
Matting and compositing

Digital Visual Effects, Spring 2005

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2005/4/27

Announcements

- Project #2 was due yesterday.
- Project #3 will be assigned next Wednesday.
- Grading proportion change. (15%,20%,20%,30%)

Outline

- Traditional matting and compositing
- Natural image matting
- Video matting
- Shadow matting
- Environment matting

*Traditional matting
and composting*

Photomontage



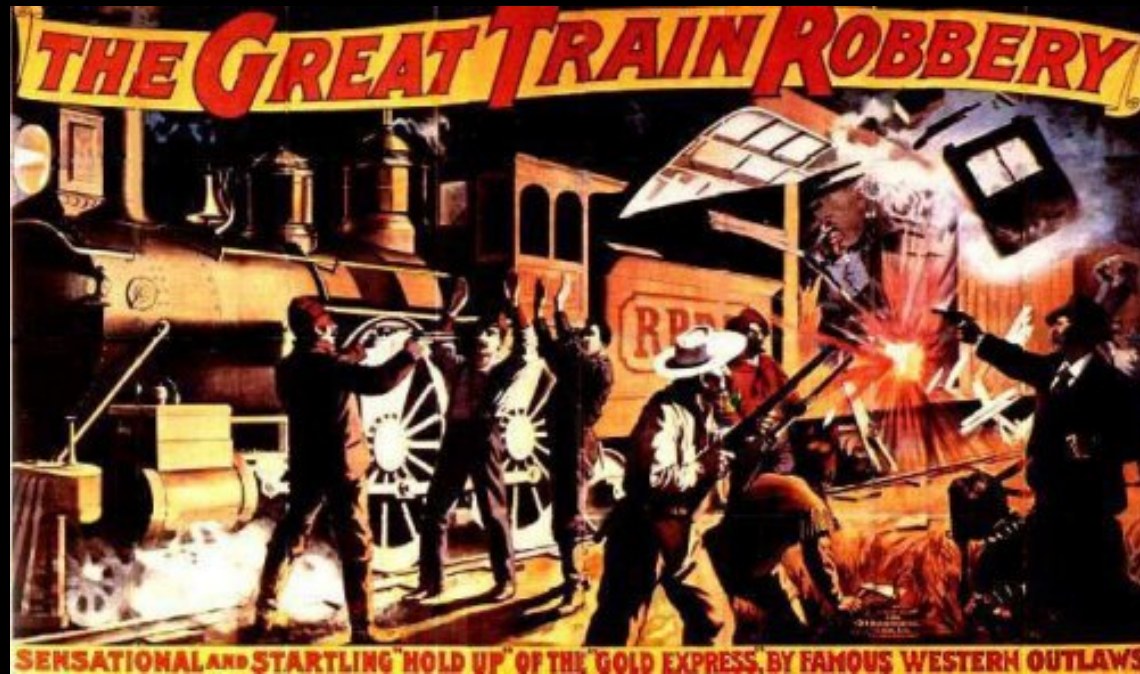
The Two Ways of Life, 1857, Oscar Gustav Rejlander
Printed from the original 32 wet collodion negatives.

Photographic compositions



Lang Ching-shan

Use of mattes for compositing



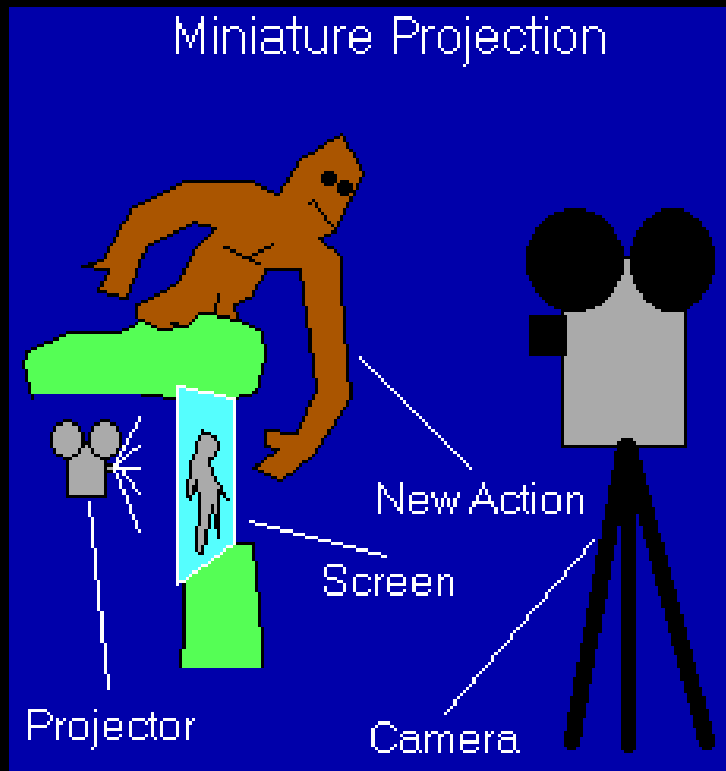
The Great Train Robbery (1903) matte shot

Use of mattes for compositing



The Great Train Robbery (1903) matte shot

Optical compositing



King Kong (1933) Stop-motion + optical compositing

Digital matting and compositing

The lost world (1925)



Miniature, stop-motion

The lost world (1997)



Computer-generated images

Digital matting and compositing

King Kong (1933)



Optical compositing

Jurassic Park III (2001)



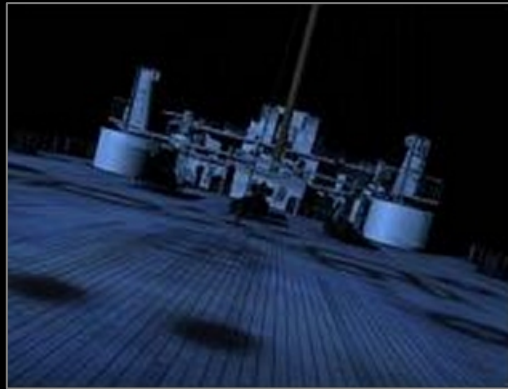
Blue-screen matting,
digital composition,
digital matte painting

Digital matting: bluescreen matting



Forrest Gump (1994)

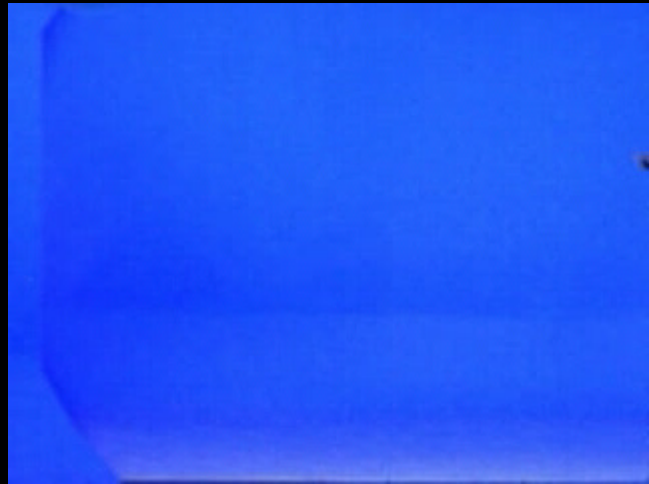
- The most common approach for films.
- Expensive, studio setup.
- Not a simple one-step process.



Titanic



Matting and compositing



background
replacement



background
editing



Matting and Compositing

Color difference method (Ultimatte)

$$C = F + \bar{\alpha}B$$

F

$\bar{\alpha}$



Blue-screen
photograph

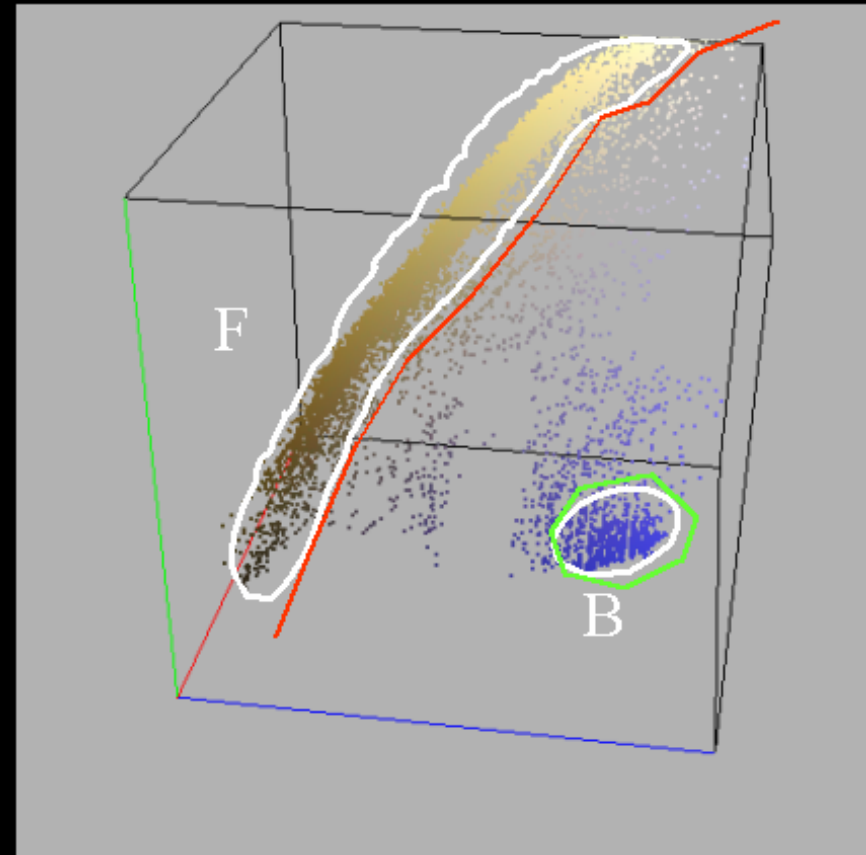


Spill suppression
if $B > G$ then $B = G$



Matte creation
 $\bar{\alpha} = B - \max(G, R)$

Chroma-keying (Primatte)



F



foreground color

α

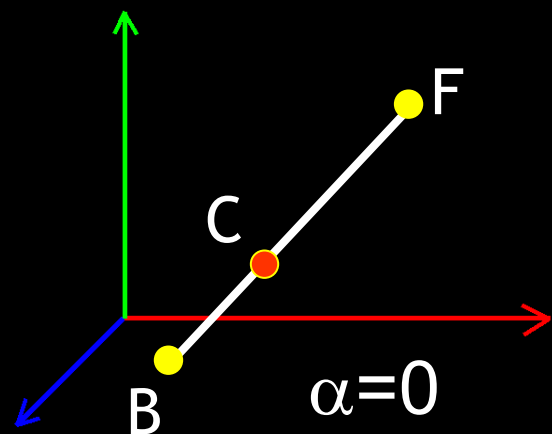


alpha matte

B



background plate



$$C = \alpha F + (1 - \alpha)B$$

compositing equation

Compositing

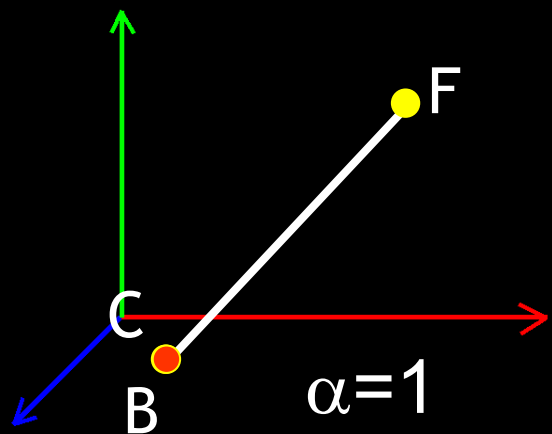
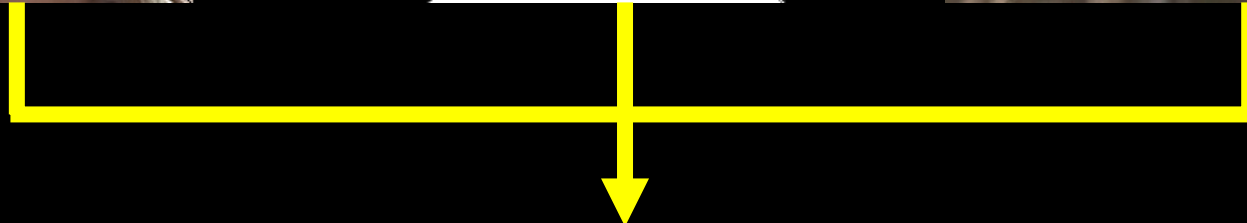
F



α



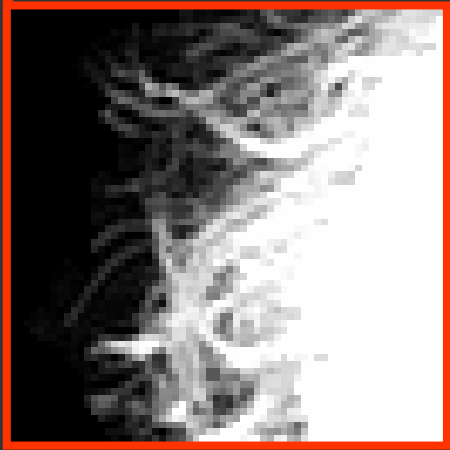
B



$$C = \alpha F + (1 - \alpha)B$$

compositing
equation

Compositing



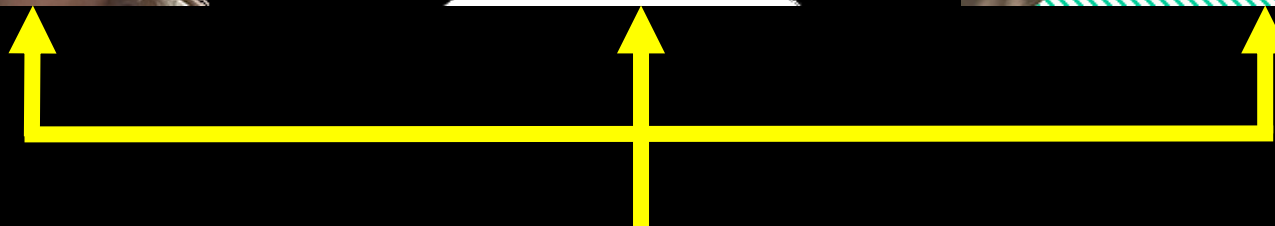
F



α



B



observation

C



$$C = \alpha F + (1 - \alpha)B$$

compositing
equation

Matting

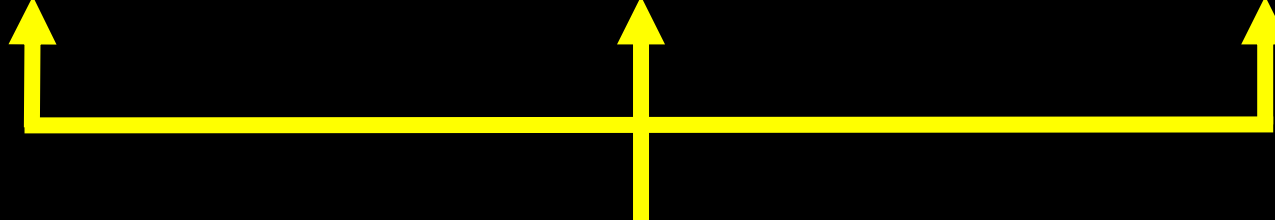
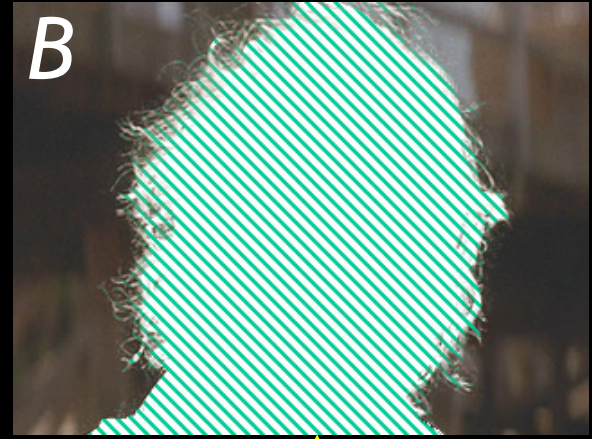
F



α



B



Three approaches:
1 reduce #unknowns
2 add observations
3 add priors

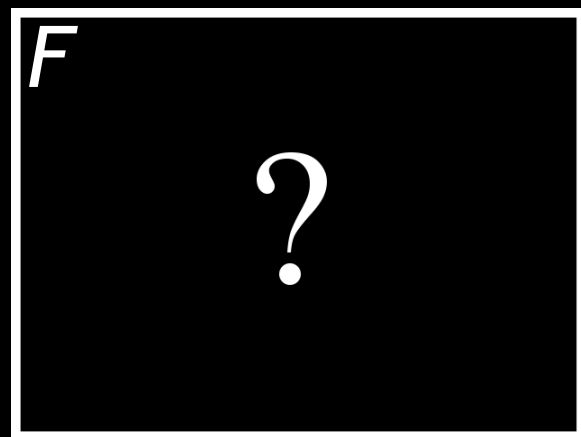
C



$$C = \alpha F + (1 - \alpha)B$$

compositing
equation

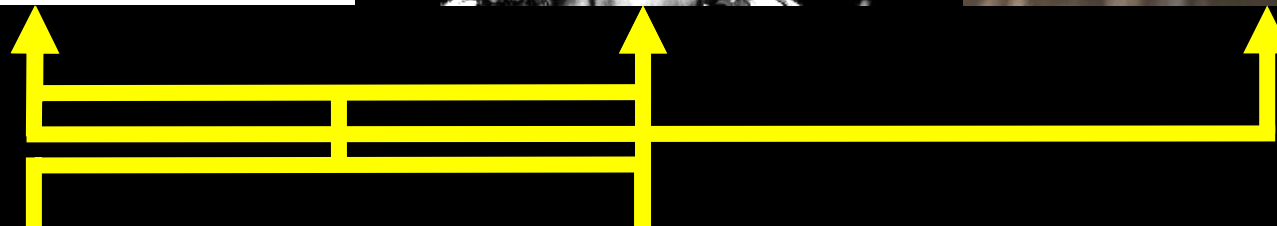
Matting



α



B



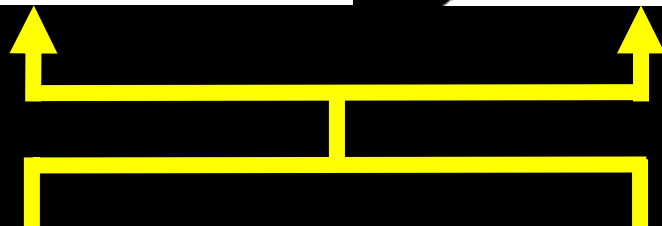
$$C = \alpha F + (1 - \alpha)B$$

difference
matting

Matting (reduce #unknowns)



α



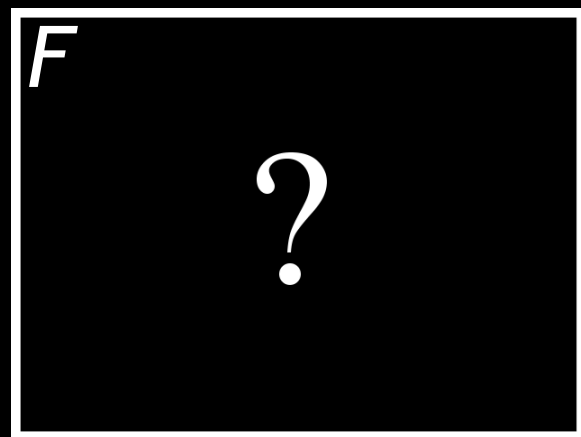
B



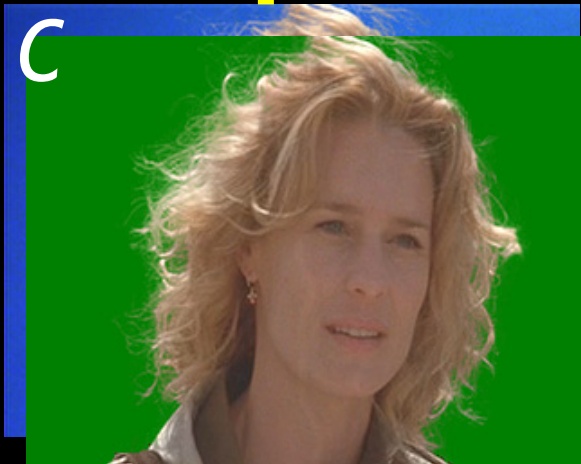
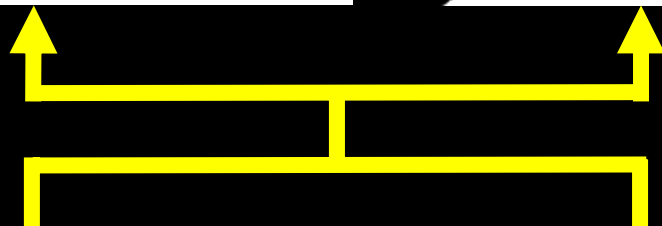
$$C = \alpha F + (1 - \alpha)B$$

blue screen
matting

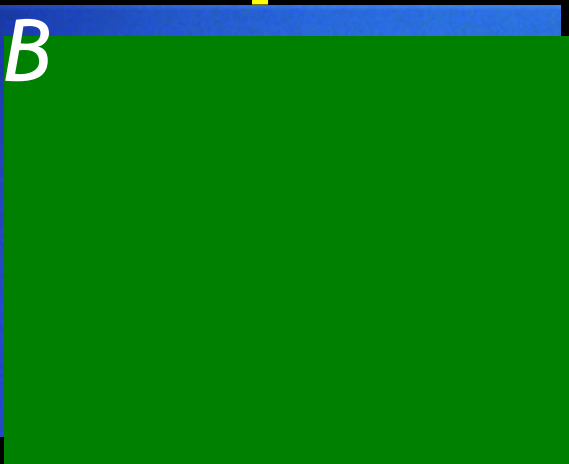
Matting (reduce #unknowns)



α



B

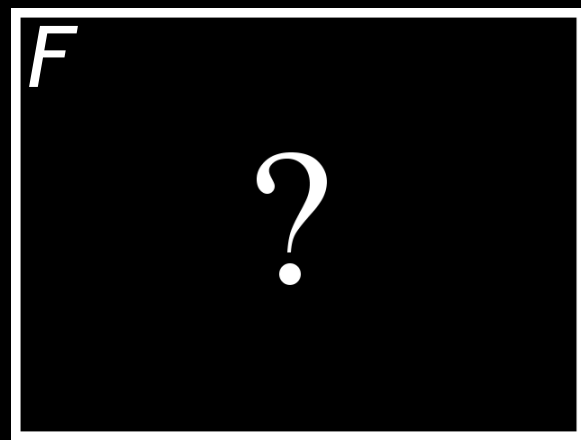


$$C = \alpha F + (1 - \alpha)B$$

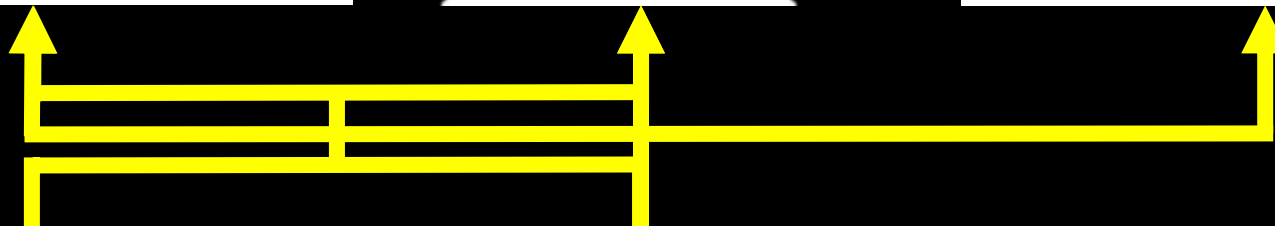
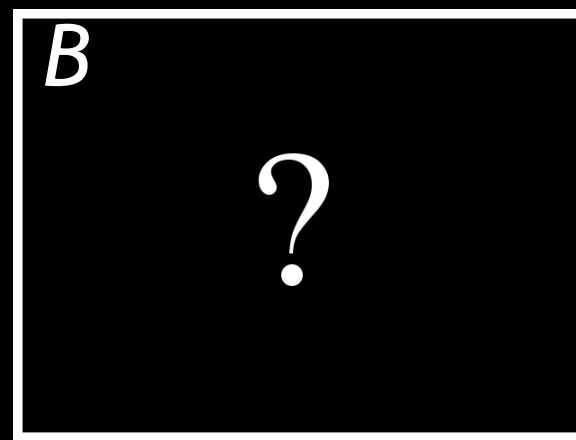
$$C = \alpha F + (1 - \alpha)B$$

triangulation

Matting (add observations)



α



BG



$$C = \alpha F + (1 - \alpha)B$$

Retrospective

Matting (add priors)

Bayesian image matting

posterior probability

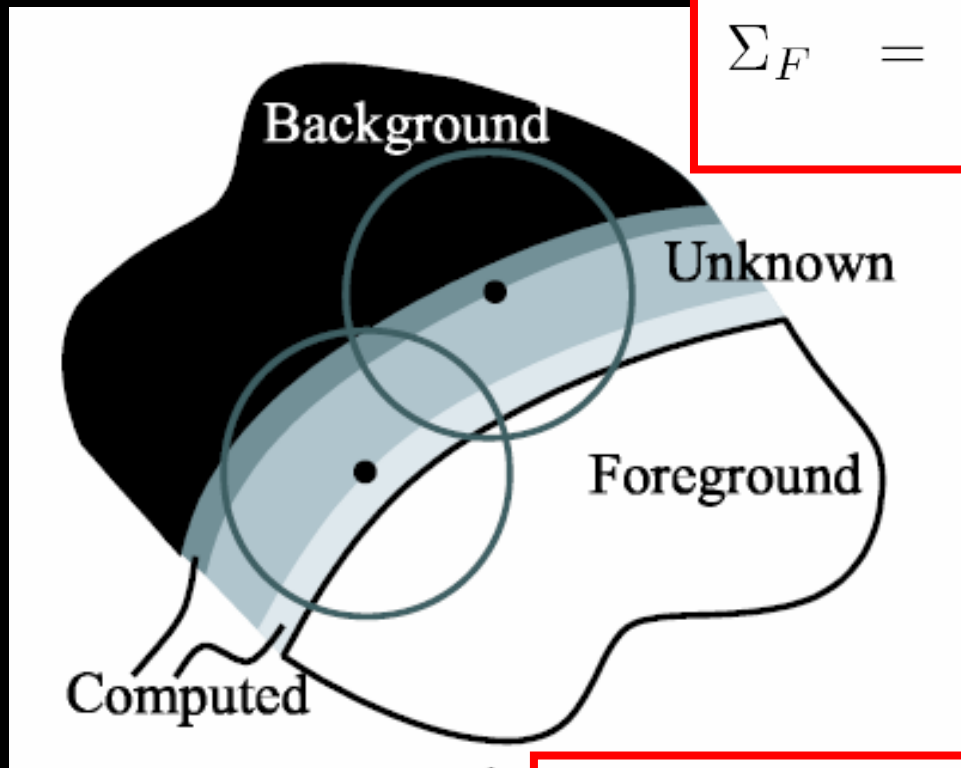
likelihood

priors

$$\begin{aligned} & \arg \max_{F, B, \alpha} P(F, B, \alpha | C) \\ &= \arg \max_{F, B, \alpha} P(C | F, B, \alpha) P(F) P(B) P(\alpha) / P(C) \end{aligned}$$

$$L(C | F, B, \alpha) = -\|C - \alpha F - (1 - \alpha)B\|^2 / \sigma_C^2$$

Bayesian framework



$$\bar{F} = \frac{1}{W} \sum_{i \in N} w_i F_i$$

$$\Sigma_F = \frac{1}{W} \sum_{i \in N} w_i (F_i - \bar{F}) (F_i - \bar{F})^T$$

$$L(F) = -(F - \bar{F})^T \Sigma_F^{-1} (F - \bar{F}) / 2$$

Priors

repeat

1. fix alpha

$$\begin{bmatrix} \Sigma_F^{-1} + I\alpha^2/\sigma_C^2 & I\alpha(1-\alpha)/\sigma_C^2 \\ I\alpha(1-\alpha)/\sigma_C^2 & \Sigma_B^{-1} + I(1-\alpha)^2/\sigma_C^2 \end{bmatrix} \begin{bmatrix} F \\ B \end{bmatrix} \\ = \begin{bmatrix} \Sigma_F^{-1}\bar{F} + C\alpha/\sigma_C^2 \\ \Sigma_B^{-1}\bar{B} + C(1-\alpha)/\sigma_C^2 \end{bmatrix}$$

