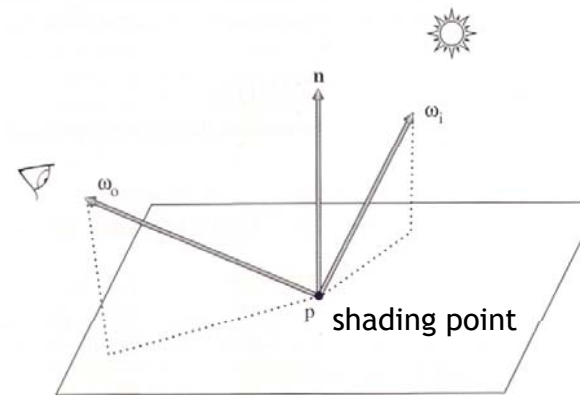


Reflection models

Digital Image Synthesis
Yung-Yu Chuang

with slides by Pat Hanrahan and Matt Pharr

Rendering equation



- shading model
- accuracy
 - expressiveness
 - speed

$$L(\omega_o) = \int_{\Omega} f(\omega_i \rightarrow \omega_o) L(\omega_i) \cos \theta_i d\omega_i$$

Taxonomy 1



$$(x, y, t, \theta, \phi, \lambda)_{in} \rightarrow (x, y, t, \theta, \phi, \lambda)_{out}$$

General function = 12D

- ↓ assume time doesn't matter (no phosphorescence)
- ↓ assume wavelengths are equal (no fluorescence)

Scattering function = 9D

- ↓ assume wavelength is discretized or integrated into RGB (This is a common assumption for computer graphics)

Single-wavelength Scattering function = 8D

$$(x, y, \theta, \phi)_{in} \rightarrow (x, y, \theta, \phi)_{out}$$

Taxonomy 2



$$(x, y, \theta, \phi)_{in} \rightarrow (x, y, \theta, \phi)_{out}$$

Single-wavelength Scattering function = 8D

ignore subsurface scattering (x,y)_{in} = (x,y)_{out}

ignore dependence on position

Bidirectional Texture Function (BTF)
Spatially-varying BRDF (SVBRDF) = 6D

Bidirectional Subsurface Scattering
Distribution Function (BSSRDF) = 6D

ignore direction of incident light

ignore dependence on position

ignore subsurface scattering

Light Fields, Surface LFs = 4D

BRDF = 4D

$$(x, y, \theta, \phi)_{out}$$

$$(\theta, \phi)_{in} \rightarrow (\theta, \phi)_{out}$$

assume Lambertian

assume isotropy

Texture Maps = 2D

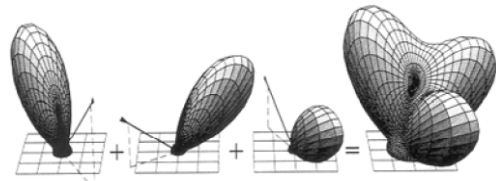
3D

$$(x, y)_{out}$$

Properties of BRDFs

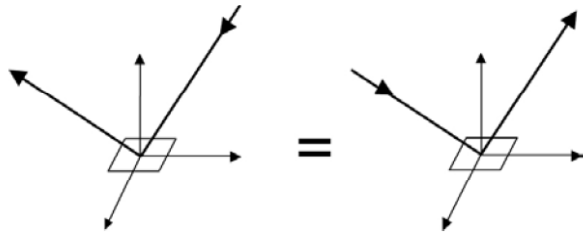


1. Linear



From Sillion, Arvo, Westin, Greenberg

2. Reciprocity principle $f_r(\omega_r \rightarrow \omega_i) = f_r(\omega_i \rightarrow \omega_r)$

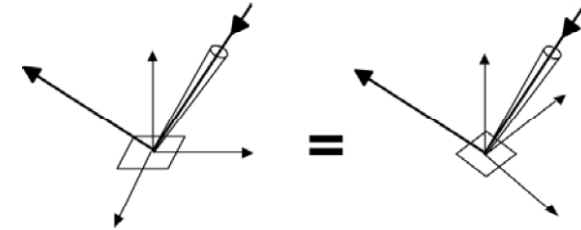


Properties of BRDFs



3. Isotropic vs. anisotropic

$$f_r(\theta_i, \varphi_i; \theta_r, \varphi_r) = f_r(\theta_i, \theta_r, \varphi_r - \varphi_i)$$

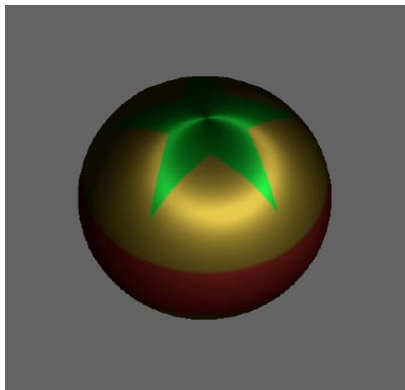


Reciprocity and isotropy

$$f_r(\theta_i, \theta_r, \varphi_r - \varphi_i) = f_r(\theta_r, \theta_i, \varphi_i - \varphi_r) = f_r(\theta_i, \theta_r, |\varphi_r - \varphi_i|)$$

4. Energy conservation $\int_{\Omega} f_r(\omega_o, \omega_i) \cos \theta_i d\omega_i \leq 1$

Isotropic and anisotropic

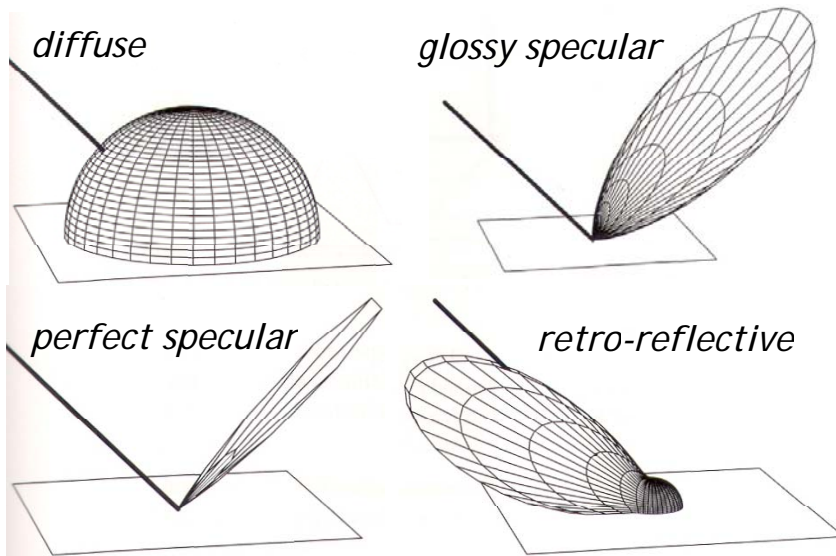


Surface reflection models

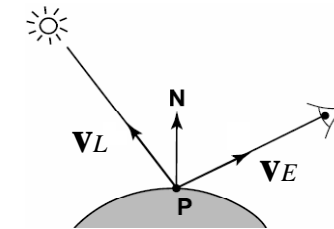


- Measured data: usually described in tabular form or coefficients of a set of basis functions
- Phenomenological models: *qualitative* approach; models with intuitive parameters
- Simulation: simulates light scattering from microgeometry and known reflectance properties
- Physical optics: solve Maxwell's equation
- Geometric optics: microfacet models

Reflection categories



Setup

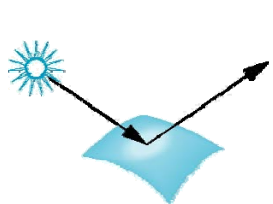


- Point **P** on a surface through a pixel **p**
- Normal **N** at **P**
- Lighting direction \mathbf{v}_L
- Viewing direction \mathbf{v}_E
- Compute color **L** for pixel **p**

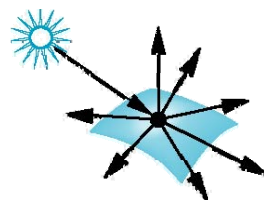
Surface types



- The smoother a surface, the more reflected light is concentrated in the direction a perfect mirror would reflected the light
- A very rough surface scatters light in all directions



smooth surface

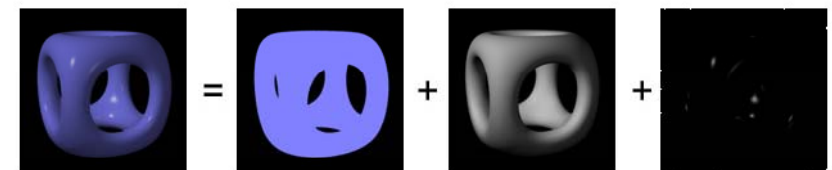


rough surface

Basics of local shading



- Diffuse reflection
 - light goes everywhere; colored by object color
- Specular reflection
 - happens only near mirror configuration; usually white
- Ambient reflection
 - constant accounted for other source of illumination



color and ambient

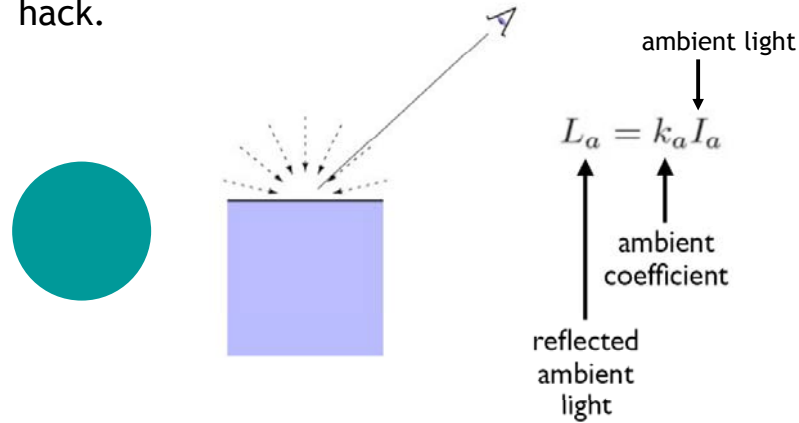
diffuse

specularity

Ambient shading



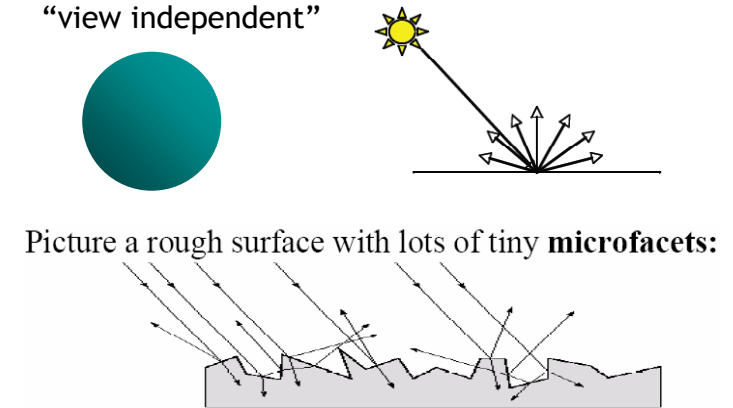
- add constant color to account for disregarded illumination and fill in black shadows; a cheap hack.



