

Working Set Selection Using Second Order Information for Training SVM

Chih-Jen Lin

Department of Computer Science
National Taiwan University



Joint work with Rong-En Fan and Pai-Hsuen Chen

Talk at NIPS 2005 Workshop on Large Scale Kernel Machines

Outline

- Large dense quadratic programming in SVM
- Decomposition methods and working set selections
- A new selection based on **second** order information
- Results and analysis
- This work appears in JMLR 2005

SVM Dual Optimization Problem

- Large dense quadratic problem

$$\begin{aligned} \min_{\alpha} \quad & \frac{1}{2} \alpha^T Q \alpha - \mathbf{e}^T \alpha \\ \text{subject to} \quad & 0 \leq \alpha_i \leq C, i = 1, \dots, l \\ & \mathbf{y}^T \alpha = 0, \end{aligned}$$

- l : # of training data
- Q : l by l fully dense matrix
- $y_i = \pm 1$
- $\mathbf{e} = [1, \dots, 1]^T$
- Difficult as Q is fully dense in general

- Do we really need to solve the dual?

Maybe not. Sometimes data **too large to do so**

- Approximating either from primal or dual side

- However, in certain situations we still hope to solve it

This talk: a faster algorithm and implementation

Decomposition Methods

- Working on a few variable each time
- Similar to coordinate-wise minimization
- Working set B , $N = \{1, \dots, l\} \setminus B$ fixed
Size of B usually ≤ 100
- Sub-problem in each iteration:

$$\min_{\alpha_B} \frac{1}{2} \begin{bmatrix} \alpha_B^T & (\alpha_N^k)^T \end{bmatrix} \begin{bmatrix} Q_{BB} & Q_{BN} \\ Q_{NB} & Q_{NN} \end{bmatrix} \begin{bmatrix} \alpha_B \\ \alpha_N^k \end{bmatrix} -$$

$$\begin{bmatrix} \mathbf{e}_B^T & (\mathbf{e}_N^k)^T \end{bmatrix} \begin{bmatrix} \alpha_B \\ \alpha_N^k \end{bmatrix}$$

$$\text{subject to } 0 \leq (\alpha_B)_t \leq C, t = 1, \dots, q, \mathbf{y}_B^T \alpha_B = -\mathbf{y}_N^T \alpha_N^k$$

Sequential Minimal Optimization (SMO)

- Consider $B = \{i, j\}$; that is, $|B| = 2$ (Platt, 1998)
Extreme of decomposition methods
- Sub-problem **analytically solved**; no need to use optimization software

$$\begin{aligned} \min_{\alpha_i, \alpha_j} \quad & \frac{1}{2} \begin{bmatrix} \alpha_i & \alpha_j \end{bmatrix} \begin{bmatrix} Q_{ii} & Q_{ij} \\ Q_{ij} & Q_{jj} \end{bmatrix} \begin{bmatrix} \alpha_i \\ \alpha_j \end{bmatrix} + (Q_{BN} \boldsymbol{\alpha}_N^k - \mathbf{e}_B)^T \begin{bmatrix} \alpha_i \\ \alpha_j \end{bmatrix} \\ \text{s.t.} \quad & 0 \leq \alpha_i, \alpha_j \leq C, \\ & y_i \alpha_i + y_j \alpha_j = -\mathbf{y}_N^T \boldsymbol{\alpha}_N^k, \end{aligned}$$

- This work focuses on selecting two elements

Existing Selection by Gradient

- Let $\mathbf{d} \equiv [\mathbf{d}_B, \mathbf{0}_N]$. Minimizing

$$\begin{aligned} f(\boldsymbol{\alpha}^k + \mathbf{d}) &\approx f(\boldsymbol{\alpha}^k) + \nabla f(\boldsymbol{\alpha}^k)^T \mathbf{d} \\ &= f(\boldsymbol{\alpha}^k) + \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B. \end{aligned}$$

- Solve

$$\begin{aligned} &\min_{\mathbf{d}_B} \quad \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B \\ &\text{subject to} \quad \mathbf{y}_B^T \mathbf{d}_B = 0, \\ &\quad d_t \geq 0, \text{ if } \alpha_t^k = 0, t \in B, \quad (1a) \\ &\quad d_t \leq 0, \text{ if } \alpha_t^k = C, t \in B, \quad (1b) \\ &\quad -1 \leq d_t \leq 1, t \in B \end{aligned}$$

$$|B| = 2$$

- First considered in (Joachims, 1998)

- $0 \leq \alpha_t \leq C$ leads to (1a) and (1b).

