## Machine Learning Techniques

(機器學習技法)



Lecture 8: Adaptive Boosting

Hsuan-Tien Lin (林軒田)

htlin@csie.ntu.edu.tw

Department of Computer Science & Information Engineering

National Taiwan University (國立台灣大學資訊工程系)



## Roadmap

- 1 Embedding Numerous Features: Kernel Models
- 2 Combining Predictive Features: Aggregation Models

## Lecture 7: Blending and Bagging

blending known diverse hypotheses uniformly, linearly, or even non-linearly; obtaining diverse hypotheses from bootstrapped data

#### Lecture 8: Adaptive Boosting

- Motivation of Boosting
- Diversity by Re-weighting
- Adaptive Boosting Algorithm
- Adaptive Boosting in Action
- 3 Distilling Implicit Features: Extraction Models

## Apple Recognition Problem

- is this a picture of an apple?
- say, want to teach a class of 6 year olds

## Apple Recognition Problem

- is this a picture of an apple?
- say, want to teach a class of 6 year olds
- gather photos under CC-BY-2.0 license on Flicker (thanks to the authors below!)

#### (APAL stands for Apple and Pear Australia Ltd)

**APAL** 

https:

//flic.

kr/p/jzRe4u



Dan Foy https: //flic. kr/p/jNQ55







https: //flic. kr/p/jzP1VB



adrianbartel https: //flic. kr/p/bdy2hZ







kr/p/7jwtGp

//flic.



APAL https: //flic. kr/p/jzPYNr

ANdrzej cH.

kr/p/51DKA8

https:

//flic.



Stuart Webster https: //flic. kr/p/9C3Ybd



APAL https: //flic. kr/p/jzScif

## Apple Recognition Problem

- is this a picture of an apple?
- say, want to teach a class of 6 year olds
- gather photos under CC-BY-2.0 license on Flicker (thanks to the authors below!)



Mr. Roboto.

https: //flic. kr/p/i5BN85



Crystal https: //flic. kr/p/kaPYp



**Richard North** 





ifh686 https: //flic. kr/p/6viRFH



**Richard North** 

https: //flic. kr/p/d8tGou



skyseeker https:

//flic. kr/p/2MvnV



Fmilian Robert Vicol

https: //flic. kr/p/bpmGXW



Janet Hudson

https: //flic. kr/p/70DBbm



Nathaniel Mc-Queen

https: //flic. kr/p/pZv1Mf

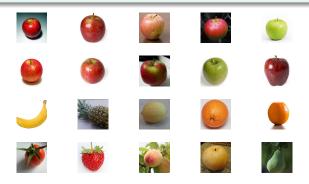


Rennett Stowe

https: //flic. kr/p/agmnrk

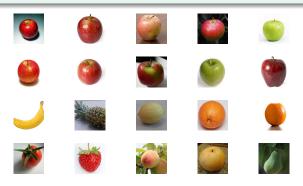
## Our Fruit Class Begins

 Teacher: Please look at the pictures of apples and non-apples below. Based on those pictures, how would you describe an apple? Michael?



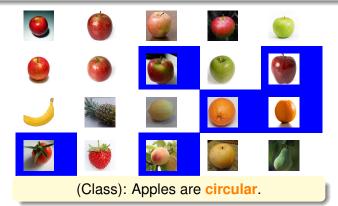
## Our Fruit Class Begins

- Teacher: Please look at the pictures of apples and non-apples below. Based on those pictures, how would you describe an apple? Michael?
- Michael: I think apples are circular.



## Our Fruit Class Begins

- Teacher: Please look at the pictures of apples and non-apples below. Based on those pictures, how would you describe an apple? Michael?
- Michael: I think apples are circular.



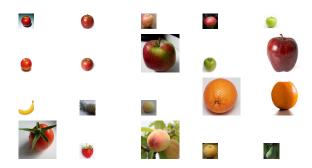
#### Our Fruit Class Continues

 Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?



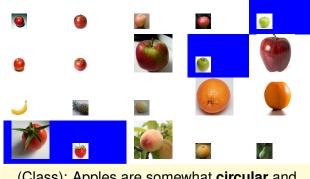
#### **Our Fruit Class Continues**

- Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?
- Tina: It looks like apples are red.



#### **Our Fruit Class Continues**

- Teacher: Being circular is a good feature for the apples. However, if you only say circular, you could make several mistakes. What else can we say for an apple? Tina?
- Tina: It looks like apples are red.



(Class): Apples are somewhat **circular** and somewhat **red**.

#### Our Fruit Class Continues More

 Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?



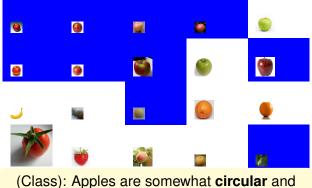
#### Our Fruit Class Continues More

- Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?
- Joey: Apples could also be green.



#### Our Fruit Class Continues More

- Teacher: Yes. Many apples are red. However, you could still make mistakes based on circular and red. Do you have any other suggestions, Joey?
- Joey: Apples could also be green.



(Class): Apples are somewhat **circular** and somewhat **red** and possibly **green**.

#### Our Fruit Class Ends

Teacher: Yes. It seems that apples might be circular, red, green.
 But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?



#### Our Fruit Class Ends

- Teacher: Yes. It seems that apples might be circular, red, green.
   But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?
- Jessica: Apples have stems at the top.



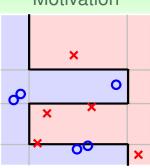
#### Our Fruit Class Ends

- Teacher: Yes. It seems that apples might be circular, red, green.
   But you may confuse them with tomatoes or peaches, right? Any more suggestions, Jessica?
- Jessica: Apples have stems at the top.



