# What then do you call proof? <br> - Henry James (1843-1916), The Wings of the Dove (1902) <br> Leibniz knew what a proof is. Descartes did not. <br> - Ian Hacking (1973) 

## What Is a Proof?

- A proof convinces a party of a certain claim.
- " $x^{n}+y^{n} \neq z^{n}$ for all $x, y, z \in \mathbb{Z}^{+}$and $n>2$."
- "Graph $G$ is Hamiltonian."
- " $x^{p}=x \bmod p$ for prime $p$ and $p \nmid x$."
- In mathematics, a proof is a fixed sequence of theorems.
- Think of it as a written examination.
- We will extend a proof to cover a proof process by which the validity of the assertion is established.
- Recall a job interview or an oral examination.


## Prover and Verifier

- There are two parties to a proof.
- The prover (Peggy).
- The verifier (Victor).
- Given an assertion, the prover's goal is to convince the verifier of its validity (completeness).
- The verifier's objective is to accept only correct assertions (soundness).
- The verifier usually has an easier job than the prover.
- The setup is very much like the Turing test. ${ }^{\text {a }}$
${ }^{\text {a }}$ Turing (1950).


## Interactive Proof Systems

- An interactive proof for a language $L$ is a sequence of questions and answers between the two parties.
- At the end of the interaction, the verifier decides whether the claim is true or false.
- The verifier must be a probabilistic polynomial-time algorithm.
- The prover runs an exponential-time algorithm. ${ }^{\text {a }}$
- If the prover is not more powerful than the verifier, no interaction is needed!

[^0]
## Interactive Proof Systems (concluded)

- The system decides $L$ if the following two conditions hold for any common input $x$.
- If $x \in L$, then the probability that $x$ is accepted by the verifier is at least $1-2^{-|x|}$.
- If $x \notin L$, then the probability that $x$ is accepted by the verifier with any prover replacing the original prover is at most $2^{-|x|}$.
- Neither the number of rounds nor the lengths of the messages can be more than a polynomial of $|x|$.



## IP ${ }^{\text {a }}$

- IP is the class of all languages decided by an interactive proof system.
- When $x \in L$, the completeness condition can be modified to require that the verifier accept with certainty without affecting IP. ${ }^{\text {b }}$
- Similar things cannot be said of the soundness condition when $x \notin L$.
- Verifier's coin flips can be public. ${ }^{\text {c }}$

[^1]
## The Relations of IP with Other Classes

- NP $\subseteq I P$.
- IP becomes NP when the verifier is deterministic and there is only one round of interaction. ${ }^{\text {a }}$
- $\mathrm{BPP} \subseteq \mathrm{IP}$.
- IP becomes BPP when the verifier ignores the prover's messages.
- $\mathrm{IP}=$ PSPACE $^{\text {b }}$

[^2]
## Graph Isomorphism

- $V_{1}=V_{2}=\{1,2, \ldots, n\}$.
- Graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$ are isomorphic if there exists a permutation $\pi$ on $\{1,2, \ldots, n\}$ so that $(u, v) \in E_{1} \Leftrightarrow(\pi(u), \pi(v)) \in E_{2}$.
- The task is to answer if $G_{1} \cong G_{2}$.
- No known polynomial-time algorithms. ${ }^{\text {a }}$
- The problem is in NP (hence IP).
- It is not likely to be NP-complete. ${ }^{\text {b }}$

[^3]
## GRAPH NONISOMORPHISM

- $V_{1}=V_{2}=\{1,2, \ldots, n\}$.
- Graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$ are nonisomorphic if there exist no permutations $\pi$ on $\{1,2, \ldots, n\}$ so that $(u, v) \in E_{1} \Leftrightarrow(\pi(u), \pi(v)) \in E_{2}$.
- The task is to answer if $G_{1} \not \neq G_{2}$.
- Again, no known polynomial-time algorithms.
- It is in coNP, but how about NP or BPP?
- It is not likely to be coNP-complete. ${ }^{\text {a }}$
- Surprisingly, GRAPH NONISOMORPHISM $\in$ IP. ${ }^{\text {b }}$

> a Schöning (1987).
${ }^{\mathrm{b}}$ Goldreich, Micali, \& Wigderson (1986).