Diffuse shading



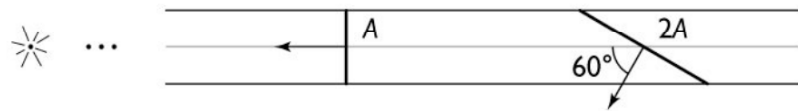
- Assume light reflects equally in all directions
 - Therefore surface looks same color from all views; “view independent”



Diffuse shading



- Illumination on an oblique surface is less than on a normal one (Lambertian cosine law)

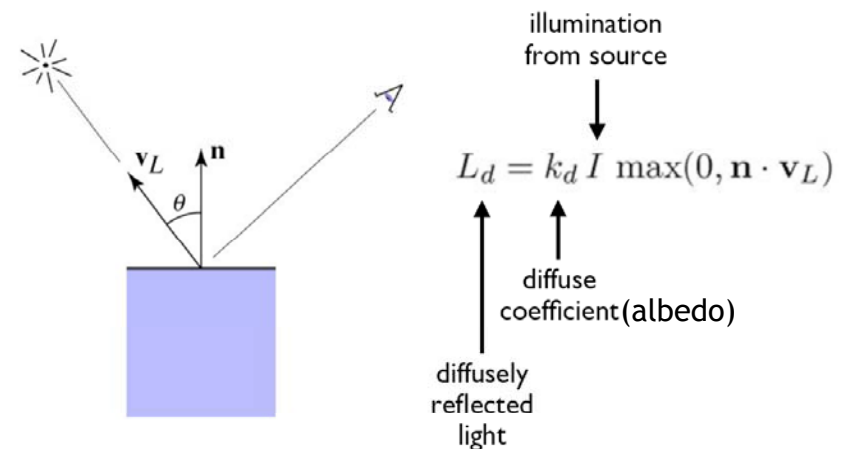


- Generally, illumination falls off as $\cos\theta$

Diffuse shading (Gouraud 1971)



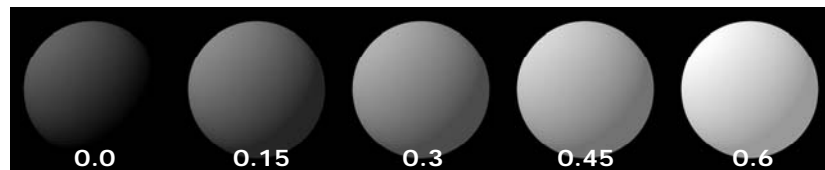
- Applies to *diffuse*, *Lambertian* or *matte* surfaces



Diffuse shading



diffuse-reflection model with different k_d



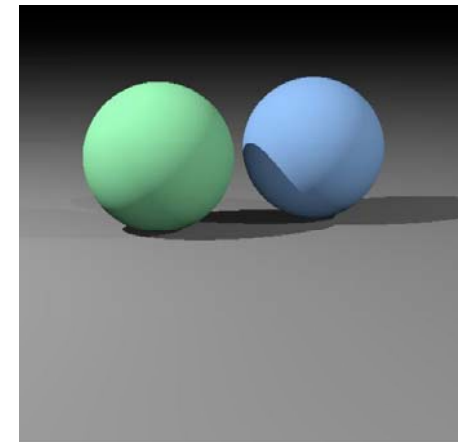
ambient and diffuse-reflection model with different k_a

and $I_a = I_p = 1.0, k_d = 0.4$

Diffuse shading



For color objects, apply the formula for each color channel separately



Specular shading



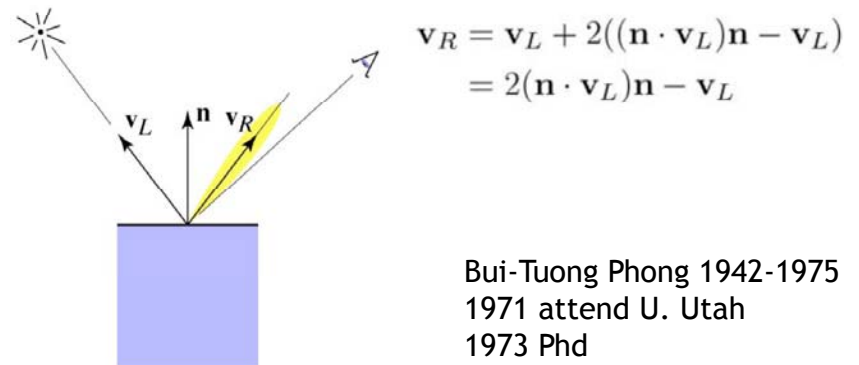
- Some surfaces have highlights, mirror like reflection; view direction dependent; especially for smooth shiny surfaces



Specular shading (Phong 1975)



- Also known as *glossy*, *rough specular* and *directional diffuse* reflection



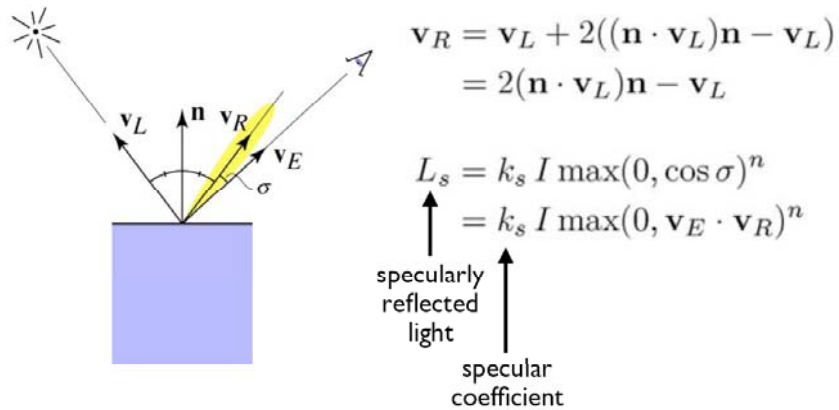
$$\begin{aligned} \mathbf{v}_R &= \mathbf{v}_L + 2((\mathbf{n} \cdot \mathbf{v}_L)\mathbf{n} - \mathbf{v}_L) \\ &= 2(\mathbf{n} \cdot \mathbf{v}_L)\mathbf{n} - \mathbf{v}_L \end{aligned}$$

Bui-Tuong Phong 1942-1975
1971 attend U. Utah
1973 Phd
1975 Stanford faculty

Specular shading



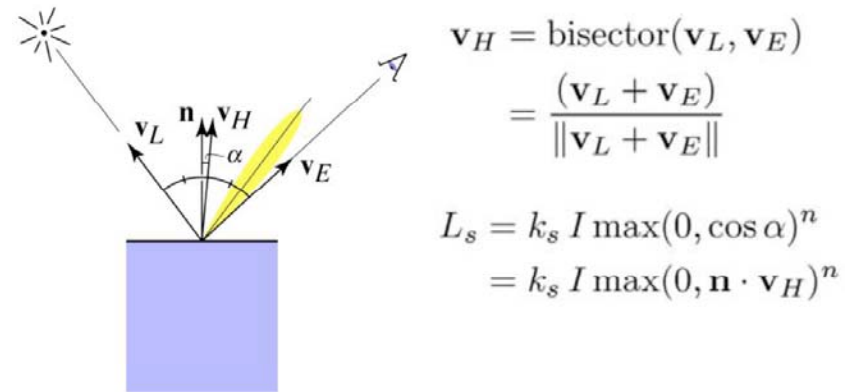
- Fall off gradually from the perfect reflection direction



Phong variant: Blinn-Phong



- Rather than computing reflection directly; just compare to normal bisection property.



Blinn-Phong



- One can prove that, for small σ

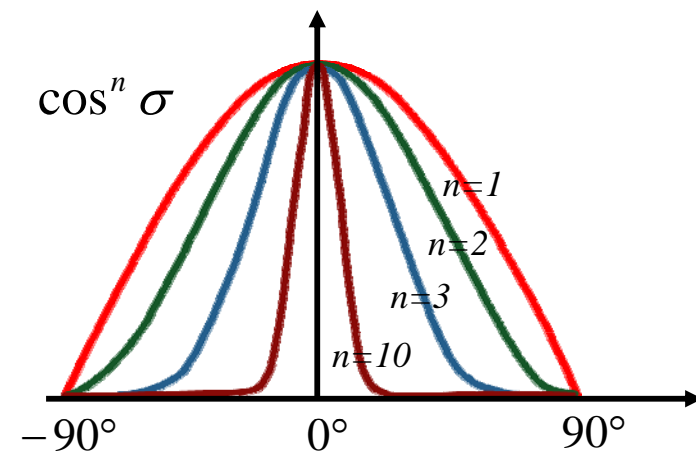
$$\cos^n \sigma = \cos^{4n} \alpha$$

- Blinn-Phong model is
 - Potentially faster (especially for directional light and orthographic projection)
 - More physically-based (closer to Torrance-Sparrow model than Phong model)

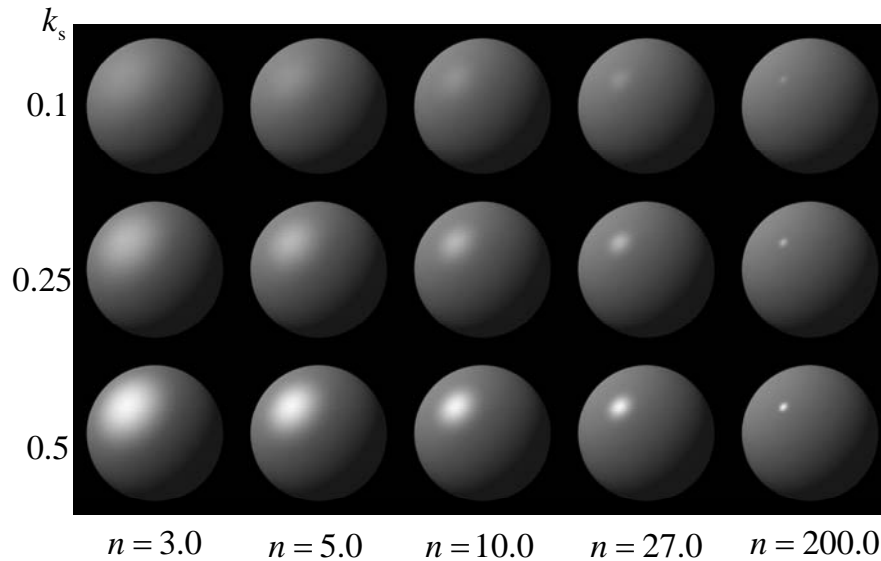
Specular shading



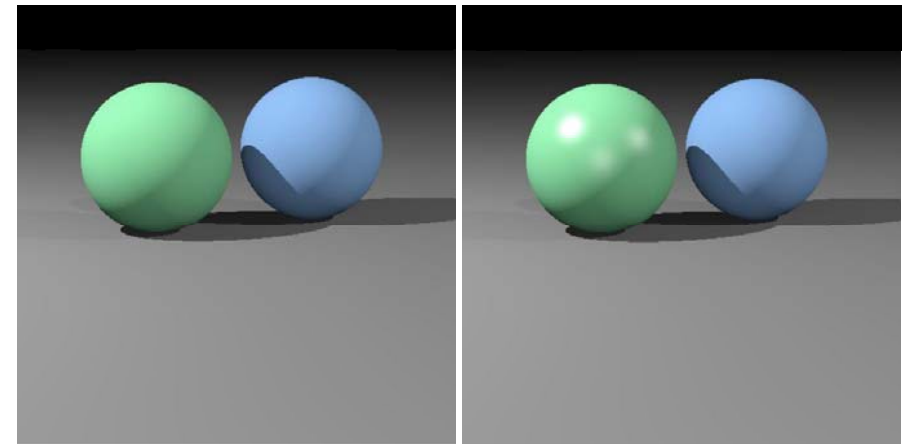
- Increasing n narrows the lobe



Specular shading



Specular shading



diffuse

diffuse + specular

Put it all together



- Include ambient, diffuse and specular

$$L = L_a + L_d + L_s$$
$$= k_a I_a + I (k_d \max(0, \mathbf{n} \cdot \mathbf{v}_L) + k_s \max(0, \mathbf{n} \cdot \mathbf{v}_H)^n)$$

