

A FAST GENERAL METHODOLOGY FOR INFORMATION-THEORETICALLY OPTIMAL ENCODINGS OF GRAPHS*

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Abstract. We propose a fast methodology for encoding graphs with information-theoretically minimum numbers of bits. Specifically, a graph with property π is called a π -graph. If π satisfies certain properties, then an n -node m -edge π -graph G can be encoded by a binary string X such that (1) G and X can be obtained from each other in $O(n \log n)$ time, and (2) X has at most $\beta(n) + o(\beta(n))$ bits for any continuous superadditive function $\beta(n)$ so that there are at most $2^{\beta(n) + o(\beta(n))}$ distinct n -node π -graphs. The methodology is applicable to general classes of graphs; this paper focuses on planar graphs. Examples of such π include all conjunctions over the following groups of properties: (1) G is a planar graph or a plane graph; (2) G is directed or undirected; (3) G is triangulated, triconnected, biconnected, merely connected, or not required to be connected; (4) the nodes of G are labeled with labels from $\{1, \dots, \ell_1\}$ for $\ell_1 \leq n$; (5) the edges of G are labeled with labels from $\{1, \dots, \ell_2\}$ for $\ell_2 \leq m$; and (6) each node (respectively, edge) of G has at most $\ell_3 = O(1)$ self-loops (respectively, $\ell_4 = O(1)$ multiple edges). Moreover, ℓ_3 and ℓ_4 are not required to be $O(1)$ for the cases of π being a plane triangulation. These examples are novel applications of small cycle separators of planar graphs and are the only nontrivial classes of graphs, other than rooted trees, with known polynomial-time information-theoretically optimal coding schemes.

Key words. data compression, graph encoding, planar graphs, triconnected graphs, biconnected graphs, triangulations, cycle separators

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1. Introduction. Let G be a graph with n nodes and m edges. This paper studies the problem of *encoding* G into a binary string X with the requirement that X can be *decoded* to reconstruct G . We propose a fast methodology for designing a coding scheme such that the bit count of X is information-theoretically optimal. Specifically, a function $\beta(n)$ is *superadditive* if $\beta(n_1) + \beta(n_2) \leq \beta(n_1 + n_2)$. A function $\beta(n)$ is *continuous* if $\beta(n + o(n)) = \beta(n) + o(\beta(n))$. For example, $\beta(n) = n^c \log^d n$ is continuous and superadditive, for any constants $c \geq 1$ and $d \geq 0$. The continuity and superadditivity are closed under additions. A graph with property π is called a π -graph. If π satisfies certain properties, then we can obtain an X such that (1) G and X can be computed from each other in $O(n \log n)$ time, and (2) X has at most $\beta(n) + o(\beta(n))$ bits for any continuous superadditive function $\beta(n)$ so that there are at most $2^{\beta(n) + o(\beta(n))}$ distinct n -node m -edge π -graphs. The methodology is applicable to general classes of graphs; this paper focuses on planar graphs.

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A *conjunction* over k groups of properties is a boolean property $\pi_1 \wedge \cdots \wedge \pi_k$, where π_i is a property in the i th group for each $i = 1, \dots, k$. Examples of suitable π for our methodology include every conjunction over the following groups:

- F1. G is a planar graph or a plane graph.
- F2. G is directed or undirected.
- F3. G is triangulated, triconnected, biconnected, merely connected, or not required to be connected.
- F4. The nodes of G are labeled with labels from $\{1, \dots, \ell_1\}$ for $\ell_1 \leq n$.
- F5. The edges of G are labeled with labels from $\{1, \dots, \ell_2\}$ for $\ell_2 \leq m$.
- F6. Each node of G has at most $\ell_3 = O(1)$ self-loops.
- F7. Each edge of G has at most $\ell_4 = O(1)$ multiple edges.

