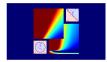
Machine Learning Foundations

(機器學習基石)



Lecture 4: Feasibility of Learning

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Roadmap

1 When Can Machines Learn?

Lecture 3: Types of Learning

focus: binary classification or regression from a batch of supervised data with concrete features

Lecture 4: Feasibility of Learning

- Learning is Impossible?
- Probability to the Rescue
- Connection to Learning
- Connection to Real Learning
- 2 Why Can Machines Learn?
- 3 How Can Machines Learn?
- 4 How Can Machines Learn Better?

A Learning Puzzle















$$y_n = +1$$



$$g(\mathbf{x}) = ?$$

let's test your 'human learning' with 6 examples :-)

whatever you say about $g(\mathbf{x})$,





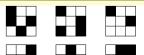






$$g(\mathbf{x}) = ?$$

whatever you say about $g(\mathbf{x})$,







$$g(\mathbf{x}) = ?$$

truth $f(\mathbf{x}) = +1$ because . . .

symmetry ⇔ +1

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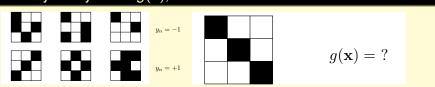
truth $f(\mathbf{x}) = +1$ because . . .

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truth
$$f(\mathbf{x}) = -1$$
 because . . .

left-top black ⇔ -1

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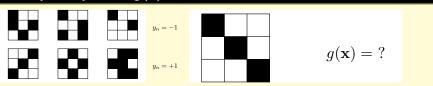
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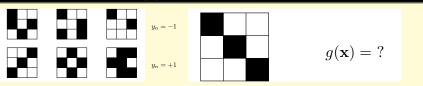
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- middle column contains at most 1 black and right-top white ⇔ -1

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all valid reasons, your adversarial teacher can always call you 'didn't learn'. :-(

A 'Simple' Binary Classification Problem

$$\begin{array}{c|cccc} \mathbf{x}_n & y_n = f(\mathbf{x}_n) \\ \hline 0 0 0 & \circ \\ 0 0 1 & \times \\ 0 1 0 & \times \\ 0 1 1 & \circ \\ 1 0 0 & \times \\ \end{array}$$

• $\mathcal{X} = \{0, 1\}^3$, $\mathcal{Y} = \{0, \times\}$, can enumerate all candidate f as \mathcal{H}

pick
$$g \in \mathcal{H}$$
 with all $g(\mathbf{x}_n) = y_n$ (like PLA), does $g \approx f$?

No Free Lunch

	X	у	g	f_1	f_2	f_3	f_4	<i>f</i> ₅	f_6	f ₇	f_8
	000	0	0	0	0	0	0	0	0	0	0
_	0 0 1	×	×	×	×	X	×			×	
\mathcal{D}	010	×	×	×	X	×	×	×	×	×	×
	0 1 1	0	0	0	0	0	0			0	0
	100	×	×	×	X	×	×	×	×	×	×
	1 0 1		?	0	0	0	0	×	×	×	×
	110		?	0	0	×	×	0	0	×	×
	111		?	0	×	0	×	0	×	0	×

• $g \approx f$ inside \mathcal{D} : sure!

No Free Lunch

	x	у	g	f_1	f_2	f_3	f_4	<i>f</i> ₅	<i>f</i> ₆	f ₇	f_8
	000	0	0	0	0	0	0	0	0	0	0
_	001	×	×	×	×	X	×	X	×	×	×
\mathcal{D}	010	×	×	×	X	×	×	×	×	×	×
$\boldsymbol{\nu}$	011	0	0	0	0	0	0	0	0	0	0
	100	×	×	×	×	×	×	×	×	×	×
,	101		?	0	0	0	0	X	×	×	×
	110		?	0	0	X	×	0	0	×	×
	111		?	0	×	0	×	0	×	0	×

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_	0 0 1	×	×	×	×	X			×		
\mathcal{D}	010	×	×	×	×	X	×	X	×	×	×
	011	0	0	0	0	0				0	0
	100	×	×	×	×	×	×	×	×	×	×
	101		?	0	0	0	0				×
	110		?	0	0	X	×	0	0	×	×
	111		?	0	×	0	×				×