$$0 \leq \alpha_t^k + d_t \Rightarrow d_t \geq 0, \text{ if } \alpha_t^k = 0,$$

$$\alpha_t^k + d_t \leq C \Rightarrow d_t \leq 0, \text{ if } \alpha_t^k = C$$

$\alpha + d$ may not be feasible. OK for finding working sets

- $-1 \leq d_t \leq 1, t \in B$ avoid $-\infty$ objective value

- Rewritten as checking first order approximation at different sub-problems of B

$$\{i, j\} = \arg \min_{B:|B|=2} \text{Sub}(B),$$

where

$$\text{Sub}(B) \equiv \min_{\mathbf{d}_B} \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B$$

$$\text{subject to } \mathbf{y}_B^T \mathbf{d}_B = 0,$$

$$d_t \geq 0, \text{ if } \alpha_t^k = 0, t \in B,$$

$$d_t \leq 0, \text{ if } \alpha_t^k = C, t \in B,$$

$$-1 \leq d_t \leq 1, t \in B.$$

- Checking all $\binom{l}{2}$ possible B 's?

Solution of Using Gradient Information

- $O(l)$ procedure

$$i \in \arg \max_{t \in I_{\text{up}}(\boldsymbol{\alpha}^k)} -y_t \nabla f(\boldsymbol{\alpha}^k)_t,$$

$$j \in \arg \min_{t \in I_{\text{low}}(\boldsymbol{\alpha}^k)} -y_t \nabla f(\boldsymbol{\alpha}^k)_t,$$

where

$I_{\text{up}}(\boldsymbol{\alpha}) \equiv \{t \mid \alpha_t < C, y_t = 1 \text{ or } \alpha_t > 0, y_t = -1\}$, and

$I_{\text{low}}(\boldsymbol{\alpha}) \equiv \{t \mid \alpha_t < C, y_t = -1 \text{ or } \alpha_t > 0, y_t = 1\}$.

- This usually called **maximal violating pair**

Better Working Set Selection

- Difficult: # iter \searrow but cost per iter \nearrow

May not imply shorter training time

- A selection by **second order** information (Fan et al., 2005)

As f is a quadratic,

$$\begin{aligned} f(\boldsymbol{\alpha}^k + \mathbf{d}) &= f(\boldsymbol{\alpha}^k) + \nabla f(\boldsymbol{\alpha}^k)^T \mathbf{d} + \frac{1}{2} \mathbf{d}^T \nabla^2 f(\boldsymbol{\alpha}^k) \mathbf{d} \\ &= f(\boldsymbol{\alpha}^k) + \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B + \frac{1}{2} \mathbf{d}_B^T \nabla^2 f(\boldsymbol{\alpha}^k)_{BB} \mathbf{d}_B \end{aligned}$$

Selection by Second-Order Information

- Using **second order information**

$$\min_{B:|B|=2} \text{Sub}(B),$$

$$\text{Sub}(B) \equiv \min_{\mathbf{d}_B} \frac{1}{2} \mathbf{d}_B^T \nabla^2 f(\boldsymbol{\alpha}^k)_{BB} \mathbf{d}_B + \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B$$

$$\text{subject to } \mathbf{y}_B^T \mathbf{d}_B = 0,$$

$$d_t \geq 0, \text{ if } \alpha_t^k = 0, t \in B,$$

$$d_t \leq 0, \text{ if } \alpha_t^k = C, t \in B.$$

- $-1 \leq d_t \leq 1, t \in B$ not needed if Q_{BB} PD

- Too expensive to check $\binom{l}{2}$ sets**

- A heuristic

1. Select

$$i \in \arg \max_t \{-y_t \nabla f(\boldsymbol{\alpha}^k)_t \mid t \in I_{\text{up}}(\boldsymbol{\alpha}^k)\}.$$

2. Select

$$j \in \arg \min_t \{\mathbf{Sub}(\{i, t\}) \mid t \in I_{\text{low}}(\boldsymbol{\alpha}^k), \\ -y_t \nabla f(\boldsymbol{\alpha}^k)_t < -y_i \nabla f(\boldsymbol{\alpha}^k)_i\}.$$