## A 2-Round Algorithm

1: Victor selects a random $i \in\{1,2\}$;
2: Victor selects a random permutation $\pi$ on $\{1,2, \ldots, n\}$;
3: Victor applies $\pi$ on graph $G_{i}$ to obtain graph $H$;
4: Victor sends $\left(G_{1}, H\right)$ to Peggy;
5: if $G_{1} \cong H$ then
6: Peggy sends $j=1$ to Victor;
7: else
8: Peggy sends $j=2$ to Victor;
9: end if
10: if $j=i$ then
11: Victor accepts; $\left\{G_{1} \not \neq G_{2}.\right\}$
12: else
13: Victor rejects; $\left\{G_{1} \cong G_{2}.\right\}$
14: end if

## Analysis

- Victor runs in probabilistic polynomial time.
- Suppose $G_{1} \not \approx G_{2}$.
- Peggy is able to tell which $G_{i}$ is isomorphic to $H$, so $j=i$.
- So Victor always accepts.
- Suppose $G_{1} \cong G_{2}$.
- No matter which $i$ is picked by Victor, Peggy or any prover sees 2 identical copies.
- Peggy or any prover with exponential power has only probability one half of guessing $i$ correctly.
- So Victor erroneously accepts with probability 1/2.
- Repeat the algorithm to obtain the desired probabilities.


## Knowledge in Proofs

- Suppose I know a satisfying assignment to a satisfiable boolean expression.
- I can convince Alice of this by giving her the assignment.
- But then I give her more knowledge than is necessary.
- Alice can claim that she found the assignment!
- Login authentication faces essentially the same issue.
- See
www.wired.com/wired/archive/1.05/atm_pr.html for a famous ATM fraud in the U.S.


## Knowledge in Proofs (concluded)

- Suppose I always give Alice random bits.
- Alice extracts no knowledge from me by any measure, but I prove nothing.
- Question 1: Can we design a protocol to convince Alice (the knowledge) of a secret without revealing anything extra?
- Question 2: How to define this idea rigorously?


## Zero Knowledge Proofs ${ }^{\text {a }}$

An interactive proof protocol $(P, V)$ for language $L$ has the perfect zero-knowledge property if:

- For every verifier $V^{\prime}$, there is an algorithm $M$ with expected polynomial running time.
- $M$ on any input $x \in L$ generates the same probability distribution as the one that can be observed on the communication channel of $\left(P, V^{\prime}\right)$ on input $x$.

[^4]
## Comments

- Zero knowledge is a property of the prover.
- It is the robustness of the prover against attempts of the verifier to extract knowledge via interaction.
- The verifier may deviate arbitrarily (but in polynomial time) from the predetermined program.
- A verifier cannot use the transcript of the interaction to convince a third-party of the validity of the claim.
- The proof is hence not transferable.


## Comments (continued)

- Whatever a verifier can "learn" from the specified prover $P$ via the communication channel could as well be computed from the verifier alone.
- The verifier does not learn anything except " $x \in L$."
- Zero-knowledge proofs yield no knowledge in the sense that they can be constructed by the verifier who believes the statement, and yet these proofs do convince him.


## Comments (continued)

- The "paradox" is resolved by noting that it is not the transcript of the conversation that convinces the verifier.
- But the fact that this conversation was held "on line."
- Computational zero-knowledge proofs are based on complexity assumptions.
- $M$ only needs to generate a distribution that is computationally indistinguishable from the verifier's view of the interaction.


## Comments (concluded)

- If one-way functions exist, then zero-knowledge proofs exist for every problem in NP. ${ }^{\text {a }}$
- If one-way functions exist, then zero-knowledge proofs exist for every problem in PSPACE. ${ }^{\text {b }}$
- The verifier can be restricted to the honest one (i.e., it follows the protocol). ${ }^{\text {c }}$
- The coins can be public. ${ }^{\text {d }}$
- The digital money Zcash (2016) is based on zero-knowledge proofs.

[^5]
## Quadratic Residuacity

- Let $n$ be a product of two distinct primes.
- Assume extracting the square root of a quadratic residue modulo $n$ is hard without knowing the factors.
- We next present a zero-knowledge proof for the input

$$
x \in Z_{n}^{*}
$$

being a quadratic residue.