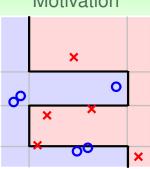
(Class): Apples are somewhat **circular**, somewhat **red**, possibly **green**, and may have **stems** at the top.

#### Motivation

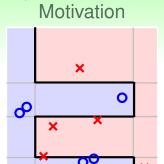


students: simple hypotheses g<sub>t</sub> (like vertical/horizontal lines)

#### Motivation

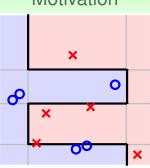


- students: simple hypotheses  $g_t$  (like vertical/horizontal lines)
- (Class): sophisticated hypothesis *G* (like black curve)



- students: simple hypotheses g<sub>t</sub> (like vertical/horizontal lines)
- (Class): sophisticated hypothesis *G* (like black curve)
- Teacher: a tactic learning algorithm that directs the students to focus on key examples

#### Motivation



- students: simple hypotheses g<sub>t</sub> (like vertical/horizontal lines)
- (Class): sophisticated hypothesis *G* (like black curve)
- Teacher: a tactic learning algorithm that directs the students to focus on key examples

next: the 'math' of such an algorithm

#### Fun Time

Which of the following can help recognize an apple?

- apples are often circular
- 2 apples are often red or green
- 3 apples often have stems at the top
- 4 all of the above

#### Fun Time

Which of the following can help recognize an apple?

- apples are often circular
- 2 apples are often red or green
- 3 apples often have stems at the top
- 4 all of the above

# Reference Answer: 4

Congratulations! You have passed first grade. :-)

$$\mathcal{D} = \{(\boldsymbol{x}_1, y_1), (\boldsymbol{x}_2, y_2), (\boldsymbol{x}_3, y_3), (\boldsymbol{x}_4, y_4)\}$$

$$\overset{\text{bootstrap}}{\Longrightarrow} \quad \tilde{\mathcal{D}}_t = \{(\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_4, y_4)\}$$

# $E_{\text{in}} \text{ on } \tilde{D}_{t}$ $E_{\text{in}}^{0/1}(h) = \frac{1}{4} \sum_{(\mathbf{x}, y) \in \tilde{D}_{t}} \llbracket y \neq h(\mathbf{x}) \rrbracket$ $(\mathbf{x}_{1}, y_{1}), (\mathbf{x}_{1}, y_{1})$ $(\mathbf{x}_{2}, y_{2})$ $(\mathbf{x}_{4}, y_{4})$

## weighted $E_{in}$ on $\mathcal{D}$

$$(\mathbf{x}_1, y_1), u_1 = 2$$
  
 $(\mathbf{x}_2, y_2), u_2 = 1$   
 $(\mathbf{x}_3, y_3), u_3 = 0$   
 $(\mathbf{x}_4, y_4), u_4 = 1$ 

# $E_{\rm in}$ on $D_{\rm in}$

$$E_{\text{in}}^{0/1}(h) = \frac{1}{4} \sum_{(\mathbf{x}, y) \in \tilde{D}_t} \llbracket y \neq h(\mathbf{x}) \rrbracket$$
$$(\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1)$$
$$(\mathbf{x}_2, y_2)$$
$$(\mathbf{x}_4, y_4)$$

$$\begin{split} \mathcal{D} &= \{ (\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_3, y_3), (\mathbf{x}_4, y_4) \} \\ \stackrel{\text{bootstrap}}{\Longrightarrow} & \tilde{\mathcal{D}}_t = \{ (\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_4, y_4) \} \end{split}$$

## weighted $E_{in}$ on $\mathcal{D}$

$$E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{4} \sum_{n=1}^{4} u_{n}^{(t)} \cdot [y_{n} \neq h(\mathbf{x}_{n})]$$

$$(\mathbf{x}_{1}, y_{1}), u_{1} = 2$$

$$(\mathbf{x}_{2}, y_{2}), u_{2} = 1$$

$$(\mathbf{x}_{3}, y_{3}), u_{3} = 0$$

$$(\mathbf{x}_{4}, y_{4}), u_{4} = 1$$

$$E_{\text{in}} \text{ on } \overline{D}_t$$

$$E_{\text{in}}^{0/1}(h) = \frac{1}{4} \sum_{(\mathbf{x}, y) \in \tilde{D}_t} \llbracket y \neq h(\mathbf{x}) \rrbracket$$

$$(\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1)$$

$$(\mathbf{x}_2, y_2)$$

 $(\mathbf{x}_4, y_4)$ 

$$\begin{split} \mathcal{D} &= \{ (\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_3, y_3), (\mathbf{x}_4, y_4) \} \\ \stackrel{\text{bootstrap}}{\Longrightarrow} & \tilde{\mathcal{D}}_t = \{ (\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_4, y_4) \} \end{split}$$

## weighted $E_{\rm in}$ on $\mathcal{D}$

$$E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{4} \sum_{n=1}^{4} u_{n}^{(t)} \cdot [y_{n} \neq h(\mathbf{x}_{n})]$$

$$(\mathbf{x}_{1}, y_{1}), u_{1} = 2$$

$$(\mathbf{x}_{2}, y_{2}), u_{2} = 1$$

$$(\mathbf{x}_{3}, y_{3}), u_{3} = 0$$

$$(\mathbf{x}_{4}, y_{4}), u_{4} = 1$$

$$E_{\text{in}} \text{ on } \overline{D}_{\ell}$$

$$E_{\text{in}}^{0/1}(h) = \frac{1}{4} \sum [y \neq h(\mathbf{x})]$$

$$(\mathbf{x}_1, y_1), (\mathbf{x}_1, y_1)$$
  
 $(\mathbf{x}_2, y_2)$   
 $(\mathbf{x}_4, y_4)$ 

each diverse  $g_t$  in bagging: by minimizing bootstrap-weighted error

#### minimize (regularized)

$$E_{\rm in}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \operatorname{err}(y_n, h(\mathbf{x}_n))$$