Moreover, ℓ_3 and ℓ_4 are not required to be $O(1)$ for the cases of π being a plane triangulation. For instance, π can be the property of being a directed unlabeled biconnected simple plane graph. These examples are novel applications of small cycle separators of planar graphs [12, 11]. Note that the rooted trees are the only other nontrivial class of graphs with a known polynomial-time information-theoretically optimal coding scheme, which encodes a tree as nested parentheses using $2(n-1)$ bits in $O(n)$ time.

Previously, Tutte proved that there are $2^{\beta(m)+o(\beta(m))}$ distinct m -edge plane triangulations where $\beta(m) = (\frac{8}{3} - \log_2 3)m + o(m) \approx 1.08m + o(m)$ [17] and that there are $2^{2m+o(n)}$ distinct m -edge n -node triconnected plane graphs that may be nonsimple [18]. Turán [16] used $4m$ bits to encode a plane graph G that may have self-loops. Keeler and Westbrook [10] improved this bit count to $3.58m$. They also gave coding schemes for several families of plane graphs. In particular, they used $1.53m$ bits for a triangulated simple G , and $3m$ bits for a connected G free of self-loops and degree-1 nodes. For a simple triangulated G , He, Kao, and Lu [5] improved the bit count to $\frac{4}{3}m + O(1)$. For a simple G that is triconnected and thus free of degree-1 nodes, they [5] improved the bit count to at most $2.835m$ bits. This bit count was later reduced to at most $\frac{3 \log_2 3}{2}m + O(1) \approx 2.378m + O(1)$ by Chuang et al. [2]. These coding schemes all take linear time for encoding and decoding, but their bit counts are not information-theoretically optimal. For labeled planar graphs, Itai and Rodeh [6] gave an encoding of $\frac{3}{2}n \log n + O(n)$ bits. For unlabeled general graphs, Naor [14] gave an encoding of $\frac{1}{2}n^2 - n \log n + O(n)$ bits.

For applications that require query support, Jacobson [7] gave a $\Theta(n)$ -bit encoding for a connected and simple planar graph G that supports traversal in $\Theta(\log n)$ time per node visited. Munro and Raman [13] improved this result and gave schemes to encode binary trees, rooted ordered trees, and planar graphs. For a general planar G , they used $2m + 8n + o(m+n)$ bits while supporting adjacency and degree queries in $O(1)$ time. Chuang et al. [2] reduced this bit count to $2m + (5 + \frac{1}{k})n + o(m+n)$ for any constant $k > 0$ with the same query support. The bit count can be further reduced if only $O(1)$ -time adjacency queries are supported, or if G is simple, triconnected, or triangulated [2]. For certain graph families, Kannan, Naor and Rudich [8] gave schemes that encode each node with $O(\log n)$ bits and support $O(\log n)$ -time testing of adjacency between two nodes. For dense graphs and complement graphs, Kao, Occhiogrosso, and Teng [9] devised two compressed representations from adjacency lists to speed up basic graph search techniques. Galperin and Wigderson [4] and Papadimitriou and Yannakakis [15] investigated complexity issues arising from encoding a graph by a small circuit that computes its adjacency matrix.

Section 2 discusses the general encoding methodology. Sections 3 and 4 use the

methodology to obtain information-theoretically optimal encodings for various classes of planar graphs. Section 5 concludes the paper with some future research directions.

2. The encoding methodology. Let $|X|$ be the number of bits in a binary string X . Let $|G|$ be the number of nodes in a graph G . Let $|S|$ be the number of elements, counting multiplicity, in a multiset S .

FACT 1 (see [1, 3]). *Let X_1, X_2, \dots, X_k be $O(1)$ binary strings. Let $n = |X_1| + |X_2| + \dots + |X_k|$. Then there exists an $O(\log n)$ -bit string χ , obtainable in $O(n)$ time, such that given the concatenation of $\chi, X_1, X_2, \dots, X_k$, the index of the first symbol of each X_i in the concatenation can be computed in $O(1)$ time.*

Let $X_1 + X_2 + \dots + X_k$ denote the concatenation of $\chi, X_1, X_2, \dots, X_k$ as in Fact 1. We call χ the *auxiliary binary string* for $X_1 + X_2 + \dots + X_k$.