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learning from \mathcal{D} (to infer something outside \mathcal{D}) is doomed if any 'unknown' f can happen. :-(

Fun Time

This is a popular 'brain-storming' problem, with a claim that 2% of the world's cleverest population can crack its 'hidden pattern'.

$$(5,3,2) \rightarrow 151022, \quad (7,2,5) \rightarrow ?$$

It is like a 'learning problem' with N = 1, $\mathbf{x}_1 = (5, 3, 2)$, $y_1 = 151022$. Learn a hypothesis from the one example to predict on $\mathbf{x} = (7, 2, 5)$. What is your answer?

151026

3 I need more examples to get the correct answer

2 143547

4 there is no 'correct' answer

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Reference Answer: (4)

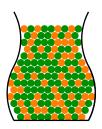
Following the same nature of the no-free-lunch problems discussed, we cannot hope to be correct under this 'adversarial' setting. BTW, (2) is the designer's answer: the first two digits $= x_1 \cdot x_2$; the next two digits $= x_1 \cdot x_3$; the last two digits $= (x_1 \cdot x_2 + x_1 \cdot x_3 - x_2)$.

Inferring Something Unknown

difficult to infer unknown target f outside \mathcal{D} in learning; can we infer something unknown in other scenarios?

Inferring Something Unknown

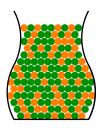
difficult to infer unknown target f outside \mathcal{D} in learning; can we infer something unknown in other scenarios?



- consider a bin of many many orange and green marbles
- do we know the orange portion (probability)? No!

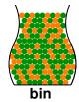
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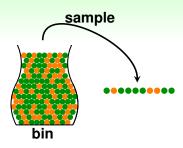
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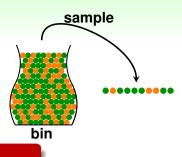


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can you infer the orange probability?



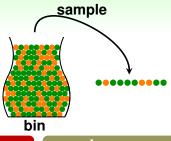




bin

assume

orange probability = μ , green probability = $1 - \mu$, with μ unknown



bin

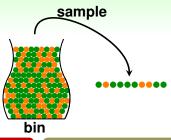
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sample

N marbles sampled independently, with orange fraction = ν , green fraction = 1 - ν ,

now ν known



bin

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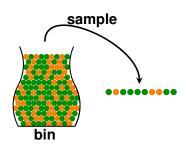
sample

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does in-sample ν say anything about out-of-sample μ ?

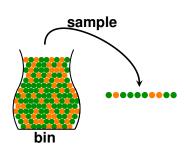
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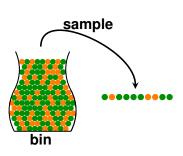
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Yes!

probably yes: in-sample ν likely **close** to unknown μ



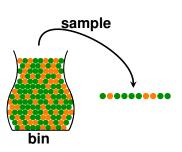
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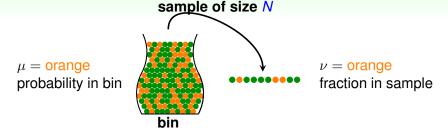
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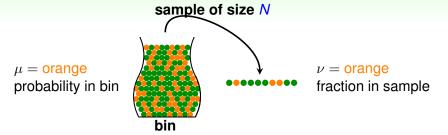


formally, what does ν say about μ ?



• in big sample (*N* large), ν is probably close to μ (within ϵ)

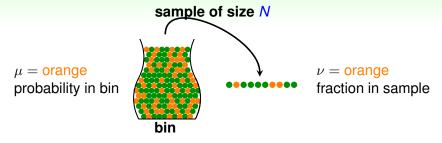
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called Hoeffding's Inequality, for marbles, coin, polling, . . .



