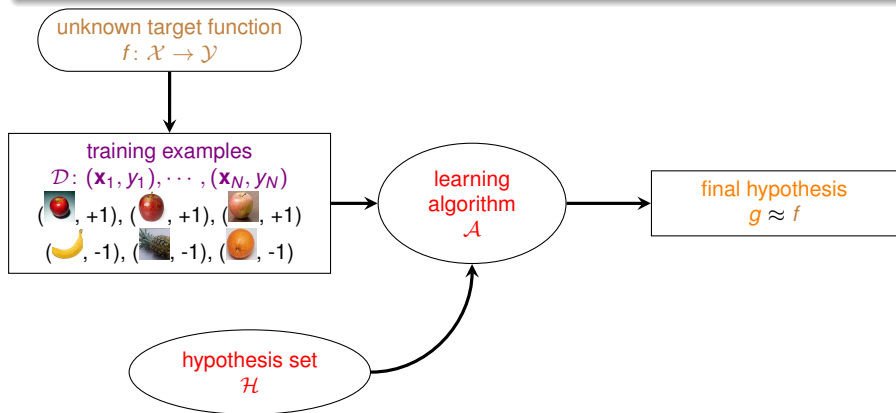


Rennett Stowe

<https://flickr.kr/p/agmnrk>

## Batch (Traditional) Machine Learning

Note: Flow Taken from my “ML Foundations” MOOC



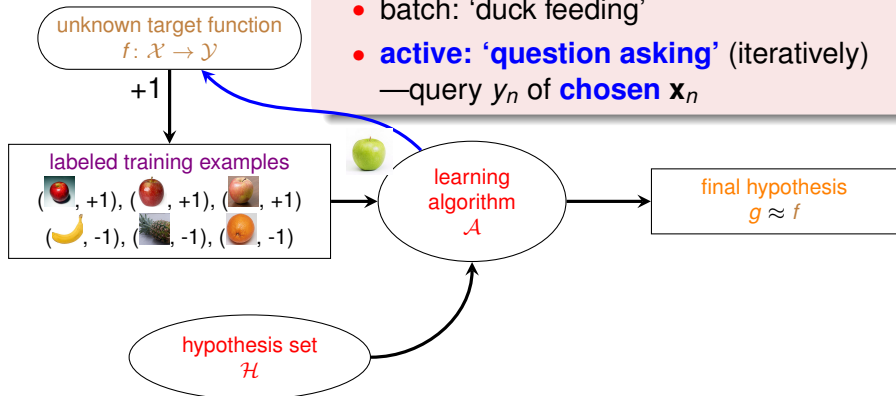
**batch** supervised classification:  
learn from **fully labeled** data

## Active Learning: Learning by 'Asking'

but labeling is **expensive**

### Protocol $\Leftrightarrow$ Learning Philosophy


- batch: 'duck feeding'
- **active: 'question asking'** (iteratively)  
—query  $y_n$  of **chosen**  $\mathbf{x}_n$



active: improve hypothesis with fewer labels  
(hopefully) by asking questions **strategically**


# Pool-Based Active Learning Problem

## Given

- labeled pool  $\mathcal{D}_l = \left\{ (\text{feature } \mathbf{x}_n \text{ }, \text{label } y_n \text{ (e.g. IsApple?)}) \right\}_{n=1}^N$
- unlabeled pool  $\mathcal{D}_u = \left\{ \tilde{\mathbf{x}}_s \right\}_{s=1}^S$

## Goal

design an algorithm that iteratively

- strategically query** some  $\tilde{\mathbf{x}}_s$   to get associated  $\tilde{y}_s$
- move  $(\tilde{\mathbf{x}}_s, \tilde{y}_s)$  from  $\mathcal{D}_u$  to  $\mathcal{D}_l$
- learn **classifier**  $g^{(t)}$  from  $\mathcal{D}_l$

and improve **test accuracy of  $g^{(t)}$**  w.r.t **#queries**

how to **query strategically**?

# How to Query Strategically?



by DFID - UK Department for International Development;  
licensed under CC BY-SA 2.0 via Wikimedia Commons

## Strategy 1

ask **most confused**  
question

## Strategy 2

ask **most frequent**  
question

## Strategy 3

ask **most helpful**  
question

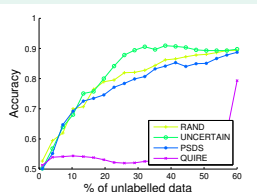
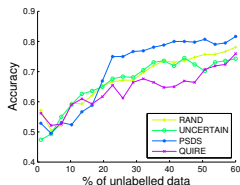
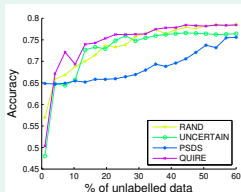
do you use a **fixed strategy** in practice? 😊



## Choice of Strategy

Strategy 1:  
uncertaintyask **most confused**  
questionStrategy 2:  
representativeask **most frequent**  
questionStrategy 3:  
exp.-err. reductionask **most helpful**  
question

- choosing one single strategy is **non-trivial**:



- human-designed strategy **heuristic** and **confine** machine's ability

can we **free** the machine 😊  
by letting it **learn to choose** the strategies?

