

FSAT

- FSAT is this function problem:
 - Let $\phi(x_1, x_2, \dots, x_n)$ be a boolean expression.
 - If ϕ is satisfiable, then return a satisfying truth assignment.
 - Otherwise, return “no.”
- We next show that if $\text{SAT} \in \text{P}$, then FSAT has a polynomial-time algorithm.

An Algorithm for FSAT Using SAT

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1:  $t := \epsilon$ ; {Truth assignment.}
2: if  $\phi \in \text{SAT}$  then
3:   for  $i = 1, 2, \dots, n$  do
4:     if  $\phi[x_i = \text{true}] \in \text{SAT}$  then
5:        $t := t \cup \{x_i = \text{true}\}$ ;
6:        $\phi := \phi[x_i = \text{true}]$ ;
7:     else
8:        $t := t \cup \{x_i = \text{false}\}$ ;
9:        $\phi := \phi[x_i = \text{false}]$ ;
10:    end if
11:  end for
12:  return  $t$ ;
13: else
14:  return “no”;
15: end if
```

Analysis

- If SAT can be solved in polynomial time, so can FSAT.
 - There are $\leq n + 1$ calls to the algorithm for SAT.^a
 - Shorter boolean expressions than ϕ are used in each call to the algorithm for SAT.
- Hence SAT and FSAT are equally hard (or easy).
- Note that this reduction from FSAT to SAT is not a Karp reduction (recall p. 217).
- Instead, it calls SAT multiple times as a subroutine.

^aContributed by Ms. Eva Ou (R93922132) on November 24, 2004.

TSP and TSP (D) Revisited

- We are given n cities $1, 2, \dots, n$ and integer distances $d_{ij} = d_{ji}$ between any two cities i and j .
- TSP (D) asks if there is a tour with a total distance at most B .
- TSP asks for a tour with the shortest total distance.
 - The shortest total distance is at most $\sum_{i,j} d_{ij}$.
 - * Recall that the input string contains d_{11}, \dots, d_{nn} .
 - * Thus the shortest total distance is less than $2^{|x|}$ in magnitude, where x is the input (why?).
- We next show that if TSP (D) \in P, then TSP has a polynomial-time algorithm.

An Algorithm for TSP Using TSP (D)

- 1: Perform a binary search over interval $[0, 2^{\lceil x \rceil}]$ by calling TSP (D) to obtain the shortest distance, C ;
- 2: **for** $i, j = 1, 2, \dots, n$ **do**
- 3: Call TSP (D) with $B = C$ and $d_{ij} = C + 1$;
- 4: **if** “no” **then**
- 5: Restore d_{ij} to old value; {Edge $[i, j]$ is critical.}
- 6: **end if**
- 7: **end for**
- 8: **return** the tour with edges whose $d_{ij} \leq C$;

Analysis

- An edge that is not on *any* optimal tour will be eliminated, with its d_{ij} set to $C + 1$.
- An edge which is not on *all remaining* optimal tours will also be eliminated.
- So the algorithm ends with n edges which are not eliminated (why?).
- There are $O(|x| + n^2)$ calls to the algorithm for TSP (D).
- So if TSP (D) can be solved in polynomial time, so can TSP.
- Hence TSP (D) and TSP are equally hard (or easy).

Function Problems Are Not Harder than Decision Problems If $P = NP$

Theorem 57 *Suppose that $P = NP$. Then, for every NP language L there exists a polynomial-time TM B that on input $x \in L$ outputs a certificate for x .*

- We are looking for a certificate in the sense of Proposition 34 (p. 273).
- That is, a certificate y for every $x \in L$ such that

$$(x, y) \in R,$$

where R is a polynomially decidable and polynomially balanced relation.

The Proof (concluded)

- Recall the algorithm for FSAT on p. 426.
- The reduction of Cook's Theorem L to SAT is a Levin reduction (p. 277).
- So there is a polynomial-time computable function R such that $x \in L$ iff $R(x) \in \text{SAT}$.
- In fact, the proof gives an efficient algorithm to transform a satisfying assignment of $R(x)$ to a certificate for x , too.
- Therefore, we can use the algorithm for FSAT to come up with an assignment for $R(x)$ and then map it back into a certificate for x .