2. fix F and B

$$\alpha = \frac{(C - B) \cdot (F - B)}{\|F - B\|^2}$$

until converge

Optimization



Bayesian image matting



Bayesian image matting



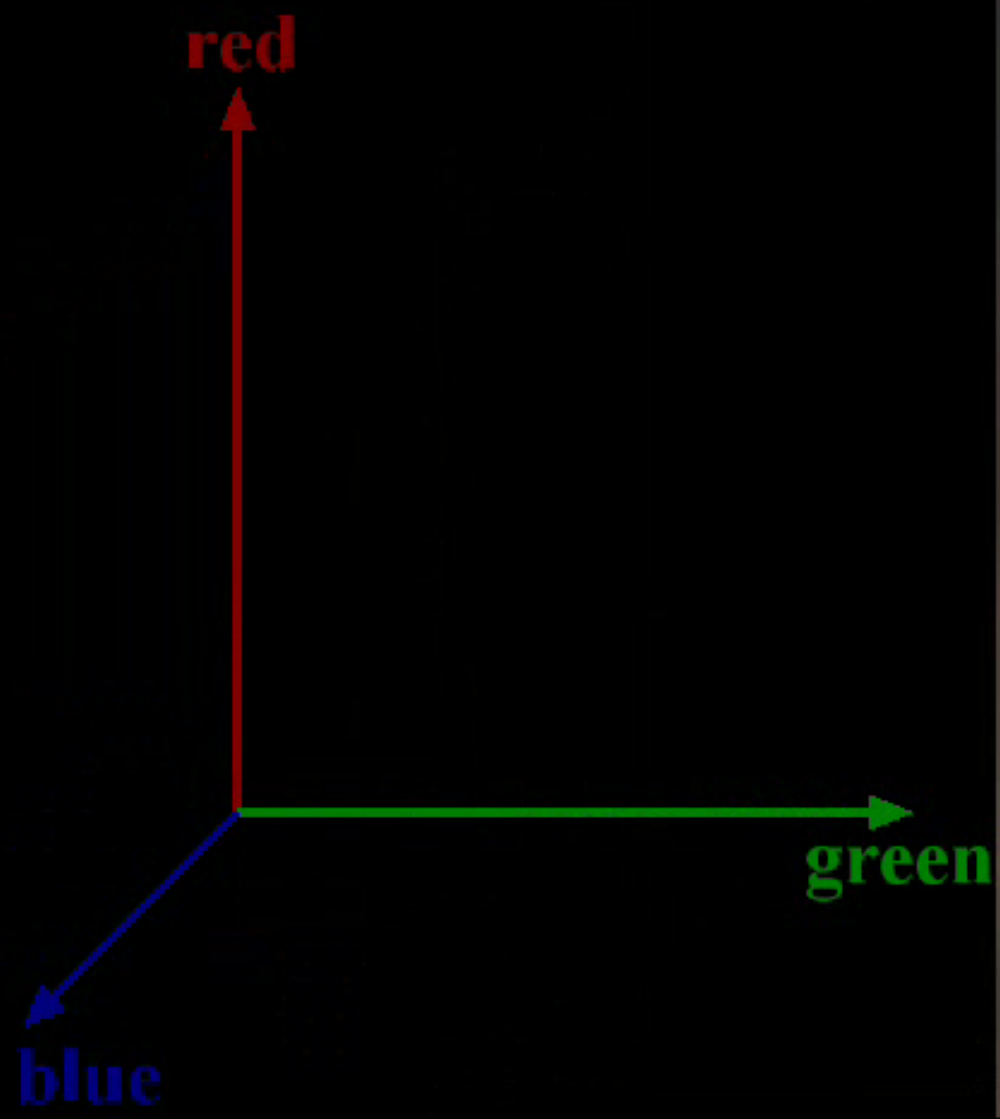
Bayesian image matting

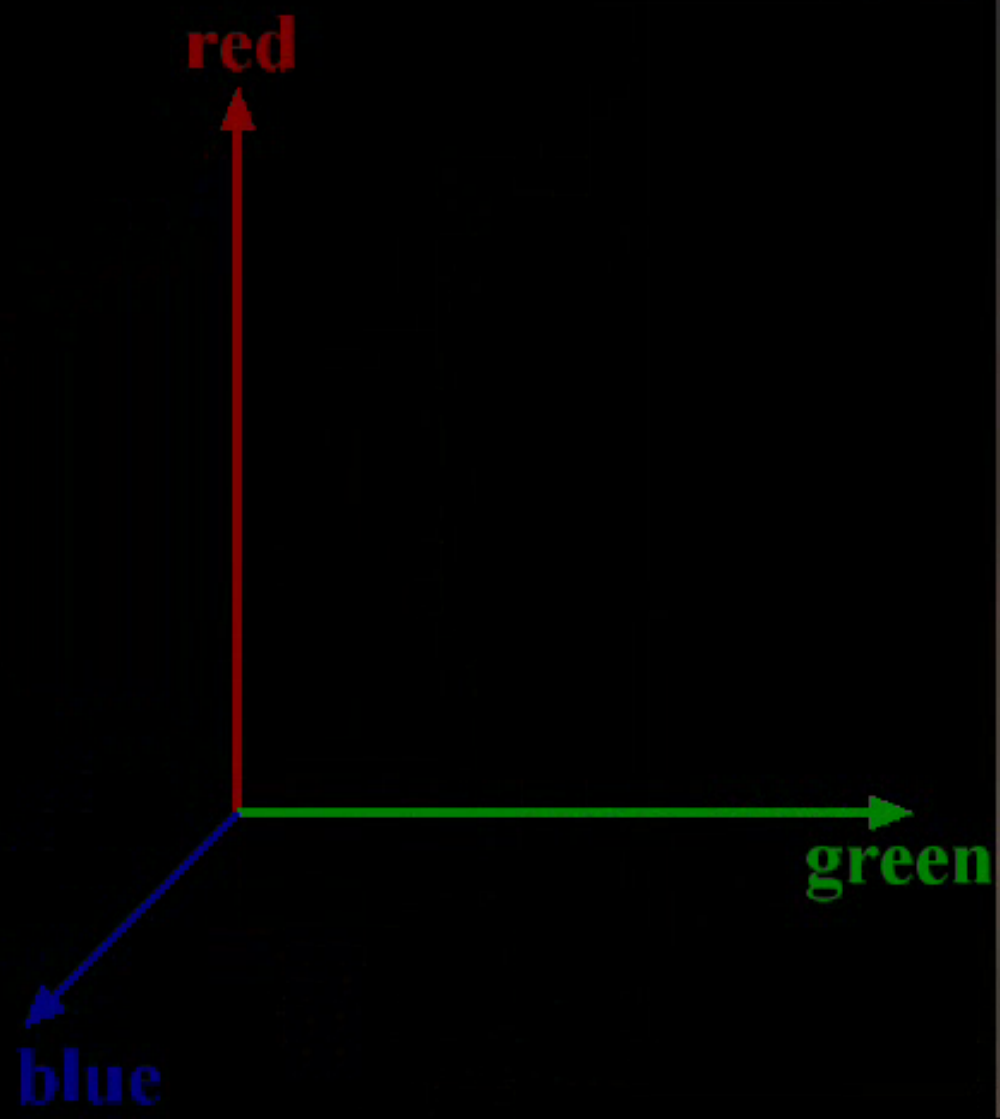


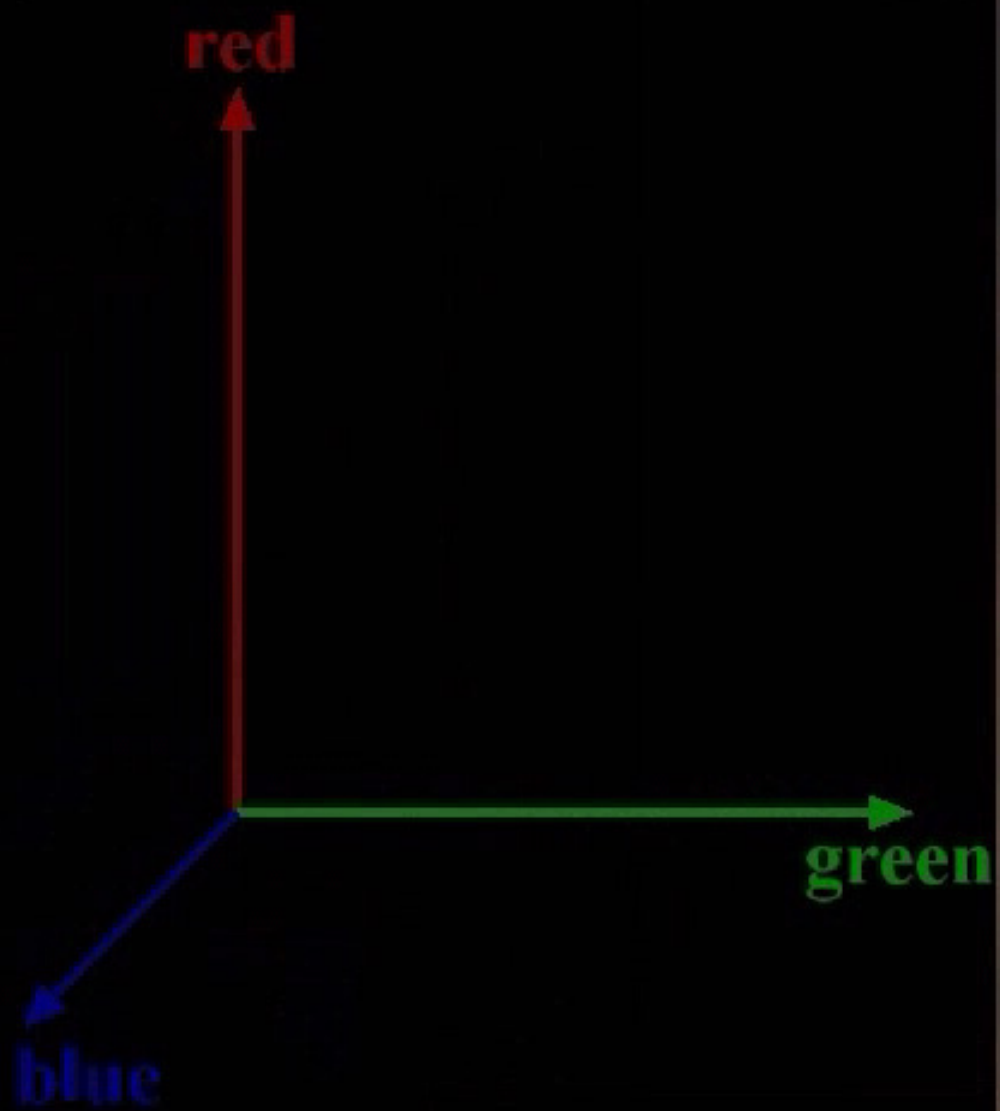
Bayesian image matting

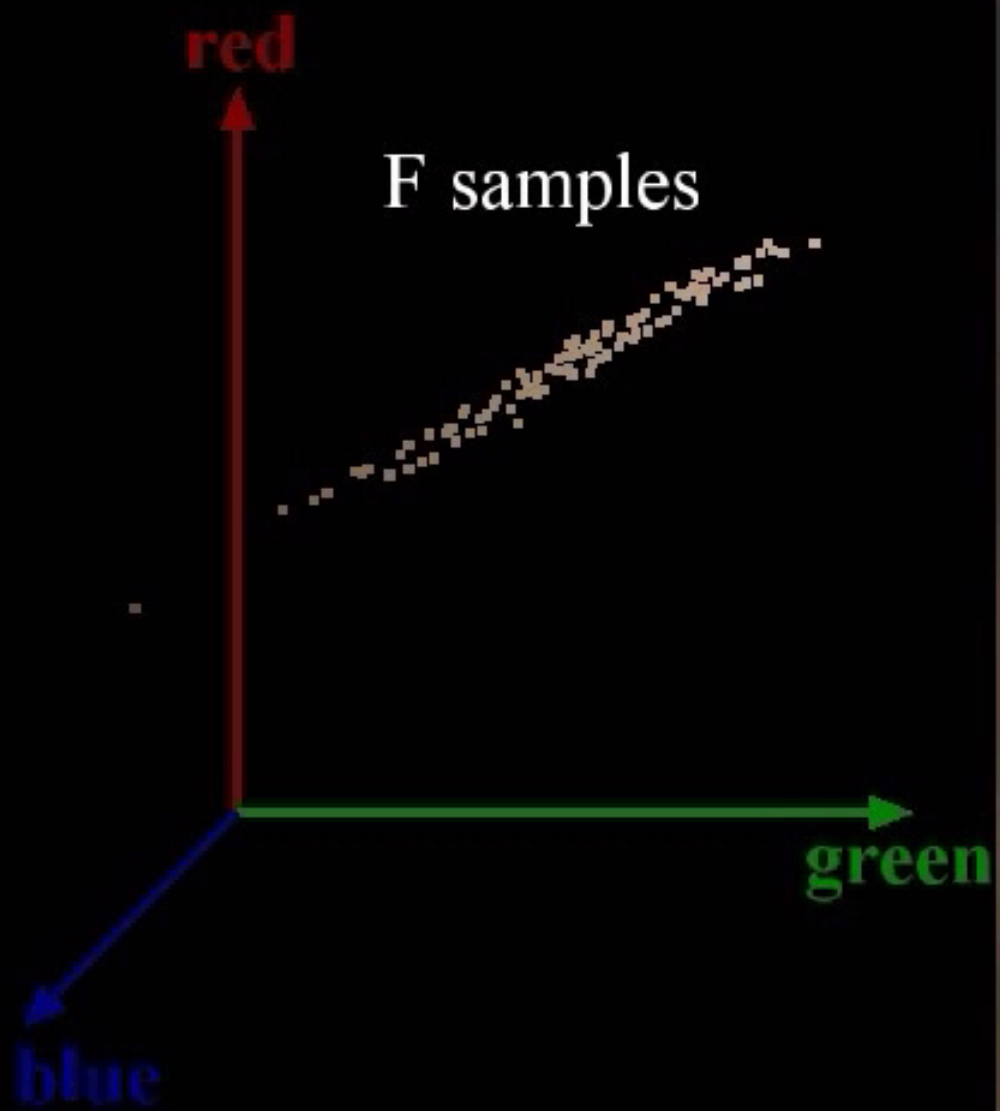


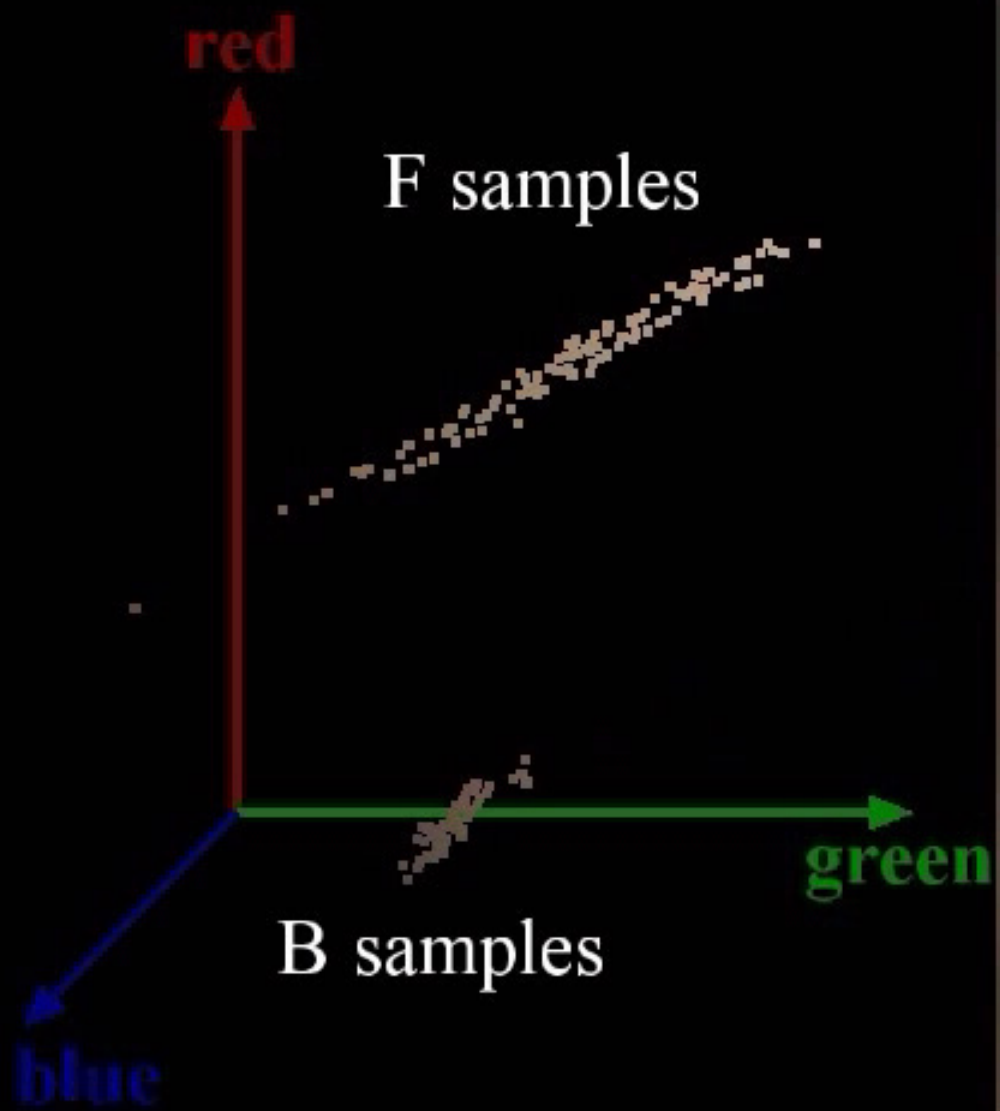
Bayesian image matting

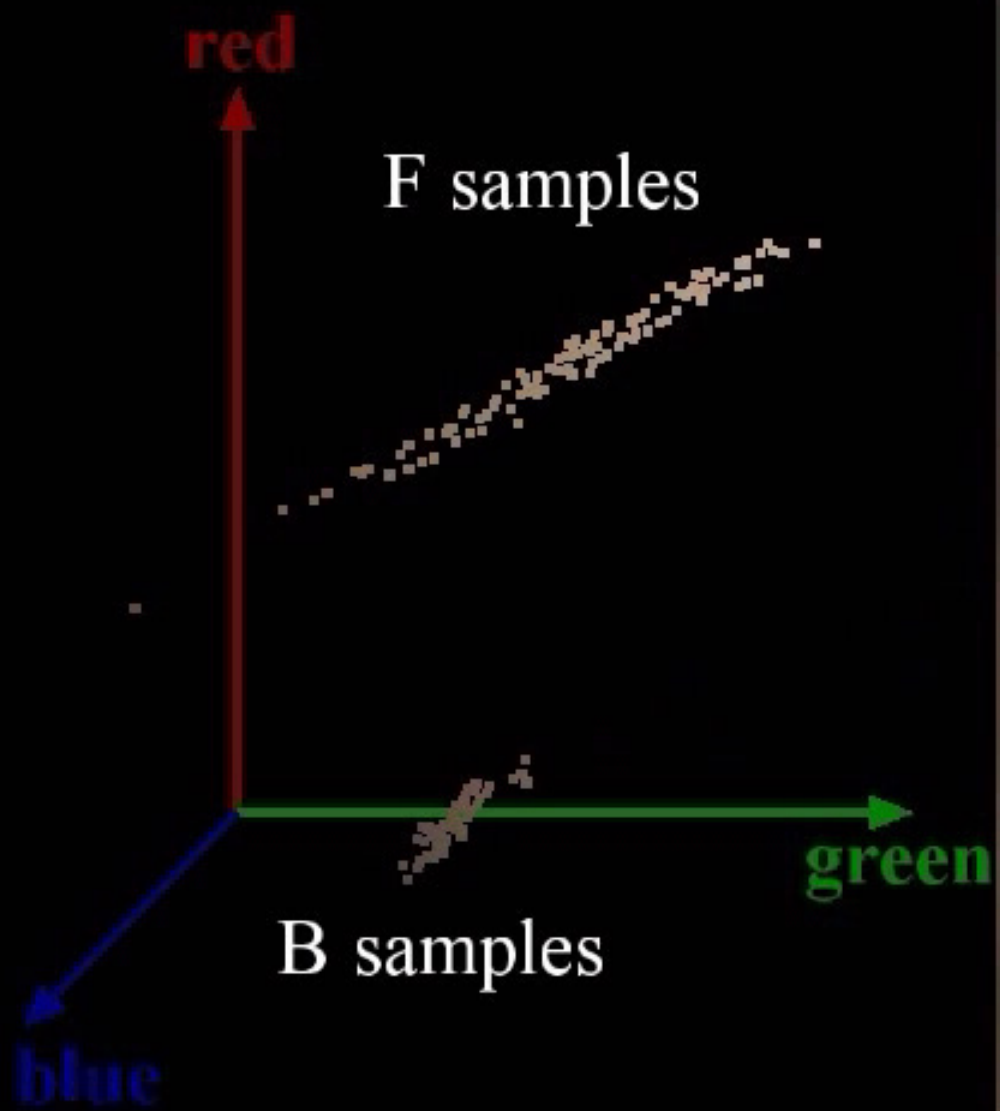


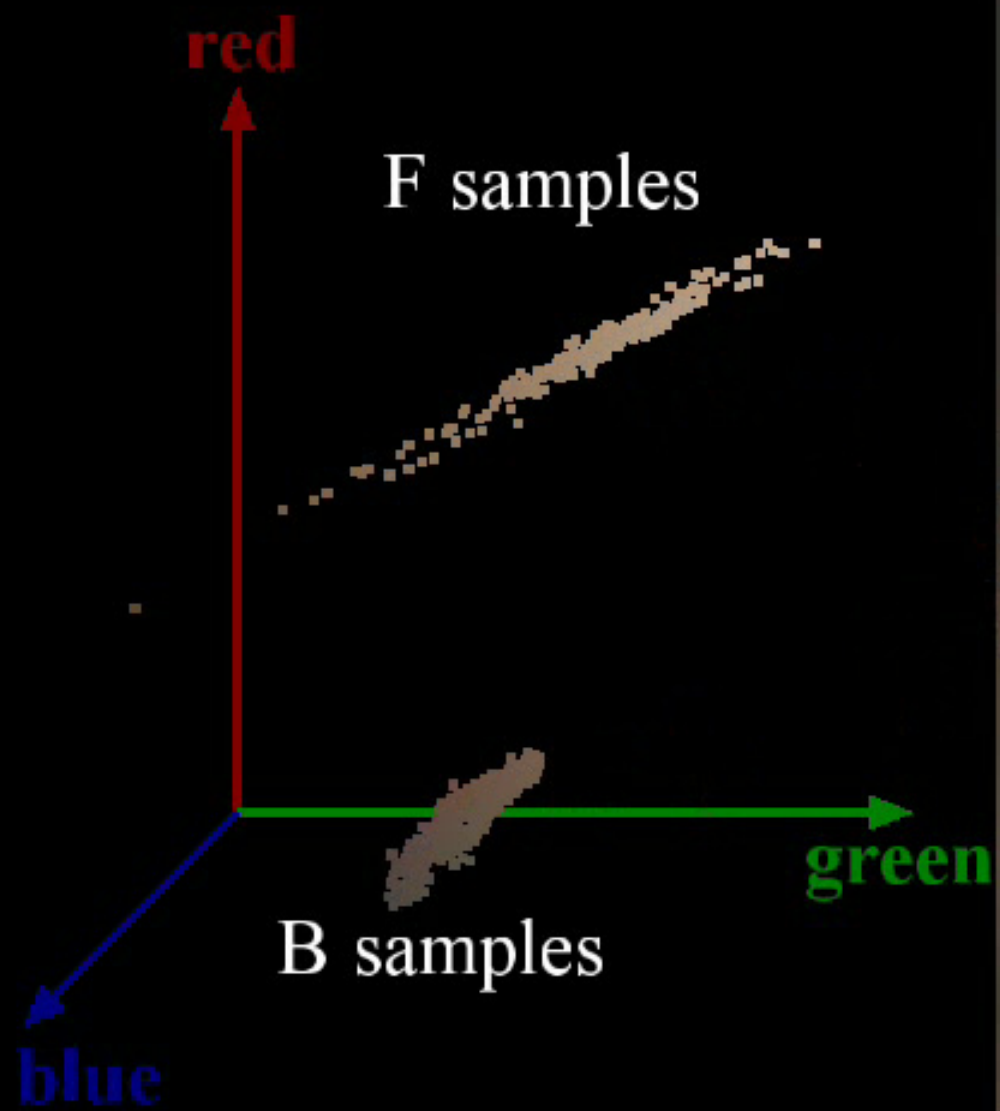