#### minimize (regularized)

$$E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \text{err}(y_n, h(\mathbf{x}_n))$$

#### SVM

$$E_{\rm in}^{\bf u} \propto C \sum_{n=1}^{N} u_n \widehat{\rm err}_{\rm SVM}$$
 by dual QP

#### minimize (regularized)

$$E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \text{err}(y_n, h(\mathbf{x}_n))$$

#### SVM

$$E_{\rm in}^{\bf u} \propto C \sum_{n=1}^{N} u_n \widehat{\rm err}_{\rm SVM}$$
 by dual QP

⇔ adjusted upper bound

$$0 \le \alpha_n \le Cu_n$$

minimize (regularized)

$$E_{\rm in}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \operatorname{err}(y_n, h(\mathbf{x}_n))$$

#### **SVM**

 $E_{\text{in}}^{\mathbf{u}} \propto C \sum_{n=1}^{N} u_n \widehat{\text{err}}_{\text{SVM}}$  by dual QP  $\Leftrightarrow$  adjusted upper bound  $0 < \alpha_n < C u_n$ 

## logistic regression

$$E_{\rm in}^{\rm u} \propto \sum_{n=1}^{N} u_n {\rm err}_{\rm CE}$$
 by SGD

minimize (regularized)

$$E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \text{err}(y_n, h(\mathbf{x}_n))$$

#### **SVM**

$$E_{\text{in}}^{\mathbf{u}} \propto C \sum_{n=1}^{N} u_n \widehat{\text{err}}_{\text{SVM}}$$
 by dual QP

⇔ adjusted upper bound

$$0 \leq \alpha_n \leq C u_n$$

#### logistic regression

$$E_{\text{in}}^{\mathbf{u}} \propto \sum_{n=1}^{N} u_n \text{err}_{\text{CE}} \text{ by SGD}$$
  
 $\Leftrightarrow \text{sample } (\mathbf{x}_n, y_n) \text{ with }$ 

 $\Leftrightarrow$  sample  $(\mathbf{x}_n, y_n)$  with probability proportional to  $u_n$ 

minimize (regularized)

$$E_{\rm in}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot \operatorname{err}(y_n, h(\mathbf{x}_n))$$

#### **SVM**

$$E_{\text{in}}^{\mathbf{u}} \propto C \sum_{n=1}^{N} u_n \widehat{\text{err}}_{\text{SVM}}$$
 by dual QP  $\Leftrightarrow$  adjusted upper bound

$$0 \le \alpha_n \le C u_n$$

## logistic regression

$$E_{\text{in}}^{\mathbf{u}} \propto \sum_{n=1}^{N} u_n \text{err}_{\text{CE}} \text{ by SGD}$$
  
 $\Leftrightarrow \text{sample } (\mathbf{x}_n, y_n) \text{ with }$ 

probability proportional to  $u_n$ 

**example-weighted** learning:

extension of class-weighted learning in Lecture 8 of ML Foundations

## Re-weighting for More Diverse Hypothesis

'improving' bagging for binary classification:
how to re-weight for more diverse hypotheses?

# Re-weighting for More Diverse Hypothesis

'improving' bagging for binary classification:

how to re-weight for more diverse hypotheses?

$$\frac{g_t}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

$$\frac{g_{t+1}}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t+1)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

'improving' bagging for binary classification:

how to re-weight for more diverse hypotheses?

$$g_{t} \leftarrow \operatorname{argmin} \left( \sum_{n=1}^{N} u_{n}^{(t)} \left[ y_{n} \neq h(\mathbf{x}_{n}) \right] \right)$$

$$g_{t+1} \leftarrow \operatorname{argmin} \left( \sum_{n=1}^{N} u_{n}^{(t+1)} \left[ y_{n} \neq h(\mathbf{x}_{n}) \right] \right)$$

if  $g_t$  'not good' for  $\mathbf{u}^{(t+1)}$ 

'improving' bagging for binary classification:

how to re-weight for more diverse hypotheses?

$$\frac{g_t}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

$$\frac{g_{t+1}}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t+1)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

if  $g_t$  'not good' for  $\mathbf{u}^{(t+1)} \Longrightarrow g_t$ -like hypotheses not returned as  $g_{t+1}$ 

'improving' bagging for binary classification:
how to re-weight for more diverse hypotheses?

$$\frac{g_t}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

$$\frac{g_{t+1}}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t+1)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

if  $g_t$  'not good' for  $\mathbf{u}^{(t+1)} \Longrightarrow g_t$ -like hypotheses not returned as  $g_{t+1} \Longrightarrow g_{t+1}$  diverse from  $g_t$ 

'improving' bagging for binary classification:

how to re-weight for more diverse hypotheses?

$$g_{t} \leftarrow \operatorname{argmin} \left( \sum_{n=1}^{N} u_{n}^{(t)} \left[ y_{n} \neq h(\mathbf{x}_{n}) \right] \right)$$

$$g_{t+1} \leftarrow \operatorname{argmin} \left( \sum_{n=1}^{N} u_{n}^{(t+1)} \left[ y_{n} \neq h(\mathbf{x}_{n}) \right] \right)$$

if  $g_t$  'not good' for  $\mathbf{u}^{(t+1)} \Longrightarrow g_t$ -like hypotheses not returned as  $g_{t+1} \Longrightarrow g_{t+1}$  diverse from  $g_t$ 

idea: **construct**  $\mathbf{u}^{(t+1)}$  to make  $g_t$  random-like

$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} [\![ y_n \neq \underline{g_t}(\mathbf{x}_n) ]\!]}{\sum_{n=1}^{N} u_n^{(t+1)}} =$$