A graph with property π is called a π -graph. Whether two π -graphs are *distinct* or *indistinct* depends on π . For example, let G_1 and G_2 be two topologically non-isomorphic plane embeddings of the same planar graph. If π is the property of being a planar graph, then G_1 and G_2 are two indistinct π -graphs. If π is the property of being a planar embedding, then G_1 and G_2 are two distinct π -graphs. Let α be the number of distinct n -node π -graphs. Clearly it takes $\lceil \log_2 \alpha \rceil$ bits to differentiate all n -node π -graphs. Let $\text{index}_\pi(G)$ be an $\lceil \log_2 \alpha \rceil$ -bit indexing scheme of the α distinct π -graphs.

Let G_0 be an input n_0 -node π -graph. Let $\lambda = \log \log \log(n_0)$. The encoding algorithm $\text{encode}_\pi(G_0)$ is merely a function call $\text{code}_\pi(G_0, \lambda)$, where the recursive function $\text{code}_\pi(G, \lambda)$ is defined as follows:

```
function  $\text{code}_\pi(G, \lambda)$ 
{
  if  $|G| = O(1)$  or  $|G| \leq \lambda$  then
    return  $\text{index}_\pi(G)$ 
  else
    {
      compute  $\pi$ -graphs  $G_1, G_2$ , and a string  $X$ , from which  $G$  can be recovered;
      return  $\text{code}_\pi(G_1, \lambda) + \text{code}_\pi(G_2, \lambda) + X$ ;
    }
}
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Clearly, the code returned by algorithm $\text{encode}_\pi(G_0)$ can be decoded to recover G_0 . For notational brevity, if it is clear from the context, the code returned by algorithm $\text{encode}_\pi(G_0)$ (respectively, function $\text{code}_\pi(G, \lambda)$) is also denoted $\text{encode}_\pi(G_0)$ (respectively, $\text{code}_\pi(G, \lambda)$).

Function $\text{code}_\pi(G, \lambda)$ *satisfies the separation property* if there exist two constants c and r , where $0 \leq c < 1$ and $r > 1$, such that the following conditions hold:

- P1. $\max(|G_1|, |G_2|) \leq |G|/r$.
- P2. $|G_1| + |G_2| = |G| + O(|G|^c)$.
- P3. $|X| = O(|G|^c)$.

Let $f(|G|)$ be the time required to obtain $\text{index}_\pi(G)$ and G from each other. Let $g(|G|)$ be the time required to obtain G_1, G_2, X from G , and vice versa.

THEOREM 2.1. *Assume that function $\text{code}_\pi(G, \lambda)$ satisfies the separation property and that there are at most $2^{\beta(n)+o(\beta(n))}$ distinct n -node π -graphs for some continuous superadditive function $\beta(n)$.*

- 1. $|\text{encode}_\pi(G_0)| \leq \beta(n_0) + o(\beta(n_0))$ for any n_0 -node π -graph G_0 .
- 2. If $f(n) = 2^{n^{O(1)}}$ and $g(n) = O(n)$, then G_0 and $\text{encode}_\pi(G_0)$ can be obtained from each other in $O(n_0 \log n_0)$ time.

Proof. The theorem holds trivially if $n_0 = O(1)$. For the rest of the proof we assume $n_0 = \omega(1)$, and thus $\lambda = \omega(1)$. Many graphs may appear during the execution of $\text{encode}_\pi(G_0)$. These graphs can be organized as nodes of a binary tree T rooted at G_0 , where (i) if G_1 and G_2 are obtained from G by calling $\text{code}_\pi(G, \lambda)$, then G_1 and G_2 are the children of G in T , and (ii) if $|G| \leq \lambda$, then G has no children in T . Further consider the multiset S consisting of all graphs G that are nodes of T . We partition S into $\ell + 1$ multisets $S(0), S(1), S(2), \dots, S(\ell)$ as follows. $S(0)$ consists of the graphs G with $|G| \leq \lambda$. For $i \geq 1$, $S(i)$ consists of the graphs G with $r^{i-1}\lambda < |G| \leq r^i\lambda$. Let $G_0 \in S(\ell)$, and thus set $\ell = O(\log \frac{n_0}{\lambda})$.