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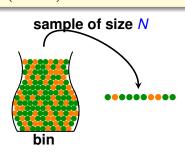
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called Hoeffding's Inequality, for marbles, coin, polling, ...

the statement ' $\nu = \mu$ ' is probably approximately correct (PAC)

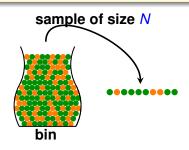
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• valid for all N and ϵ



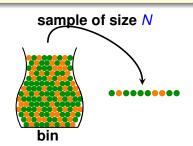
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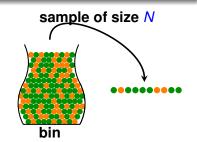
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if large N, can probably infer unknown μ by known ν

Fun Time

Let $\mu = 0.4$. Use Hoeffding's Inequality

$$\mathbb{P}\left[\left|\nu-\mu\right|>\epsilon\right]\leq 2\exp\left(-2\epsilon^2N\right)$$

to bound the probability that a sample of 10 marbles will have $\nu \leq$ 0.1. What bound do you get?

- **1** 0.67
- **2** 0.40
- **3** 0.33
- 4 0.05

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Reference Answer: (3)

Set N=10 and $\epsilon=0.3$ and you get the answer. BTW, 4 is the actual probability and Hoeffding gives only an upper bound to that.

bin

- unknown orange prob. μ
- marble ∈ bin
- orange •
- green •
- size-N sample from bin

of i.i.d. marbles



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<u>learning</u>

target f



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learning

target $f(\mathbf{x})$



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learning

• fixed hypothesis $h(\mathbf{x}) \stackrel{?}{=} \text{target } f(\mathbf{x})$



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- $\mathbf{x} \in \mathcal{X}$



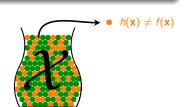
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learning

- fixed hypothesis $h(\mathbf{x}) \stackrel{?}{=} \text{target } f(\mathbf{x})$
- $\mathbf{x} \in \mathcal{X}$
- h is wrong $\Leftrightarrow h(\mathbf{x}) \neq f(\mathbf{x})$



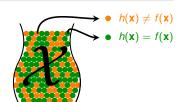
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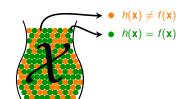
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- check h on $\mathcal{D} = \{(\mathbf{x}_n, \underbrace{y_n}_{f(\mathbf{x}_n)})\}$

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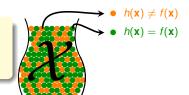
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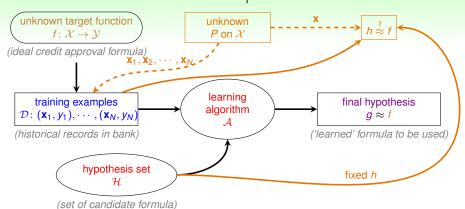
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with i.i.d. \mathbf{x}_n

if large N & i.i.d. \mathbf{x}_n , can probably infer unknown $[\![h(\mathbf{x}) \neq f(\mathbf{x})]\!]$ probability by known $[\![h(\mathbf{x}_n) \neq y_n]\!]$ fraction



Added Components



for any fixed h, can probably infer

unknown
$$E_{\text{out}}(\mathbf{h}) = \underset{\mathbf{x} \sim P}{\mathcal{E}} [h(\mathbf{x}) \neq f(\mathbf{x})]$$

by known $E_{\text{in}}(\mathbf{h}) = \frac{1}{N} \sum_{n=1}^{N} [h(\mathbf{x}_n) \neq y_n].$

for any fixed h, in 'big' data (N large),

in-sample error $E_{\text{in}}(h)$ is probably close to out-of-sample error $E_{\text{out}}(h)$ (within ϵ)

$$\mathbb{P}\left[\left|\mathcal{E}_{\mathsf{in}}(h) - \mathcal{E}_{\mathsf{out}}(h)\right| > \epsilon\right] \leq 2\exp\left(-2\epsilon^2\mathsf{N}\right)$$

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same as the 'bin' analogy ...

valid for all N and ε

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if
$${}^{`}E_{in}(h) \approx E_{out}(h){}^{"}$$
 and ${}^{`}E_{in}(h)$ small $\Longrightarrow E_{out}(h)$ small