What If $NP = coNP$?^a

- Can you say similar things?

^aContributed by Mr. Ren-Shuo Liu (D98922016) on October 27, 2009.

Randomized Computation

I know that half my advertising works,
I just don't know which half.
— John Wanamaker

I know that half my advertising is
a waste of money,
I just don't know which half!
— McGraw-Hill ad.

Randomized Algorithms^a

- Randomized algorithms flip unbiased coins.
- There are important problems for which there are no known efficient *deterministic* algorithms but for which very efficient randomized algorithms exist.
 - Extraction of square roots, for instance.
- There are problems where randomization is *necessary*.
 - Secure protocols.
- Randomized version can be more efficient.
 - Parallel algorithm for maximal independent set.

^aRabin (1976); Solovay and Strassen (1977).

“Four Most Important Randomized Algorithms”^a

1. Primality testing.^b
2. Graph connectivity using random walks.^c
3. Polynomial identity testing.^d
4. Algorithms for approximate counting.^e

^aTrevisan (2006).

^bRabin (1976); Solovay and Strassen (1977).

^cAleliunas, Karp, Lipton, Lovász, and Rackoff (1979).

^dSchwartz (1980); Zippel (1979).

^eSinclair and Jerrum (1989).

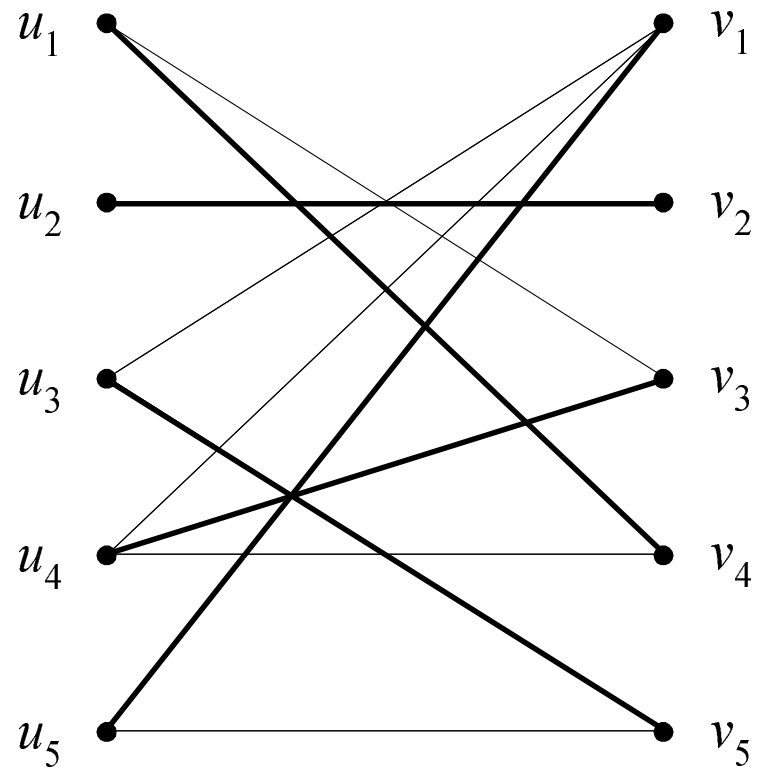
Bipartite Perfect Matching

- We are given a **bipartite graph** $G = (U, V, E)$.
 - $U = \{u_1, u_2, \dots, u_n\}$.
 - $V = \{v_1, v_2, \dots, v_n\}$.
 - $E \subseteq U \times V$.
- We are asked if there is a **perfect matching**.
 - A permutation π of $\{1, 2, \dots, n\}$ such that

$$(u_i, v_{\pi(i)}) \in E$$

for all $i \in \{1, 2, \dots, n\}$.

A Perfect Matching



Symbolic Determinants

- We are given a bipartite graph G .
- Construct the $n \times n$ matrix A^G whose (i, j) th entry A_{ij}^G is a variable x_{ij} if $(u_i, v_j) \in E$ and zero otherwise.

Symbolic Determinants (concluded)

- The **determinant** of A^G is

$$\det(A^G) = \sum_{\pi} \operatorname{sgn}(\pi) \prod_{i=1}^n A_{i, \pi(i)}^G. \quad (5)$$

- π ranges over all permutations of n elements.