Define $p = \sum_{H \in S(0)} |H|$. We first show

$$(1) \quad |S(i)| < \frac{p}{r^{i-1}\lambda}$$

for every $i = 1, \dots, \ell$. Let G be a graph in $S(i)$. Let $S(0, G)$ be the set consisting of the leaf descendants of G in T ; for example, $S(0, G_0) = S(0)$. By condition P2, $|G| \leq \sum_{H \in S(0, G)} |H|$. By condition P1, no two graphs in $S(i)$ are related in T . Therefore $S(i)$ contains at most one ancestor of H in T for every graph H in $S(0)$. It follows that $\sum_{G \in S(i)} |G| \leq \sum_{G \in S(i)} \sum_{H \in S(0, G)} |H| \leq p$. Since $|G| > r^{i-1}\lambda$ for every G in $S(i)$, inequality (1) holds.

Statement 1. Suppose that the children of G in T are G_1 and G_2 . Let $b(G) = |X| + |\chi|$, where χ is the auxiliary binary string for $\text{code}_\pi(G_1, \lambda) + \text{code}_\pi(G_2, \lambda) + X$. Let $q = \sum_{i \geq 1} \sum_{G \in S(i)} b(G)$. Then $|\text{encode}_\pi(G_0)| = q + \sum_{H \in S(0)} |\text{code}_\pi(H, \lambda)| \leq q + \sum_{H \in S(0)} (\beta(|H|) + o(\beta(|H|)))$. By the superadditivity of $\beta(n)$, $|\text{encode}_\pi(G_0)| \leq q + \beta(p) + o(\beta(p))$. Since $\beta(n)$ is continuous, Statement 1 can be proved by showing $p = n_0 + o(n_0)$ and $q = o(n_0)$ below.

By condition P3, $|X| = O(|G|^c)$. By Fact 1, $|\chi| = O(\log |G|)$. Thus, $b(G) = O(|G|^c)$, and

$$(2) \quad q = \sum_{i \geq 1} \sum_{G \in S(i)} O(|G|^c).$$

Now we regard the execution of $\text{encode}_\pi(G_0)$ as a process of growing T . Let $a(T) = \sum_{H \text{ is a leaf of } T} |H|$. At the beginning of the function call $\text{encode}_\pi(G_0)$, T has exactly one node G_0 , and thus $a(T) = n_0$. At the end of the function call, T is fully expanded, and thus $a(T) = p$. By condition P2, during the execution of $\text{encode}_\pi(G_0)$, every function call $\text{code}_\pi(G, \lambda)$ with $|G| > \lambda$ increases $a(T)$ by $O(|G|^c)$. Hence

$$(3) \quad p = n_0 + \sum_{i \geq 1} \sum_{G \in S(i)} O(|G|^c).$$

Note that

$$(4) \quad \sum_{i \geq 1} \sum_{G \in S(i)} |G|^c \leq \sum_{i \geq 1} (r^i \lambda)^c p / (r^{i-1} \lambda) = p \lambda^{c-1} r \sum_{i \geq 1} r^{(c-1)i} = p \lambda^{c-1} O(1) = o(p).$$

By (3) and (4), we have $p = n_0 + o(p)$, and thus $p = O(n_0)$. Therefore $\sum_{i \geq 1} \sum_{G \in S(i)} |G|^c = o(n_0)$. By (2) and (3), $p = n_0 + o(n_0)$ and $q = o(n_0)$, finishing the proof of Statement 1.

Statement 2. By conditions P1 and P2, $|H| = \Omega(\lambda)$ for every $H \in S(0)$. Since $\sum_{H \in S(0)} |H| = p = n_0 + o(n_0)$, $|S(0)| = O(n_0/\lambda)$. Together with (1), we know