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$${}^{`}E_{\text{in}}(h) \approx E_{\text{out}}(h){}^{"}$$
 and ${}^{`}E_{\text{in}}(h)$ small' $\Longrightarrow E_{\text{out}}(h)$ small $\Longrightarrow h \approx f$ with respect to P

for any fixed h, when data large enough,

$$E_{\text{in}}(h) \approx E_{\text{out}}(h)$$

for any fixed h, when data large enough,

$$E_{\text{in}}(h) \approx E_{\text{out}}(h)$$

Can we claim 'good learning' ($g \approx f$)?

for any fixed h, when data large enough,

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Can we claim 'good learning' ($g \approx f$)?

Yes!

if $E_{in}(h)$ small for the fixed h and A pick the h as g

$$\implies$$
 ' $g = f$ ' PAC

for any fixed *h*, when data large enough,

$$E_{\text{in}}(h) \approx E_{\text{out}}(h)$$

Can we claim 'good learning' $(g \approx f)$?

Yes!

if $E_{in}(h)$ small for the fixed h and A pick the h as g $\implies `q = f' \text{ PAC}$

No!

if ${\mathcal A}$ forced to pick THE h as g

for any fixed h, when data large enough,

$$E_{\text{in}}(h) \approx E_{\text{out}}(h)$$

Can we claim 'good learning' $(g \approx f)$?

Yes!

if $E_{in}(h)$ small for the fixed h and A pick the h as g \Longrightarrow 'g = f' PAC

No!

if \mathcal{A} forced to pick THE h as g $\Longrightarrow E_{\mathrm{in}}(h)$ almost always not small

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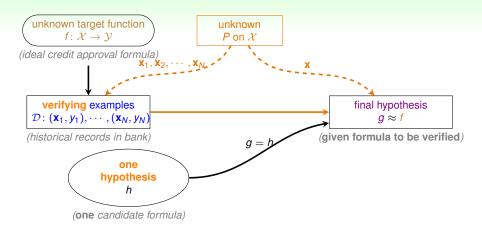
No!

if \mathcal{A} forced to pick THE h as g $\Rightarrow E_{\text{in}}(h)$ almost always not small $\Rightarrow g \neq f$ PAC!

real learning:

 \mathcal{A} shall make choices $\in \mathcal{H}$ (like PLA) rather than being forced to pick one h. :-(

The 'Verification' Flow



can now use 'historical records' (data) to verify 'one candidate formula' h

Your friend tells you her secret rule in investing in a particular stock: 'Whenever the stock goes down in the morning, it will go up in the afternoon; vice versa.' To verify the rule, you chose 100 days uniformly at random from the past 10 years of stock data, and found that 80 of them satisfy the rule. What is the best guarantee that you can get from the verification?

- 1 You'll definitely be rich by exploiting the rule in the next 100 days.
- 2 You'll likely be rich by exploiting the rule in the next 100 days, if the market behaves similarly to the last 10 years.
- 3 You'll likely be rich by exploiting the 'best rule' from 20 more friends in the next 100 days.
- You'd definitely have been rich if you had exploited the rule in the past 10 years.

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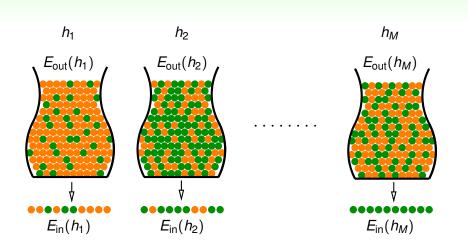
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- 4 You'd definitely have been rich if you had exploited the rule in the past 10 years.

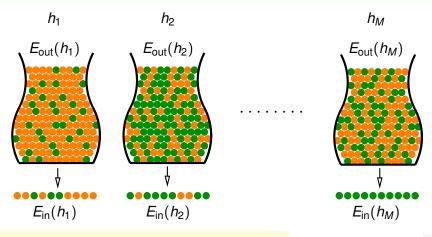
Reference Answer: (2)

(1): no free lunch; (3): no 'learning' guarantee in verification; (4): verifying with only 100 days, possible that the rule is mostly wrong for whole 10 years.