- Sum over many lights

$$L = L_a + \sum_i (L_d)_i + (L_s)_i$$
$$= k_a I_a + \sum_i I_i (k_d \max(0, \mathbf{n} \cdot (\mathbf{v}_L)_i) + k_s \max(0, \mathbf{n} \cdot (\mathbf{v}_H)_i)^n)$$

[Knoll's class on local shading](#)

Reflection models

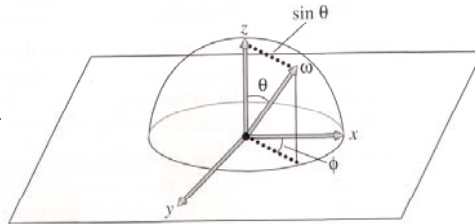
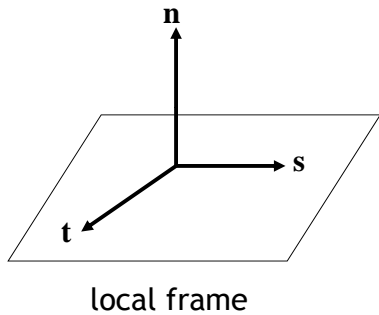


- BRDF/BTDF/BSDF
- Scattering from realistic surfaces is best described as a mixture of multiple BRDFs and BTDFs.
- **core/reflection.***
- Material = BSDF that combines multiple BRDFs and BTDFs. (chap. 9)
- Textures = reflection and transmission properties that vary over the surface. (chap. 10)

Geometric setting



incident and outgoing directions are normalized and outward facing after being transformed into the local frame



$$\cos \theta = \omega_z, \quad \sin \theta = \sqrt{1 - \omega_z^2}$$

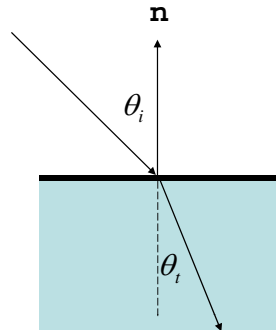
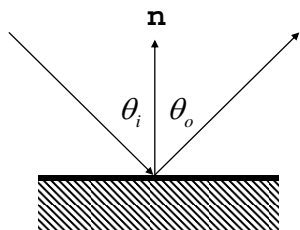
$$\cos \phi = \frac{\omega_x}{\sin \theta}, \quad \sin \phi = \frac{\omega_y}{\sin \theta}$$

Specular reflection and transmission



- Reflection: $\theta_i = \theta_o$
- Transmission: $\eta_i \sin \theta_i = \eta_t \sin \theta_t$ (Snell's law)

↑ index of refraction dispersion



Fresnel reflectance



- Reflectivity and transmissiveness: fraction of incoming light that is reflected or transmitted; they are usually **view dependent**. Hence, the reflectivity is not a constant and should be corrected by *Fresnel equation*

- *Fresnel reflectance* for dielectrics

$$r_{\parallel} = \frac{\eta_t \cos \theta_i - \eta_i \cos \theta_t}{\eta_t \cos \theta_i + \eta_i \cos \theta_t}$$

$$r_{\perp} = \frac{\eta_i \cos \theta_i - \eta_t \cos \theta_t}{\eta_i \cos \theta_i + \eta_t \cos \theta_t}$$

- Assume light is unpolarized

$$F_r(\omega_i) = \frac{1}{2} (r_{\parallel}^2 + r_{\perp}^2)$$

$$F_t(\omega_i) = (1 - F_r(\omega_i))$$

BxDF



- **BxDFType**
 - BSDF_REFLECTION, BSDF_TRANSMISSION
 - BSDF_DIFFUSE, BSDF_GLOSSY (retro-reflective), BSDF_SPECULAR
- Spectrum **f**(Vector &wo, Vector &wi)=0;
- Spectrum **Sample_f**(Vector &wo, Vector *wi, float u1, float u2, float *pdf);
used to find an incident direction for an outgoing direction; especially useful for reflection with a delta distribution
- Spectrum **rho**(Vector &wo, int nSamples, float *samples);
hemispherical-directional reflectance; computed analytically or by sampling $\rho_{hd}(\omega_o) = \int_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i| d\omega_i$
- Spectrum **rho**(int nSamples, float *samples1, float *sample2);
hemispherical-hemispherical reflectance $\rho_{hh} = \frac{1}{\pi} \int_{\Omega} \int_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i \cos \theta_o| d\omega_i d\omega_o$

Indices of refraction



medium	Index of refraction
Vaccum	1.0
Air at sea level	1.00029
Ice	1.31
Water (20°C)	1.333
Fused quartz	1.46
Glass	1.5-1.6
Sapphire	1.77
Diamond	2.42

Fresnel reflectance



- *Fresnel reflectance* for conductors (no transmission)

$$r_{\parallel}^2 = \frac{\overset{\text{index of refraction}}{\eta^2 + k^2} \cos^2 \theta_i - 2\eta \cos \theta_i + 1}{\overset{\text{absorption coefficient}}{\eta^2 + k^2} \cos^2 \theta_i + 2\eta \cos \theta_i + 1}$$

$$r_{\perp}^2 = \frac{(\eta^2 + k^2) - 2\eta \cos \theta_i + \cos^2 \theta_i}{(\eta^2 + k^2) + 2\eta \cos \theta_i + \cos^2 \theta_i}$$

$$F_r(\omega_i) = \frac{1}{2}(r_{\parallel}^2 + r_{\perp}^2)$$

η and k for a few conductors



Object	η	k
Gold	0.370	2.820
Silver	0.177	3.638
Copper	0.617	2.630
Steel	2.485	3.433

- However, for most conductors, these coefficients are unknown. Approximations are used to find plausible values for these quantities if reflectance at the normal incidence is known.

Fresnel class



```
class Fresnel {
public:
    virtual Spectrum Evaluate(float cosi) const = 0;
};
class FresnelConductor : public Fresnel {
public:
    FresnelConductor(Spectrum &e, Spectrum &k)
        : eta(e), k(k) {}
private:
    Spectrum eta, k;
};
class FresnelDielectric : public Fresnel {
public:
    FresnelDielectric(float ei, float et) {
        eta_i = ei; eta_t = et;
    }
private:
    float eta_i, eta_t;
};
```

Evaluate directly implements
Fresnel formula for conductor

Evaluate directly implements
Fresnel formula for dielectric

Specular reflection

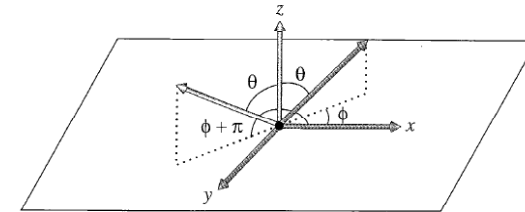


```
class SpecularReflection : public BxDF {
public:
    SpecularReflection(const Spectrum &r, Fresnel *f)
    : BxDF(BxDFType(BSDF_REFLECTION | BSDF_SPECULAR)),
      R(r), fresnel(f) { }
    Spectrum f(const Vector &, const Vector &) const {
        return Spectrum(0.);
    }
    Spectrum Sample_f(const Vector &wo, Vector *wi,
                      float u1, float u2, float *pdf) const;
    float Pdf(const Vector &wo, const Vector &wi) const {
        return 0.;
    }
private:
    Spectrum R;
    Fresnel *fresnel;
};
```

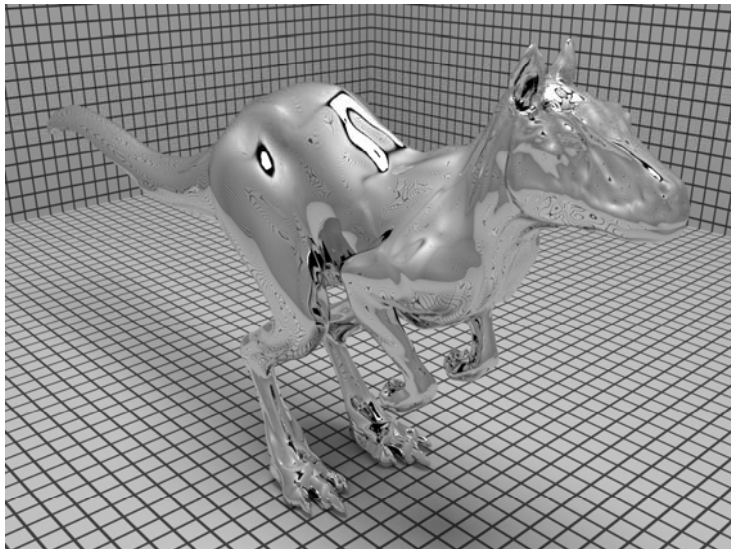
Specular reflection



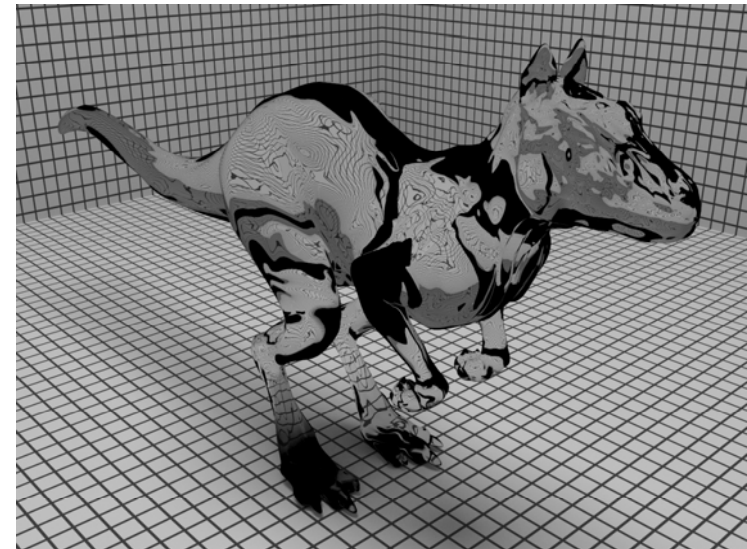
```
Spectrum SpecularReflection::Sample_f(Vector &wo,
Vector *wi, float u1, float u2, float *pdf) const{
    // Compute perfect specular reflection direction
    *wi = Vector(-wo.x, -wo.y, wo.z);
    *pdf = 1.f;
    return fresnel->Evaluate(CosTheta(wo)) * R /
        fabsf(CosTheta(*wi));
}
```