$|S(i)| = O(\frac{n_0}{r^i \lambda})$ for every $i = 0, \dots, \ell$. By the definition of $S(i)$, $|G| \leq r^i \lambda$ for every $i = 0, \dots, \ell$. Therefore G_0 and $\text{encode}_\pi(G_0)$ can be obtained from each other in time

$$\frac{n_0}{\lambda} O \left(f(\lambda) + \sum_{1 \leq i \leq \ell} r^{-i} g(r^i \lambda) \right).$$

Clearly $f(\lambda) = 2^{\lambda^{O(1)}} = 2^{o(\log \log n_0)} = o(\log n_0)$. Since $\ell = O(\log n_0)$ and $g(n) = O(n)$, $\sum_{1 \leq i \leq \ell} r^{-i} g(r^i \lambda) = \sum_{1 \leq i \leq \ell} \lambda = O(\lambda \log n_0)$, and Statement 2 follows. \square

Sections 3 and 4 use Theorem 2.1 to encode various classes of graphs G . Section 3 considers plane triangulations. Section 4 considers planar graphs and plane graphs.

3. Plane triangulations. A *plane triangulation* is a plane graph, each of whose faces has size exactly 3. For any plane triangulation P with n nodes, m edges, and f faces, Euler's formula ensures that $n - m + f = 2$ even if P contains self-loops and multiple edges. One can then obtain $m = 3n - 6$. Therefore every n -node plane triangulation, simple or not, has exactly $3n - 6$ edges.

In this section, let π be an arbitrary conjunction over the following groups of properties of a plane triangulation G : F2, F6, and F7, where ℓ_3 and ℓ_4 are not required to be $O(1)$. Our encoding scheme is based on the next fact.

FACT 2 (see [12]). *Let H be an n -node m -edge undirected plane graph, each of whose faces has size at most d . We can compute a node-simple cycle C of H in $O(n + m)$ time such that*

- C has at most $2\sqrt{dn}$ nodes; and
- the numbers of H 's nodes inside and outside C are at most $2n/3$, respectively.

Let G be a given n -node π -graph. Let G' be obtained from the undirected version of G by deleting the self-loops. Clearly each face of G' has size at most 4. Let C' be a cycle of G' having size at most $4\sqrt{n}$ guaranteed by Fact 2. Let C consist of the edges of G corresponding to the edges of C' in G' . Note that C is not necessarily a directed cycle if G is directed. Since G' does not have self-loops, $2 \leq |C| \leq 4\sqrt{n}$. If $\ell_4 \geq 2$, then $|C|$ can be 2. Let G_{in} (respectively, G_{out}) be the subgraph of G formed by C and the part of G inside (respectively, outside) C . Let x be an arbitrary node on C .

G_1 is obtained by placing a cycle C_1 of three nodes outside G_{in} and then triangulating the face between C_1 and G_{in} such that a particular node y_1 of C_1 has degree strictly lower than the other two. Clearly this is feasible even if $|C| = 2$. The edge directions of $G_1 - G_{\text{in}}$ can be arbitrarily assigned according to π .

G_2 is obtained from G_{out} by (1) placing a cycle C_2 of three nodes outside G_{out} and then triangulating the face between C_2 and G_{out} such that a particular node y_2 of C_2 has degree strictly lower than the other two, and (2) triangulating the face inside C by placing a new node z inside of C and then connecting it to each node of C by an edge. Note that (2) is feasible even if $|C| = 2$. Similarly, the edge directions of $G_2 - G_{\text{out}}$ can be arbitrarily assigned according to π .