'improving' bagging for binary classification:

how to re-weight for more diverse hypotheses?

$$\frac{g_t}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

$$\frac{g_{t+1}}{g_{t+1}} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \left( \sum_{n=1}^{N} u_n^{(t+1)} \left[ y_n \neq h(\mathbf{x}_n) \right] \right)$$

if  $g_t$  'not good' for  $\mathbf{u}^{(t+1)} \Longrightarrow g_t$ -like hypotheses not returned as  $g_{t+1} \Longrightarrow g_{t+1}$  diverse from  $g_t$ 

idea: **construct**  $\mathbf{u}^{(t+1)}$  to make  $g_t$  random-like

$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{1}{2}$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} [y_n \neq g_t(\mathbf{x}_n)]}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{1}{2}, \text{ where}$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \blacksquare_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \qquad , \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)}$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \blacksquare_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)}$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \blacksquare_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \bullet_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

• need: 
$$(total \ u_n^{(t+1)} \ of \ incorrect) = (total \ u_n^{(t+1)} \ of \ correct)$$

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \blacksquare_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

• need: 
$$\underbrace{(\text{total } u_n^{(t+1)} \text{ of incorrect})}_{=t+1} = \underbrace{(\text{total } u_n^{(t+1)} \text{ of correct})}_{=t+1}$$

one possibility by re-scaling (multiplying) weights, if

(total 
$$u_n^{(t)}$$
 of incorrect) = 1126; (total  $u_n^{(t)}$  of correct) = 6211; incorrect:  $u_n^{(t+1)} \leftarrow u_n^{(t)}$  correct:  $u_n^{(t+1)} \leftarrow u_n^{(t)}$ .

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \blacksquare_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

• need: 
$$\underbrace{(\text{total } u_n^{(t+1)} \text{ of incorrect})}_{=t+1} = \underbrace{(\text{total } u_n^{(t+1)} \text{ of correct})}_{=t+1}$$

one possibility by re-scaling (multiplying) weights, if

(total 
$$u_n^{(t)}$$
 of incorrect) = 1126; (total  $u_n^{(t)}$  of correct) = 6211; incorrect:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 6211$  correct:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 1126$ 

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \bullet_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

- need:  $\underbrace{(\text{total } u_n^{(t+1)} \text{ of incorrect})}_{\text{t+1}} = \underbrace{(\text{total } u_n^{(t+1)} \text{ of correct})}_{\text{t+1}}$
- one possibility by re-scaling (multiplying) weights, if

(total 
$$u_n^{(t)}$$
 of incorrect) = 1126; (total  $u_n^{(t)}$  of correct) = 6211; (weighted incorrect rate) =  $\frac{1126}{7337}$  (weighted correct rate) =  $\frac{6211}{7337}$  incorrect:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 6211$  correct:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 1126$ 

want: 
$$\frac{\sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^{N} u_n^{(t+1)}} = \frac{\blacksquare_{t+1}}{\blacksquare_{t+1} + \bullet_{t+1}} = \frac{1}{2}, \text{ where}$$

$$\blacksquare_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket, \bullet_{t+1} = \sum_{n=1}^{N} u_n^{(t+1)} \llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$$

• need: 
$$\underbrace{(\text{total } u_n^{(t+1)} \text{ of incorrect})}_{t+1} = \underbrace{(\text{total } u_n^{(t+1)} \text{ of correct})}_{t+1}$$

one possibility by re-scaling (multiplying) weights, if

(total 
$$u_n^{(t)}$$
 of incorrect) = 1126; (total  $u_n^{(t)}$  of correct) = 6211; (weighted incorrect rate) =  $\frac{1126}{7337}$  (weighted correct rate) =  $\frac{6211}{7337}$  incorrect:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 6211$  correct:  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot 1126$ 

'optimal' re-weighting under weighted incorrect rate  $\epsilon_t$ : multiply incorrect  $\propto (1 - \epsilon_t)$ ; multiply correct  $\propto \epsilon_t$ 

#### Fun Time

For four examples with  $u_n^{(1)} = \frac{1}{4}$  for all examples. If  $g_1$  predicts the first example wrongly but all the other three examples correctly. After the 'optimal' re-weighting, what is  $u_1^{(2)}/u_2^{(2)}$ ?

- **1** 4
- **2** 3
- **3** 1/3
- **4** 1/4

#### Fun Time

For four examples with  $u_n^{(1)} = \frac{1}{4}$  for all examples. If  $g_1$  predicts the first example wrongly but all the other three examples correctly. After the 'optimal' re-weighting, what is  $u_1^{(2)}/u_2^{(2)}$ ?

- **1** 4
- **2** 3
- **3** 1/3
- **4** 1/4

## Reference Answer: 2

By 'optimal' re-weighting,  $u_1$  is scaled proportional to  $\frac{3}{4}$  and every other  $u_n$  is scaled proportional to  $\frac{1}{4}$ . So example 1 is now three times more important than any other example.