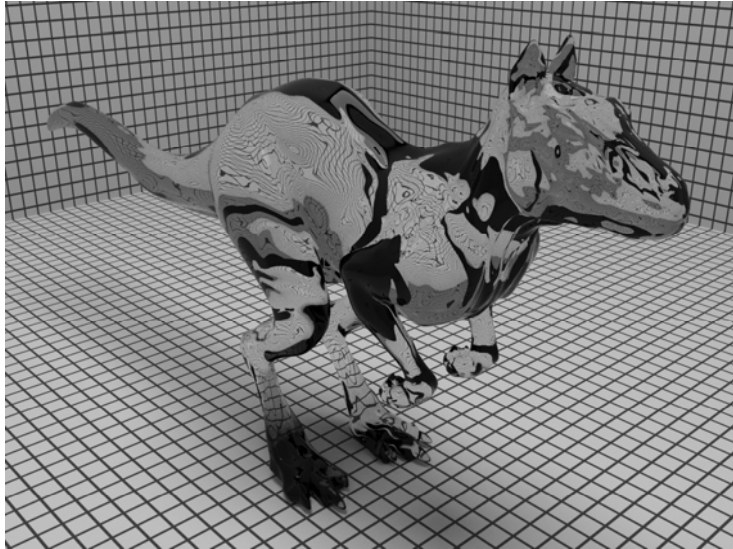
Perfect specular reflection



Perfect specular transmission



Fresnel modulation



Lambertian reflection



- It is not physically feasible, but provides a good approximation to many real-world surfaces.

```
class COREDLL Lambertian : public BxDF {
public:
    Lambertian(Spectrum &reflectance)
        : BxDF(BxDFType(BSDF_REFLECTION | BSDF_DIFFUSE)),
          R(reflectance), RoverPI(reflectance * INV_PI) {}
    Spectrum f(Vector &wo, Vector &wi) {return RoverPI;}
    Spectrum rho(Vector &, int, float *) { return R; }
    Spectrum rho(int, float *) { return R; }
private:
    Spectrum R, RoverPI;
};
```

Derivations



$$\rho_{hh} = \frac{1}{\pi} \iint_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i \cos \theta_o| d\omega_i d\omega_o$$

Derivations



$$\rho_{hh} = \frac{1}{\pi} \iint_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i \cos \theta_o| d\omega_i d\omega_o$$

$$R = \frac{1}{\pi} \iint_{\Omega} c |\cos \theta_i \cos \theta_o| d\omega_i d\omega_o$$

$$R = \frac{c}{\pi} \cdot \int_{\Omega} \cos \theta_i d\omega_i \cdot \int_{\Omega} \cos \theta_o d\omega_o = c\pi$$

$$c = \frac{R}{\pi}$$

$$\begin{aligned} \int_{\Omega} \cos \theta_i d\omega_i &= \int_0^{2\pi} \int_0^{\pi/2} \cos \theta_i \sin \theta_i d\theta_i d\phi_i \\ &= \int_0^{2\pi} d\phi_i \int_0^{\pi/2} \cos \theta_i \sin \theta_i d\theta_i \\ &= 2\pi \int_0^{\pi/2} \frac{1}{2} \sin(2\theta_i) d(2\theta_i) \\ &= \frac{\pi}{2} \cdot [-\cos(2\theta_i)]_0^{\pi/2} = \pi \end{aligned}$$

Derivations



$$\rho_{hd}(\omega_o) = \int_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i| d\omega_i$$

Derivations

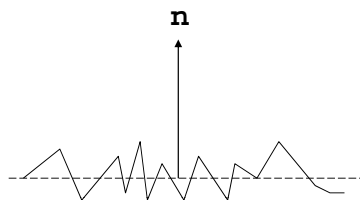


$$\begin{aligned} \rho_{hd}(\omega_o) &= \int_{\Omega} f_r(p, \omega_o, \omega_i) |\cos \theta_i| d\omega_i \\ &= \int_{\Omega} \frac{R}{\pi} \cos \theta_i d\omega_i \\ &= \frac{R}{\pi} \int_{\Omega} \cos \theta_i d\omega_i \\ &= \frac{R}{\pi} \cdot \pi = R \end{aligned}$$

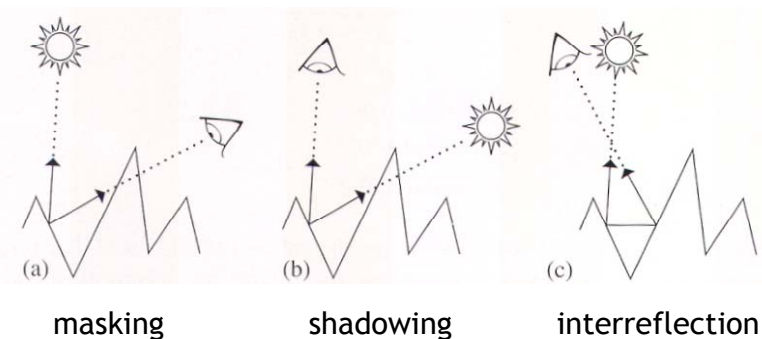
Microfacet models



- Rough surfaces can be modeled as a collection of small microfacets. Their **aggregate behavior** determines the scattering.
- Two components: distribution of microfacets and how light scatters from individual microfacet → closed-form BRDF expression



Important geometric effects to consider



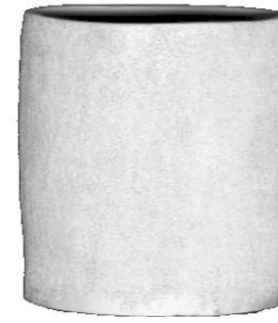
Most microfacet models assume that all microfacets make up symmetric V-shaped grooves so that only neighboring microfacet needs to be considered. Particular models consider these effects with varying degrees of accuracy.

Oren-Nayar model



- Many real-world materials such as concrete, sand and cloth are not real Lambertian. Specifically, rough surfaces generally appear brighter as the illumination direction approaches the viewing direction.
- A collection of symmetric V-shaped perfect **Lambertian** grooves whose orientation angles follow a **Gaussian distribution**.
- Don't have a closed-form solution, instead they used an approximation

Oren-Nayar model



(a) Real image



(b) Lambertian model

Oren-Nayar model



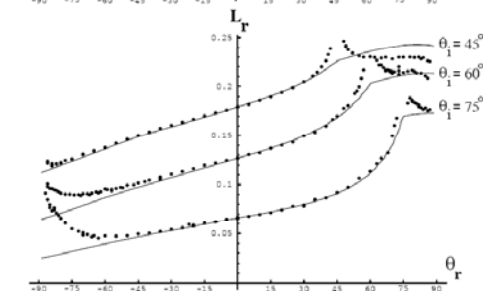
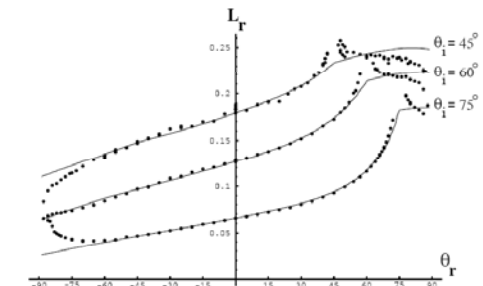
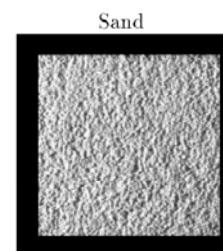
standard deviation for Gaussian

$$A = 1 - \frac{\sigma^2}{2(\sigma^2 + 0.33)}, \quad B = \frac{0.45\sigma^2}{\sigma^2 + 0.09}$$

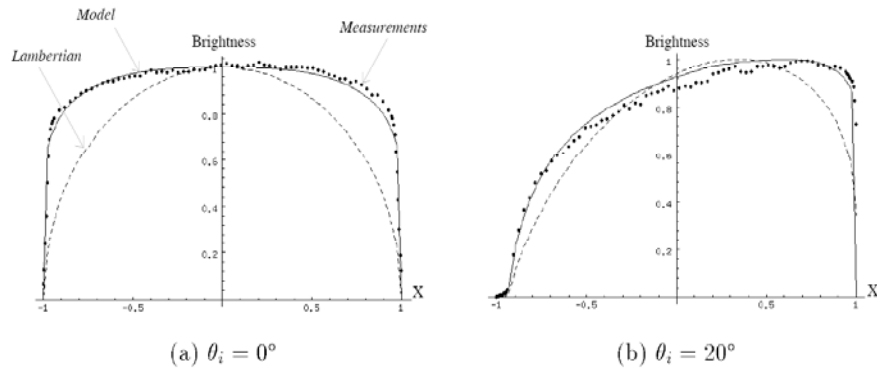
$$\alpha = \max(\theta_i, \theta_o), \quad \beta = \min(\theta_i, \theta_o)$$

$$f_r(\omega_i, \omega_o) = \frac{\rho}{\pi} (A + B \max(0, \cos(\phi_i - \phi_o))) \sin \alpha \tan \beta$$

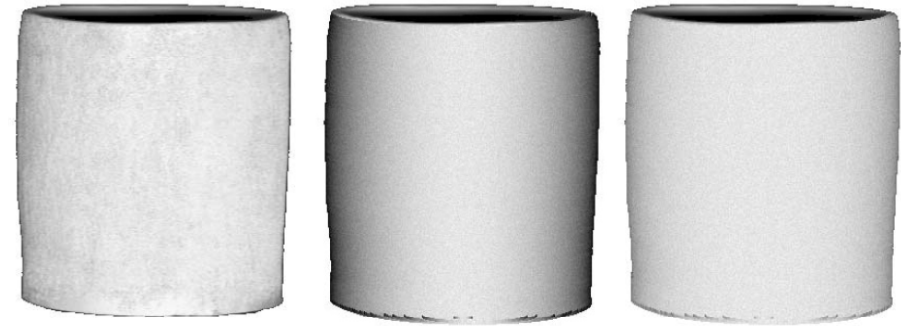
Oren-Nayar model



Oren-Nayar model



Oren-Nayar model



(a) Real image (b) Lambertian model (c) Proposed model

Oren-Nayar model



```
class OrenNayar : public BxDF {
public:
    Spectrum f(const Vector &wo, const Vector &wi) const;
    OrenNayar(const Spectrum &reflectance, float sig)
    : BxDF(BxDFType(BSDF_REFLECTION | BSDF_DIFFUSE)),
      R(reflectance) {
        float sigma = Radians(sig);
        float sigma2 = sigma*sigma;
        A = 1.f - (sigma2 / (2.f * (sigma2 + 0.33f)));
        B = 0.45f * sigma2 / (sigma2 + 0.09f);
    }
private:
    Spectrum R;
    float A, B;
};
```