## Zero-Knowledge Proof of Quadratic Residuacity

1: for $m=1,2, \ldots, \log _{2} n$ do
2: $\quad$ Peggy chooses a random $v \in Z_{n}^{*}$ and sends $y=v^{2} \bmod n$ to Victor;
3: Victor chooses a random bit $i$ and sends it to Peggy;
4: Peggy sends $z=u^{i} v \bmod n$, where $u$ is a square root of $x ;\left\{u^{2} \equiv x \bmod n\right.$. $\}$
5: $\quad$ Victor checks if $z^{2} \equiv x^{i} y \bmod n$;
6: end for
7: Victor accepts $x$ if Line 5 is confirmed every time;

## A Useful Corollary of Lemma 81 (p. 680)

Corollary 82 Let $n=p q$ be a product of two distinct primes. (1) If $x$ and $y$ are both quadratic residues modulo $n$, then $x y \in Z_{n}^{*}$ is a quadratic residue modulo $n$. (2) If $x$ is a quadratic residue modulo $n$ and $y$ is a quadratic nonresidue modulo $n$, then $x y \in Z_{n}^{*}$ is a quadratic nonresidue modulo $n$.

- Suppose $x$ and $y$ are both quadratic residues modulo $n$.
- Let $x \equiv a^{2} \bmod n$ and $y \equiv b^{2} \bmod n$.
- Now $x y$ is a quadratic residue as $x y \equiv(a b)^{2} \bmod n$.


## The Proof (concluded)

- Suppose $x$ is a quadratic residue modulo $n$ and $y$ is a quadratic nonresidue modulo $n$.
- By Lemma 81 (p. 680), $(x \mid p)=(x \mid q)=1$ but, say, $(y \mid p)=-1$.
- Now $x y$ is a quadratic nonresidue as $(x y \mid p)=-1$, again by Lemma 81 (p. 680).


## Analysis

- Suppose $x$ is a quadratic residue.
- Then $x$ 's square root $u$ can be computed by Peggy.
- Peggy can answer all challenges.
- Now,

$$
z^{2} \equiv\left(u^{i}\right)^{2} v^{2} \equiv\left(u^{2}\right)^{i} v^{2} \equiv x^{i} y \bmod n .
$$

- So Victor will accept $x$.


## Analysis (continued)

- Suppose $x$ is a quadratic nonresidue.
- Corollary 82 (p. 708) says if $a$ is a quadratic residue, then $x a$ is a quadratic nonresidue.
- As $y$ is a quadratic residue, $x^{i} y$ can be a quadratic residue (see Line 5) only when $i=0$.
- Peggy can answer only one of the two possible challenges, when $i=0 .{ }^{\text {a }}$
- So Peggy will be caught in any given round with probability one half.
${ }^{\text {a }}$ Line $5\left(z^{2} \equiv x^{i} y \bmod n\right)$ cannot equate a quadratic residue $z^{2}$ with a quadratic nonresidue $x^{i} y$ when $i=1$.


## Analysis (continued)

- How about the claim of zero knowledge?
- The transcript between Peggy and Victor when $x$ is a quadratic residue can be generated without Peggy!
- Here is how.
- Suppose $x$ is a quadratic residue. ${ }^{a}$
- In each round of interaction with Peggy, the transcript is a triplet $(y, i, z)$.
- We present an efficient Bob that generates $(y, i, z)$ with the same probability without accessing Peggy's power.

[^6]
## Analysis (concluded)

1: Bob chooses a random $z \in Z_{n}^{*}$;
2: Bob chooses a random bit $i$;
3: Bob calculates $y=z^{2} x^{-i} \bmod n ;{ }^{\text {a }}$
4: Bob writes $(y, i, z)$ into the transcript;
${ }^{\text {a }}$ Recall Line 5 on p. 707: Victor checks if $z^{2} \equiv x^{i} y \bmod n$.

## Comments

- Assume $x$ is a quadratic residue.
- For $(y, i, z), y$ is a random quadratic residue, $i$ is a random bit, and $z$ is a random number.
- Bob cheats because $(y, i, z)$ is not generated in the same order as in the original transcript.
- Bob picks Peggy's answer $z$ first.
- Bob then picks Victor's challenge $i$.
- Bob finally patches the transcript.