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n \neq \frac{g_t}{N} (\mathbf{x}_n) \rrbracket}{\sum_{n=1}^N u_n^{(t)}}$$
,

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n \neq \frac{g_t}{g_t} (\mathbf{x}_n) \rrbracket}{\sum_{n=1}^N u_n^{(t)}},$$

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$

```
\begin{array}{cccc} \text{incorrect} & \leftarrow & \text{incorrect} & \cdot & \blacklozenge_t \\ \text{correct} & \leftarrow & \text{correct} & / & \blacklozenge_t \end{array}
```

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n \neq \underline{g_t}(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^N u_n^{(t)}}$$
,

multiply incorrect  $\propto (1 - \epsilon_t)$ ; multiply correct  $\propto \epsilon_t$ 

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 
$$\frac{\mathsf{incorrect}}{\mathsf{correct}} \leftarrow \frac{\mathsf{incorrect}}{\mathsf{correct}} \cdot \blacklozenge_t$$

equivalent to optimal re-weighting

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} [y_n \neq \underline{g_t}(\mathbf{x}_n)]}{\sum_{n=1}^N u_n^{(t)}}$$
,

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 
$$\begin{array}{ccc} \text{incorrect} & \leftarrow & \text{incorrect} & \cdot & \blacklozenge_t \\ \text{correct} & \leftarrow & \text{correct} & / & \blacklozenge_t \end{array}$$

- · equivalent to optimal re-weighting
- $\phi_t \ge 1$  iff  $\epsilon_t \le \frac{1}{2}$  —physical meaning:

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n \neq \underline{g_t}(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^N u_n^{(t)}}$$
,

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 
$$\frac{\mathsf{incorrect}}{\mathsf{correct}} \leftarrow \frac{\mathsf{incorrect}}{\mathsf{correct}} \cdot \blacklozenge_t$$

- equivalent to optimal re-weighting
- $\phi_t \geq 1$  iff  $\epsilon_t \leq \frac{1}{2}$ 
  - —physical meaning: scale up incorrect; scale down correct

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket}{\sum_{n=1}^N u_n^{(t)}}$$
,

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 
$$\frac{\mathsf{incorrect}}{\mathsf{correct}} \leftarrow \frac{\mathsf{incorrect}}{\mathsf{correct}} \cdot \blacklozenge_t$$

- · equivalent to optimal re-weighting
- $\phi_t \geq 1$  iff  $\epsilon_t \leq \frac{1}{2}$ 
  - —physical meaning: scale up incorrect; scale down correct
  - —like what Teacher does

'optimal' re-weighting: let 
$$\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} [y_n \neq \mathbf{g}_t(\mathbf{x}_n)]}{\sum_{n=1}^N u_n^{(t)}}$$
,

multiply incorrect  $\propto (1 - \epsilon_t)$ ; multiply correct  $\propto \epsilon_t$ 

define scaling factor 
$$\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 
$$\frac{\mathsf{incorrect}}{\mathsf{correct}} \leftarrow \frac{\mathsf{incorrect}}{\mathsf{correct}} \cdot \blacklozenge_t$$

- equivalent to optimal re-weighting
- $\phi_t \ge 1$  iff  $\epsilon_t \le \frac{1}{2}$ 
  - —physical meaning: scale up incorrect; scale down correct
  - —like what Teacher does

scaling-up incorrect examples leads to diverse hypotheses

$$\mathbf{u}^{(1)} = ?$$
 for  $t = 1, 2, ..., T$ 

1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error

$$\mathbf{u}^{(1)} = ?$$
 for  $t = 1, 2, ..., T$ 

- 1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$

```
\mathbf{u}^{(1)} = ? for t = 1, 2, ..., T
```

- 1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x})$  =?

```
u^{(1)} = ? for t = 1, 2, ..., T
```

- ① obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$

```
\mathbf{u}^{(1)} = ? for t = 1, 2, ..., T
```

- ① obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$
  - G(x):

```
\mathbf{u}^{(1)} = ? for t = 1, 2, ..., T
```

- 1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$
  - *G*(**x**):
    - uniform?

```
u^{(1)} = ? for t = 1, 2, ..., T
```

- ① obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$
  - G(x):
    - uniform? but g<sub>2</sub> very bad for E<sub>in</sub> (why?:-))

```
u^{(1)} = ? for t = 1, 2, ..., T
```

- ① obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$
  - G(x):
    - uniform? but  $g_2$  very bad for  $E_{in}$  (why? :-))
    - linear, non-linear? as you wish

```
u^{(1)} = ? for t = 1, 2, ..., T
```

- ① obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where  $\epsilon_t$  = weighted error (incorrect) rate of  $g_t$  return  $G(\mathbf{x}) = ?$ 
  - want  $g_1$  'best' for  $E_{in}$ :  $u_n^{(1)} = \frac{1}{N}$
  - *G*(**x**):
    - uniform? but g<sub>2</sub> very bad for E<sub>in</sub> (why? :-))
    - linear, non-linear? as you wish

next: a special algorithm to aggregate **linearly on the fly** with theoretical guarantee

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- ② update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- $\odot$  compute  $\alpha_t$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- ② update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- 3 compute  $\alpha_t$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

wish: large  $\alpha_t$  for 'good'  $g_t \leftarrow$ 

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- $\odot$  compute  $\alpha_t$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

• wish: large  $\alpha_t$  for 'good'  $g_t \longleftarrow \alpha_t = \text{monotonic}(\phi_t)$ 

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- 3 compute  $\alpha_t = \ln(\blacklozenge_t)$ return  $G(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^T \alpha_t g_t(\mathbf{x})\right)$ 
  - wish: large α<sub>t</sub> for 'good' g<sub>t</sub> ← α<sub>t</sub> = monotonic(♦<sub>t</sub>)
  - will take  $\alpha_t = \ln(\blacklozenge_t)$

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- 3 compute  $\alpha_t = \ln(\phi_t)$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

- wish: large  $\alpha_t$  for 'good'  $g_t \longleftarrow \alpha_t = \text{monotonic}(\blacklozenge_t)$
- will take  $\alpha_t = \ln(\blacklozenge_t)$ 
  - $\epsilon_t = \frac{1}{2} \Longrightarrow \bullet_t = 1 \Longrightarrow \alpha_t = 0$  (bad  $g_t$  zero weight)