Oren-Nayar model



standard deviation for Gaussian

$$A = 1 - \frac{\sigma^2}{2(\sigma^2 + 0.33)}, \quad B = \frac{0.45\sigma^2}{\sigma^2 + 0.09}$$

$$\alpha = \max(\theta_i, \theta_o), \quad \beta = \min(\theta_i, \theta_o)$$

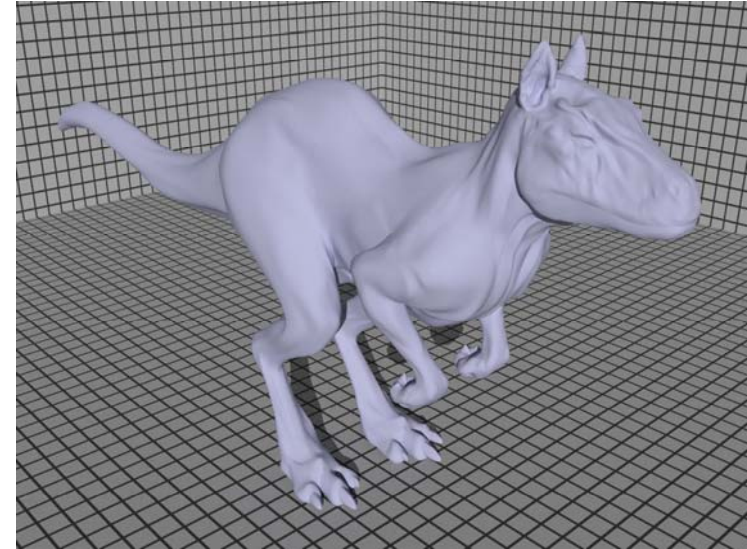
$$f_r(\omega_i, \omega_o) = \frac{\rho}{\pi} (A + B \max(0, \cos(\phi_i - \phi_o))) \sin \alpha \tan \beta$$

Oren-Nayar model

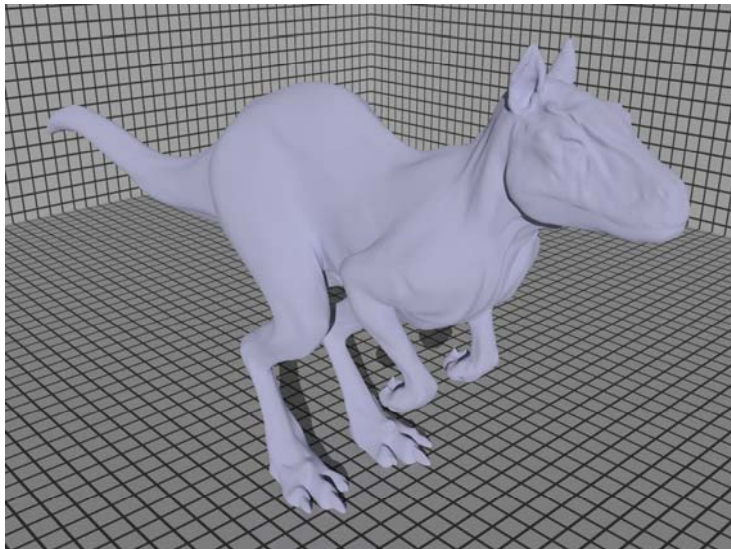


```
Spectrum OrenNayar::f(Vector &wo, Vector &wi)vconst{
    float sinthetai = SinTheta(wi);
    float sinthetao = SinTheta(wo);
    float sinphii = SinPhi(wi), cosphii = CosPhi(wi);
    float sinphio = SinPhi(wo), cosphio = CosPhi(wo);
    float dcos = cosphii * cosphio + sinphii * sinphio;
    float maxcos = max(0.f, dcos);
    float sinalpha, tanbeta;
    if (fabsf(CosTheta(wi)) > fabsf(CosTheta(wo))) {
        sinalpha = sinthetao;
        tanbeta = sinthetai / fabsf(CosTheta(wi));
    } else {
        sinalpha = sinthetai;
        tanbeta = sinthetao / fabsf(CosTheta(wo));
    }
    return R * INV_PI *
        (A + B * maxcos * sinalpha * tanbeta);
}
```

Lambertian



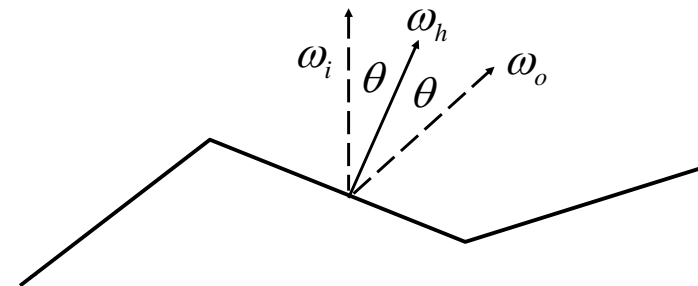
Oren-Nayar model



Torrance-Sparrow model



- One of the first microfacet models, designed to model metallic surfaces
- A collection of perfectly smooth mirrored microfacets with distribution $D(\omega_h)$

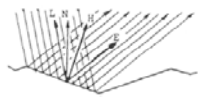


Torrance-Sparrow model

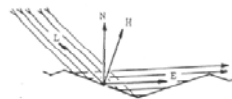


- Microfacet distribution D
- Fresnel reflection F
- Geometric attenuation G

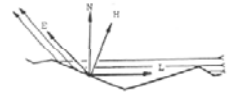
$$f_r(\omega_i \omega_o) = \frac{D(\omega_h) G(\omega_i, \omega_o) F(\omega_i, \omega_h)}{4 \cos \theta_i \cos \theta_o}$$



$$G = 1$$

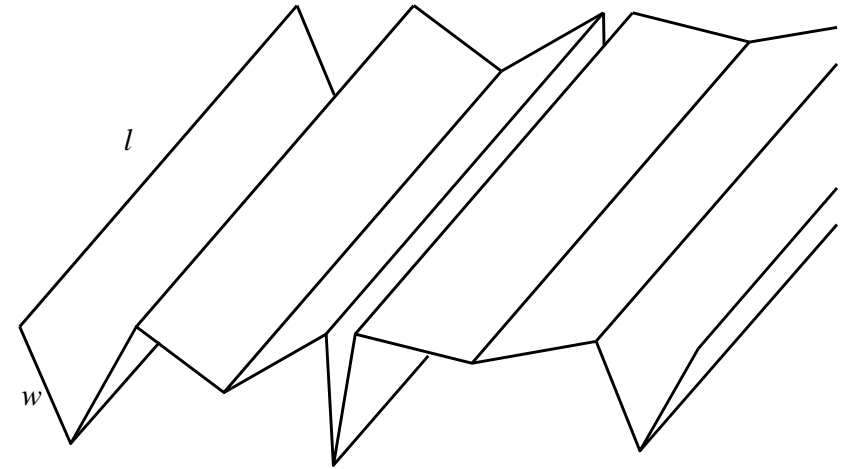


$$G = \frac{2(N \cdot H)(N \cdot \omega_i)}{(H \cdot \omega_i)}$$



$$G = \frac{2(N \cdot H)(N \cdot \omega_o)}{(H \cdot \omega_o)}$$

Configuration

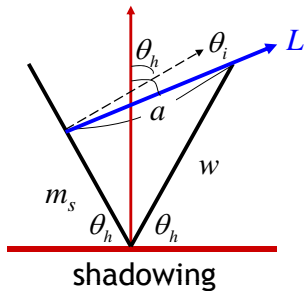


Geometry attenuation factor



$$G = \frac{\text{facet area that is both visible and illuminated}}{\text{total facet area}}$$

$$= \frac{1 \cdot \min(w - m_s, w - m_v)}{1 \cdot w} = \min\left(1 - \frac{m_s}{w}, 1 - \frac{m_v}{w}\right)$$



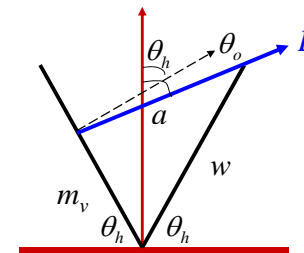
$$a \sin \theta_i = w \cos \theta_h + m_s \cos \theta_h \times \cos \theta_i$$

$$a \cos \theta_i = w \sin \theta_h - m_s \sin \theta_h \times \sin \theta_i$$

$$\frac{m_s}{w} = -\frac{\cos(\theta_h + \theta_i)}{\cos(\theta_h - \theta_i)}$$

$$1 - \frac{m_s}{w} = \frac{2 \cos \theta_h \cos \theta_i}{\cos(\theta_h - \theta_i)}$$

Geometry attenuation factor



$$1 - \frac{m_v}{w} = \frac{2 \cos \theta_h \cos \theta_o}{\cos(\theta_h - \theta_o)}$$

$$G = \min\left(1 - \frac{m_s}{w}, 1 - \frac{m_v}{w}\right) = \min\left(\frac{2 \cos \theta_h \cos \theta_i}{\cos(\theta_h - \theta_i)}, \frac{2 \cos \theta_h \cos \theta_o}{\cos(\theta_h - \theta_o)}\right)$$

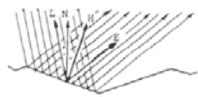
$$G(\omega_o, \omega_i) = \min\left(1, \min\left(\frac{2(n \cdot \omega_h)(n \cdot \omega_i)}{\omega_i \cdot \omega_h}, \frac{2(n \cdot \omega_h)(n \cdot \omega_o)}{\omega_o \cdot \omega_h}\right)\right)$$

Torrance-Sparrow model

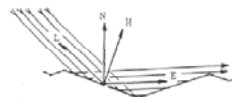


- Microfacet distribution D
- Fresnel reflection F
- Geometric attenuation G

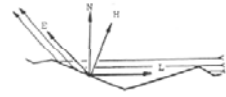
$$f_r(\omega_i \omega_o) = \frac{D(\omega_h) G(\omega_i, \omega_o) F(\omega_i, \omega_h)}{4 \cos \theta_i \cos \theta_o}$$



$$G = 1$$



$$G = \frac{2(N \cdot H)(N \cdot \omega_i)}{(H \cdot \omega_i)}$$



$$G = \frac{2(N \cdot H)(N \cdot \omega_o)}{(H \cdot \omega_o)}$$

Microfacet model



```
class MicrofacetDistribution {
public:
    virtual ~MicrofacetDistribution() { }
    virtual float D(const Vector &wh) const=0;
    virtual void Sample_f(const Vector &wo,
        Vector *wi, float u1, float u2,
        float *pdf) const = 0;
    virtual float Pdf(const Vector &wo,
        const Vector &wi) const = 0;
};
```

Microfacet model



```
class Microfacet : public BxDF {
public:
    Microfacet(const Spectrum &reflectance, Fresnel *f,
        MicrofacetDistribution *d);
    Spectrum f(const Vector &wo, const Vector &wi) const;
    float G(Vector &wo, Vector &wi, Vector &wh) const {
        float NdotWh = fabsf(CosTheta(wh));
        float NdotWo = fabsf(CosTheta(wo));
        float NdotWi = fabsf(CosTheta(wi));
        float WodotWh = AbsDot(wo, wh);
        return min(1.f, min((2.f*NdotWh*NdotWo/WodotWh),
            (2.f*NdotWh*NdotWi/WodotWh)));
    }
    ...
private:
    Spectrum R;    Fresnel *fresnel;
    MicrofacetDistribution *distribution;
};
```