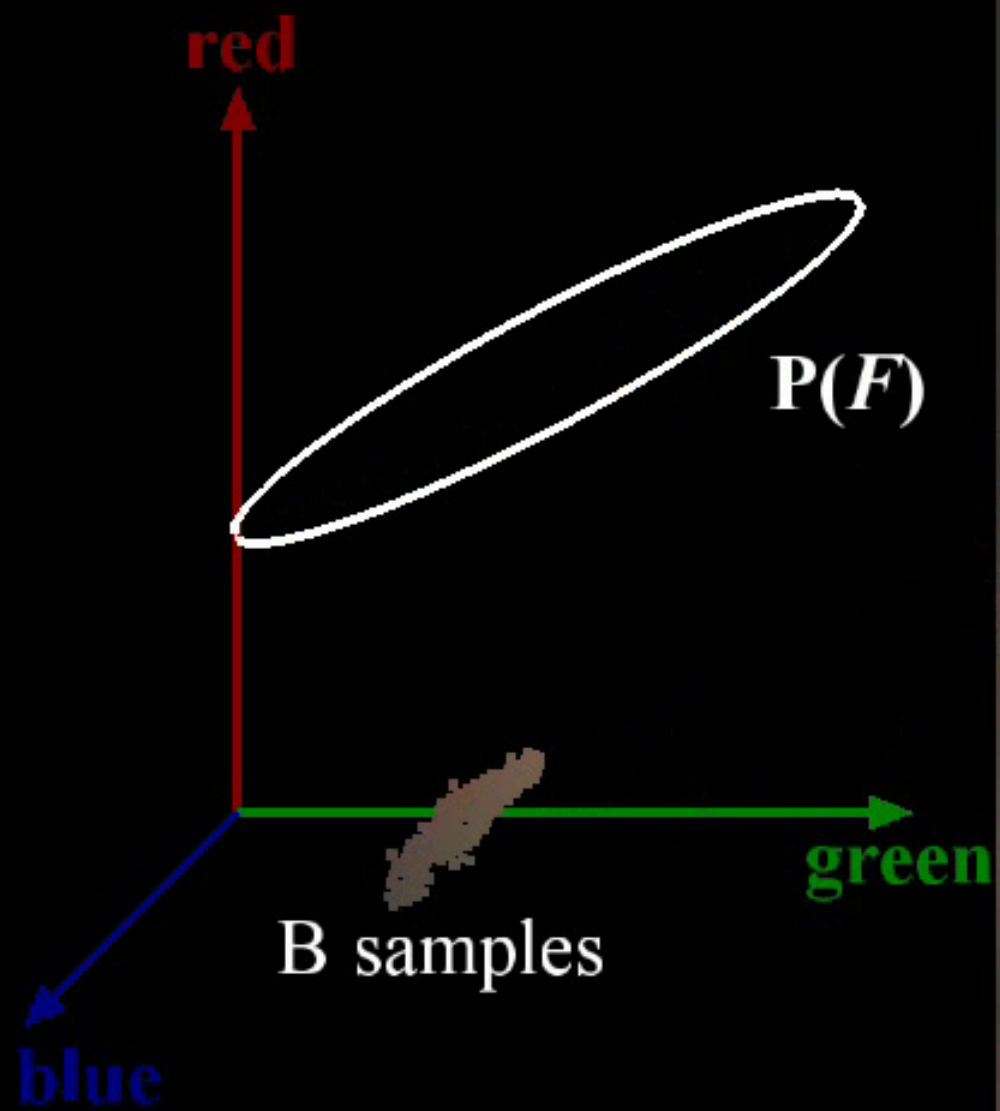


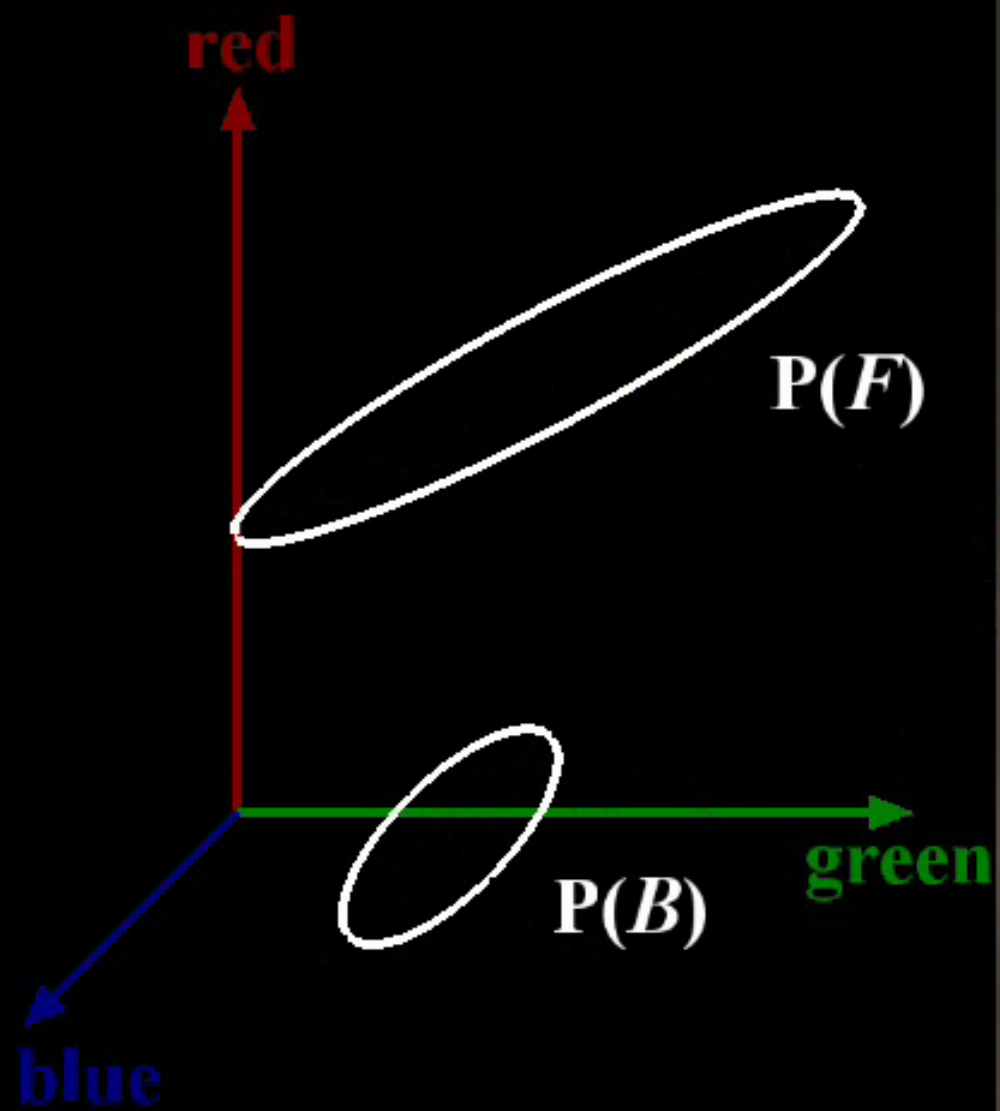


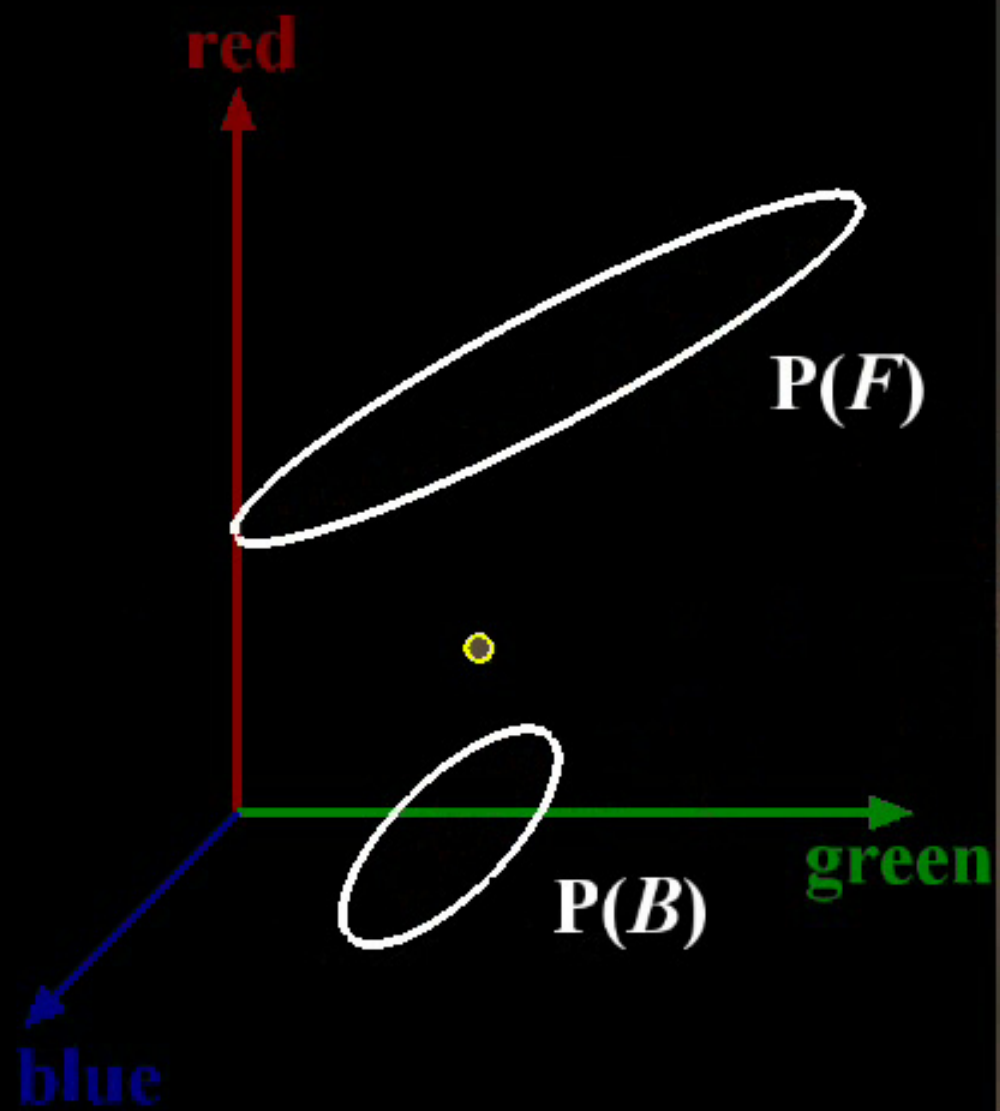


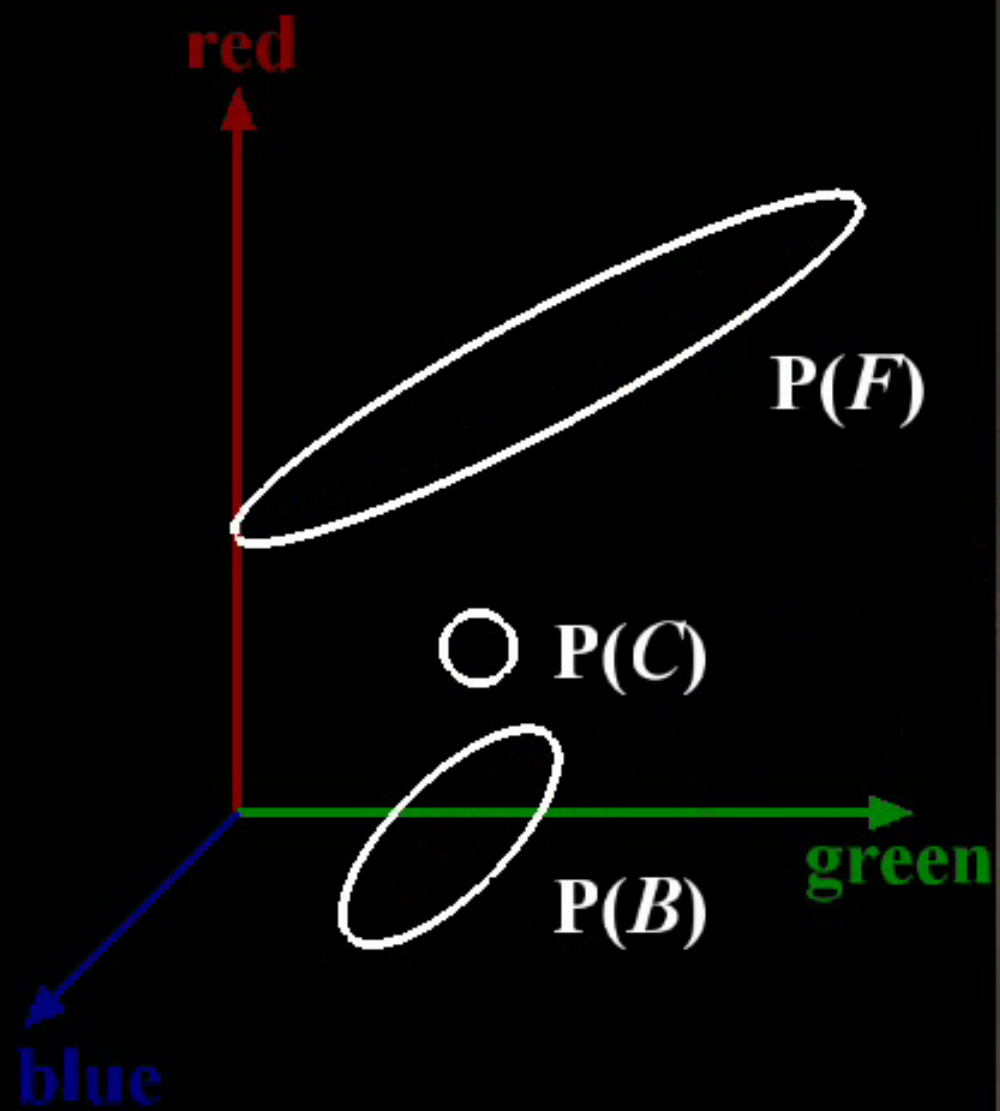


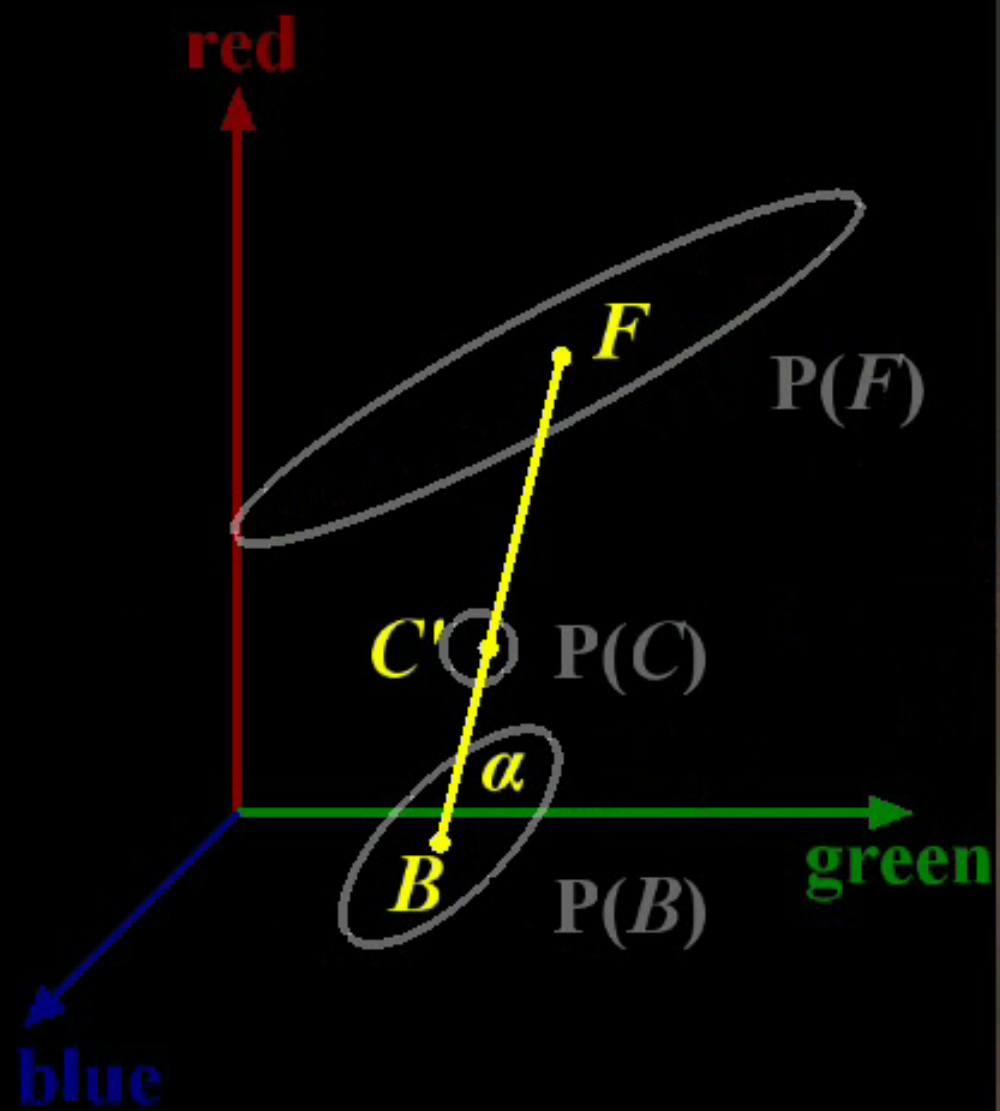












alpha



Results

input

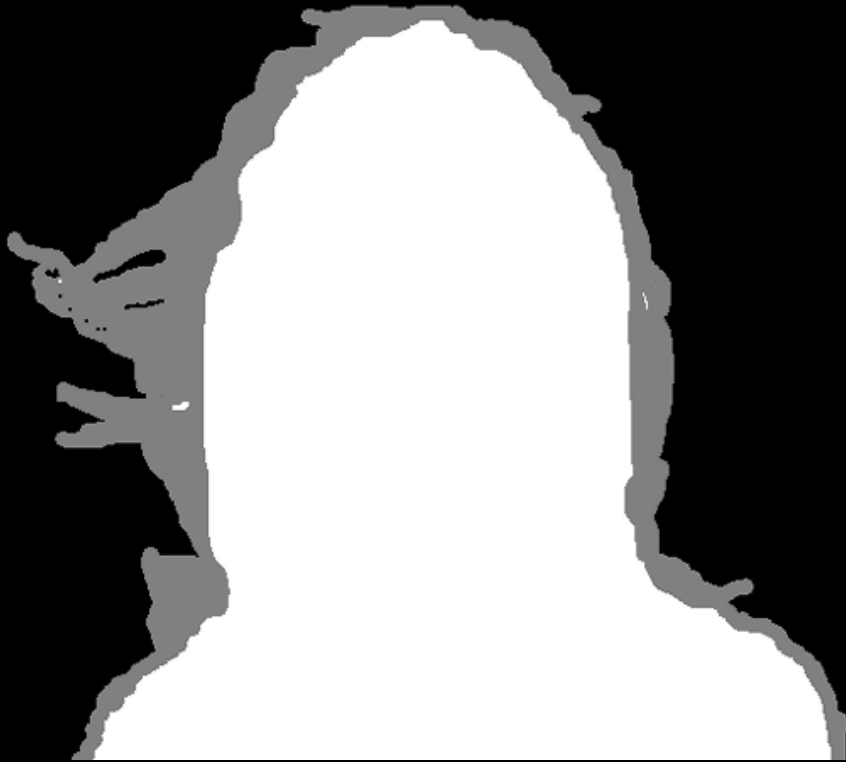


composite



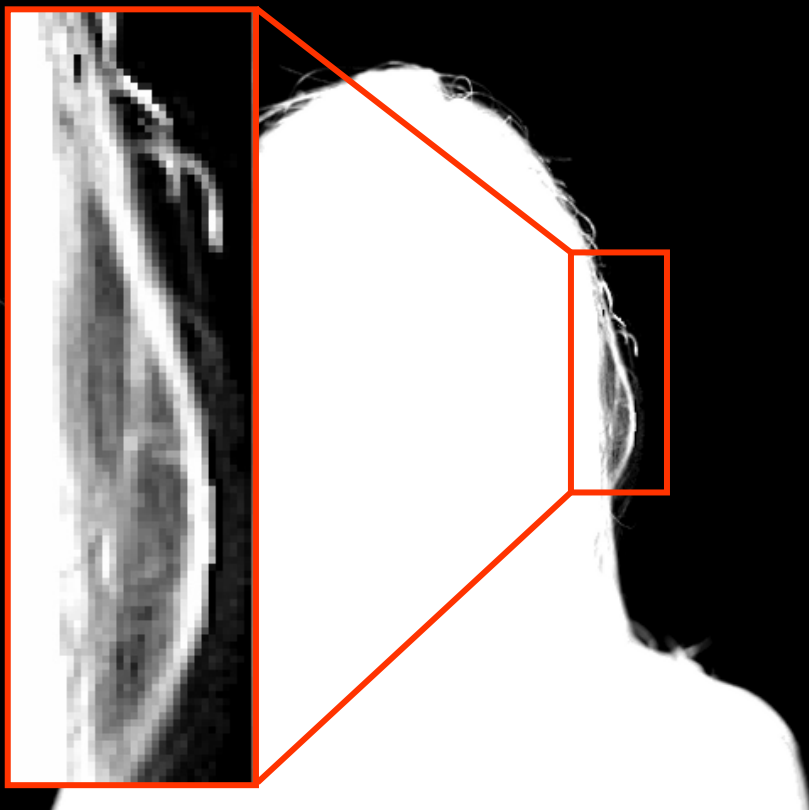
Results

trimap

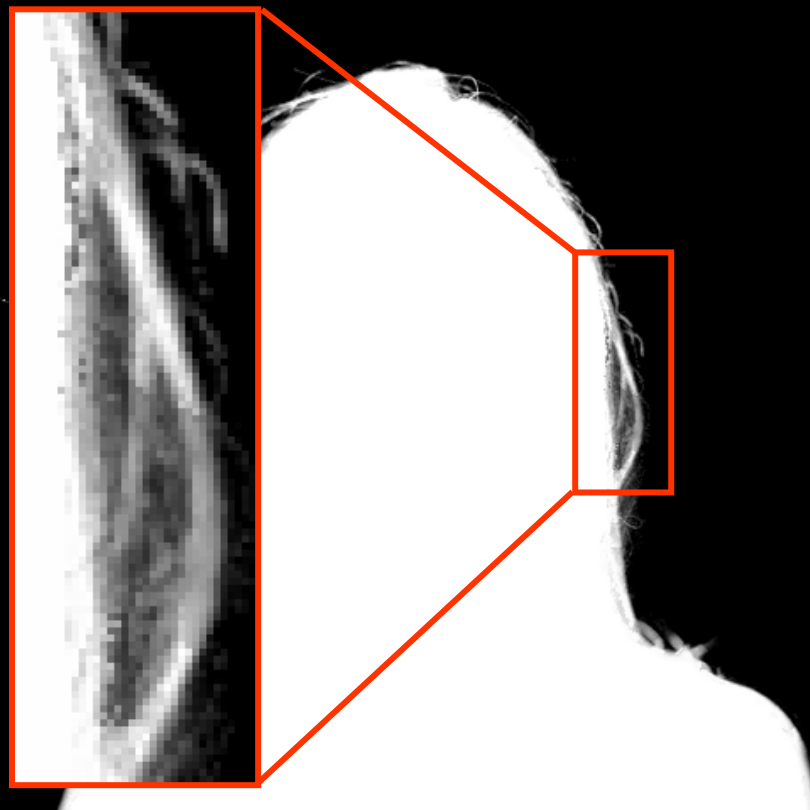


Comparisons

Bayesian



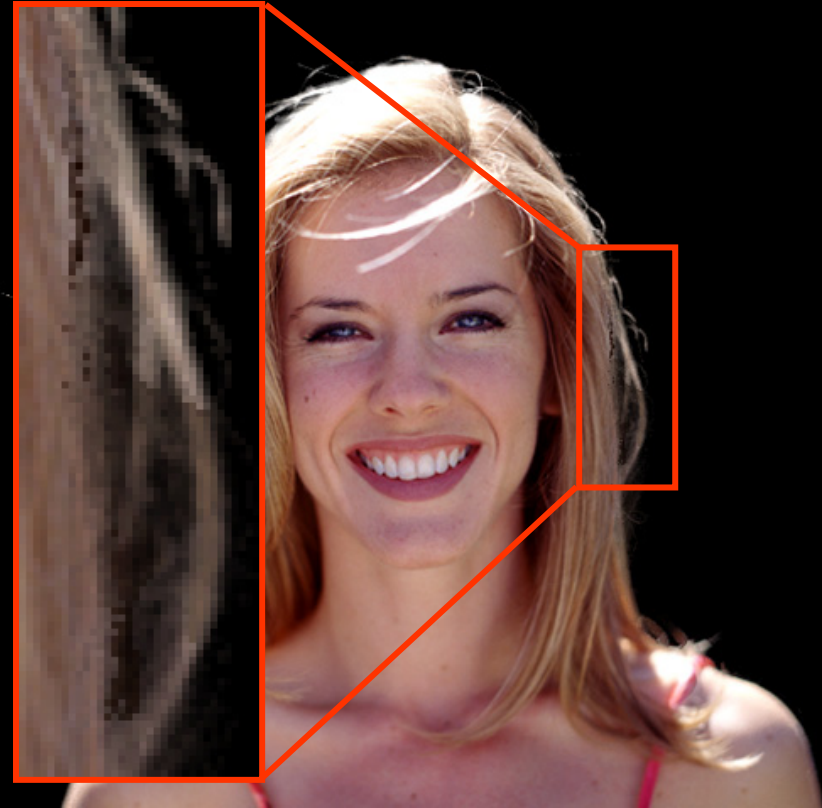
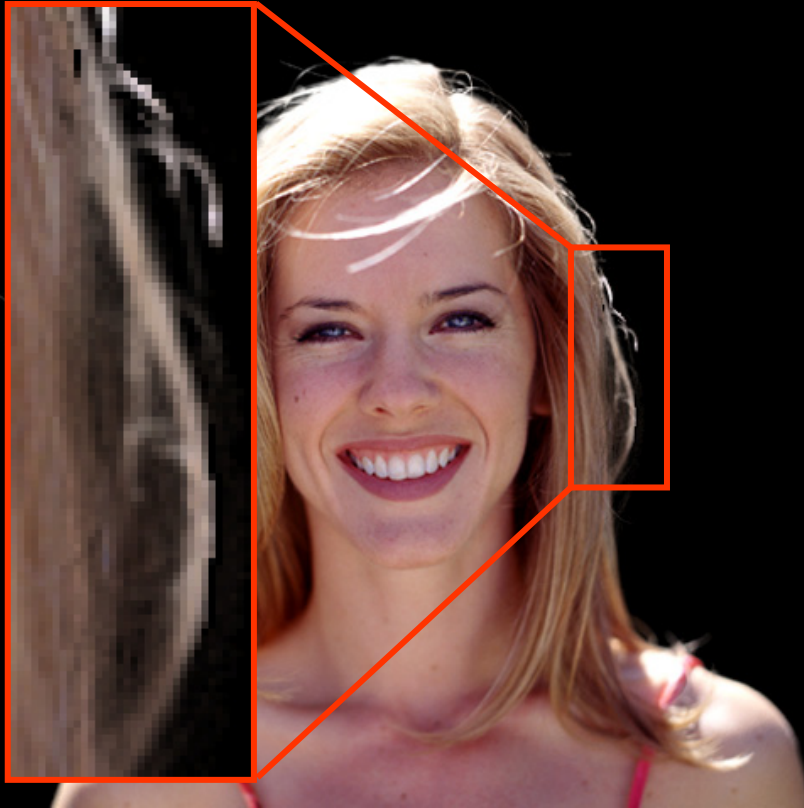
Ruzon-Tomasi