# Our Contributions

*a philosophical and algorithmic study of active learning, which ...*

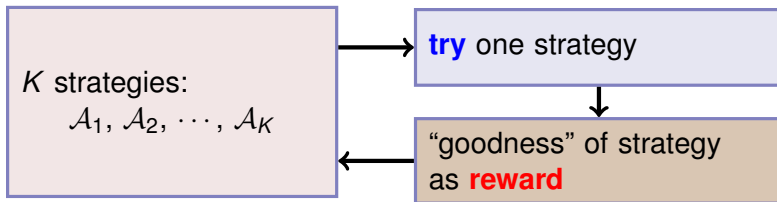
- allows machine to make **intelligent choice of strategies**, just like my **cute daughter**
- studies **sound feedback scheme** to tell machine about goodness of choice, just like **what I do**
- results in **promising active learning performance**, just like (hopefully) **bright future** of my daughter 😊

will describe **key philosophical ideas** behind our proposed approach

## Idea: Trial-and-Reward Like Human



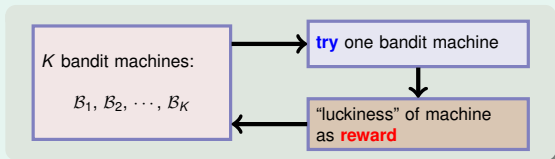
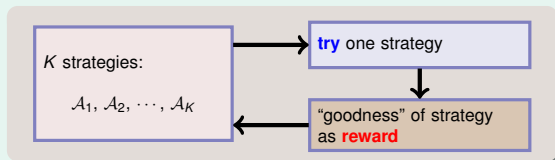
by DFID - UK Department for International Development;  
 licensed under CC BY-SA 2.0 via Wikimedia Commons



two issues: **try** and **reward**

## Reduction to Bandit

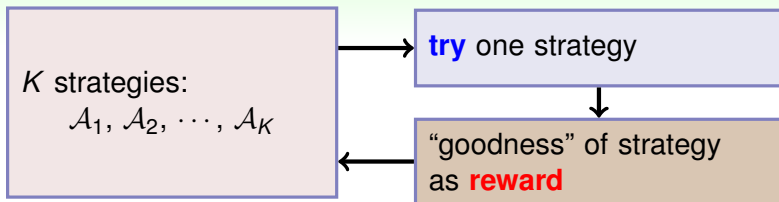
when do humans **trial**-and-**reward**?  
**gambling** 😊



—will take one well-known **probabilistic bandit learner (EXP4.P)**

intelligent choice of strategy  
 $\implies$  intelligent choice of **bandit machine**

## Active Learning by Learning



Given:  $K$  existing active learning strategies

for  $t = 1, 2, \dots, T$

- ① let EXP4.P **decide strategy**  $\mathcal{A}_k$  **to try**
- ② **query the**  $\tilde{x}_s$  suggested by  $\mathcal{A}_k$ , and compute  $g^{(t)}$
- ③ evaluate **goodness of**  $g^{(t)}$  as **reward** of **trial** to update EXP4.P

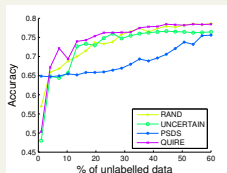
only remaining problem: **what reward?**

# Ideal Reward

**ideal reward** after updating classifier  $g^{(t)}$  by the query  $(\mathbf{x}_{n_t}, y_{n_t})$ :

$$\text{accuracy} \frac{1}{M} \sum_{m=1}^M \mathbb{I}[y_m = g^{(t)}(\mathbf{x}_m)] \text{ on test set } \{(\mathbf{x}_m, y_m)\}_{m=1}^M$$

- **test accuracy** as **reward**:  
area under query-accuracy curve  $\equiv$  **cumulative reward**



- **test accuracy infeasible** in practice  
—labeling **expensive**, remember? 😊

difficulty: approximate **test accuracy on the fly**

# Training Accuracy as Reward

test accuracy  ~~$\frac{1}{M} \sum_{m=1}^M \mathbb{I}[y_m = g^{(t)}(\mathbf{x}_m)]$~~  infeasible, naïve replacement:

accuracy  $\frac{1}{t} \sum_{\tau=1}^t \mathbb{I}[y_{n_\tau} = g^{(t)}(\mathbf{x}_{n_\tau})]$  on **labeled pool**  $\{(\mathbf{x}_{n_\tau}, y_{n_\tau})\}_{\tau=1}^t$