Microfacet model

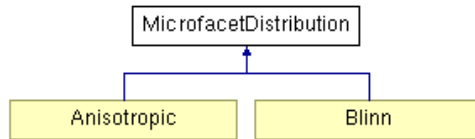


```
Spectrum Microfacet::f(Vector &wo, Vector &wi)
{
    float cosThetaO = fabsf(CosTheta(wo));
    float cosThetaI = fabsf(CosTheta(wi));
    if (cosThetaI == 0.f || cosThetaO == 0.f)
        return Spectrum(0.f);
    Vector wh = wi + wo;
    if (wh.x == 0. && wh.y == 0. && wh.z == 0.)
        return Spectrum(0.f);
    wh = Normalize(wh);
    float cosThetaH = Dot(wi, wh);
    Spectrum F = fresnel->Evaluate(cosThetaH);
    return R * distribution->D(wh) * G(wo, wi, wh) * F
        / (4.f * cosThetaI * cosThetaO);
}
```

Microfacet models



- Blinn
- Anisotropic



Blinn microfacet distribution



- Distribution of microfacet normals is modeled by an exponential falloff

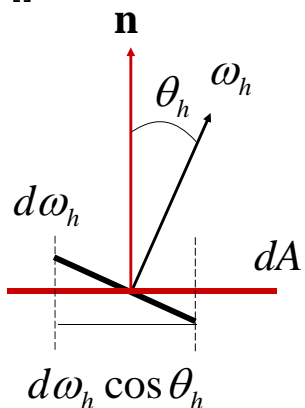
$$D(\omega_h) \propto (\omega_h \cdot \mathbf{n})^e = (\cos \theta_h)^e$$
- For smooth surfaces, this falloff happens very quickly; for rough surfaces, it is more gradual.
- Microfacet distribution must be normalized to ensure that they are physically plausible. The projected area of all microfacet faces over some area dA , the sum should be dA .

$$\int_{\Omega} D(\omega_h) \cos \theta_h d\omega_h = 1$$

Blinn microfacet distribution



$$\int_{\Omega} D(\omega_h) \cos \theta_h d\omega_h = 1 \quad \int_{\Omega} c(\omega_h \cdot \mathbf{n})^e \cos \theta_h d\omega_h = 1$$



Blinn microfacet distribution



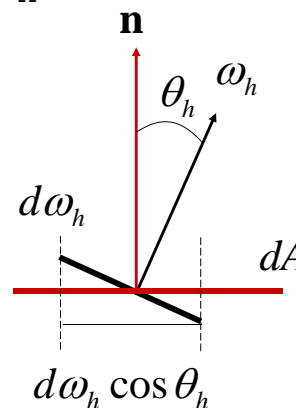
$$\int_{\Omega} D(\omega_h) \cos \theta_h d\omega_h = 1 \quad \int_{\Omega} c(\omega_h \cdot \mathbf{n})^e \cos \theta_h d\omega_h = 1$$

$$\int_0^{2\pi} \int_0^{\frac{\pi}{2}} c(\cos \theta_h)^{e+1} \sin \theta_h d\theta_h d\phi_h = 1$$

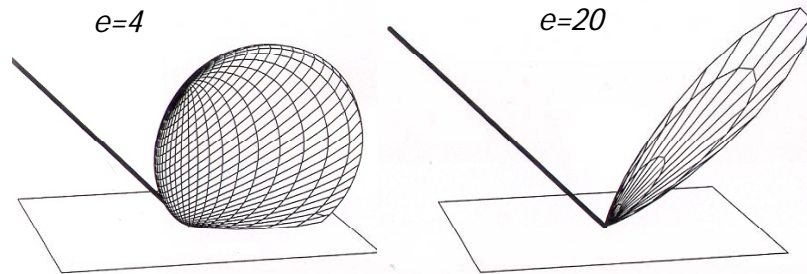
$$2\pi c \int_0^{\frac{\pi}{2}} (\cos \theta_h)^{e+1} (-d \cos \theta_h) = 1$$

$$-2\pi c \frac{(\cos \theta_h)^{e+2}}{e+2} \Big|_{\cos \theta_h=1}^{\cos \theta_h=0} = 1$$

$$c = \frac{e+2}{2\pi} \quad D(\omega_h) = \frac{e+2}{2\pi} (\omega_h \cdot \mathbf{n})^e$$

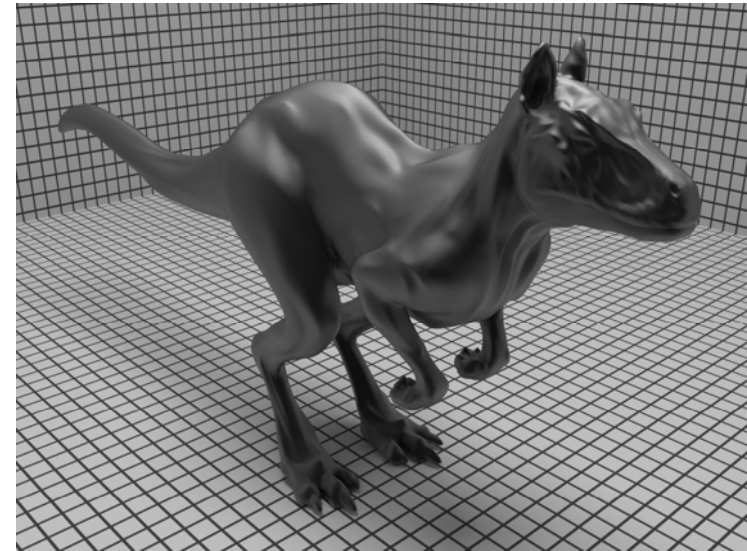


Blinn microfacet distribution



```
class Blinn : public MicrofacetDistribution
{
    ...
    float Blinn::D(const Vector &wh) const {
        float costhetah = fabsf(CosTheta(wh));
        return (exponent+2) * INV_TWOPI *
            powf(max(0.f, costhetah), exponent);
    }
}
```

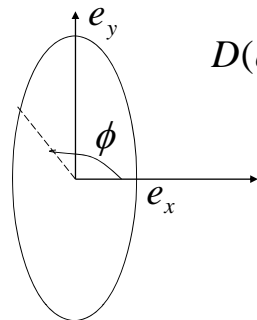
Torrance-Sparrow with Blinn distribution



Anisotropic microfacet model



- Blinn microfacet model is radially symmetric (only depending on θ_h); hence, it is isotropic.
- Ashikmin and Shirley have developed a microfacet model for anisotropic surfaces



$$D(\omega_h) \propto (\omega_h \cdot \mathbf{n})^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h}$$

Ashikmin-Shirley model



$$\int_{\Omega} c(\omega_h \cdot \mathbf{n})^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h} \cos \theta_h d\omega_h = 1$$

Ashikmin-Shirley model



$$\int_{\Omega} c(\omega_h \cdot \mathbf{n})^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h} \cos \theta_h d\omega_h = 1$$

$$\int_0^{2\pi/\pi/2} \int_0^{\pi/2} c(\cos \theta_h)^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 1} \sin \theta_h d\theta_h d\phi_h = 1$$

$$c \int_0^{2\pi/\pi/2} \int_0^{\pi/2} (\cos \theta_h)^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 1} d\cos \theta_h d\phi_h = -1$$

$$c \int_0^{2\pi} \frac{(\cos \theta_h)^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 2}}{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 2} \Big|_1^0 d\phi_h = -1$$

$$c \int_0^{2\pi} \frac{1}{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 2} d\phi_h = 1$$

Ashikmin-Shirley model



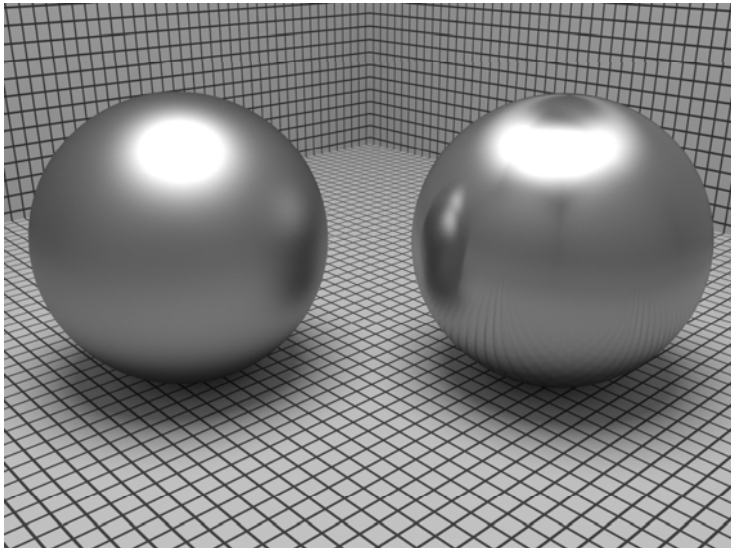
$$c \int_0^{2\pi} \frac{1}{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h + 2} d\phi_h = 1$$

$$\int \frac{1}{a \cos^2(x) + b \sin^2(x) + 2} dx = \frac{\tan^{-1}\left(\frac{\sqrt{2+2} \tan(x)}{\sqrt{a+2}}\right)}{\sqrt{a+2} \sqrt{b+2}}$$

$$c \frac{2\pi}{\sqrt{e_x+2} \sqrt{e_y+2}} = 1$$

$$D(\omega_h) = \frac{\sqrt{(e_x+2)(e_y+2)}}{2\pi} (\omega_h \cdot \mathbf{n})^{e_x \cos^2 \phi_h + e_y \sin^2 \phi_h}$$

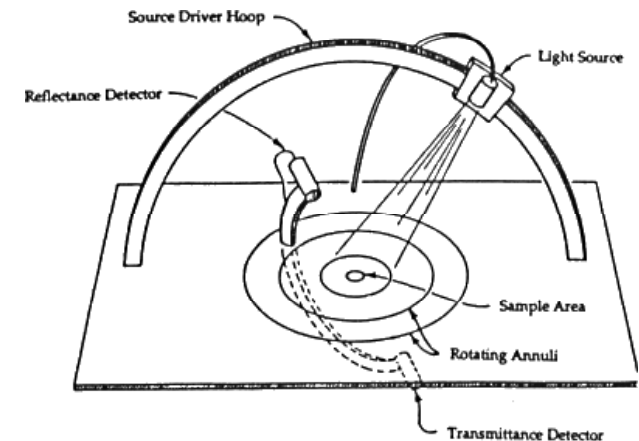
Anisotropic microfacet model



Measured BRDFs



- An effective approach for realistic materials is to use measured data. The following device is proposed by Greg Ward in SIGGRAPH 1992



Measured BRDFs



- The measured data can be
 1. Fitted into parametric models: compact and memory saving; not flexible enough to capture full complexity of scattering properties
 2. Used directly: memory intensive, difficult to adjust, more subjective to measurement noise; high fidelity
- Measured data may come in one of two forms:
 1. regularly spaced tabularized data (efficient to look up but could be more difficult to acquire)
 2. a large number of irregularly spaced individual samples
- pbrt has support for both: `RegularHalfangleBRDF` and `IrregIsotropicBRDF`

Irregular isotropic measured BRDF



- Because of isotropy, we could use the mapping
$$m(\theta_i, \phi_i, \theta_o, \phi_o) \rightarrow (\theta_i, \theta_o, \phi_i - \phi_o)$$
- For the following properties, we instead use the mapping

$$m(\theta_i, \phi_i, \theta_o, \phi_o) \rightarrow (\sin \theta_i \sin \theta_o, \Delta\phi / \pi, \cos \theta_i \cos \theta_o)$$