Comparisons

Bayesian

Ruzon-Tomasi



Comparisons

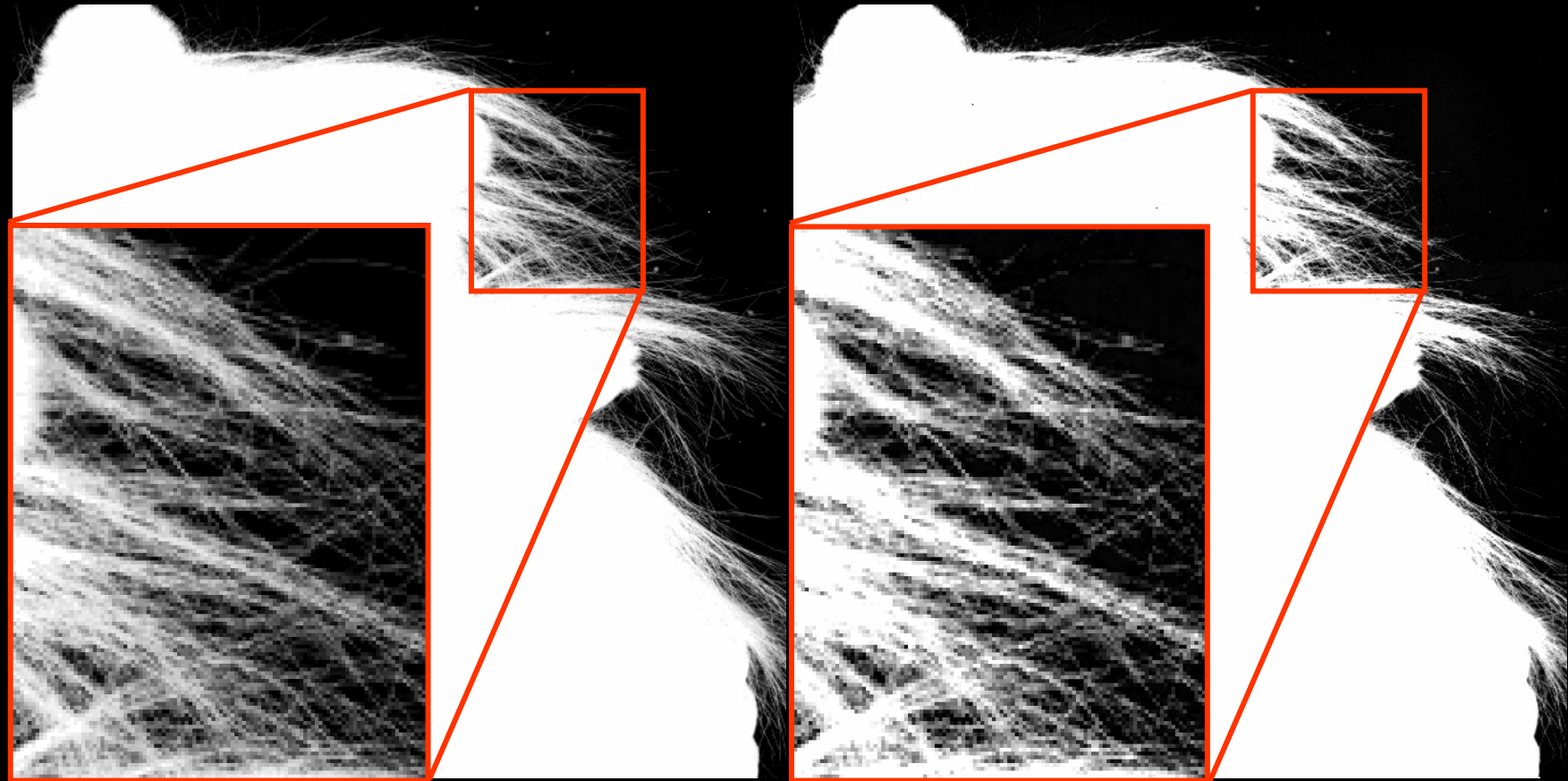
input image



Comparisons

Bayesian

Mishima



Comparisons

Bayesian



Mishima



Comparisons

Video matting

input
video



Video matting

input
video



input
key
trimaps



Video matting

input
video



interpo-
lated
trimaps

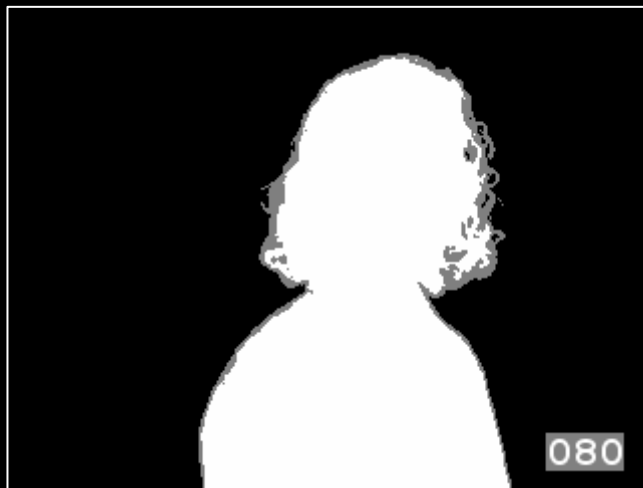


Video matting

input
video



interpo-
lated
trimaps



output
alpha



Video matting

input
video



Compo-
site



interpo-
lated
trimaps

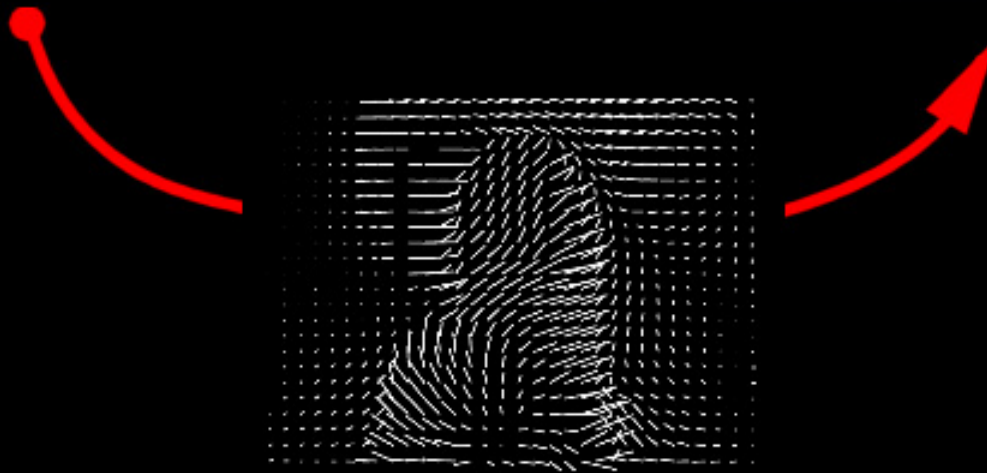


output
alpha



Video matting





optical flow



optical flow





t



t+1



t+2



t+3



t



t+1



t+2



t+3



t

t+1

t+2

t+3



+



t



t+1



t+2



t+3



t

t+1

t+2

t+3



+







Sample composite



Garbage mattes



Garbage mattes



Background estimation



Background estimation



Alpha matte



*without
background*



*with
background*

Comparison

input



composite

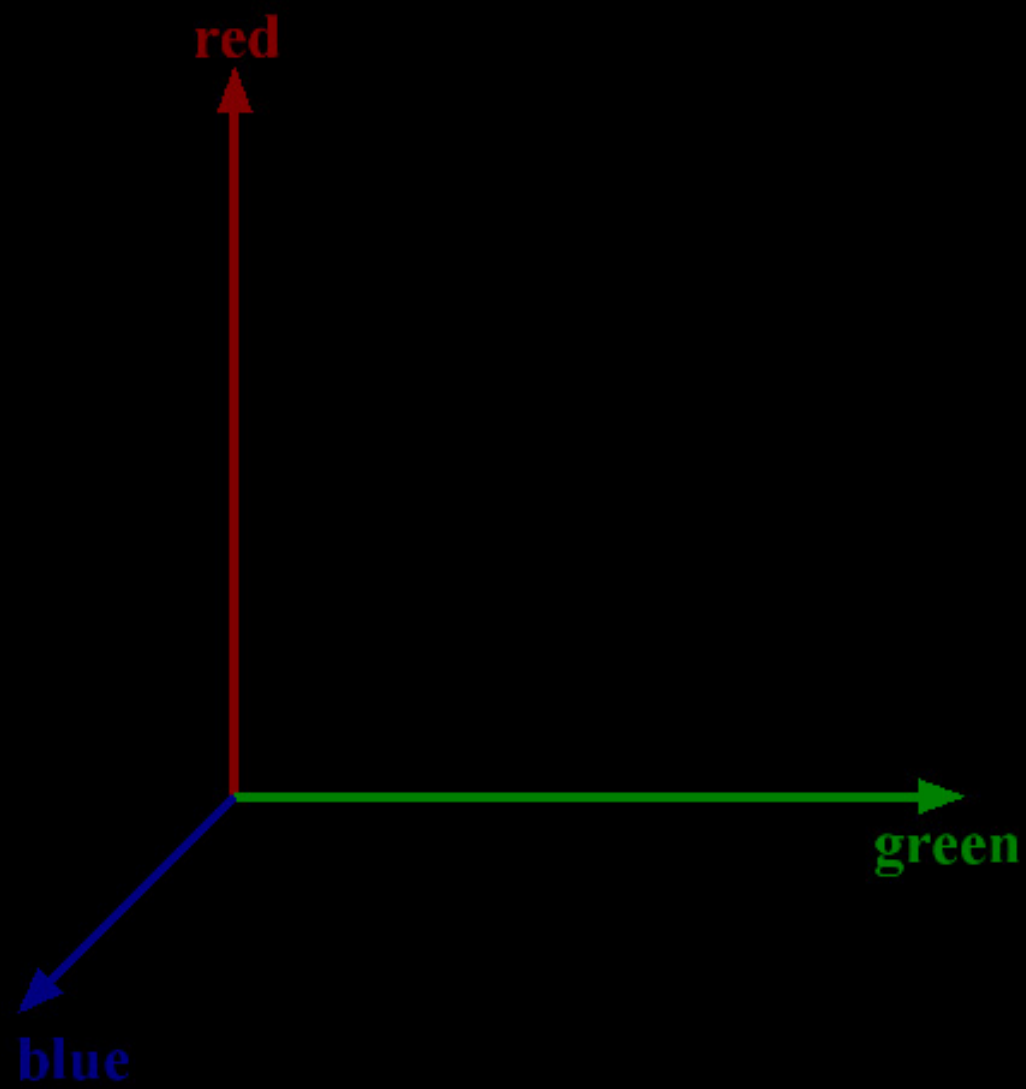








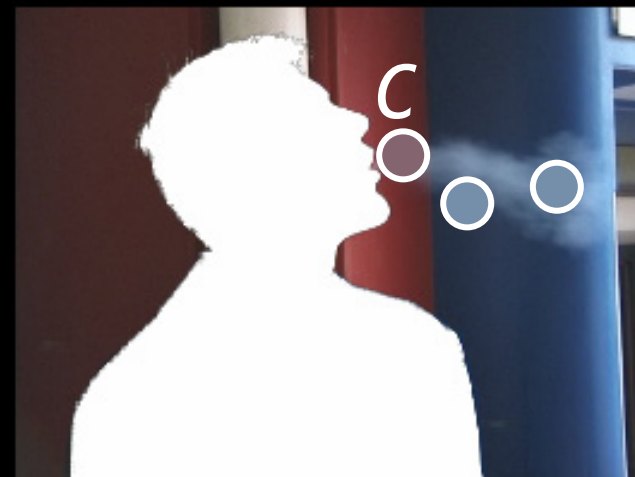
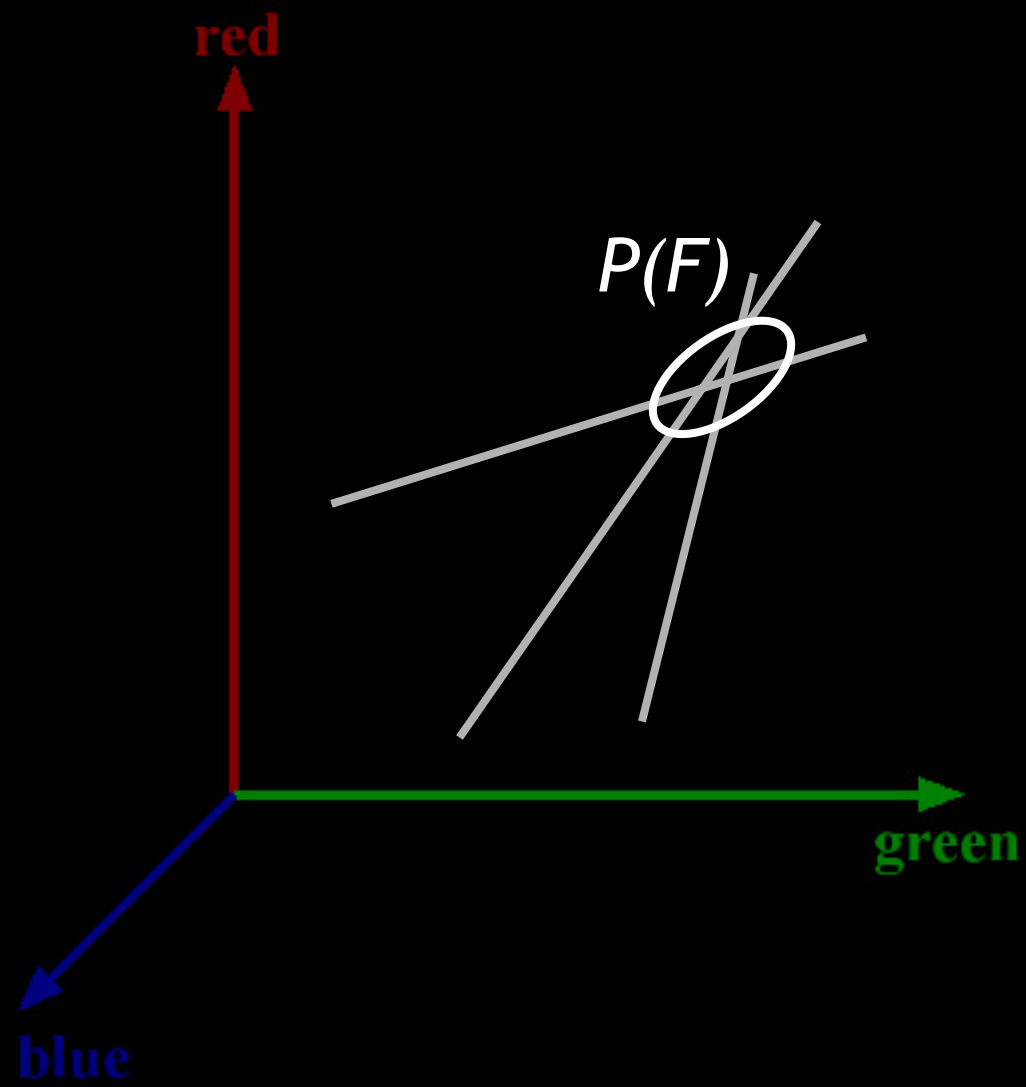




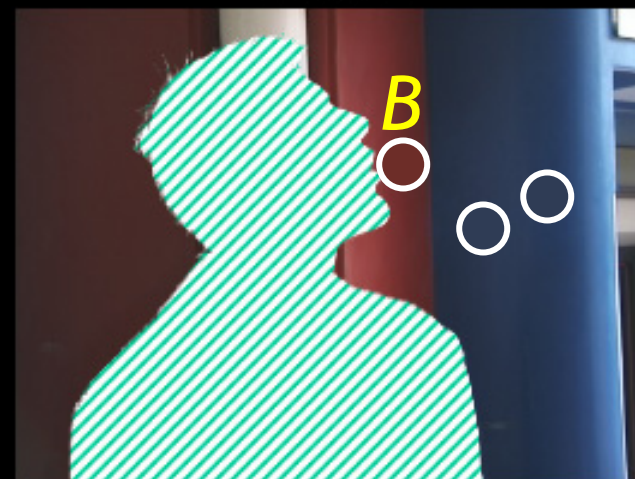
frame



clean plate



frame



clean plate







*Shadow matting
and composting*

source scene



target background



blue screen image



target background



blue screen composite



target background



blue screen composite

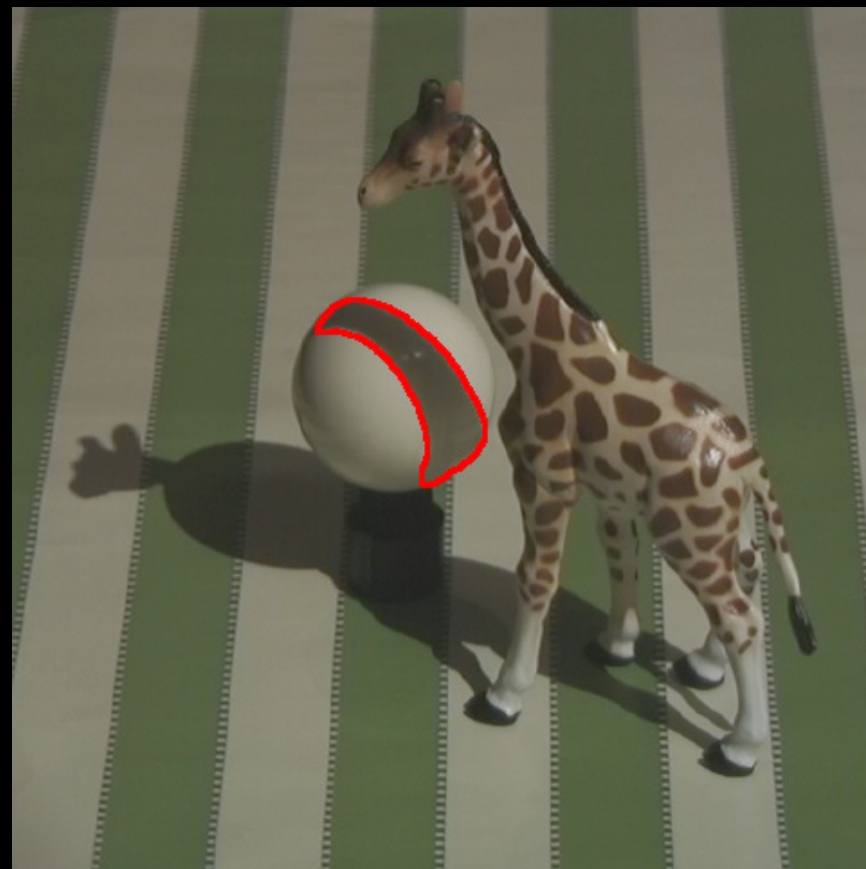
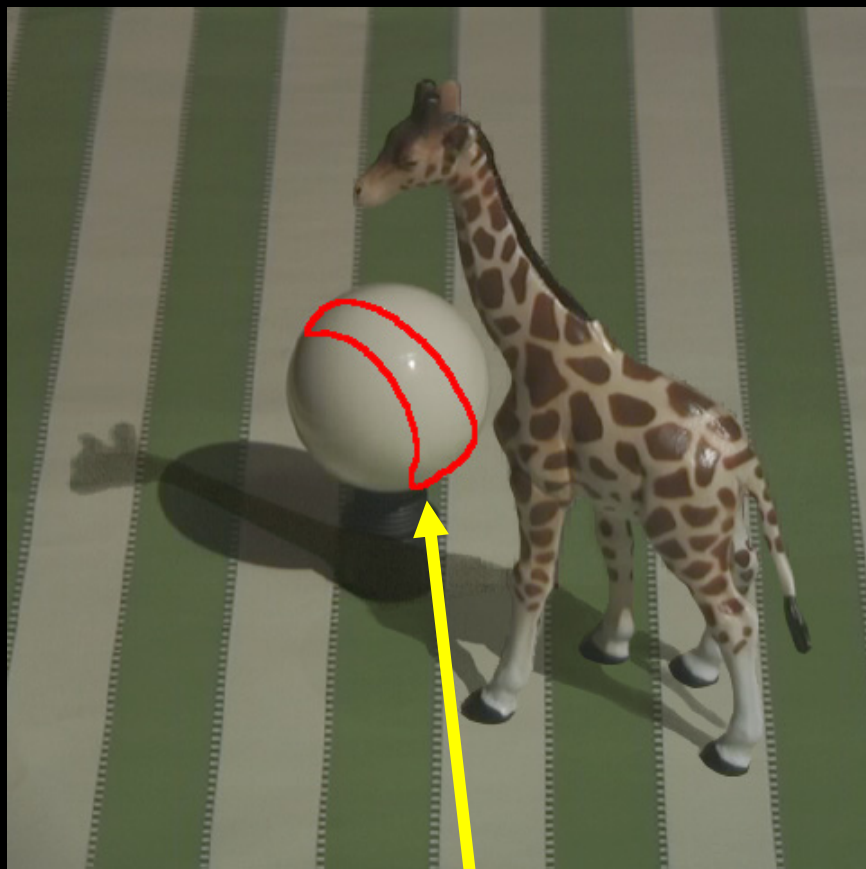


photograph



blue screen composite

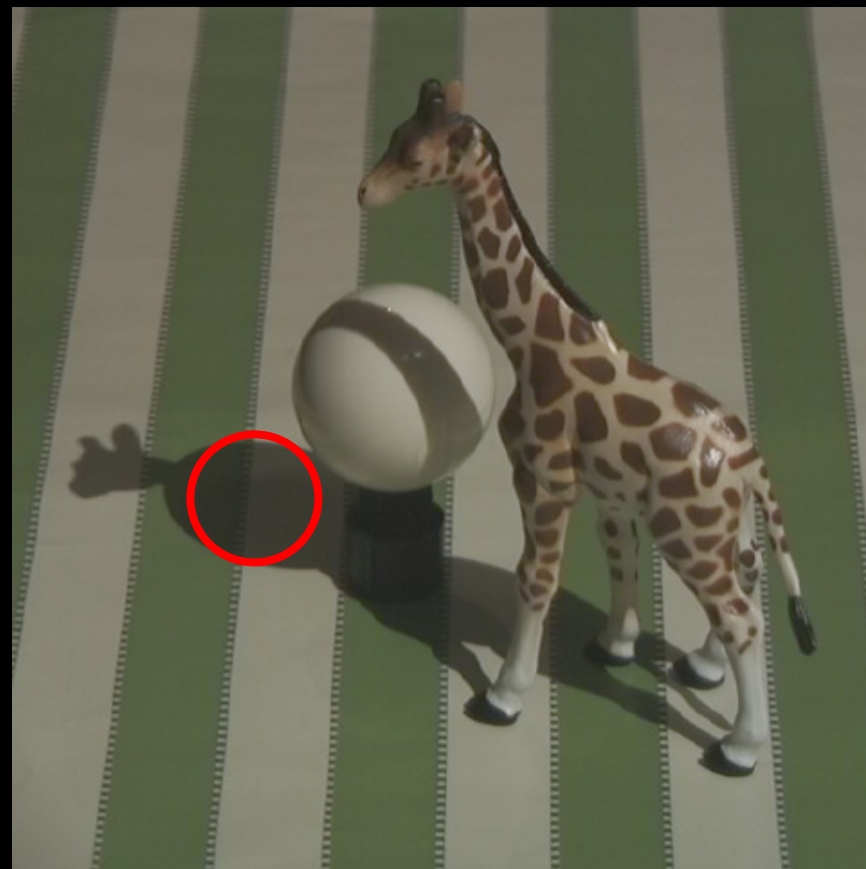
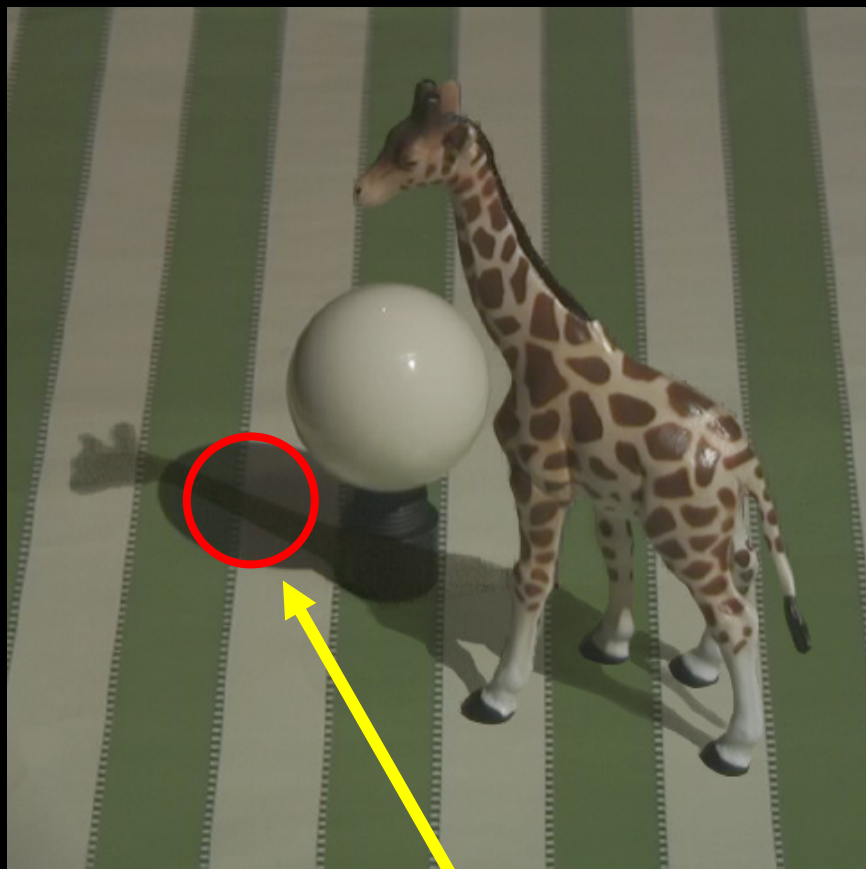
photograph



Geometric errors

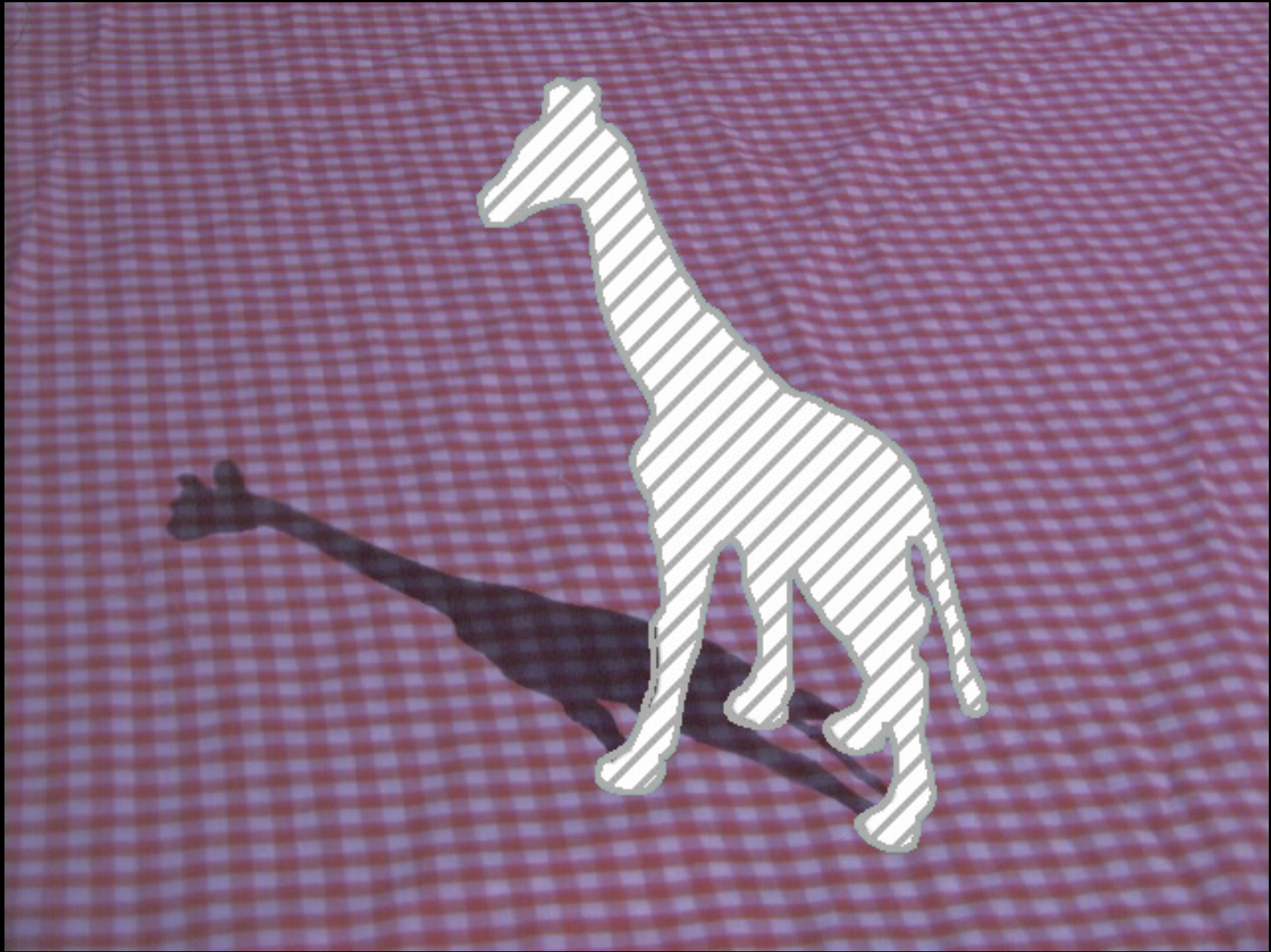
blue screen composite

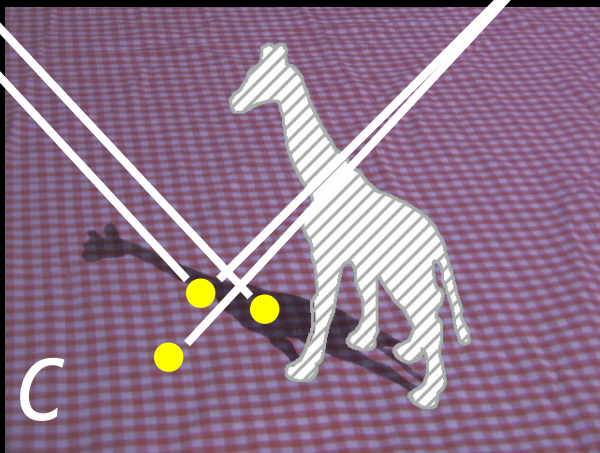
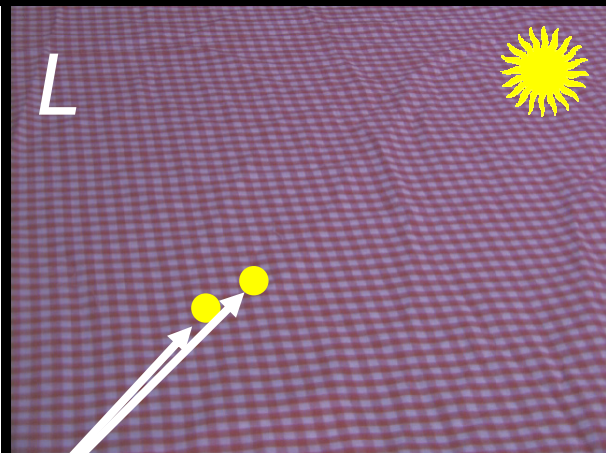
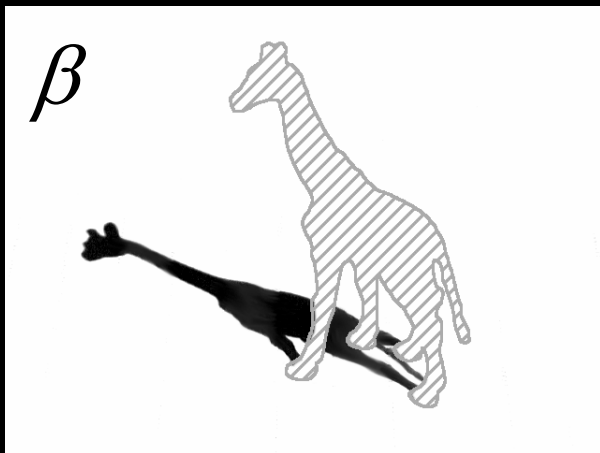
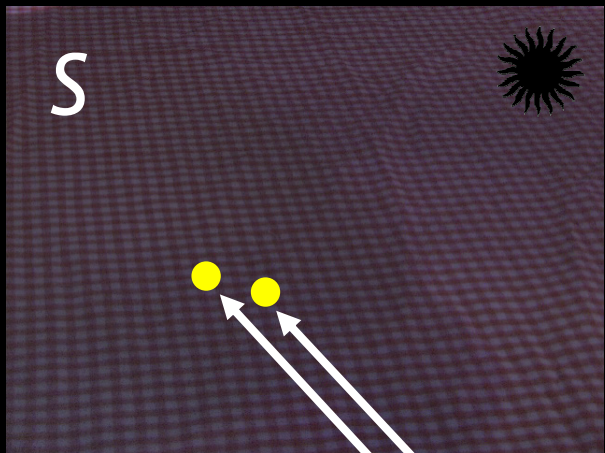
photograph

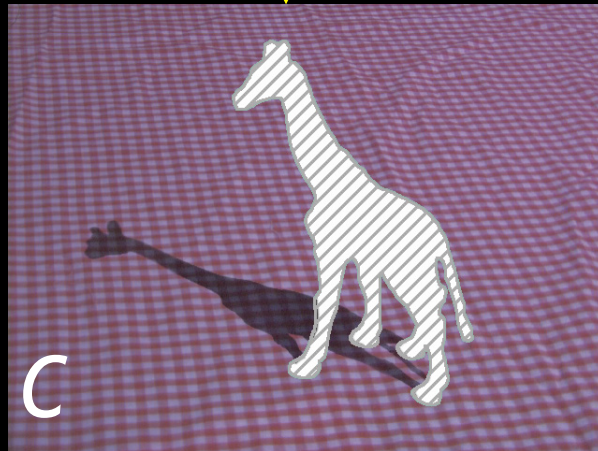
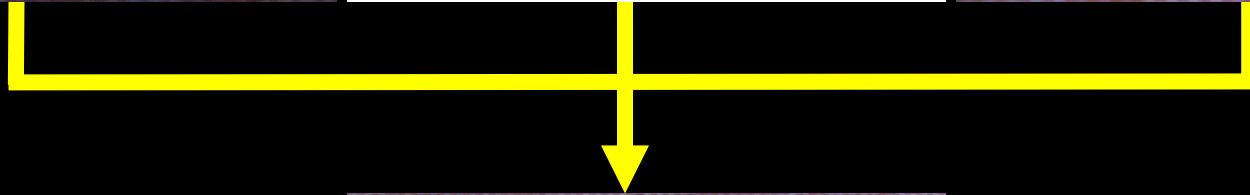
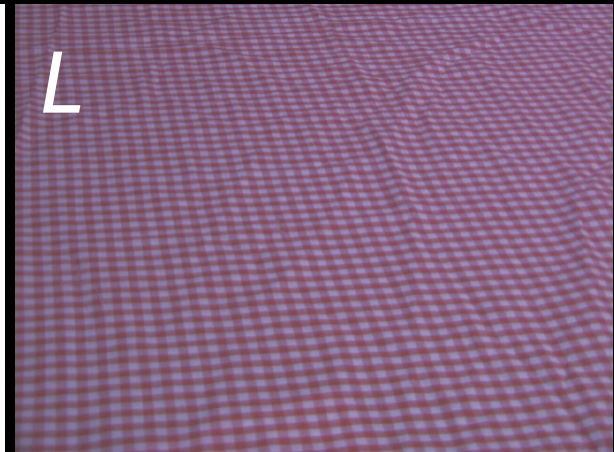
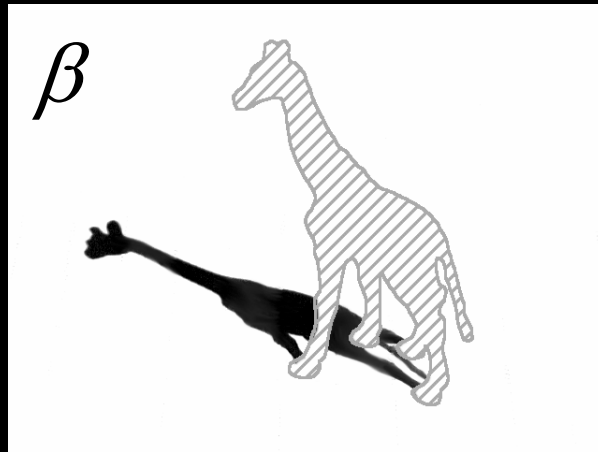
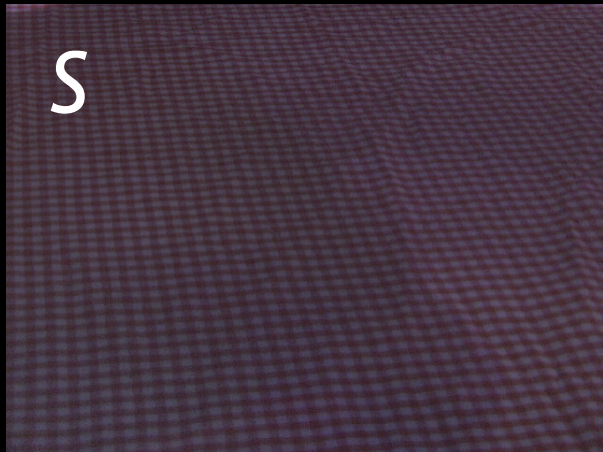