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- 3 compute  $\alpha_t = \ln(\blacklozenge_t)$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

- wish: large  $\alpha_t$  for 'good'  $g_t \longleftarrow \alpha_t = \text{monotonic}(\phi_t)$
- will take  $\alpha_t = \ln(\blacklozenge_t)$ 
  - $\epsilon_t = \frac{1}{2} \Longrightarrow \blacklozenge_t = 1 \Longrightarrow \alpha_t = 0$  (bad  $g_t$  zero weight)
  - $\epsilon_t = \bar{0} \Longrightarrow \blacklozenge_t = \infty \Longrightarrow \alpha_t = \infty$  (super  $g_t$  superior weight)

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- **1** obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where ...
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , where ...
- 3 compute  $\alpha_t = \ln(\phi_t)$

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

- wish: large α<sub>t</sub> for 'good' g<sub>t</sub> ← α<sub>t</sub> = monotonic(♦<sub>t</sub>)
- will take  $\alpha_t = \ln(\blacklozenge_t)$ 
  - $\epsilon_t = \frac{1}{2} \Longrightarrow \bullet_t = 1 \Longrightarrow \alpha_t = 0$  (bad  $g_t$  zero weight)
  - $\epsilon_t = 0 \Longrightarrow \phi_t = \infty \Longrightarrow \alpha_t = \infty$  (super  $q_t$  superior weight)
- Adaptive Boosting = weak base learning algorithm  $\mathcal{A}$  (Student)
  - + optimal re-weighting factor ♦<sub>t</sub> (Teacher)
  - + 'magic' linear aggregation  $\alpha_t$  (Class)

# Adaptive Boosting (AdaBoost) Algorithm

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- 1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by

$$[y_n \neq g_t(\mathbf{x}_n)]$$
 (incorrect examples):  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot \blacklozenge_t$   $[y_n = g_t(\mathbf{x}_n)]$  (correct examples):  $u_n^{(t+1)} \leftarrow u_n^{(t)} / \blacklozenge_t$ 

where 
$$lacklost _t = \sqrt{rac{1-\epsilon_t}{\epsilon_t}}$$
 and  $\epsilon_t = rac{\sum_{n=1}^N u_n^{(t)} \llbracket y_n 
eq g_t(\mathbf{x}_n) 
rbracket}{\sum_{n=1}^N u_n^{(t)}}$ 

3 compute  $\alpha_t = \ln(\blacklozenge_t)$ 

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

# Adaptive Boosting (AdaBoost) Algorithm

$$\mathbf{u}^{(1)} = [\frac{1}{N}, \frac{1}{N}, \cdots, \frac{1}{N}]$$
  
for  $t = 1, 2, \dots, T$ 

- 1 obtain  $g_t$  by  $\mathcal{A}(\mathcal{D}, \mathbf{u}^{(t)})$ , where  $\mathcal{A}$  tries to minimize  $\mathbf{u}^{(t)}$ -weighted 0/1 error
- 2 update  $\mathbf{u}^{(t)}$  to  $\mathbf{u}^{(t+1)}$  by

$$\llbracket y_n \neq g_t(\mathbf{x}_n) \rrbracket$$
 (incorrect examples):  $u_n^{(t+1)} \leftarrow u_n^{(t)} \cdot \blacklozenge_t$   $\llbracket y_n = g_t(\mathbf{x}_n) \rrbracket$  (correct examples):  $u_n^{(t+1)} \leftarrow u_n^{(t)} / \blacklozenge_t$ 

where 
$$lackloslash_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$$
 and  $\epsilon_t = \frac{\sum_{n=1}^N u_n^{(t)} [y_n \neq g_t(\mathbf{x}_n)]}{\sum_{n=1}^N u_n^{(t)}}$ 

3 compute  $\alpha_t = \ln(\blacklozenge_t)$ 

return 
$$G(\mathbf{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t g_t(\mathbf{x})\right)$$

AdaBoost: provable boosting property

From VC bound

$$E_{\text{out}}(G) \leq E_{\text{in}}(G) + O\left(\sqrt{\underbrace{O(d_{\text{VC}}(\mathcal{H}) \cdot T \log T)}_{d_{\text{VC}} \text{ of all possible } G} \cdot \frac{\log N}{N}}\right)$$

From VC bound

$$E_{\text{out}}(G) \leq E_{\text{in}}(G) + O\left(\sqrt{\underbrace{O(d_{\text{VC}}(\mathcal{H}) \cdot T \log T)}_{d_{\text{VC}} \text{ of all possible } G} \cdot \frac{\log N}{N}}\right)$$

first term can be small:

$$E_{in}(G) = 0$$
 after  $T = O(\log N)$  iterations if  $\epsilon_t \le \epsilon < \frac{1}{2}$  always

From VC bound

$$E_{\text{out}}(G) \leq E_{\text{in}}(G) + O\left(\sqrt{\underbrace{O(d_{\text{VC}}(\mathcal{H}) \cdot T \log T)}_{d_{\text{VC}} \text{ of all possible } G} \cdot \frac{\log N}{N}}\right)$$

- first term can be small:
  - $E_{in}(G) = 0$  after  $T = O(\log N)$  iterations if  $\epsilon_t \le \epsilon < \frac{1}{2}$  always
- second term can be small: overall d<sub>VC</sub> grows "slowly" with T

From VC bound

$$E_{\mathrm{out}}(G) \leq E_{\mathrm{in}}(G) + O\left(\sqrt{\underbrace{O(d_{\mathrm{VC}}(\mathcal{H}) \cdot T \log T)}_{d_{\mathrm{VC}} \text{ of all possible } G} \cdot \frac{\log N}{N}}\right)$$

- first term can be small
  - $E_{in}(G) = 0$  after  $T = O(\log N)$  iterations if  $\epsilon_t \le \epsilon < \frac{1}{2}$  always
- second term can be small: overall d<sub>VC</sub> grows "slowly" with T

#### boosting view of AdaBoost:

if A is weak but always **slightly better than random** ( $\epsilon_t \le \epsilon < \frac{1}{2}$ ), then (AdaBoost+A) can be strong ( $E_{in} = 0$  and  $E_{out}$  small)

### Fun Time

According to  $\alpha_t = \ln(\blacklozenge_t)$ , and  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , when would  $\alpha_t > 0$ ?