3. Return $B = \{i, j\}$.

- **The same** i as using the gradient information

Check only $O(l)$ B 's to decide j

- Sub($\{i, t\}$) can be **easily** solved

If $K_{ii} + K_{jj} - 2K_{ij} > 0$,

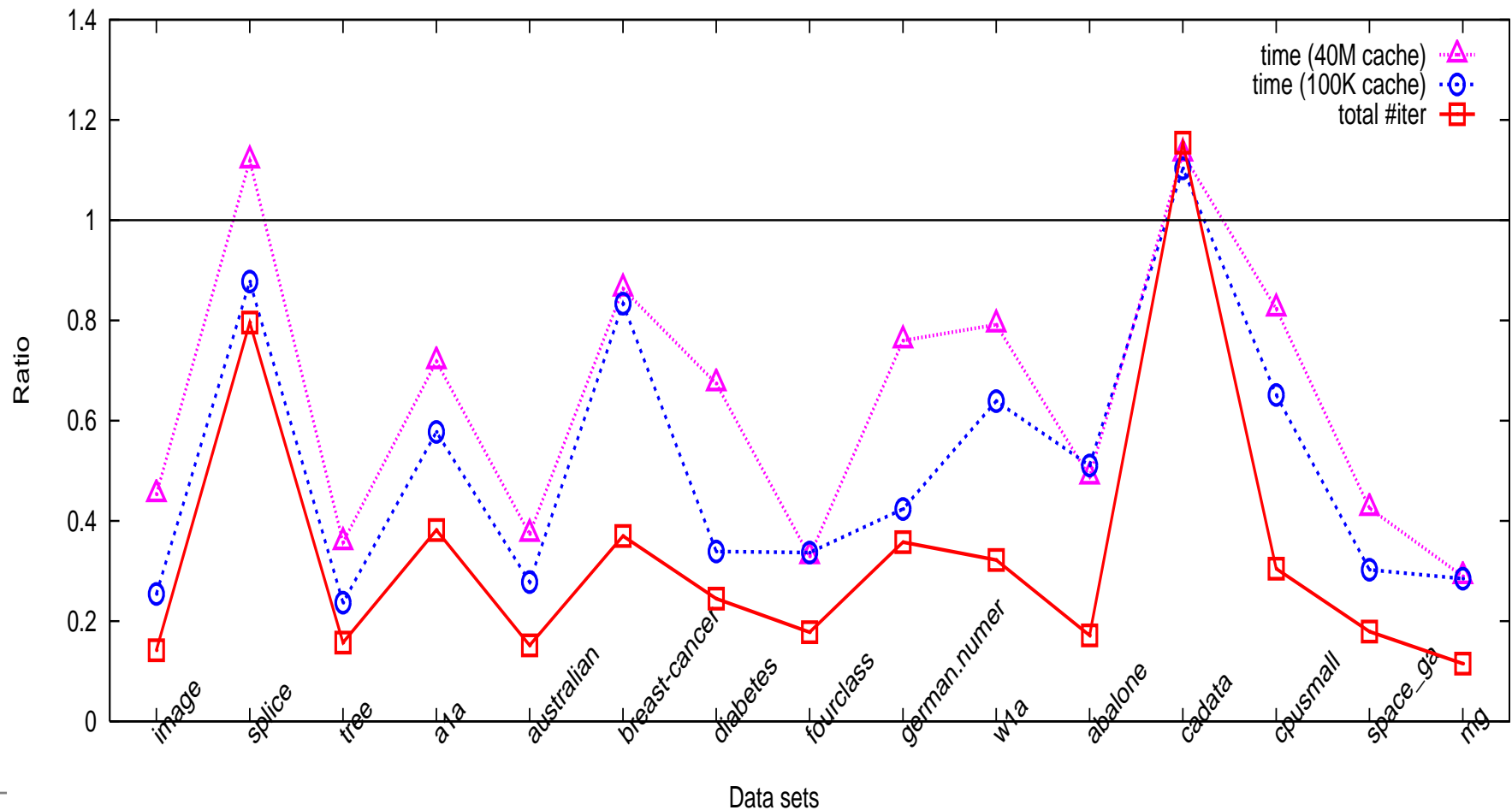
$$\text{Sub}(\{i, t\}) = -\frac{(-y_i \nabla f(\boldsymbol{\alpha}^k)_i + y_t \nabla f(\boldsymbol{\alpha}^k)_t)^2}{2(K_{ii} + K_{tt} - 2K_{it})}$$

- Convergence established in (Fan et al., 2005)

Details not shown here

Comparison of Two Selections

- Iteration and time **ratio** between using second-order information and maximal violating pair