Photometric errors





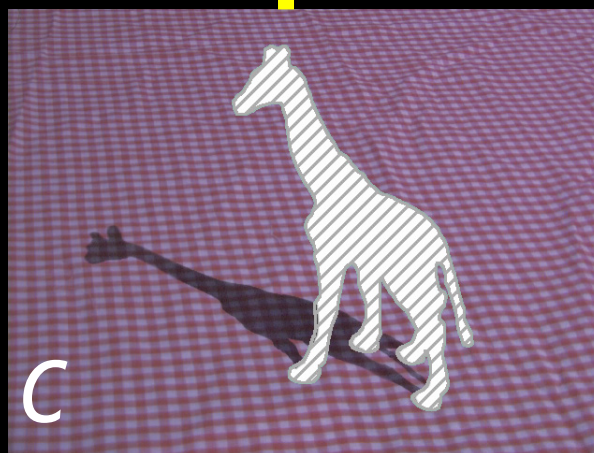
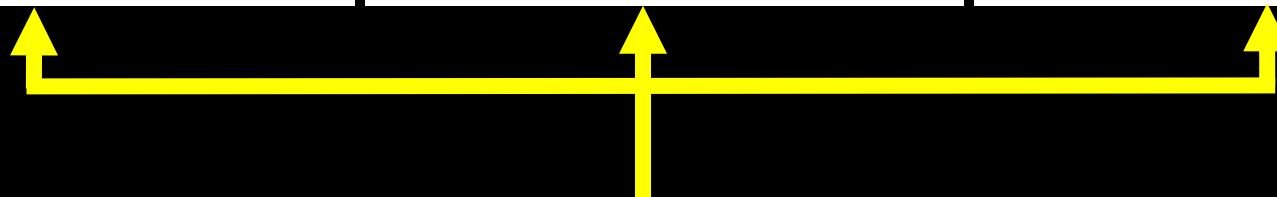
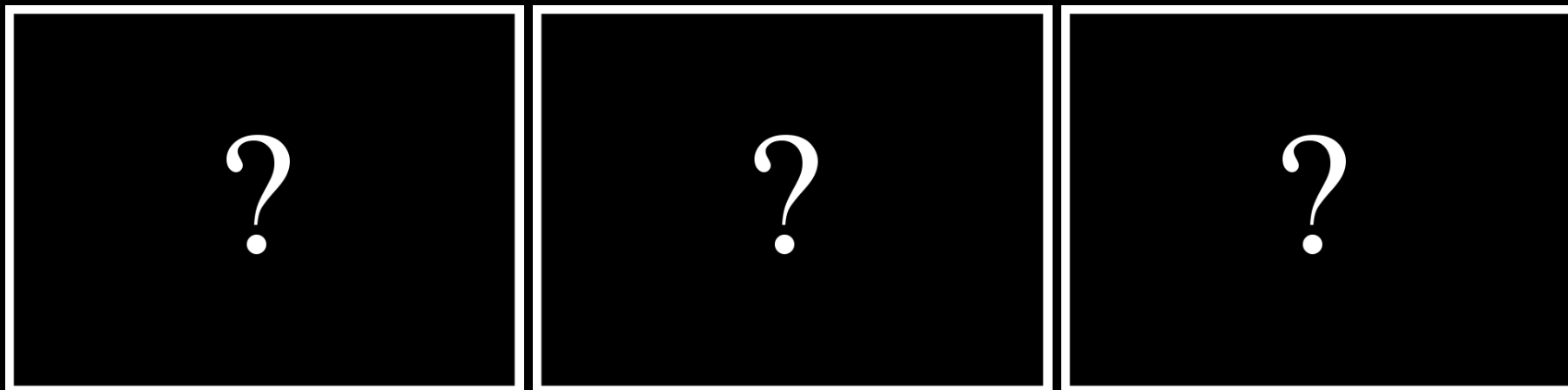




$$C = \beta L + (1 - \beta) S$$

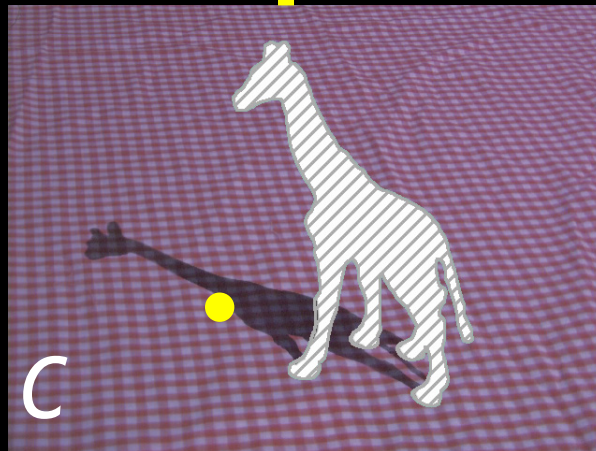
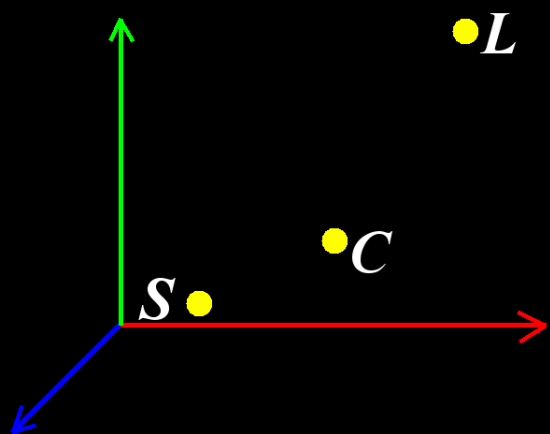
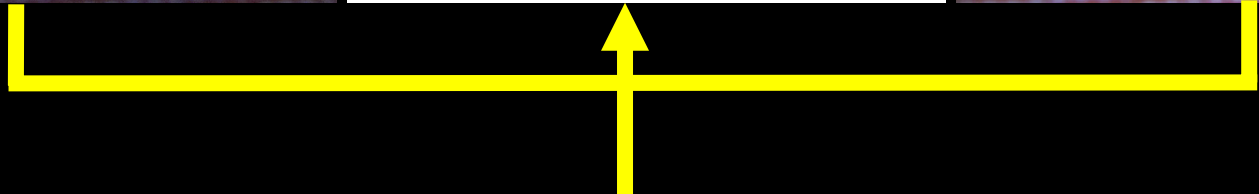
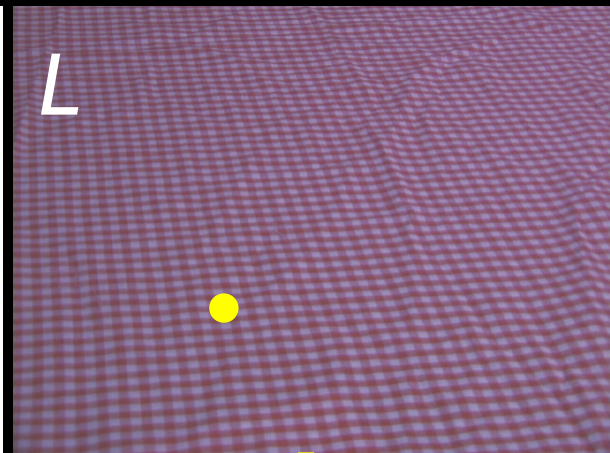
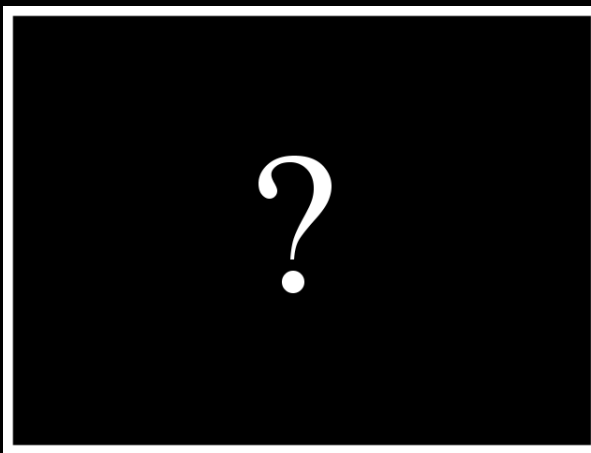
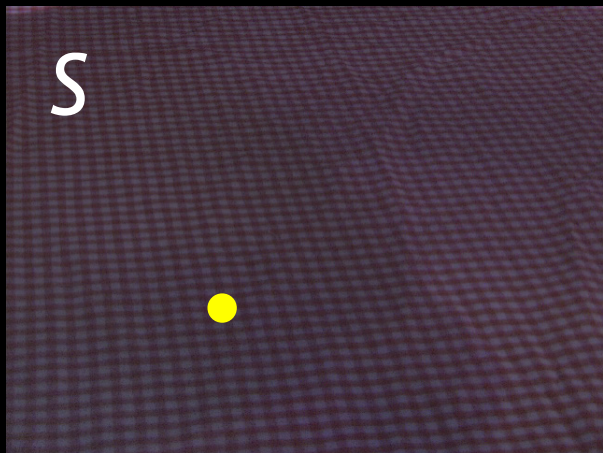
shadow
compositing
equation

Shadow compositing equation



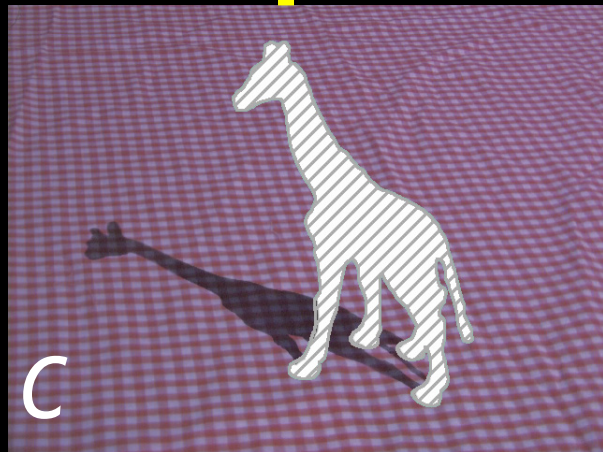
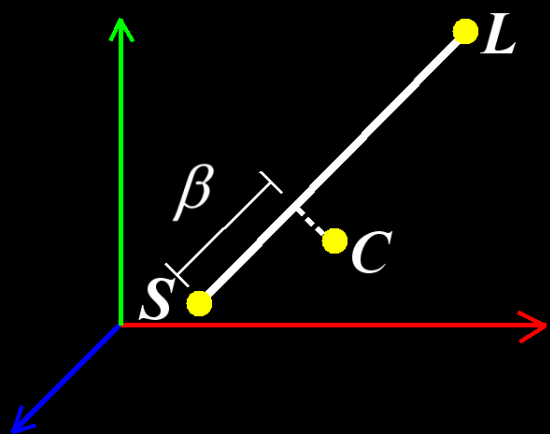
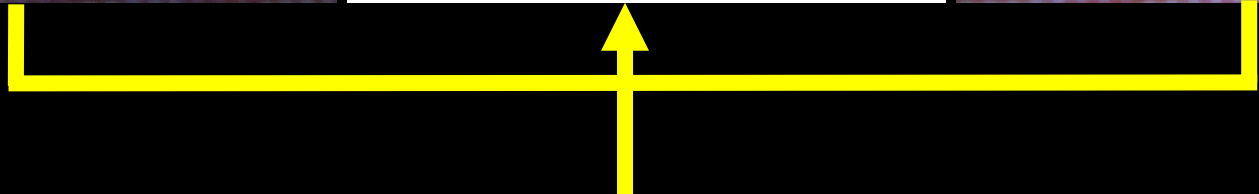
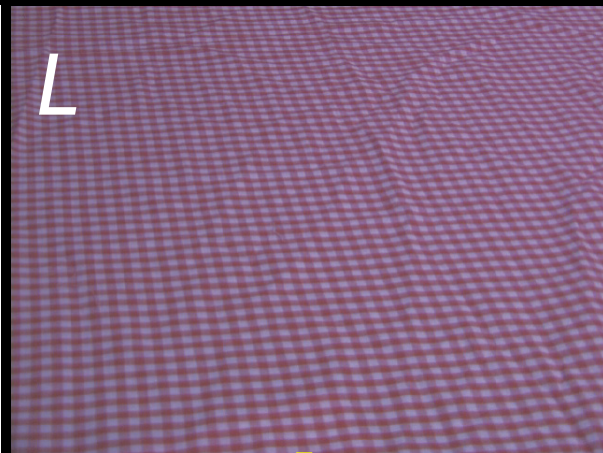
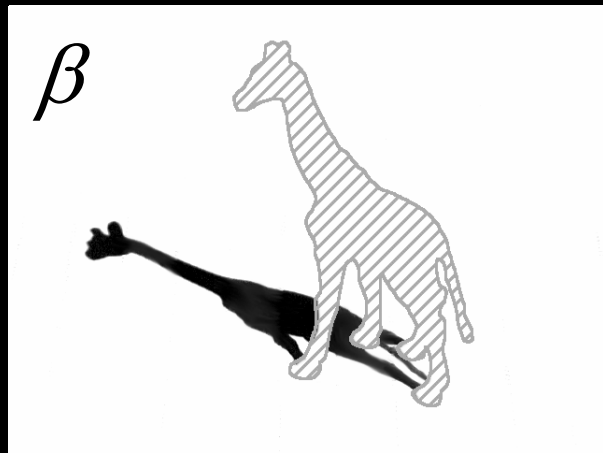
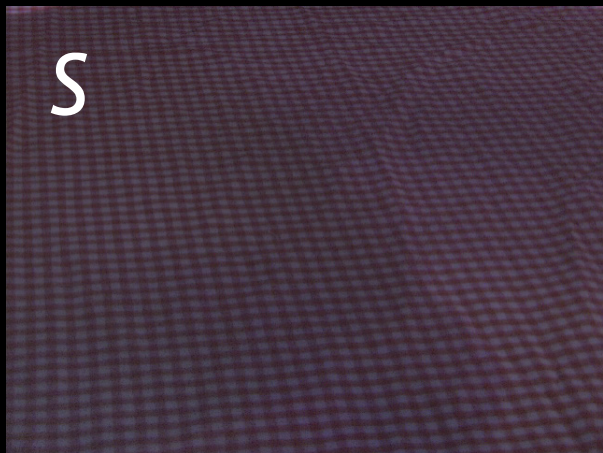
$C = \beta L + (1 - \beta) S$
shadow
compositing
equation

Shadow matting



$C = \beta L + (1 - \beta)S$
shadow
compositing
equation

Shadow matting



$$C = \beta L + (1 - \beta)S$$

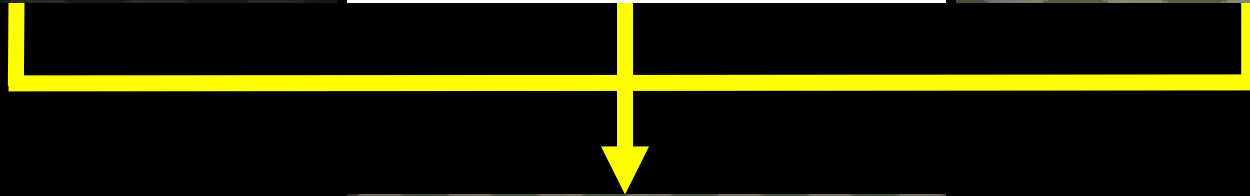
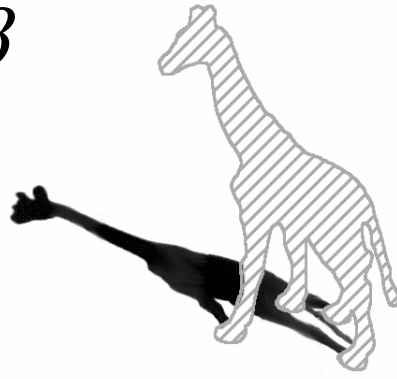
shadow
compositing
equation

Shadow matting

S

β

L



$$C = \beta L + (1 - \beta) S$$

shadow
compositing
equation

Shadow compositing



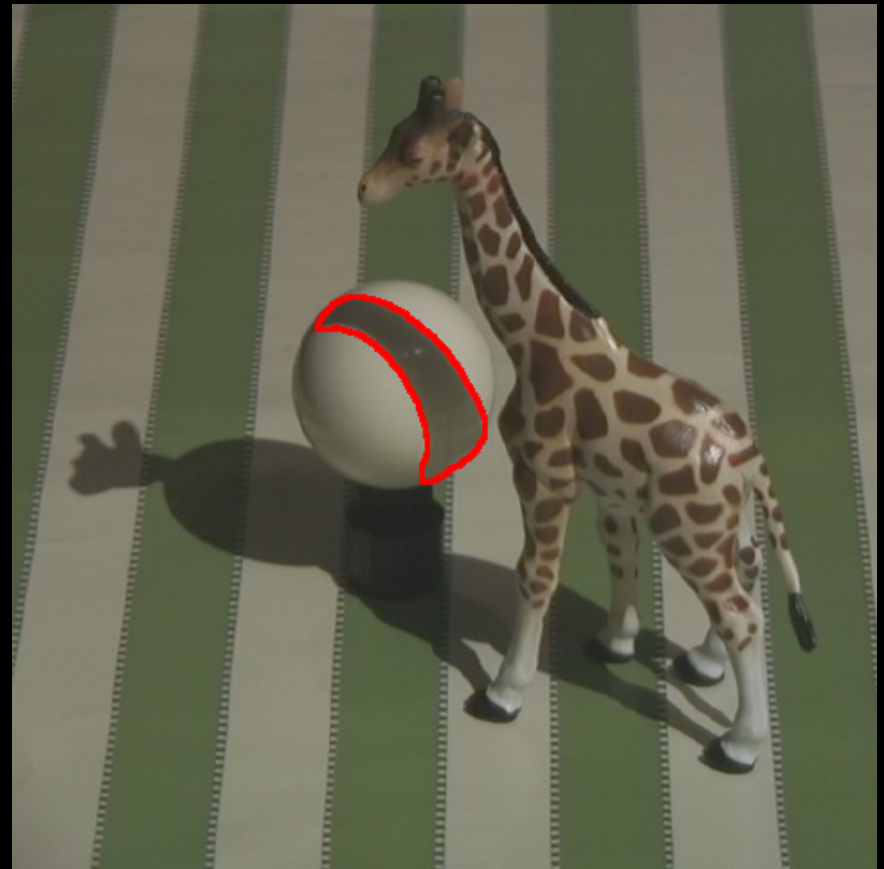
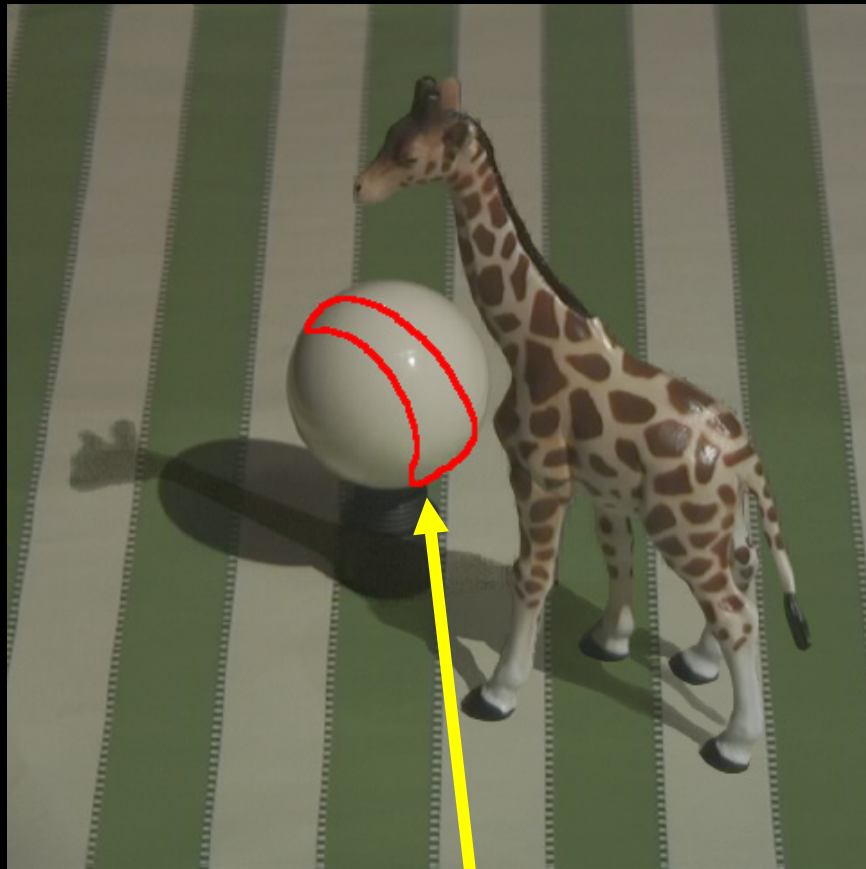