- 1  $\epsilon_t < \frac{1}{2}$
- **2**  $\epsilon_t > \frac{1}{2}$
- $3 \epsilon_t \neq 1$
- $4 \epsilon_t \neq 0$

#### Fun Time

According to  $\alpha_t = \ln(\blacklozenge_t)$ , and  $\blacklozenge_t = \sqrt{\frac{1-\epsilon_t}{\epsilon_t}}$ , when would  $\alpha_t > 0$ ?

- $\bullet_t < \tfrac{1}{2}$
- $2 \epsilon_t > \frac{1}{2}$
- $\epsilon_t \neq 1$
- $\mathbf{4} \; \epsilon_t \neq \mathbf{0}$

# Reference Answer: (1)

The math part should be easy for you, and it is interesting to think about the physical meaning:  $\alpha_t > 0$  ( $g_t$  is useful for G) if and only if the weighted error rate of  $g_t$  is better than random!

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} u_n \cdot [\![ y_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{u}_n \cdot [\![ \mathbf{y}_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

### a popular choice: decision stump

• in ML Foundations Homework 2, remember? :-)

$$h_{\mathbf{s},i,\theta}(\mathbf{x}) = \mathbf{s} \cdot \operatorname{sign}(x_i - \theta)$$

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{u}_n \cdot [\![ \mathbf{y}_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

### a popular choice: decision stump

• in ML Foundations Homework 2, remember? :-)

$$h_{\mathbf{s},i,\theta}(\mathbf{x}) = \mathbf{s} \cdot \operatorname{sign}(x_i - \theta)$$

 positive and negative rays on some feature: three parameters (feature i, threshold θ, direction s)

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{u}_n \cdot [\![ \mathbf{y}_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

### a popular choice: decision stump

• in ML Foundations Homework 2, remember? :-)

$$h_{\mathbf{s},i,\theta}(\mathbf{x}) = \mathbf{s} \cdot \operatorname{sign}(x_i - \theta)$$

- positive and negative rays on some feature: three parameters (feature i, threshold θ, direction s)
- physical meaning: vertical/horizontal lines in 2D

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{u}_n \cdot [\![ \mathbf{y}_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

### a popular choice: decision stump

• in ML Foundations Homework 2, remember? :-)

$$h_{\mathbf{s},i,\theta}(\mathbf{x}) = \mathbf{s} \cdot \operatorname{sign}(x_i - \theta)$$

- positive and negative rays on some feature: three parameters (feature i, threshold θ, direction s)
- physical meaning: vertical/horizontal lines in 2D
- efficient to optimize: O(d ⋅ N log N) time

want: a 'weak' base learning algorithm  $\mathcal{A}$  that minimizes  $E_{\text{in}}^{\mathbf{u}}(h) = \frac{1}{N} \sum_{n=1}^{N} \mathbf{u}_n \cdot [\![ \mathbf{y}_n \neq h(\mathbf{x}_n) ]\!]$  a little bit

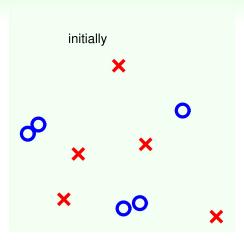
### a popular choice: decision stump

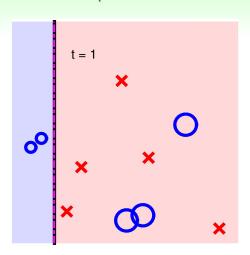
• in ML Foundations Homework 2, remember? :-)

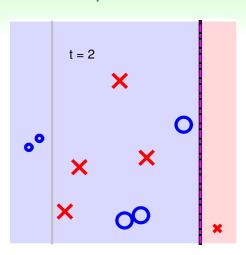
$$h_{\mathbf{s},i,\theta}(\mathbf{x}) = \mathbf{s} \cdot \operatorname{sign}(x_i - \theta)$$

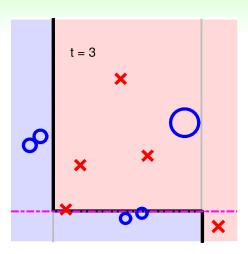
- positive and negative rays on some feature: three parameters (feature i, threshold θ, direction s)
- physical meaning: vertical/horizontal lines in 2D
- efficient to optimize: O(d · N log N) time

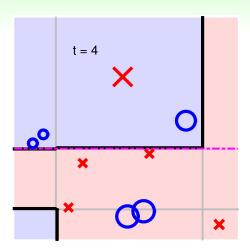
decision stump model: allows efficient minimization of  $E_{in}^{u}$ but perhaps too weak to work by itself