- **training accuracy** as **reward**:  
**training accuracy**  $\approx$  **test accuracy**?
- not necessarily!!  
—for active learning strategy that asks **easiest** questions:
  - **training accuracy high**:  $\mathbf{x}_{n_\tau}$  easy to label
  - **test accuracy low**: not enough information about **harder instances**

**training accuracy**:  
too **biased** to approximate **test accuracy**

# Weighted Training Accuracy as Reward

training accuracy  $\frac{1}{t} \sum_{\tau=1}^t \mathbb{I}[y_{n_\tau} = g^{(t)}(\mathbf{x}_{n_\tau})]$  biased,  
 want **unbiased estimator**

- non-uniform sampling** theorem: if  $(\mathbf{x}_{n_\tau}, y_{n_\tau})$  sampled with probability  $p_\tau > 0$  from data set  $\{(\mathbf{x}_n, y_n)\}_{n=1}^N$  in iteration  $\tau$ ,

$$\begin{aligned} \text{weighted training accuracy} & \frac{1}{t} \sum_{\tau=1}^t \frac{1}{p_\tau} \mathbb{I}[y_{n_\tau} = g(\mathbf{x}_{n_\tau})] \\ & \approx \frac{1}{N} \sum_{n=1}^N \mathbb{I}[y_n = g(\mathbf{x}_n)] \text{ in } \mathbf{expectation} \end{aligned}$$

- with **probabilistic query** like EXP4.P:  
**weighted training accuracy**  $\approx$  test accuracy

**weighted training accuracy:**  
**unbiased approx. of test accuracy on the fly**



# Human-Designed Criterion as Reward

(Baram et al., 2004) COMB approach:

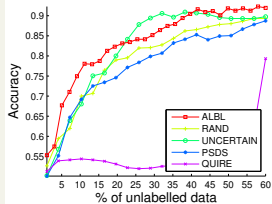
bandit + **balancedness** of  $g^{(t)}$  on unlabeled data as reward

- why? human criterion that matches classifier to **domain assumption**
- but many active learning applications are on **unbalanced data!** —assumption may be **unrealistic**

existing strategies: active learning **by acting**;  
COMB: active learning **by acting**;  
ours: active learning **by learning**

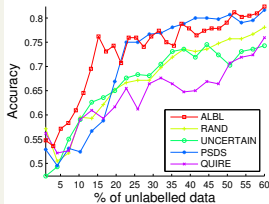
# Comparison with Single Strategies

## UNCERTAIN Best



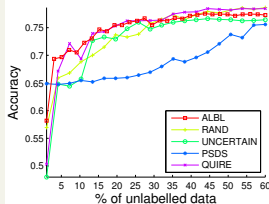
vehicle

## PSDS Best



sonar

## QUIRE Best

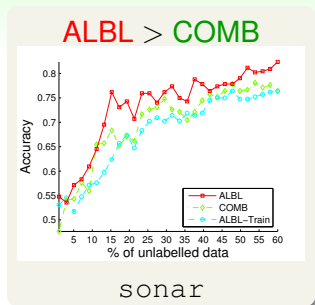
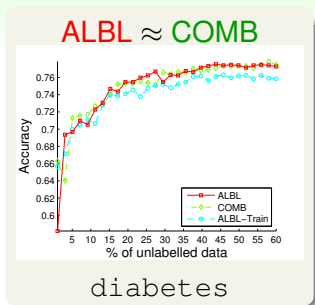


diabetes

- **no single best strategy** for every data set  
—choosing/blending needed
- **ALBL** consistently **matches the best**  
—similar findings across other data sets

**ALBL**: effective in **making intelligent choices**

# Comparison with Other Adaptive Blending Algorithms



- **ALBL  $>$  ALBL-Train** generally  
— **importance-weighted** mechanism needed for correcting **biased training accuracy**
- **ALBL** consistently **comparable to or better than COMB**  
— **learning performance** more useful than **human-criterion**

**ALBL: effective in utilizing performance**

# Conclusion

## Active Learning by Learning

- based on **bandit learning** + **unbiased performance estimator** as reward
- effective in **making intelligent choices**  
—comparable or superior to the best of existing strategies
- effective in **utilizing learning performance**  
—superior to human-criterion-based blending

## New Directions

- **open-source tool** being developed
- extending to **more sophisticated active learning problems**

Thank you! Questions?