Geometric errors

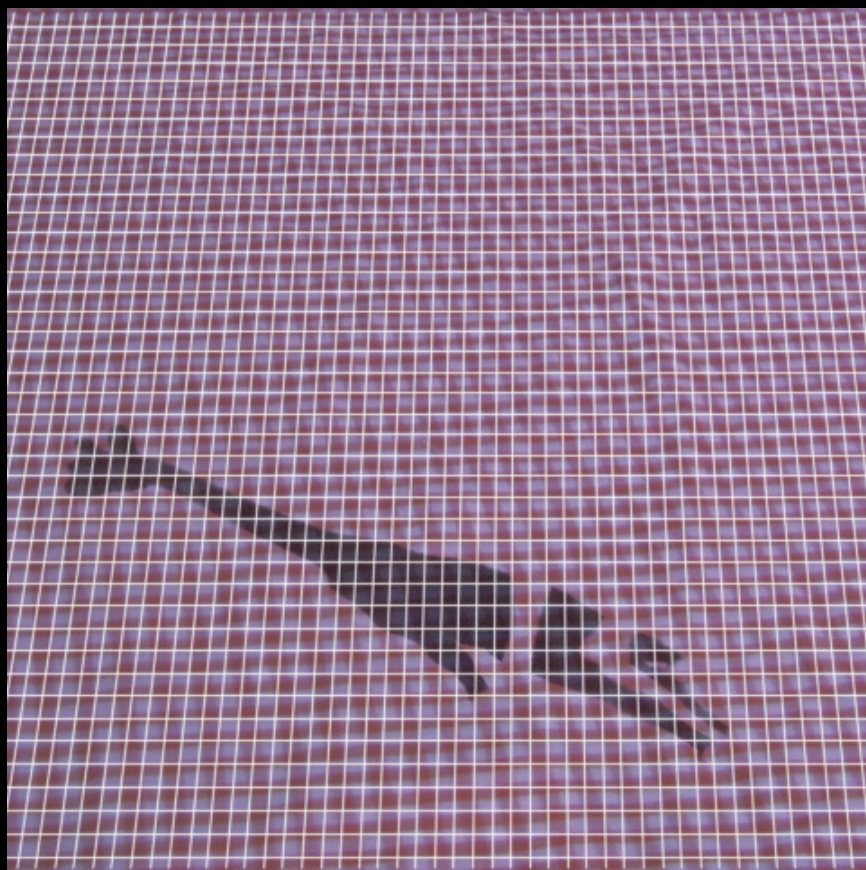
source scene



target background



source scene

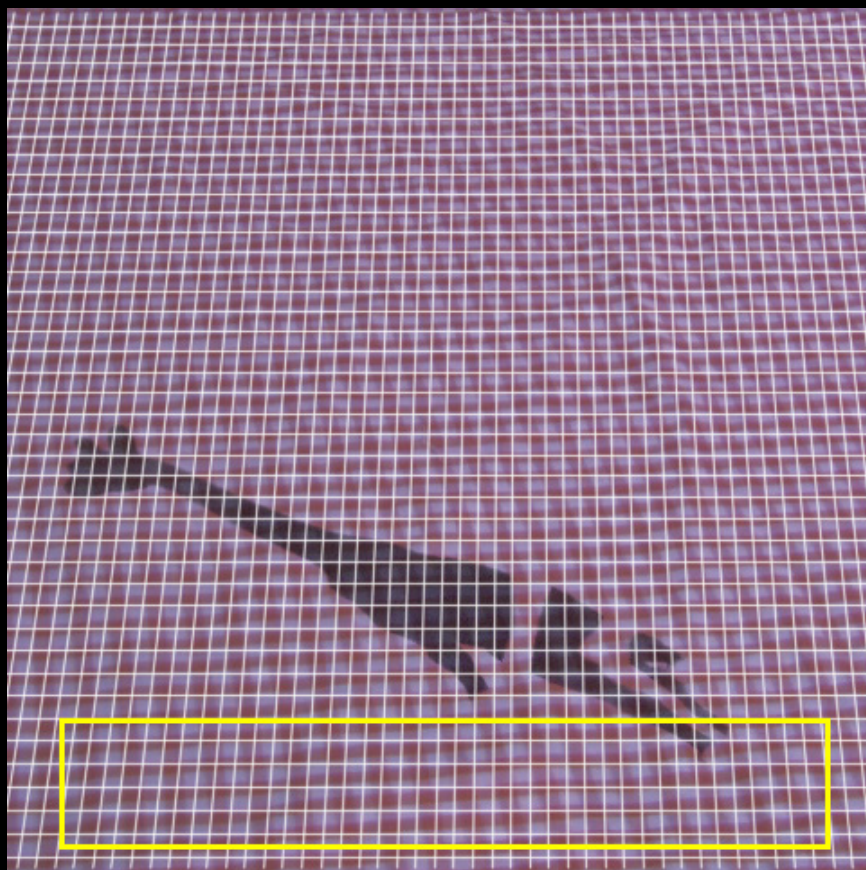


target background

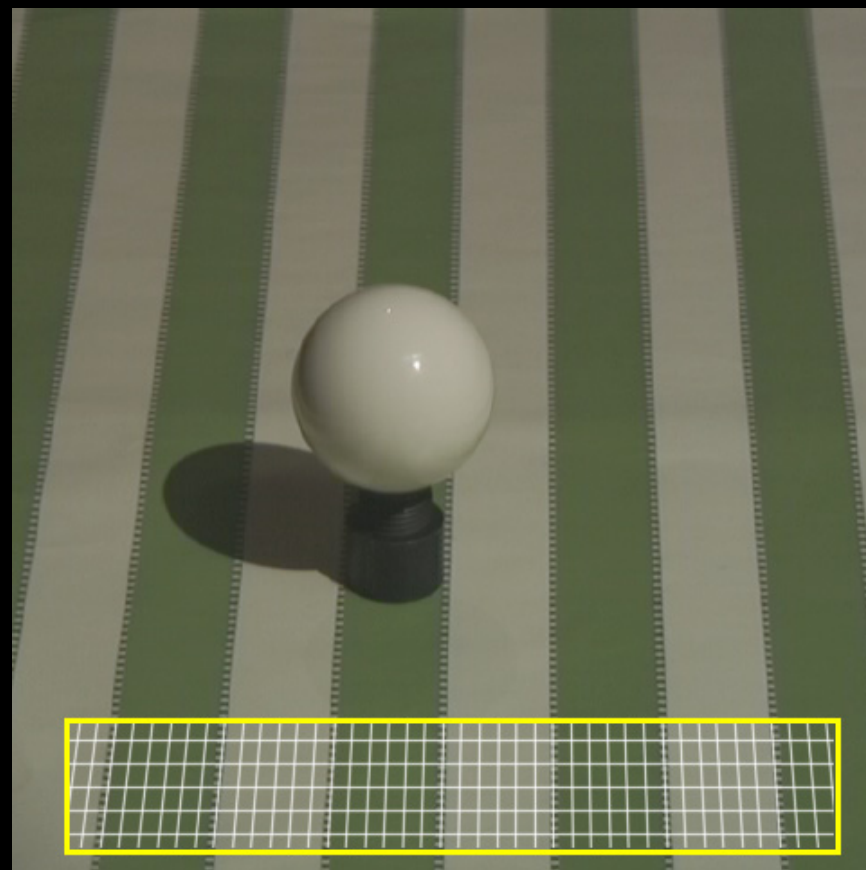


Requirement #1

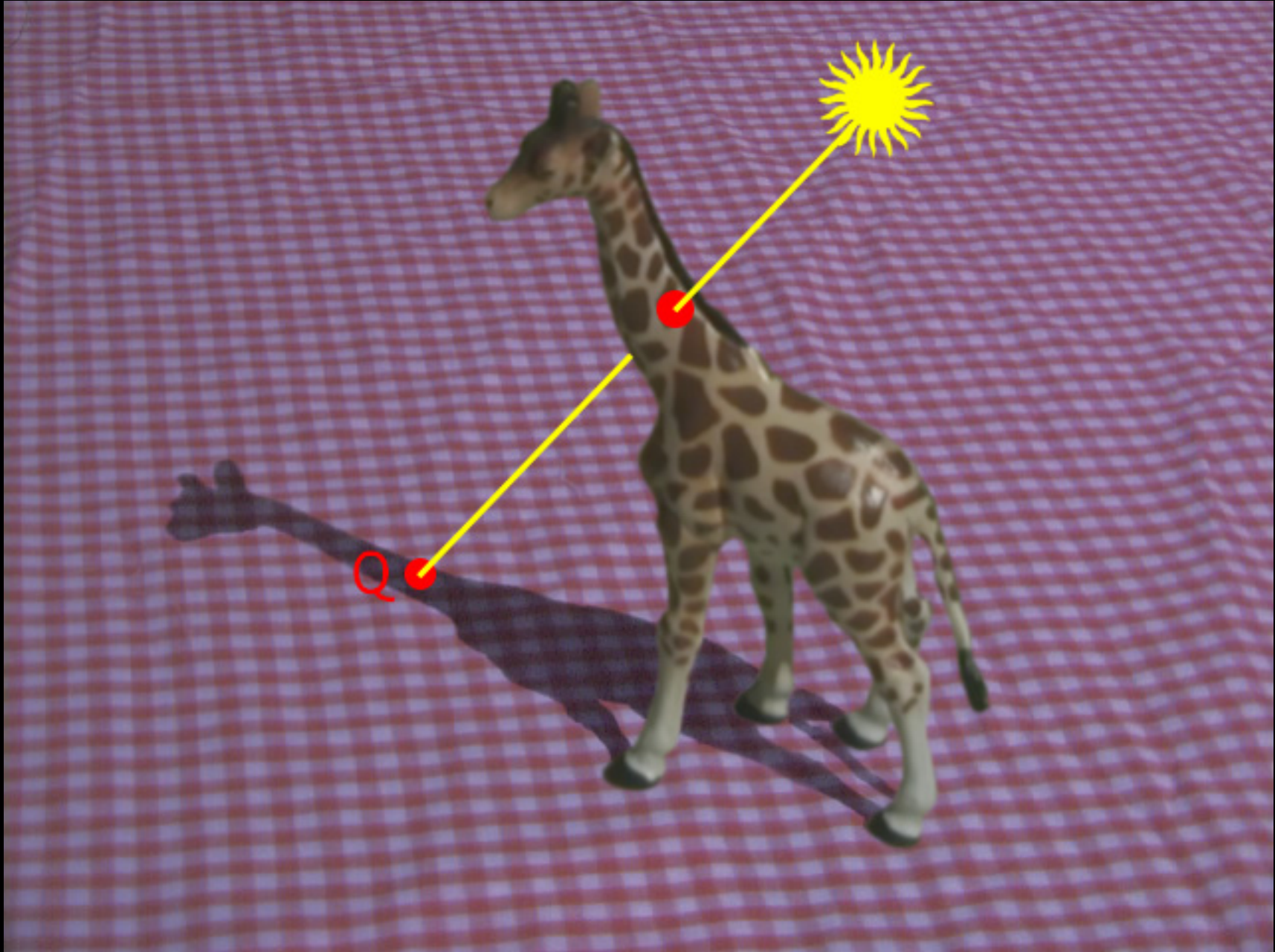
source scene

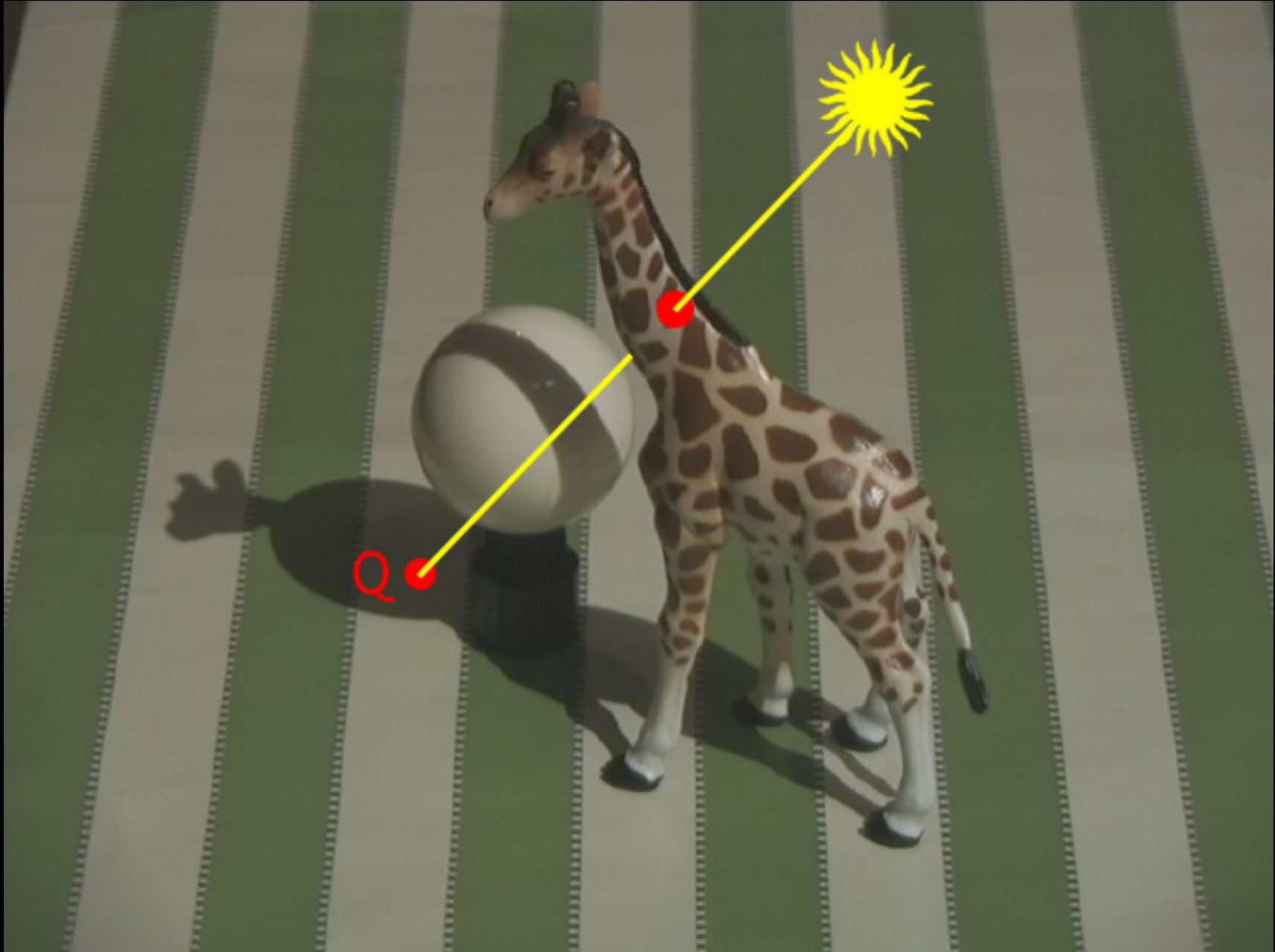


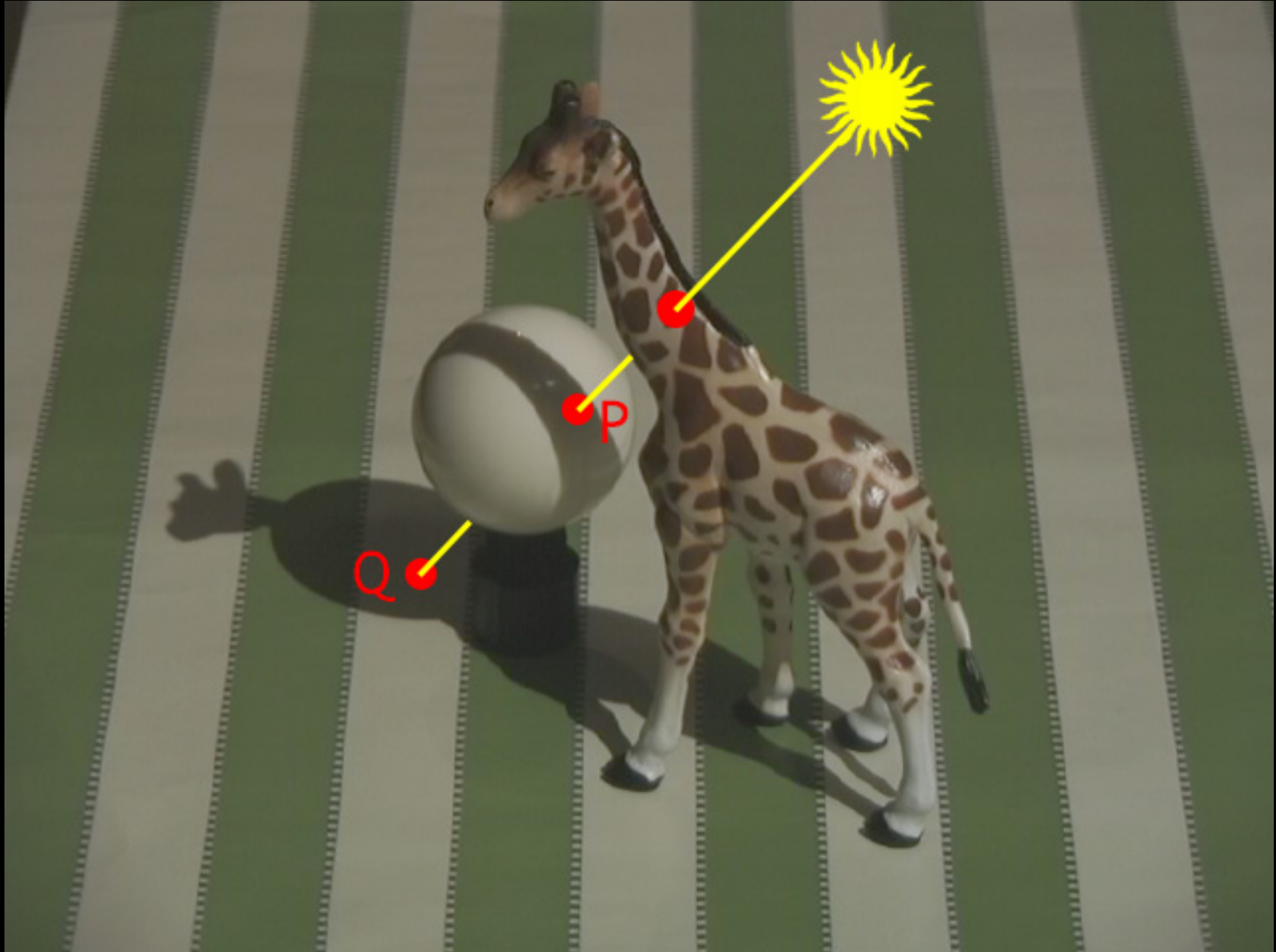
target background

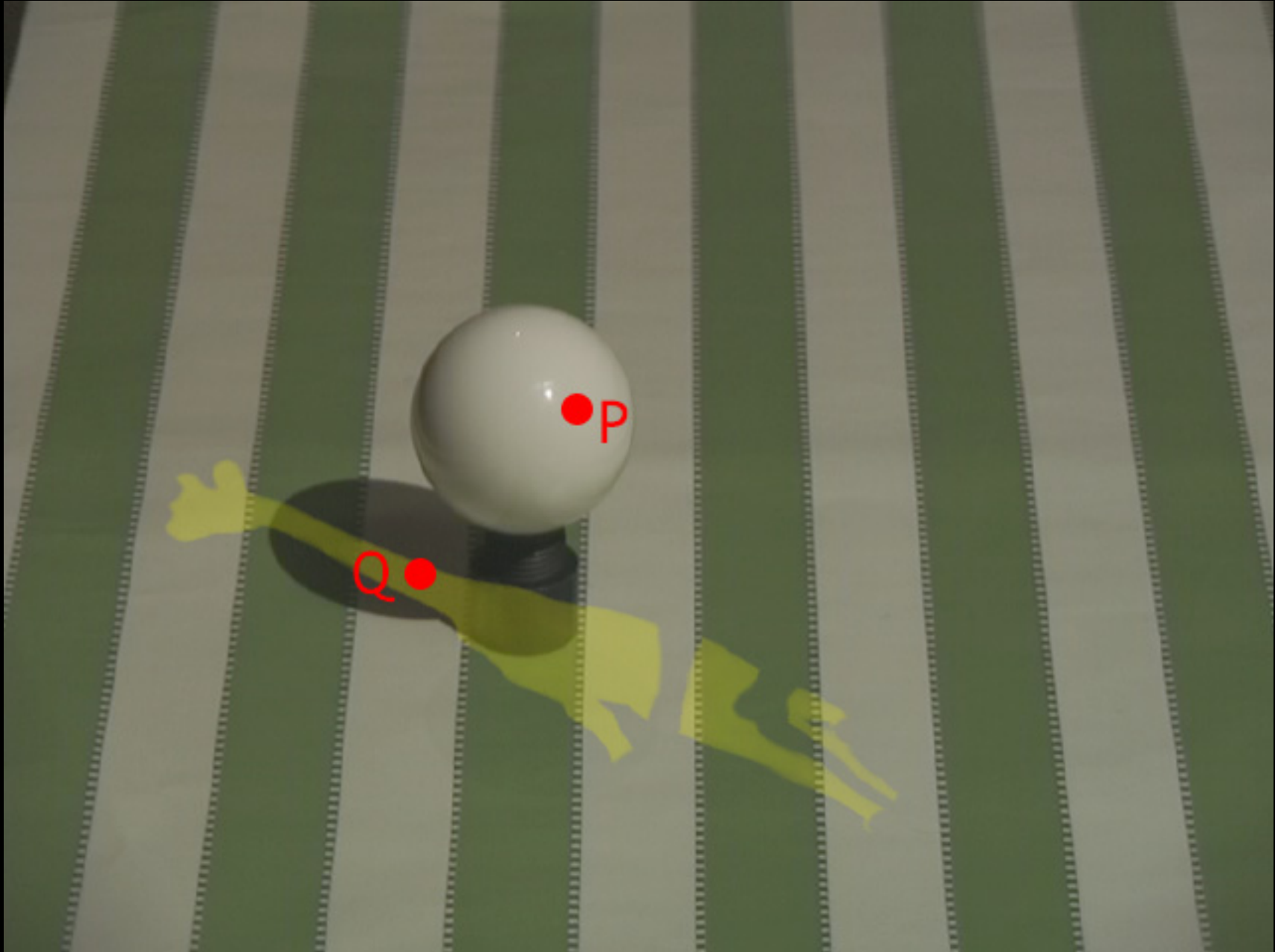


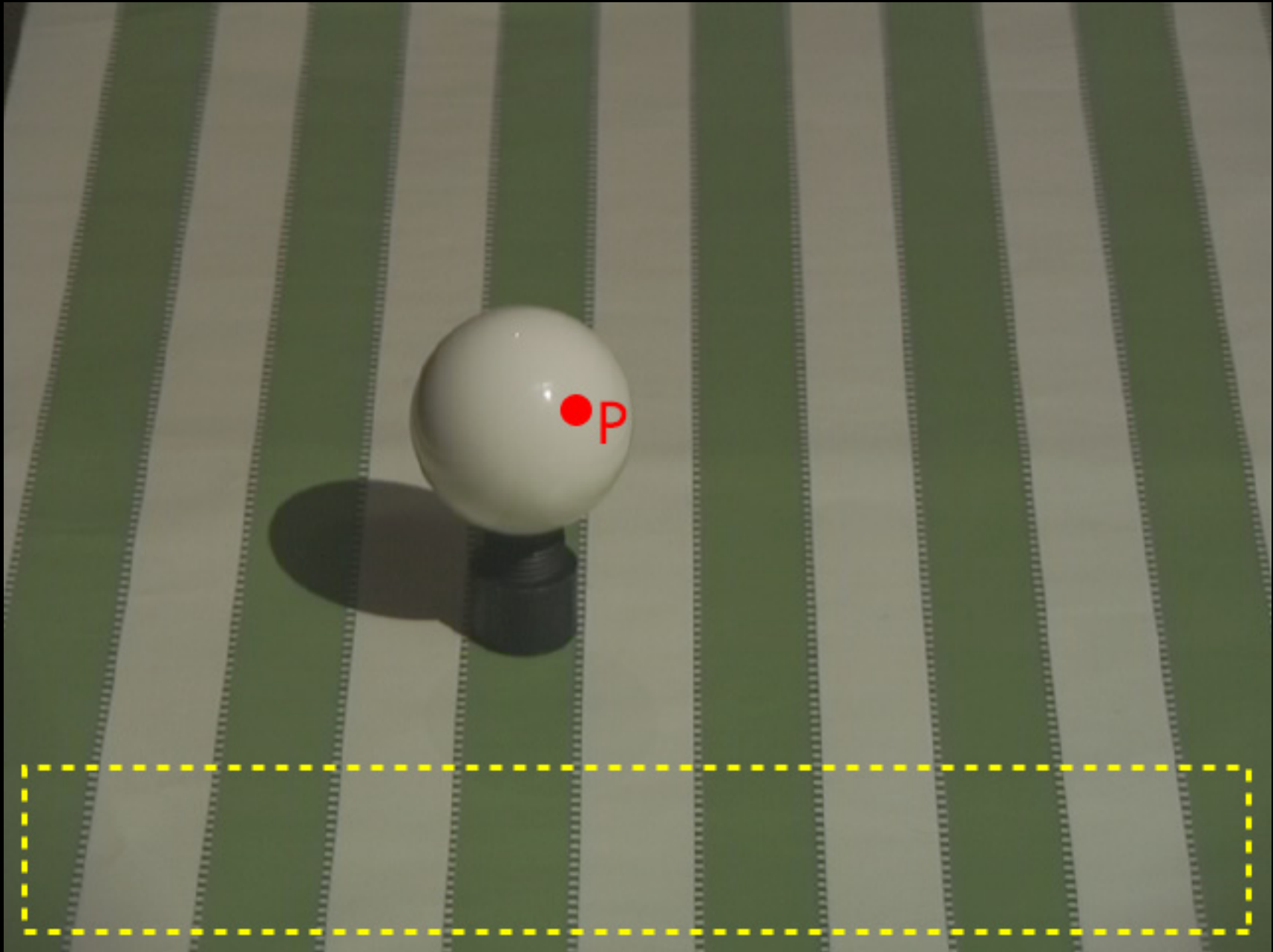