Let u be a node of G . Let v be a node on the boundary $B(G)$ of the exterior face of G . Define $\text{dfs}(u, G, v)$ as follows. Let w be the counterclockwise neighbor of v on $B(G)$. We perform a depth-first search of G starting from v such that (1) the neighbors of each node are visited in the counterclockwise order around that node, and (2) w is the second visited node. A numbering is assigned the first time a node is visited. Let $\text{dfs}(u, G, v)$ be the binary number assigned to u in the above depth-first search. Let $X = \text{dfs}(x, G_1, y_1) + \text{dfs}(x, G_2, y_2) + \text{dfs}(z, G_2, y_2)$.

LEMMA 3.1.

1. G_1 and G_2 are π -graphs.
2. There exists a constant $r > 1$ with $\max(|G_1|, |G_2|) \leq n/r$.
3. $|G_1| + |G_2| = n + O(\sqrt{n})$.
4. $|X| = O(\log n)$.
5. G_1, G_2, X can be obtained from G in $O(n)$ time.
6. G can be obtained from G_1, G_2, X in $O(n)$ time.

Proof. Statements 1–5 are straightforward by Fact 2 and the definitions of G_1, G_2 , and X . Statement 6 is proved as follows. It takes $O(n)$ time to locate y_1 (respectively, y_2) in G_1 (respectively, G_2) by looking for the node with the lowest degree on $B(G_1)$ (respectively, $B(G_2)$). By Fact 1, it takes $O(1)$ time to obtain $\text{dfs}(y_1, G_1, x)$, $\text{dfs}(y_2, G_2, x)$, and $\text{dfs}(y_2, G_2, z)$ from X . Therefore x and z can be located in G_1 and G_2 in $O(n)$ time by depth-first traversal. Now G_{in} can be obtained from G_1 by removing $B(G_1)$ and its incident edges. The cycle C in G_{in} is simply $B(G_{\text{in}})$. Also, G_{out} can be obtained from G_2 by removing $B(G_2), z$, and their incident edges. The C in G_{out} is simply the boundary of the face that encloses z and its incident edges in G_2 . Since we know the positions of x in G_{in} and G_{out} , G can be obtained from G_{in} and G_{out} by fitting them together along C by aligning x . The overall time complexity is $O(n)$. \square

THEOREM 3.2. *Let G_0 be an n_0 -node π -graph. Then G_0 and $\text{encode}_\pi(G_0)$ can be obtained from each other in $O(n_0 \log n_0)$ time. Moreover, $|\text{encode}_\pi(G_0)| \leq \beta(n_0) + o(\beta(n_0))$ for any continuous superadditive function $\beta(n)$ such that there are at most $2^{\beta(n)+o(\beta(n))}$ distinct n -node π -graphs.*

Proof. Since an n -node π -graph has $O(n)$ edges, there are at most $2^{O(n \log n)}$ distinct n -node π -graphs. Thus, there exists an indexing scheme $\text{index}_\pi(G)$ such that $\text{index}_\pi(G)$ and G can be obtained from each other in $2^{|G|^{O(1)}}$ time. The theorem follows from Theorem 2.1 and Lemma 3.1. \square

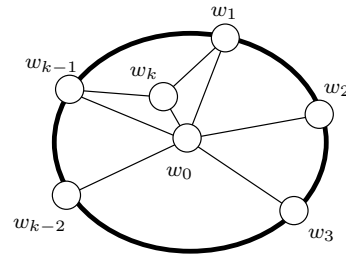
4. Planar graphs and plane graphs. In this section, let π be an arbitrary conjunction over the following groups of properties of G : F1, F2, F3, F6, and F7. Clearly an n -node π -graph has $O(n)$ edges.

Let G be an input n -node π -graph. For the cases of π being a planar graph rather than a plane graph, let G be embedded first. Note that this is only for the encoding process to be able to apply Fact 2. At the base level, we still use the indexing scheme for π -graphs rather than the one for embedded π -graphs. As shown below, the decoding process does not require the π -graphs to be embedded.