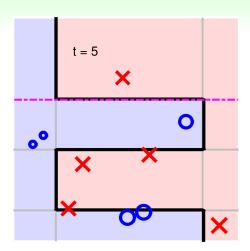


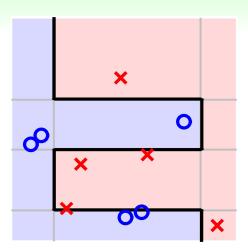




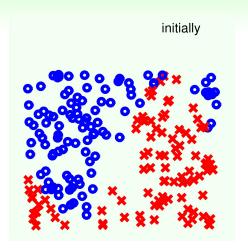


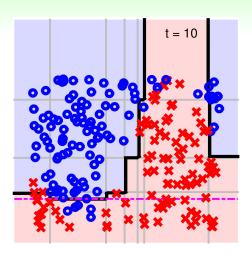


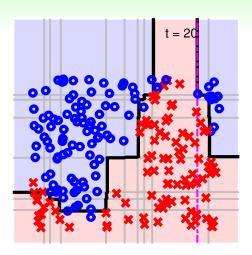


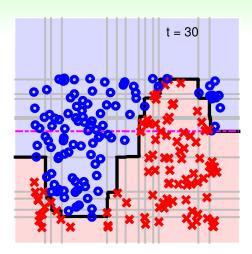


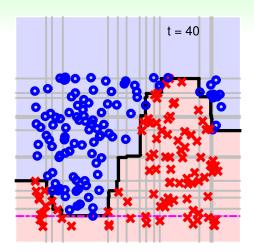
'Teacher'-like algorithm works!

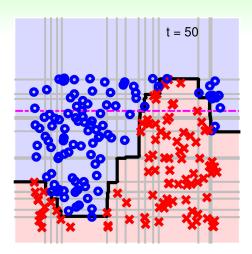


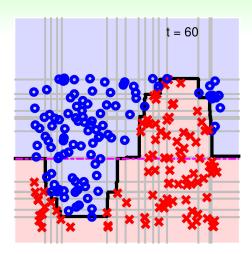


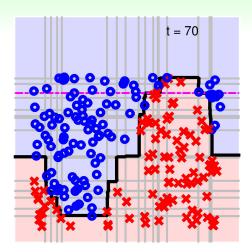


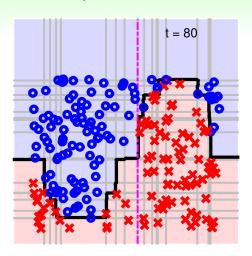


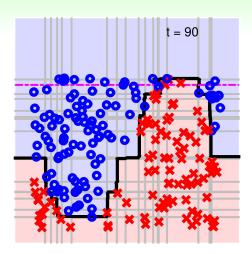


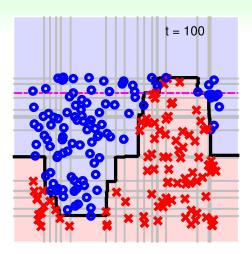












AdaBoost-Stump: non-linear yet efficient

Adaptive Boosting in Action

# AdaBoost-Stump in Application



original picture by F.U.S.I.A. assistant and derivative work by Sylenius via Wikimedia Commons

The World's First 'Real-Time' Face Detection Program

Adaptive Boosting in Action

### AdaBoost-Stump in Application



original picture by F.U.S.I.A. assistant and derivative work by Sylenius via Wikimedia Commons

### The World's First 'Real-Time' Face Detection Program

 AdaBoost-Stump as core model: linear aggregation of key patches selected out of 162,336 possibilities in 24x24 images —feature selection achieved through AdaBoost-Stump

Hsuan-Tien Lin (NTU CSIE)

Adaptive Boosting in Action

### AdaBoost-Stump in Application



original picture by F.U.S.I.A. assistant and derivative work by Sylenius via Wikimedia Commons

### The World's First 'Real-Time' Face Detection Program

- AdaBoost-Stump as core model: linear aggregation of key patches selected out of 162,336 possibilities in 24x24 images —feature selection achieved through AdaBoost-Stump
- modified linear aggregation G to rule out non-face earlier
   efficiency achieved through modified linear aggregation

### AdaBoost-Stump in Application



original picture by F.U.S.I.A. assistant and derivative work by Sylenius via Wikimedia Commons

### The World's First 'Real-Time' Face Detection Program

- AdaBoost-Stump as core model: linear aggregation of key patches selected out of 162,336 possibilities in 24x24 images —feature selection achieved through AdaBoost-Stump
- modified linear aggregation G to rule out non-face earlier
   efficiency achieved through modified linear aggregation

# AdaBoost-Stump:

efficient feature selection and aggregation

### Fun Time

For a data set of size 9876 that contains  $\mathbf{x}_n \in \mathbb{R}^{5566}$ , after running AdaBoost-Stump for 1126 iterations, what is the number of distinct features within  $\mathbf{x}$  that are effectively used by G?

- $0 \le \text{number} \le 1126$
- 2 1126 < number ≤ 5566</p>
- **3**  $5566 < \text{number} \le 9876$
- 4 9876 < number

#### Fun Time

For a data set of size 9876 that contains  $\mathbf{x}_n \in \mathbb{R}^{5566}$ , after running AdaBoost-Stump for 1126 iterations, what is the number of distinct features within  $\mathbf{x}$  that are effectively used by G?

- **1**  $0 \le \text{number} \le 1126$
- 2 1126 < number ≤ 5566</p>
- **3**  $5566 < number \le 9876$
- 4 9876 < number

# Reference Answer: 1

Each decision stump takes only one feature. So 1126 decision stumps need at most 1126 distinct features.

# Summary

- 1 Embedding Numerous Features: Kernel Models
- 2 Combining Predictive Features: Aggregation Models

### Lecture 8: Adaptive Boosting

- Motivation of Boosting aggregate weak hypotheses for strength
- Diversity by Re-weighting scale up incorrect, scale down correct
- Adaptive Boosting Algorithm two heads are better than one, theoretically
- Adaptive Boosting in Action
   AdaBoost-Stump useful and efficient
- next: learning conditional aggregation instead of linear one
- 3 Distilling Implicit Features: Extraction Models