Requirement #2

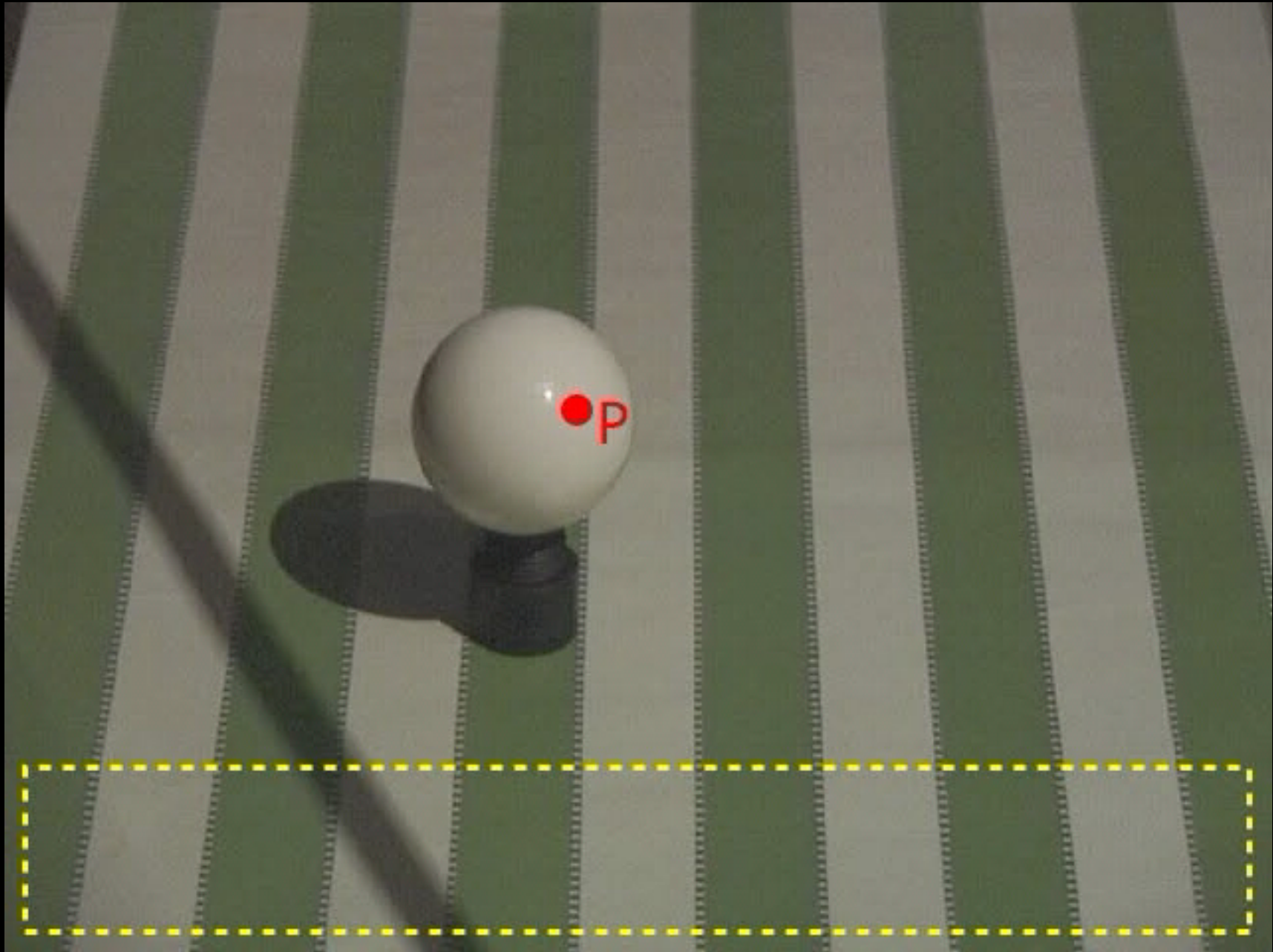


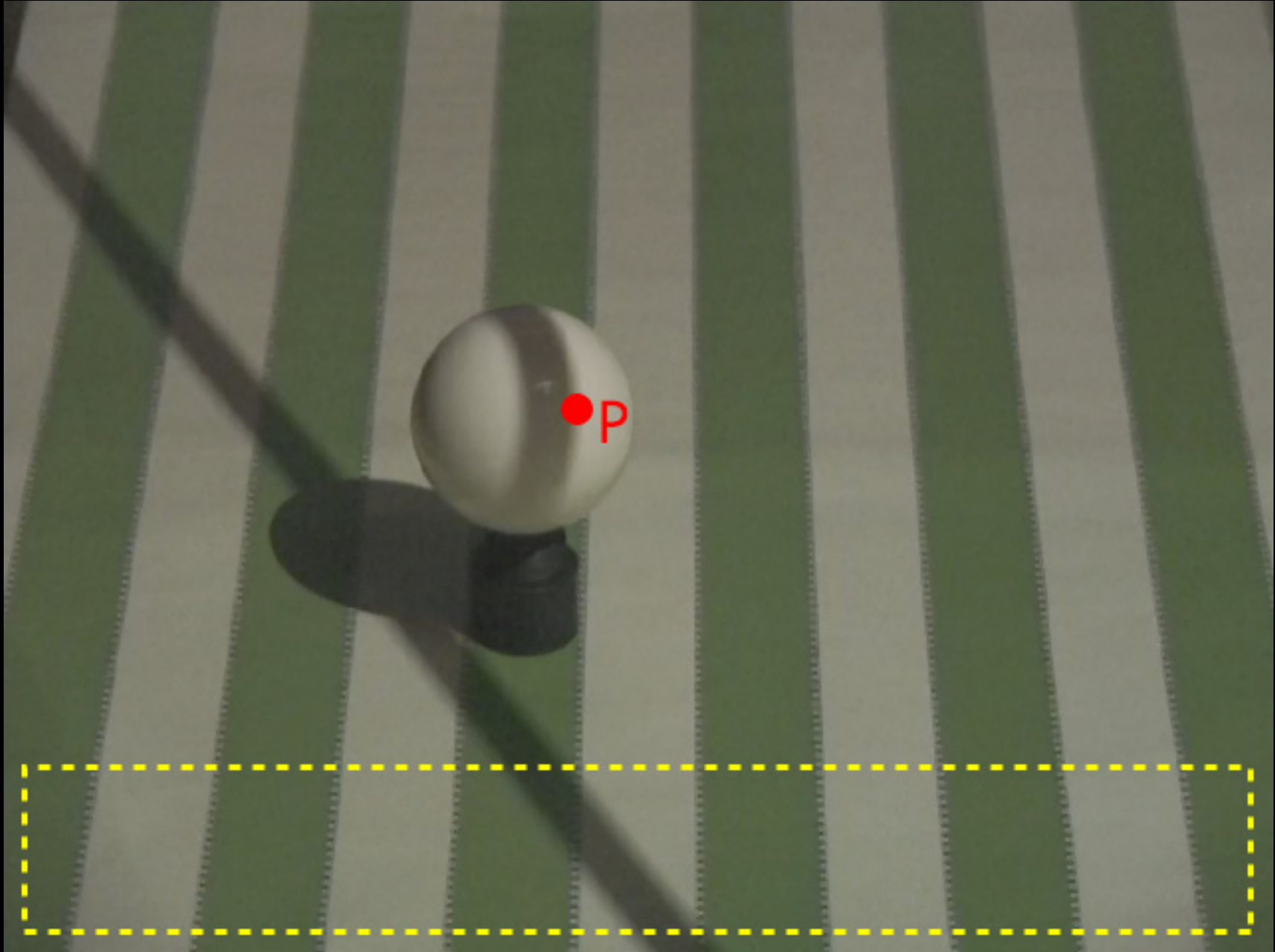


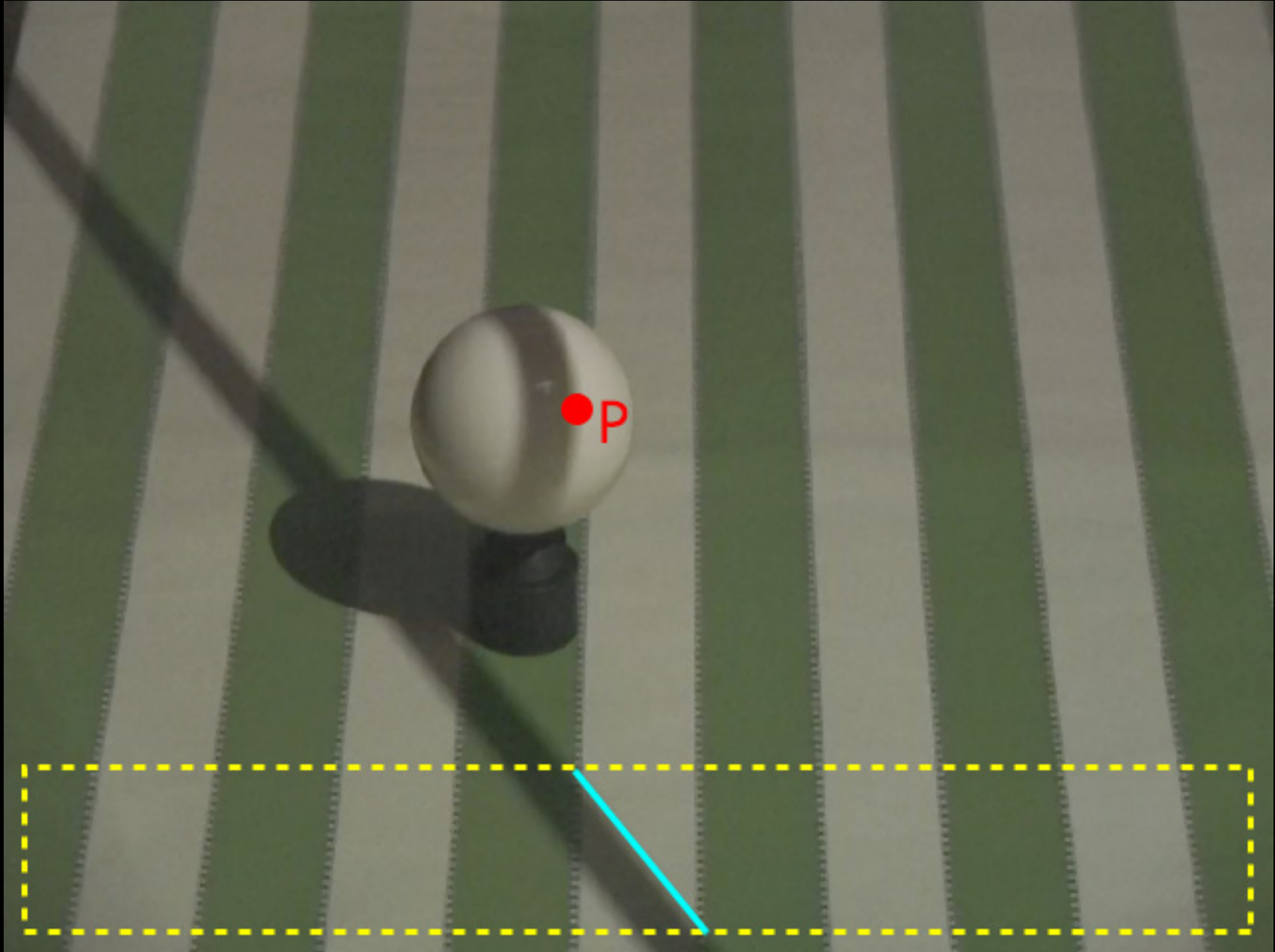


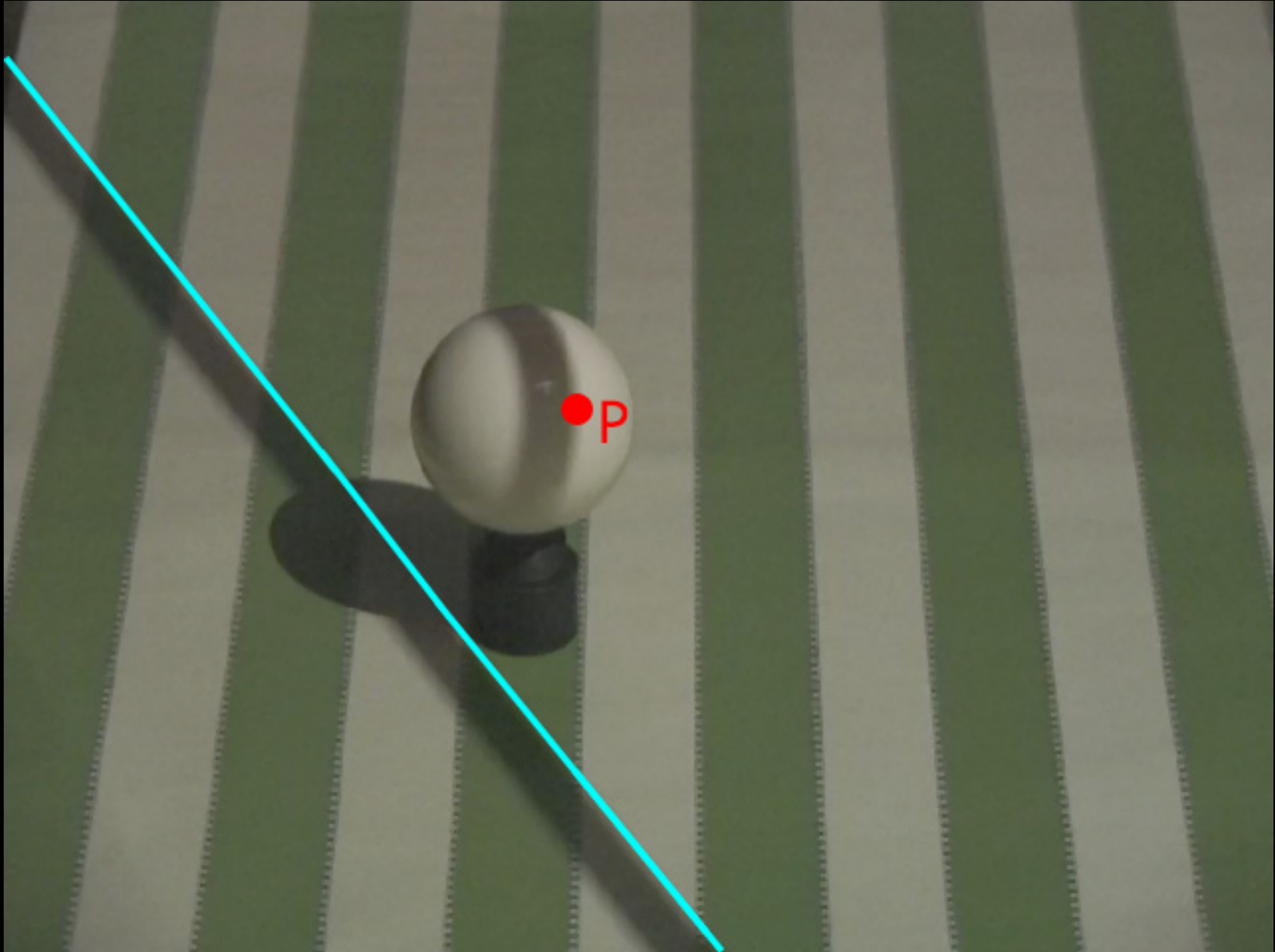


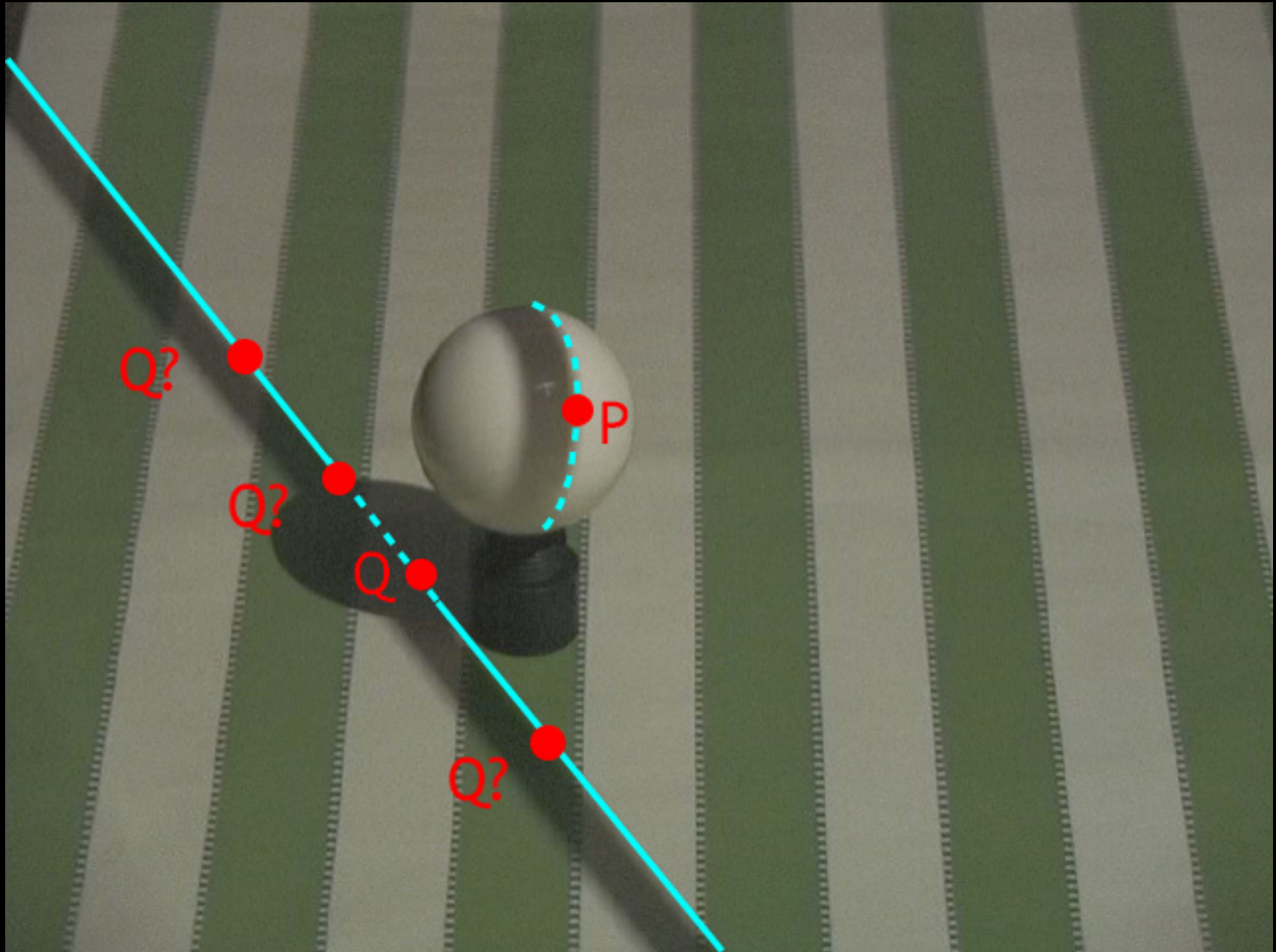


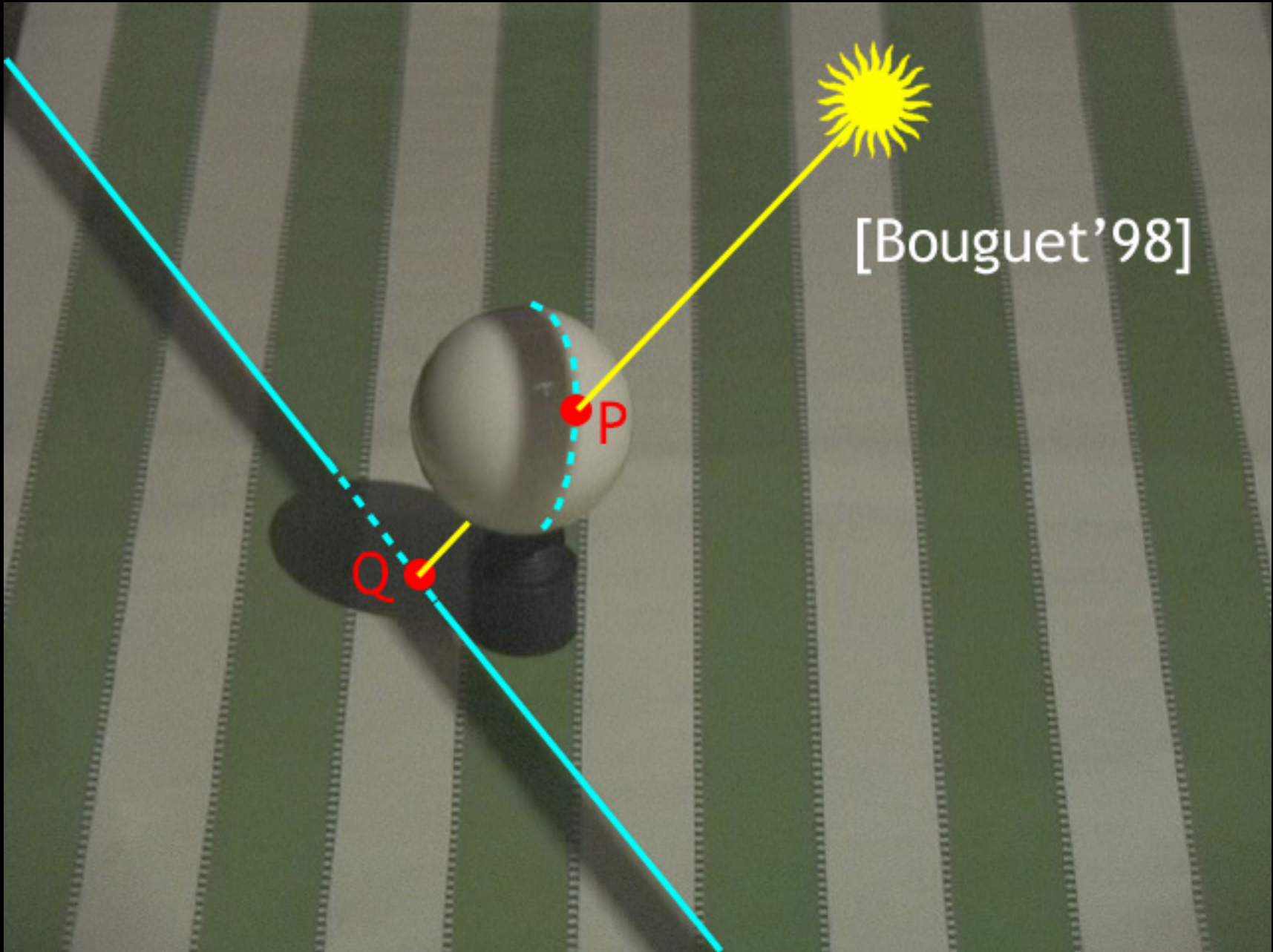


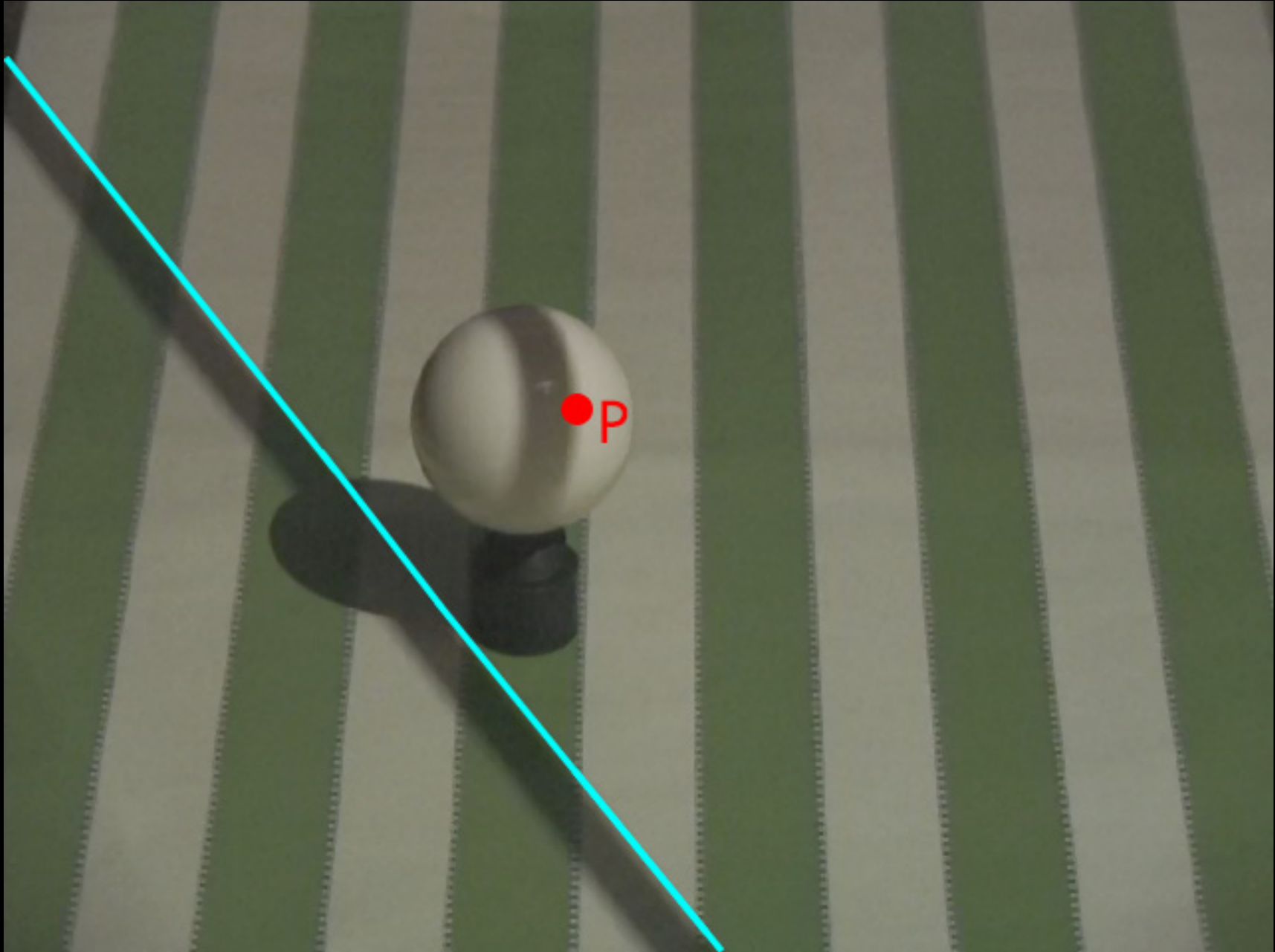


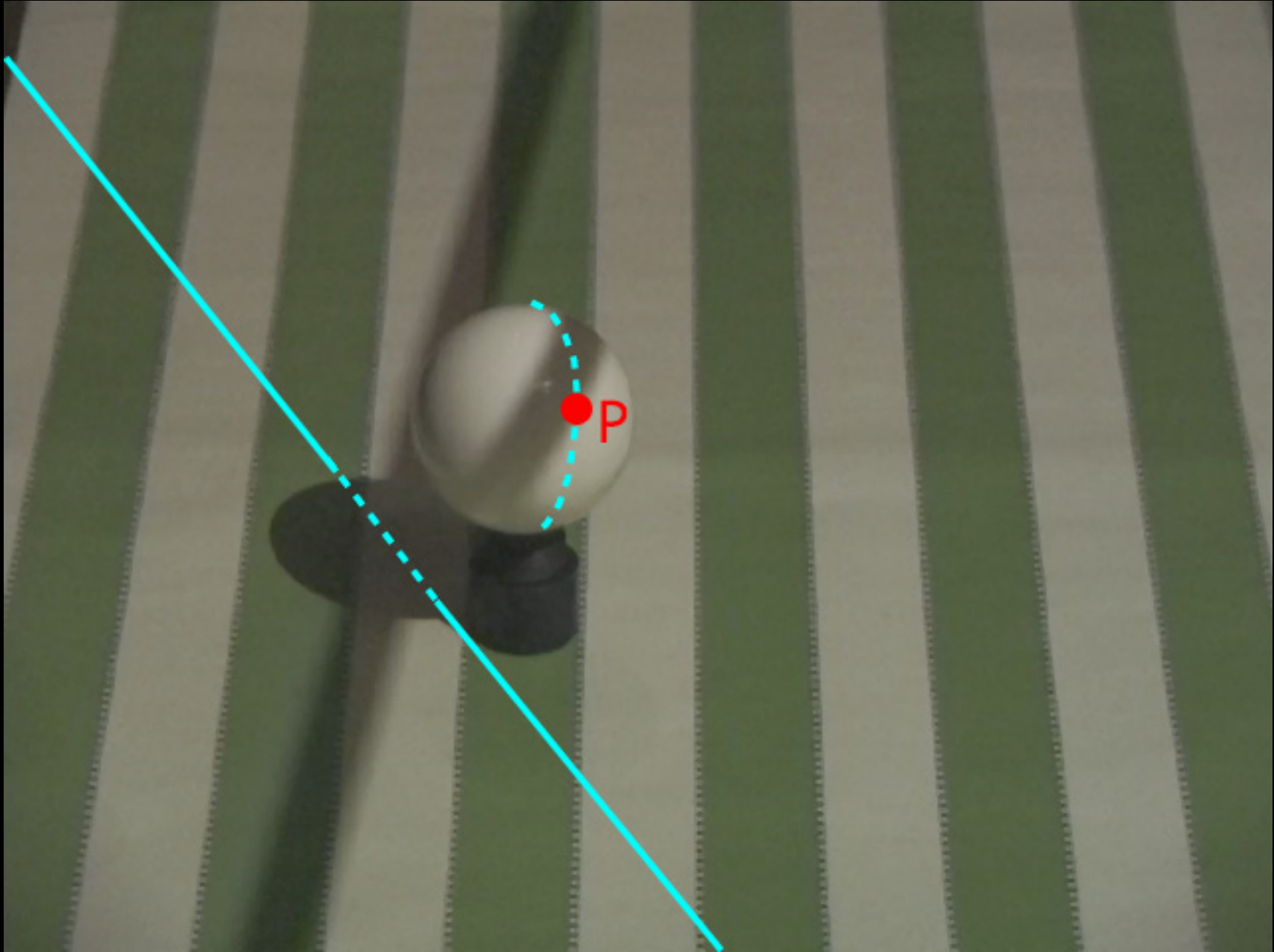


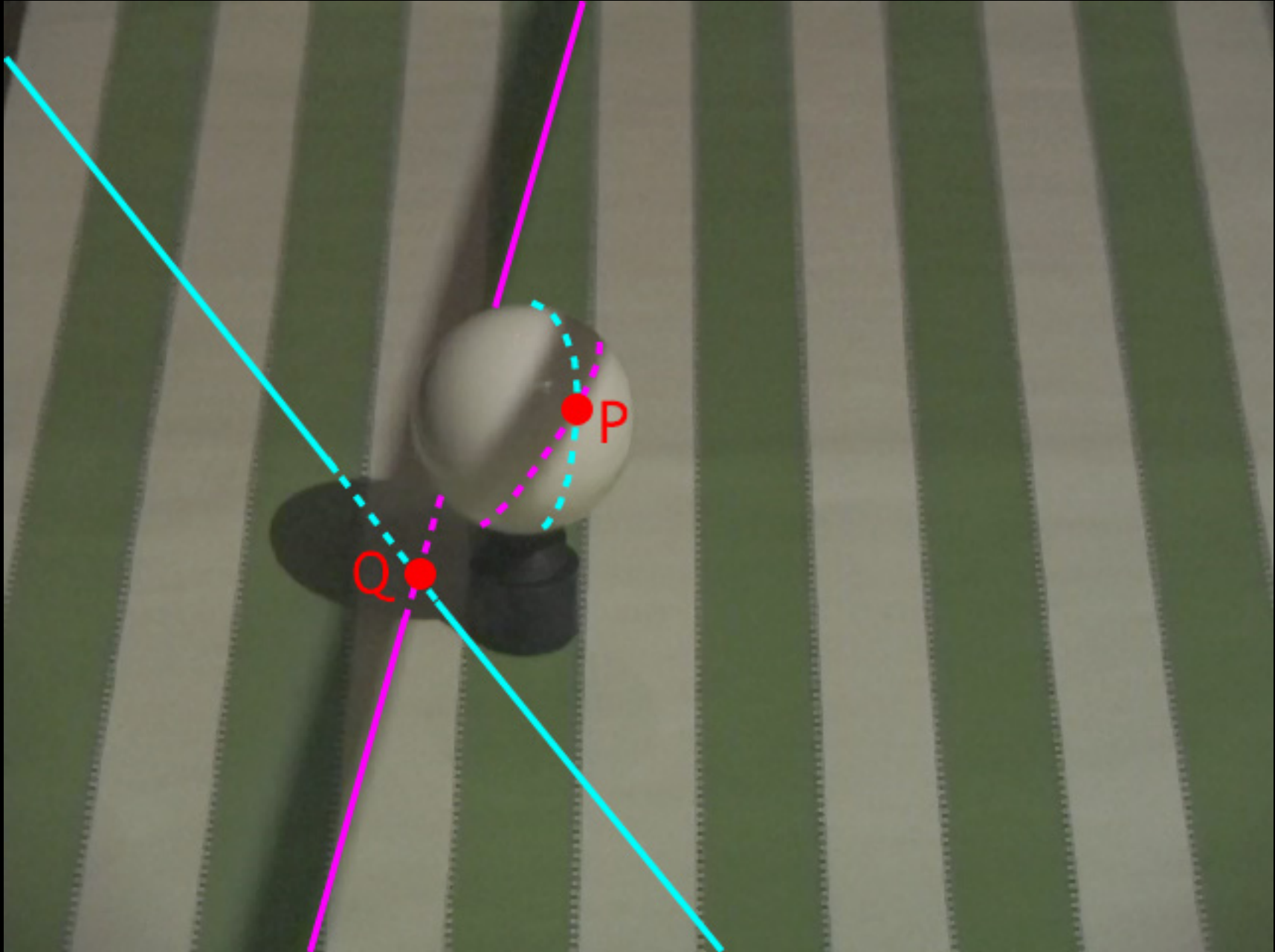


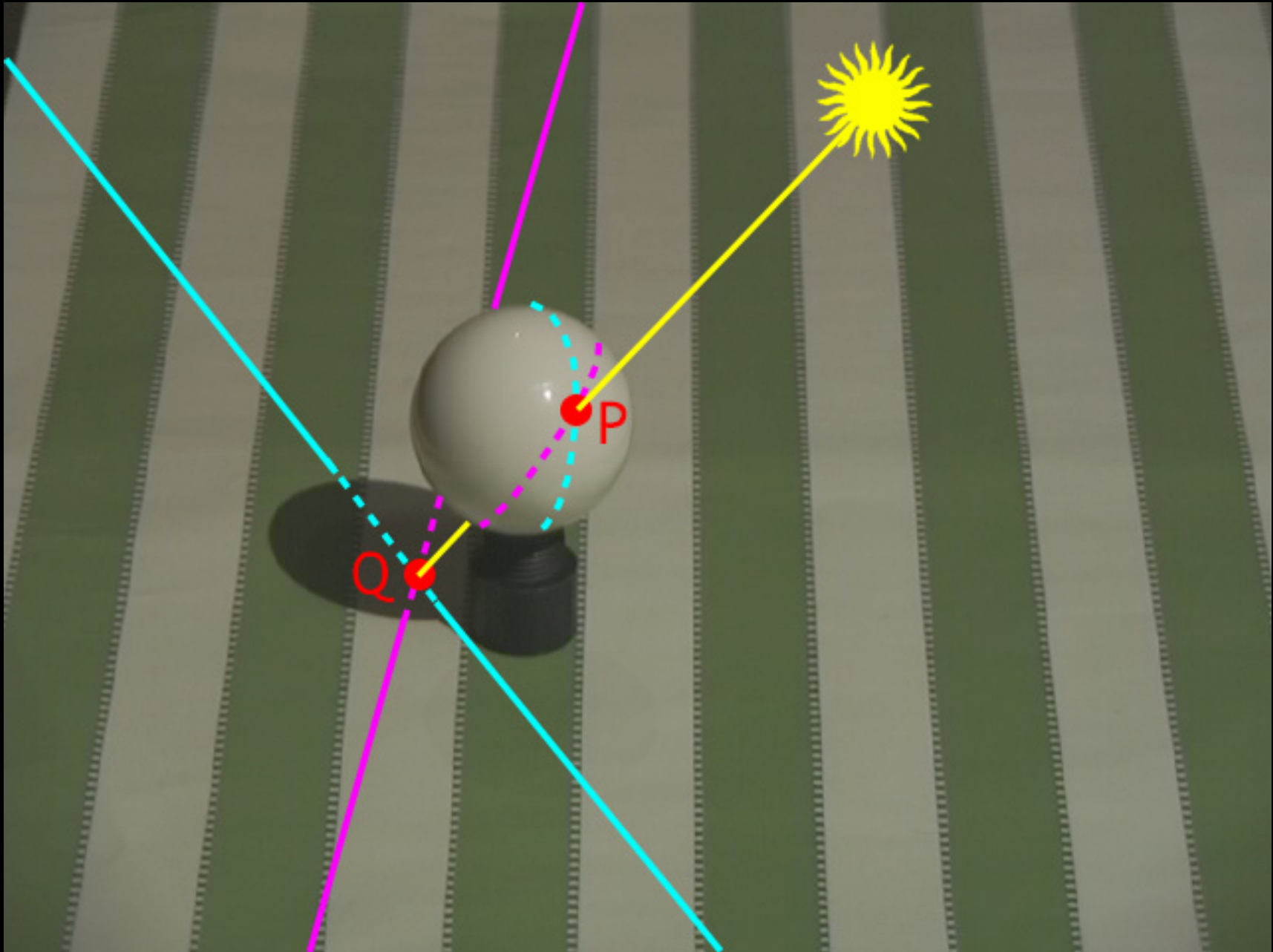