Let G' be obtained from the undirected version of G by (1) triangulating each of its faces that has size more than 3 such that no additional multiple edges are introduced, and then (2) deleting its self-loops. Let C' be a cycle of G' guaranteed by Fact 2. Let C consists of (a) the edges of G corresponds to the edges of C' in G' , and (b) the edges of C' that are added into G' by the triangulation. (C is not necessarily a directed cycle of a directed G .) Let G_C be the union of G and C . Let G_{in} (respectively, G_{out}) be the subgraph of G_C formed by C and the part of G_C inside (respectively, outside) C . Let $C = x_1 x_2 \cdots x_\ell x_{\ell+1}$, where $x_{\ell+1} = x_1$. By Fact 2, $\ell = O(\sqrt{n})$.

LEMMA 4.1. *Let H be an $O(n)$ -node $O(n)$ -edge graph. There exists an integer k with $n^{0.6} \leq k \leq n^{0.7}$ such that H does not contain any node of degree k or $k - 1$.*

Proof. Assume for a contradiction that such a k does not exist. It follows that the sum of degrees of all nodes in H is at least $(n^{0.6} + n^{0.7})(n^{0.7} - n^{0.6})/4 = \Omega(n^{1.4})$. This contradicts the fact that H has $O(n)$ edges. \square

FIG. 1. A k -wheel graph W_k .

Let W_k , with $k \geq 3$, be a k -wheel graph defined as follows. As shown in Figure 1, W_k consists of $k + 1$ nodes $w_0, w_1, w_2, \dots, w_{k-1}, w_k$, where $w_1, w_2, \dots, w_k, w_1$ form a cycle. w_0 is a degree- k node incident to each node on the cycle. Finally, w_1 is incident to w_{k-1} . Clearly W_k is triconnected. Also, w_1 and w_k are the only degree-4 neighbors of w_0 in W_k . Let k_1 (respectively, k_2) be an integer k guaranteed by Lemma 4.1 for G_{in} (respectively, G_{out}). Now we define G_1 , G_2 , and X as follows.

G_1 is obtained from G_{in} and a k_1 -wheel graph W_{k_1} by adding an edge (w_i, x_i) for every $i = 1, \dots, \ell$. Clearly for the case of π being a plane graph, G_1 can be embedded such that W_{k_1} is outside G_{in} , as shown in Figure 2(a). Thus, the original embedding of G_{in} can be obtained from G_1 by removing all nodes of W_{k_1} . The edge directions of $G_1 - G_{\text{in}}$ can be arbitrarily assigned according to π .

G_2 is obtained from G_{out} and a k_2 -wheel graph W_{k_2} by adding an edge (w_i, x_i) for every $i = 1, \dots, \ell$. Clearly for the case of π being a plane graph, G_2 can be embedded such that W_{k_2} is inside C , as shown in Figure 2(b). Thus, the original embedding of G_{out} can be obtained from G_2 by removing all nodes of W_{k_2} . The edge directions of $G_2 - G_{\text{out}}$ can be arbitrarily assigned according to π .

Let X be an $O(\sqrt{n})$ -bit string which encodes k_1 , k_2 , and whether each edge (x_i, x_{i+1}) is an original edge in G , for $i = 1, \dots, \ell$.

LEMMA 4.2.

1. G_1 and G_2 are π -graphs.
2. There exists a constant $r > 1$ with $\max(|G_1|, |G_2|) \leq n/r$.
3. $|G_1| + |G_2| = n + O(n^{0.7})$.
4. $|X| = O(\sqrt{n})$.