- $\operatorname{sgn}(\pi)$ is 1 if π is the product of an even number of transpositions and -1 otherwise.
- Equivalently, $\operatorname{sgn}(\pi) = 1$ if the number of (i, j) s such that $i < j$ and $\pi(i) > \pi(j)$ is even.^a

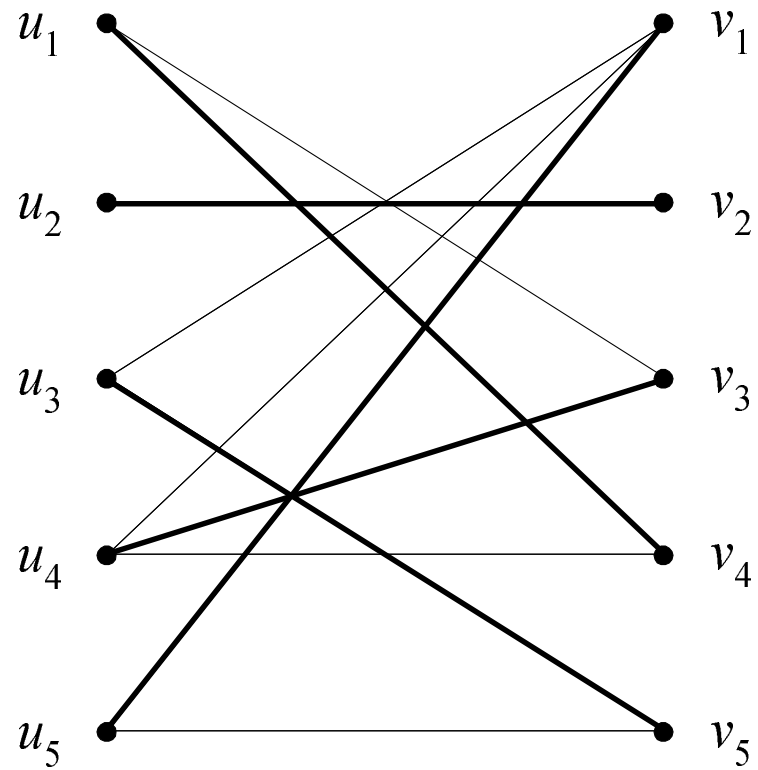
^aContributed by Mr. Hwan-Jeu Yu (D95922028) on May 1, 2008.

Determinant and Bipartite Perfect Matching

- In $\sum_{\pi} \text{sgn}(\pi) \prod_{i=1}^n A_{i,\pi(i)}^G$, note the following:
 - Each summand corresponds to a possible perfect matching π .
 - As all variables appear only *once*, all of these summands are different monomials and will not cancel.
- It is essentially an exhaustive enumeration.

Proposition 58 (Edmonds (1967)) *G has a perfect matching if and only if $\det(A^G)$ is not identically zero.*

A Perfect Matching in a Bipartite Graph



The Perfect Matching in the Determinant

- The matrix is

$$A^G = \begin{bmatrix} 0 & 0 & x_{13} & \boxed{x_{14}} & 0 \\ 0 & \boxed{x_{22}} & 0 & 0 & 0 \\ x_{31} & 0 & 0 & 0 & \boxed{x_{35}} \\ x_{41} & 0 & \boxed{x_{43}} & x_{44} & 0 \\ \boxed{x_{51}} & 0 & 0 & 0 & x_{55} \end{bmatrix}.$$

- $\det(A^G) = -x_{14}x_{22}x_{35}x_{43}x_{51} + x_{13}x_{22}x_{35}x_{44}x_{51} + x_{14}x_{22}x_{31}x_{43}x_{55} - x_{13}x_{22}x_{31}x_{44}x_{55}$, each denoting a perfect matching.

How To Test If a Polynomial Is Identically Zero?

- $\det(A^G)$ is a polynomial in n^2 variables.
- There are exponentially many terms in $\det(A^G)$.
- Expanding the determinant polynomial is not feasible.
 - Too many terms.
- Observation: If $\det(A^G)$ is *identically zero*, then it remains zero if we substitute *arbitrary* integers for the variables x_{11}, \dots, x_{nn} .