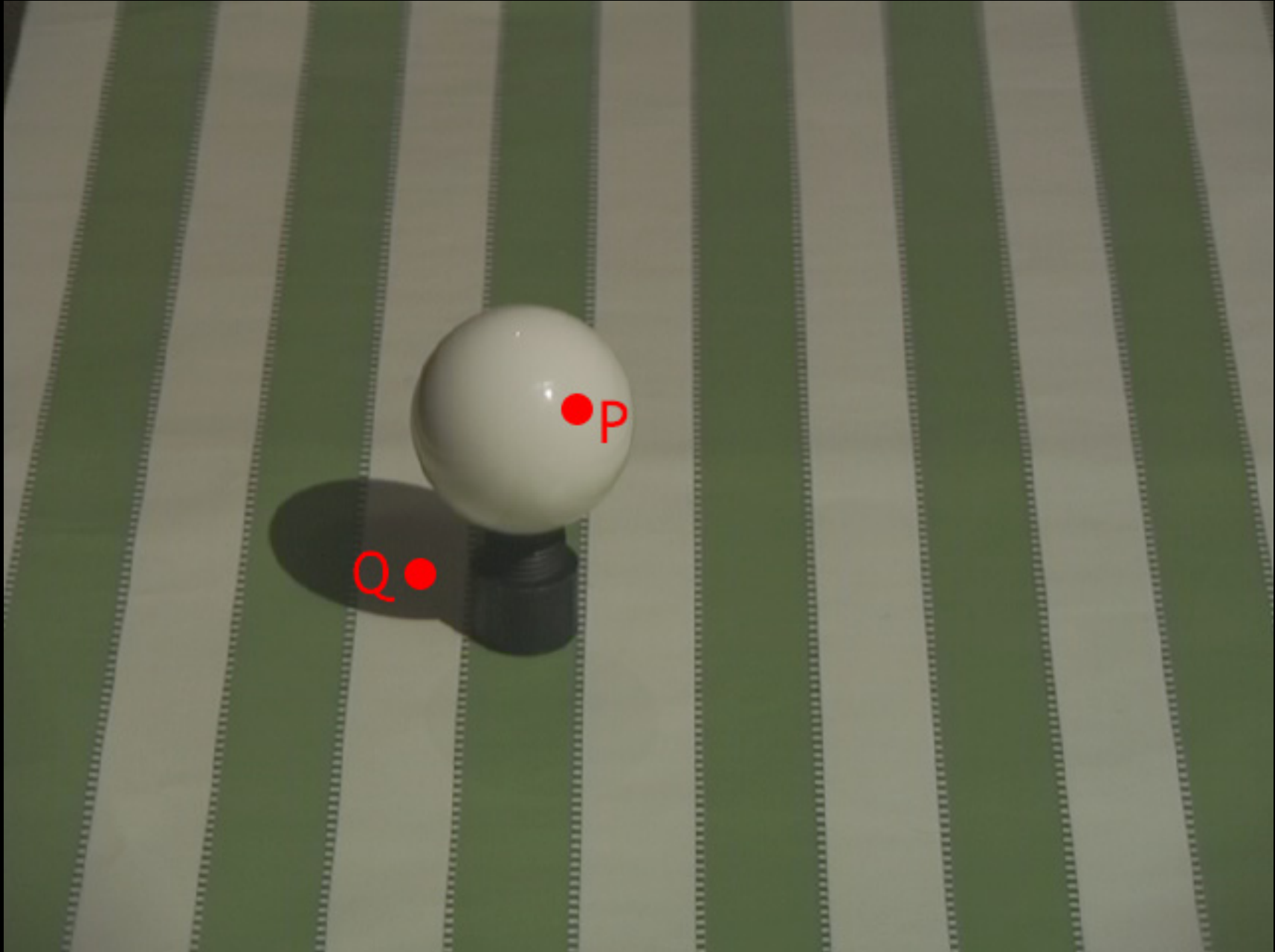


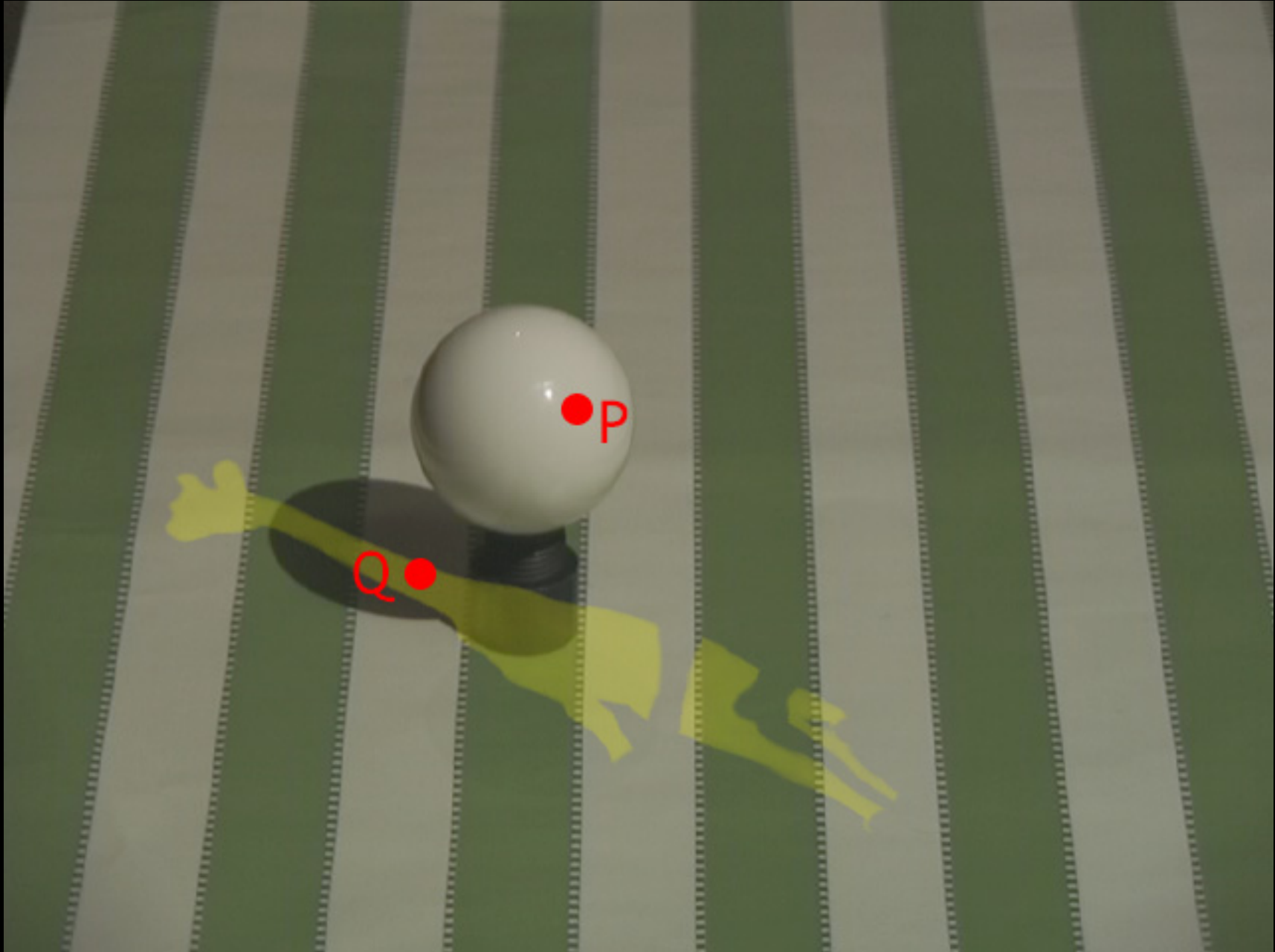


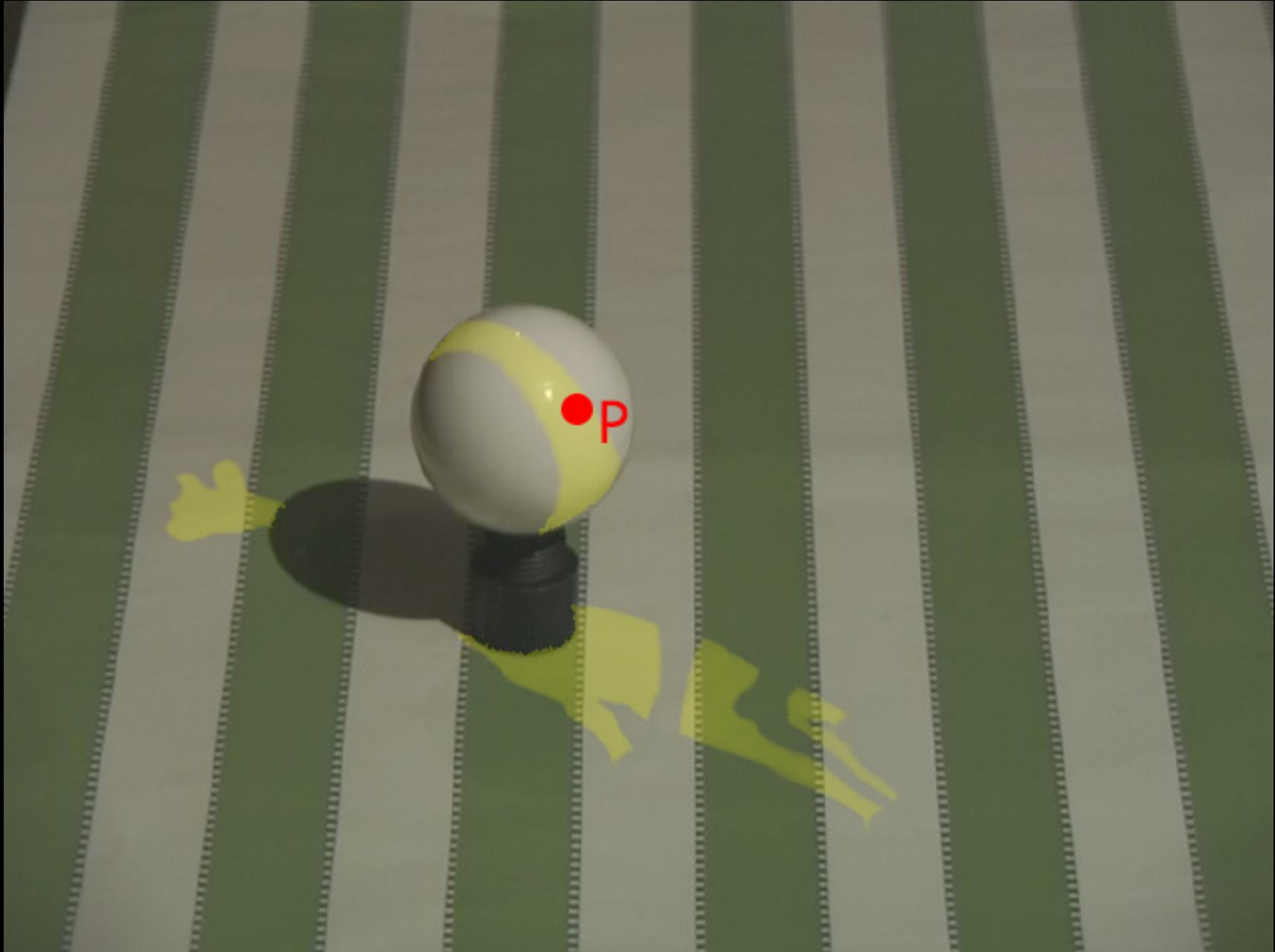
















96x3x1 stick

camera

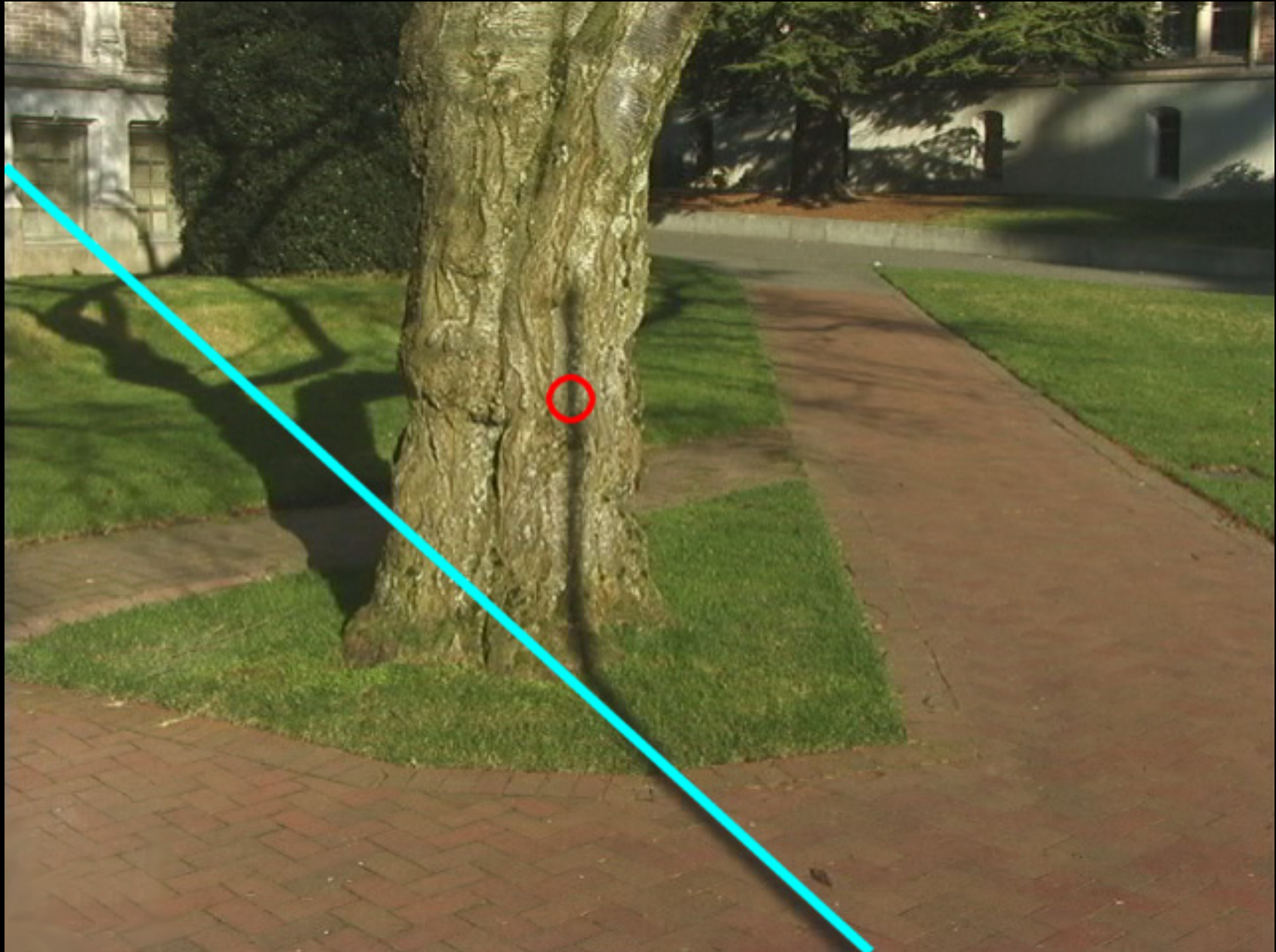
cast shadow



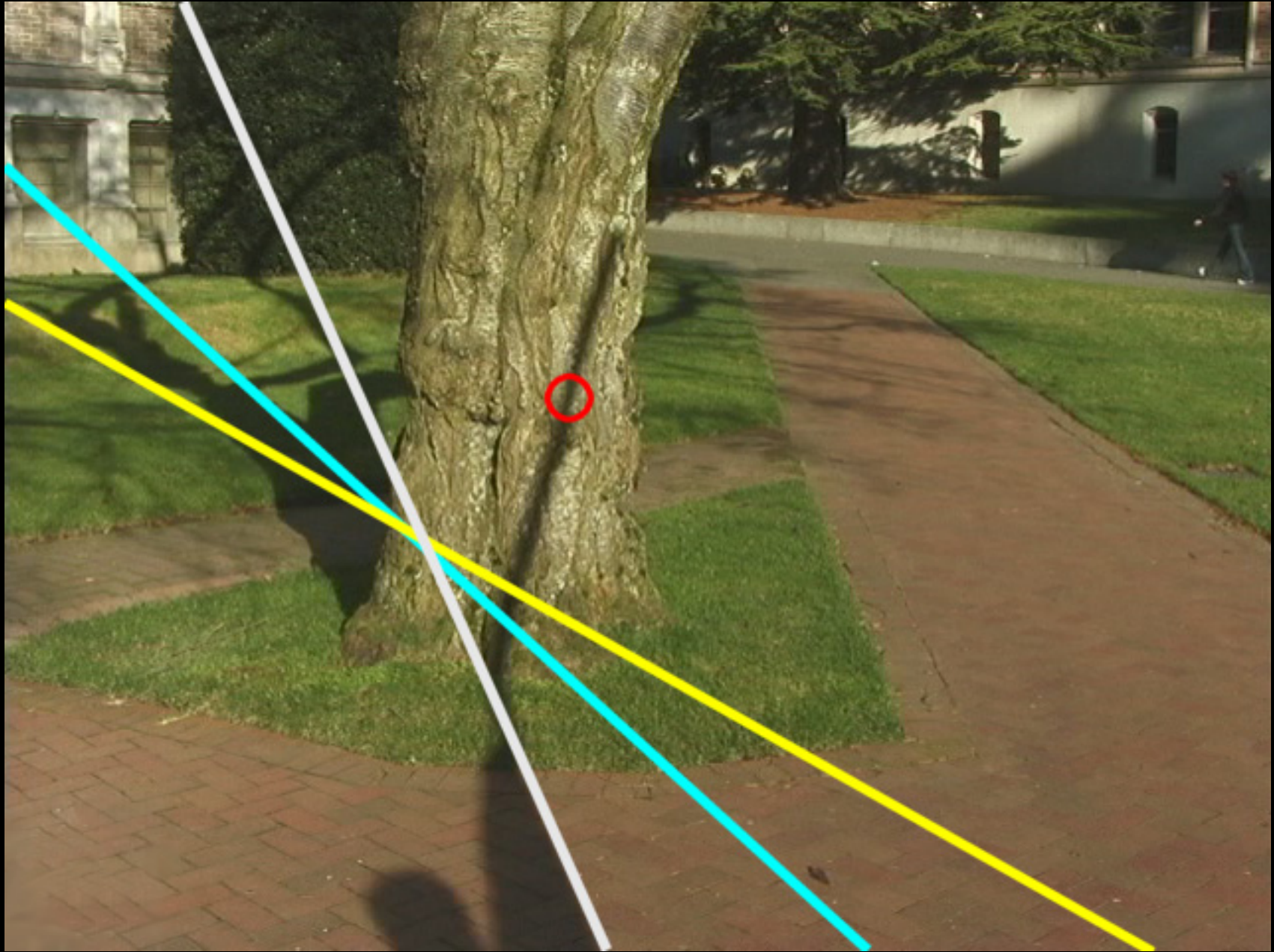




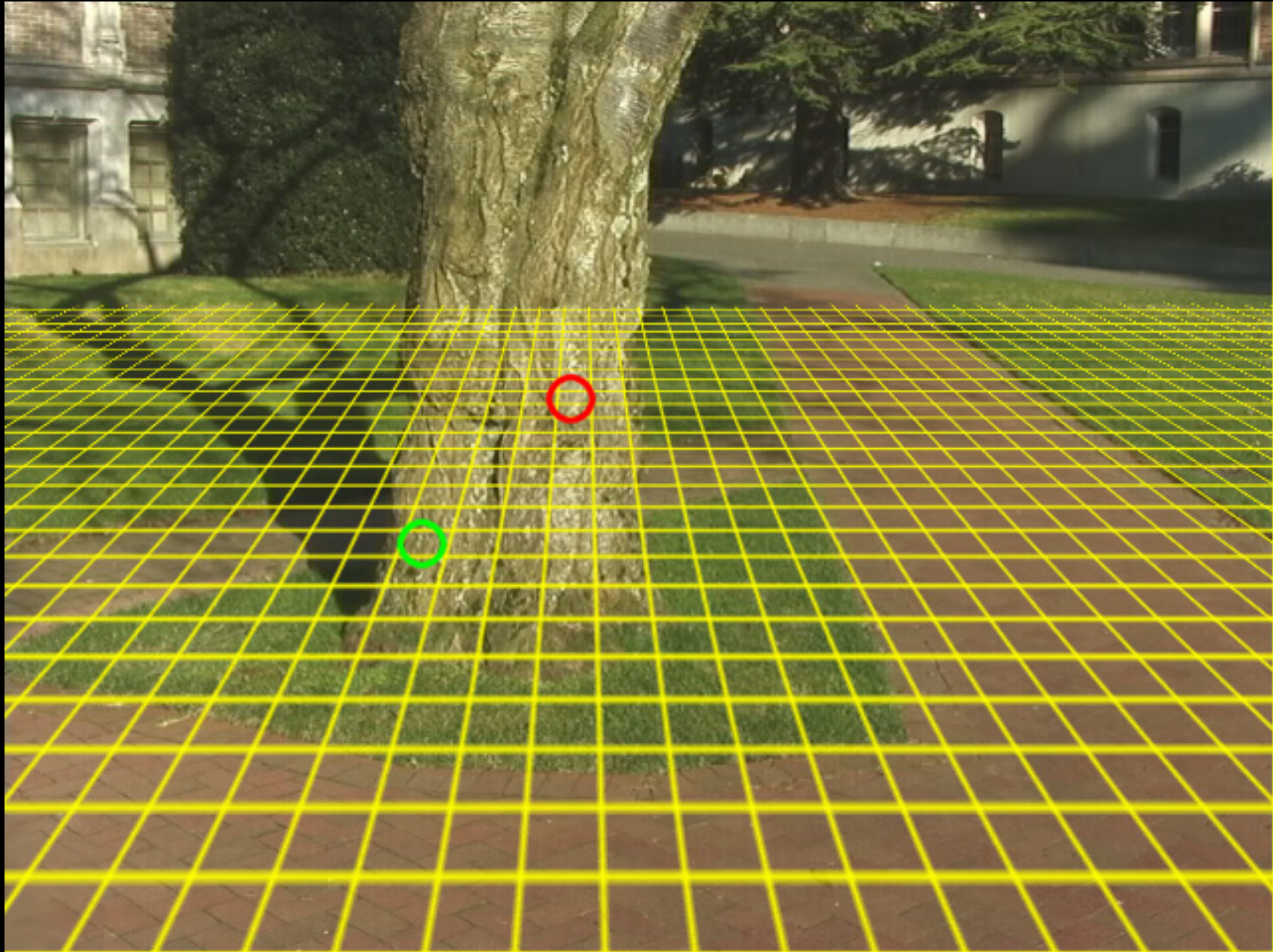


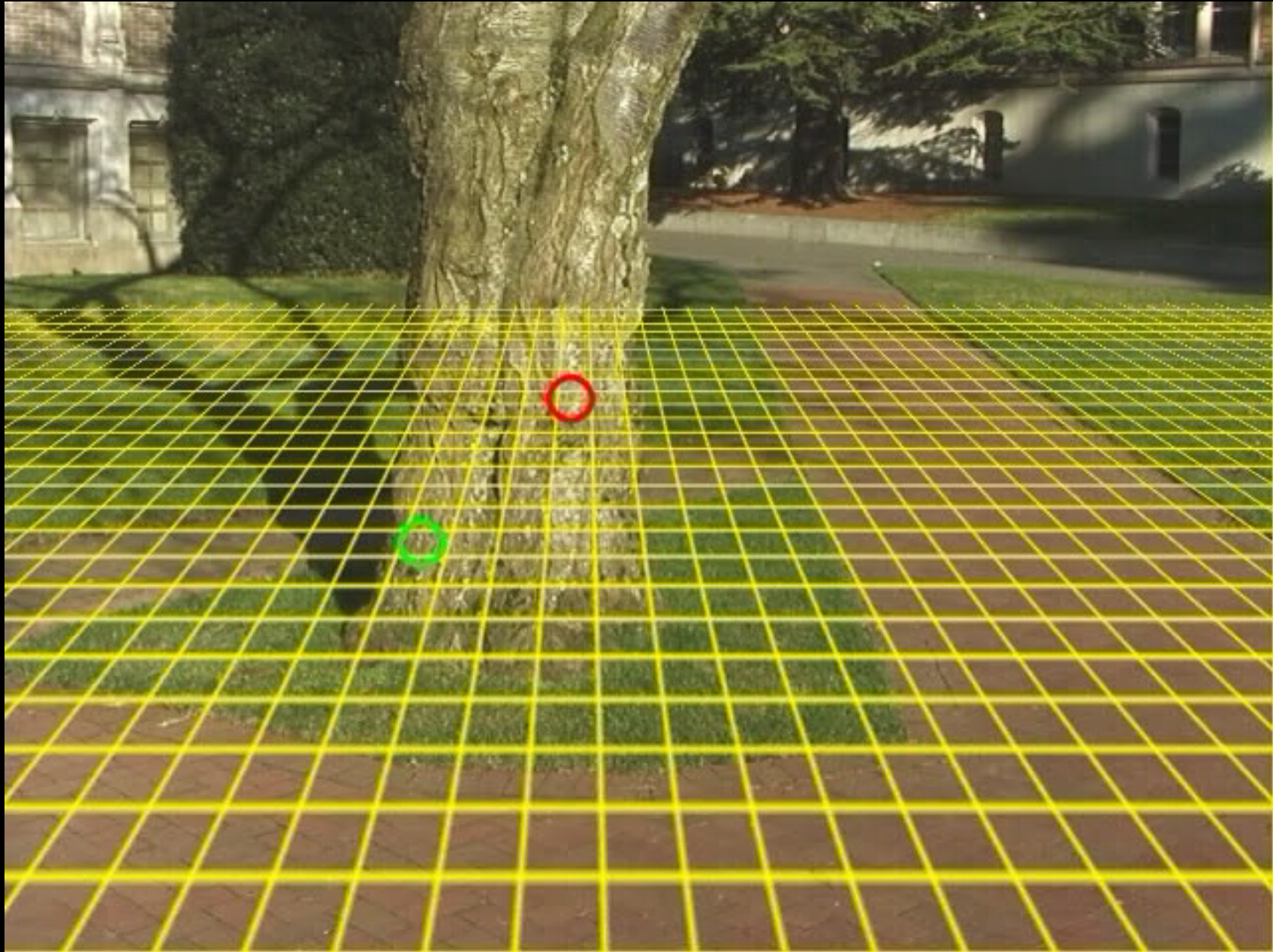


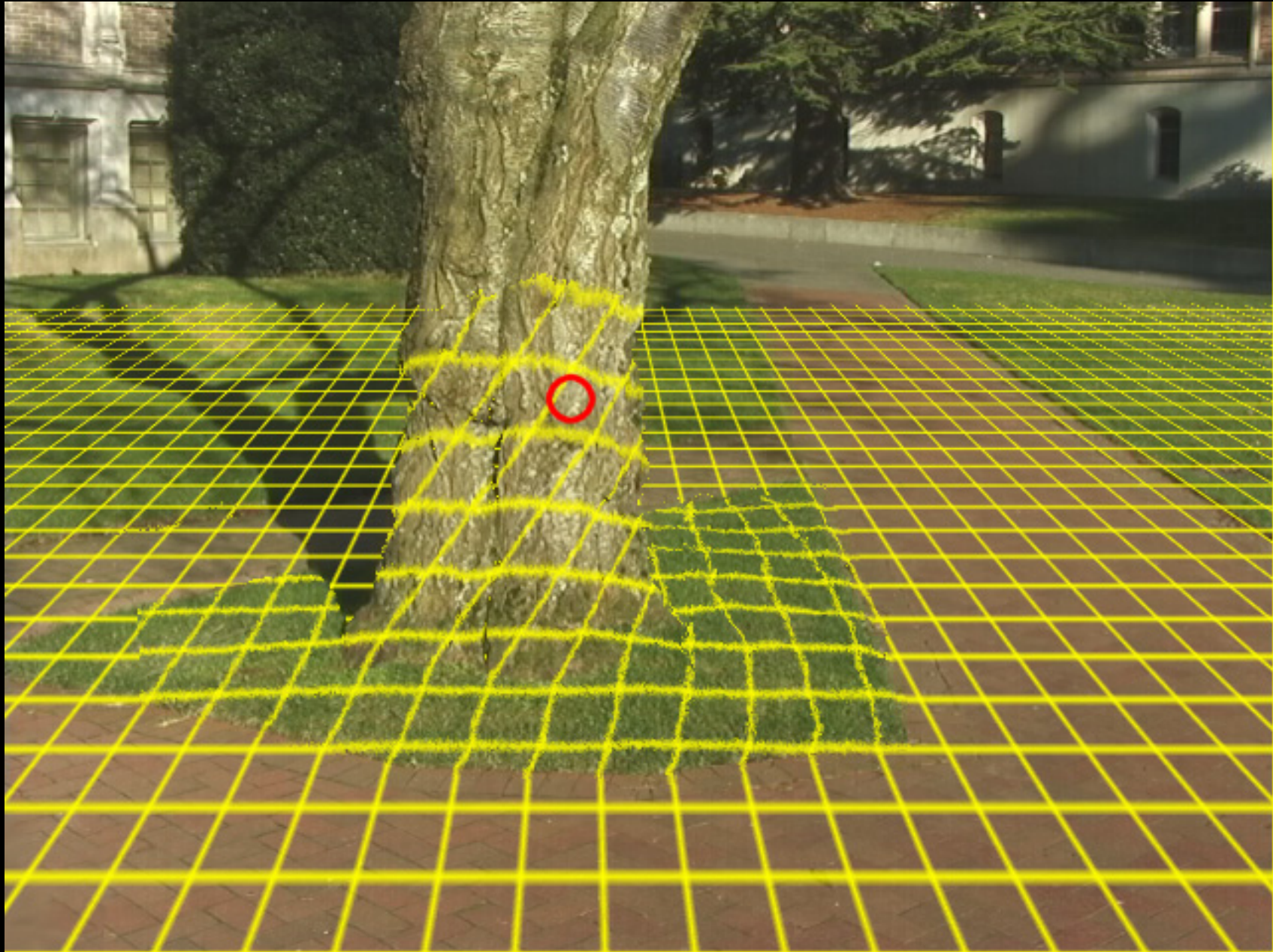




















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