1. Distance between points is meaningful
2. Isotropy is reflected
3. Reciprocity is represented

IrregIsotropicBRDF



```
class IrregIsotropicBRDF : public BxDF {
public:
    IrregIsotropicBRDF(KdTree<IrregIsotropicBRDFSample> *d)
        : BxDF(BxDFType(BSDF_REFLECTION | BSDF_GLOSSY)),
          isoBRDFData(d) { }
    Spectrum f(const Vector &wo, const Vector &wi) const;
private:
    const KdTree<IrregIsotropicBRDFSample> *isoBRDFData;
};
```

IrregIsotropicBRDF



```
Point BRDFRemap(const Vector &wo, const Vector &wi)
{
    float cosi = CosTheta(wi), coso = CosTheta(wo);
    float sini = SinTheta(wi), sino = SinTheta(wo);
    float phii = SphericalPhi(wi),
           phio = SphericalPhi(wo);
    float dphi = phii - phio;
    if (dphi < 0.) dphi += 2.f * M_PI;
    if (dphi > 2.f * M_PI) dphi -= 2.f * M_PI;
    if (dphi > M_PI) dphi = 2.f * M_PI - dphi;

    return Point(sini * sino, dphi / M_PI,
                cosi * coso);
}
```

IrregIsotropicBRDF



```
Spectrum IrregIsotropicBRDF::f(const Vector &wo,
                               const Vector &wi)
{
    Point m = BRDFRemap(wo, wi);
    float lastMaxDist2 = .001f;
    while (true) {
        IrregIsoProc proc;
        float maxDist2 = lastMaxDist2;
        isoBRDFData->Lookup(m, proc, maxDist2);
        if (proc.nFound > 2 || lastMaxDist2 > 1.5f)
            return proc.v.Clamp() / proc.sumWeights;
        lastMaxDist2 *= 2.f;
    }
}
```

IrregIsoProc



```
struct IrregIsoProc {
    IrregIsoProc() { sumWeights = 0.f; nFound = 0; }
    void operator()(const Point &p, const
                    IrregIsotropicBRDFSample &sample,
                    float d2, float &maxDist2)
    {
        float weight = expf(-100.f * d2);
        v += weight * sample.v;
        sumWeights += weight;
        ++nFound;
    }
    Spectrum v;
    float sumWeights;
    int nFound;
};
```

Regular halfangle format

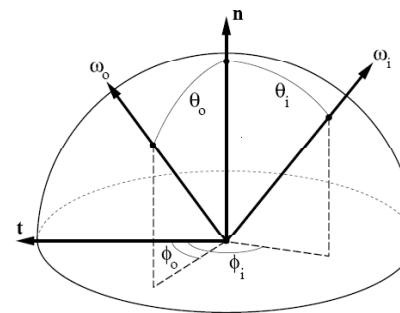


- Supports isotropic measured BRDFs stored in a format used by Matusik et al. (2003).
- Rusunkiewicz proposed to use a mapping based on the half-angle vector and the difference vector, found by applying to ω_i the rotation which rotates the half vector to $(0,0,1)$

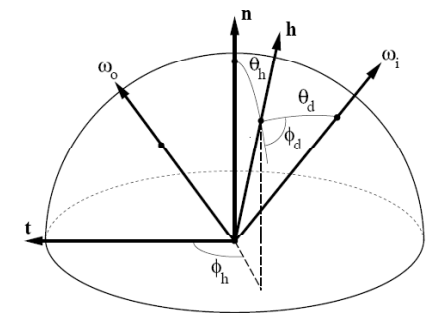
$$m(\theta_i, \phi_i, \theta_o, \phi_o) \rightarrow (\theta_h, \phi_h, \theta_d, \phi_d)$$

- Assuming isotropy, ϕ_h can be dropped and the table is indexed by $(\sqrt{\theta_h}, \theta_d, \phi_d)$. The square root is used to increase sampling for near-zero θ_h because small change there could lead to big function value change

Data representation

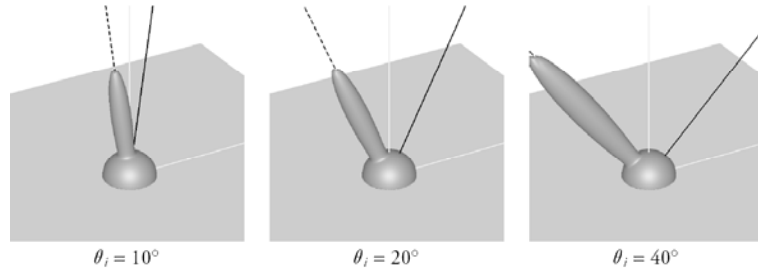


standard coordinate

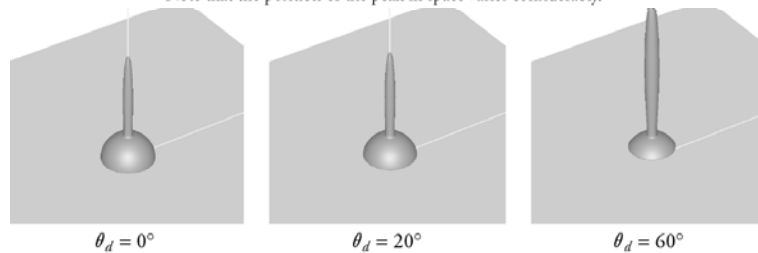


Rusunkiewicz coordinate

Data representation



The Cook-Torrance-Sparrow BRDF seen as a function of (θ_o, ϕ_o) , for various values of (θ_i, ϕ_i) .
Note that the position of the peak in space varies considerably.



RegularHalfangleBRDF



```
class RegularHalfangleBRDF : public BxDF {
public:
    RegularHalfangleBRDF(const float *d,
        uint32_t nth, uint32_t ntd, uint32_t npd)
        :BxDF(BxDFType(BSDF_REFLECTION|BSDF_GLOSSY)),...
        { }
    Spectrum f(const Vector &wo, const Vector &wi);
private:
    const float *brdf;
    const uint32_t nThetaH, nThetaD, nPhiD;
};
```

RegularHalfangleBRDF



```
Spectrum RegularHalfangleBRDF::f(Vector &wo,
                                Vector &wi)
{
    Vector wh = wi + wo;
    if (wh.x==0.f && wh.y==0.f && wh.z==0.f)
        return Spectrum (0.f);
    wh = Normalize(wh);
    float whTheta = SphericalTheta(wh);
    float whCosPhi = CosPhi(wh),
          whSinPhi = SinPhi(wh);
    float whCosTheta = CosTheta(wh),
          whSinTheta = SinTheta(wh);
    Vector whx(whCosPhi*whCosTheta, whSinPhi*whCosTheta,
              -whSinTheta);
    Vector why(-whSinPhi, whCosPhi, 0);
    Vector wd(Dot(wi, whx), Dot(wi, why), Dot(wi, wh));
```

Rotation matrix to align the halfangle vector to z-axis; whx, why and wh are rows.

RegularHalfangleBRDF



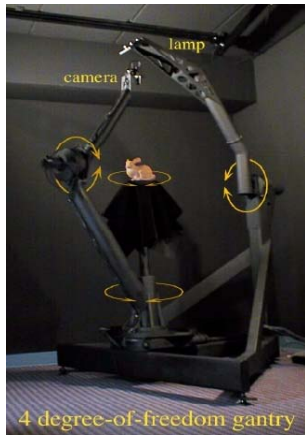
```
float wdTheta = SphericalTheta(wd),
      wdPhi = SphericalPhi(wd);
if (wdPhi > M_PI) wdPhi -= M_PI;

#define REMAP(V, MAX, COUNT) \
    Clamp(int((V) / (MAX) * (COUNT)), 0, (COUNT)-1)
int whThetaIndex = REMAP(sqrtf(max(0.f, whTheta /
    (M_PI / 2.f))), 1.f, nThetaH);
int wdThetaIndex = REMAP(wdTheta, M_PI/2.f, nThetaD);
int wdPhiIndex = REMAP(wdPhi, M_PI, nPhiD);
#undef REMAP
int index = wdPhiIndex + nPhiD *
    (wdThetaIndex + whThetaIndex * nThetaD);
return Spectrum::FromRGB(&brdf[3*index]);
}
```

Lafortune model



An efficient model to fit measured data to a parameterized model with a relatively small number of parameters



modified Phong model

$$f_r(p, \omega_o, \omega_i) = (\omega_o \cdot R(\omega_i, \mathbf{n}))^e$$

$$= (\omega_o \cdot (-\omega_{ix}, -\omega_{iy}, \omega_{iz}))^e$$

orientation vector $(o_{i,x}, o_{i,y}, o_{i,z})$

$(-1, -1, +1)$ specular $(1, 1, 1)$ retro-reflective

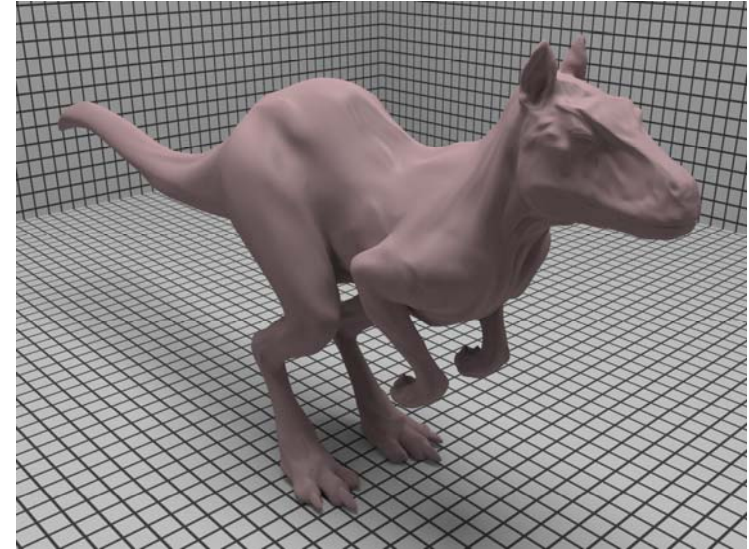
$(-1, -1, +0.5)$ off-specular

Lafortune model

$$f_r(p, \omega_o, \omega_i)$$

$$= \frac{\rho_d}{\pi} + \sum_{i=1}^n (\omega_o \cdot (\omega_{ix} o_{i,x}, \omega_{iy} o_{i,y}, \omega_{iz} o_{i,z}))^{e_i}$$

Lafortune model (for a measured clay)

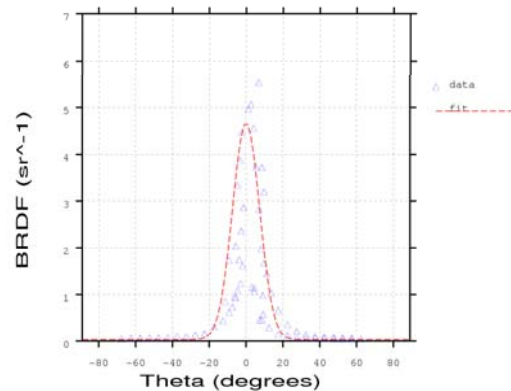


Ward model



$$f(\omega_i, \omega_o) = \frac{\rho_d}{\pi} + \rho_s \frac{1}{4\pi\sigma^2 \sqrt{\cos\theta_i \cos\theta_o}} \exp\left[-\frac{\tan^2\theta_h}{\sigma^2}\right]$$

$$f(\omega_i, \omega_o) = \frac{\rho_d}{\pi} + \rho_s \frac{1}{4\pi\sigma_x\sigma_y\sqrt{\cos\theta_i \cos\theta_o}} \exp\left[-\tan^2\theta_h \left(\frac{\cos^2\phi_h}{\sigma_x^2} + \frac{\sin^2\phi_h}{\sigma_y^2}\right)\right]$$