- What is the likelihood of obtaining a zero when $\det(A^G)$ is *not* identically zero?

Number of Roots of a Polynomial

Lemma 59 (Schwartz (1980)) *Let $p(x_1, x_2, \dots, x_m) \not\equiv 0$ be a polynomial in m variables each of degree at most d . Let $M \in \mathbb{Z}^+$. Then the number of m -tuples*

$$(x_1, x_2, \dots, x_m) \in \{0, 1, \dots, M - 1\}^m$$

such that $p(x_1, x_2, \dots, x_m) = 0$ is

$$\leq mdM^{m-1}.$$

- By induction on m (consult the textbook).

Density Attack

- The density of roots in the domain is at most

$$\frac{mdM^{m-1}}{M^m} = \frac{md}{M}. \quad (6)$$

- So suppose $p(x_1, x_2, \dots, x_m) \not\equiv 0$.
- Then a random

$$(x_1, x_2, \dots, x_m) \in \{0, 1, \dots, M - 1\}^m$$

has a probability of $\leq md/M$ of being a root of p .

- Note that M is under our control.

Density Attack (concluded)

Here is a sampling algorithm to test if $p(x_1, x_2, \dots, x_m) \not\equiv 0$.

- 1: Choose i_1, \dots, i_m from $\{0, 1, \dots, M - 1\}$ randomly;
- 2: **if** $p(i_1, i_2, \dots, i_m) \neq 0$ **then**
- 3: **return** “ p is not identically zero”;
- 4: **else**
- 5: **return** “ p is (probably) identically zero”;
- 6: **end if**

A Randomized Bipartite Perfect Matching Algorithm^a

We now return to the original problem of bipartite perfect matching.

- 1: Choose n^2 integers i_{11}, \dots, i_{nn} from $\{0, 1, \dots, 2n^2 - 1\}$ randomly;
- 2: Calculate $\det(A^G(i_{11}, \dots, i_{nn}))$ by Gaussian elimination;
- 3: **if** $\det(A^G(i_{11}, \dots, i_{nn})) \neq 0$ **then**
- 4: **return** “ G has a perfect matching”;
- 5: **else**
- 6: **return** “ G has no perfect matchings”;
- 7: **end if**

^aLovász (1979). According to Paul Erdős, Lovász wrote his first significant paper “at the ripe old age of 17.”

Analysis

- If G has no perfect matchings, the algorithm will always be correct.
- Suppose G has a perfect matching.
 - The algorithm will answer incorrectly with probability at most $n^2d/(2n^2) = 0.5$ with $d = 1$ in Eq. (6) on p. 447.
 - Run the algorithm *independently* k times and output “ G has no perfect matchings” if and only if they all say no.
 - The error probability is now reduced to at most 2^{-k} .

Analysis (concluded)^a

- Note that we are calculating

$\text{prob}[\text{algorithm answers "no"} \mid G \text{ has no perfect matchings}]$,
 $\text{prob}[\text{algorithm answers "yes"} \mid G \text{ has a perfect matching}]$.

- We are *not* calculating

$\text{prob}[G \text{ has no perfect matchings} \mid \text{algorithm answers "no"}]$,
 $\text{prob}[G \text{ has a perfect matching} \mid \text{algorithm answers "yes"}]$.

^aThanks to a lively class discussion on May 1, 2008.

But How Large Can $\det(A^G(i_{11}, \dots, i_{nn}))$ Be?

- It is at most

$$n! (2n^2)^n .$$

- Stirling's formula says $n! \sim \sqrt{2\pi n} (n/e)^n$.
- Hence

$$\log_2 \det(A^G(i_{11}, \dots, i_{nn})) = O(n \log_2 n)$$

bits are sufficient for representing the determinant.

- We skip the details about how to make sure that all intermediate results are of polynomial sizes.

Lószló Lovász (1948–)



An Intriguing Question^a

- Is there an (i_{11}, \dots, i_{nn}) that will always give correct answers for all bipartite graphs of $2n$ nodes?
- A theorem on p. 543 shows that such a witness exists!
- Whether it can be found efficiently is another question.

^aThanks to a lively class discussion on November 24, 2004.