Multiple h



Multiple h



real learning (say like PLA):

BINGO when getting •••••••?



Q: if everyone in size-150 NTU ML class flips a coin 5 times, and one of the students gets 5 heads for her coin 'g'. Is 'g' really magical?



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BAD sample: E_{in} and E_{out} far away
—can get worse when involving 'choice'

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e.g., $E_{out} = \frac{1}{2}$, but getting all heads ($E_{in} = 0$)!

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	\mathcal{D}_1	\mathcal{D}_2	 D_{1126}	 D_{5678}	 Hoeffding
h	BAD			BAD	$\mathbb{P}_{\mathcal{D}}\left[\mathbf{BAD} \ \mathcal{D} \ \text{for } h \right] \leq \dots$

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Hoeffding: small

$$\mathbb{P}_{\mathcal{D}}\left[\textbf{BAD} \; \mathcal{D} \right] = \sum_{\mathsf{all \; possible} \mathcal{D}} \mathbb{P}(\mathcal{D}) \cdot \left[\!\!\left[\textbf{BAD} \; \mathcal{D} \right] \!\!\right]$$

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h_1	BAD					BAD	$\mathbb{P}_{\mathcal{D}}\left[\mathbf{BAD} \ \mathcal{D} \text{ for } h_1 \right] \leq \dots$	
h_2		BAD					$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;h_2\right]\leq\ldots$	
h_3	BAD	BAD				BAD	$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;\mathit{h}_{3}\right]\leq\ldots$	
h_M	BAD					BAD	$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;h_{M}\right]\leq\ldots$	

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all	BAD	BAD		BAD	?

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h ₂		BAD			$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;h_{2}\right]\leq\ldots$
h ₃	BAD	BAD		BAD	$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;h_3\right]\leq\ldots$
h_{M}	BAD			BAD	$\mathbb{P}_{\mathcal{D}}\left[BAD\;\mathcal{D}\;for\;h_{M}\right]\leq\ldots$
all	BAD	BAD		BAD	?

for *M* hypotheses, bound of $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\ \mathcal{D}]$?

Connection to Real Learning

Bound of BAD Data

 $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\;\mathcal{D}]$

 $= \mathbb{P}_{\mathcal{D}} [\mathbf{BAD} \ \mathcal{D} \text{ for } h_1 \text{ or } \mathbf{BAD} \ \mathcal{D} \text{ for } h_2 \text{ or } \dots \text{ or } \mathbf{BAD} \ \mathcal{D} \text{ for } h_M]$

 \leq

 $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\;\mathcal{D}]$

 $\mathbb{P}_{\mathcal{D}}$ [BAD \mathcal{D} for h_1 or BAD \mathcal{D} for h_2 or ... or BAD \mathcal{D} for h_M]

 $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\ \mathcal{D}\ \mathsf{for}\ h_1] + \mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\ \mathcal{D}\ \mathsf{for}\ h_2] + \ldots + \mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\ \mathcal{D}\ \mathsf{for}\ h_M]$

Connection to Real Learning

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\mathbb{P}_{\mathcal{D}}[\mathsf{BAD}\;\mathcal{D}]
```

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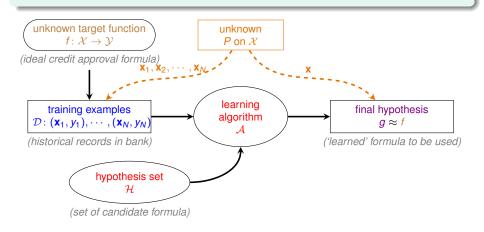
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'most reasonable' \mathcal{A} (like PLA/pocket): pick the h_m with lowest $E_{in}(h_m)$ as g

Connection to Real Learning The 'Statistical' Learning Flow

if $|\mathcal{H}| = M$ finite, N large enough, for whatever g picked by A, $E_{\text{out}}(g) \approx E_{\text{in}}(g)$