Ward model

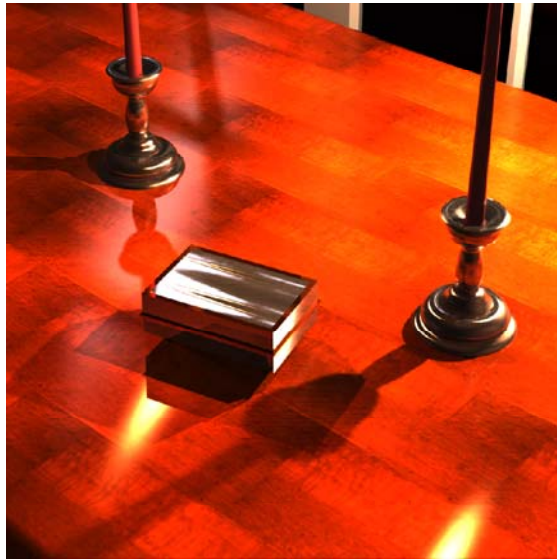


photograph

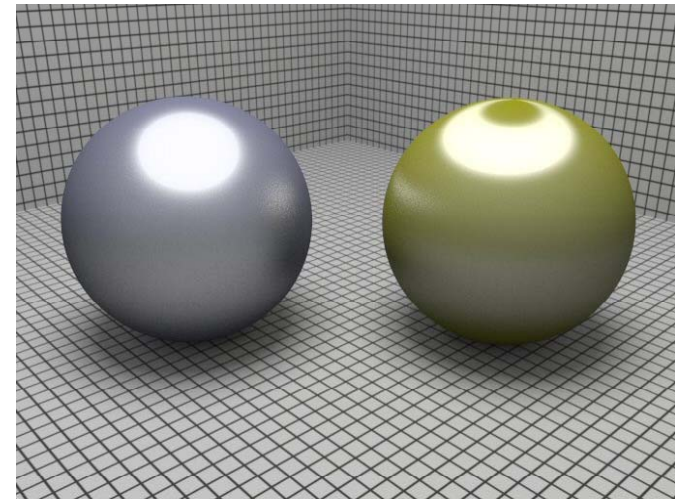
isotropic

anisotropic

Ward model



Ward model



A data-driven reflectance model

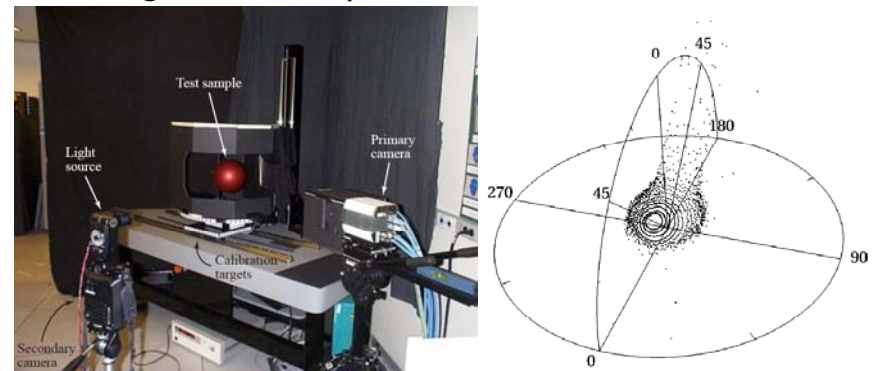


- Analytic models
- measure-then-fit
 - approximation: reduce noise but also characteristic of the model
 - non-obvious error metric: often biased to specular
 - difficult optimization: nonlinear; depends on initial guess
- Tabulated BRDF
 - time-consuming
 - not editable
- Data-Driven Reflectance Model by Matusik et. al. in SIGGRAPH 2003

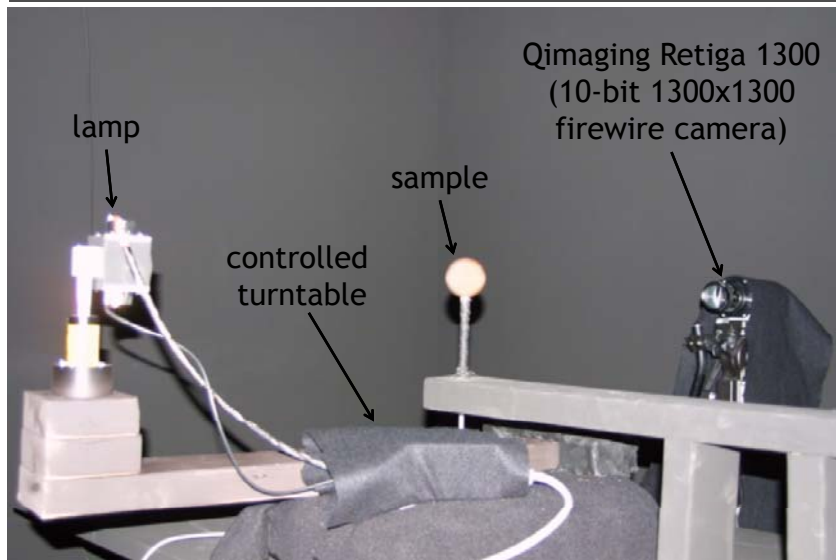
Acquisition



- Requirements: dense samples and wide range of BRDF models
- Inspired by Marschner; requires a spherically homogeneous sample of the material



Acquisition



Acquisition



- Fixed calibrated camera; the light moves roughly every 0.5 degree
- It took 3 hours to take a total of 330 HDR images for a sample. (18 10-bit pictures for each HDR; linearly fitted)
- Each pixel gives one BRDF sample

Acquisition



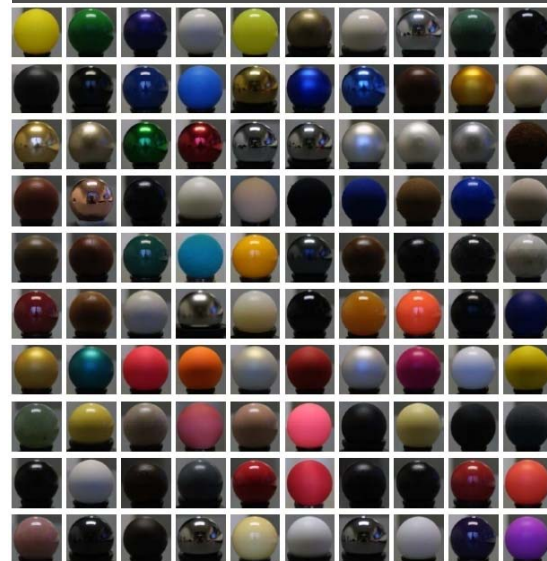
$90 \times 90 \times 180 = 1,458,000$ bins (isotropic, reciprocity to reduce 360 to 180)
20-80M samples in total
For each bin; remove top and bottom 25% and then find the average
Reduce systematic error and tolerate spatial material variation



photograph

rendering using
tabulated BRDF

Acquisition



130 materials
were scanned;
100 of them
shown here

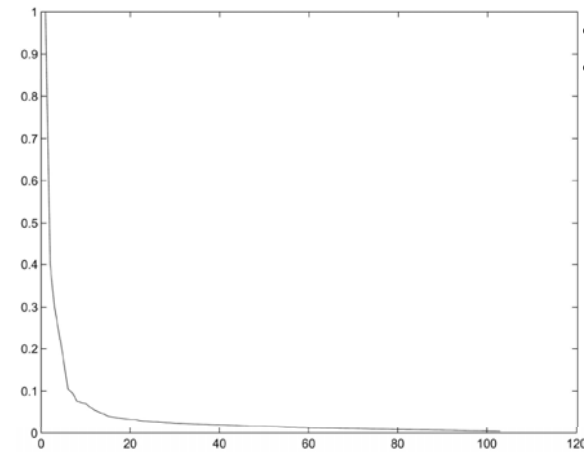
Tabulated BRDF



Linear dimension reduction



- SVD on the 4,374,000x104 matrix.

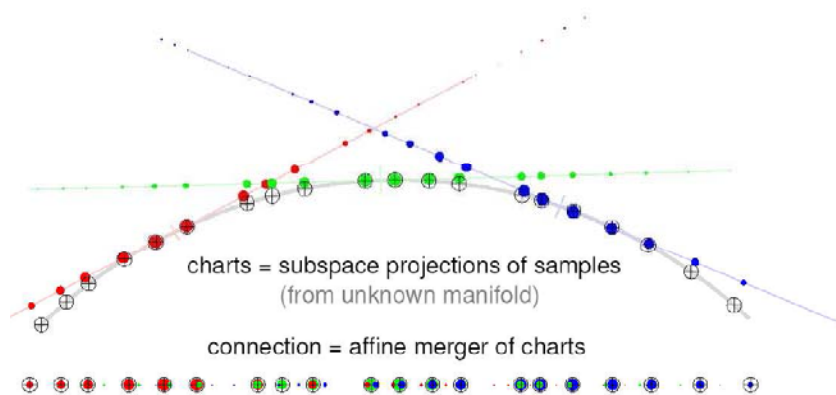


- 45D space
- It spans a space bigger than the space of all possible BRDFs
 1. more parameters than most models
 2. it interpolates invalid BRDF

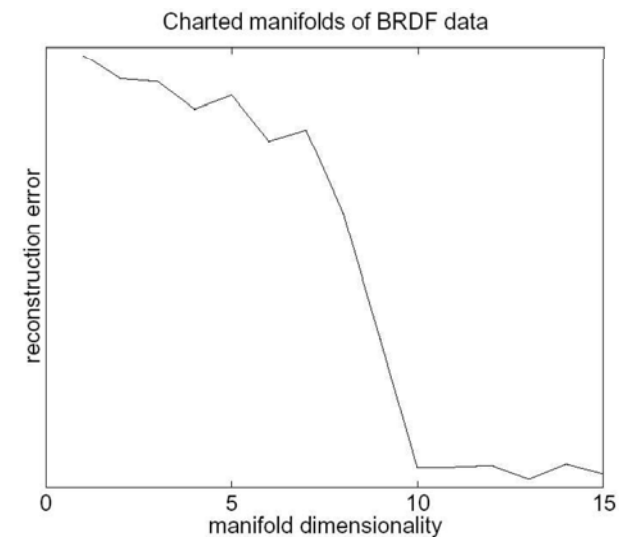
Nonlinear dimension reduction



- Charting by Matt Brand



Nonlinear dimension reduction



- 10D gives good reconstruction
- Choose to work on 15D

Model construction



- A subject characterized each BRDF by 16 categories as yes, no and unclear: redness, greenness, blueness, specularness, diffuseness, glossiness, metallic-like, plastic-like, roughness, silverness, gold-like, fabric-like, acrylic-like, greasiness, dustiness, rubber-like
- SVM is used to build the model

Results



Results



Results



Polished steel



Black oxidized