## Comments (concluded)

- So it is not the transcript that convinces Victor, but that conversation with Peggy is held "on line."
- The same holds even if the transcript was generated by a cheating Victor's interaction with (honest) Peggy.
- But we skip the details. ${ }^{\text {a }}$

[^7]
## Zero-Knowledge Proof of 3 Colorability ${ }^{\text {a }}$

1: for $i=1,2, \ldots,|E|^{2}$ do
2: $\quad$ Peggy chooses a random permutation $\pi$ of the 3-coloring $\phi$;
3: Peggy samples encryption schemes randomly, commits ${ }^{\text {b }}$ them, and sends $\pi(\phi(1)), \pi(\phi(2)), \ldots, \pi(\phi(|V|))$ encrypted to Victor;
4: Victor chooses at random an edge $e \in E$ and sends it to Peggy for the coloring of the endpoints of $e$;
5: $\quad$ if $e=(u, v) \in E$ then
6: Peggy reveals the colors $\pi(\phi(u))$ and $\pi(\phi(v))$ and "proves"
that they correspond to their encryptions;
7: else
8: Peggy stops;
9: end if
${ }^{\text {a }}$ Goldreich, Micali, \& Wigderson (1986).
${ }^{\mathrm{b}}$ Contributed by Mr. Ren-Shuo Liu (D98922016) on December 22, 2009.

10: if the "proof" provided in Line 6 is not valid then
11: Victor rejects and stops;
12: end if
13:

$$
\text { if } \pi(\phi(u))=\pi(\phi(v)) \text { or } \pi(\phi(u)), \pi(\phi(v)) \notin\{1,2,3\} \text { then }
$$

14: Victor rejects and stops;
15: end if
16: end for
17: Victor accepts;

## Analysis

- If the graph is 3-colorable and both Peggy and Victor follow the protocol, then Victor always accepts.
- Suppose the graph is not 3-colorable and Victor follows the protocol.
- Let $e$ be an edge that is not colored legally.
- Victor will pick it with probability $1 / m$ per round, where $m=|E|$.
- Then however Peggy plays, Victor will reject with probability at least $1 / \mathrm{m}$ per round.


## Analysis (concluded)

- So Victor will accept with probability at most

$$
\left(1-m^{-1}\right)^{m^{2}} \leq e^{-m} .
$$

- Thus the protocol is a valid IP protocol.
- This protocol yields no knowledge to Victor as all he gets is a bunch of random pairs.
- The proof that the protocol is zero-knowledge to any verifier is intricate. ${ }^{\text {a }}$

[^8]
## Comments

- Each $\pi(\phi(i))$ is encrypted by a different cryptosystem in Line 3 . ${ }^{\text {a }}$
- Otherwise, the coloring will be revealed in Line 6.
- Each edge $e$ must be picked randomly. ${ }^{\text {b }}$
- Otherwise, Peggy will know Victor's game plan and plot accordingly.

[^9]


> Just because the problem is NP-complete does not mean that you should not try to solve it. - Stephen Cook $(2002)$

## Tackling Intractable Problems

- Many important problems are NP-complete or worse.
- Heuristics have been developed to attack them.
- They are approximation algorithms.
- How good are the approximations?
- We are looking for theoretically guaranteed bounds, not "empirical" bounds.
- Are there NP problems that cannot be approximated well (assuming NP $\neq \mathrm{P}$ )?
- Are there NP problems that cannot be approximated at all (assuming $\mathrm{NP} \neq \mathrm{P}$ )?


## Some Definitions

- Given an optimization problem, each problem instance $x$ has a set of feasible solutions $F(x)$.
- Each feasible solution $s \in F(x)$ has a cost $c(s) \in \mathbb{Z}^{+}$.
- Here, cost refers to the quality of the feasible solution, not the time required to obtain it.
- It is our objective function: total distance, number of satisfied clauses, cut size, etc.


## Some Definitions (concluded)

- The optimum cost is

$$
\operatorname{OPT}(x)=\min _{s \in F(x)} c(s)
$$

for a minimization problem.

- It is

$$
\operatorname{OPT}(x)=\max _{s \in F(x)} c(s)
$$

for a maximization problem.

## Approximation Algorithms

- Let (polynomial-time) algorithm $M$ on $x$ returns a feasible solution.
- $M$ is an $\epsilon$-approximation algorithm, where $\epsilon \geq 0$, if for all $x$,

$$
\frac{|c(M(x))-\operatorname{OPT}(x)|}{\max (\operatorname{OPT}(x), c(M(x)))} \leq \epsilon
$$

- For a minimization problem,

$$
\frac{c(M(x))-\min _{s \in F(x)} c(s)}{c(M(x))} \leq \epsilon
$$

- For a maximization problem,

$$
\begin{equation*}
\frac{\max _{s \in F(x)} c(s)-c(M(x))}{\max _{s \in F(x)} c(s)} \leq \epsilon \tag{17}
\end{equation*}
$$