```
 \text{if } |\mathcal{H}| = \textit{M} \text{ finite, } \textit{N} \text{ large enough,} \\ \text{for whatever } \textit{g} \text{ picked by } \mathcal{A}, \ \textit{E}_{\text{out}}(\textit{g}) \approx \textit{E}_{\text{in}}(\textit{g}) \\ \text{if } \mathcal{A} \text{ finds one } \textit{g} \text{ with } \textit{E}_{\text{in}}(\textit{g}) \approx \textit{0}, \\ \end{aligned}
```

PAC guarantee for $E_{\text{out}}(q) \approx 0$

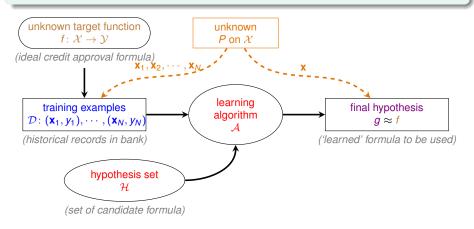
unknown target function unknown $f \colon \mathcal{X} \to \mathcal{V}$ P on \mathcal{X} (ideal credit approval formula) learning final hypothesis training examples algorithm $\mathcal{D}: (\mathbf{x}_1, y_1), \cdots, (\mathbf{x}_N, y_N)$ $q \approx f$ (historical records in bank) ('learned' formula to be used) hypothesis set \mathcal{H} (set of candidate formula)

The 'Statistical' Learning Flow

if $|\mathcal{H}| = M$ finite, N large enough, for whatever g picked by \mathcal{A} , $E_{\text{out}}(g) \approx E_{\text{in}}(g)$

if \mathcal{A} finds one g with $E_{\text{in}}(g) \approx 0$,

PAC guarantee for $E_{\text{out}}(g) \approx 0 \Longrightarrow$ learning possible :-)

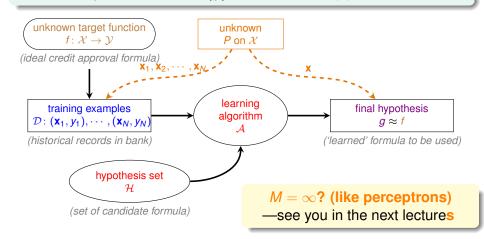


The 'Statistical' Learning Flow if $|\mathcal{H}| = M$ finite. N large enough

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PAC guarantee for $E_{\mathsf{out}}(g) \approx 0 \Longrightarrow \mathsf{learning}$ possible :-)



Fun Time

Consider 4 hypotheses.

$$h_1(\mathbf{x}) = \text{sign}(x_1), \ h_2(\mathbf{x}) = \text{sign}(x_2),$$

 $h_3(\mathbf{x}) = \text{sign}(-x_1), \ h_4(\mathbf{x}) = \text{sign}(-x_2).$

For any N and ϵ , which of the following statement is not true?

- 1 the BAD data of h_1 and the BAD data of h_2 are exactly the same
- 2 the BAD data of h_1 and the BAD data of h_3 are exactly the same
- 3 $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \text{ for some } h_k] \leq 8 \exp\left(-2\epsilon^2 N\right)$
- **4** $\mathbb{P}_{\mathcal{D}}[\mathsf{BAD} \text{ for some } h_k] \leq 4 \exp\left(-2\epsilon^2 N\right)$

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Reference Answer: 1

The important thing is to note that (2) is true, which implies that (4) is true if you revisit the union bound. Similar ideas will be used to conguer the $M=\infty$ case.

Summary

1 When Can Machines Learn?

Lecture 3: Types of Learning

Lecture 4: Feasibility of Learning

- Learning is Impossible?
 absolutely no free lunch outside D
- ullet Probability to the Rescue probably approximately correct outside ${\mathcal D}$
- Connection to Learning
 verification possible if E_{in}(h) small for fixed h
- Connection to Real Learning learning possible if $|\mathcal{H}|$ finite and $E_{in}(g)$ small
- 2 Why Can Machines Learn?
 - next: what if $|\mathcal{H}| = \infty$?
- 3 How Can Machines Learn?
- 4 How Can Machines Learn Better?