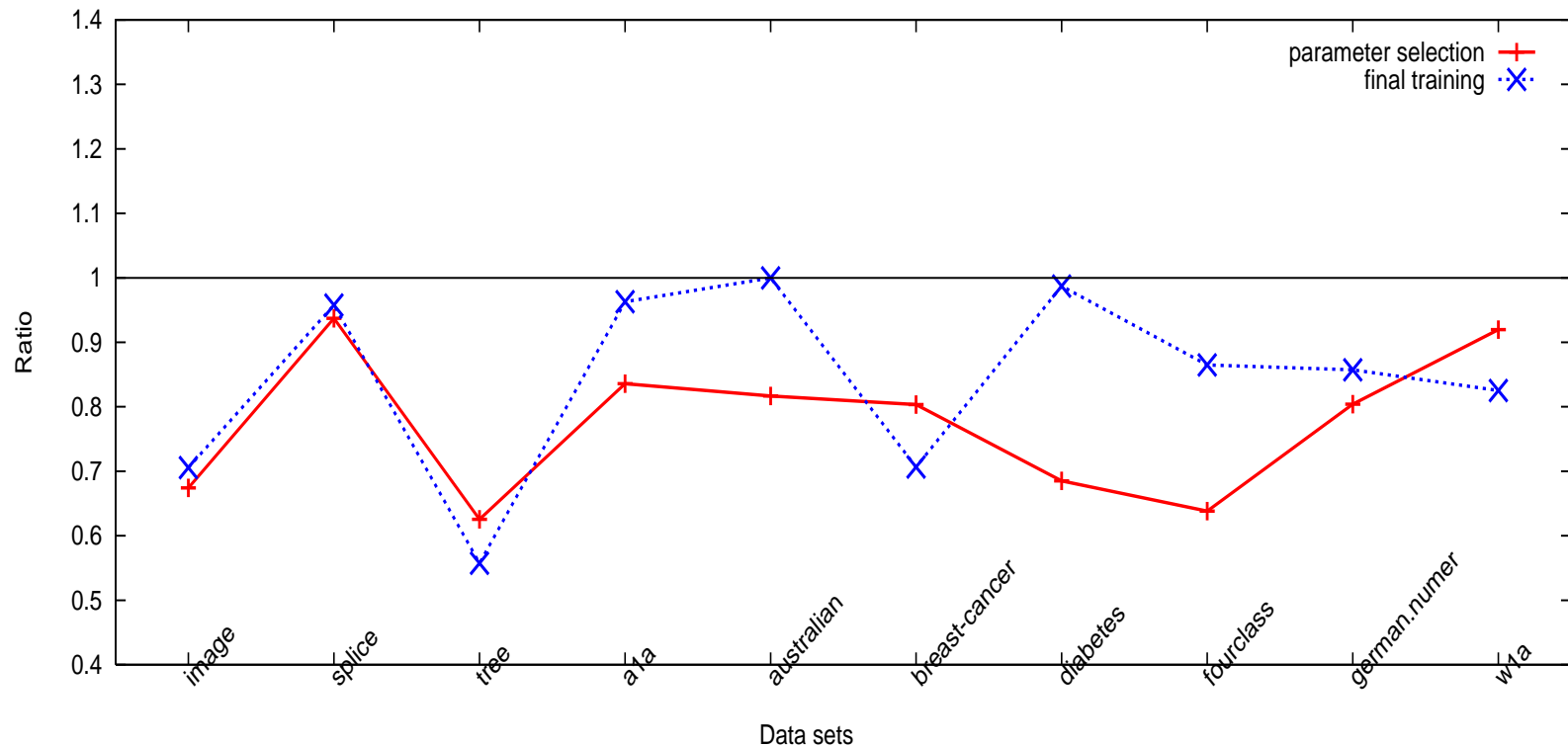


- A complete comparison is not easy
 - Try **enough** data sets
 - Consider **parameter selection**
- Details not shown here

More about Second-Order Selection

- What if we check all $\binom{l}{2}$ sets

Iteration ratio between checking **all** and checking $O(l)$:



- Fewer iterations, but ratio (0.7 to 0.8) **not enough** to justify the **higher** cost per iteration

Why not Keeping Feasibility?

$$\min_{\mathbf{d}_B} \quad \frac{1}{2} \mathbf{d}_B^T \nabla^2 f(\boldsymbol{\alpha}^k)_{BB} \mathbf{d}_B + \nabla f(\boldsymbol{\alpha}^k)_B^T \mathbf{d}_B$$

- **Two** types of constraints:

$$\mathbf{y}_B^T \mathbf{d}_B = 0,$$

$$\mathbf{y}_B^T \mathbf{d}_B = 0,$$

$$d_t \geq 0, \text{ if } \alpha_t^k = 0, t \in B,$$

$$0 \leq \alpha^k + d_t \leq C, t \in B$$

$$d_t \leq 0, \text{ if } \alpha_t^k = C, t \in B$$

- Related work (Lai et al., 2003a,b)
 - **Heuristically** select some pairs
 - Check function reduction while keeping feasibility
- **Higher cost** in selecting working sets
- We proved: at final iterations two are indeed **the same**

Conclusions

- Finding better working sets for SVM decomposition methods is difficult
- We proposed one based on **second** order information
- Results **better** than the commonly used selection from first order information
- Implementation in LIBSVM (after version 2.8)

<http://www.csie.ntu.edu.tw/~cjlin/libsvm>

Replacing the maximal violating pair selection