## Lower and Upper Bounds

- For a minimization problem,

$$
\min _{s \in F(x)} c(s) \leq c(M(x)) \leq \frac{\min _{s \in F(x)} c(s)}{1-\epsilon}
$$

- For a maximization problem,

$$
\begin{equation*}
(1-\epsilon) \times \max _{s \in F(x)} c(s) \leq c(M(x)) \leq \max _{s \in F(x)} c(s) . \tag{18}
\end{equation*}
$$

## Lower and Upper Bounds (concluded)

- $\epsilon$ ranges between 0 (best) and 1 (worst).
- For minimization problems, an $\epsilon$-approximation algorithm returns solutions within

$$
\left[\mathrm{OPT}, \frac{\mathrm{OPT}}{1-\epsilon}\right]
$$

- For maximization problems, an $\epsilon$-approximation algorithm returns solutions within

$$
[(1-\epsilon) \times \text { OPT, OPT }]
$$

## Approximation Thresholds

- For each NP-complete optimization problem, we shall be interested in determining the smallest $\epsilon$ for which there is a polynomial-time $\epsilon$-approximation algorithm.
- But sometimes $\epsilon$ has no minimum value.
- The approximation threshold is the greatest lower bound of all $\epsilon \geq 0$ such that there is a polynomial-time $\epsilon$-approximation algorithm.
- By a standard theorem in real analysis, such a threshold exists. ${ }^{\text {a }}$

[^10]
## Approximation Thresholds (concluded)

- The approximation threshold of an optimization problem is anywhere between 0 (approximation to any desired degree) and 1 (no approximation is possible).
- If $\mathrm{P}=\mathrm{NP}$, then all optimization problems in $N P$ have an approximation threshold of 0 .
- So assume $\mathrm{P} \neq \mathrm{NP}$ for the rest of the discussion.


## Approximation Ratio

- $\epsilon$-approximation algorithms can also be measured via the approximation ratio: ${ }^{\text {a }}$

$$
\frac{c(M(x))}{\operatorname{OPT}(x)}
$$

- For a minimization problem, the approximation ratio is

$$
\begin{equation*}
1 \leq \frac{c(M(x))}{\min _{s \in F(x)} c(s)} \leq \frac{1}{1-\epsilon} \tag{19}
\end{equation*}
$$

- For a maximization problem, the approximation ratio is

$$
\begin{equation*}
1-\epsilon \leq \frac{c(M(x))}{\max _{s \in F(x)} c(s)} \leq 1 \tag{20}
\end{equation*}
$$

[^11]
## Approximation Ratio (concluded)

- Suppose there is an approximation algorithm that achieves an approximation ratio of $\theta$.
- For a minimization problem, it implies a $\left(1-\theta^{-1}\right)$-approximation algorithm by Eq. (19).
- For a maximization problem, it implies a ( $1-\theta$ )-approximation algorithm by Eq. (20).


## NODE COVER

- NODE COVER seeks the smallest $C \subseteq V$ in graph $G=(V, E)$ such that for each edge in $E$, at least one of its endpoints is in $C$.
- A heuristic to obtain a good node cover is to iteratively move a node with the highest degree to the cover.
- This turns out to produce an approximation ratio of ${ }^{\text {a }}$

$$
\frac{c(M(x))}{\operatorname{OPT}(x)}=\Theta(\log n)
$$

- So it is not an $\epsilon$-approximation algorithm for any constant $\epsilon<1$ (see p. 733).

[^12]
## A 0.5-Approximation Algorithm ${ }^{\text {a }}$

1: $C:=\emptyset$;
2: while $E \neq \emptyset$ do
3: $\quad$ Delete an arbitrary edge $[u, v]$ from $E$;
4: $\quad$ Add $u$ and $v$ to $C$; \{Add 2 nodes to $C$ each time.\}
5: $\quad$ Delete edges incident with $u$ or $v$ from $E$;
6: end while
7: return $C$;
${ }^{\text {a }}$ Gavril (1974).

## Analysis

- It is easy to see that $C$ is a node cover.
- $C$ contains $|C| / 2$ edges. ${ }^{\text {a }}$
- No two edges of $C$ share a node. ${ }^{\text {b }}$
- Any node cover $C^{\prime}$ must contain at least one node from each of the edges of $C$.
- If there is an edge in $C$ both of whose ends are outside $C^{\prime}$, then $C^{\prime}$ will not be a cover.
${ }^{\text {a }}$ The edges deleted in Line 3.
${ }^{\mathrm{b}}$ In fact, $C$ as a set of edges is a maximal matching.