5. G_1, G_2, X can be obtained from G in $O(n)$ time.
6. G can be obtained from G_1, G_2, X in $O(n)$ time.

Proof. Since W_{k_1} and W_{k_2} are both triconnected, and each node of C has degree at least 3 in G_1 and G_2 , statement 1 holds for each case of the connectivity of the input π -graph G . Statements 2–5 are straightforward by Fact 2 and the definitions of G_1 , G_2 , and X . Statement 6 is proved as follows. First of all, we obtain k_1 from X . Since G_{in} does not contain any node of degree k_1 or $k_1 - 1$, w_0 is the only degree- k_1 node in G_1 . Therefore it takes $O(n)$ time to identify w_0 in G_1 . w_{k_1} is the only degree-3 neighbor of w_0 . Since $k_1 > \ell$, w_1 is the only degree-5 neighbor of w_0 . w_2 is the common neighbor of w_0 and w_1 that is not adjacent to w_{k_1} . From now on, w_i , for each $i = 3, 4, \dots, \ell$, is the common neighbor of w_0 and w_{i-1} other than w_{i-2} . Clearly, w_1, w_2, \dots, w_ℓ and thus x_1, x_2, \dots, x_ℓ can be identified in $O(n)$ time. G_{in} can now be obtained from G_1 by removing W_{k_1} . Similarly, G_{out} can be obtained from G_2 and X by deleting W_{k_2} after identifying x_1, x_2, \dots, x_ℓ . Finally, G_C can be recovered by fitting G_{in} and G_{out} together by aligning x_1, x_2, \dots, x_ℓ . Based on X , G can then be

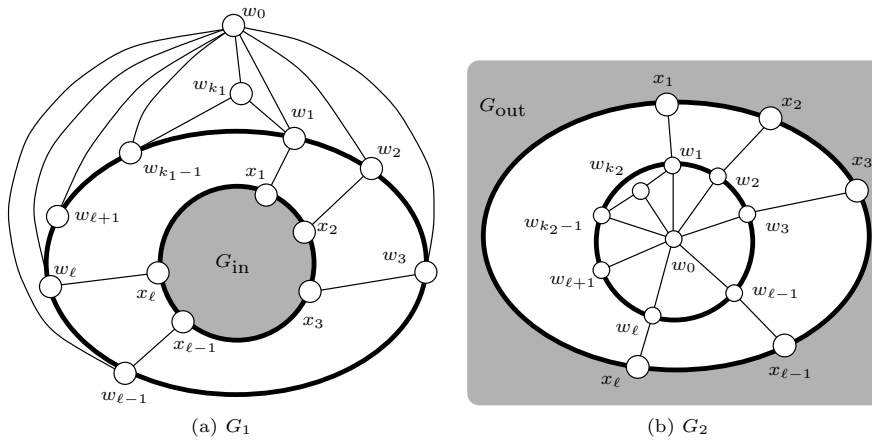


FIG. 2. G_1 and G_2 . The gray area of G_1 is G_{in} . The gray area of G_2 is G_{out} .

obtained from G_C by removing the edges of C that are not originally in G . \square

Remark. In the proof for statement 6 of Lemma 4.2, identifying the degree- k_1 node (and the k_1 -wheel graph W_{k_1}) does not require the embedding for G_1 . Therefore the decoding process does not require the π -graphs to be embedded. This is different from the proof of Lemma 3.1.

THEOREM 4.3. *Let G_0 be an n_0 -node π -graph. Then G_0 and $\text{encode}_\pi(G_0)$ can be obtained from each other in $O(n_0 \log n_0)$ time. Moreover, $|\text{encode}_\pi(G_0)| \leq \beta(n_0) + o(\beta(n_0))$ for any continuous superadditive function $\beta(n)$ such that there are at most $2^{\beta(n)+o(\beta(n))}$ distinct n -node π -graphs.*

Proof. Since there are at most $2^{O(n \log n)}$ distinct n -node π -graphs, there exists an indexing scheme $\text{index}_\pi(G)$ such that $\text{index}_\pi(G)$ and G can be obtained from each other in $2^{|G|^{O(1)}}$ time. The theorem follows from Theorem 2.1 and Lemma 4.2. \square

5. Concluding remarks. For brevity, we left out F4 and F5 in sections 3 and 4. One can verify that Theorems 3.2 and 4.3 hold even if π is a conjunction over F1 through F7 including F4 and F5.

The coding schemes given in this paper require $O(n \log n)$ time for encoding and decoding. An immediate open question is whether one can encode some graphs other than rooted trees in $O(n)$ time using information-theoretically minimum number of bits. It would be of significance to determine whether the tight bound of the number of distinct π -graphs for each π is indeed continuous superadditive.

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