## Analysis (concluded)

- This means that $\operatorname{OPT}(G) \geq|C| / 2$.
- The approximation ratio is hence

$$
\frac{|C|}{\operatorname{OPT}(G)} \leq 2
$$

- So we have a 0.5 -approximation algorithm. ${ }^{\text {a }}$
- And the approximation threshold is therefore $\leq 0.5$.

[^13]
## The 0.5 Bound Is Tight for the Algorithm ${ }^{\text {a }}$


${ }^{\text {a }}$ Contributed by Mr. Jenq-Chung Li (R92922087) on December 20, 2003. König's theorem says the size of a maximum matching equals that of a minimum node cover in a bipartite graph.

## Remarks

- The approximation threshold is at least ${ }^{\text {a }}$

$$
1-(10 \sqrt{5}-21)^{-1} \approx 0.2651
$$

- The approximation threshold is 0.5 if one assumes the unique games conjecture (UGC). ${ }^{\text {b }}$
- This ratio 0.5 is also the lower bound for any "greedy" algorithms. ${ }^{\text {c }}$

[^14]
## Maximum Satisfiability

- Given a set of clauses, mAXSAT seeks the truth assignment that satisfies the most.
- mAX2SAT is already NP-complete (p. 349), so mAXSAT is NP-complete.
- Consider the more general $k$-maXgSat for constant $k$.
- Let $\Phi=\left\{\phi_{1}, \phi_{2}, \ldots, \phi_{m}\right\}$ be a set of boolean expressions in $n$ variables.
- Each $\phi_{i}$ is a general expression involving up to $k$ variables.
- $k$-MAXGSAT seeks the truth assignment that satisfies the most expressions.


[^0]:    ${ }^{\text {a }}$ See the problem to Note 12.3 .7 on p. 296 and Proposition 19.1 on p. 475 , both of the textbook, about alternative complexity assumptions without affecting the definition. Contributed by Mr. Young-San Lin (B97902055) and Mr. Chao-Fu Yang (B97902052) on December 18, 2012.

[^1]:    ${ }^{\text {a }}$ Goldwasser, Micali, \& Rackoff (1985).
    ${ }^{\text {b }}$ Goldreich, Mansour, \& Sipser (1987).
    ${ }^{\text {c }}$ Goldwasser \& Sipser (1989).

[^2]:    ${ }^{\text {a }}$ Recall Proposition 40 on p. 328.
    ${ }^{\mathrm{b}}$ Shamir (1990).

[^3]:    ${ }^{\text {a }}$ The recent bound of Babai (2015) is $2^{O\left(\log ^{c} n\right)}$ for some constant $c$.
    ${ }^{\text {b }}$ Schöning (1987).

[^4]:    ${ }^{\text {a }}$ Goldwasser, Micali, \& Rackoff (1985).

[^5]:    ${ }^{\text {a }}$ Goldreich, Micali, \& Wigderson (1986).
    ${ }^{\text {b }}$ Ostrovsky \& Wigderson (1993).
    ${ }^{\text {c }}$ Vadhan (2006).
    ${ }^{\text {d }}$ Vadhan (2006).

[^6]:    ${ }^{\text {a }}$ There is no zero-knowledge requirement when $x \notin L$.

[^7]:    ${ }^{\text {a }}$ Or apply Vadhan (2006).

[^8]:    ${ }^{\text {a }}$ But no longer necessary because of Vadhan (2006).

[^9]:    ${ }^{\text {a }}$ Contributed by Ms. Yui-Huei Chang (R96922060) on May 22, 2008
    ${ }^{\text {b }}$ Contributed by Mr. Chang-Rong Hung (R96922028) on May 22, 2008

[^10]:    ${ }^{\text {a }}$ Bauldry (2009).

[^11]:    ${ }^{a}$ Williamson \& Shmoys (2011).

[^12]:    ${ }^{\text {a }}$ Chvátal (1979).

[^13]:    ${ }^{\text {a }}$ Recall p. 733.

[^14]:    ${ }^{\text {a }}$ Dinur $\&$ Safra (2002).
    ${ }^{\mathrm{b}}$ Khot \& Regev (2008).
    ${ }^{\text {c }}$ Davis \& Impagliazzo (2004).

